

SBOS147A – SEPTEMBER 1986 – JULY 2005

Fast-Settling FET-Input INSTRUMENTATION AMPLIFIER

FEATURES

- LOW BIAS CURRENT: 50pA max
- FAST SETTling: 4 μ s to 0.01%
- HIGH CMR: 106dB min; 90dB at 10kHz
- INTERNAL GAINS: 1, 10, 100, 200, 500
- VERY LOW GAIN DRIFT: 10 to 50ppm/°C
- LOW OFFSET DRIFT: 2 μ V/°C
- LOW COST
- PINOUT SIMILAR TO AD524 AND AD624

APPLICATIONS

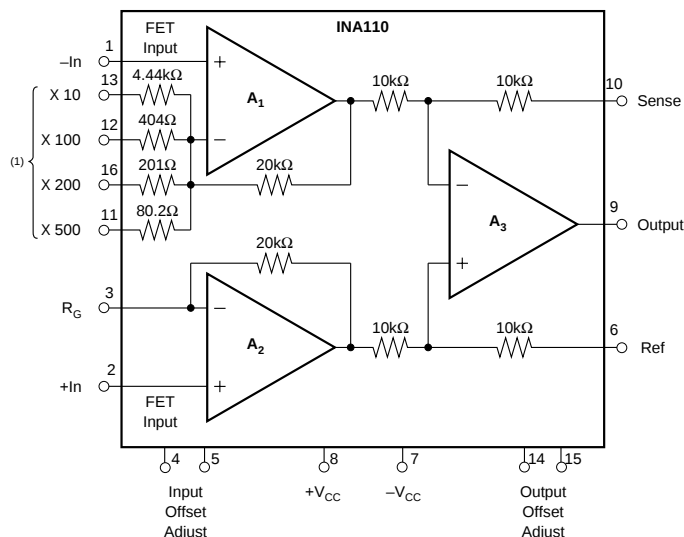
- MULTIPLEXED INPUT DATA ACQUISITION SYSTEM
- FAST DIFFERENTIAL PULSE AMPLIFIER
- HIGH SPEED GAIN BLOCK
- AMPLIFICATION OF HIGH IMPEDANCE SOURCES

DESCRIPTION

The INA110 is a versatile monolithic FET-input instrumentation amplifier. Its current-feedback circuit topology and laser trimmed input stage provide excellent dynamic performance and accuracy. The INA110 settles in 4 μ s to 0.01%, making it ideal for high speed or multiplexed-input data acquisition systems.

Internal gain-set resistors are provided for gains of 1, 10, 100, 200, and 500V/V. Inputs are protected for differential and common-mode voltages up to $\pm V_{CC}$. Its very high input impedance and low input bias current make the INA110 ideal for applications requiring input filters or input protection circuitry.

The INA110 is available in 16-pin plastic and ceramic DIPs, and in the SOL-16 surface-mount package. Military, industrial and commercial temperature range grades are available.



NOTE: (1) Connect to R_G for desired gain.



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PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

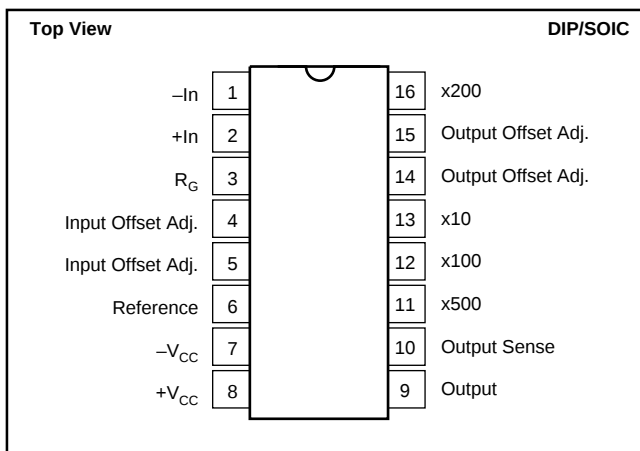
Supply Voltage	$\pm 18\text{V}$
Input Voltage Range	$\pm V_{CC}$
Operating Temperature Range: G	-55°C to $+125^{\circ}\text{C}$
P, U	-25°C to $+85^{\circ}\text{C}$
Storage Temperature Range: G	-65°C to $+150^{\circ}\text{C}$
P, U	-40°C to $+85^{\circ}\text{C}$
Lead Temperature (soldering, 10s): G, P	$+300^{\circ}\text{C}$
(soldering, 3s): U	$+260^{\circ}\text{C}$
Output Short Circuit Duration	Continuous to Common

NOTE: (1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability.

PACKAGE/ORDERING INFORMATION

For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

PIN CONFIGURATION



ELECTROSTATIC DISCHARGE SENSITIVITY

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

ELECTRICAL CHARACTERISTICS

At +25°C, $\pm V_{CC} = 15\text{VDC}$, and $R_L = 2\text{k}\Omega$, unless otherwise specified.

PARAMETER	CONDITIONS	INA110AG			INA110BG, SG			INA110KP, KU			UNITS
		MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
GAIN											
Range of Gain		1	*	800	*	$G = 1 + [40\text{k}/(R_G + 50\Omega)]$	*	*	*	*	V/V
Gain Equation ⁽¹⁾			*						*	*	V/V
Gain Error, DC: $G = 1$			0.002	0.04		*	0.02		*	*	%
$G = 10$			0.01	0.1		0.005	0.05		*	*	%
$G = 100$			0.02	0.2		0.01	0.1		*	*	%
$G = 200$			0.04	0.4		0.02	0.2		*	*	%
$G = 500$			0.1	1		0.05	0.5		*	*	%
Gain Temp. Coefficient: $G = 1$			± 3	± 20		*	± 10		*	*	ppm/°C
$G = 10$			± 4	± 20		± 2	± 10		*	*	ppm/°C
$G = 100$			± 6	± 40		± 3	± 20		*	*	ppm/°C
$G = 200$			± 10	± 60		± 5	± 30		*	*	ppm/°C
$G = 500$			± 25	± 100		± 10	± 50		*	*	ppm/°C
Nonlinearity, DC: $G = 1$			± 0.001	± 0.01		± 0.0005	± 0.005		*	*	% of FS
$G = 10$			± 0.002	± 0.01		± 0.001	± 0.005		*	*	% of FS
$G = 100$			± 0.004	± 0.02		± 0.002	± 0.01		*	*	% of FS
$G = 200$			± 0.006	± 0.02		± 0.003	± 0.01		*	*	% of FS
$G = 500$			± 0.01	± 0.04		± 0.005	± 0.02		*	*	% of FS
OUTPUT											
Voltage, $R_L = 2\text{k}\Omega$	Over Temperature	± 10	± 12.7		*	*		*	*		V
Current	Over Temperature	± 5	± 25		*	*		*	*		mA
Short-Circuit Current			± 25			*			*		mA
Capacitive Load	Stability		5000			*			*		pF
INPUT OFFSET VOLTAGE⁽²⁾											
Initial Offset: G, P			$\pm(100 + 1000/G)$	$\pm(500 + 5000/G)$		$\pm(50 + 600/G)$	$\pm(250 + 3000/G)$		*	*	μV
U									$\pm(200 + 2000/G)$	$\pm(1000 + 5000/G)$	μV
vs Temperature			$\pm(2 + 20/G)$	$\pm(5 + 100/G)$		$\pm(1 + 10/G)$	$\pm(2 + 50/G)$		*	*	$\mu\text{V}/^\circ\text{C}$
vs Supply	$V_{CC} = \pm 6\text{V to } \pm 18\text{V}$		$\pm(4 + 60/G)$	$\pm(30 + 300/G)$		$\pm(2 + 30/G)$	$\pm(10 + 180/G)$		*	*	$\mu\text{V/V}$
BIAS CURRENT											
Initial Bias Current	Each Input		20	100		10	50		*	*	pA
Initial Offset Current			2	50		1	25		*	*	pA
Impedance: Differential			$5 \times 10^{12} 6$			*			*	*	ΩpF
Common-Mode			$2 \times 10^{12} 1$			*			*	*	ΩpF
VOLTAGE RANGE											
Range, Linear Response	$V_{IN} \text{ Diff.} = 0\text{V}^{(3)}$	± 10	± 12					*	*		V
CMR with $1\text{k}\Omega$ Source Imbalance:											
$G = 1$	DC	70	90		80	100		*	*		dB
$G = 10$	DC	87	104		96	112		*	*		dB
$G = 100$	DC	100	110		106	116		*	*		dB
$G = 200$	DC	100	110		106	116		*	*		dB
$G = 500$	DC	100	110		106	116		*	*		dB
INPUT NOISE⁽⁴⁾											
Voltage, $f_O = 10\text{kHz}$			10			*			*		$\text{nV}/\sqrt{\text{Hz}}$
$f_B = 0.1\text{Hz to } 10\text{Hz}$			1			*			*		μV_{PP}
Current, $f_O = 10\text{kHz}$			1.8			*			*		$\text{fA}/\sqrt{\text{Hz}}$
OUTPUT NOISE⁽⁴⁾											
Voltage, $f_O = 10\text{kHz}$			65			*			*		$\text{nV}/\sqrt{\text{Hz}}$
$f_B = 0.1\text{Hz to } 10\text{Hz}$			8			*			*		μV_{PP}
DYNAMIC RESPONSE											
Small Signal: $G = 1$	-3dB		2.5			*			*		MHz
$G = 10$			2.5			*			*		MHz
$G = 100$			470			*			*		kHz
$G = 200$			240			*			*		kHz
$G = 500$			100			*			*		kHz
Full Power	$V_{OUT} = \pm 10\text{V},$ $G = 2 \text{ to } 100$	190	270		*	*			*	*	kHz
Slew Rate	$G = 2 \text{ to } 100$	12	17		*	*			*	*	V/ μs
Settling Time:	$V_O = 20\text{V Step}$										
0.1%, $G = 1$			4			*			*		μs
$G = 10$			2			*			*		μs
$G = 100$			3			*			*		μs
$G = 200$			5			*			*		μs
$G = 500$			11			*			*		μs

ELECTRICAL CHARACTERISTICS (Cont)

At +25°C, $\pm V_{CC}$ 15VDC, and $R_L = 2K\Omega$, unless otherwise specified.

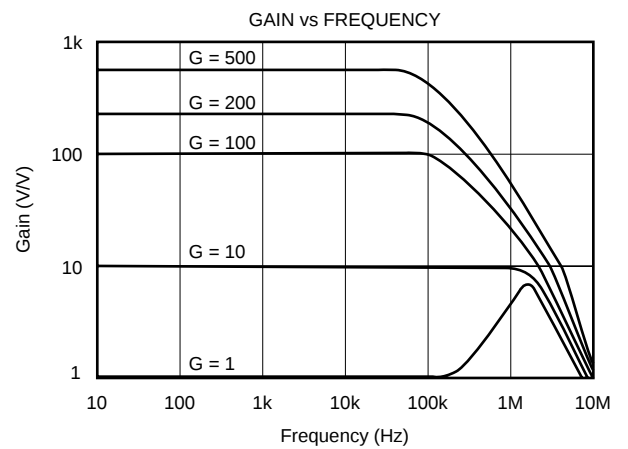
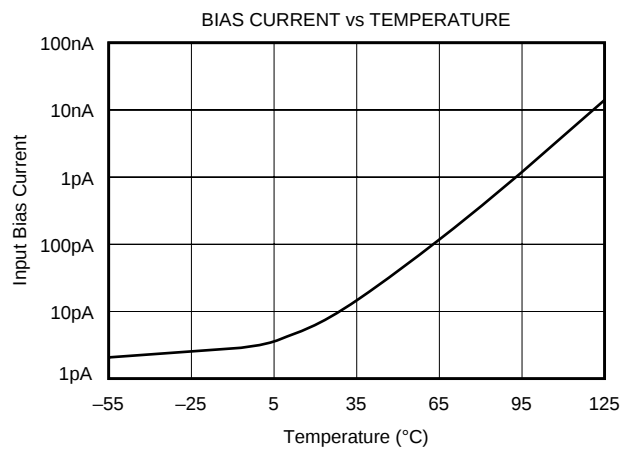
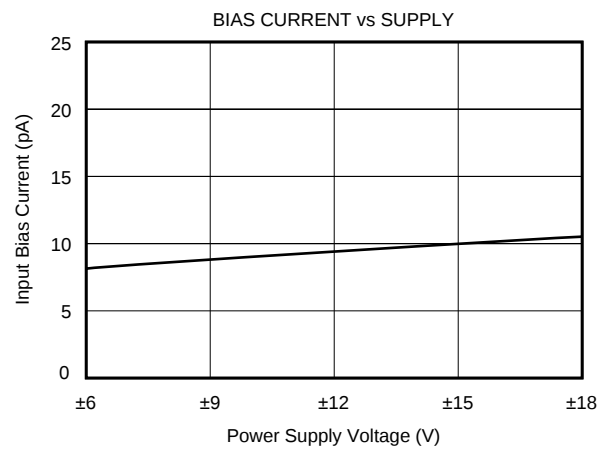
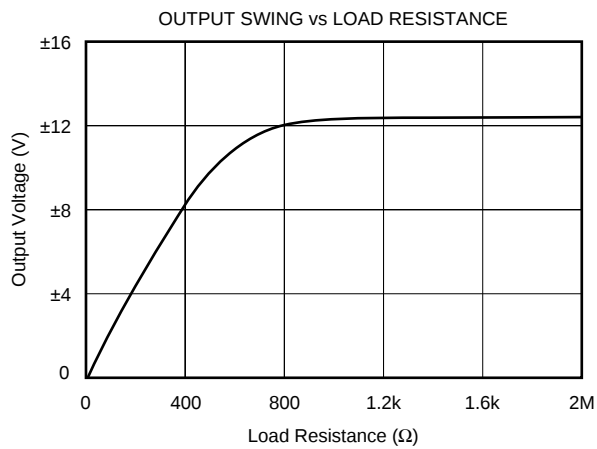
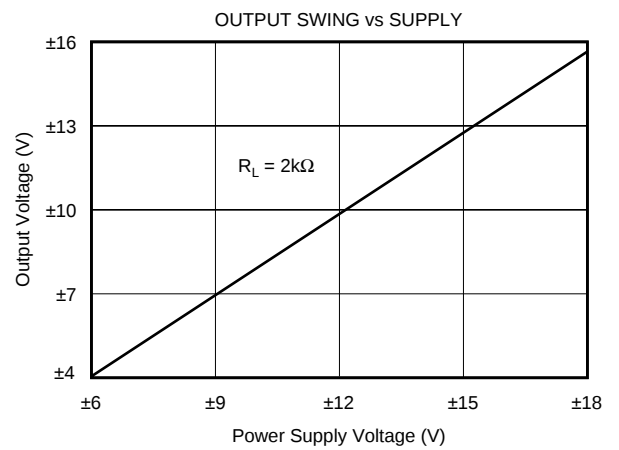
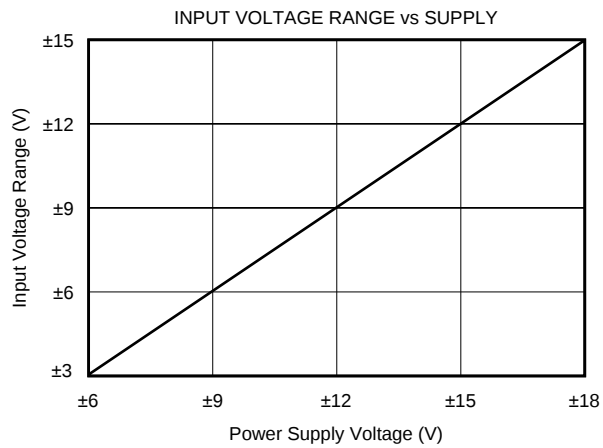
PARAMETER	CONDITIONS	INA110AG			INA110BG, SG			INA110KP, KU			UNITS
		MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
DYNAMIC RESPONSE (CONT) Settling Time: 0.01%, G = 1 G = 10 G = 100 G = 200 G = 500 Recovery ⁽⁵⁾	$V_O = 20V$ Step 50% Overdrive		5 3 4 7 16 1	12.5 7.5 7.5 12.5 25		* * * * * *	* * * * *		* * * * * *		μS μS μS μS μS μS
POWER SUPPLY Rated Voltage Voltage Range Quiescent Current	$V_O = 0V$	± 6	± 15 ± 3	± 18 ± 4.5	*	* *	* *	*	* *	* *	V V mA
TEMPERATURE RANGE Specification: P, U G Operation Storage θ_{JA}		-25 -55 -65	100	+85 +125 +150	* -55 *		* +125 * *	0 -25 -40		+70 +85 +85	°C °C °C °C °C/W

* Same as INA110AG.

NOTES: (1) Gains other than 1, 10, 100, 200, and 500 can be set by adding an external resistor, R_G , between pin 3 and pins 11, 12 and 16. Gain accuracy is a function of R_G and the internal resistors which have a $\pm 20\%$ tolerance with 20ppm/°C drift. (2) Adjustable to zero. (3) For differential input voltage other than zero, see Typical Characteristics. (4) $V_{NOISE RTI} = \sqrt{V_{N INPUT}^2 + (V_{N OUTPUT}/Gain)^2}$. (5) Time required for output to return from saturation to linear operation following the removal of an input overdrive voltage.

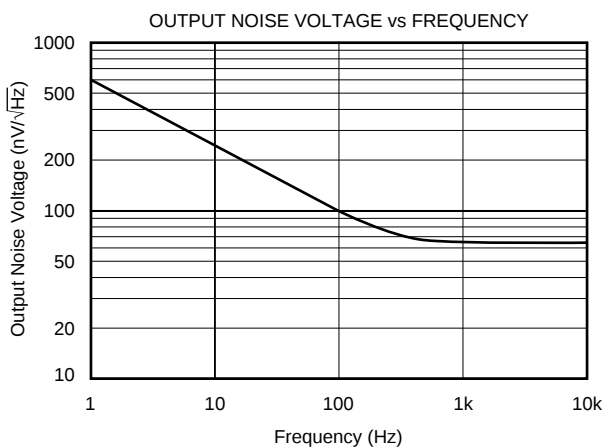
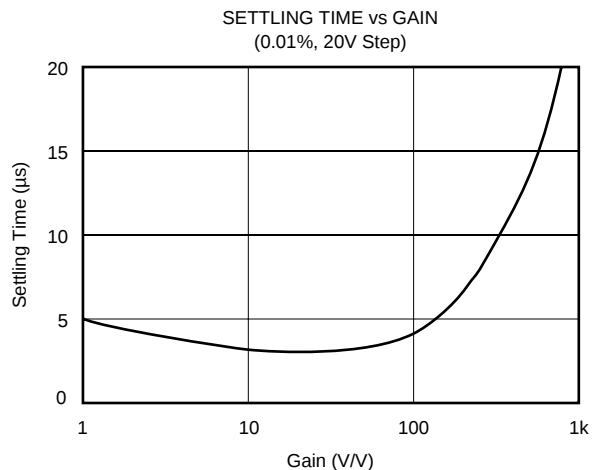
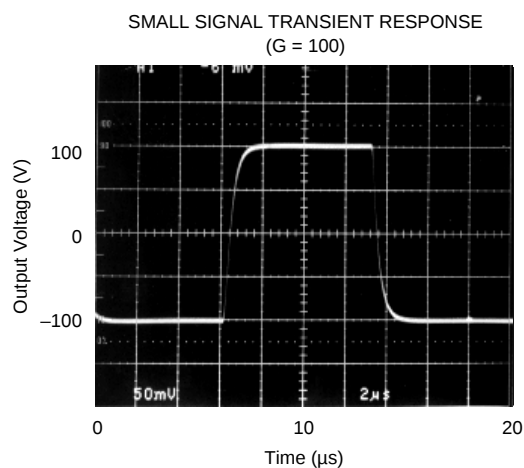
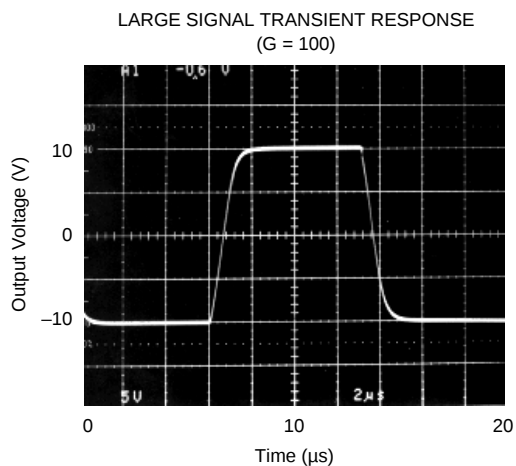
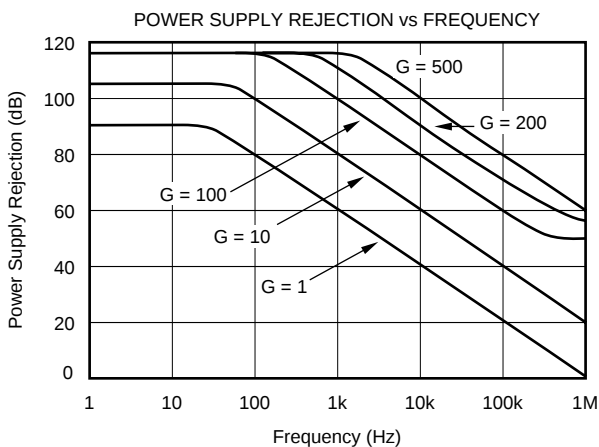
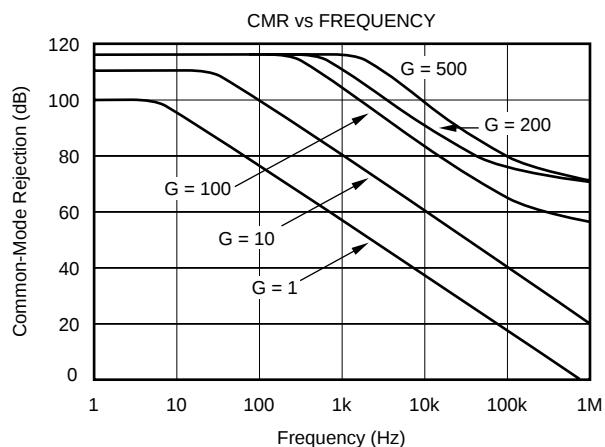
TYPICAL CHARACTERISTICS

At $T_A = +25^\circ\text{C}$ and $\pm V_{CC} = 15\text{VDC}$, unless otherwise noted.



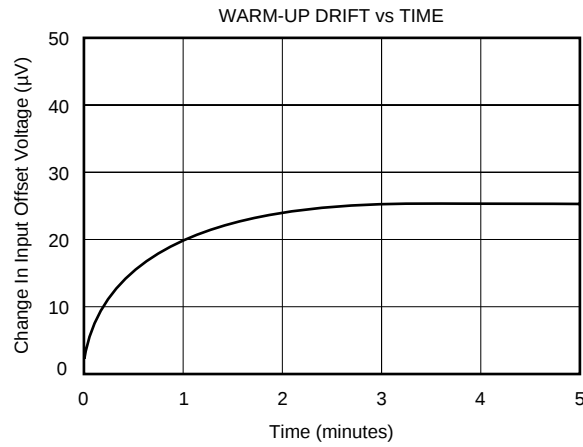
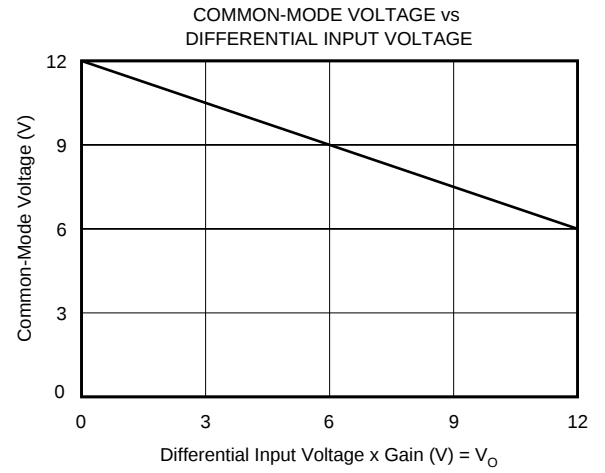
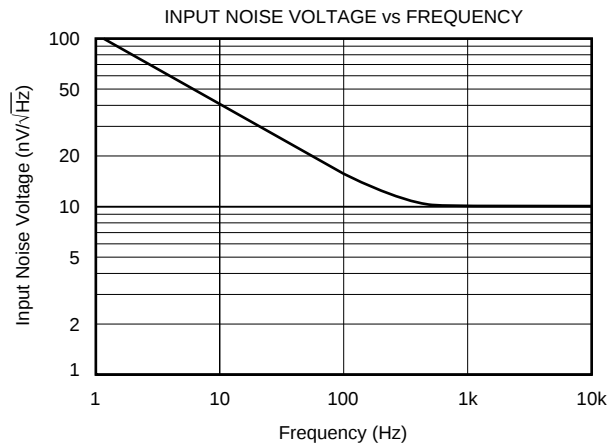
TYPICAL CHARACTERISTICS (Cont)

At $T_A = +25^\circ\text{C}$ and $\pm V_{CC} = 15\text{VDC}$, unless otherwise noted.



TYPICAL CHARACTERISTICS (Cont)

At $T_A = +25^\circ\text{C}$ and $\pm V_{CC} = 15\text{VDC}$, unless otherwise noted.



DISCUSSION OF PERFORMANCE

A simplified diagram of the INA110 is shown on the first page. The design consists of the classical three operational amplifier configuration using current-feedback type op amps with precision FET buffers on the input. The result is an instrumentation amplifier with premium performance not normally found in integrated circuits.

The input section (A_1 and A_2) incorporates high performance, low bias current, and low drift amplifier circuitry. The amplifiers are connected in the noninverting configuration to provide high input impedance ($10^{12}\Omega$). Laser-trimming is used to achieve low offset voltage. Input cascoding assures low bias current and high CMR. Thin-film resistors on the integrated circuit provide excellent gain accuracy and temperature stability.

The output section (A_3) is connected in a unity-gain difference amplifier configuration. Precision matching of the four $10\text{k}\Omega$ resistors, especially over temperature and time, assures high common-mode rejection.

BASIC POWER SUPPLY AND SIGNAL CONNECTIONS

Figure 1 shows the proper connections for power supply and signal. Supplies should be decoupled with $1\mu\text{F}$ tantalum capacitors as close to the amplifier as possible. To avoid gain and CMR errors introduced by the external circuit, connect grounds as indicated, being sure to minimize ground resistance. Resistance in series with the reference (pin 6) will degrade CMR. To maintain stability, avoid capacitance from the output to the gain set, offset adjust, and input pins.

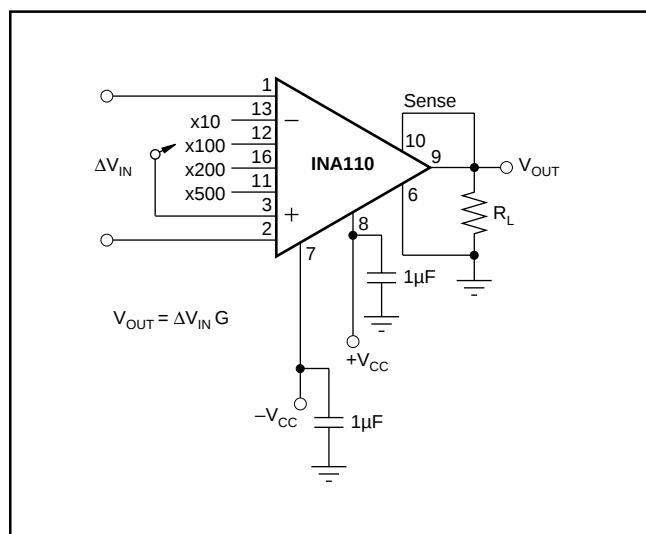


FIGURE 1. Basic Circuit Connection.

OFFSET ADJUSTMENT

Figure 2 shows the offset adjustment circuit for the INA110. Both the offset of the input stage and output stage can be adjusted separately. Notice that the offset referred to the

INA110's input (RTI) is the offset of the input stage plus the offset of the output stage divided by the gain of the input stage. This allows specification of offset independent of gain.

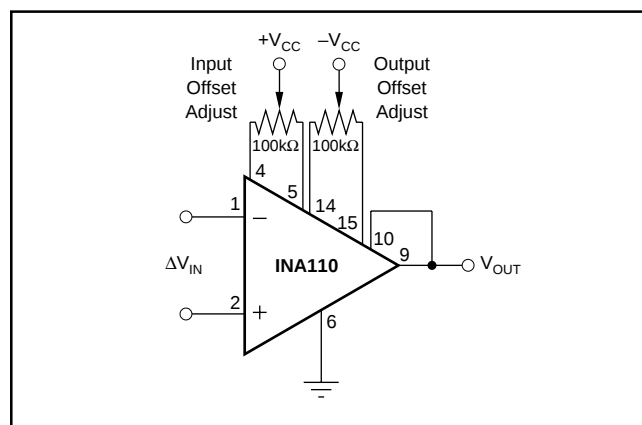


FIGURE 2. Offset Adjustment Circuit.

For systems using computer autozeroing techniques, neither offset nor offset drift are of concern. In many other applications, the factory-trimmed offset gives excellent results. When greater accuracy is desired, one adjustment is usually sufficient. In high gains (>100) adjust only the input offset, and in low gains the output offset. For higher precision in all gains, both can be adjusted by first selecting high gain and adjusting input offset and then low gain and adjusting output offset. The offset adjustment will, however, add to the drift by approximately $0.33\mu\text{V}/^{\circ}\text{C}$ per $100\mu\text{V}$ of input offset voltage that is adjusted. Therefore, care should be taken when considering use of adjustment.

Output offsetting can be accomplished as shown in Figure 3 by applying a voltage to the reference (pin 6) through a buffer. This limits the resistance in series with pin 6 to minimize CMR error. Be certain to keep this resistance low. Note that the offset error can be adjusted at this reference point with no appreciable degradation in offset drift.

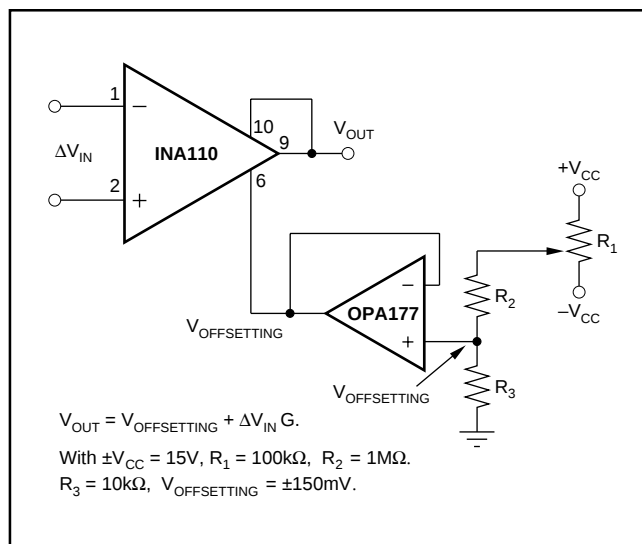


FIGURE 3. Output Offsetting.

GAIN SELECTION

Gain selection is accomplished by connecting the appropriate pins together on the INA110. Table I shows possible gains from the internal resistors. Keep the connections as short as possible to maintain accuracy.

GAIN	CONNECT PIN 3 TO PIN	GAIN ACCURACY (%)	GAIN DRIFT (ppm/°C)
The following gains have assured accuracy:			
1	none	0.02	10
10	13	0.05	10
100	12	0.1	20
200	16	0.2	30
500	11	0.5	50
The following gains have typical accuracy as shown:			
300	12, 16	0.25	10
600	11, 12	0.25	40
700	11, 16	2	40
800	11, 12, 16	2	80

TABLE I. Internal Gain Connections.

Gains other than 1, 10, 100, 200, and 500 can be set by adding an external resistor, R_G , between pin 3 and pins 12, 16, and 11. Gain accuracy is a function of R_G and the internal resistors which have a $\pm 20\%$ tolerance with 20ppm/°C drift. The equation for choosing R_G is shown below.

$$R_G = \frac{40k\Omega}{G - 1} - 50\Omega$$

Gain can also be changed in the output stage by adding resistance to the feedback loop shown in Figure 4. This is useful for increasing the total gain or reducing the input stage gain to prevent saturation of input amplifiers.

The output gain can be changed as shown in Table II. Matching of R_1 and R_3 is required to maintain high CMR. R_2 sets the gain with no effect on CMR.

OUTPUT STAGE GAIN	R_1 AND R_3	R_2
2	1.2k Ω	2.74k Ω
5	1k Ω	511 Ω
10	1.5k Ω	340 Ω

TABLE II. Output Stage Gain Control.

COMMON-MODE INPUT RANGE

It is important not to exceed the input amplifiers' dynamic range (see Typical Characteristics). The differential input signal and its associated common-mode voltage should not cause the output of A_1 and A_2 (input amplifiers) to exceed approximately $\pm 10V$ with $\pm 15V$ supplies or nonlinear operation will result. Such large common-mode voltages, when the INA110 is in high gain, can cause saturation of the input stage even though the differential input is very small. This can be avoided by reducing the input stage gain and increasing the output stage gain with an H pad attenuator (see Figure 4).

OUTPUT SENSE

An output sense has been provided to allow greater accuracy in connecting the load. By attaching this feedback point to the load at the load site, IR drops due to load currents that

are eliminated since they are inside the feedback loop. Proper connection is shown in Figure 1. When more current is to be supplied, a power booster can be placed within the feedback loop as shown in Figure 5. Buffer errors are minimized by the loop gain of the output amplifier.

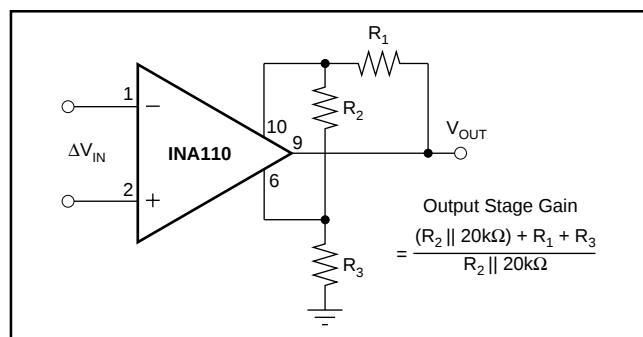


FIGURE 4. Gain Adjustment of Output Stage Using H Pad Attenuator.

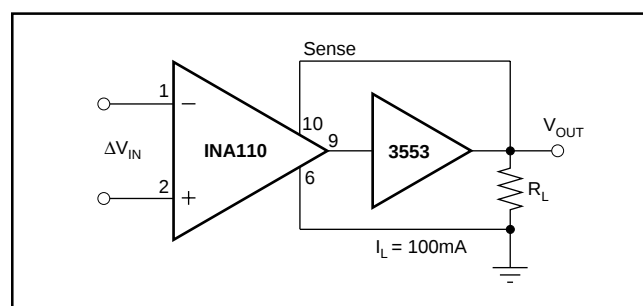


FIGURE 5. Current Boosting the Output.

LOW BIAS CURRENT OF FET INPUT ELIMINATES DC ERRORS

Because the INA110 has FET inputs, bias currents drawn through input source resistors have a negligible effect on DC accuracy. The picoamp levels produce no more than microvolts through megohm sources. Thus, input filtering and input series protection are readily achievable.

A return path for the input bias currents must always be provided to prevent charging of stray capacitance. Otherwise, the output can wander and saturate. A 1M Ω to 10M Ω resistor from the input to common will return floating sources such as transformers, thermocouples, and AC-coupled inputs (see Applications section).

DYNAMIC PERFORMANCE

The INA110 is a fast-settling FET input instrumentation amplifier. Therefore, careful attention to minimize stray capacitance is necessary to achieve specified performance. High source resistance will interact with input capacitance to reduce the overall bandwidth. Also, to maintain stability, avoid capacitance from the output to the gain set, offset adjust, and input pins.

Applications with balanced-source impedance will provide the best performance. In some applications, mismatched source impedances may be required. If the impedance in the

negative input exceeds that in the positive input, stray capacitance from the output will create a net negative feedback and improve the circuit stability. If the impedance in the positive input is greater, the feedback due to stray capacitance will be positive and instability may result. The degree of positive feedback depends upon source impedance imbalance, operating gain, and board layout. The addition of a small bypass capacitor of 5pF to 50pF directly between the inputs of the IA will generally eliminate any positive feedback. CMR errors due to the input impedance mismatch will also be reduced by the capacitor.

The INA110 is designed for fast settling with easy gain selection. It has especially excellent settling in high gain. It can also be used in fast-settling unity-gain applications. As with all such amplifiers, the INA110 does exhibit significant gain peaking when set to a gain of 1. It is, however, unconditionally stable. The gain peaking can be cancelled by band-limiting the negative input to 400kHz with a simple external RC circuit for applications requiring flat response. CMR is not affected by the addition of the 400kHz RC in a gain of 1.

Another distinct advantage of the INA110 is the high frequency CMR response. High frequency noise and sharp common-mode transients will be rejected. To preserve AC CMR, be sure to minimize stray capacitance on the input lines. Matching the RCs in the two inputs will help to maintain high AC CMR.

APPLICATIONS

In addition to general purpose uses, the INA110 is designed to accurately handle two important and demanding applications: (1) inputs with high source impedances such as capacitance/crystal/photodetector sensors and low-pass filters and series-input protection devices, and (2) rapid-scanning data acquisition systems requiring fast settling time. Because the user has access to the output sense, current sources can also be constructed using a minimum of external components. Figures 6 through 19 show application circuits.

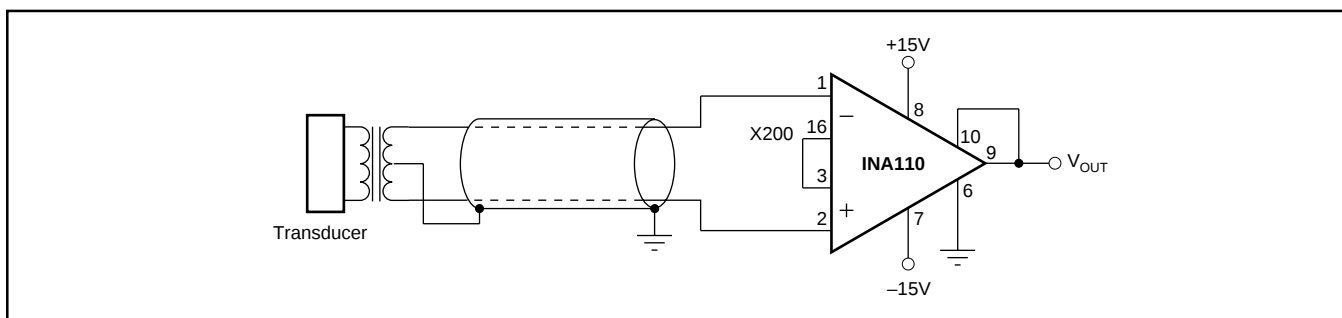


FIGURE 6. Transformer-Coupled Amplifier.

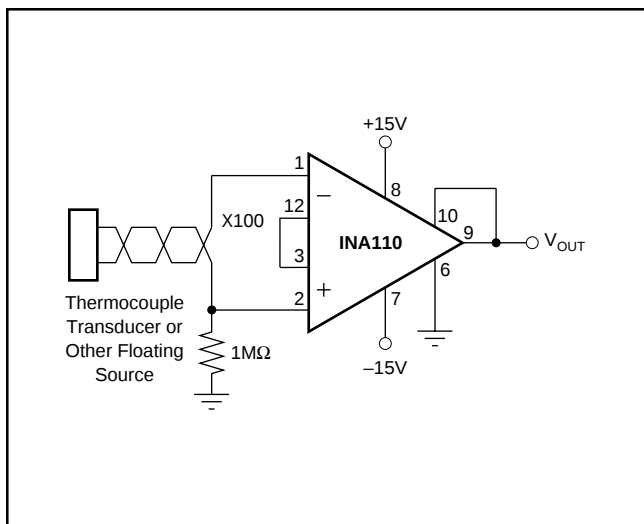


FIGURE 7. Floating Source Instrumentation Amplifier.

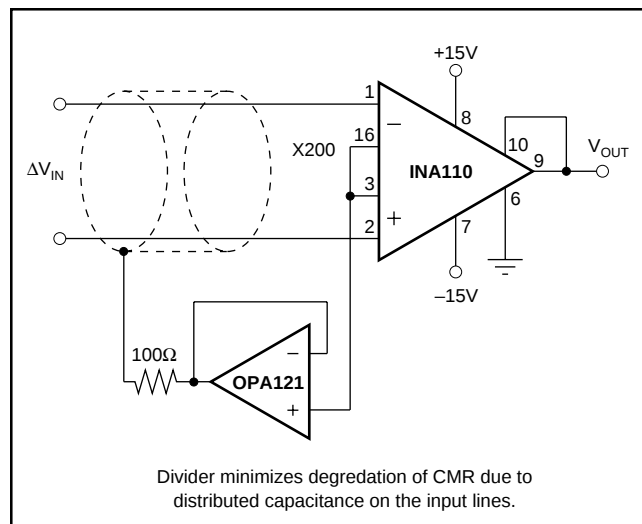


FIGURE 8. Instrumentation Amplifier with Shield Driver.

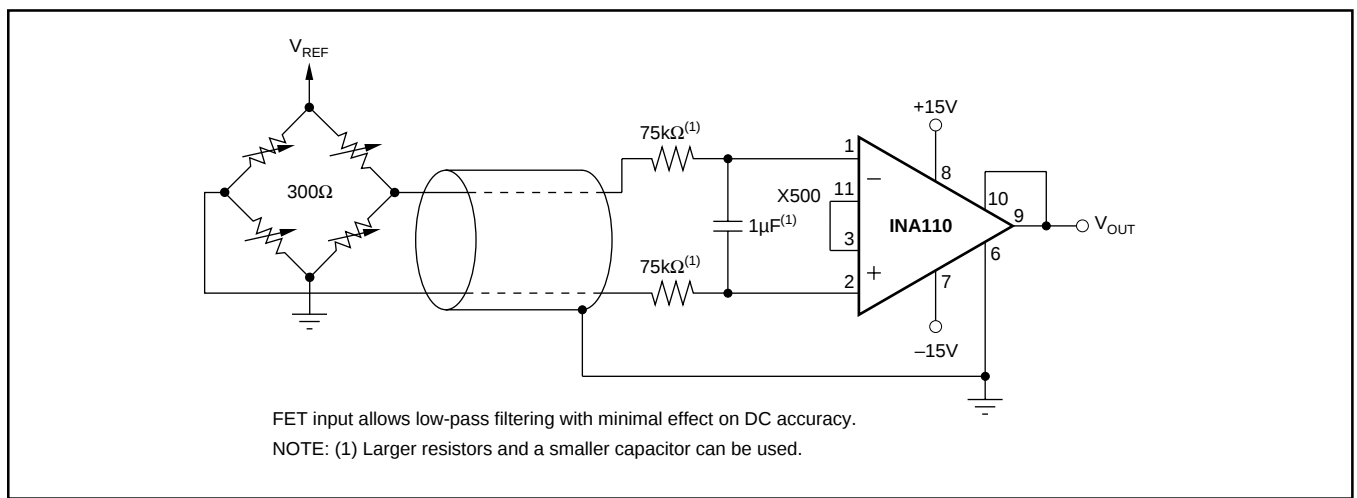


FIGURE 9. Bridge Amplifier with 1Hz Low-Pass Input Filter.

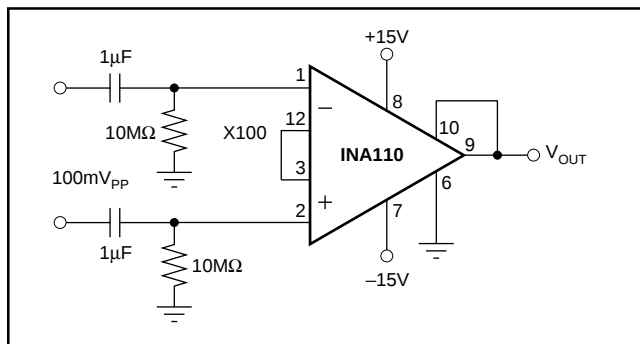


FIGURE 10. AC-Coupled Differential Amplifier for Frequencies Greater Than 0.016Hz.

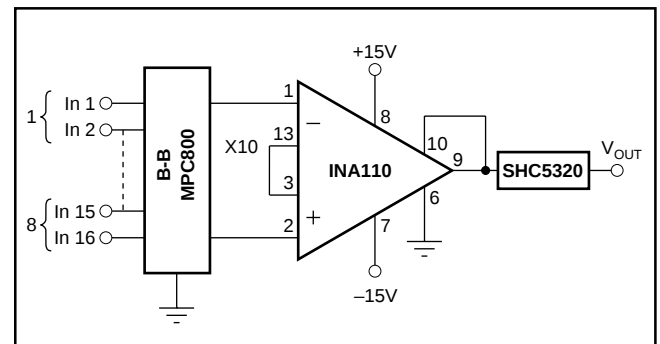


FIGURE 12. Rapid-Scanning-Rate Data Acquisition Channel with 5μs Settling to 0.01%.

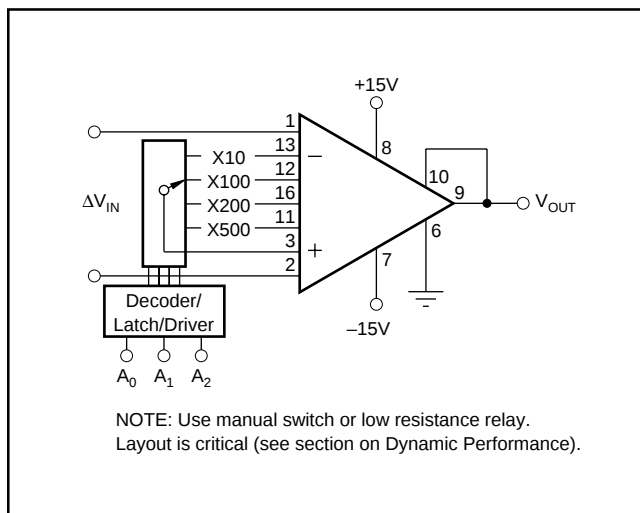


FIGURE 11. Programmable-Gain Instrumentation Amplifier (Precision Noninverting or Inverting Buffer with Gain).

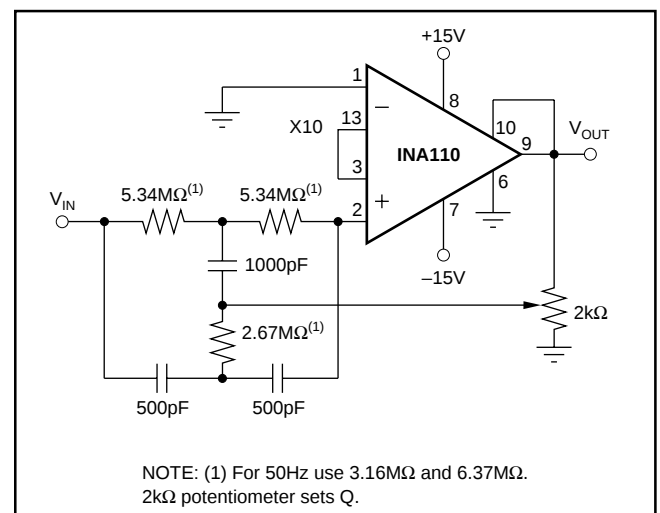


FIGURE 13. 60Hz Input Notch Filter.

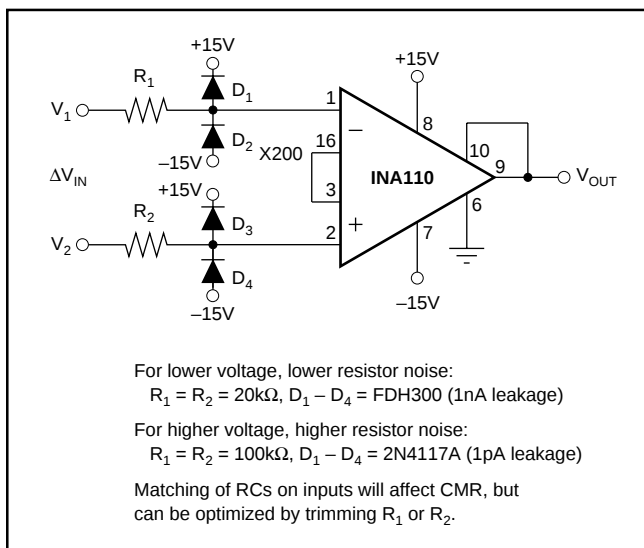


FIGURE 14. Input-Protected Instrumentation Amplifier.

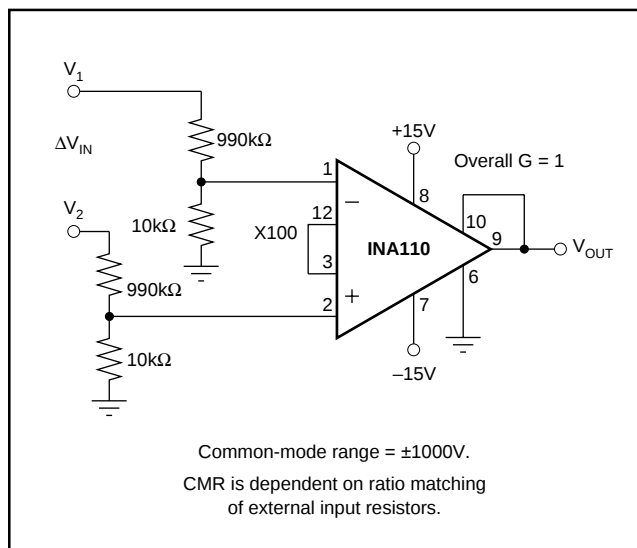


FIGURE 15. High Common-Mode Voltage Differential Amplifier.

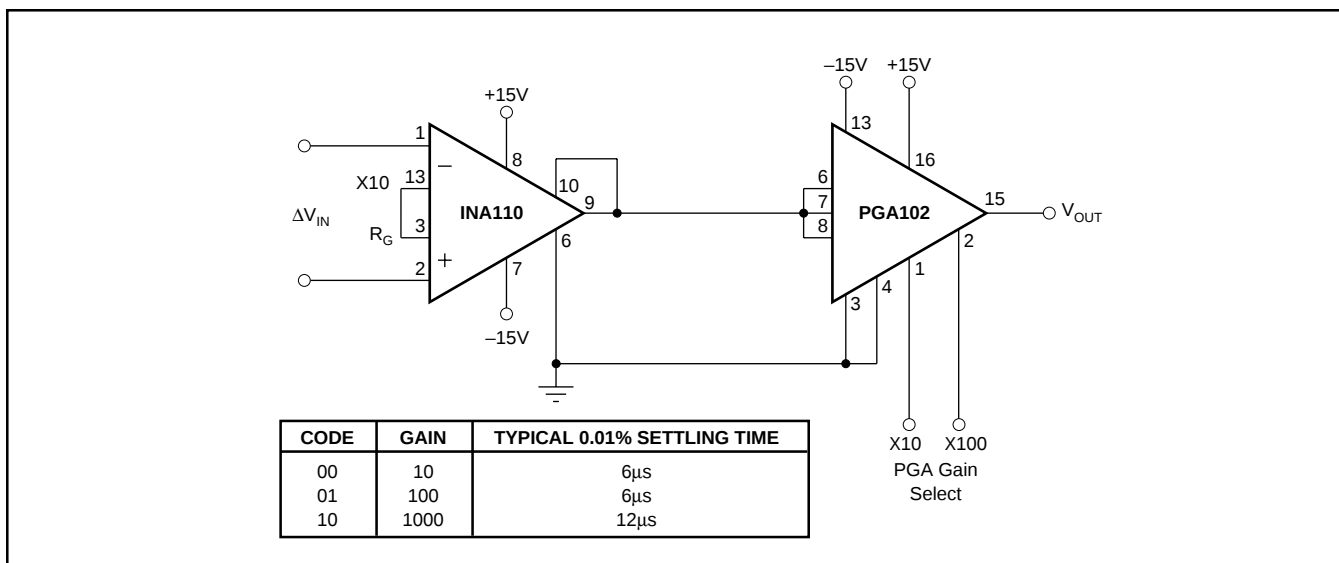


FIGURE 16. Digitally-Controlled Fast-Settling Programmable Gain Instrumentation Amplifier.

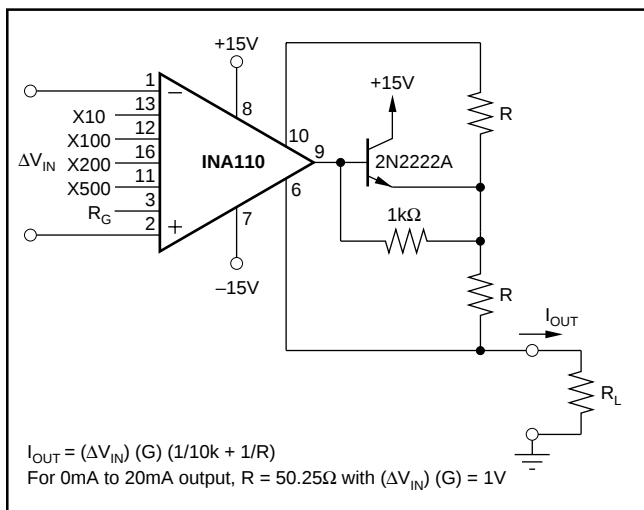


FIGURE 17. Differential Input FET Buffered Current Source.

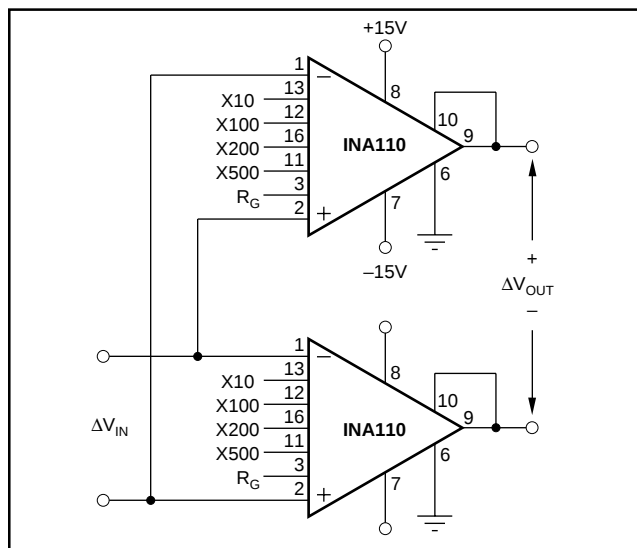


FIGURE 18. Differential Input/Differential Output Amplifier.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
INA110KP	Active	Production	PDIP (N) 16	25 TUBE	Yes	NIPDAU	N/A for Pkg Type	-55 to 125	INA110KP
INA110KP.A	Active	Production	PDIP (N) 16	25 TUBE	Yes	NIPDAU	N/A for Pkg Type	-55 to 125	INA110KP
INA110KU	Active	Production	SOIC (DW) 16	40 TUBE	Yes	NIPDAUAG	Level-3-260C-168 HR	-	INA110KU
INA110KU.A	Active	Production	SOIC (DW) 16	40 TUBE	Yes	NIPDAUAG	Level-3-260C-168 HR	-55 to 125	INA110KU
INA110SG	Active	Production	CDIP SB (JD) 16	24 TUBE	Yes	AU	N/A for Pkg Type	-	INA110SG
INA110SG.A	Active	Production	CDIP SB (JD) 16	24 TUBE	Yes	AU	N/A for Pkg Type	-55 to 125	INA110SG

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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TUBE

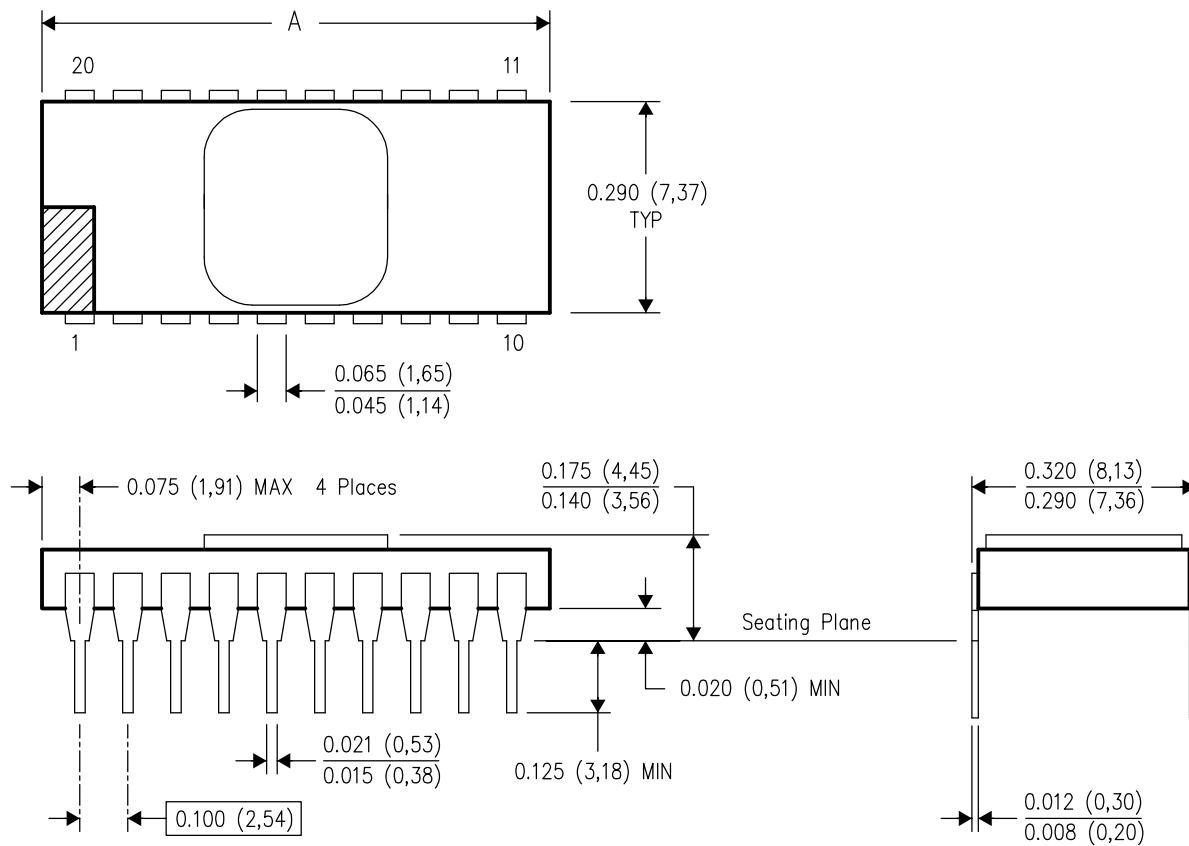

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
INA110KP	N	PDIP	16	25	506	13.97	11230	4.32
INA110KP.A	N	PDIP	16	25	506	13.97	11230	4.32
INA110KU	DW	SOIC	16	40	507	12.83	5080	6.6
INA110KU.A	DW	SOIC	16	40	507	12.83	5080	6.6
INA110SG	JD	CDIP SB	16	24	506.98	15.24	12290	NA
INA110SG.A	JD	CDIP SB	16	24	506.98	15.24	12290	NA

JD (R-CDIP-T**)

CERAMIC SIDE-BRAZE DUAL-IN-LINE PACKAGE

20 PINS SHOWN



PINS **	8	14	16	18	20	24
DIM						
A MAX	0.405 (10,29)	0.757 (19,23)	0.810 (20,57)	0.910 (23,11)	1.010 (25,65)	1.100 (27,94)

4040086-2/F 07/03

- NOTES:
- All linear dimensions are in inches (millimeters).
 - This drawing is subject to change without notice.
 - This package is hermetically sealed with a metal lid.
 - The terminals are gold plated.
 - Falls within MIL STD 1835 CDIP2 - T8, T14, T16, T18, T20 and T24 respectively.

GENERIC PACKAGE VIEW

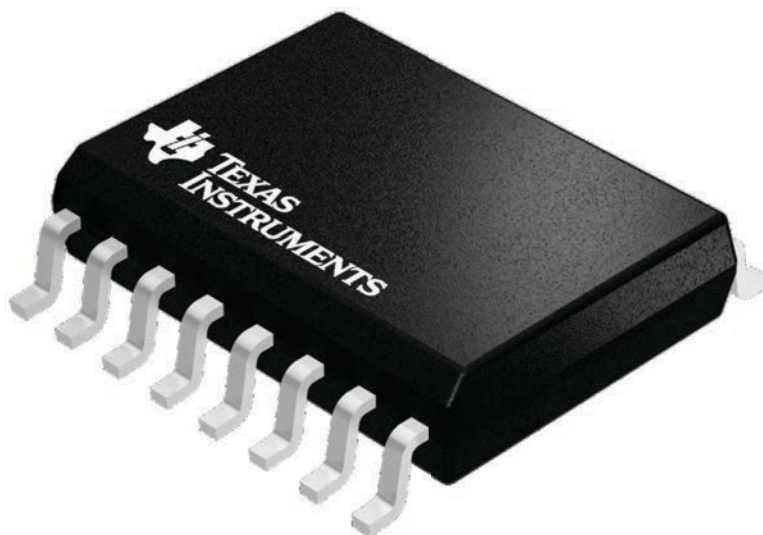
DW 16

SOIC - 2.65 mm max height

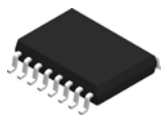
7.5 x 10.3, 1.27 mm pitch

SMALL OUTLINE INTEGRATED CIRCUIT

This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.



4224780/A

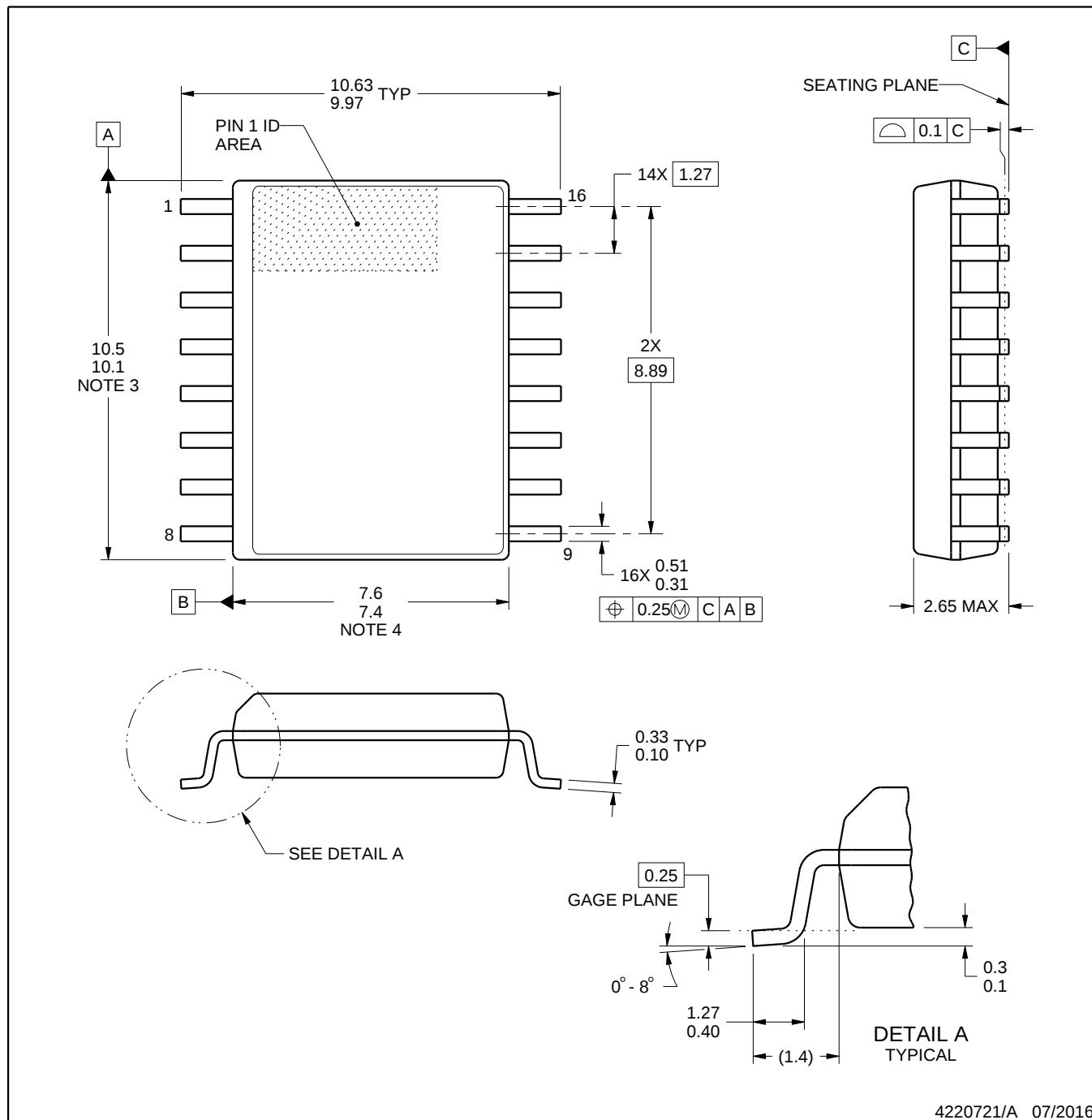


DW0016A

PACKAGE OUTLINE

SOIC - 2.65 mm max height

SOIC



4220721/A 07/2016

NOTES:

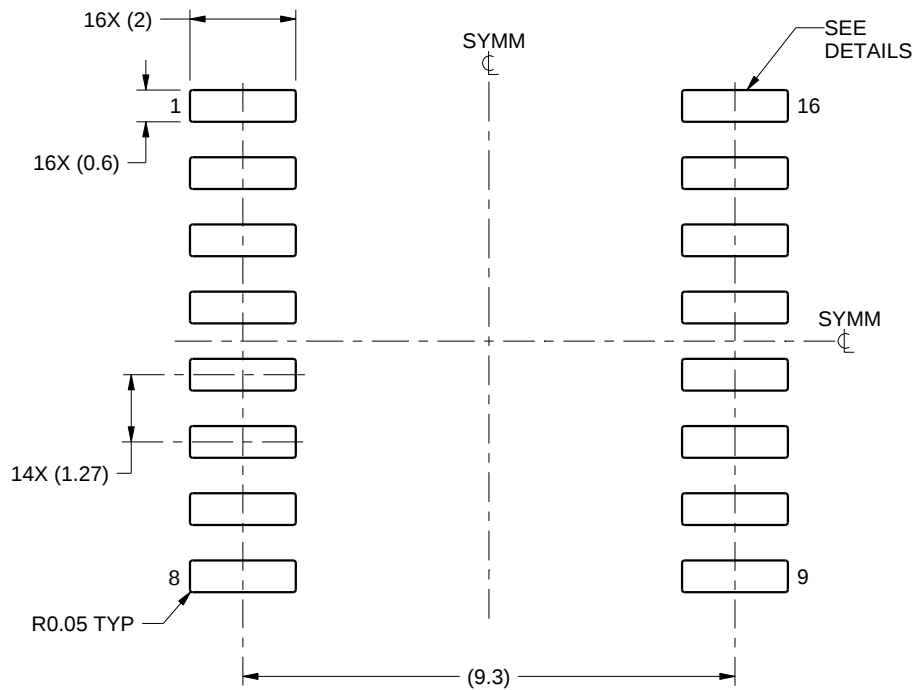
1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm, per side.
5. Reference JEDEC registration MS-013.

EXAMPLE BOARD LAYOUT

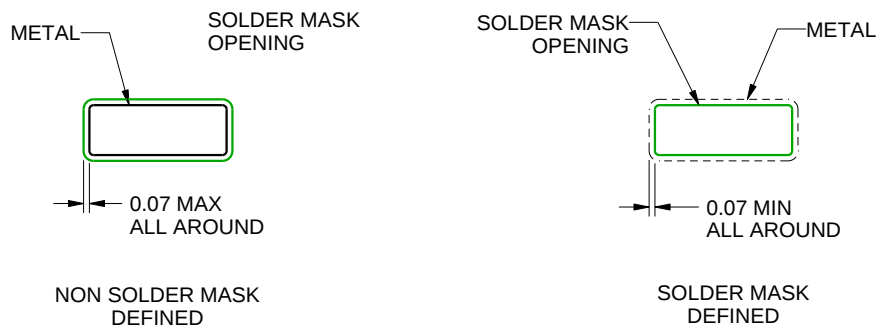
DW0016A

SOIC - 2.65 mm max height

SOIC



LAND PATTERN EXAMPLE
SCALE:7X



SOLDER MASK DETAILS

4220721/A 07/2016

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

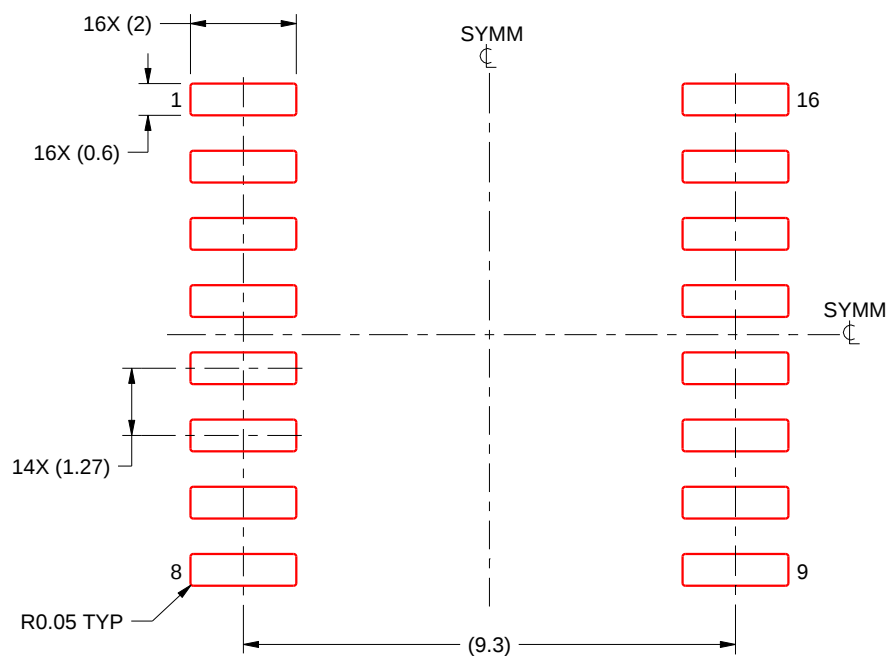
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

DW0016A

SOIC - 2.65 mm max height

SOIC



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:7X

4220721/A 07/2016

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

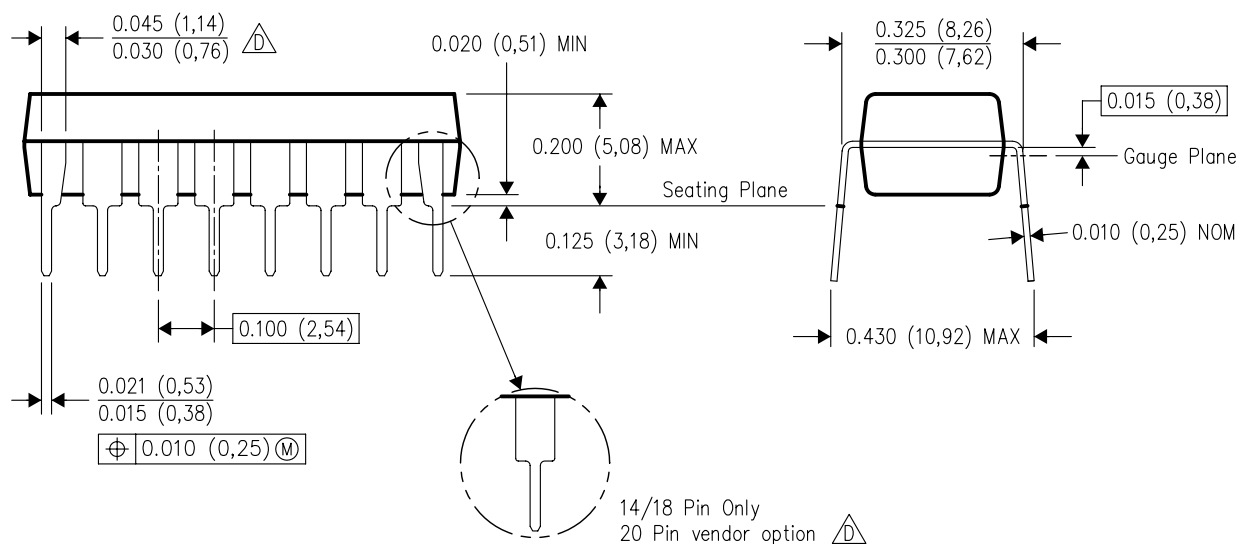
N (R-PDIP-T**)

16 PINS SHOWN

PLASTIC DUAL-IN-LINE PACKAGE



PINS ** DIM	14	16	18	20
A MAX	0.775 (19,69)	0.775 (19,69)	0.920 (23,37)	1.060 (26,92)
A MIN	0.745 (18,92)	0.745 (18,92)	0.850 (21,59)	0.940 (23,88)
MS-001 VARIATION	AA	BB	AC	AD



4040049/E 12/2002

NOTES:

- A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
-  Falls within JEDEC MS-001, except 18 and 20 pin minimum body length (Dim A).
 The 20 pin end lead shoulder width is a vendor option, either half or full width.

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