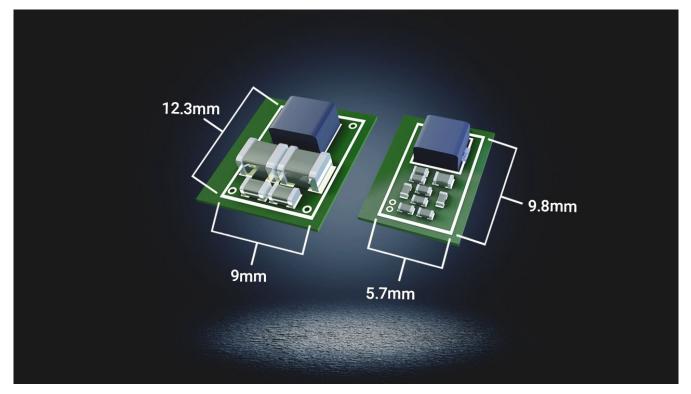
Technical Article How to Reduce EMI and Shrink Power-supply Size with an Integrated Active EMI Filter



Orlando Murray



This technical article is co-authored by Tim Hegarty

Design engineers working on low-electromagnetic interference (EMI) applications typically face two major challenges: the need to reduce the EMI of their designs while also shrinking solution size. Front-end passive filtering to mitigate conducted EMI generated by the switching power supply ensures compliance with conducted EMI standards, but this method can be at odds with the need to increase the power density of low-EMI designs, especially given the adverse effects of higher switching speeds on the overall EMI signature. These passive filters tend to be bulky and can occupy as much as 30% of the total volume of the power solution. Therefore, minimizing the volume of the EMI filter while increasing power density remains a priority for system designers.

Active EMI filtering (AEF) technology, a relatively new approach to EMI filtering, attenuates EMI and enables engineers to achieve a significant reduction in passive filter size and cost, along with improved EMI performance. To illustrate the key benefits that AEF can offer in terms of EMI performance and space savings, in this technical article I'll review results from an automotive synchronous buck controller design with integrated AEF functionality.

EMI filtering

Passive filtering reduces the conducted emissions of a power electronic circuit by using inductors and capacitors to create an impedance mismatch in the EMI current path. In contrast, active filtering senses the voltage at the input bus and produces a current of opposite phase that directly cancels with the EMI current generated by a switching stage.

1



Within this context, take a look at the simplified passive and active filter circuits in Figure 1, where i_N and Z_N respectively denote the current source and impedance of the Norton-equivalent circuit for differential-mode noise of a DC/DC regulator.

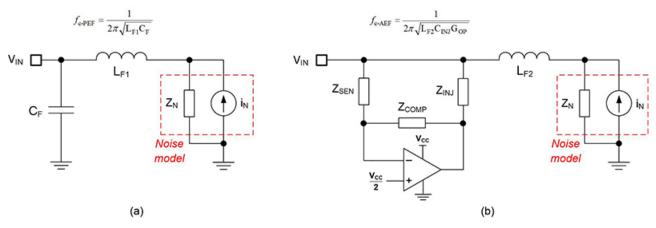


Figure 1. Conventional passive filtering (a) and active filtering (b) circuit implementations

The active EMI filter configured with voltage sense and current cancellation (VSCC) in Figure 1b uses an operational-amplifier (op-amp) circuit as a capacitive multiplier to replace the filter capacitor (C_F) in the passive design. The active filter sensing, injection and compensation impedances as shown use relatively low capacitance values with small component footprints to design a gain term denoted as G_{OP} . The effective active capacitance is set by the op-amp circuit gain and an injection capacitor (C_{INJ}).

Figure 1 includes expressions for the effective filter cutoff frequencies. The effective G_{OP} enables an active design with reduced inductor and capacitor values and a cutoff frequency equivalent to that of the passive implementation.

Improved filtering performance

Figure 2 compares passive and active EMI filter designs based on conducted EMI tests to meet the Comité International Spécial des Perturbations Radioélectriques (CISPR) 25 Class 5 standard using peak and average detectors. Each design uses a power stage based on the LM25149-Q1 synchronous buck DC/DC controller, providing an output of 5 V and 6 A from an automotive battery input of 13.5 V. The switching frequency is 440 kHz.



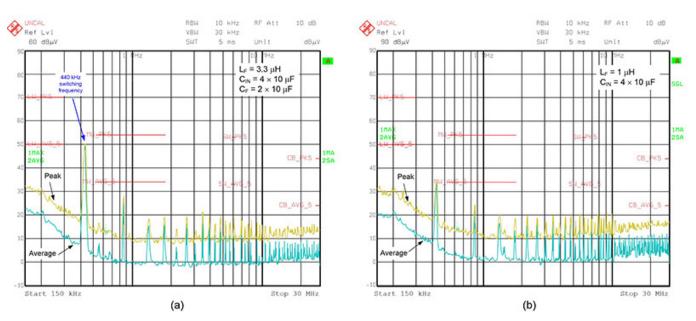


Figure 2. Comparing a passive filter solution (a) and active filter design (b) using equivalent power-stage operating conditions

Figure 3 presents the results when enabling and disabling the AEF circuit. The active EMI filter shows much better low- and medium-frequency attenuation compared to the unfiltered or raw noise signature. The fundamental frequency component at 440 kHz has its peak EMI level reduced by almost 50 dB, making it much easier for designers to meet strict EMI requirements.

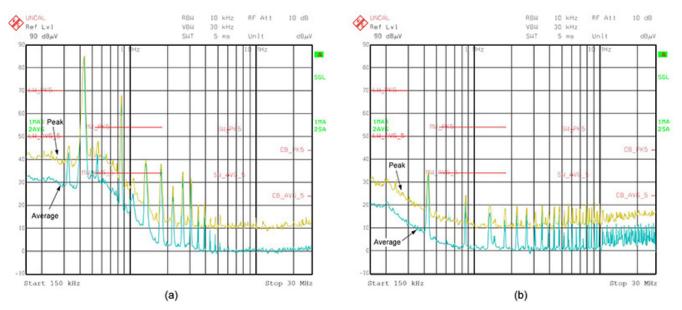


Figure 3. Comparing filtering performance when AEF is disabled (a) and enabled (b)

PCB space savings

Figure 4 offers a printed circuit board (PCB) layout comparison of the passive and active filter stages that provided the results in Figure 2. The inductor footprint reduces from 5 mm by 5 mm to 4 mm by 4 mm. In addition, two 1210 capacitors that derate significantly with applied voltage are replaced by several small, stable-valued 0402 components for AEF sensing, injection and compensation. This filter solution decreases the footprint by nearly 50%, while the volume decreases by over 75%.



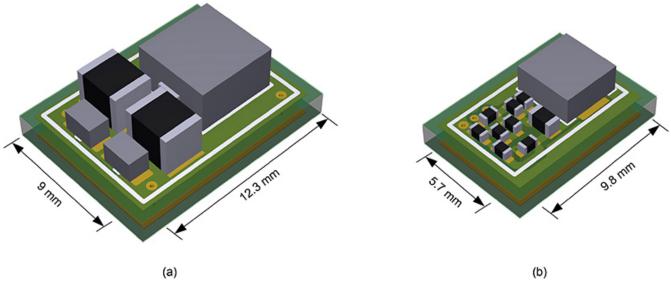


Figure 4. PCB layout size comparison of passive (a) and active (b) filter designs

Passive component advantages

As I mentioned, the lower filter inductance value for AEF reduces the footprint and cost compared to the inductor in a passive filter design. Moreover, a physically smaller inductor typically has a winding geometry with a lower parasitic winding capacitance and higher self-resonant frequency, leading to better filtering performance in the higher conducted frequency range for CISPR 25: 30 MHz to 108 MHz.

Some automotive designs require two input capacitors connected in series for fail-safe robustness when connected directly across the battery-supply rail. As a result, the active circuit can support additional space savings, as small 0402/0603 sensing and injection capacitors connect in series to replace multiple 1210 capacitors. The smaller capacitors simplify component procurement as components are readily available and not supply-constrained.

Conclusion

Amid a continual focus on EMI, particularly in automotive applications, an active filter using voltage sense and current injection enables a low EMI signature and ultimately leads to a reduced footprint and volume, as well as an improved solution cost. The integration of an AEF circuit with a synchronous buck controller helps resolve the trade-offs between low EMI and high power density in DC/DC regulator applications.

Additional resources

- Review these white papers:
 - "Time-Saving and Cost-Effective Innovations for EMI Reduction in Power Supplies."
 - "An Overview of Conducted EMI Specifications for Power Supplies."
- Watch this video on active EMI filtering.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2023, Texas Instruments Incorporated