

SCAN92LV090 9 Channel Bus LVDS Transceiver w/ Boundary SCAN

Check for Samples: [SCAN92LV090](#)

FEATURES

- IEEE 1149.1 (JTAG) Compliant
- Bus LVDS Signaling
- Low Power CMOS Design
- High Signaling Rate Capability (Above 100 Mbps)
- 0.1V to 2.3V Common Mode Range for $V_{ID} = 200\text{mV}$
- $\pm 100\text{ mV}$ Receiver Sensitivity
- Supports Open and Terminated Failsafe on Port Pins
- 3.3V Operation
- Glitch Free Power Up/Down (Driver & Receiver Disabled)
- Light Bus Loading (5 pF Typical) per Bus LVDS Load
- Designed for Double Termination Applications
- Balanced Output Impedance
- Product Offered in 64 Pin LQFP Package and NFBGA Package
- High Impedance Bus Pins on Power Off ($V_{CC} = 0\text{V}$)

DESCRIPTION

The SCAN92LV090A is one in a series of Bus LVDS transceivers designed specifically for the high speed, low power proprietary backplane or cable interfaces. The device operates from a single 3.3V power supply and includes nine differential line drivers and nine receivers. To minimize bus loading, the driver outputs and receiver inputs are internally connected. The separate I/O of the logic side allows for loop back support. The device also features a flow through pin out which allows easy PCB routing for short stubs between its pins and the connector.

The driver translates 3V TTL levels (single-ended) to differential Bus LVDS (BLVDS) output levels. This allows for high speed operation, while consuming minimal power with reduced EMI. In addition, the differential signaling provides common mode noise rejection of $\pm 1\text{V}$.

The receiver threshold is less than $\pm 100\text{ mV}$ over a $\pm 1\text{V}$ common mode range and translates the differential Bus LVDS to standard (TTL/CMOS) levels.

This device is compliant with IEEE 1149.1 Standard Test Access Port and Boundary Scan Architecture with the incorporation of the defined boundary-scan test logic and test access port consisting of Test Data Input (TDI), Test Data Out (TDO), Test Mode Select (TMS), Test Clock (TCK), and the optional Test Reset (TRST).

SIMPLIFIED FUNCTIONAL DIAGRAM

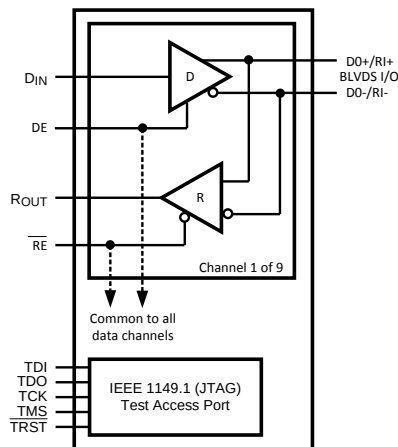


Figure 1.



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CONNECTION DIAGRAM

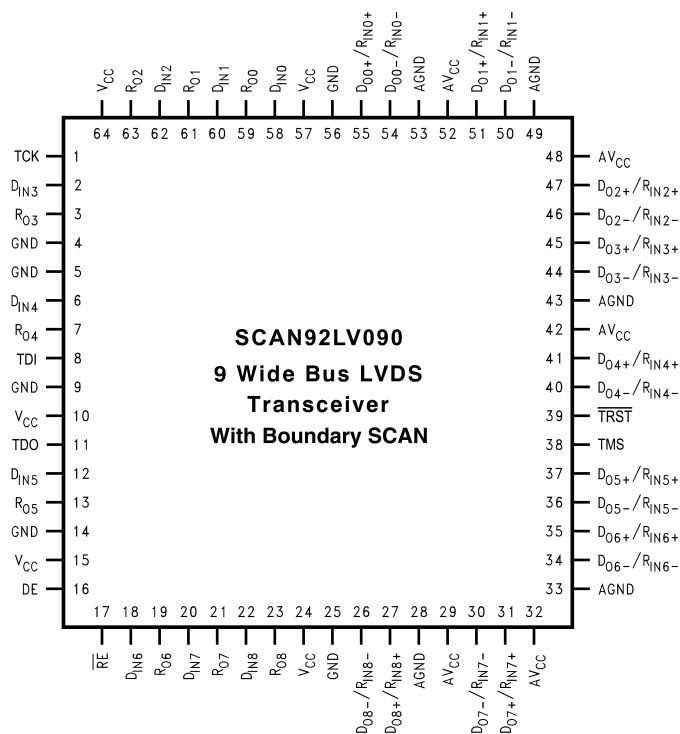


Figure 2. Top View
Package Number PM0064

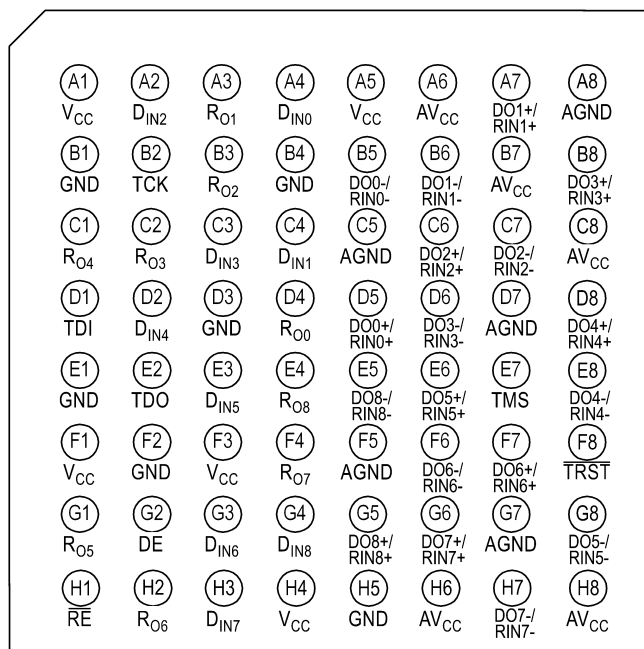


Figure 3. Top View
Package Number NZC0064A

PINOUT DESCRIPTION

Pin Name	LQFP Pin #	NFBGA Pin #	Input/Output	Descriptions
DO+/RI+	27, 31, 35, 37, 41, 45, 47, 51, 55	A7, B8, C6, D5, D8, E6, F7, G5, G6	I/O	True Bus LVDS Driver Outputs and Receiver Inputs.
DO-/RI-	26, 30, 34, 36, 40, 44, 46, 50, 54	B5, B6, C7, D6, E5, E8, F6, G8, H7	I/O	Complimentary Bus LVDS Driver Outputs and Receiver Inputs.
D _{IN}	2, 6, 12, 18, 20, 22, 58, 60, 62	A2, A4, C3, C4, D2, E3, G3, G4, H3	I	TTL Driver Input.
RO	3, 7, 13, 19, 21, 23, 59, 61, 63	A3, B3, C1, C2, D4, E4, F4, G1, H2	O	TTL Receiver Output.
$\overline{\text{RE}}$	17	H1	I	Receiver Enable TTL Input (Active Low).
DE	16	G2	I	Driver Enable TTL Input (Active High).
GND	4, 5, 9, 14, 25, 56	B1, B4, D3, E1, F2, H5	Power	Ground for digital circuitry (must connect to GND on PC board). These pins connected internally.
V _{CC}	10, 15, 24, 57, 64	A1, A5, F1, F3, H4	Power	V _{CC} for digital circuitry (must connect to V _{CC} on PC board). These pins connected internally.
AGND	28, 33, 43, 49, 53	A8, C5, D7, F5, G7	Power	Ground for analog circuitry (must connect to GND on PC board). These pins connected internally.
AV _{CC}	29, 32, 42, 48, 52	A6, B7, C8, H6, H8	Power	Analog V _{CC} (must connect to V _{CC} on PC board). These pins connected internally.
$\overline{\text{TRST}}$	39	F8	I	Test Reset Input to support IEEE 1149.1 (Active Low)
TMS	38	E7	I	Test Mode Select Input to support IEEE 1149.1
TCK	1	B2	I	Test Clock Input to support IEEE 1149.1
TDI	8	D1	I	Test Data Input to support IEEE 1149.1
TDO	11	E2	O	Test Data Output to support IEEE 1149.1



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ABSOLUTE MAXIMUM RATINGS ⁽¹⁾⁽²⁾⁽³⁾

Supply Voltage (V _{CC})		4.0V
Enable Input Voltage (DE, $\overline{\text{RE}}$)		–0.3V to (V _{CC} +0.3V)
Driver Input Voltage (D _{IN})		–0.3V to (V _{CC} +0.3V)
Receiver Output Voltage (R _{OUT})		–0.3V to (V _{CC} +0.3V)
Bus Pin Voltage (DO/RI $\pm$)		–0.3V to +3.9V
ESD (HBM 1.5 k Ω , 100 pF)		>4.5 kV
Driver Short Circuit Duration		momentary
Receiver Short Circuit Duration		momentary
Maximum Package Power Dissipation at 25°C	LQFP	1.74 W
	Derate LQFP Package	13.9 mW/°C
	θ_{ja}	71.7°C/W
	θ_{jc}	10.9°C/W
Junction Temperature		+150°C
Storage Temperature Range		–65°C to +150°C
Lead Temperature (Soldering, 4 sec.)		260°C

- (1) Absolute Maximum Ratings are those values beyond which the safety of the device cannot be ensured. They are not meant to imply that the devices should be operated at these limits. The table of “Electrical Characteristics” provides conditions for actual device operation.
- (2) All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to ground unless otherwise specified except V_{OD}, ΔV_{OD} and V_{ID}.
- (3) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

RECOMMENDED OPERATING CONDITIONS

		Min	Max	Units
Supply Voltage (V_{CC})		3.0	3.6	V
Receiver Input Voltage		0.0	2.4	V
Operating Free Air Temperature		-40	+85	°C
Maximum Input Edge Rate	(20% to 80%) ⁽¹⁾			$\Delta t/\Delta V$
	Data		1.0	ns/V
	Control		3.0	ns/V

- (1) Generator waveforms for all tests unless otherwise specified: $f = 25$ MHz, $Z_O = 50\Omega$, $t_r, t_f = <1.0$ ns (0%–100%). To ensure fastest propagation delay and minimum skew, data input edge rates should be equal to or faster than 1ns/V; control signals equal to or faster than 3ns/V. In general, the faster the input edge rate, the better the AC performance.

DC ELECTRICAL CHARACTERISTICS

Over recommended operating supply voltage and temperature ranges unless otherwise specified ⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Pin	Min	Typ	Max	Units
V_{OD}	Output Differential Voltage	$R_L = 27\Omega$, See Figure 4	DO+/RI+, DO-/RI-	240	300	460	mV
ΔV_{OD}	V_{OD} Magnitude Change					27	mV
V_{OS}	Offset Voltage			1.1	1.3	1.5	V
ΔV_{OS}	Offset Magnitude Change				5	10	mV
V_{OH}	Driver Output High Voltage ⁽³⁾	$R_L = 27\Omega$			1.4	1.65	V
V_{OL}	Driver Output Low Voltage ⁽³⁾	$R_L = 27\Omega$		0.95	1.1		V
I_{OSD}	Output Short Circuit Current ⁽⁴⁾	$V_{OD} = 0V$, $DE = V_{CC}$, Driver outputs shorted together			36	65	mA
V_{OH}	Voltage Output High ⁽⁵⁾	$V_{ID} = +300$ mV	R_{OUT}	$V_{CC}-0.2$			V
		Inputs Open		$V_{CC}-0.2$			V
		Inputs Terminated, $R_L = 27\Omega$		$V_{CC}-0.2$			V
V_{OL}	Voltage Output Low	$I_{OL} = 2.0$ mA, $V_{ID} = -300$ mV			0.05	0.075	V
I_{OD}	Receiver Output Dynamic Current ⁽⁴⁾	$V_{ID} = 300$ mV, $V_{OUT} = V_{CC}-1.0V$		-110	75		mA
		$V_{ID} = -300$ mV, $V_{OUT} = 1.0V$			75	110	mA
V_{TH}	Input Threshold High	$DE = 0V$, $V_{CM} = 1.5V$	DO+/RI+, DO-/RI-			+100	mV
V_{TL}	Input Threshold Low			-100			mV
V_{CMR}	Receiver Common Mode Range			$ V_{ID} /2$		2.4 – $ V_{ID} /2$	V
I_{IN}	Input Current	$DE = 0V$, $\overline{RE} = 2.4V$, $V_{IN} = +2.4V$ or $0V$		-25	± 1	+25	μA
		$V_{CC} = 0V$, $V_{IN} = +2.4V$ or $0V$		-20	± 1	+20	μA
V_{IH}	Minimum Input High Voltage		$\overline{D_{IN}}$, DE , RE , TCK , $TRST$, TMS , TDI	2.0		V_{CC}	V
V_{IL}	Maximum Input Low Voltage			GND		0.8	V
I_{IH}	Input High Current	$V_{IN} = V_{CC}$ or $2.4V$	$\overline{D_{IN}}$, DE , $\overline{RE}$	-20	± 10	+20	μA
I_{IL}	Input Low Current	$V_{IN} = GND$ or $0.4V$		-20	± 10	+20	μA
V_{CL}	Input Diode Clamp Voltage	$I_{CLAMP} = -18$ mA		-1.5	-0.8		V
I_{IH}	Input High Current	$V_{IN} = V_{CC}$	TDI , TMS , TCK , $TRST$	-20		+20	μA
I_{ILR}	Input Low Current	$V_{IN} = GND$, $V_{CC} = 3.6v$	$\overline{TDI}$, TMS , $TRST$	-25		-115	μA

- (1) All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to ground unless otherwise specified except V_{OD} , ΔV_{OD} and V_{ID} .
- (2) All typicals are given for $V_{CC} = +3.3V$ and $T_A = +25^\circ C$, unless otherwise stated.
- (3) The SCAN92LV090 functions within datasheet specification when a resistive load is applied to the driver outputs.
- (4) Only one output at a time should be shorted, do not exceed maximum package power dissipation capacity.
- (5) V_{OH} failsafe terminated test performed with 27Ω connected between RI+ and RI- inputs. No external voltage is applied.

DC ELECTRICAL CHARACTERISTICS (continued)

Over recommended operating supply voltage and temperature ranges unless otherwise specified ⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Pin	Min	Typ	Max	Units
I_{IL}	Input Low Current	$V_{IN} = GND$	TCK	-20		+20	μA
I_{CCD}	Power Supply Current Drivers Enabled, Receivers Disabled	No Load, $\overline{DE} = \overline{RE} = V_{CC}$, $DIN = V_{CC}$ or GND	V_{CC}		50	80	mA
I_{CCR}	Power Supply Current Drivers Disabled, Receivers Enabled	$DE = \overline{RE} = 0V$, $V_{ID} = \pm 300mV$			50	80	mA
I_{CCZ}	Power Supply Current, Drivers and Receivers tri-state	$DE = 0V$; $\overline{RE} = V_{CC}$, $DIN = V_{CC}$ or GND			50	80	mA
I_{CC}	Power Supply Current, Drivers and Receivers Enabled	$DE = V_{CC}$; $\overline{RE} = 0V$, $DIN = V_{CC}$ or GND, $R_L = 27\Omega$			160	210	mA
I_{CCS}	Power Supply Current (SCAN Test Mode), Drivers and Receivers Enabled	$DE = V_{CC}$; $\overline{RE} = 0V$, $DIN = V_{CC}$ or GND, $R_L = 27\Omega$, TAP in any state other than Test-Logic-Reset			180	230	mA
I_{OFF}	Power Off Leakage Current	$V_{CC} = 0V$ or OPEN, D_{IN} , DE , $\overline{RE} = 0V$ or OPEN, $V_{APPLIED} = 3.6V$ (Port Pins)	DO+/RI+, DO-/RI-	-20		+20	μA
C_{OUTPUT}	Capacitance @ Bus Pins		DO+/RI+, DO-/RI-		5		pF
C_{OUTPUT}	Capacitance @ R_{OUT}		R_{OUT}		7		pF

AC ELECTRICAL CHARACTERISTICS

Over recommended operating supply voltage and temperature ranges unless otherwise specified ⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Units
DIFFERENTIAL DRIVER TIMING REQUIREMENTS						
t _{PHLD}	Differential Prop. Delay High to Low ⁽²⁾	R _L = 27Ω, See Figure 5 and Figure 6 C _L = 10 pF	1.0	1.8	2.6	ns
t _{PLHD}	Differential Prop. Delay Low to High ⁽²⁾		1.0	1.8	2.6	ns
t _{SKD1}	Differential Skew t _{PHLD} –t _{PLHD} ⁽³⁾			120		ps
t _{SKD2}	Chip to Chip Skew ⁽⁴⁾				1.6	ns
t _{SKD3}	Channel to Channel Skew ⁽⁵⁾			0.25	0.55	ns
t _{TLH}	Transition Time Low to High			0.5	1.2	ns
t _{THL}	Transition Time High to Low			0.5	1.2	ns
t _{PHZ}	Disable Time High to Z	R _L = 27Ω, See Figure 7 and Figure 8 C _L = 10 pF		3	8	ns
t _{PLZ}	Disable Time Low to Z			3	8	ns
t _{PZH}	Enable Time Z to High			3	8	ns
t _{PZL}	Enable Time Z to Low			3	8	ns
DIFFERENTIAL RECEIVER TIMING REQUIREMENTS						
t _{PHLD}	Differential Prop. Delay High to Low ⁽²⁾	See Figure 9 and Figure 10 C _L = 35 pF	2.0	2.4	3.9	ns
t _{PLHD}	Differential Prop Delay Low to High ⁽²⁾		2.0	2.4	3.9	ns
t _{SDK1}	Differential Skew t _{PHLD} –t _{PLHD} ⁽³⁾			210		ps
t _{SDK2}	Chip to Chip Skew ⁽⁴⁾				1.9	ns
t _{SDK3}	Channel to Channel skew ⁽⁵⁾			0.35	0.7	ns
t _{TLH}	Transition Time Low to High			1.5	2.5	ns
t _{THL}	Transition Time High to Low			1.5	2.5	ns

- (1) Generator waveforms for all tests unless otherwise specified: $f = 25$ MHz, $Z_O = 50\Omega$, t_r , $t_f = <1.0$ ns (0%–100%). To ensure fastest propagation delay and minimum skew, data input edge rates should be equal to or faster than 1ns/V; control signals equal to or faster than 3ns/V. In general, the faster the input edge rate, the better the AC performance.
- (2) Propagation delays are specified by design and characterization.
- (3) $t_{SKD1} |t_{PHLD} - t_{PLHD}|$ is the worse case skew between any channel and any device over recommended operation conditions.
- (4) Chip to Chip skew is the difference in differential propagation delay between any channels of any devices, either edge.
- (5) Channel to Channel skew is the difference in driver output or receiver output propagation delay between any channels within a device, common edge.

AC ELECTRICAL CHARACTERISTICS (continued)Over recommended operating supply voltage and temperature ranges unless otherwise specified ⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Units
t _{PHZ}	Disable Time High to Z	R _L = 500Ω, See Figure 11 and Figure 12 C _L = 35 pF		4.5	10	ns
t _{PLZ}	Disable Time Low to Z			3.5	8	ns
t _{PZH}	Enable Time Z to High			3.5	8	ns
t _{PZL}	Enable Time Z to Low			3.5	8	ns
SCAN CIRCUITRY TIMING REQUIREMENTS						
f _{MAX}	Maximum TCK Clock Frequency	R _L = 500Ω, C _L = 35 pF	25.0	75.0		MHz
t _S	TDI to TCK, H or L		1.5			ns
t _H	TDI to TCK, H or L		1.5			ns
t _S	TMS to TCK, H or L		2.5			ns
t _H	TMS to TCK, H or L		1.5			ns
t _W	TCK Pulse Width, H or L		10.0			ns
t _W	$\overline{\text{TRST}}$ Pulse Width, L		2.5			ns
t _{REC}	Recovery Time, $\overline{\text{TRST}}$ to TCK		2.0			ns

APPLICATIONS INFORMATION

General application guidelines and hints may be found in the following application notes: AN-808 ([SNLA028](#)), AN-1108 ([SNLA008](#)), AN-977 ([SNLA166](#)), AN-971 ([SNLA165](#)), and AN-903 ([SNLA034](#)).

There are a few common practices which should be implied when designing PCB for Bus LVDS signaling. Recommended practices are:

- Use at least 4 PCB board layer (Bus LVDS signals, ground, power and TTL signals).
- Keep drivers and receivers as close to the (Bus LVDS port side) connector as possible.
- Bypass each Bus LVDS device and also use distributed bulk capacitance between power planes. Surface mount capacitors placed close to power and ground pins work best. Two or three high frequency, multi-layer ceramic (MLC) surface mount (0.1 μF , 0.01 μF , 0.001 μF) in parallel should be used between each V_{CC} and ground. The capacitors should be as close as possible to the V_{CC} pin.
 - Multiple vias should be used to connect V_{CC} and Ground planes to the pads of the by-pass capacitors.
 - In addition, randomly distributed by-pass capacitors should be used.
- Use the termination resistor which best matches the differential impedance of your transmission line.
- Leave unused Bus LVDS receiver inputs open (floating). Limit traces on unused inputs to <0.5 inches.
- Isolate TTL signals from Bus LVDS signals

MEDIA (CONNECTOR or BACKPLANE) SELECTION:

- Use controlled impedance media. The backplane and connectors should have a matched differential impedance.

Table 1. Functional Table

MODE SELECTED	DE	$\overline{\text{RE}}$
DRIVER MODE	H	H
RECEIVER MODE	L	L
tri-state MODE	L	H
LOOP BACK MODE	H	L

Table 2. Transmitter Mode

INPUTS		OUTPUTS	
DE	D_{IN}	DO+	DO–
H	L	L	H
H	H	H	L
H	$0.8\text{V} < D_{IN} < 2.0\text{V}$	X	X
L	X	Z	Z

Table 3. Receiver Mode⁽¹⁾

INPUTS		OUTPUT
$\overline{\text{RE}}$	(RI+) – (RI–)	
L	L (< –100 mV)	L
L	H (> +100 mV)	H
L	$-100\text{ mV} < V_{ID} < +100\text{ mV}$	X
H	X	Z

- (1) X = High or Low logic state
 L = Low state
 Z = High impedance state
 H = High state

TEST CIRCUITS AND TIMING WAVEFORMS

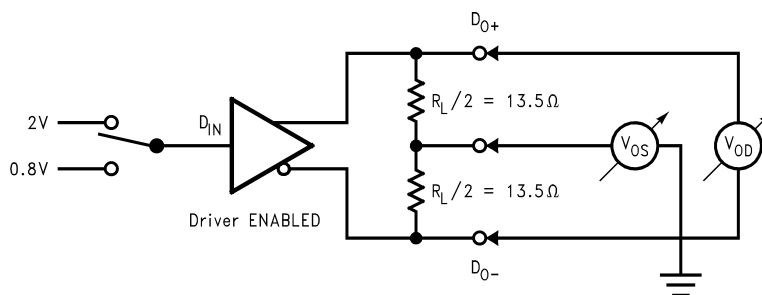


Figure 4. Differential Driver DC Test Circuit

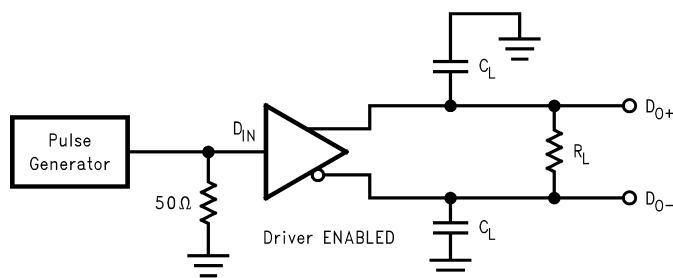


Figure 5. Differential Driver Propagation Delay and Transition Time Test Circuit

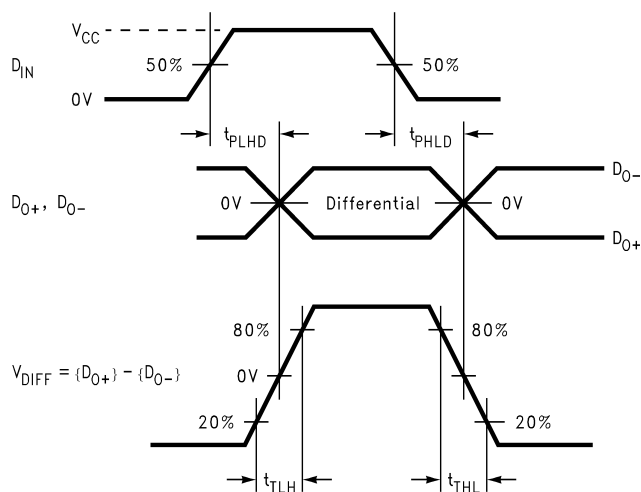


Figure 6. Differential Driver Propagation Delay and Transition Time Waveforms

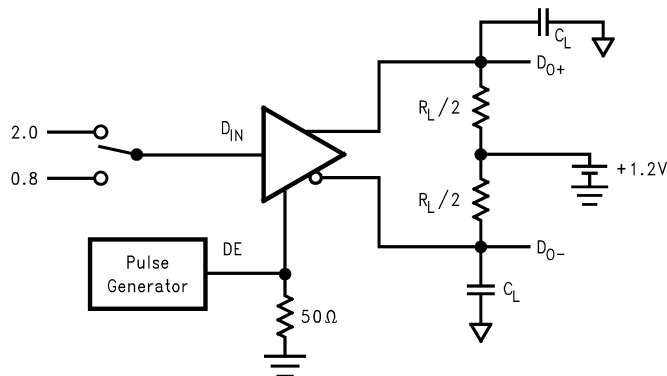


Figure 7. Driver Tri-State Delay Test Circuit

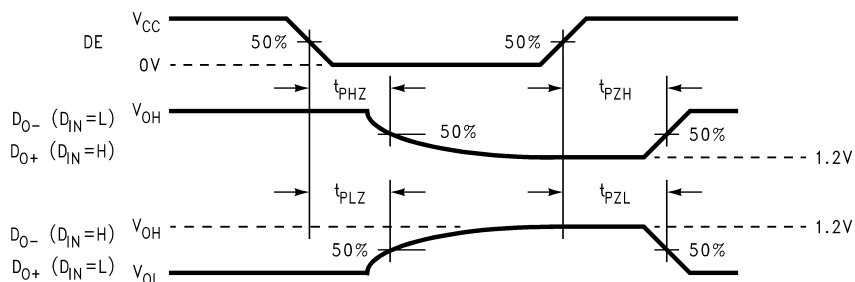


Figure 8. Driver Tri-State Delay Waveforms

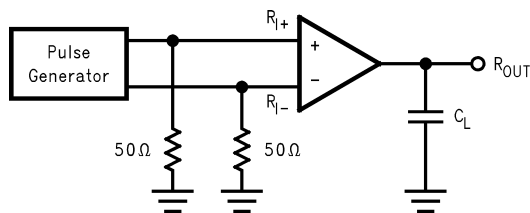


Figure 9. Receiver Propagation Delay and Transition Time Test Circuit

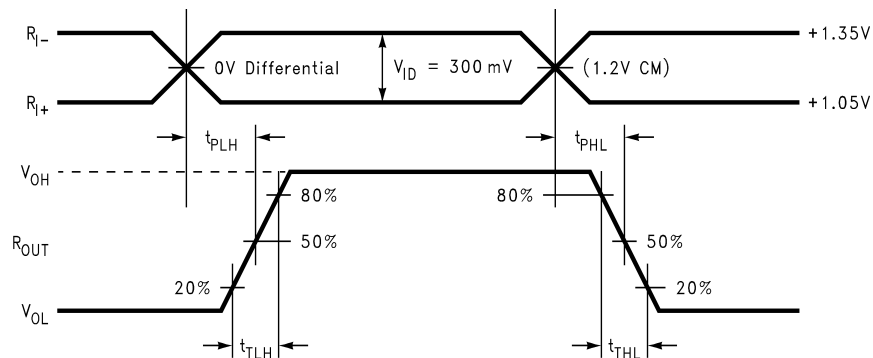


Figure 10. Receiver Propagation Delay and Transition Time Waveforms

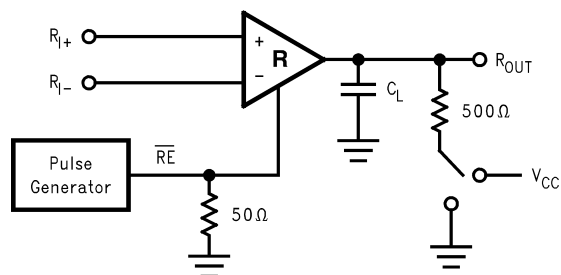


Figure 11. Receiver Tri-State Delay Test Circuit

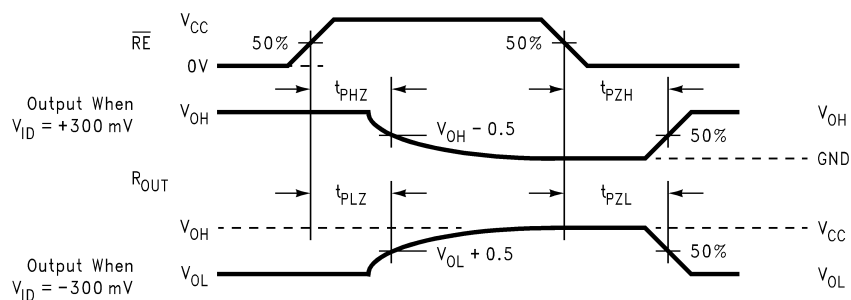


Figure 12. Receiver Tri-State Delay Waveforms

TYPICAL BUS APPLICATION CONFIGURATIONS

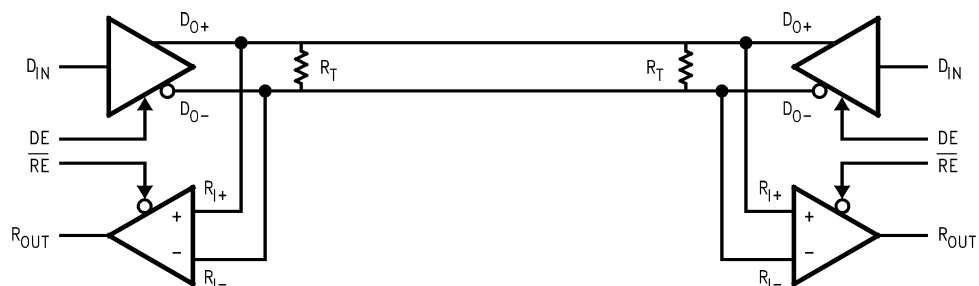


Figure 13. Bi-Directional Half-Duplex Point-to-Point Applications

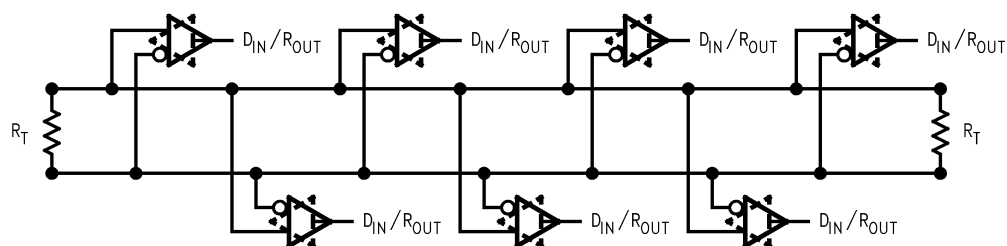


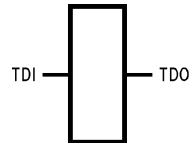
Figure 14. Multi-Point Bus Applications

DESCRIPTION OF BOUNDARY-SCAN CIRCUITRY

The SCAN92LV090 features two unique Scan test modes, each which requires a unique BSDL model depending on the level of test access and fault coverage goals. In the first mode (Mode0), only the TTL Inputs and Outputs of each transceiver are accessible via a 1149.1 compliant protocol. In the second mode (Mode1), both the TTL Inputs and Outputs and the differential LVDS I/Os are included in the Scan chain.

All test modes are handled by the ATPG software, and BSDL selection should be invisible to the user.

The BYPASS register is a single bit shift register stage identical to scan cell TYPE1. It captures a fixed logic low.



**Figure 15. Bypass Register Scan Chain Definition
Logic 0**

The INSTRUCTION register is an eight-bit register which captures the value 00111101.

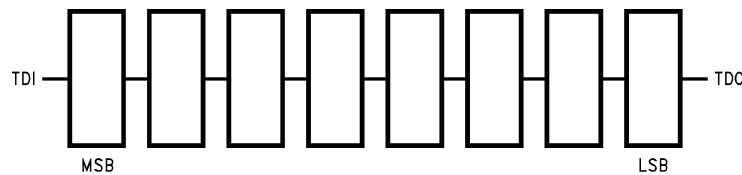


Figure 16. Instruction Register Scan Chain Definition

Table 4. MSB → LSB (Mode0)

Instruction Code	Instruction
00000000	EXTEST
10000010	SAMPLE/PRELOAD
10000111	CLAMP
00000110	HIGHZ
All Others	BYPASS

Table 5. MSB → LSB (Mode1)

Instruction Code	Instruction
10011001	EXTEST
10010010	SAMPLE/PRELOAD
10001111	CLAMP
00000110	HIGHZ
All Others	BYPASS

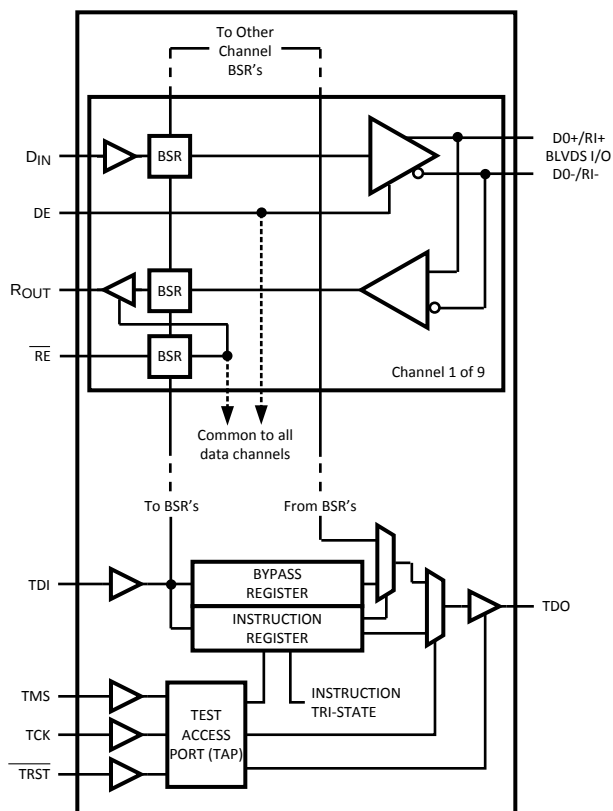


Figure 17. Mode 0 Boundary Scan Register Configuration
(Refer to the BSDL for exact register order)

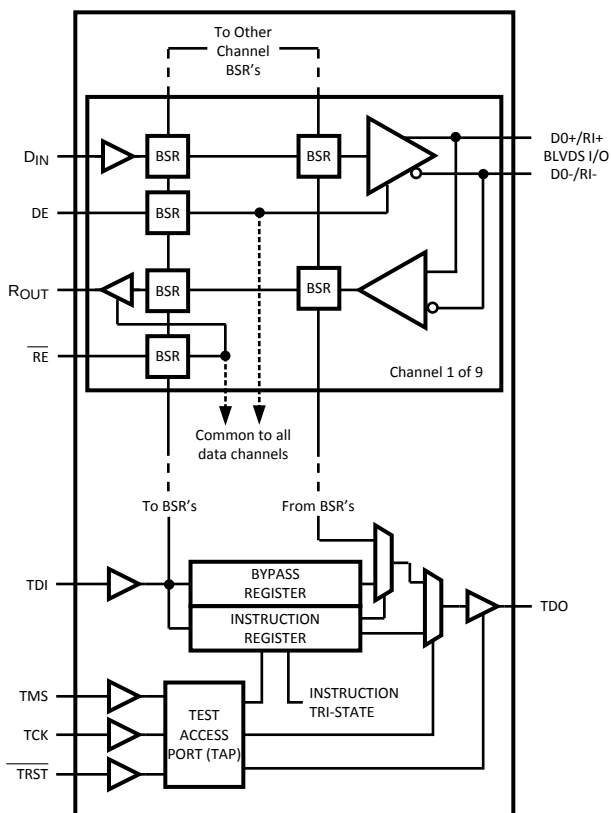


Figure 18. Mode 1 Boundary Scan Register Configuration
(Refer to the BSDL for exact register order)

REVISION HISTORY

Changes from Revision H (April 2013) to Revision I	Page
• Changed layout of National Data Sheet to TI format	13

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
SCAN92LV090SLC	NRND	Production	NFBGA (NZC) 64	360 EIAJ TRAY (10+1)	No	Call TI	Call TI	-40 to 85	SCAN92LV090 SLC
SCAN92LV090SLC.A	NRND	Production	NFBGA (NZC) 64	360 EIAJ TRAY (10+1)	No	Call TI	Call TI	-40 to 85	SCAN92LV090 SLC
SCAN92LV090SLC/NO.A	Active	Production	NFBGA (NZC) 64	360 EIAJ TRAY (10+1)	Yes	SNAGCU	Level-4-260C-72 HR	-40 to 85	SCAN92LV090 SLC
SCAN92LV090SLC/NOPB	Active	Production	NFBGA (NZC) 64	360 EIAJ TRAY (10+1)	Yes	SNAGCU	Level-4-260C-72 HR	-40 to 85	SCAN92LV090 SLC
SCAN92LV090VEH/NO.A	Active	Production	LQFP (PM) 64	160 JEDEC TRAY (10+1)	Yes	SN	Level-3-260C-168 HR	-40 to 85	SCAN92LV090 VEH
SCAN92LV090VEH/NOPB	Active	Production	LQFP (PM) 64	160 JEDEC TRAY (10+1)	Yes	SN	Level-3-260C-168 HR	-40 to 85	SCAN92LV090 VEH

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

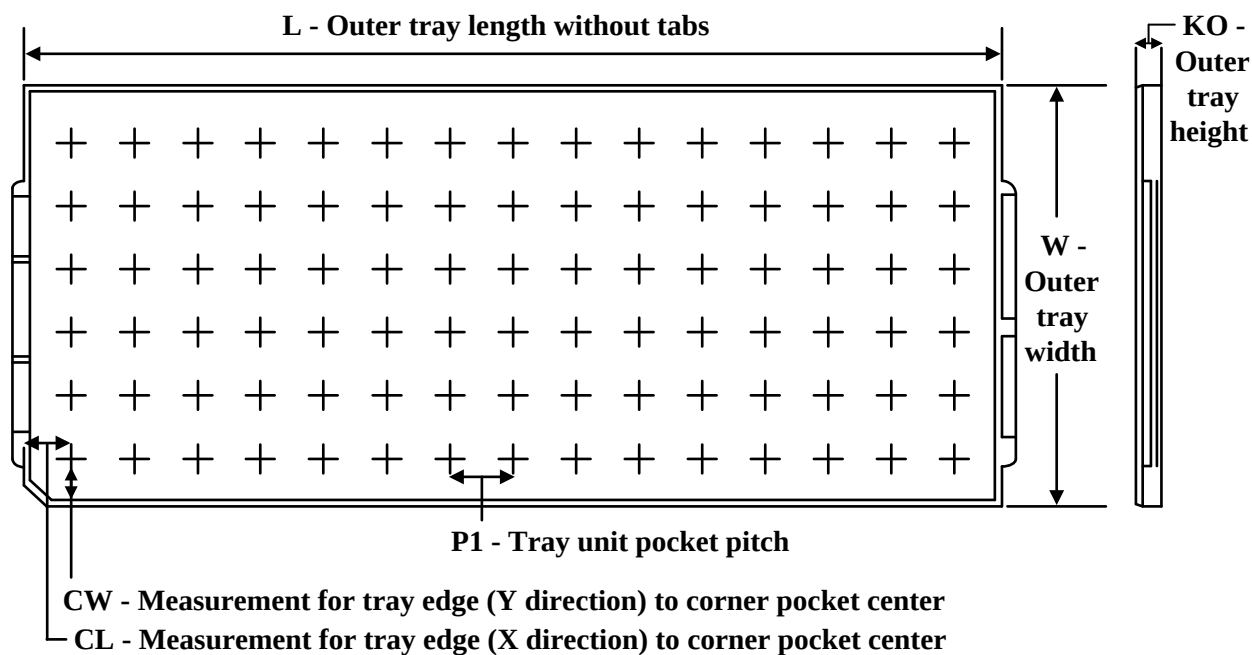
⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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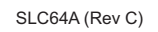
TRAY

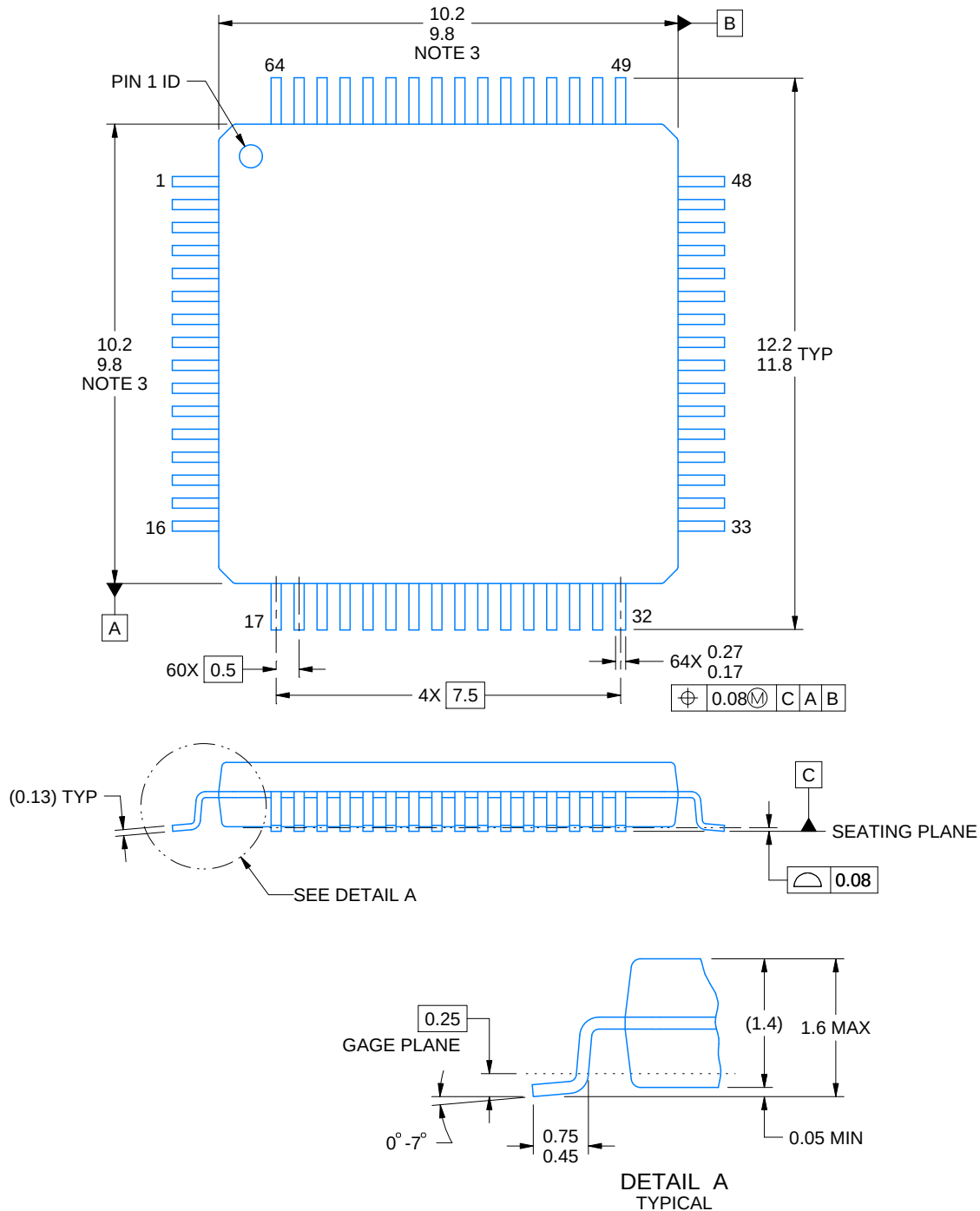
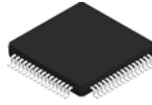


Chamfer on Tray corner indicates Pin 1 orientation of packed units.

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	Unit array matrix	Max temperature (°C)	L (mm)	W (mm)	K0 (µm)	P1 (mm)	CL (mm)	CW (mm)
SCAN92LV090SLC	NZC	NFBGA	64	360	12 x 30	150	322.6	135.9	7620	10	12.5	12.95
SCAN92LV090SLC.A	NZC	NFBGA	64	360	12 x 30	150	322.6	135.9	7620	10	12.5	12.95
SCAN92LV090SLC/ NO.A	NZC	NFBGA	64	360	12 x 30	150	322.6	135.9	7620	10	12.5	12.95
SCAN92LV090SLC/ NOPB	NZC	NFBGA	64	360	12 x 30	150	322.6	135.9	7620	10	12.5	12.95
SCAN92LV090VEH/ NO.A	PM	LQFP	64	160	8 X 20	150	322.6	135.9	7620	15.2	13.1	13
SCAN92LV090VEH/ NOPB	PM	LQFP	64	160	8 X 20	150	322.6	135.9	7620	15.2	13.1	13





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NOTES:

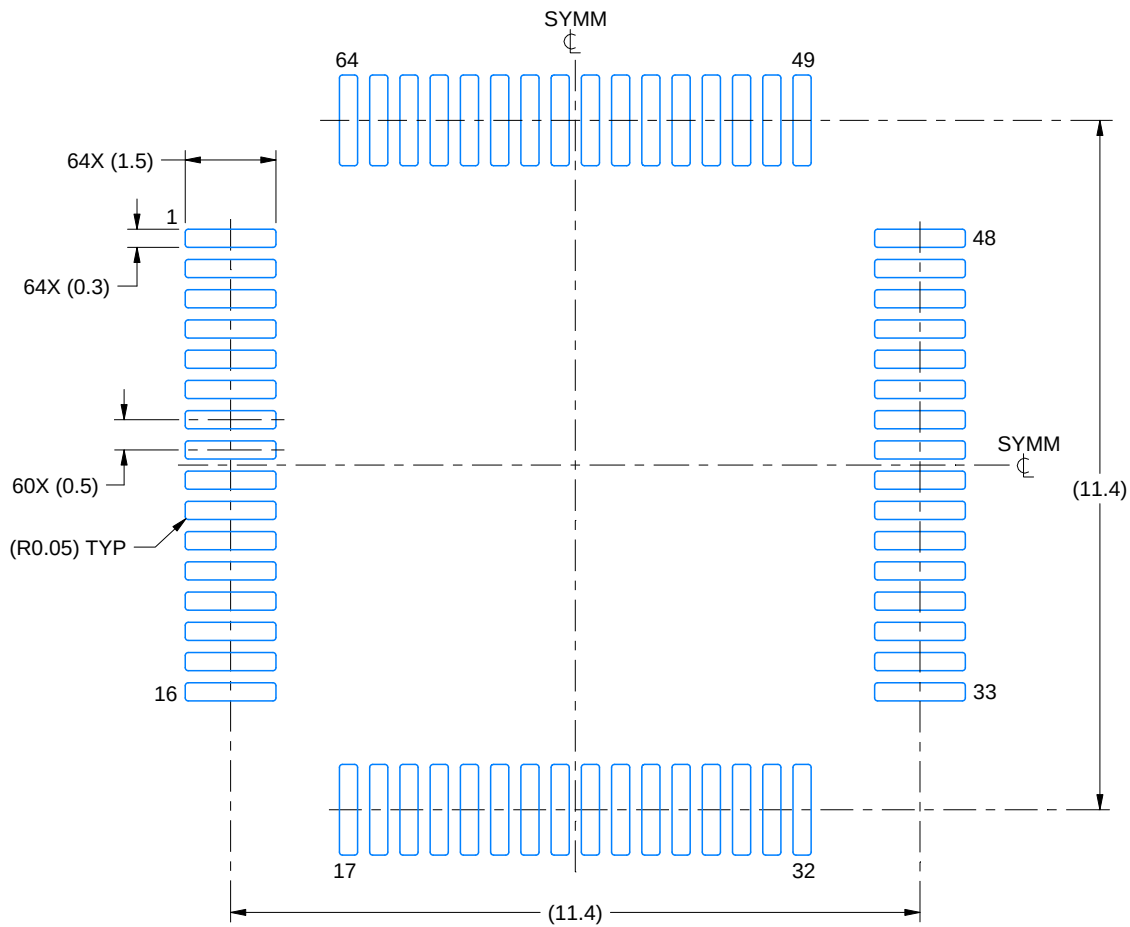
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MS-026.

EXAMPLE BOARD LAYOUT

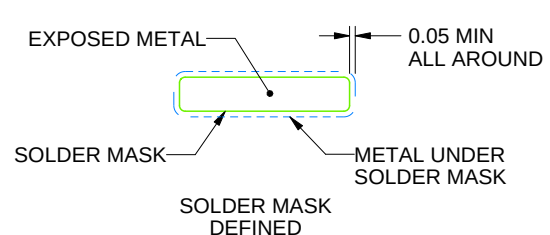
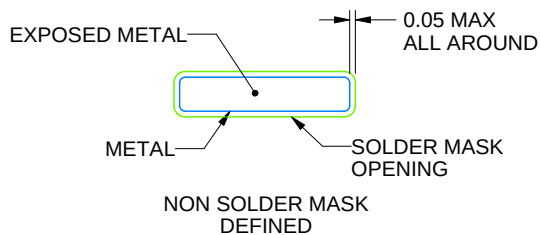
PM0064A

LQFP - 1.6 mm max height

PLASTIC QUAD FLATPACK



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X



SOLDER MASK DETAILS

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NOTES: (continued)

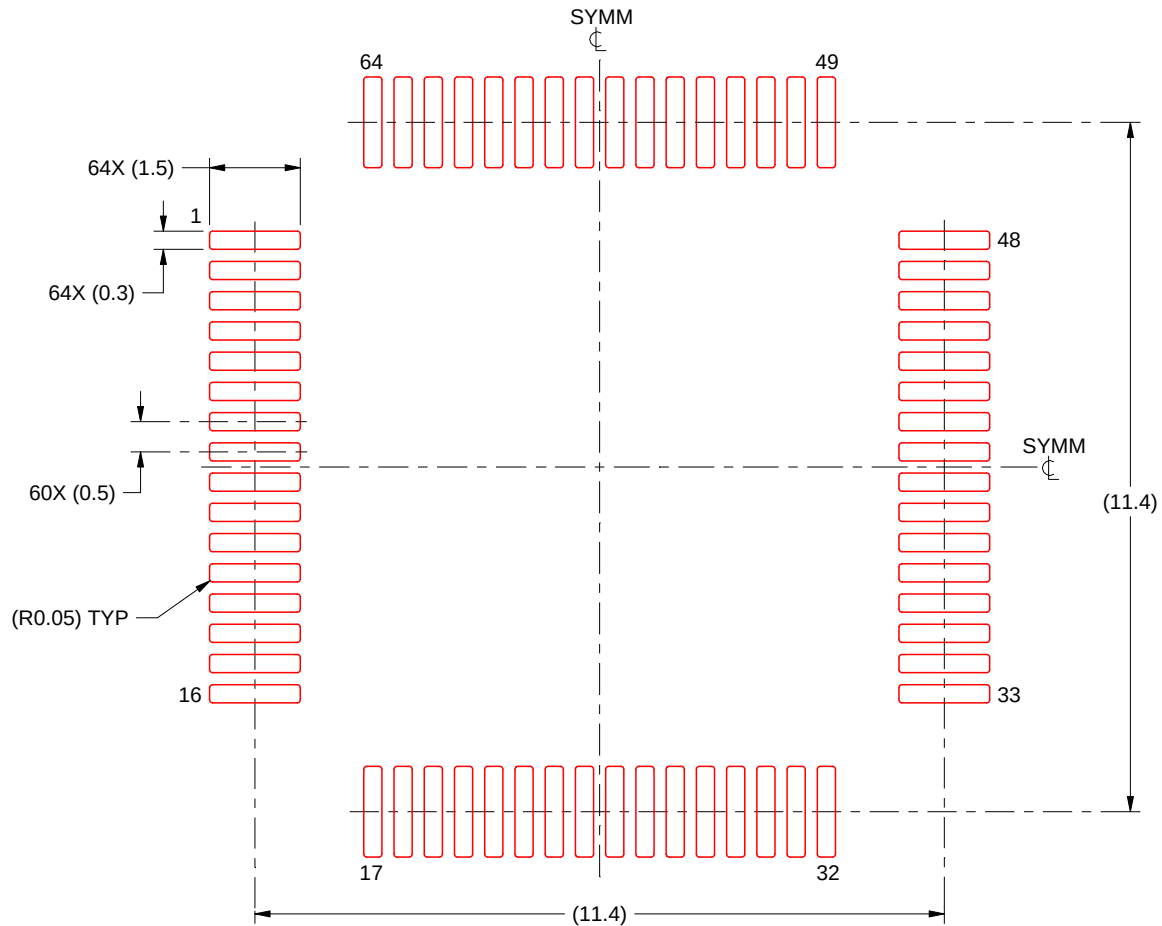
5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
7. For more information, see Texas Instruments literature number SLMA004 (www.ti.com/lit/slma004).

EXAMPLE STENCIL DESIGN

PM0064A

LQFP - 1.6 mm max height

PLASTIC QUAD FLATPACK



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:8X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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