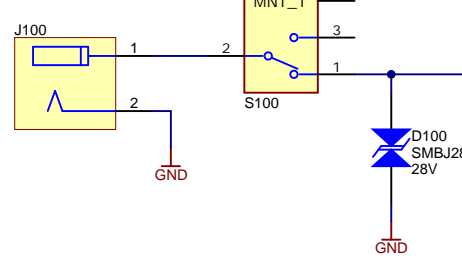
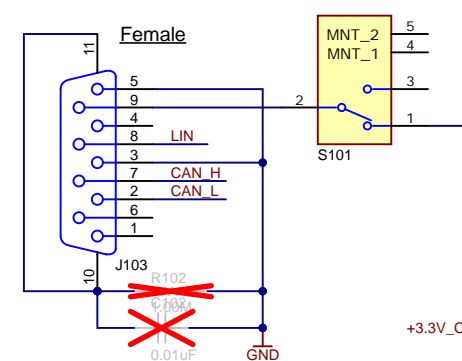


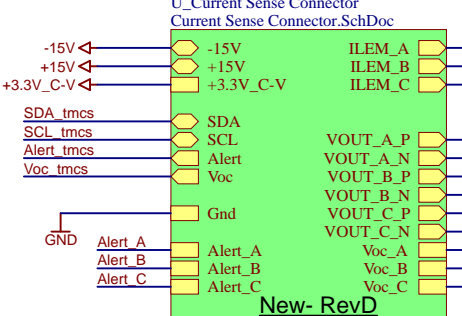
12-V input



Backup 12-V supply from DB9



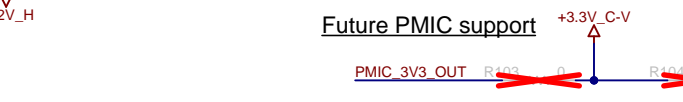
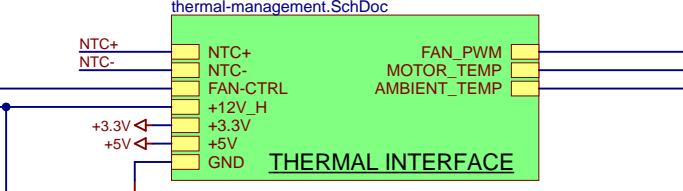
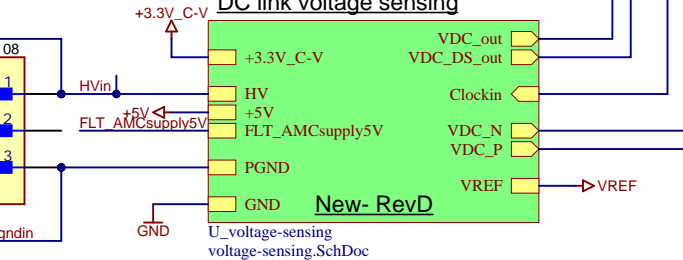
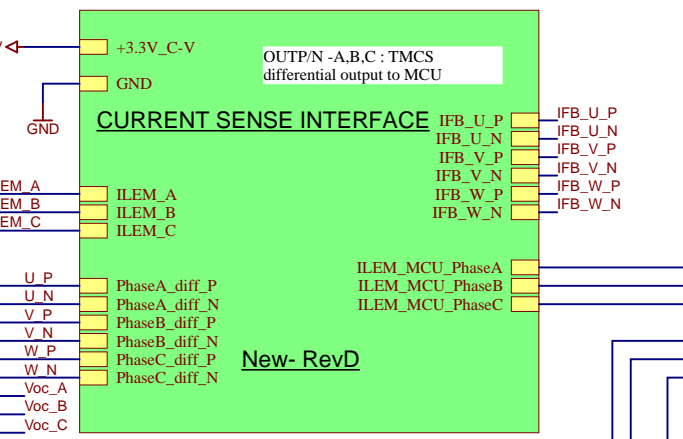
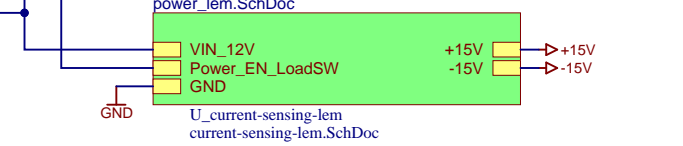
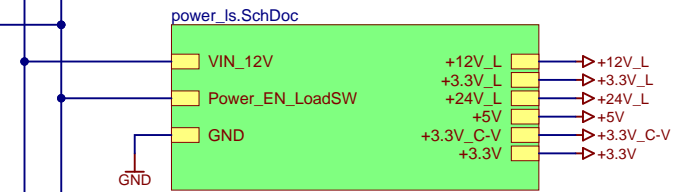
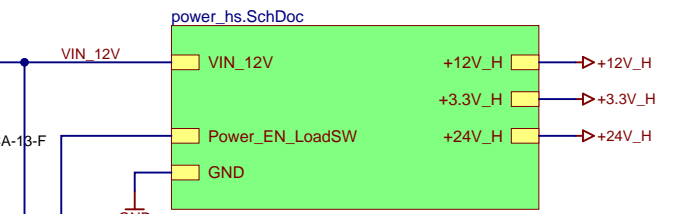
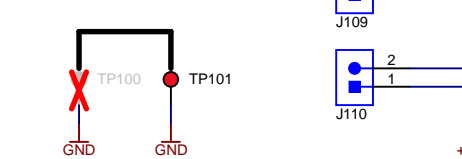
Current sensing (LEM)



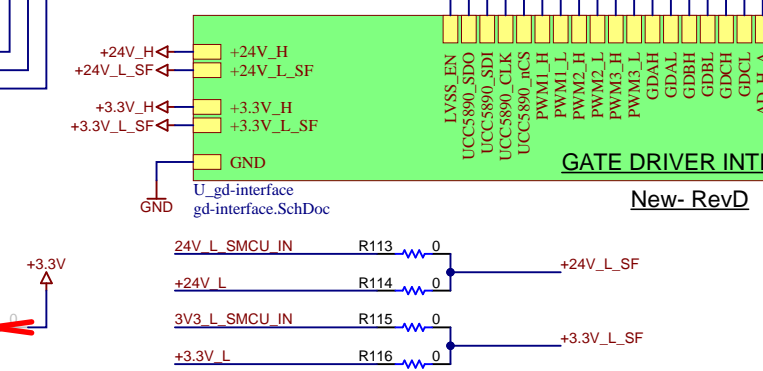
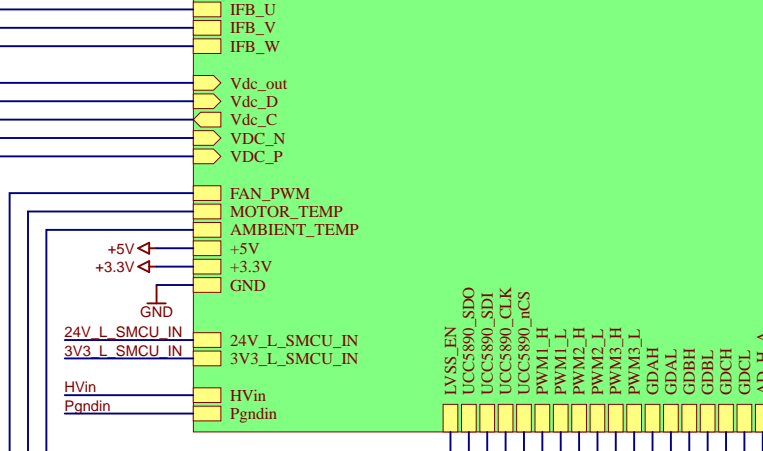
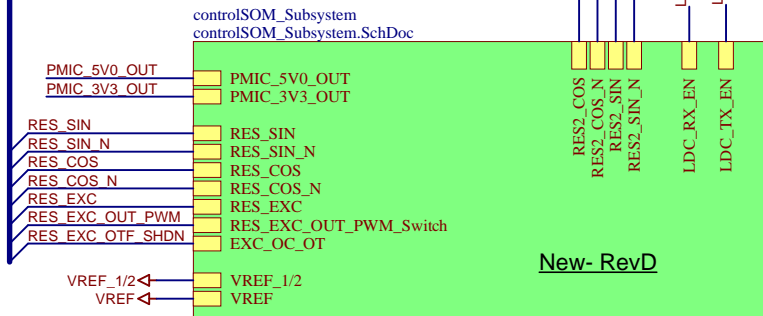
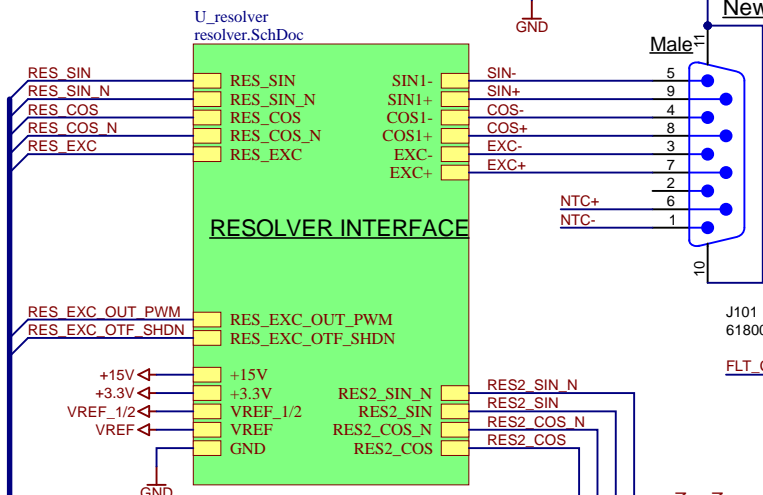
CURRENT SENSE CONNECTOR



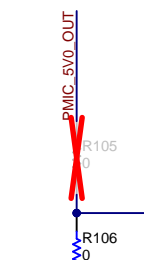
Grounding Bracket for Osci.



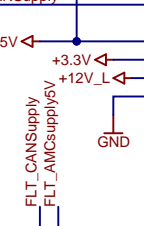
RevD CONTROL BOARD



New- RevD



can lin interface.SchDoc



LDC INTERFACE



New- RevD



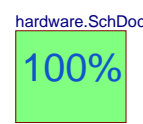
New- RevD



New- RevD



Revision History				
Rev	ECN #	Approved Date	Approved by	Notes
RevB	N/A	DEC-2022	H. Zhang, T.Urban	Project taken over by Panacek, Urban, Santrac
RevC	N/A	TBD		Sitara CC #1, Wake on CAN, AGDS, Wheelie
RevD	N/A			



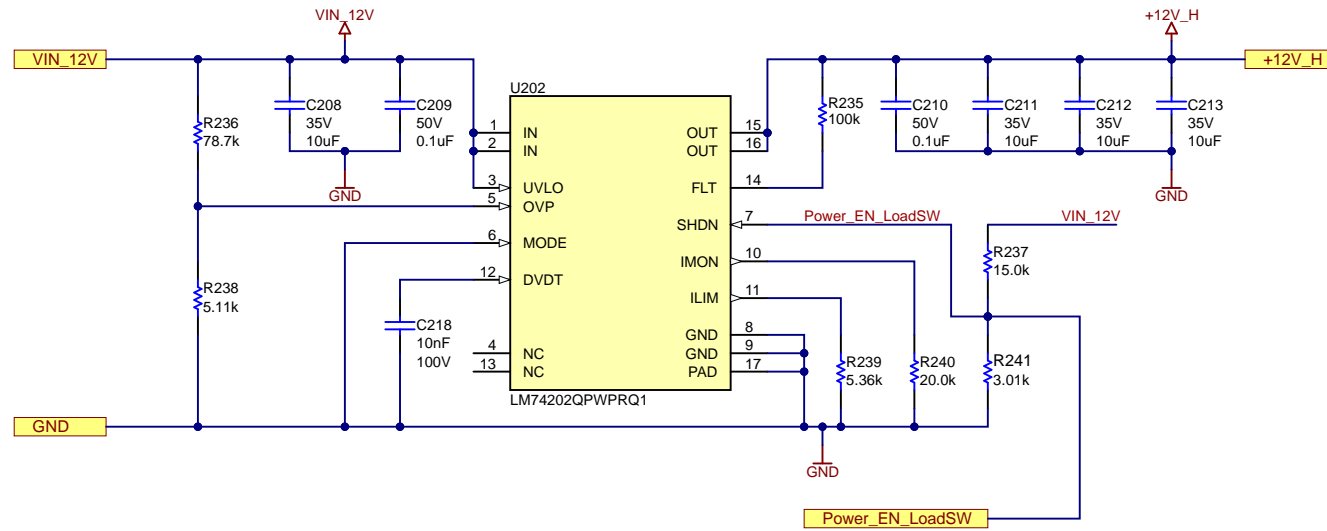
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TID #: <a href="https://www.ti.com/tool/TID0100">https://www.ti.com/tool/TID0100</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: Block diagram
SVN Rev: Not in version control	Assembly Variant: 001	Sheet 1 of 19
Drawn By: Shaurya, Masoud, Jiri	File: WS-inverter-control-brd-RevC-SEM-hierarchy_SchDoc	
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	

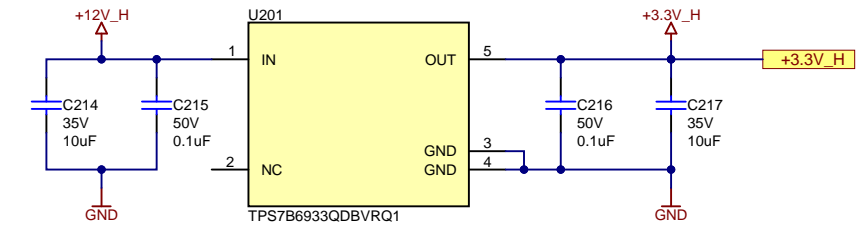


### High Side Power Rail

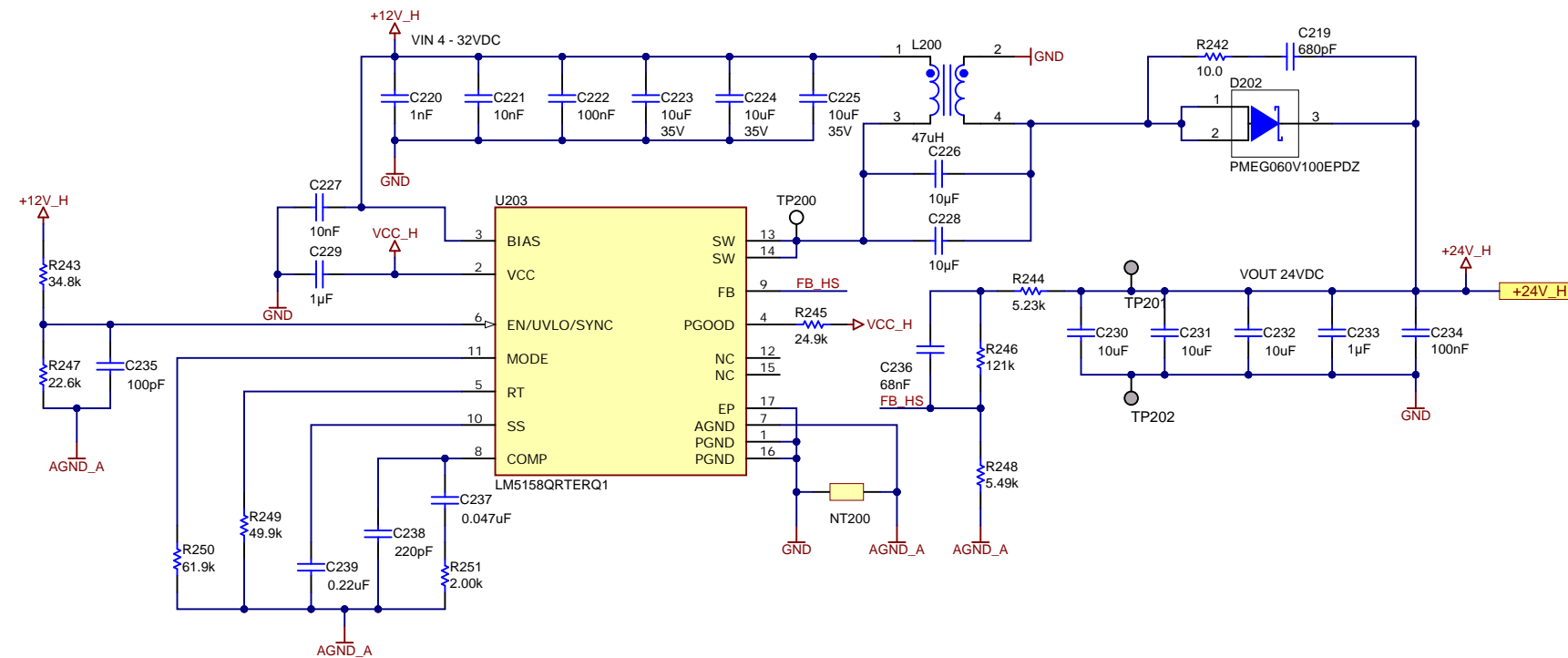
#### Ideal diode with integrated overvoltage and overcurrent protection



#### High-side logic power supply



#### Magneto MV (UCC14240-Q1) pre-regulator

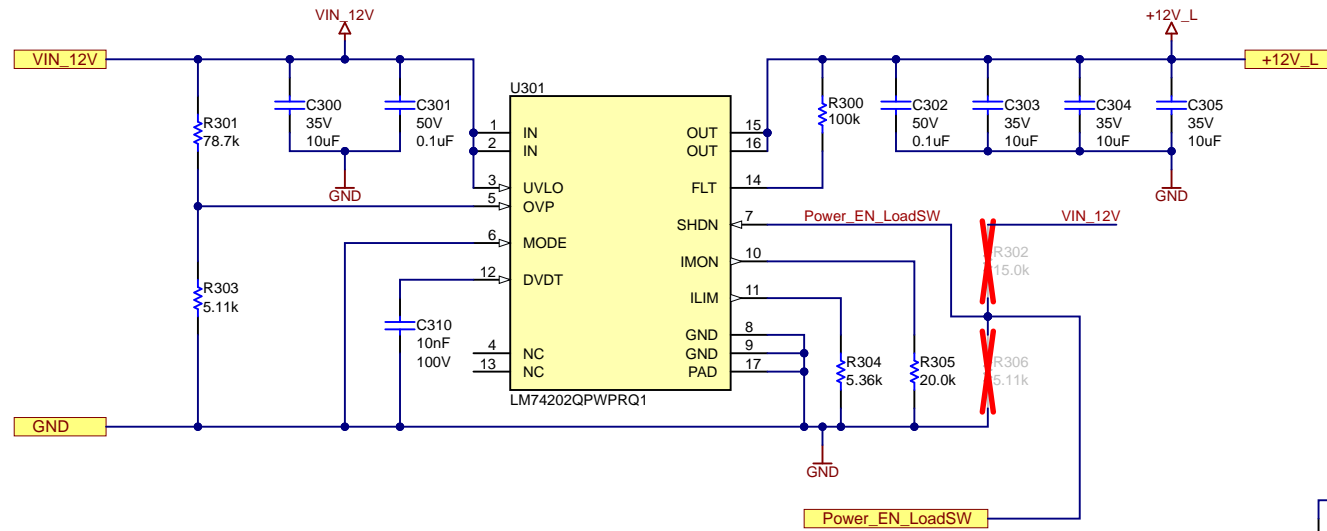


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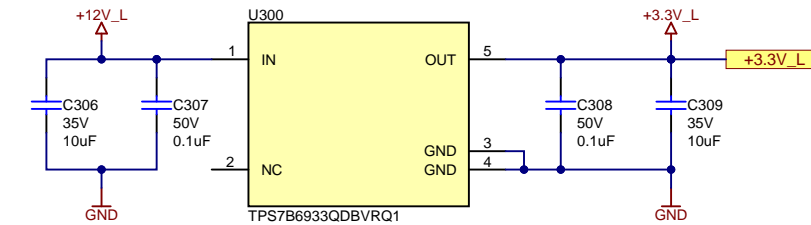
Orderable: N/A	Designed for: Public Release	Mod. Date: 1/14/2025
TID #: <a href="https://www.ti.com/tool/TIDR011">https://www.ti.com/tool/TIDR011</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: High-Side Power Rail
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 2 of 19
Drawn By: Panacek	File: power_hs.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	

Low Side Power Rail

Ideal diode with integrated overvoltage and overcurrent protection

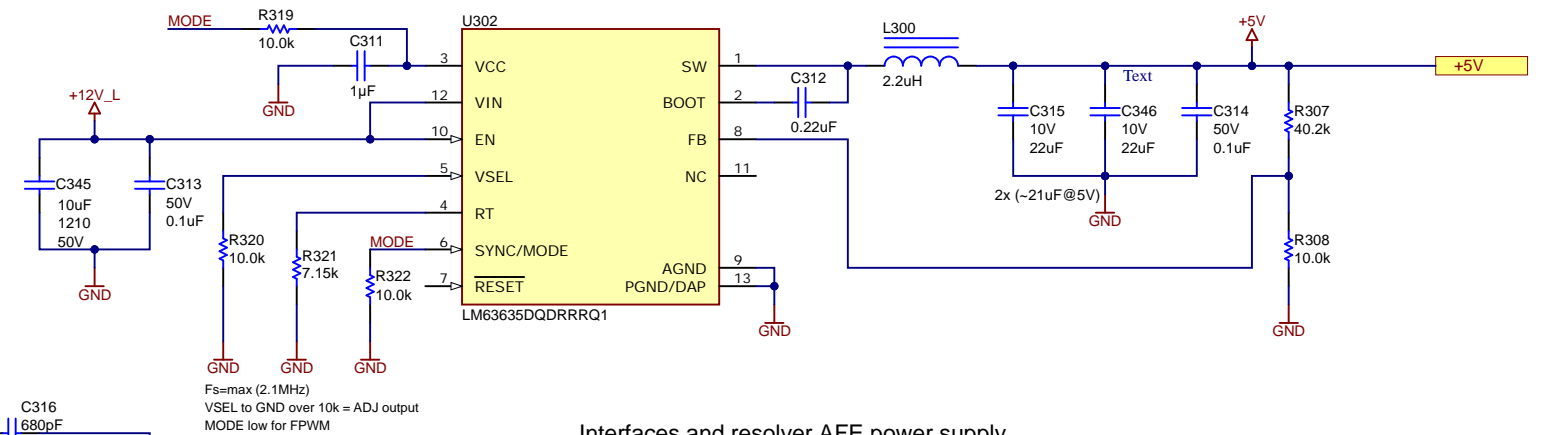


Low-side logic power supply

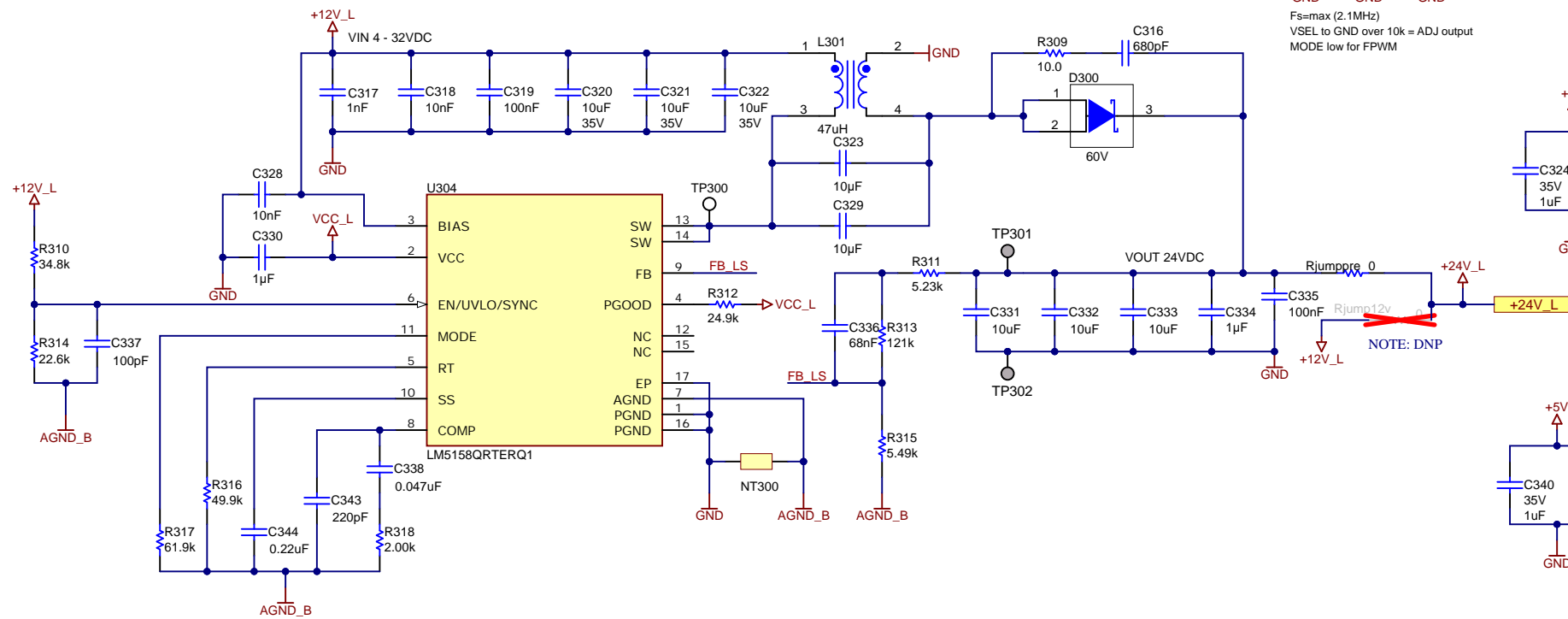


Controlcard and interfaces power supply

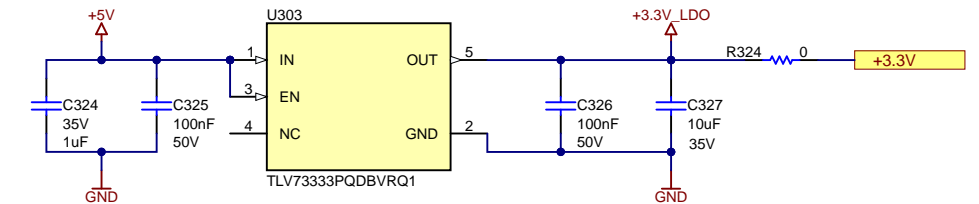
RevC Change: Swap from LMR50410Y5F (2.1MHz, Iout=1A, FPWM) to LM5365-Q1 (2MHz, Iout=3A, FPWM) - PMP30578  
 RevC Change: 5V has to be always available. Power\_EN\_LoadSW is now removed from the MCU and turns on load switches as soon as voltage reaches the threshold



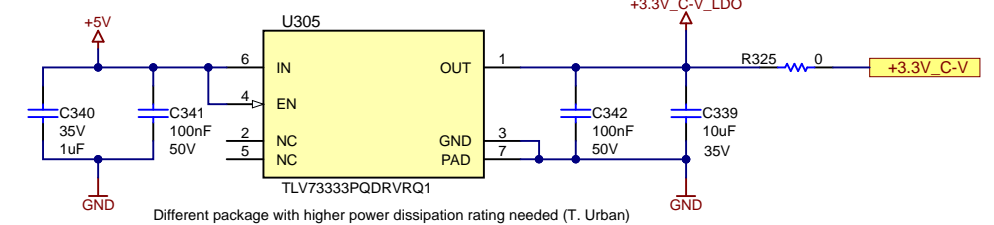
Magneto MV (UCC14240-Q1) pre-regulator



Interfaces and resolver AFE power supply



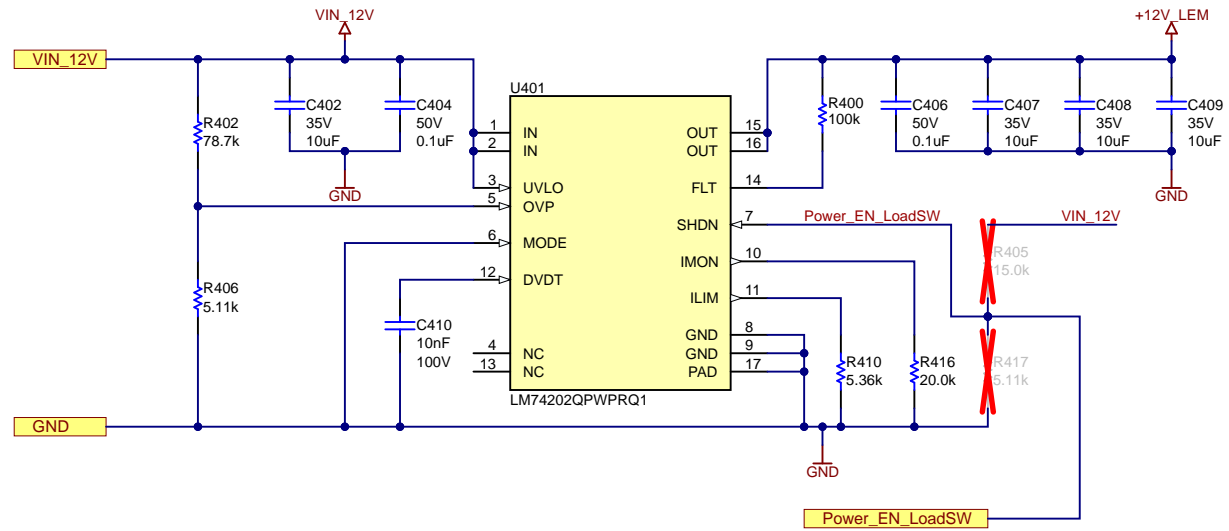
Voltage and current sensing power supply



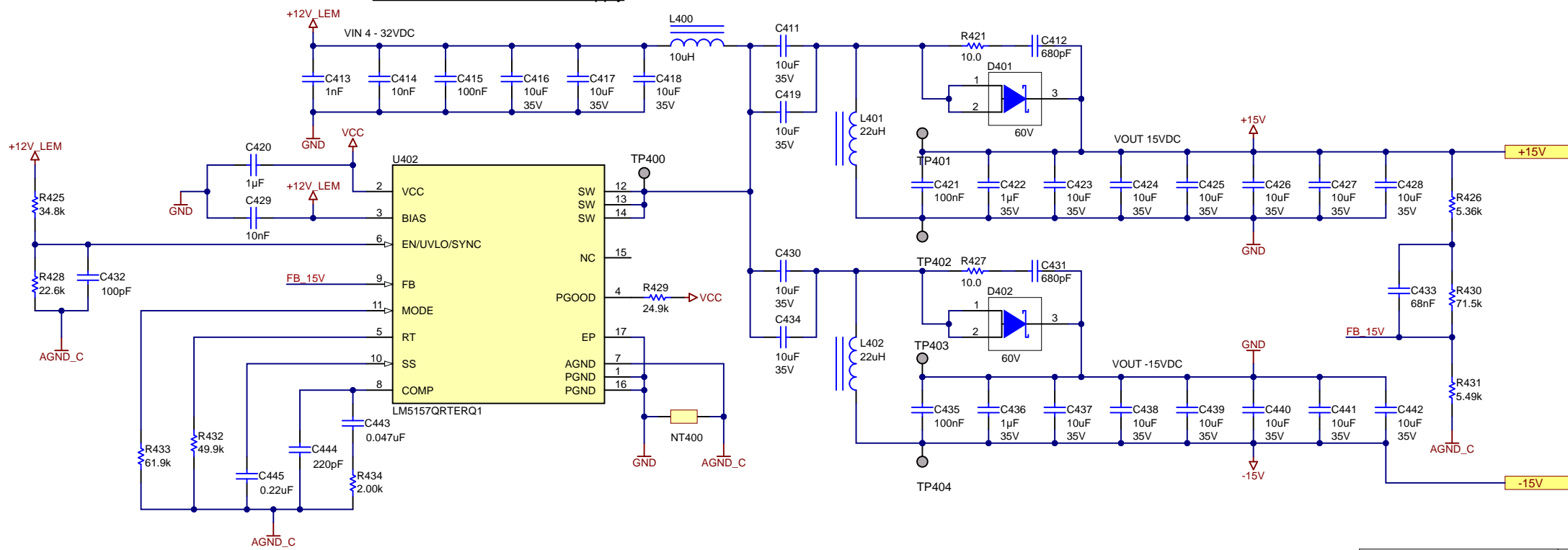
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Number: N/A	Rev: RevD	Sheet Title: Low-Side Power Rail
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 3 of 19
Drawn By: Panacek	File: power_ls.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	

Ideal diode with integrated overvoltage and overcurrent protection



LEM current sensor +/-15V supply



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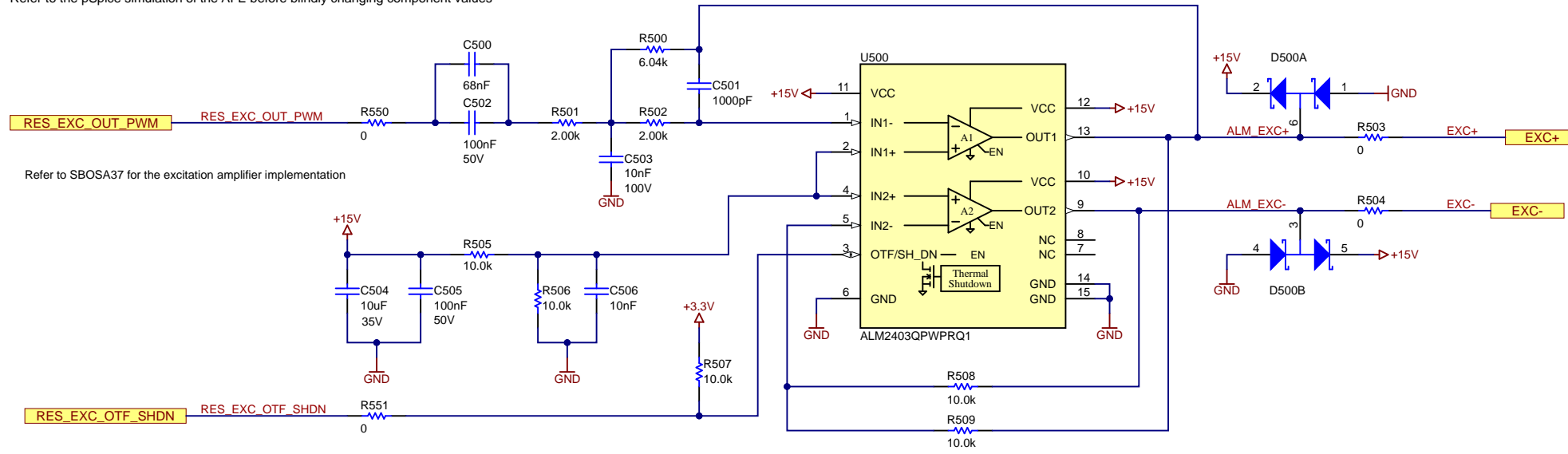
Orderable: N/A	Designed for: Public Release	Mod. Date: 1/14/2025
TID #: <a href="https://www.ti.com/tool/TID01000">https://www.ti.com/tool/TID01000</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: LEM sensors power supply
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 4 of 19
Drawn By: Panacek	File: power_lem.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	



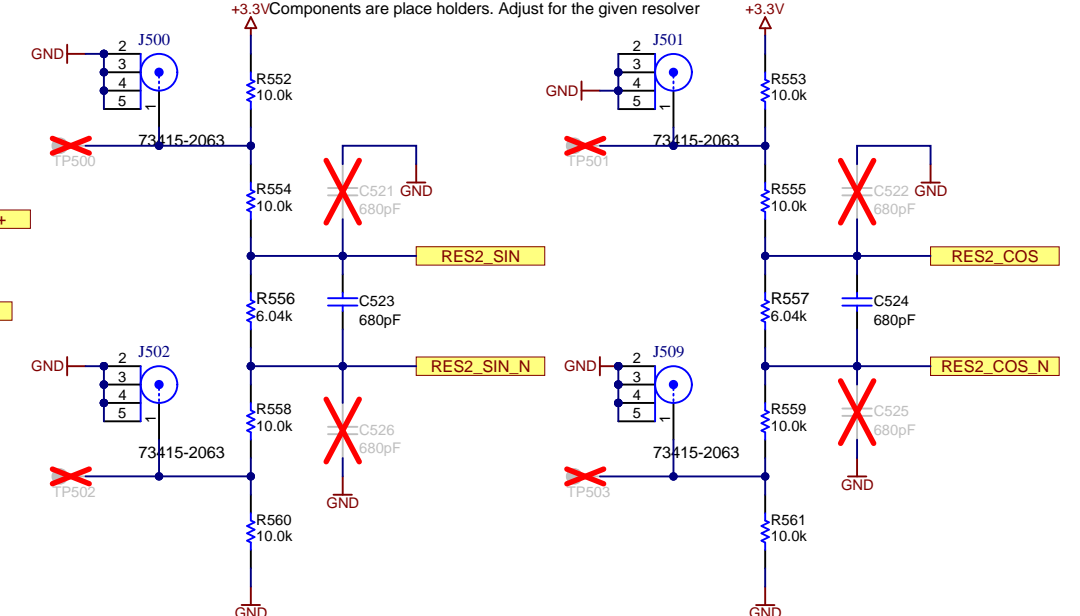
**IMPORTANT NOTES:**

Resolver sub-system optimized for 7-Vrms 10kHz resolvers  
 The current resolver sub-system does not support any additional diagnostic features  
 0-ohm resistors and MMCX connectors allow for single-ended & differential resolver testing with AM263p on both channels  
 Refer to the pSpice simulation of the AFE before blindly changing component values

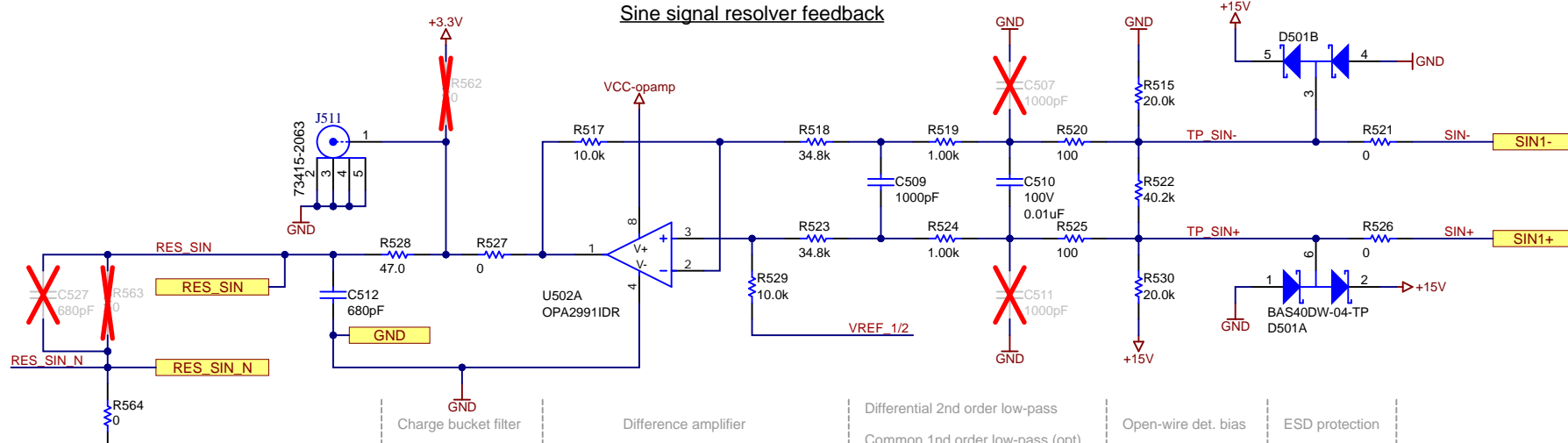
**Excitation amplifier**



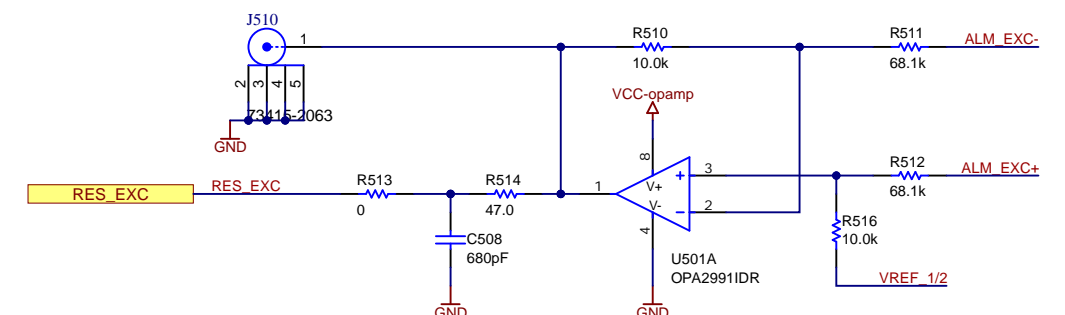
**AM263P differential resolver2 AFE support**



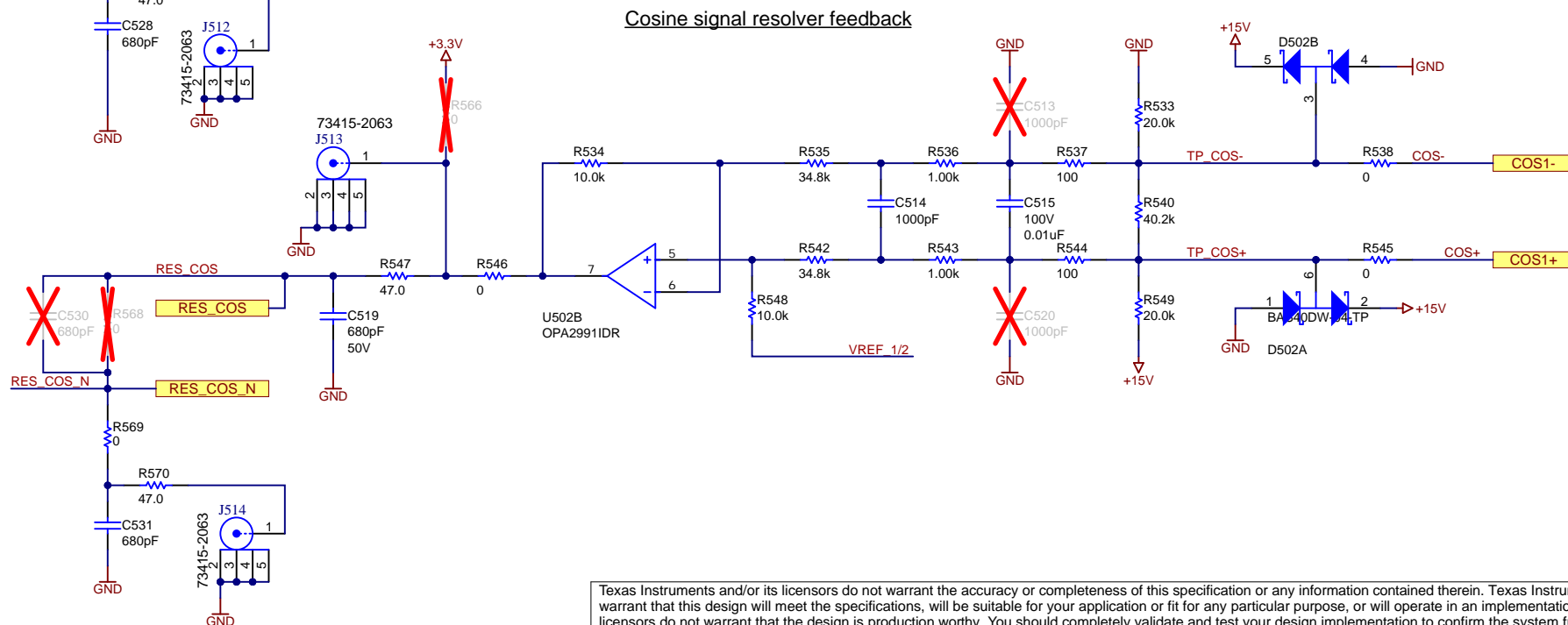
**Sine signal resolver feedback**



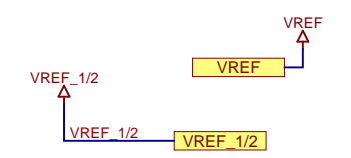
**Excitation amplifier feedback sensing (optional)**



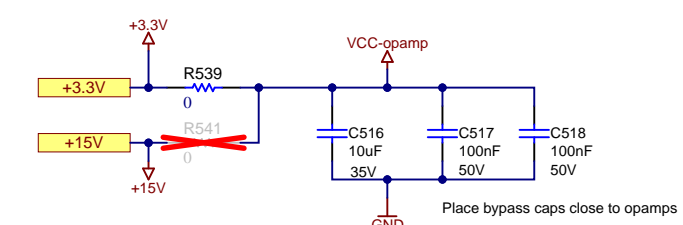
**Cosine signal resolver feedback**



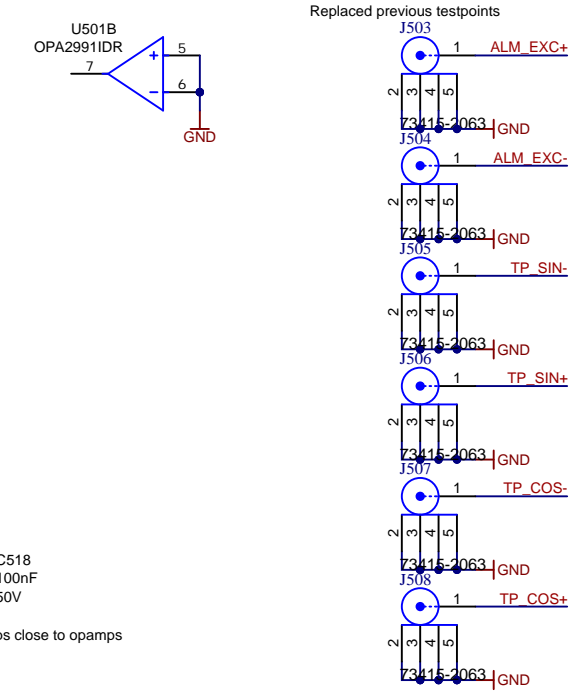
**DC offset (50% of the Vref)**



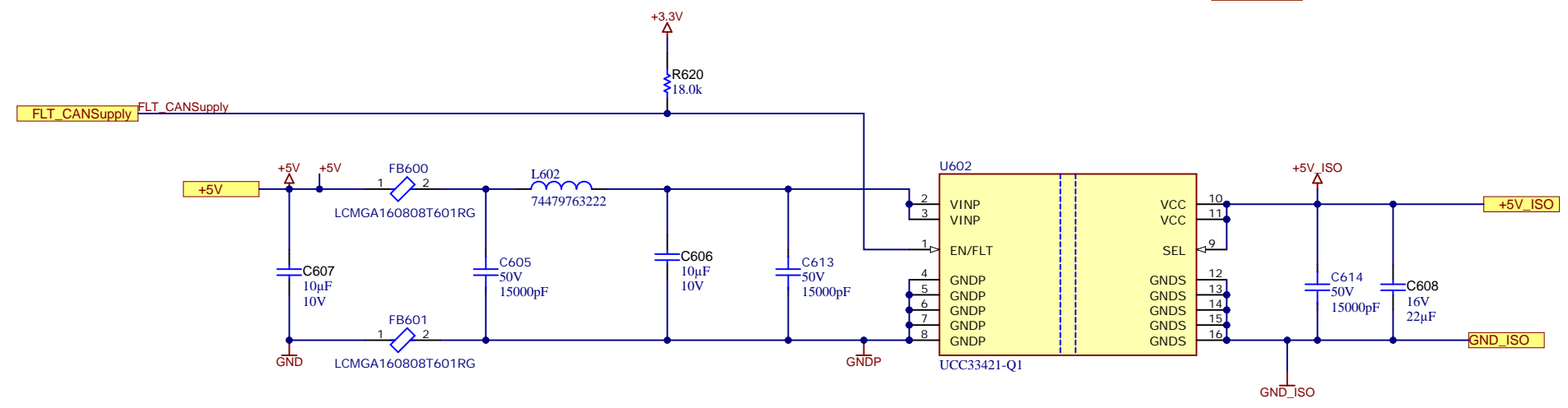
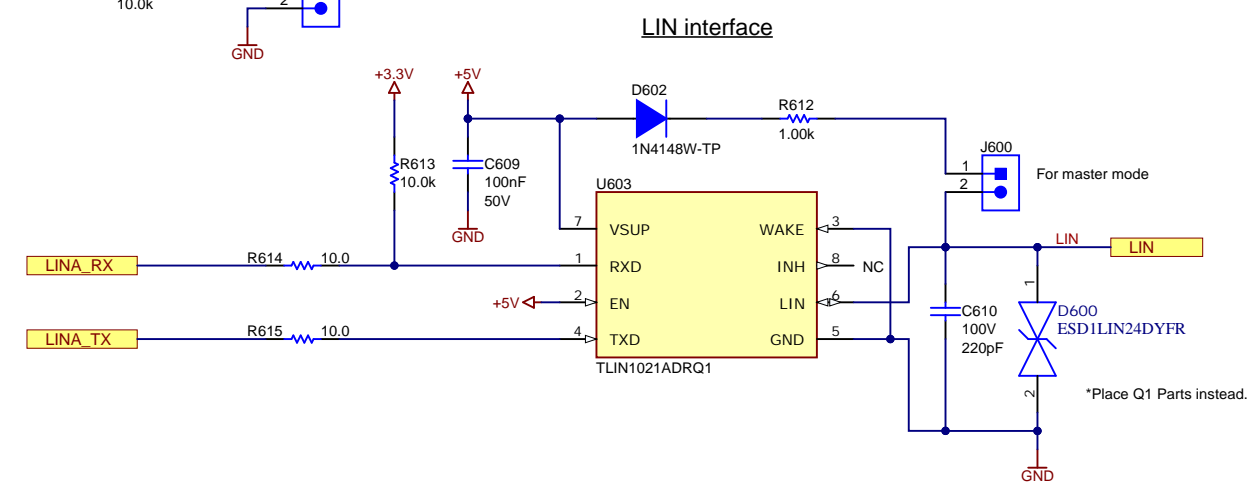
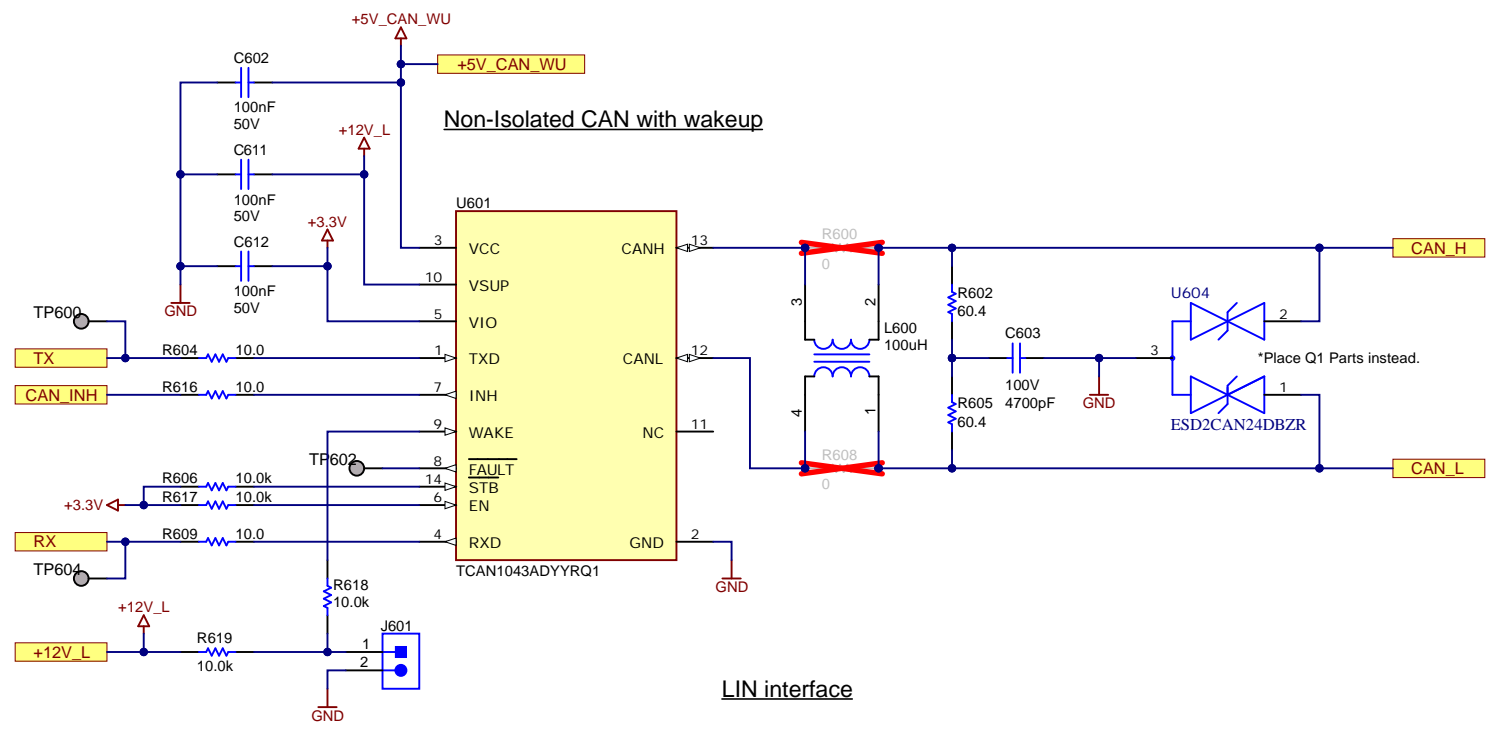
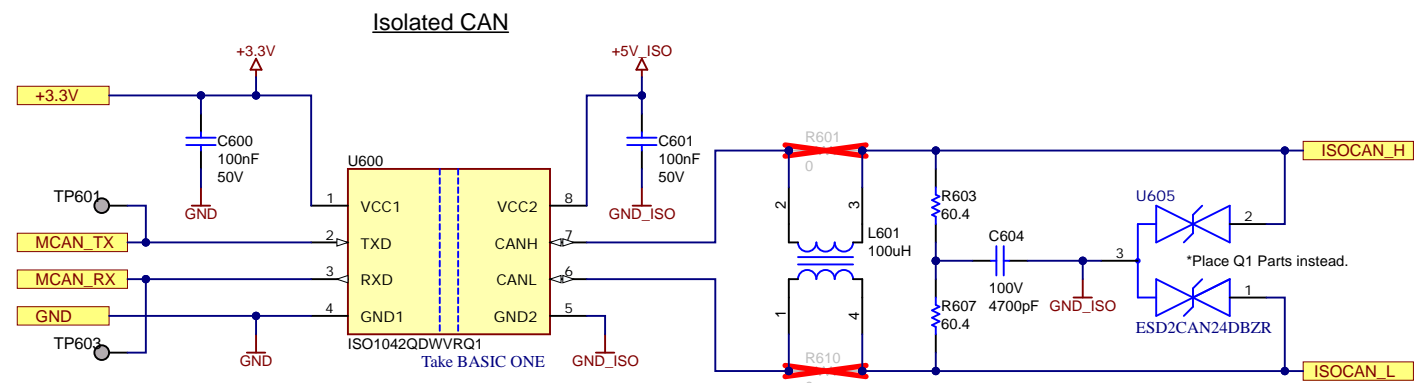
**AFE power supply selection (3.3V default)**



**Test MMCX (rq. H. Zhang)**



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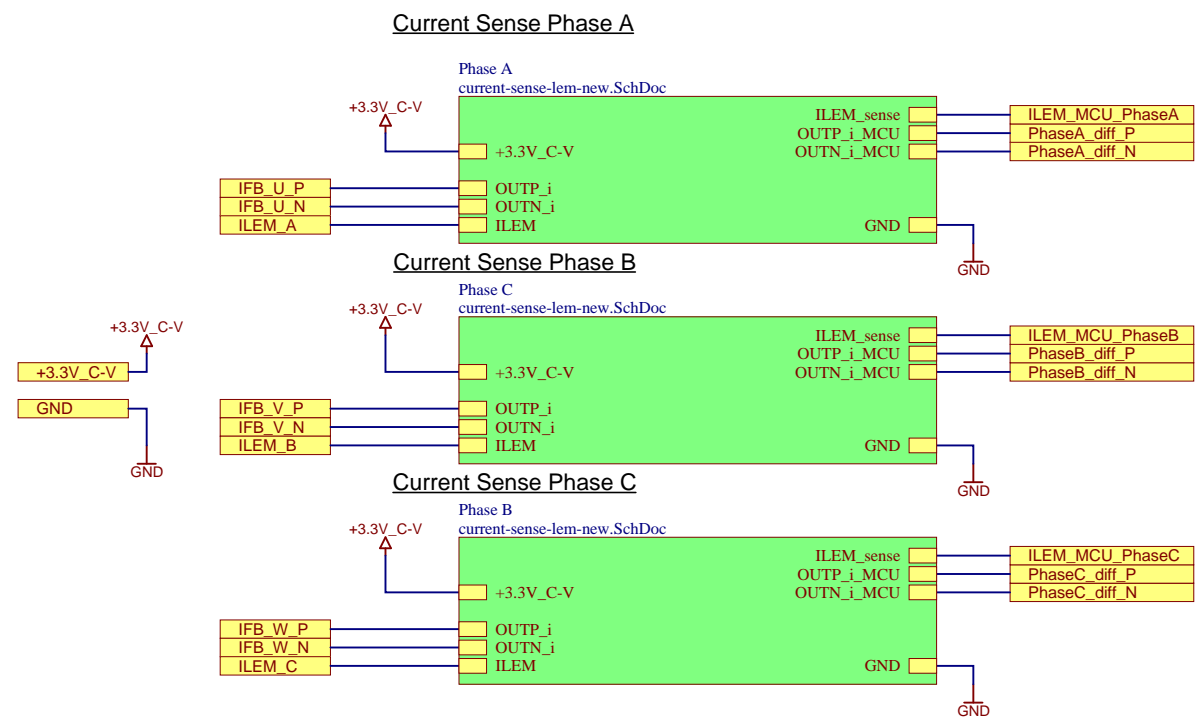
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TID #: <a href="https://www.ti.com/tool/TID0111">https://www.ti.com/tool/TID0111</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: Communication Interfaces
SVN Rev: Not in version control	Assembly Variant: 001	Sheet 6 of 19
Drawn By: Panacek	File: can_lin_interface.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	



**IMPORTANT NOTES:**

This circuit re-uses the original Wolfspeed circuitry. It would be better to use a device such INA296A (soon Q1)



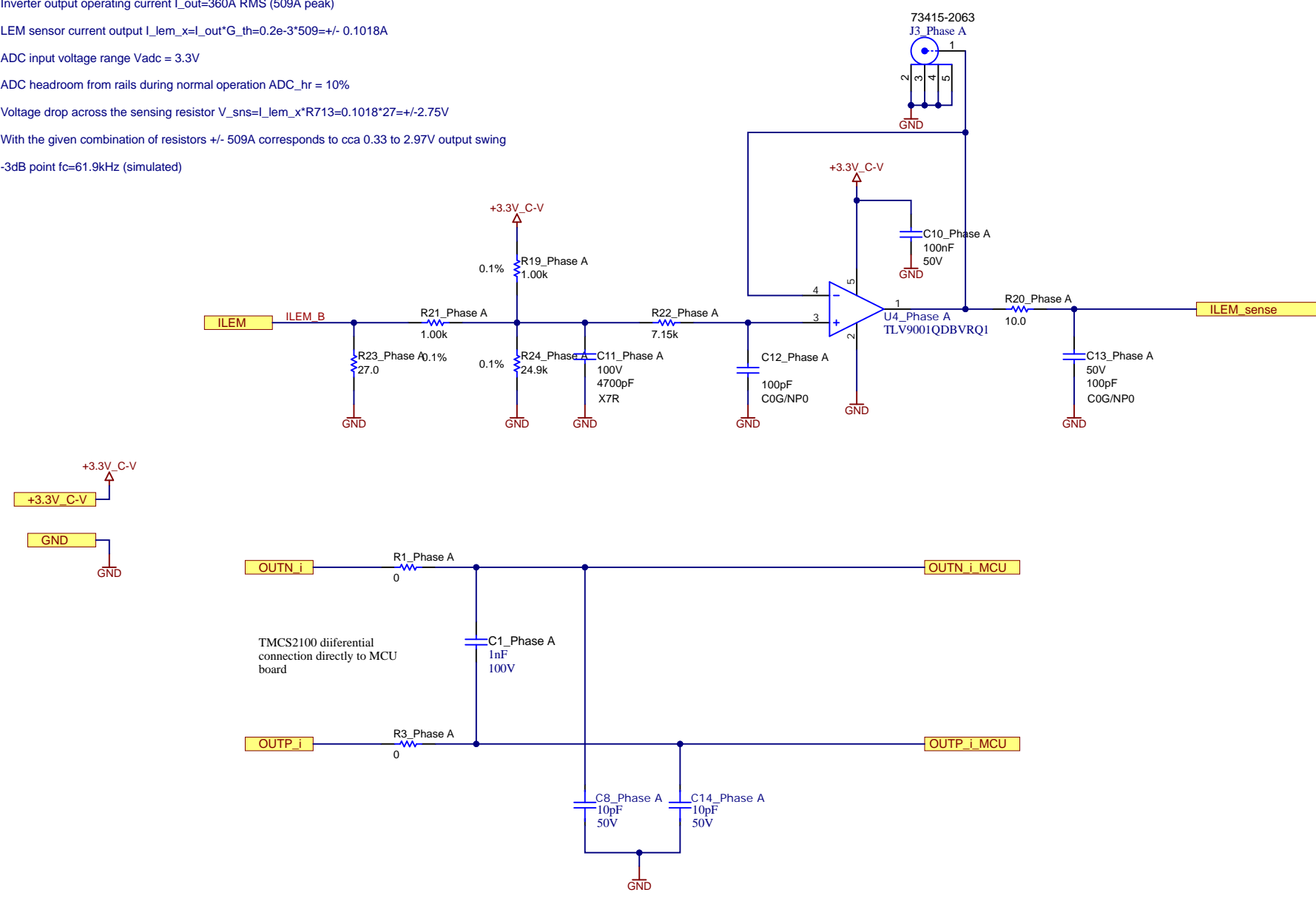
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TID #: <a href="https://www.ti.com/tool/TID0111">https://www.ti.com/tool/TID0111</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: Current Sensing Front-End
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 7 of 19
Drawn By: Panacek	File: current-sensing-lem.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	





LEM LF510 current output with  $G_{th}=0.2\text{mA/A}$   
 Inverter output operating current  $I_{out}=360\text{A RMS (509A peak)}$   
 LEM sensor current output  $I_{lem\_x}=I_{out}*G_{th}=0.2e-3*509=\pm 0.1018\text{A}$   
 ADC input voltage range  $V_{adc} = 3.3\text{V}$   
 ADC headroom from rails during normal operation  $ADC_{hr} = 10\%$   
 Voltage drop across the sensing resistor  $V_{sns}=I_{lem\_x}*R_{713}=0.1018*27=\pm 2.75\text{V}$   
 With the given combination of resistors  $\pm 509\text{A}$  corresponds to cca 0.33 to 2.97V output swing  
 -3dB point  $f_c=61.9\text{kHz}$  (simulated)



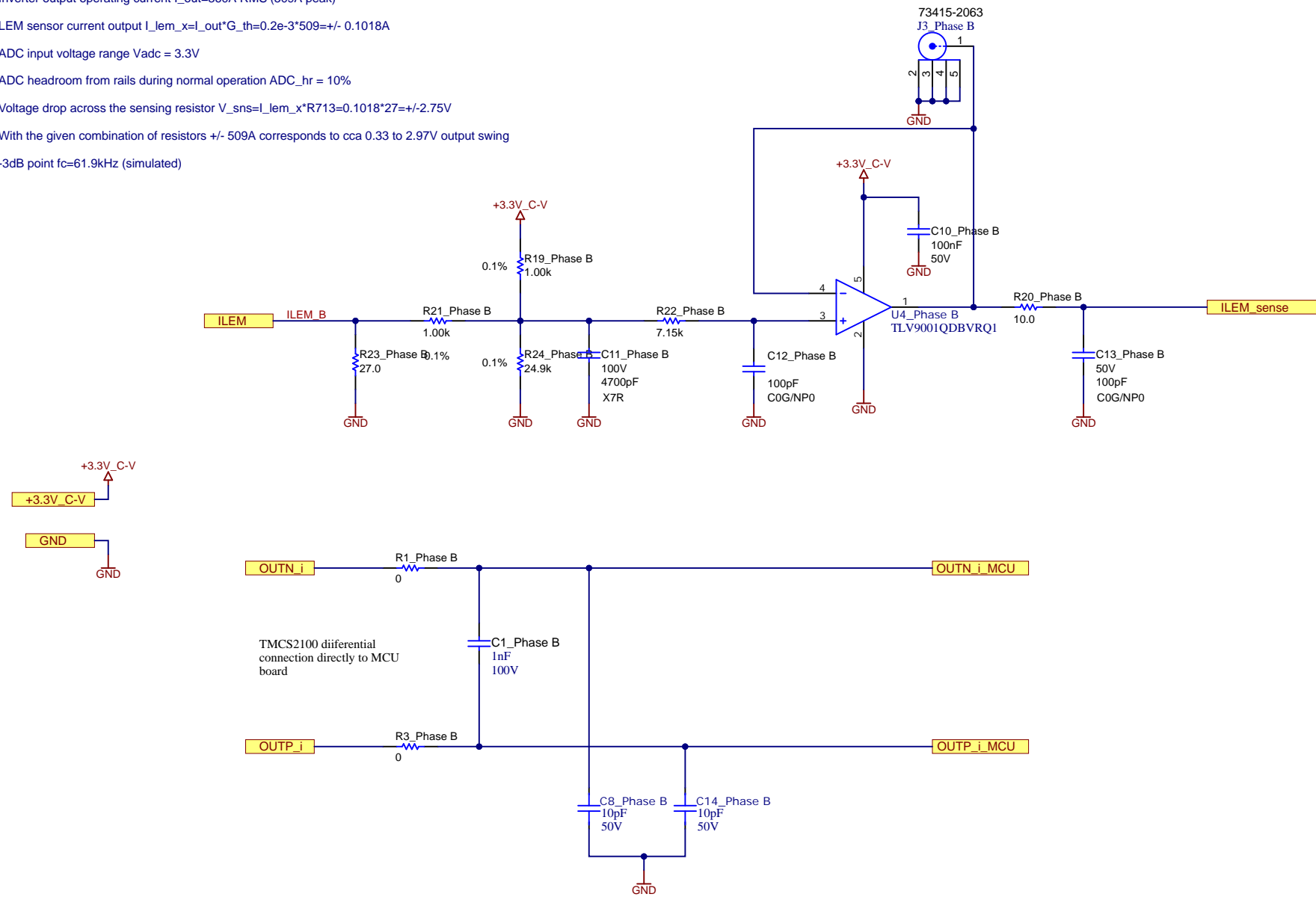
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TID #: <a href="https://www.ti.com/tool/TIDR011">https://www.ti.com/tool/TIDR011</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title:
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 8 of 19
Drawn By:	File: current-sense-lem-new.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	





LEM LF510 current output with  $G_{th}=0.2mA/A$   
 Inverter output operating current  $I_{out}=360A$  RMS (509A peak)  
 LEM sensor current output  $I_{lem\_x}=I_{out}*G_{th}=0.2e-3*509=\pm 0.1018A$   
 ADC input voltage range  $V_{adc} = 3.3V$   
 ADC headroom from rails during normal operation  $ADC_{hr} = 10\%$   
 Voltage drop across the sensing resistor  $V_{sns}=I_{lem\_x}*R_{713}=\pm 0.1018*27=\pm 2.75V$   
 With the given combination of resistors  $\pm 509A$  corresponds to cca 0.33 to 2.97V output swing  
 -3dB point  $f_c=61.9kHz$  (simulated)

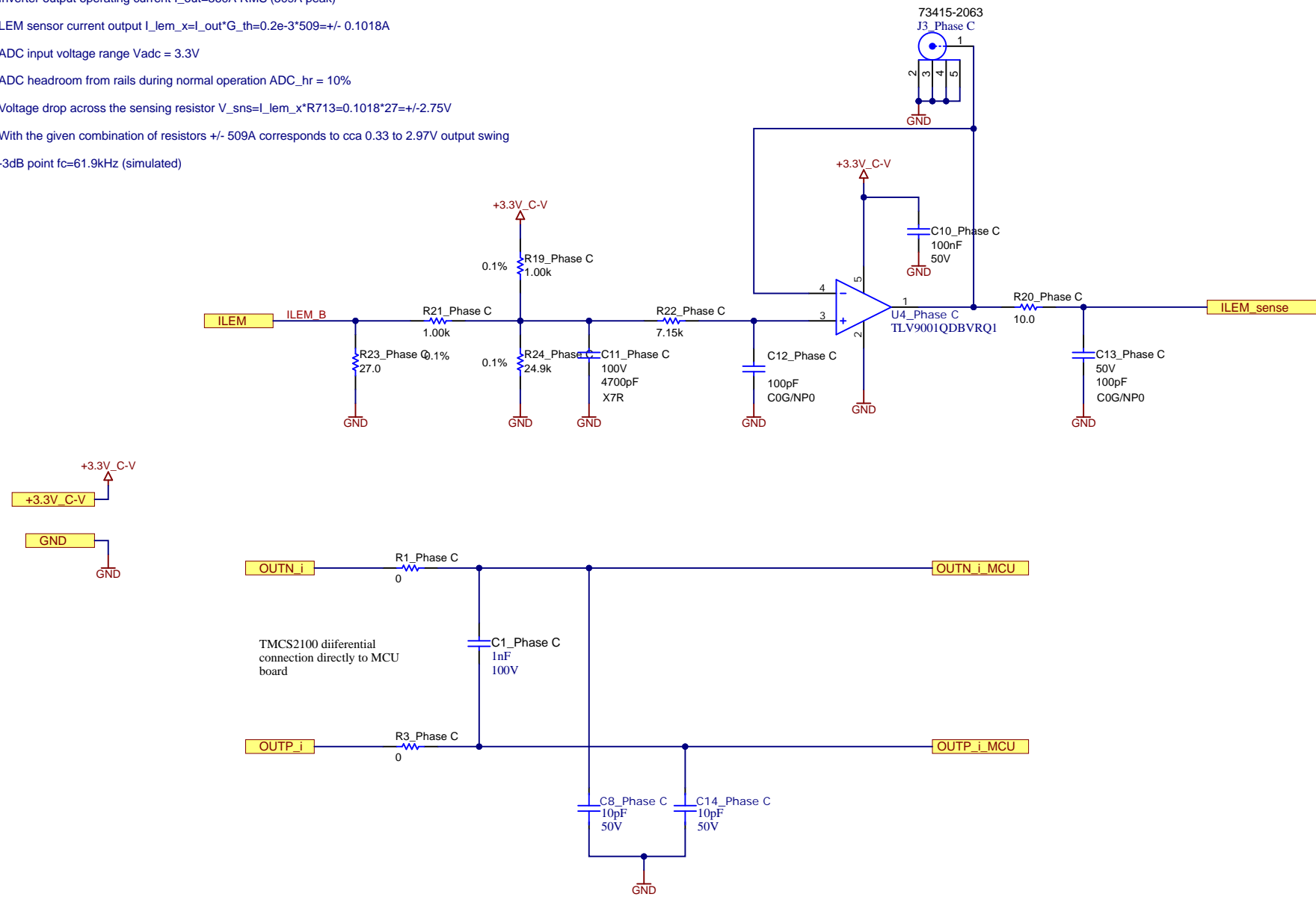


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TID #: <a href="https://www.ti.com/tool/TID017">https://www.ti.com/tool/TID017</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title:
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 8 of 19
Drawn By:	File: current-sense-lem-new.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	



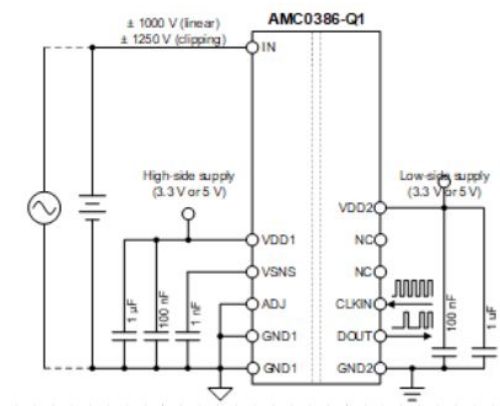
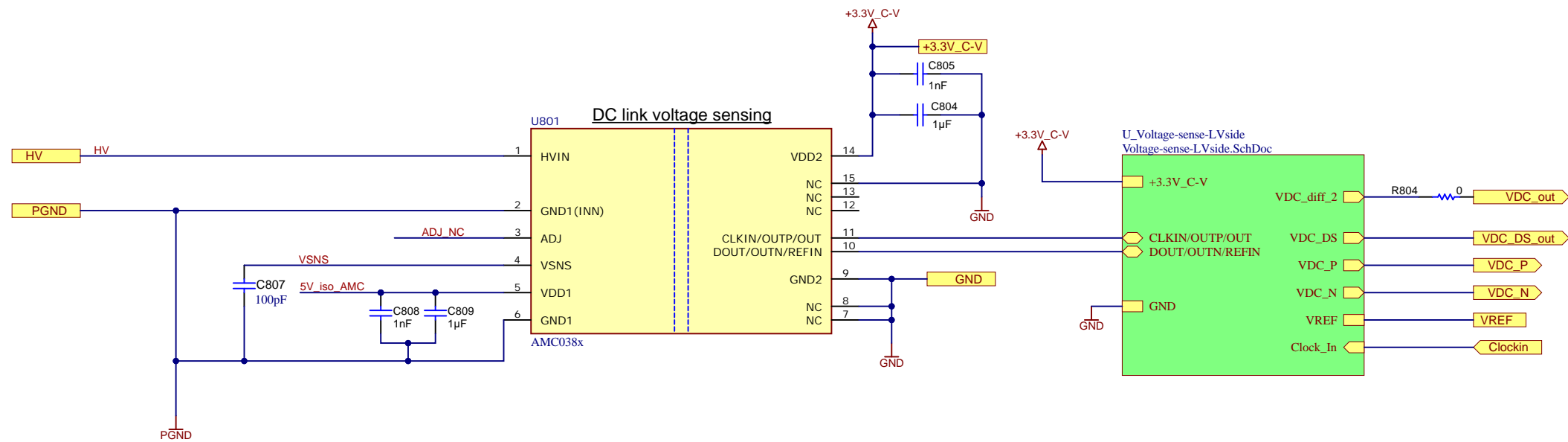
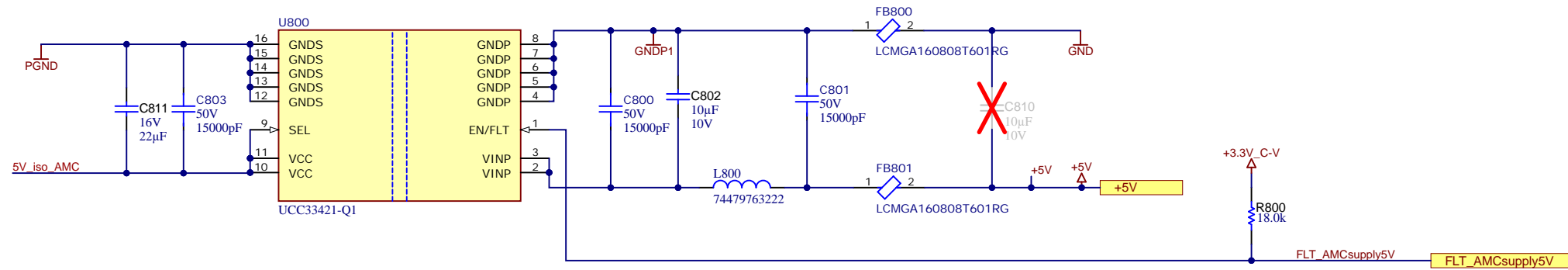
LEM LF510 current output with  $G_{th}=0.2\text{mA/A}$   
 Inverter output operating current  $I_{out}=360\text{A RMS (509A peak)}$   
 LEM sensor current output  $I_{lem\_x}=I_{out}*G_{th}=0.2e-3*509=\pm 0.1018\text{A}$   
 ADC input voltage range  $V_{adc} = 3.3\text{V}$   
 ADC headroom from rails during normal operation  $ADC_{hr} = 10\%$   
 Voltage drop across the sensing resistor  $V_{sns}=I_{lem\_x}*R_{713}=0.1018*27=\pm 2.75\text{V}$   
 With the given combination of resistors  $\pm 509\text{A}$  corresponds to cca  $0.33$  to  $2.97\text{V}$  output swing  
 $-3\text{dB point } f_c=61.9\text{kHz (simulated)}$



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TID #: <a href="https://www.ti.com/tool/TID641">https://www.ti.com/tool/TID641</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title:
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 8 of 19
Drawn By:	File: current-sense-lem-new.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	





Orderable: N/A	Designed for: Public Release	Mod. Date: 4/17/2025
TID #: <a href="https://www.ti.com/tool/TIDR011">https://www.ti.com/tool/TIDR011</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: HV Sensing
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 9 of 19
Drawn By: Panacek	File: voltage-sensing.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	

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A

B

C

D

A

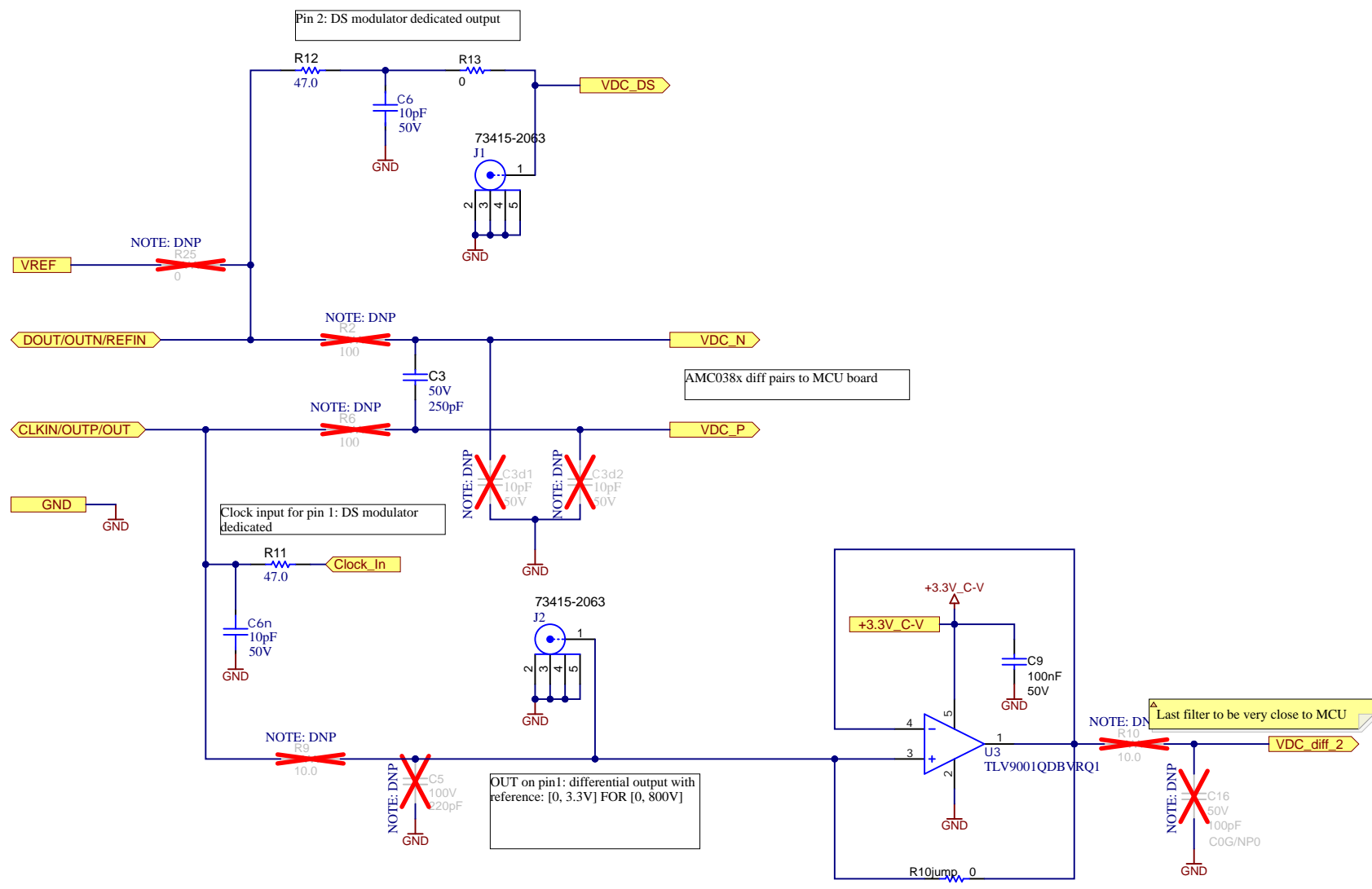
B

C

D

**\*\*Use the port and wire it directly. Make a note detailed.**

OUTP and OUTN differential outputs towards an op-amp to gain 1 output. Range: [0, 3.3V] for [0, 800V]

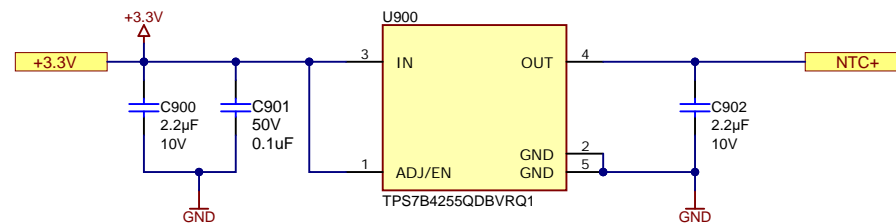


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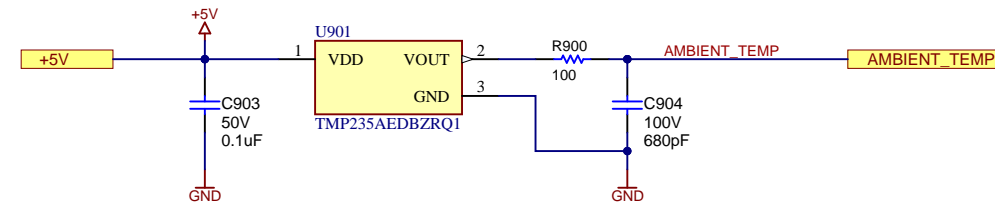
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TID #: <a href="https://www.ti.com/tool/TID01000">https://www.ti.com/tool/TID01000</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title:
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 10 of 19
Drawn By:	File: Voltage-sense-LVside.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	



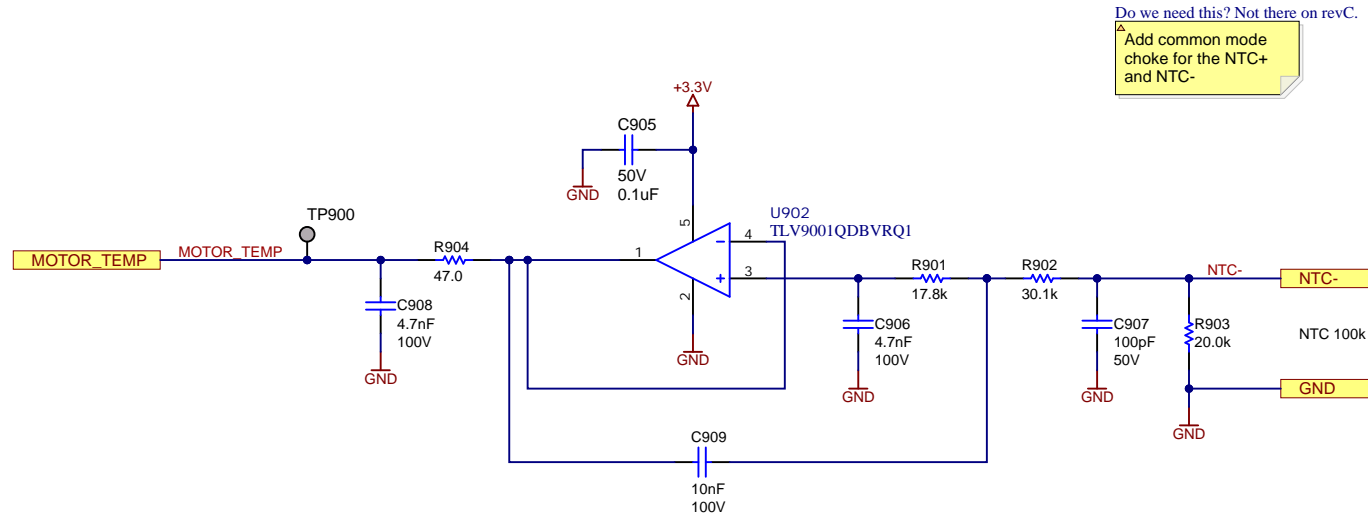
Tracking LDO for protecting the NTC excitation



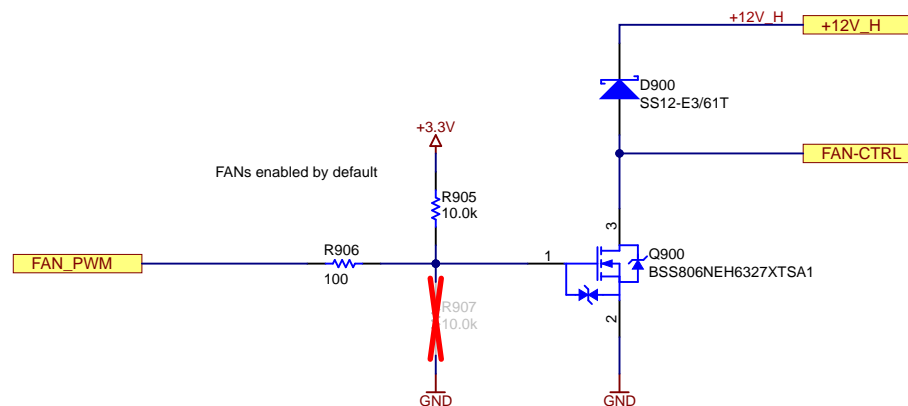
Ambient temperature sensing



Motor temperature sensing



Cooling FANs speed control



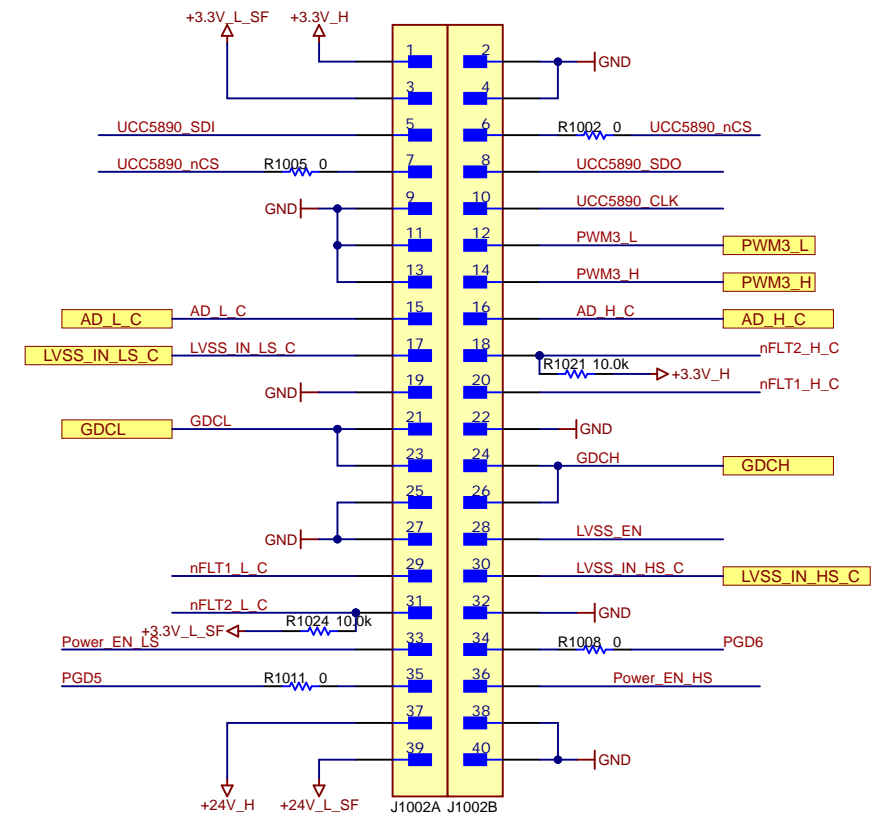
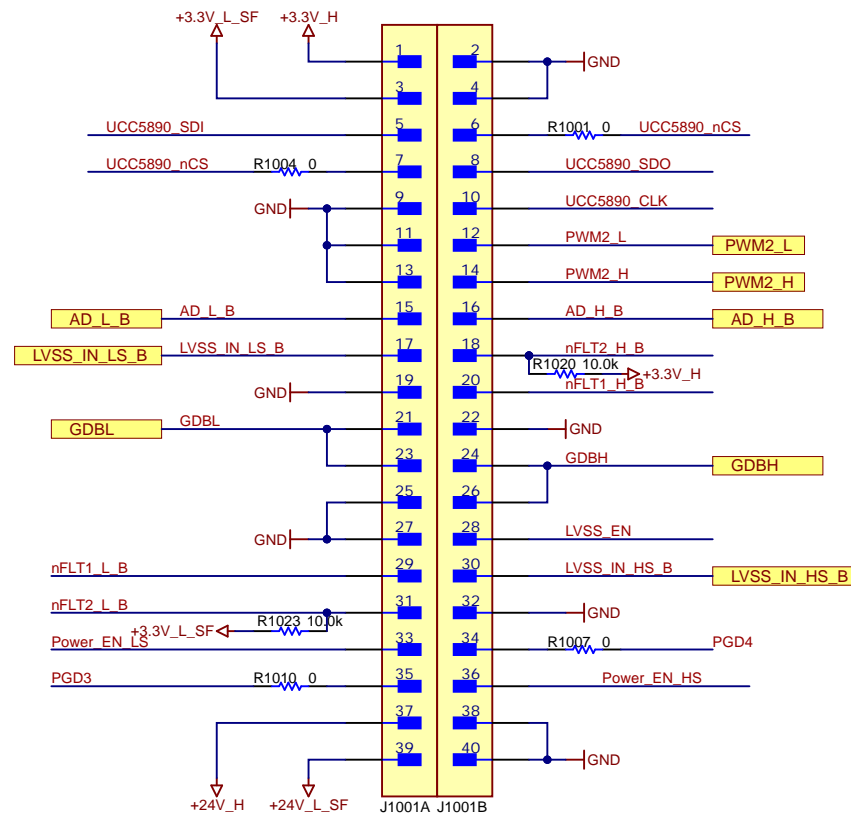
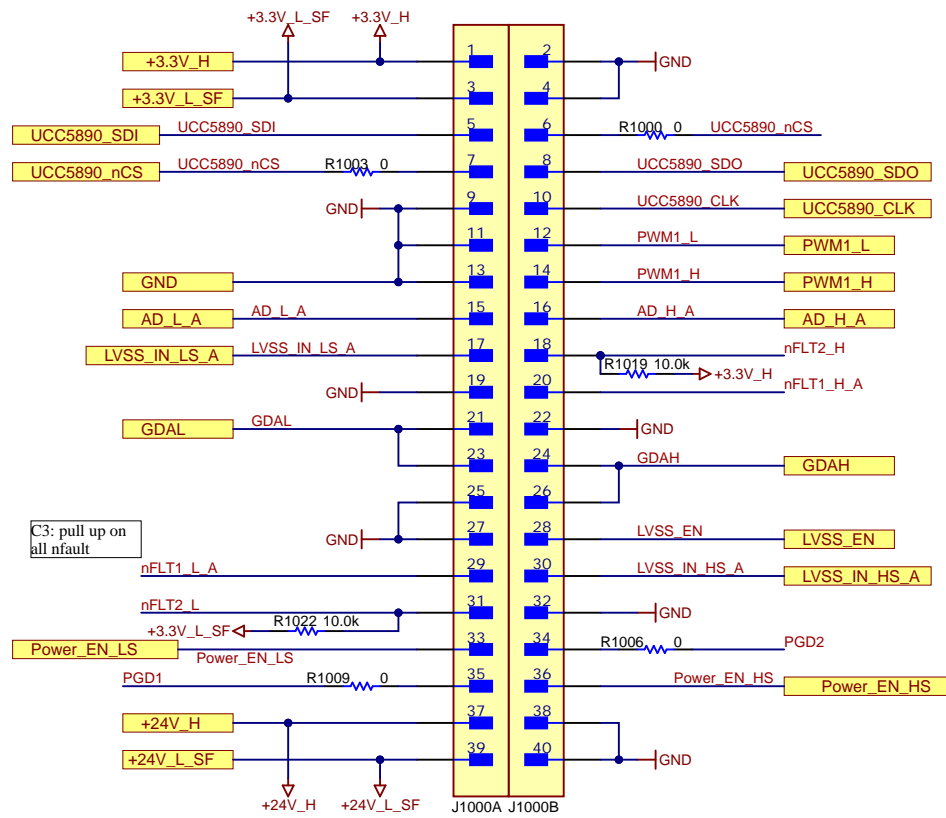
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TID #: <a href="https://www.ti.com/tool/TID00000111">https://www.ti.com/tool/TID00000111</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: Thermal Management
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 11 of 19
Drawn By: Panacek	File: thermal-management.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	

Interface to the GD board - PHASE A

Interface to the GD board - PHASE B

Interface to the GD board - PHASE C



Cable: FFSD-20-D-02.00-01-N

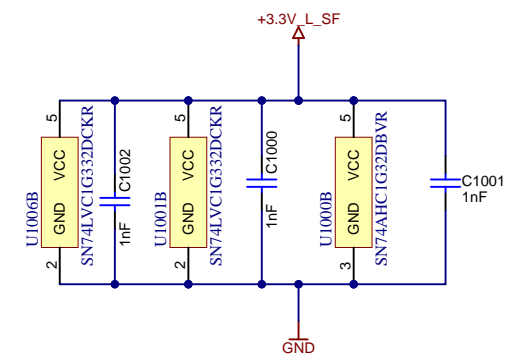
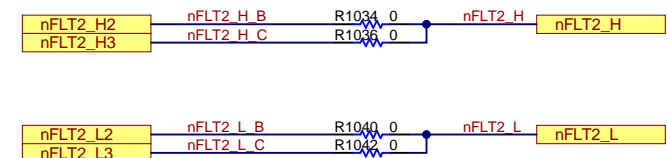
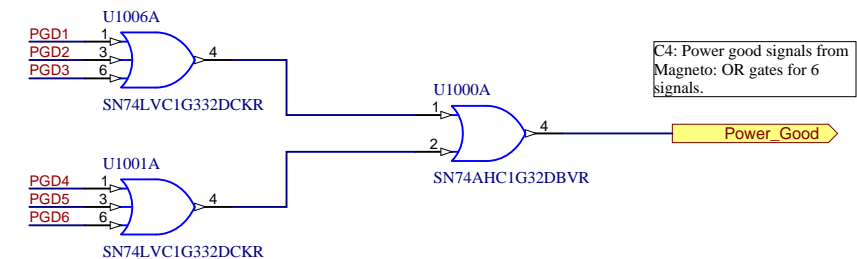
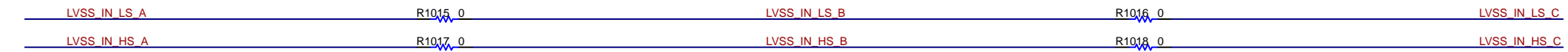
Cable: FFSD-20-D-02.00-01-N

Cable: FFSD-20-D-02.00-01-N

GDAL R1013 0 GDAH

GDBL R1014 0 GDBH

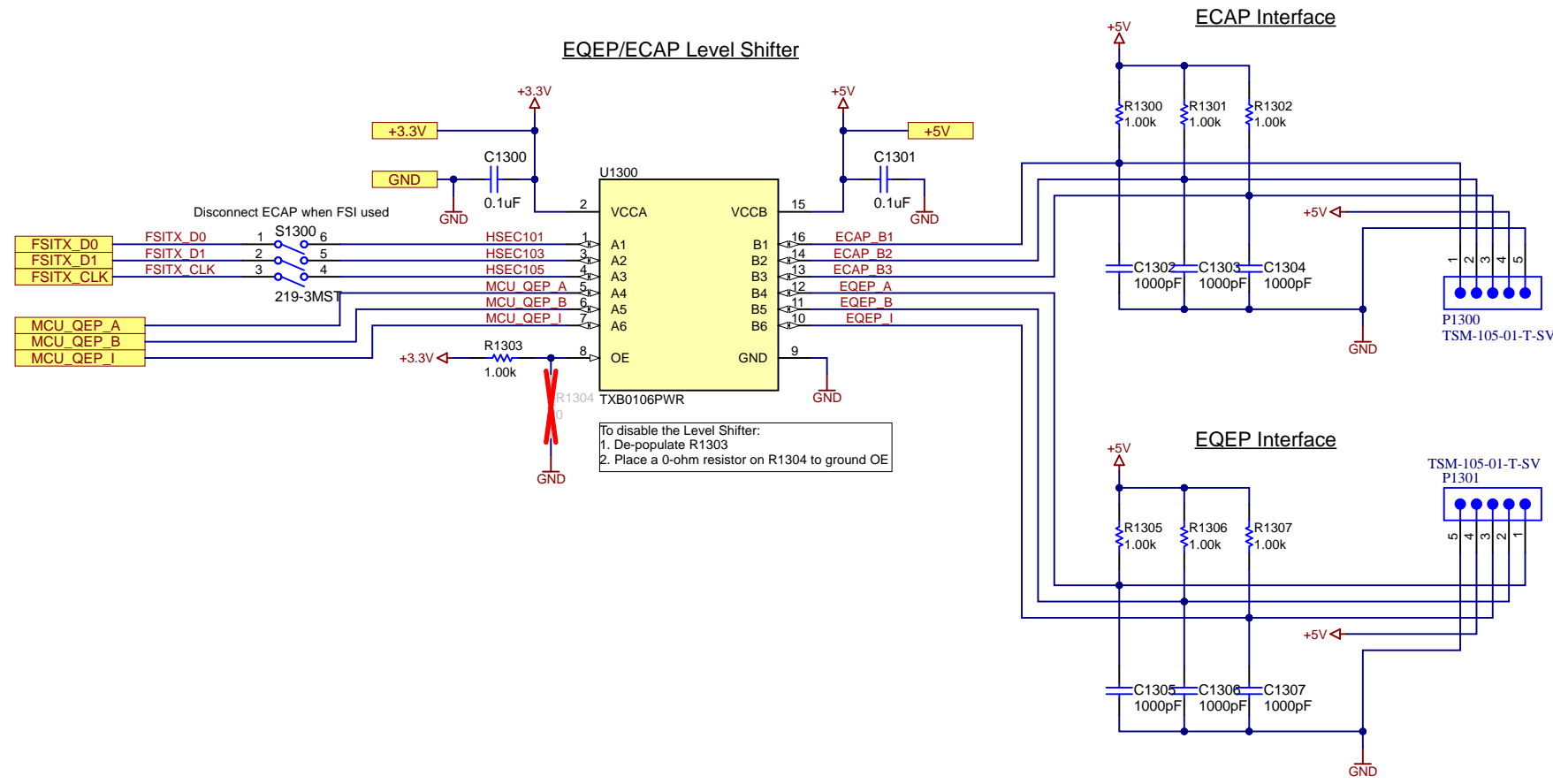
GDCL R1012 0 GDCH



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TID #: <a href="https://www.ti.com/tool/TID621">https://www.ti.com/tool/TID621</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: GD Interface
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 12 of 19
Drawn By: Panacek	File: gd-interface.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	





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TID #: <a href="https://www.ti.com/tool/TID011">https://www.ti.com/tool/TID011</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: EQEO/ECAP Inerface
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 13 of 19
Drawn By: Panacek	File: eqep_ecap_interface.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	

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A

A



DANGER HIGH VOLTAGE



FID1200

Fiducial



FID1201

Fiducial



FID1202

Fiducial



FID1203

Fiducial



FID1204

Fiducial



FID1205

Fiducial

LBL1200

PCB Label

THT-14-423-10  
Size: 0.65" x 0.20"

PCB Number: N/A  
PCB Rev: RevD

PCB  
LOGO  
FCC disclaimer

PCB  
LOGO  
Texas Instruments

PCB  
LOGO  
WEEE logo

B

B

C

C

D

D

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TID #: <a href="https://www.ti.com/tool/TID#">https://www.ti.com/tool/TID#</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: Hardware / Mechanical
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 14 of 19
Drawn By: Panacek	File: hardware.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	



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1

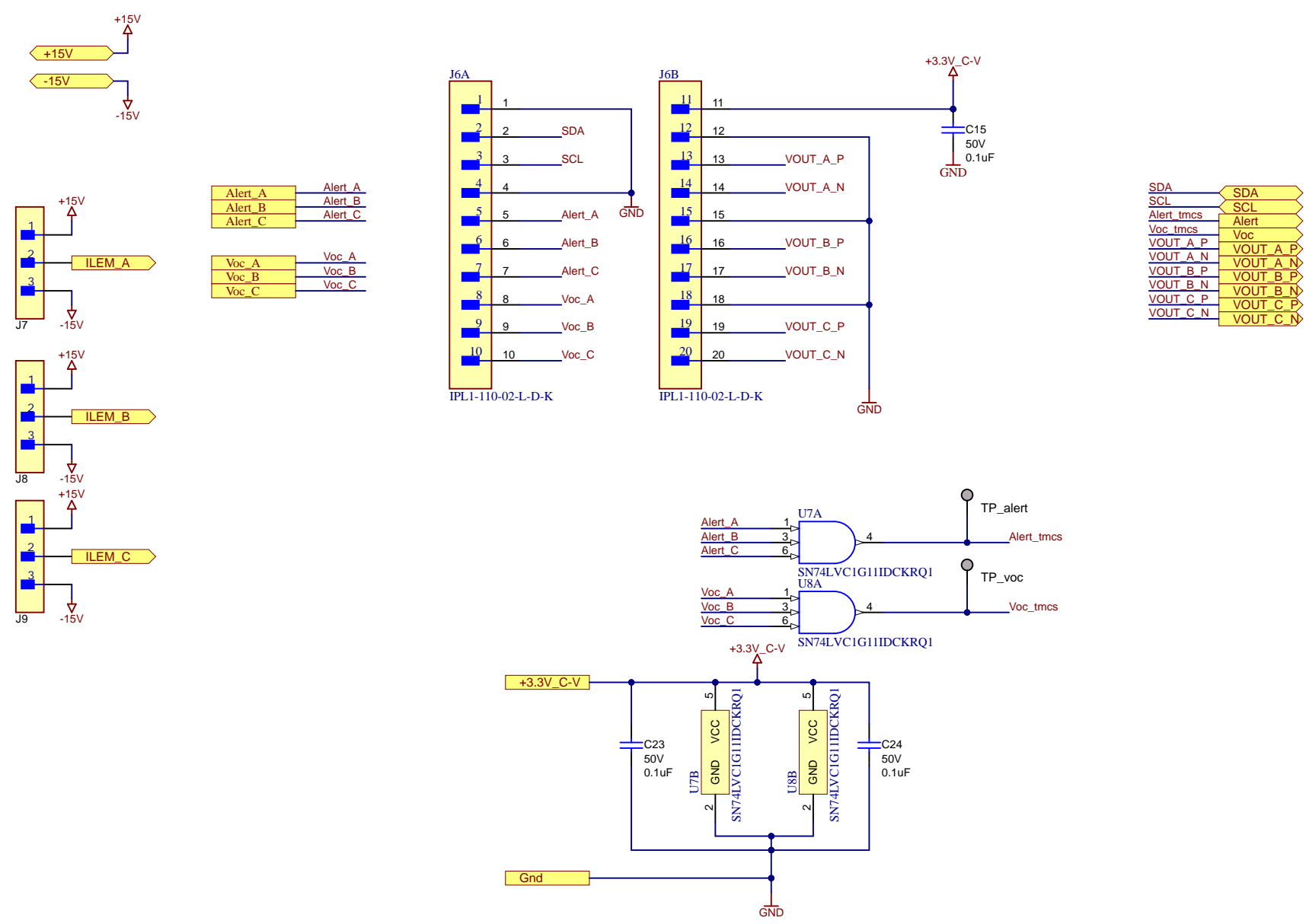
2

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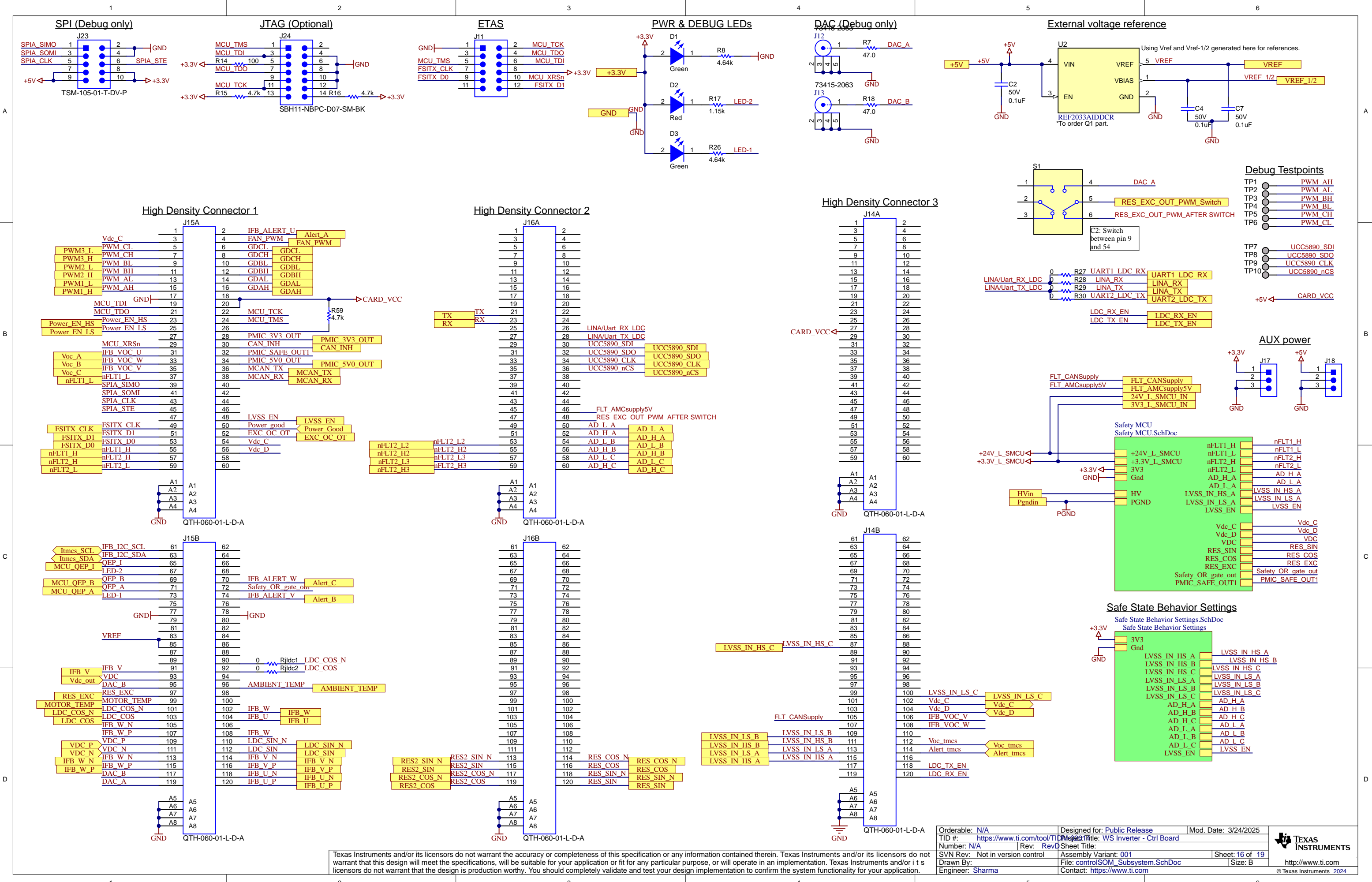
6



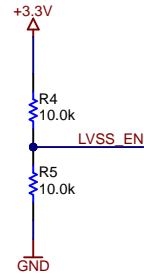
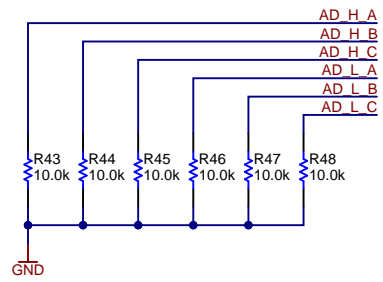
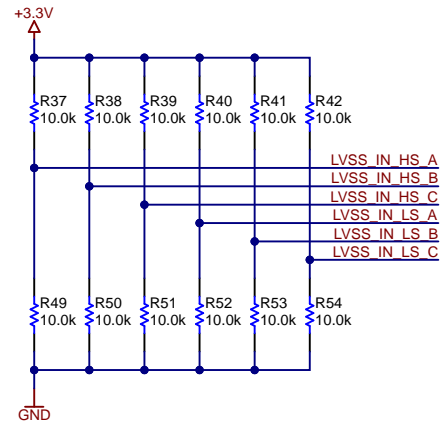
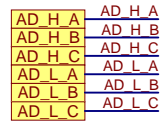
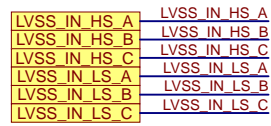
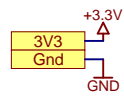
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TID #: <a href="https://www.ti.com/tool/TIDR011">https://www.ti.com/tool/TIDR011</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title:
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 15 of 19
Drawn By:	File: Current Sense Connector.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	





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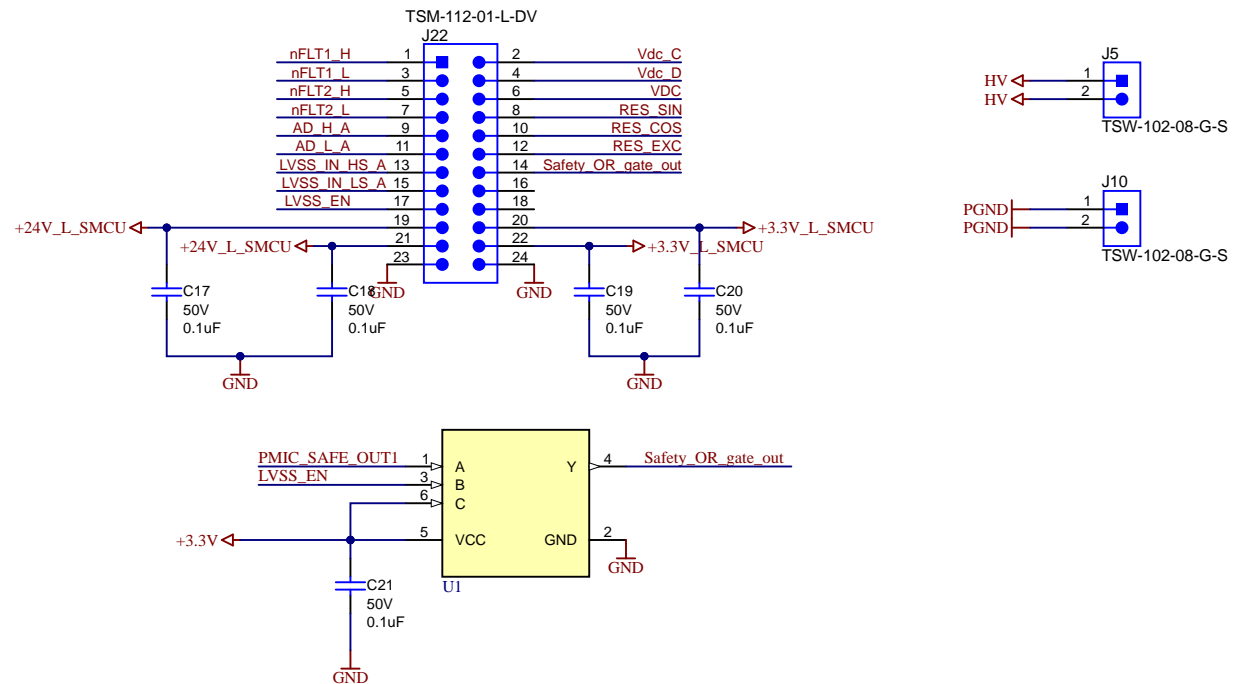
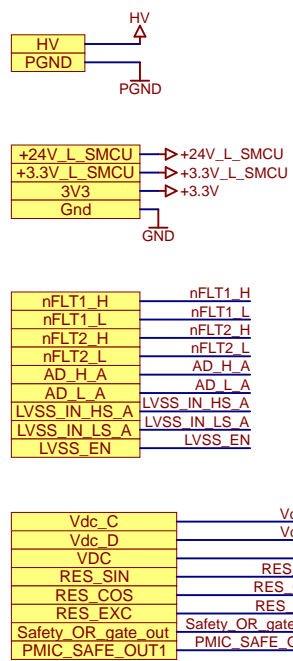
Orderable: N/A	Designed for: Public Release	Mod. Date: 1/14/2025
TID #: <a href="https://www.ti.com/tool/TID01000">https://www.ti.com/tool/TID01000</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title:
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 17 of 19
Drawn By:	File: Safe State Behavior Settings.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	



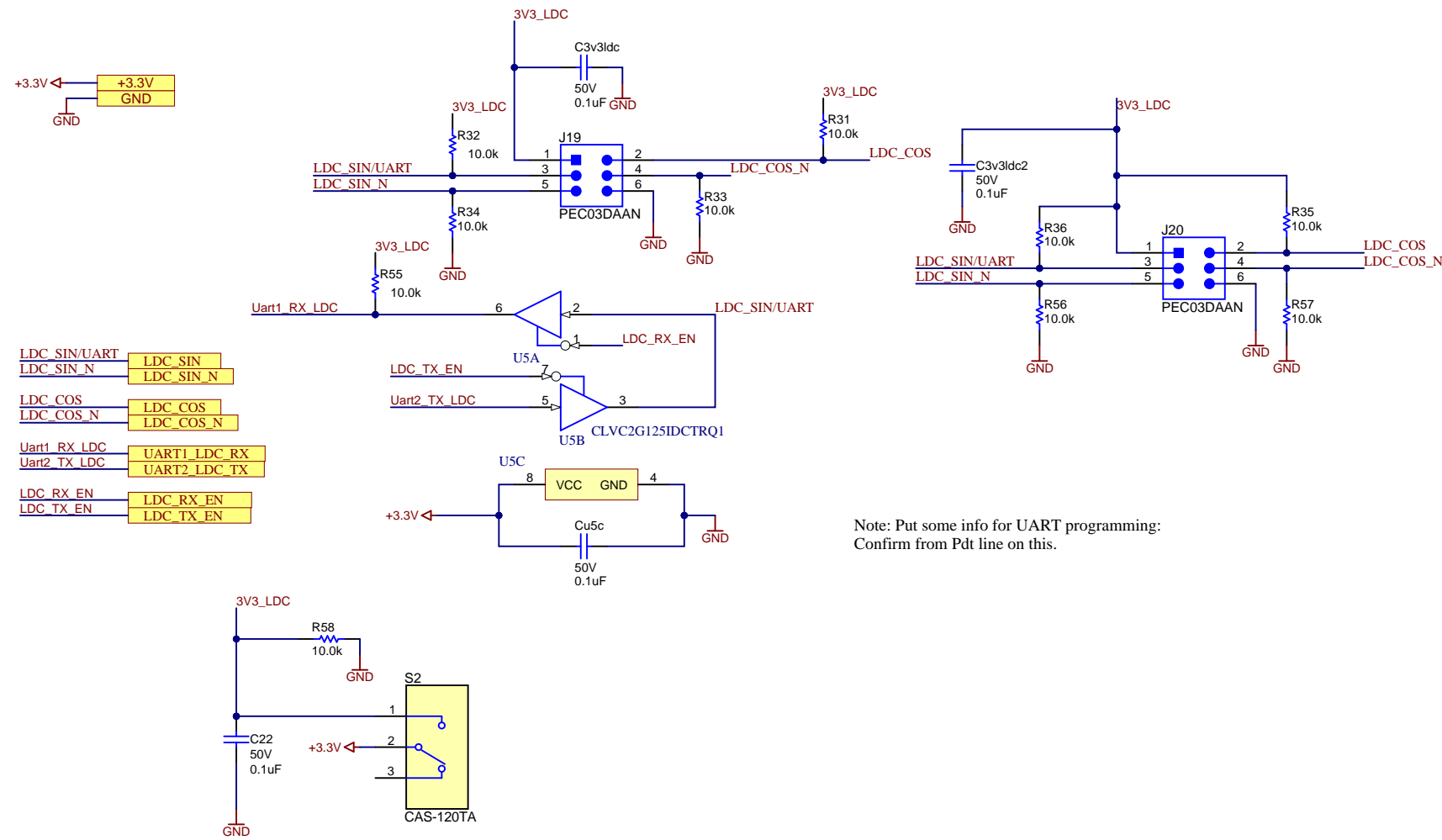
MCU2 --> LVSS\_AD H/L (phase A)  
 MCU1 --> LVSS\_AD H/L (phase B and C)

Power tree:  
 Flyback from HV DC:  
 1- MCU2  
 2- Low side drivers  
 KL30:  
 1- MCU1  
 2- High side drivers

Safety\_OR\_gate\_out:  
 PMIC\_SAFE\_OUT1 OR LVSS\_EN



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- LDC\_SIN/UART → LDC\_SIN
- LDC\_SIN\_N → LDC\_SIN\_N
- LDC\_COS → LDC\_COS
- LDC\_COS\_N → LDC\_COS\_N
- Uart1\_RX\_LDC → UART1\_LDC\_RX
- Uart2\_TX\_LDC → UART2\_LDC\_TX
- LDC\_RX\_EN → LDC\_RX\_EN
- LDC\_TX\_EN → LDC\_TX\_EN

Note: Put some info for UART programming:  
Confirm from Pdt line on this.

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TID #: <a href="https://www.ti.com/tool/TID0111">https://www.ti.com/tool/TID0111</a>	Project Title: WS Inverter - Ctrl Board	
Number: N/A	Rev: RevD	Sheet Title: Resolver Analog Front-End
SVN Rev: Not in version control	Assembly Variant: 001	Sheet: 19 of 19
Drawn By: Panacek	File: LDC.SchDoc	Size: B
Engineer: Sharma	Contact: <a href="https://www.ti.com">https://www.ti.com</a>	

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