

LFx5x JFET Input Operational Amplifiers

1 Features

- Advantages
 - Replace Expensive Hybrid and Module FET Op Amps
 - Rugged JFETs Allow Blow-Out Free Handling Compared With MOSFET Input Devices
 - Excellent for Low Noise Applications Using Either High or Low Source Impedance—Very Low 1/f Corner
 - Offset Adjust Does Not Degrade Drift or Common-Mode Rejection as in Most Monolithic Amplifiers
 - New Output Stage Allows Use of Large Capacitive Loads (5,000 pF) Without Stability Problems
 - Internal Compensation and Large Differential Input Voltage Capability
- Common Features
 - Low Input Bias Current: 30 pA
 - Low Input Offset Current: 3 pA
 - High Input Impedance: $10^{12} \Omega$
 - Low Input Noise Current: $0.01 \text{ pA}/\sqrt{\text{Hz}}$
 - High Common-Mode Rejection Ratio: 100 dB
 - Large DC Voltage Gain: 106 dB
- Uncommon Features
 - Extremely Fast Settling Time to 0.01%:
 - 4 μs for the LFx55 devices
 - 1.5 μs for the LFx56
 - 1.5 μs for the LFx57 ($A_V = 5$)
 - Fast Slew Rate:
 - 5 V/ μs for the LFx55
 - 12 V/ μs for the LFx56
 - 50 V/ μs for the LFx57 ($A_V = 5$)
 - Wide Gain Bandwidth:
 - 2.5 MHz for the LFx55 devices
 - 5 MHz for the LFx56
 - 20 MHz for the LFx57 ($A_V = 5$)
 - Low Input Noise Voltage:
 - $20 \text{ nV}/\sqrt{\text{Hz}}$ for the LFx55
 - $12 \text{ nV}/\sqrt{\text{Hz}}$ for the LFx56
 - $12 \text{ nV}/\sqrt{\text{Hz}}$ for the LFx57 ($A_V = 5$)

2 Applications

- Precision High-Speed Integrators
- Fast D/A and A/D Converters
- High Impedance Buffers
- Wideband, Low Noise, Low Drift Amplifiers
- Logarithmic Amplifiers
- Photocell Amplifiers
- Sample and Hold Circuits

3 Description

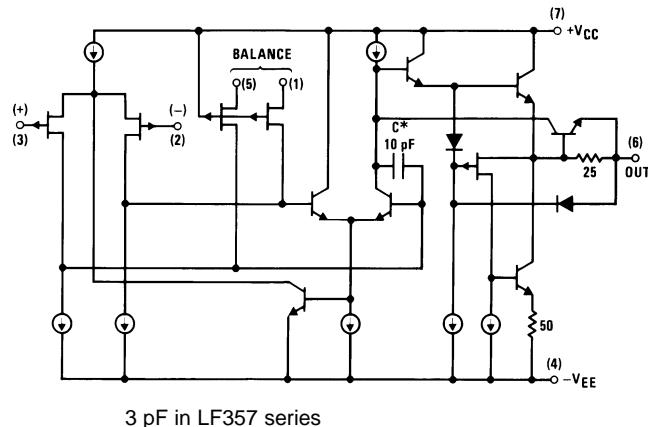
The LFx5x devices are the first monolithic JFET input operational amplifiers to incorporate well-matched, high-voltage JFETs on the same chip with standard bipolar transistors (BI-FET™ Technology). These amplifiers feature low input bias and offset currents/low offset voltage and offset voltage drift, coupled with offset adjust, which does not degrade drift or common-mode rejection. The devices are also designed for high slew rate, wide bandwidth, extremely fast settling time, low voltage and current noise and a low 1/f noise corner.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LFx5x	SOIC (8)	4.90 mm x 3.91 mm
	TO-CAN (8)	9.08 mm x 9.08 mm
	PDIP (8)	9.81 mm x 6.35 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic



An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. **PRODUCTION DATA**.

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

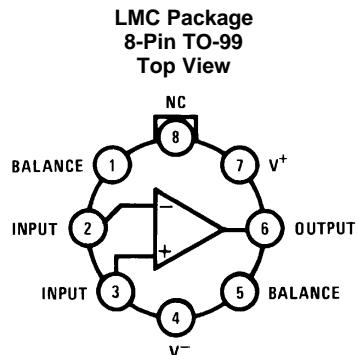
Changes from Revision C (March 2013) to Revision D

- Added *Pin Configuration and Functions* section, *ESD Ratings* table, *Thermal Information* table, *Feature Description* section, *Device Functional Modes*, *Application and Implementation* section, *Power Supply Recommendations* section, *Layout* section, *Device and Documentation Support* section, and *Mechanical, Packaging, and Orderable Information* section 1
- Removed T_{HIGH} parameter as it is redundant to T_A maximum 4

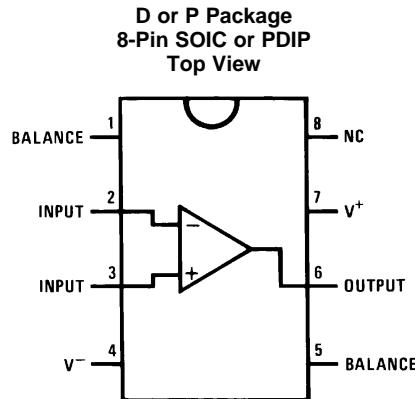
Changes from Revision B (March 2013) to Revision C

- Changed layout of National Data Sheet to TI format 31

5 Pin Configuration and Functions



Available per JM38510/11401 or
JM38510/11402



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
BALANCE	1, 5	I	Balance for input offset voltage
+INPUT	3	I	Noninverting input
-INPUT	2	I	Inverting input
NC	8	—	No connection
OUTPUT	6	O	Output
V+	7	—	Positive power supply
V-	4	—	Negative power supply

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾⁽²⁾⁽³⁾

			MIN	MAX	UNIT	
Supply voltage	LF155x, LF256x, LF356B		±22		V	
	LF35x		±18			
Differential input voltage	LF15x, LF25x, LF356B		±40		V	
	LF35x		±30			
Input voltage ⁽⁴⁾	LF15x, LF25x, LF356B		±20		V	
	LF35x		±16			
Output short circuit duration			Continuous		—	
T _{JMAX}	LMC package	LF15x		150	°C	
		LF25x, LF356B, LF35x		115		
	P package	LF25x, LF356B, LF35x		100		
	D package	LF25x, LF356B, LF35x		100		
Soldering information (lead temp.)	TO-99 package	Soldering (10 sec.)			°C	
	PDIP package	Soldering (10 sec.)				
	SOIC package	Vapor phase (60 sec.)	LF25x, LF356B, LF35x	215		
		Infrared (15 sec.)	LF25x, LF356B, LF35x	220		
Storage temperature, T _{stg}			-65	150	°C	

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{JMAX}, θ_{JA}, and the ambient temperature, T_A. The maximum available power dissipation at any temperature is P_D = (T_{JMAX} - T_A) / θ_{JA} or the 25°C P_{dMAX}, whichever is less.
- (3) If Military/Aerospace specified devices are required, contact the TI Sales Office/Distributors for availability and specifications.
- (4) Unless otherwise specified the absolute maximum negative input voltage is equal to the negative power supply voltage.

6.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾⁽²⁾	±1000	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) 100 pF discharged through 1.5-kΩ resistor

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Supply voltage, V _S	LF15x	±15	V _S	±20	V
	LF25x	±15	V _S	±20	
	LF356B	±15	V _S	±20	
	LF35x			±15	
T _A	LF15x	-55	T _A	125	°C
	LF25x	-25	T _A	85	
	LF356B	0	T _A	70	
	LF35x	0	T _A	70	

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		LF155, LF156, LF355, LF357			LF356	UNIT
		P (PDIP)	D (SOIC)	LMC (TO-99)	P (PDIP)	
		8 PINS	8 PINS	8 PINS	8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	130	195	—	55.2	°C/W
	Still Air	—	—	160	—	
	400 LF/Min Air Flow	—	—	65	—	
$R_{\theta JC(\text{top})}$	Junction-to-case (top) thermal resistance	—	—	23	44.5	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	—	—	—	32.4	°C/W
Ψ_{JT}	Junction-to-top characterization parameter	—	—	—	21.7	°C/W
Ψ_{JB}	Junction-to-board characterization parameter	—	—	—	32.3	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 AC Electrical Characteristics, $T_A = T_J = 25^\circ\text{C}$, $V_S = \pm 15 \text{ V}$

PARAMETER		TEST CONDITIONS			MIN	TYP	MAX	UNIT	
SR	Slew Rate	LF15x: $A_V = 1$	LFx55	—	—	5	—	V/μs	
			LFx56, LF356B	—	—	7.5	—		
			LFx56, LF356B	—	—	12	—		
		LF357: $A_V = 5$	LFx57	—	—	50	—		
GBW	Gain Bandwidth Product	LFx55	—	—	—	2.5	—	MHz	
		LFx56, LF356B	—	—	—	5	—		
		LFx57	—	—	—	20	—		
t_s	Settling Time to 0.01% ⁽¹⁾	LFx55	—	—	—	4	—	μs	
		LFx56, LF356B	—	—	—	1.5	—		
		LFx57	—	—	—	1.5	—		
e_n	Equivalent Input Noise Voltage	$R_S = 100 \Omega$	$f = 100 \text{ Hz}$	LFx55	—	25	—	nV/√Hz	
				LFx56, LF356B	—	15	—		
			$f = 1000 \text{ Hz}$	LFx57	—	15	—		
			$f = 1000 \text{ Hz}$	LFx55	—	20	—		
			$f = 1000 \text{ Hz}$	LFx56, LF356B	—	12	—	nV/√Hz	
			$f = 1000 \text{ Hz}$	LFx57	—	12	—		
			$f = 100 \text{ Hz}$	LFx55	—	—	0.01	pA/√Hz	
			$f = 100 \text{ Hz}$	LFx56, LF356B	—	—	0.01		
i_n	Equivalent Input Current Noise		$f = 1000 \text{ Hz}$	LFx57	—	—	—		
			$f = 1000 \text{ Hz}$	LFx55	—	—	—		
			$f = 1000 \text{ Hz}$	LFx56, LF356B	—	—	—		
C_{IN}	Input Capacitance	LFx57			—	—	3	pF	
		LFx55			—	—	—		
		LFx56, LF356B			—	—	—		

(1) Settling time is defined here, for a unity gain inverter connection using 2-kΩ resistors for the LF15x. It is the time required for the error voltage (the voltage at the inverting input pin on the amplifier) to settle to within 0.01% of its final value from the time a 10-V step input is applied to the inverter. For the LF357, $A_V = -5$, the feedback resistor from output to input is 2 kΩ and the output step is 10 V (See [Settling Time Test Circuit](#)).

6.6 DC Electrical Characteristics, $T_A = T_J = 25^\circ\text{C}$, $V_S = \pm 15 \text{ V}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply current	LF155		2	4	mA
	LF355		2	4	
	LFx56, LF356B		5	7	
	LF356		5	10	
	LF357		5	10	

6.7 DC Electrical Characteristics

See ⁽¹⁾

PARAMETER	TEST CONDITIONS			MIN	TYP	MAX	UNIT	
V_{OS} Input offset voltage	$R_S = 50 \Omega$	$T_A = 25^\circ\text{C}$	LF15x, LF25x, LF356B		3	5	mV	
			LF35x		3	10		
		Over temperature	LF15x		7			
			LF25x, LF356B		6.5			
			LF35x		13			
$\Delta V_{OS}/\Delta T$ Average TC of input offset voltage	$R_S = 50 \Omega$	LF15x, LF25x, LF356B, LF35x			5		$\mu\text{V}/^\circ\text{C}$	
$\Delta T_C/\Delta V_{OS}$ Change in average TC with V_{OS} adjust	$R_S = 50 \Omega$ ⁽²⁾	LF15x, LF25x, LF356B, LF35x			0.5		$\mu\text{V}/^\circ\text{C}$ per mV	
I_{OS} Input offset current		$T_J = 25^\circ\text{C}$ ^{(1) (3)}	LF15x, LF25x, LF356B		3	20	pA	
			LF35x		3	50		
		$T_J \leq T_{HIGH}$	LF15x		20			
			LF25x, LF356B		1			
			LF35x		2			
I_B Input bias current		$T_J = 25^\circ\text{C}$ ^{(1) (3)}	LF15x, LF25x, LF356B		30	100	pA	
			LF35x		30	200		
		$T_J \leq T_{HIGH}$	LF15x		50			
			LF25x, LF356B		5			
			LF35x		8			
R_{IN} Input resistance	$T_J = 25^\circ\text{C}$	LF15x, LF25x, LF356B, LF35x			10^{12}		Ω	
A_{VOL} Large signal voltage gain	$V_S = \pm 15 \text{ V}$, $V_O = \pm 10 \text{ V}$, $R_L = 2 \text{ k}\Omega$	$T_A = 25^\circ\text{C}$	LF15x, LF25x, LF356B		50	200	V/mV	
			LF35x		25	200		
		Over temperature	LF15x, LF25x, LF356B		25			
			LF35x		15			
V_O Output voltage swing	$V_S = \pm 15 \text{ V}$, $R_L = 10 \text{ k}\Omega$		LF15x, LF25x, LF356B, LF35x			± 12	± 13	
	$V_S = \pm 15 \text{ V}$, $R_L = 2 \text{ k}\Omega$		LF15x, LF25x, LF356B, LF35x			± 10	± 12	

(1) Unless otherwise stated, these test conditions apply:

	LF15x	LF25x	LF356B	LF35x
Supply Voltage, V_S	$\pm 15 \text{ V} \leq V_S \leq \pm 20 \text{ V}$	$\pm 15 \text{ V} \leq V_S \leq \pm 20 \text{ V}$	$\pm 15 \text{ V} \leq V_S \leq \pm 20 \text{ V}$	$V_S = \pm 15 \text{ V}$
T_A	$-55^\circ\text{C} \leq T_A \leq +125^\circ\text{C}$	$-25^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$	$0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$	$0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$
T_{HIGH}	$+125^\circ\text{C}$	$+85^\circ\text{C}$	$+70^\circ\text{C}$	$+70^\circ\text{C}$

and V_{OS} , I_B and I_{OS} are measured at $V_{CM} = 0$.

- (2) The Temperature Coefficient of the adjusted input offset voltage changes only a small amount ($0.5 \mu\text{V}/^\circ\text{C}$ typically) for each mV of adjustment from its original unadjusted value. Common-mode rejection and open-loop voltage gain are also unaffected by offset adjustment.
- (3) The input bias currents are junction leakage currents which approximately double for every 10°C increase in the junction temperature, T_J . Due to limited production test time, the input bias currents measured are correlated to junction temperature. In normal operation the junction temperature rises above the ambient temperature as a result of internal power dissipation, P_d . $T_J = T_A + \theta_{JA} P_d$ where θ_{JA} is the thermal resistance from junction to ambient. Use of a heat sink is recommended if input bias current is to be kept to a minimum.

DC Electrical Characteristics (continued)

See ⁽¹⁾

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
V _{CM}	Input common-mode voltage range V _S = ±15 V	V _{CM} , High	LF15x, LF25x, LF356B	11	15.1		V
			LF35x	10	15.1		
		V _{CM} , Low	LF15x, LF25x, LF356B	-12	-11		
			LF35x	-12	-10		
CMRR	Common-mode rejection ratio	LF15x, LF25x, LF356B			85	100	dB
		LF35x			80	100	
PSRR	Supply voltage rejection ratio ⁽⁴⁾	LF15x, LF25x, LF356B			85	100	dB
		LF35x			80	100	

(4) Supply Voltage Rejection is measured for both supply magnitudes increasing or decreasing simultaneously, in accordance with common practice.

6.8 Power Dissipation Ratings

			MIN	MAX	UNIT
Power Dissipation at T _A = 25°C ⁽¹⁾ ⁽²⁾	LMC Package (Still Air)	LF15x		560	mW
		LF25x, LF356B, LF35x		400	
	LMC Package (400 LF/Min Air Flow)	LF15x		1200	
		LF25x, LF356B, LF35x		1000	
	P Package	LF25x, LF356B, LF35x		670	
	D Package	LF25x, LF356B, LF35x		380	

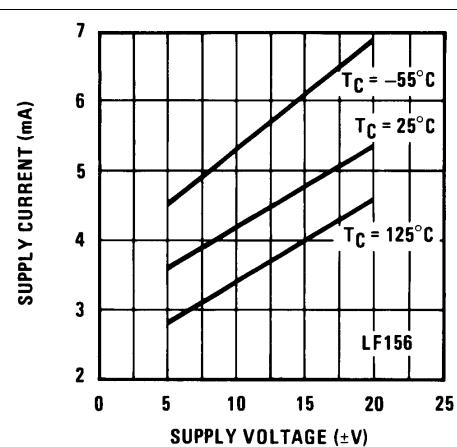
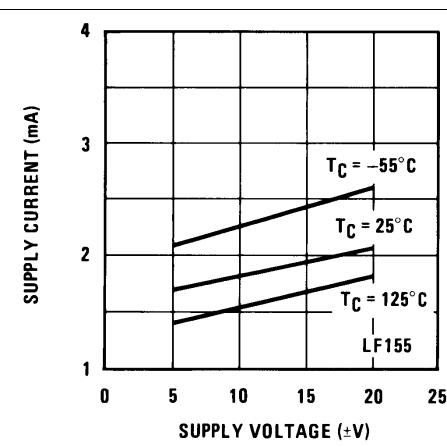
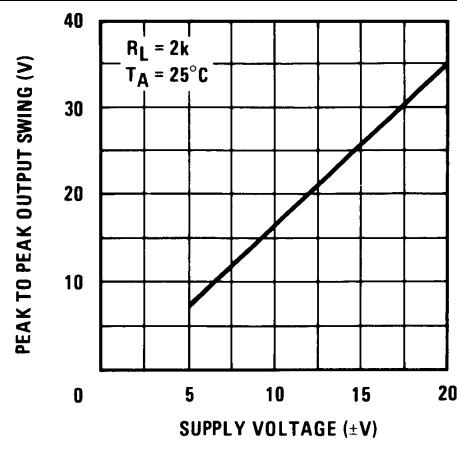
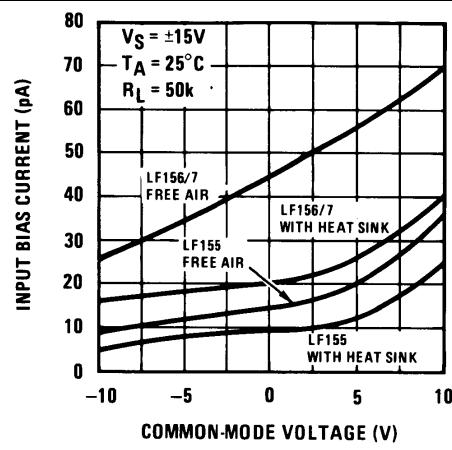
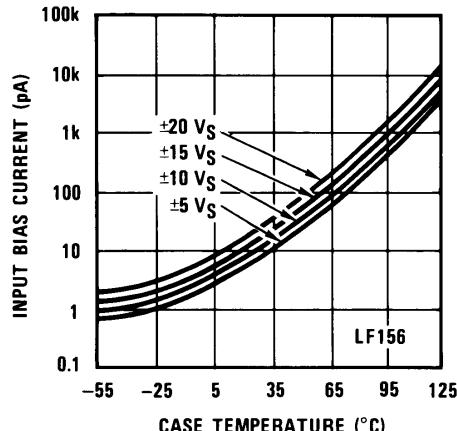
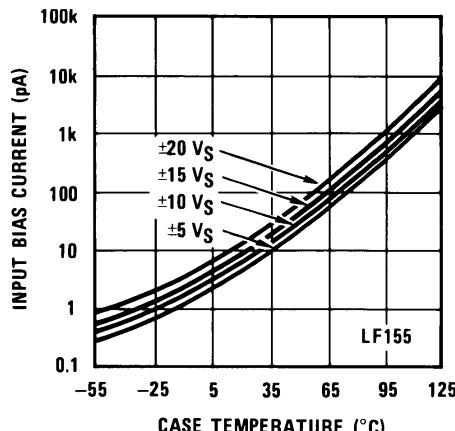
(1) The maximum power dissipation for these devices must be derated at elevated temperatures and is dictated by T_{JMAX}, θ_{JA}, and the ambient temperature, T_A. The maximum available power dissipation at any temperature is P_D = (T_{JMAX} – T_A) / θ_{JA} or the 25°C P_{dMAX}, whichever is less.

(2) Maximum power dissipation is defined by the package characteristics. Operating the part near the maximum power dissipation may cause the part to operate outside specified limits.

6.9 Typical Characteristics

6.9.1 Typical DC Performance Characteristics

Curves are for LF155 and LF156 unless otherwise specified.



Typical DC Performance Characteristics (continued)

Curves are for LF155 and LF156 unless otherwise specified.

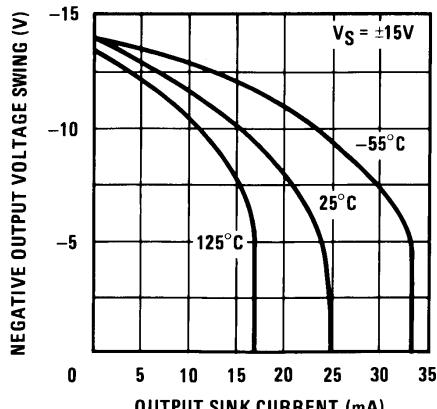


Figure 7. Negative Current Limit

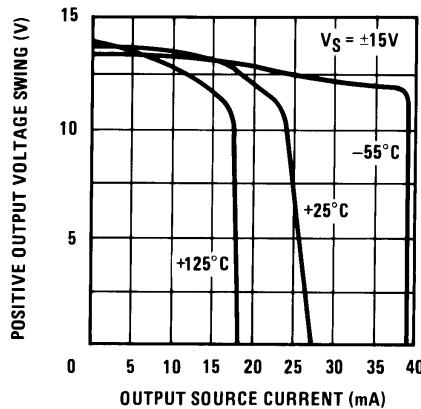


Figure 8. Positive Current Limit

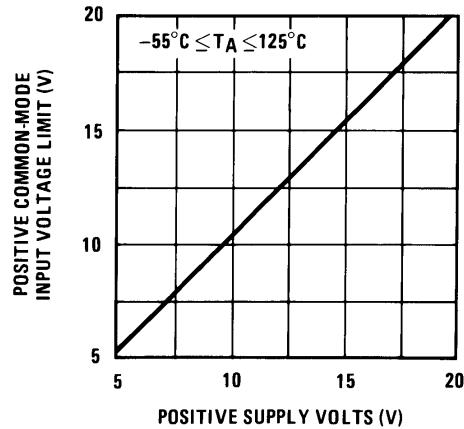


Figure 9. Positive Common-Mode Input Voltage Limit

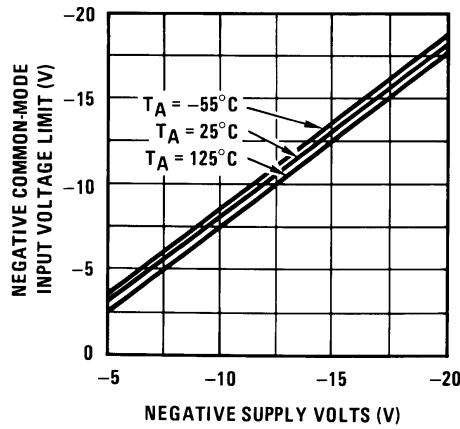


Figure 10. Negative Common-Mode Input Voltage Limit

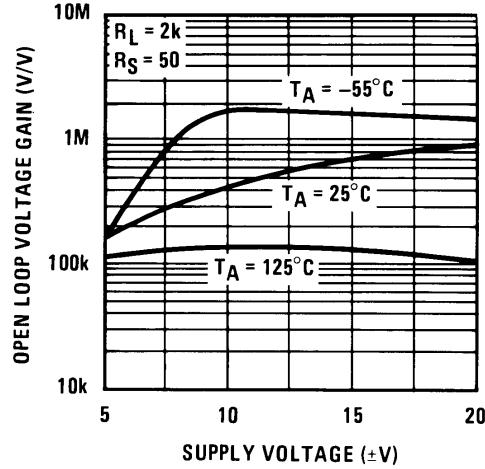


Figure 11. Open-Loop Voltage Gain

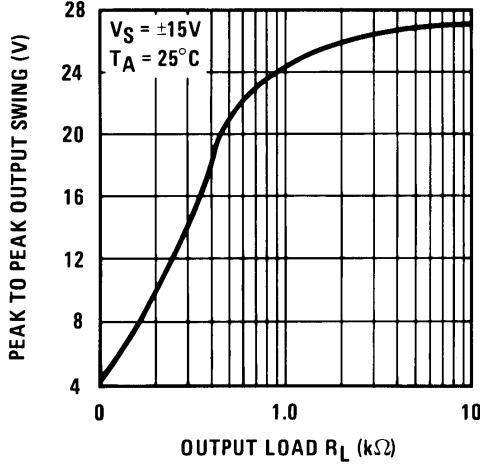
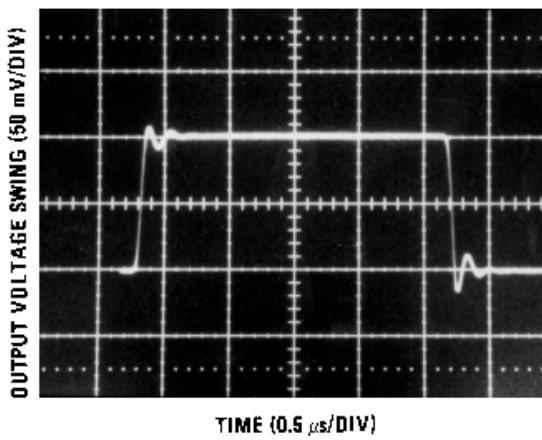
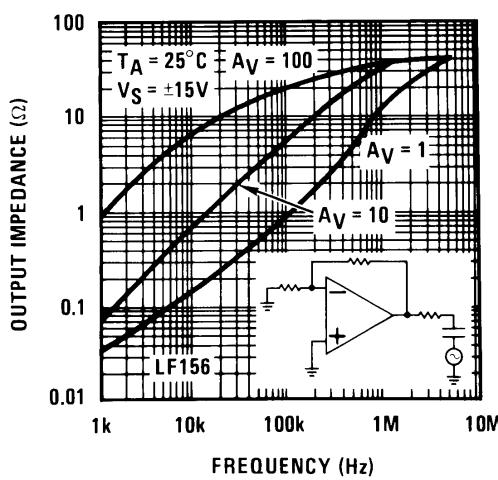
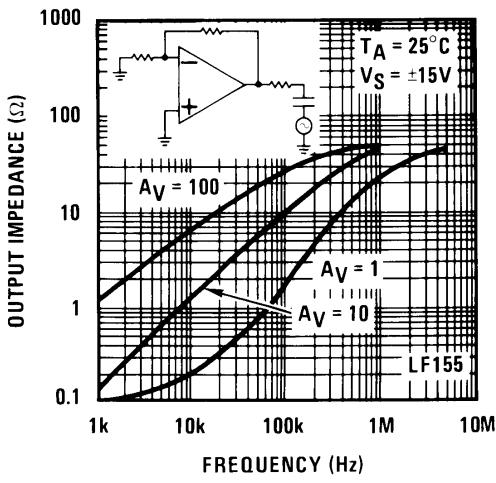
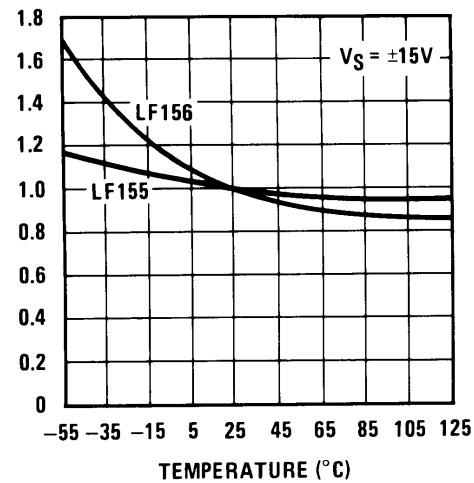
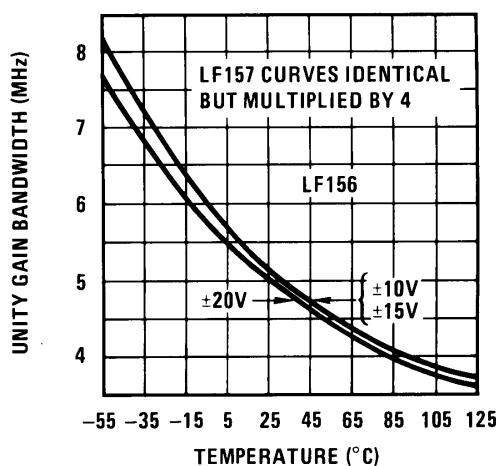
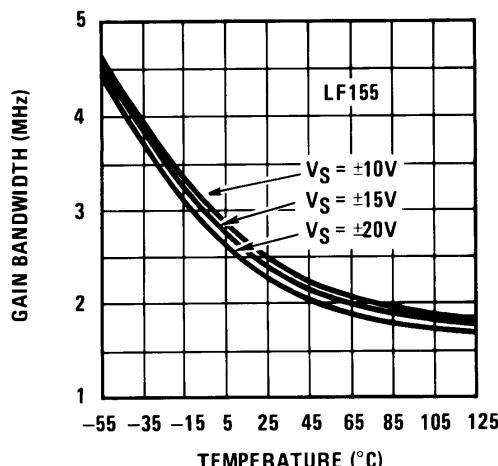


Figure 12. Output Voltage Swing

6.9.2 Typical AC Performance Characteristics



Typical AC Performance Characteristics (continued)

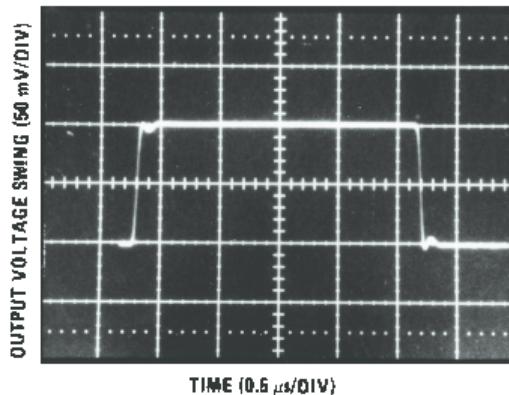


Figure 19. LF156 Small Signal Pulse Response, $A_V = +1$

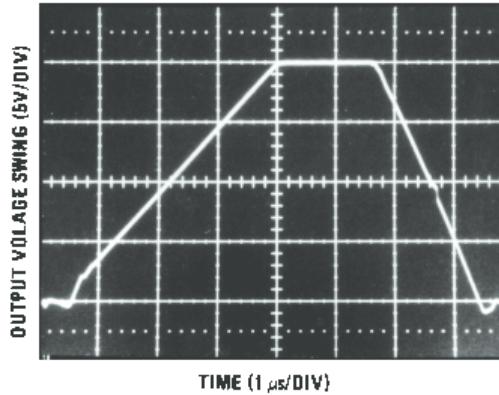


Figure 20. LF155 Large Signal Pulse Response, $A_V = +1$

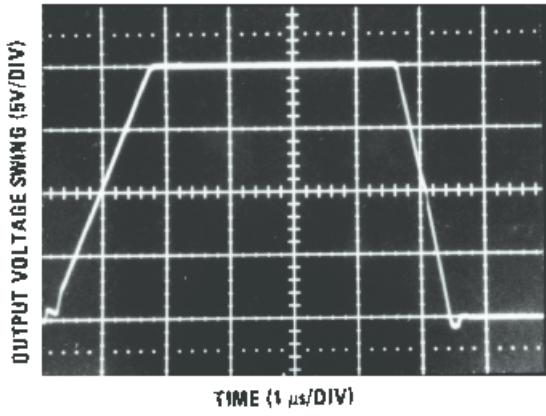


Figure 21. LF156 Large Signal Pulse Response, $A_V = +1$

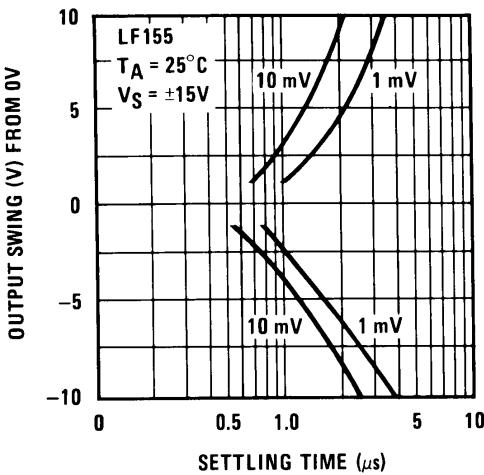


Figure 22. Inverter Settling Time

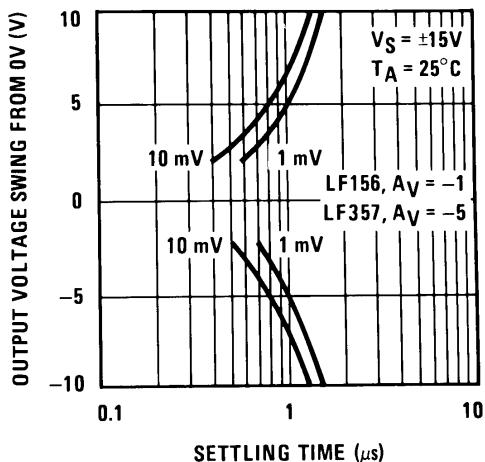


Figure 23. Inverter Settling Time

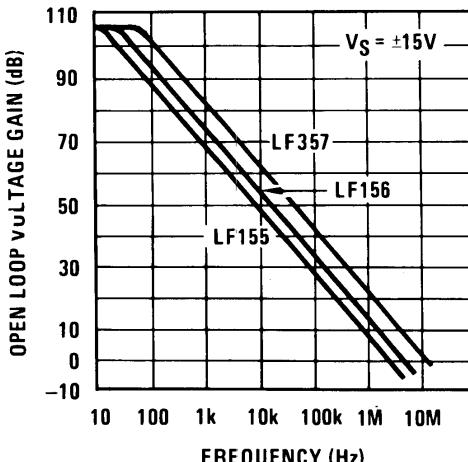


Figure 24. Open-Loop Frequency Response

Typical AC Performance Characteristics (continued)

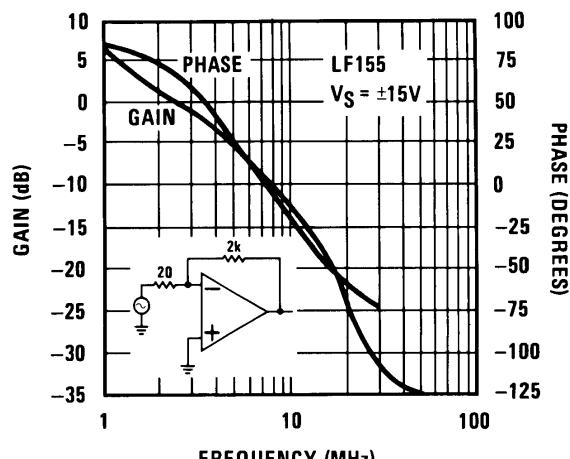


Figure 25. Bode Plot

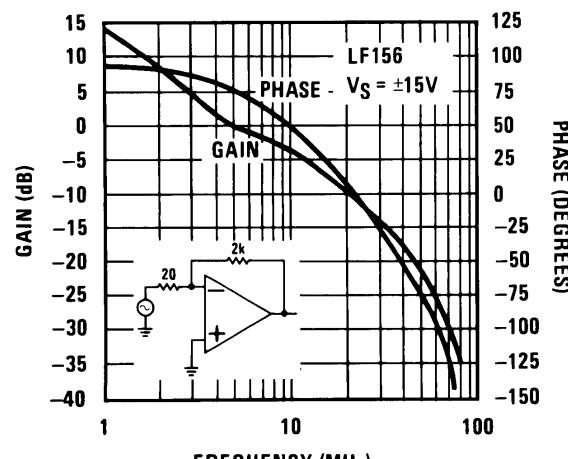


Figure 26. Bode Plot

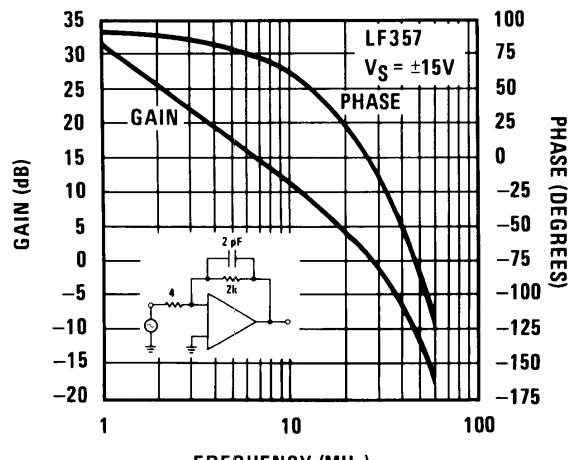


Figure 27. Bode Plot

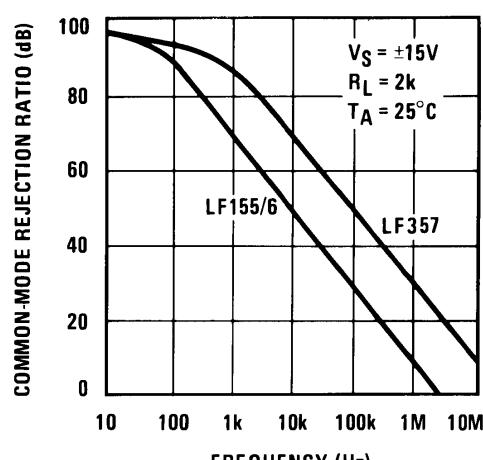


Figure 28. Common-Mode Rejection Ratio

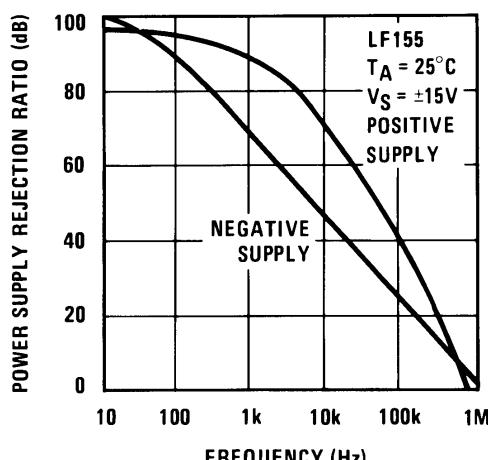


Figure 29. Power Supply Rejection Ratio

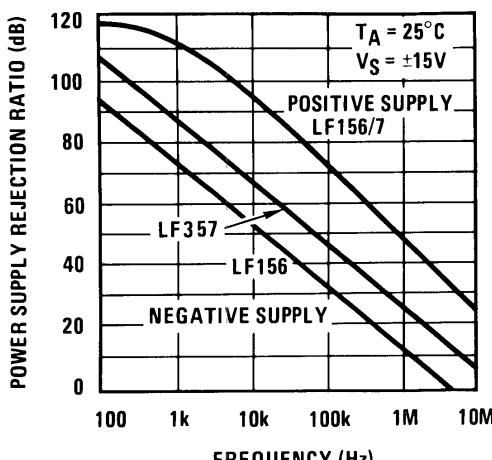


Figure 30. Power Supply Rejection Ratio

Typical AC Performance Characteristics (continued)

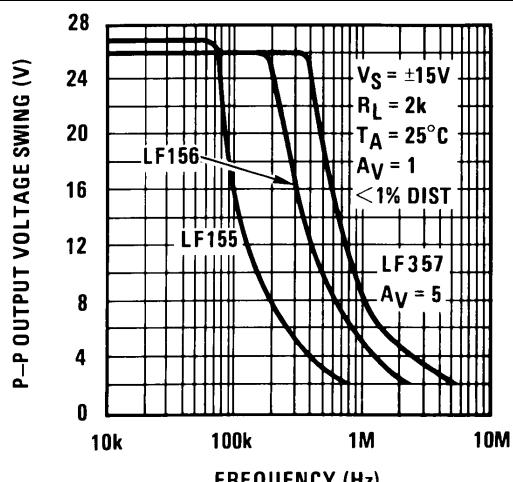


Figure 31. Undistorted Output Voltage Swing

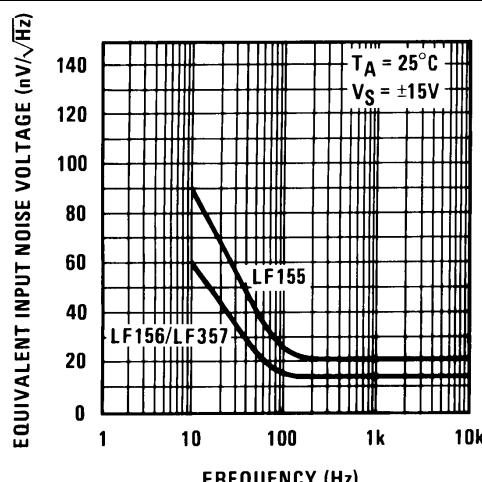


Figure 32. Equivalent Input Noise Voltage

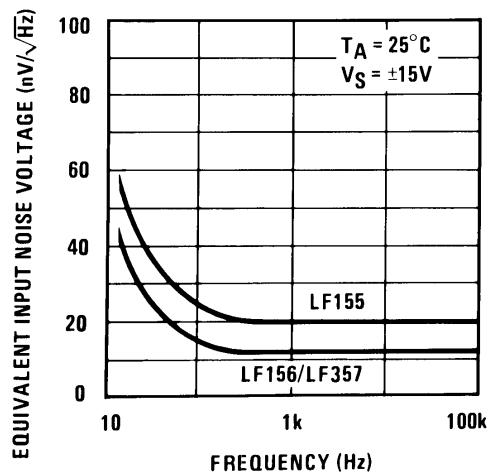


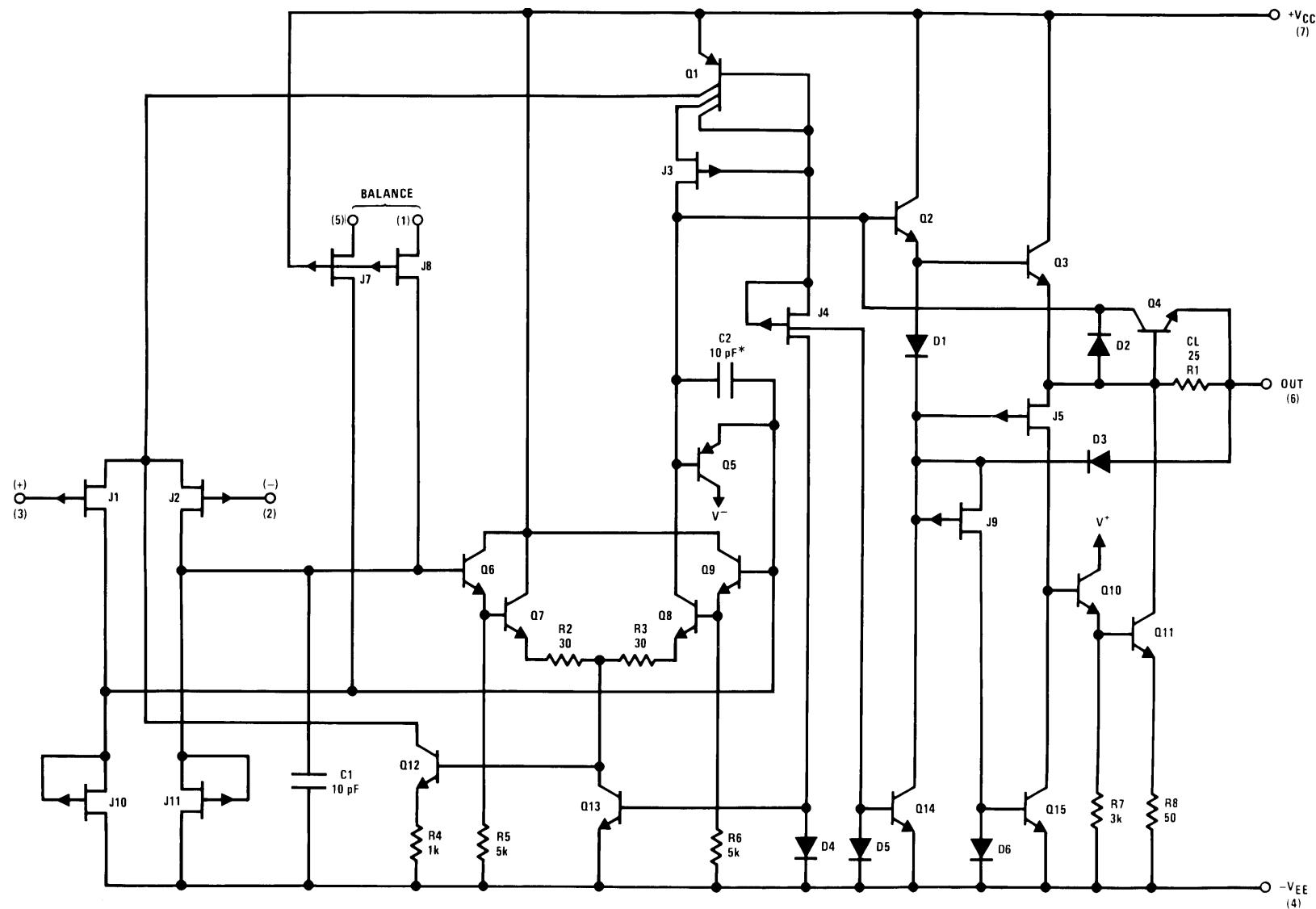
Figure 33. Equivalent Input Noise Voltage (Expanded Scale)

7 Detailed Description

7.1 Overview

These are the first monolithic JFET input operational amplifiers to incorporate well matched, high voltage JFETs on the same chip with standard bipolar transistors (BI-FET Technology). These amplifiers feature low input bias and offset currents, as well as low offset voltage and offset voltage drift, coupled with offset adjust which does not degrade drift or common-mode rejection. These devices can replace expensive hybrid and module FET operational amplifiers. Designed for low voltage and current noise and a low 1/f noise corner, these devices are excellent for low noise applications using either high or low source impedance.

7.2 Functional Block Diagram



*C = 3 pF in LF357 series.

Figure 34. Detailed Schematic

7.3 Feature Description

7.3.1 Large Differential Input Voltage

These are operational amplifiers with JFET input devices. These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be allowed to exceed the negative supply as this will cause large currents to flow which can result in a destroyed unit.

7.3.2 Large Common-Mode Input Voltage

These amplifiers will operate with the common-mode input voltage equal to the positive supply. In fact, the common-mode voltage can exceed the positive supply by approximately 100 mV independent of supply voltage and over the full operating temperature range. The positive supply can therefore be used as a reference on an input as, for example, in a supply current monitor and/or limiter.

7.4 Device Functional Modes

The LFx5x has a single functional mode and operates according to the conditions listed in the *Recommended Operating Conditions*.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

These are op amps with JFET input devices. These JFETs have large reverse breakdown voltages from gate to source and drain eliminating the need for clamps across the inputs. Therefore large differential input voltages can easily be accommodated without a large increase in input current. The maximum differential input voltage is independent of the supply voltages. However, neither of the input voltages should be allowed to exceed the negative supply as this will cause large currents to flow which can result in a destroyed unit.

Exceeding the negative common-mode limit on either input will force the output to a high state, potentially causing a reversal of phase to the output. Exceeding the negative common-mode limit on both inputs will force the amplifier output to a high state. In neither case does a latch occur since raising the input back within the common-mode range again puts the input stage and thus the amplifier in a normal operating mode.

Exceeding the positive common-mode limit on a single input will not change the phase of the output however, if both inputs exceed the limit, the output of the amplifier will be forced to a high state.

These amplifiers will operate with the common-mode input voltage equal to the positive supply. In fact, the common-mode voltage can exceed the positive supply by approximately 100 mV independent of supply voltage and over the full operating temperature range. The positive supply can therefore be used as a reference on an input as, for example, in a supply current monitor and/or limiter.

Precautions should be taken to ensure that the power supply for the integrated circuit never becomes reversed in polarity or that the unit is not inadvertently installed backwards in a socket as an unlimited current surge through the resulting forward diode within the IC could cause fusing of the internal conductors and result in a destroyed unit.

All of the bias currents in these amplifiers are set by FET current sources. The drain currents for the amplifiers are therefore essentially independent of supply voltage.

As with most amplifiers, care should be taken with lead dress, component placement and supply decoupling in order to ensure stability. For example, resistors from the output to an input should be placed with the body close to the input to minimize pick-up and maximize the frequency of the feedback pole by minimizing the capacitance from the input to ground.

A feedback pole is created when the feedback around any amplifier is resistive. The parallel resistance and capacitance from the input of the device (usually the inverting input) to AC ground set the frequency of the pole. In many instances the frequency of this pole is much greater than the expected 3-dB frequency of the closed loop gain and consequently there is negligible effect on stability margin. However, if the feedback pole is less than approximately six times the expected 3-dB frequency a lead capacitor should be placed from the output to the input of the op amp. The value of the added capacitor should be such that the RC time constant of this capacitor and the resistance it parallels is greater than or equal to the original feedback pole time constant.

8.2 Typical Application

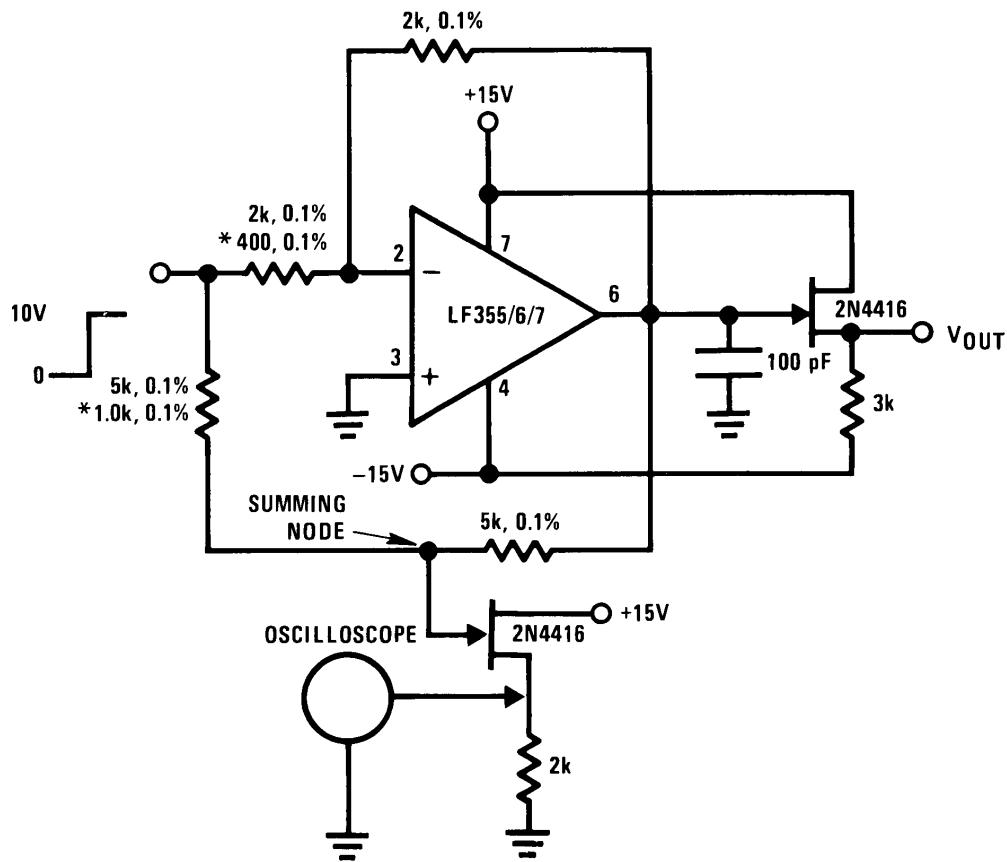


Figure 35. Settling Time Test Circuit

8.2.1 Design Requirements

Settling time is tested with the LF35x connected as unity gain inverter and LF357 connected for $A_V = -5$

8.2.2 Detailed Design Procedure

Connect the circuit components as shown in Figure 35. In particular, use FET to isolate the probe capacitance.

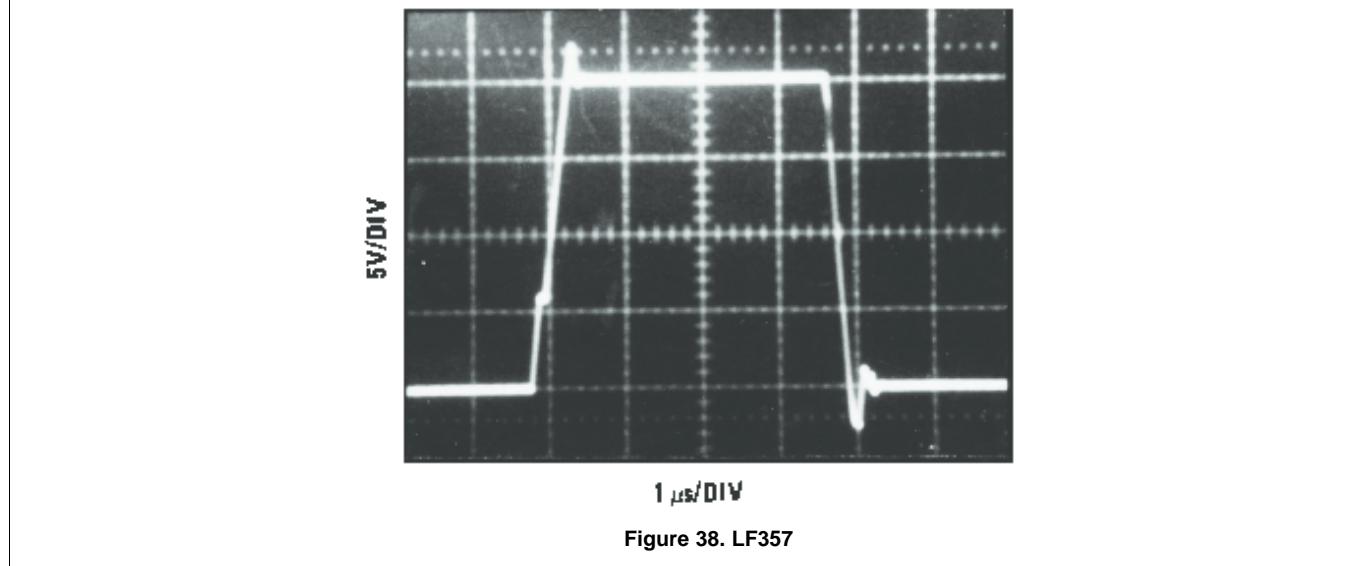
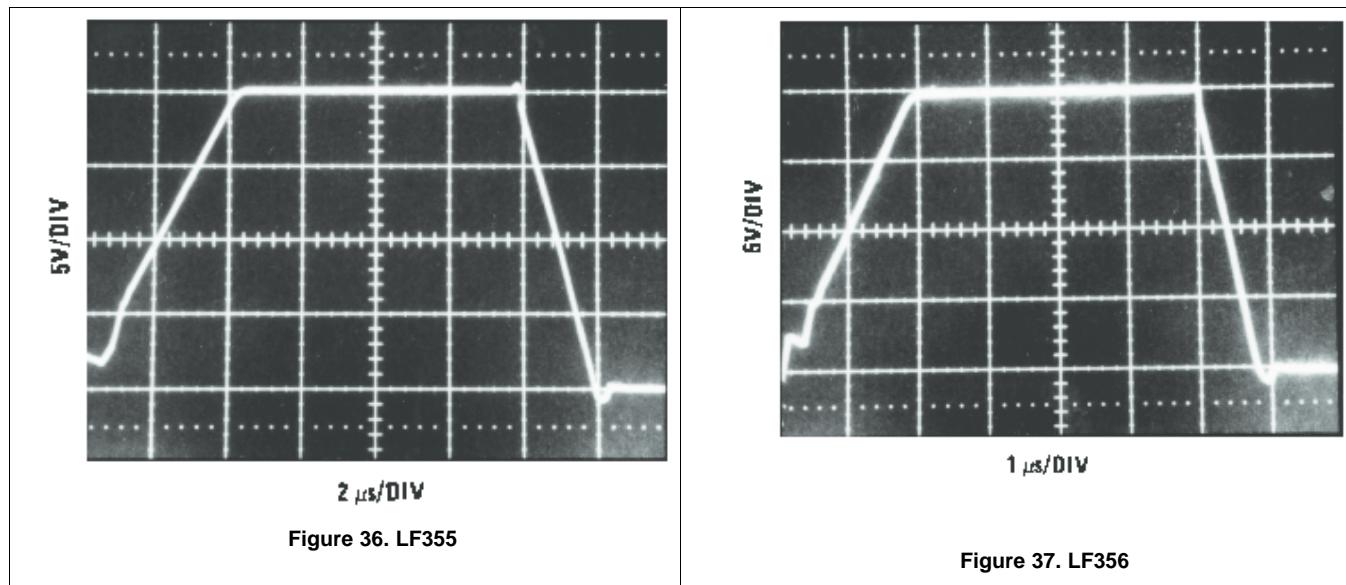
Apply a 10-V step function to the input.

Use an oscilloscope to probe the circuit as shown in Figure 35.

Typical Application (continued)

8.2.3 Application Curves

Large Signal Inverter Output, V_{OUT} (from Settling Time Circuit)



8.3 System Examples

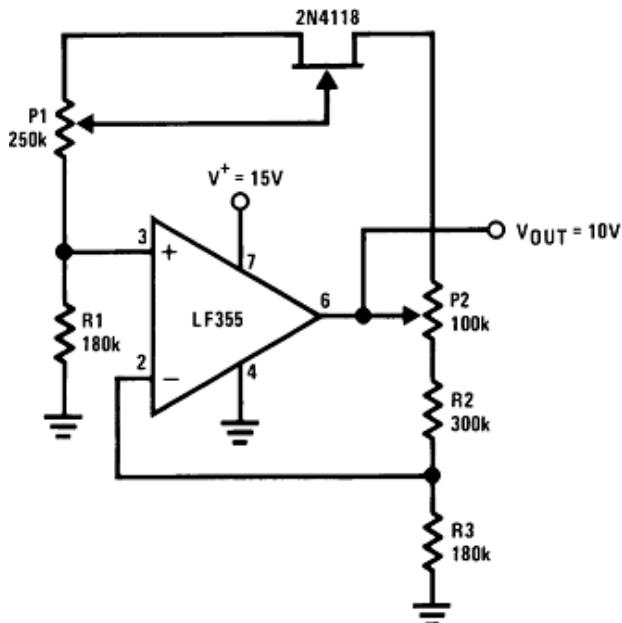


Figure 39. Low Drift Adjustable Voltage Reference

- $\Delta V_{OUT} / \Delta T = \pm 0.002\% / ^\circ C$
- All resistors and potentiometers should be wire-wound
- P1: drift adjust
- P2: V_{OUT} adjust
- Use LF155 for
 - Low I_B
 - Low drift
 - Low supply current

System Examples (continued)

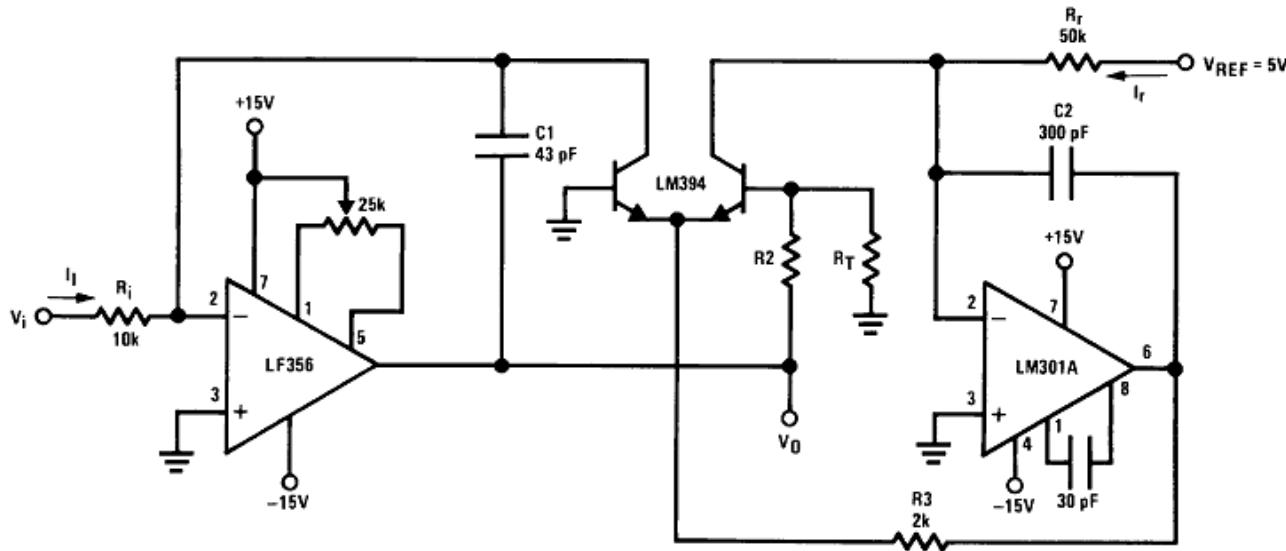


Figure 40. Fast Logarithmic Converter

- Dynamic range: $100 \mu\text{A} \leq I_i \leq 1 \text{ mA}$ (5 decades), $|V_o| = 1 \text{ V/decade}$
- Transient response: $3 \mu\text{s}$ for $\Delta I_i = 1 \text{ decade}$
- C1, C2, R2, R3: added dynamic compensation
- V_{OS} adjust the LF156 to minimize quiescent error
- R_T : Tel Labs type Q81 + 0.3%/°C

$$|V_{OUT}| = \left[1 + \frac{R2}{R_T} \right] \frac{kT}{q} \ln \frac{V_i}{V_{REF} R_i} = \log V_i \frac{1}{R_i I_r} \quad R2 = 15.7\text{k}, R_T = 1\text{k}, 0.3\%/\text{°C} \quad (1)$$

System Examples (continued)

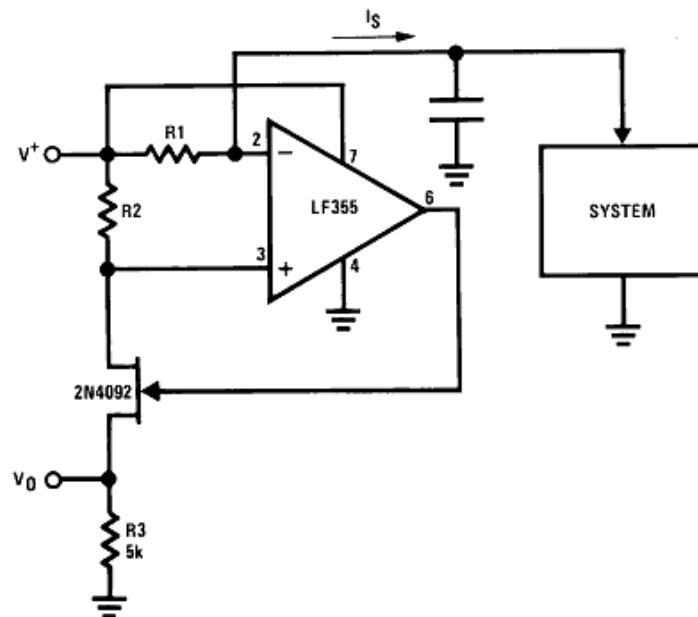


Figure 41. Precision Current Monitor

- $V_O = 5 R1/R2$ (V/mA of I_S)
- $R1, R2, R3$: 0.1% resistors
- Use LF155 for
 - Common-mode range to supply range
 - Low I_B
 - Low V_{OS}
 - Low Supply Current

System Examples (continued)

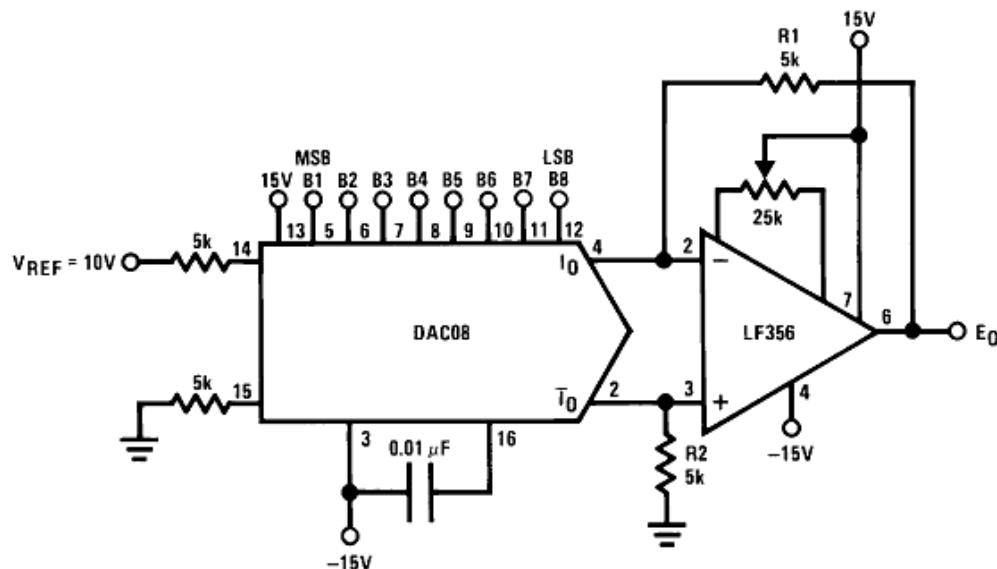


Figure 42. 8-Bit D/A Converter With Symmetrical Offset Binary Operation

- R1, R2 should be matched within $\pm 0.05\%$
- Full-scale response time: 3 μ s

Table 1. Bit Illustration of the 8-Bit D/A Converter

E_o	B1	B2	B3	B4	B5	B6	B7	B8	COMMENTS
+9.920	1	1	1	1	1	1	1	1	Positive Full-Scale
+0.040	1	0	0	0	0	0	0	0	(+) Zero-Scale
-0.040	0	1	1	1	1	1	1	1	(-) Zero-Scale
-9.920	0	0	0	0	0	0	0	0	Negative Full-Scale

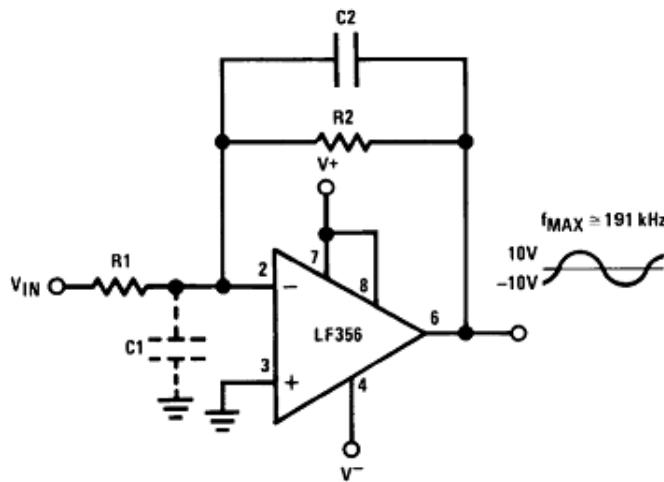


Figure 43. Wide BW Low Noise, Low Drift Amplifier

$$\bullet \text{ Power BW: } f_{\text{MAX}} = \frac{S_r}{2\pi V_p} \cong 191 \text{ kHz} \quad (2)$$

Parasitic input capacitance $C_1 \approx (3 \text{ pF for LF155, LF156 and LF357 plus any additional layout capacitance})$ interacts with feedback elements and creates undesirable high frequency pole. To compensate add C_2 such that: $R_2 C_2 \approx R_1 C_1$.

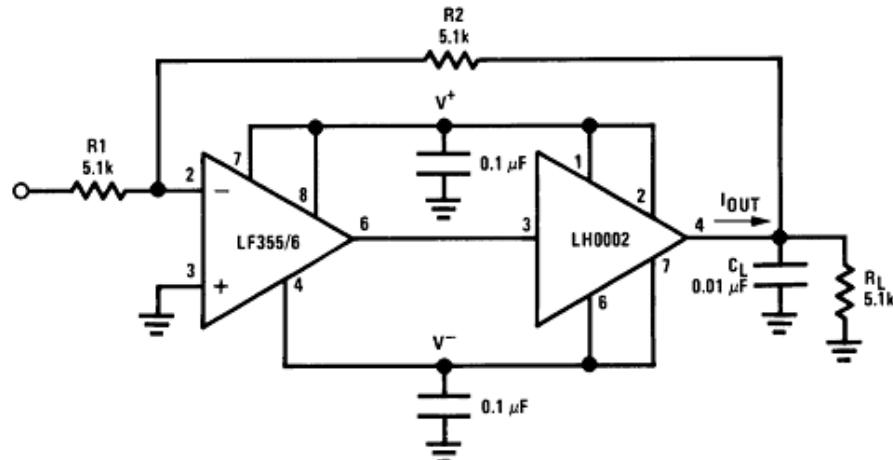


Figure 44. Boosting the LF156 With a Current Amplifier

- $I_{OUT(MAX)} \approx 150 \text{ mA}$ (will drive $R_L \geq 100 \Omega$)
 - $\frac{\Delta V_{OUT}}{\Delta T} = \frac{0.15}{10^{-2}} \text{ V}/\mu\text{s}$ (with C_L shown)
- No additional phase shift added by the current amplifier

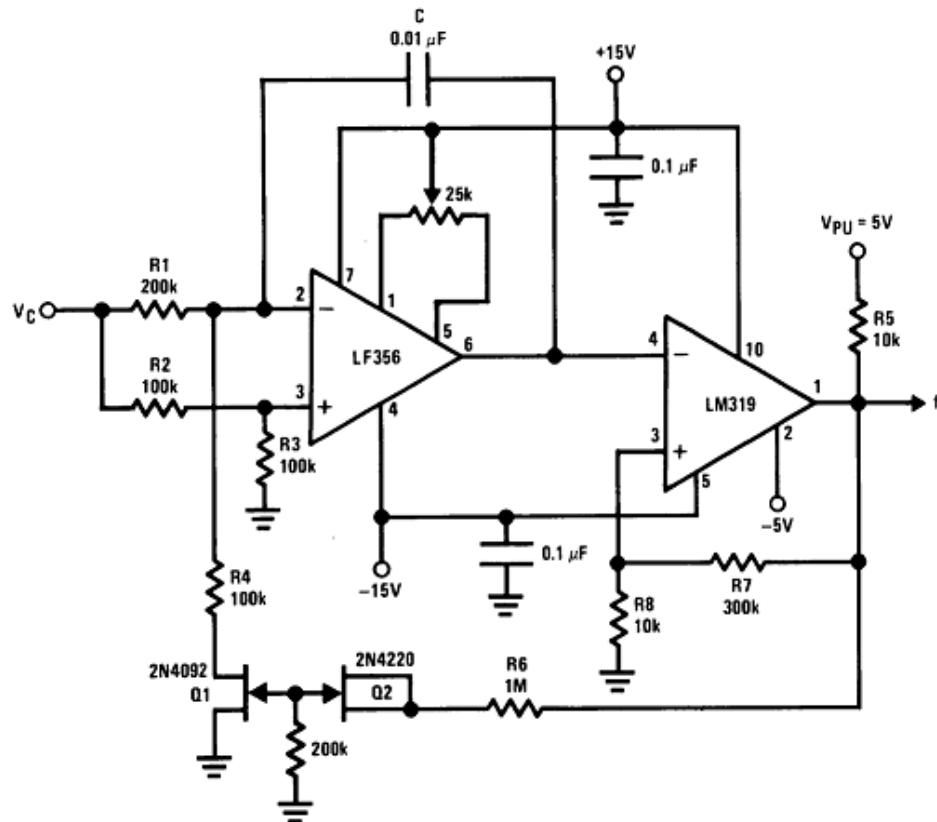


Figure 45. Decades VCO

R1, R4 matched. Linearity 0.1% over 2 decades.

$$f = \frac{V_C (R8 + R7)}{(8 V_{PU} R8 R1) C} \quad 0 \leq V_C \leq 30V, \quad 10 \text{ Hz} \leq f \leq 10 \text{ kHz} \quad (4)$$

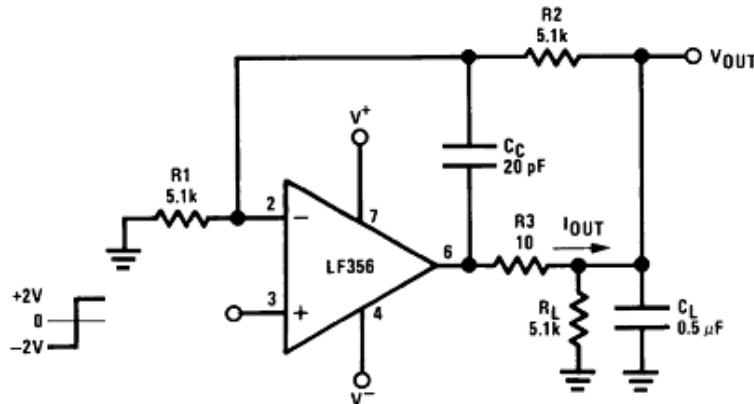


Figure 46. Isolating Large Capacitive Loads

- Overshoot 6%
- t_s 10 μ s
- When driving large C_L , the V_{OUT} slew rate determined by C_L and $I_{OUT(MAX)}$:

$$\frac{\Delta V_{OUT}}{\Delta T} = \frac{I_{OUT}}{C_L} \cong \frac{0.02}{0.5} V/\mu\text{s} = 0.04 V/\mu\text{s} \quad (\text{with } C_L \text{ shown}) \quad (5)$$

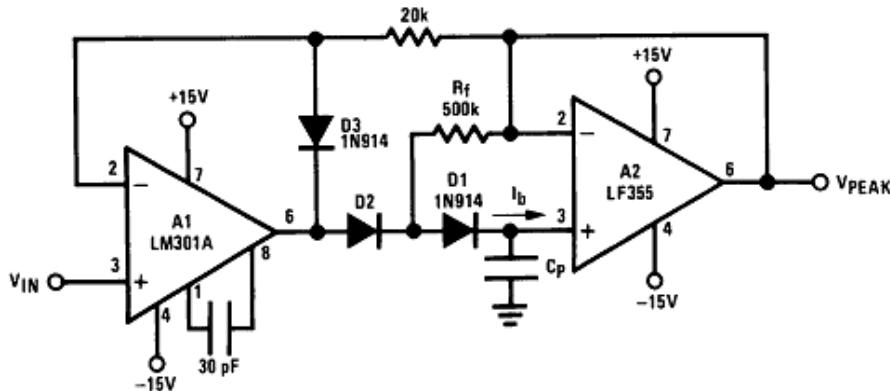


Figure 47. Low Drift Peak Detector

- By adding D1 and R_f , $V_{D1} = 0$ during hold mode. Leakage of D2 provided by feedback path through R_f .
- Leakage of circuit is essentially I_b (LF155, LF156) plus capacitor leakage of C_p .
- Diode D3 clamps V_{OUT} (A1) to $V_{IN} - V_{D3}$ to improve speed and to limit reverse bias of D2.
- Maximum input frequency should be $\ll \frac{1}{2\pi R_f C_{D2}}$ where C_{D2} is the shunt capacitance of D2.

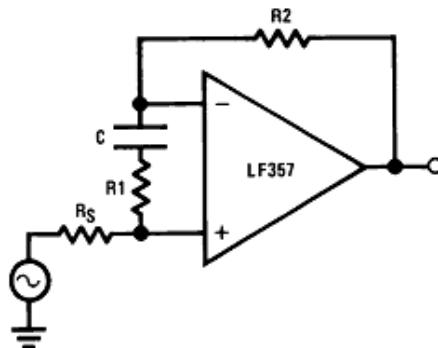


Figure 48. Noninverting Unity Gain Operation for LF157

$$R1C \geq \frac{1}{(2\pi)(5 \text{ MHz})}$$

$$R1 = \frac{R2 + R_S}{4}$$

$$A_V(\text{DC}) = 1$$

$$f_{-3 \text{ dB}} \approx 5 \text{ MHz}$$

(6)

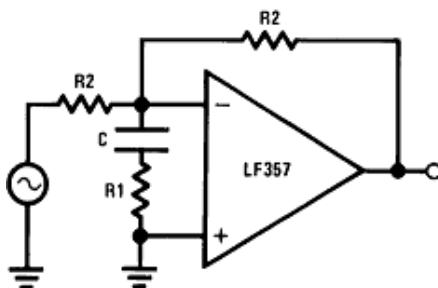


Figure 49. Inverting Unity Gain for LF157

$$R1C \geq \frac{1}{(2\pi)(5 \text{ MHz})}$$

$$R1 = \frac{R2}{4}$$

$$A_V(\text{DC}) = -1$$

$$f_{-3 \text{ dB}} \approx 5 \text{ MHz}$$

(7)

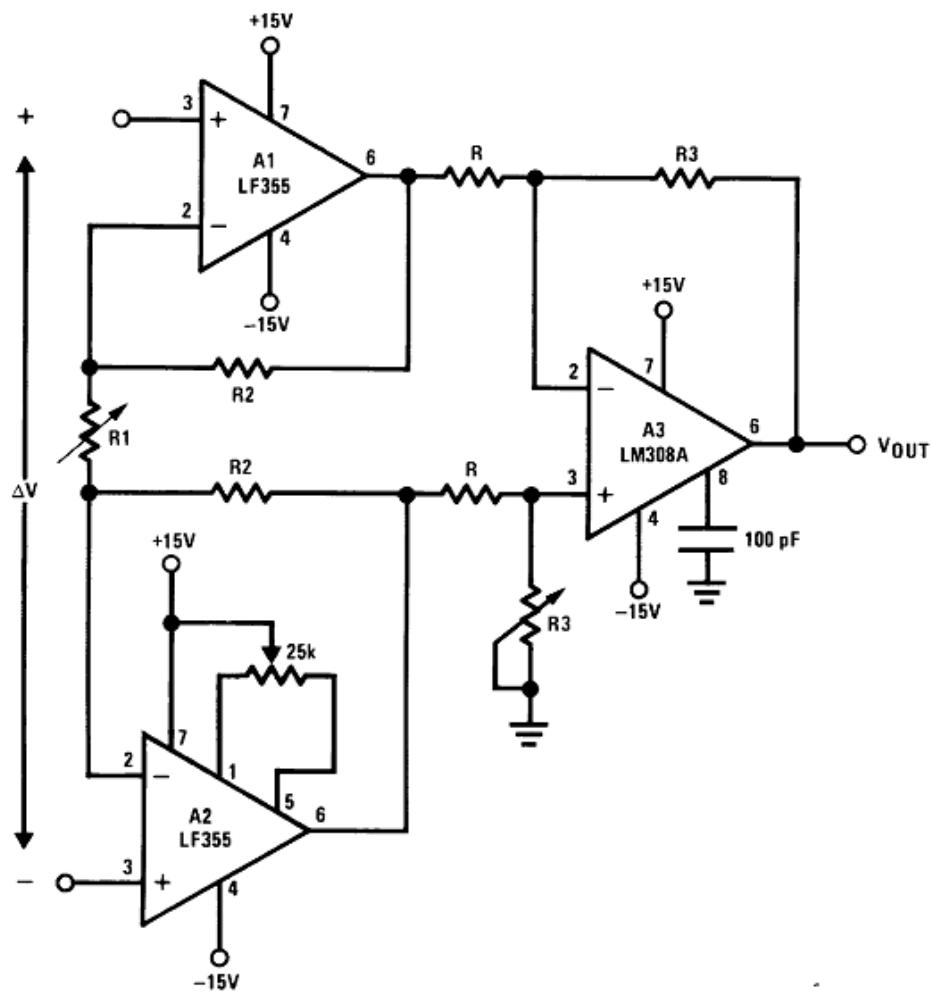


Figure 50. High Impedance, Low Drift Instrumentation Amplifier

- System V_{OS} adjusted via A2 V_{OS} adjust
- Trim R3 to boost up CMRR to 120 dB. Instrumentation amplifier resistor array recommended for best accuracy and lowest drift

$$\bullet V_{OUT} = \frac{R3}{R} \left[\frac{2R2}{R1} + 1 \right] \Delta V, V^- + 2V \leq V_{IN} \text{ common-mode} \leq V^+ \quad (8)$$

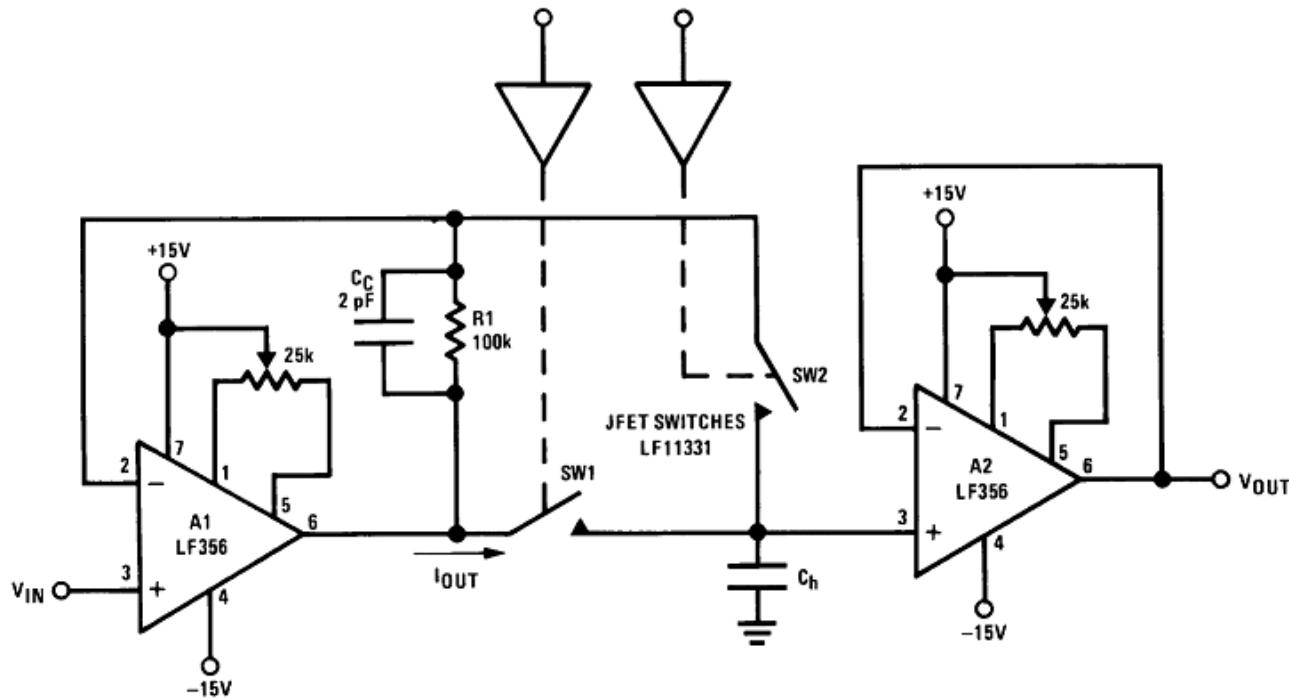


Figure 51. Fast Sample and Hold

- Both amplifiers (A1, A2) have feedback loops individually closed with stable responses (overshoot negligible)
- Acquisition time T_A , estimated by:

$$T_A \cong \left[\frac{2R_{ON} V_{IN} C_h}{S_r} \right]^{1/2} \text{ provided that:}$$

$$V_{IN} < 2\pi S_r R_{ON} C_h \text{ and } T_A > \frac{V_{IN} C_h}{I_{OUT(MAX)}}, R_{ON} \text{ is of SW1}$$

$$\text{If inequality not satisfied: } T_A \cong \frac{V_{IN} C_h}{20 \text{ mA}} \quad (9)$$

- LF156 develops full S_r output capability for $V_{IN} \geq 1 \text{ V}$
- Addition of SW2 improves accuracy by putting the voltage drop across SW1 inside the feedback loop
- Overall accuracy of system determined by the accuracy of both amplifiers, A1 and A2

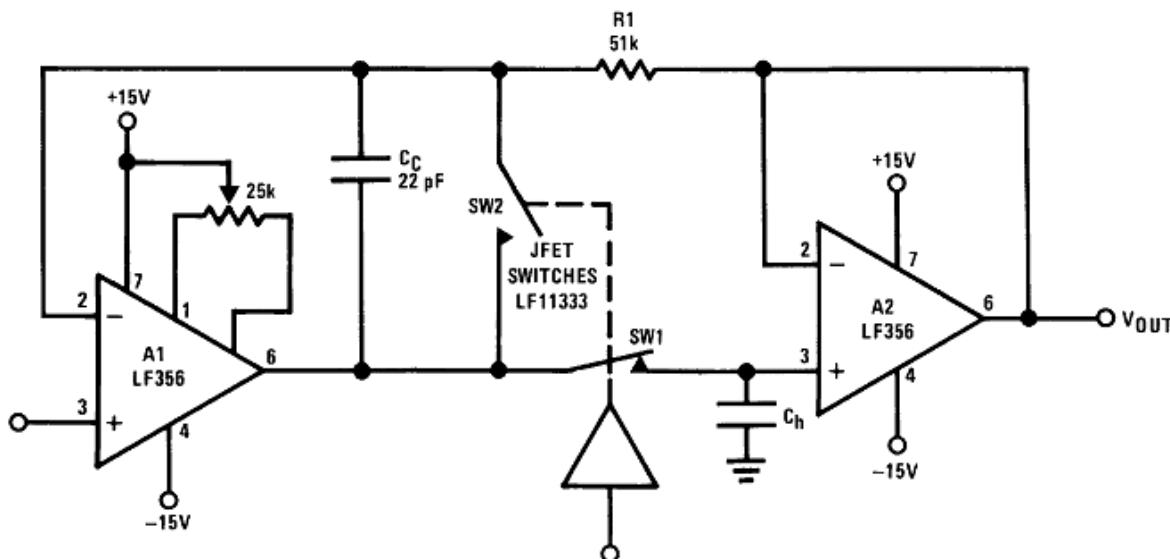


Figure 52. High Accuracy Sample and Hold

- By closing the loop through A2, the V_{OUT} accuracy will be determined uniquely by A1.
 - No V_{OS} adjust required for A2.
- T_A can be estimated by same considerations as previously but, because of the added
 - propagation delay in the feedback loop (A2) the overshoot is not negligible.
- Overall system slower than fast sample and hold
- R1, C_C : additional compensation
- Use LF156 for
 - Fast settling time
 - Low V_{OS}

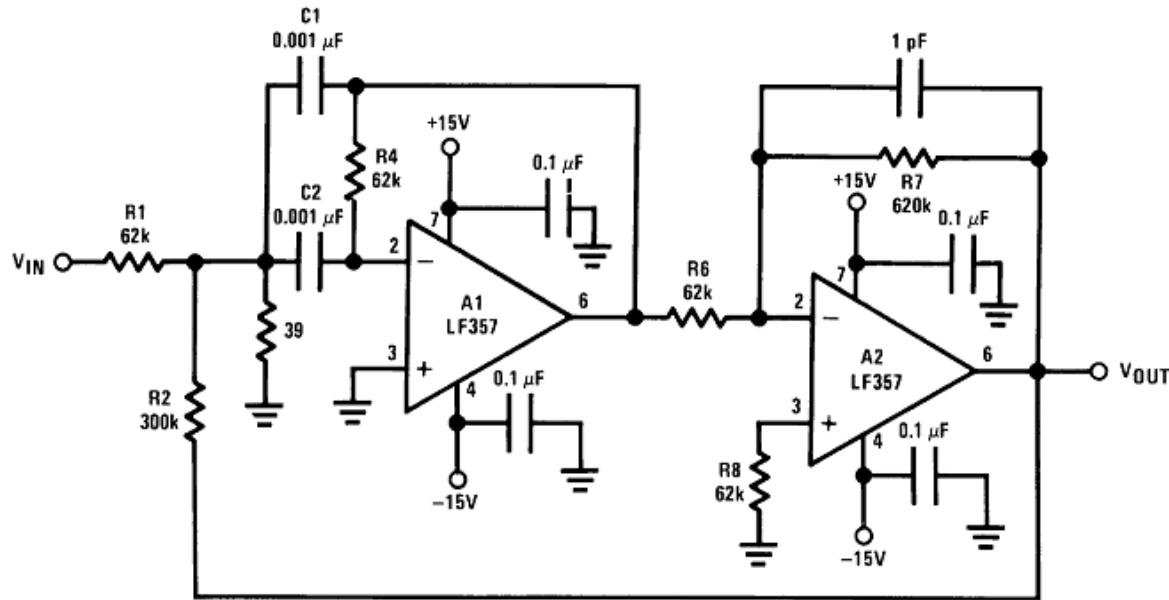


Figure 53. High Q Band Pass Filter

- By adding positive feedback (R2)

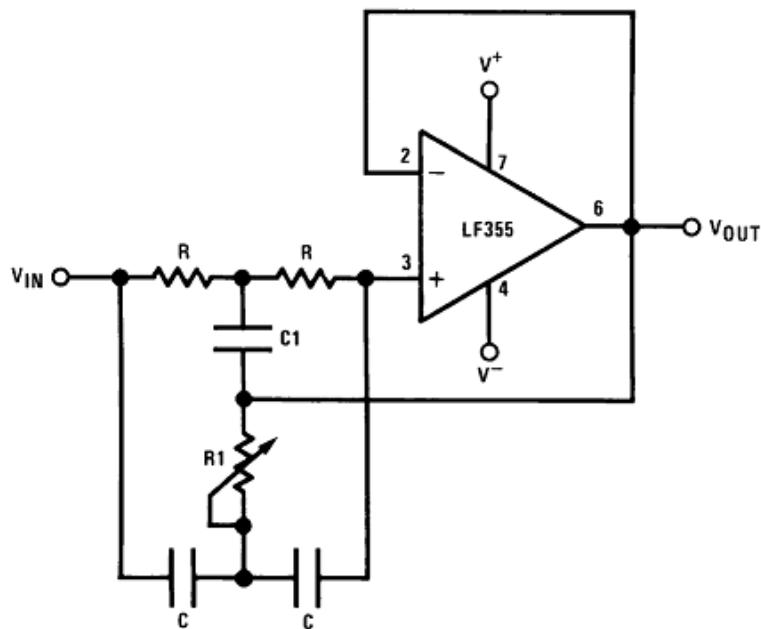
- Q increases to 40

- $f_{BP} = 100$ kHz

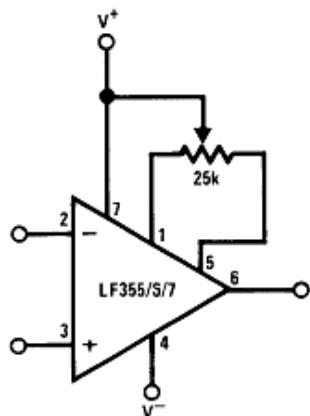
$$\frac{V_{OUT}}{V_{IN}} = 10 \sqrt{Q} \quad (10)$$

- Clean layout recommended

- Response to a 1-V_{p-p} tone burst: 300 μs


Figure 54. High Q Notch Filter

- $2R1 = R = 10 \text{ M}\Omega$
 - $2C = C1 = 300 \text{ pF}$
- Capacitors should be matched to obtain high Q
- $f_{\text{NOTCH}} = 120 \text{ Hz}$, notch = -55 dB , $Q > 100$
- Use LF155 for
 - Low I_B
 - Low supply current


Figure 55. V_{OS} Adjustment

- V_{OS} is adjusted with a 25-k potentiometer
- The potentiometer wiper is connected to V^+
- For potentiometers with temperature coefficient of 100 ppm/ $^{\circ}\text{C}$ or less the additional drift with adjust is $\approx 0.5 \mu\text{V}/^{\circ}\text{C}/\text{mV}$ of adjustment
- Typical overall drift: $5 \mu\text{V}/^{\circ}\text{C} \pm (0.5 \mu\text{V}/^{\circ}\text{C}/\text{mV}$ of adj.)

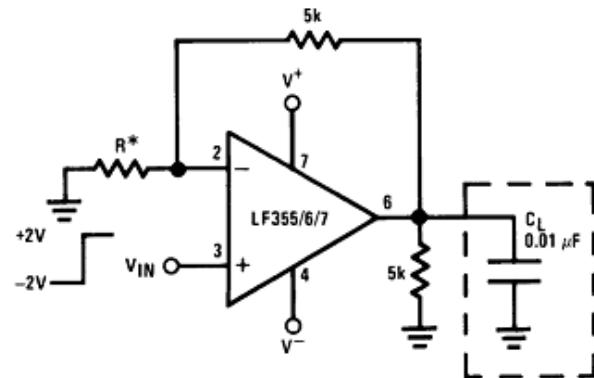


Figure 56. Driving Capacitive Loads

- *LF15x $R = 5\text{k}$, LF357 $R = 1.25\text{k}$
- Due to a unique output stage design, these amplifiers have the ability to drive large capacitive loads and still maintain stability. $C_{L(\text{MAX})} \approx 0.01\text{ }\mu\text{F}$.
- Overshoot $\leq 20\%$, Settling time (t_s) $\approx 5\text{ }\mu\text{s}$

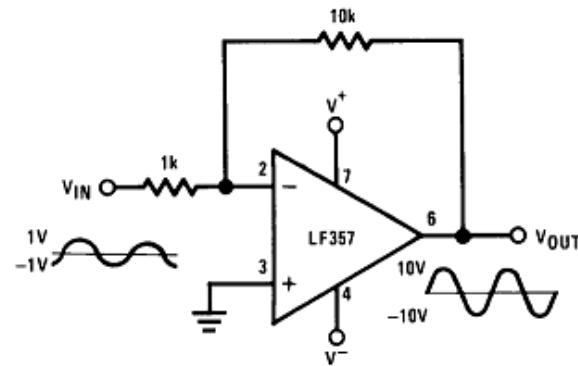


Figure 57. LF357 - A Large Power BW Amplifier

For distortion $\leq 1\%$ and a 20 Vp-p V_{OUT} swing, power bandwidth is: 500 kHz.

9 Power Supply Recommendations

See the *Recommended Operating Conditions* for the minimum and maximum values for the supply input voltage and operating junction temperature.

10 Layout

10.1 Layout Guidelines

10.1.1 Printed-Circuit-Board Layout For High-Impedance Work

It is generally recognized that any circuit which must operate with less than 1000 pA of leakage current requires special layout of the PCB. When one wishes to take advantage of the low input bias current of the LFx5x, typically less than 30 pA, it is essential to have an excellent layout. Fortunately, the techniques of obtaining low leakages are quite simple. First, the user must not ignore the surface leakage of the PCB, even though it may sometimes appear acceptably low, because under conditions of high humidity or dust or contamination, the surface leakage will be appreciable.

To minimize the effect of any surface leakage, lay out a ring of foil completely surrounding the inputs of the LFx5x and the terminals of capacitors, diodes, conductors, resistors, relay terminals, and so forth, connected to the inputs of the op amp, as in [Figure 62](#). To have a significant effect, guard rings must be placed on both the top and bottom of the PCB. This PC foil must then be connected to a voltage that is at the same voltage as the amplifier inputs, because no leakage current can flow between two points at the same potential. For example, a PCB trace-to-pad resistance of 10 TΩ, which is normally considered a very large resistance, could leak 5 pA if the trace were a 5-V bus adjacent to the pad of the input. If a guard ring is used and held close to the potential of the amplifier inputs, it will significantly reduce this leakage current.

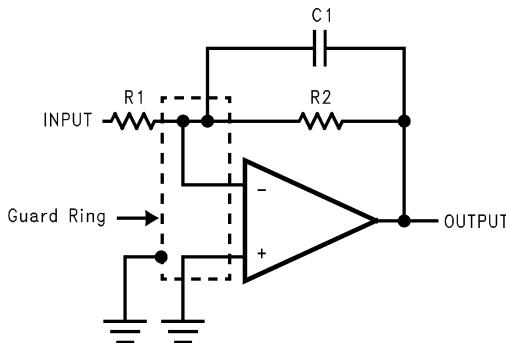


Figure 58. Inverting Amplifier

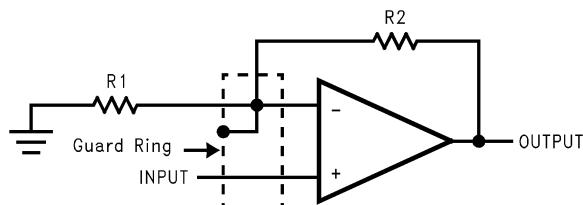


Figure 59. Noninverting Amplifier

Layout Guidelines (continued)

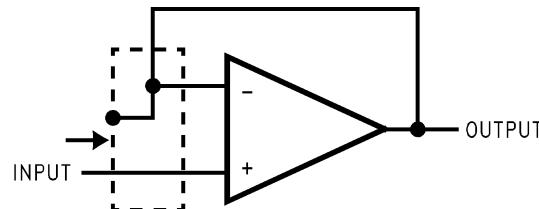
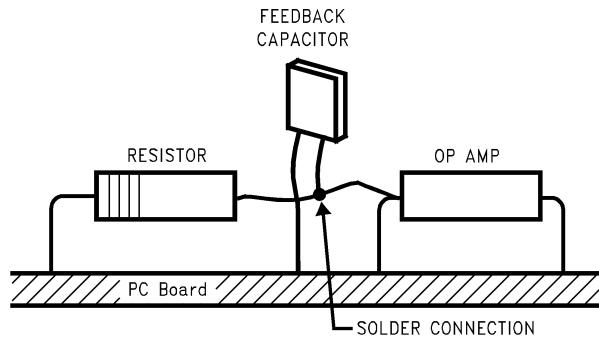


Figure 60. Typical Connections Of Guard Rings

The designer should be aware that when it is inappropriate to lay out a PCB for the sake of just a few circuits, there is another technique which is even better than a guard ring on a PCB: Do not insert the input pin of the amplifier into the board at all, but bend it up in the air and use only air as an insulator. Air is an excellent insulator. In this case you may have to forego some of the advantages of PCB construction, but the advantages are sometimes well worth the effort of using point-to-point up-in-the-air wiring. See Figure 61.



(Input pins are lifted out of PCB and soldered directly to components. All other pins connected to PCB).

Figure 61. Air Wiring

Another potential source of leakage that might be overlooked is the device package. When the LF_x5x is manufactured, the device is always handled with conductive finger cots. This is to assure that salts and skin oils do not cause leakage paths on the surface of the package. We recommend that these same precautions be adhered to, during all phases of inspection, test and assembly.

10.2 Layout Example

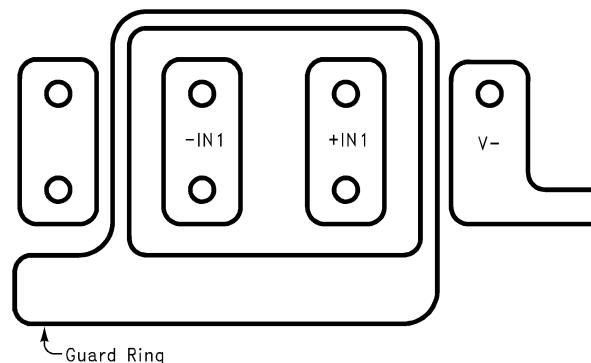


Figure 62. Examples Of Guard Ring In PCB Layout

11 Device and Documentation Support

11.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 2. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
LF156	Click here				
LF256	Click here				
LF356	Click here				

11.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.3 Trademarks

BI-FET, E2E are trademarks of Texas Instruments.

All other trademarks are the property of their respective owners.

11.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.5 Glossary

[SLYZ022](#) — *TI Glossary.*

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LF156 MD8	Active	Production	DIESALE (Y) 0	204 JEDEC TRAY (5+1)	Yes	Call TI	Level-1-NA-UNLIM	-55 to 125	
LF156H	Active	Production	TO-99 (LMC) 8	500 OTHER	No	Call TI	Level-1-NA-UNLIM	-55 to 125	(LF156H, LF156H)
LF156H/NOPB	Active	Production	TO-99 (LMC) 8	500 OTHER	Yes	Call TI	Level-1-NA-UNLIM	-55 to 125	(LF156H, LF156H)
LF256H	Active	Production	TO-99 (LMC) 8	500 OTHER	No	Call TI	Level-1-NA-UNLIM	-25 to 85	(LF256H, LF256H)
LF256H/NOPB	Active	Production	TO-99 (LMC) 8	500 OTHER	Yes	Call TI	Level-1-NA-UNLIM	-25 to 85	(LF256H, LF256H)
LF356M/NOPB	Active	Production	SOIC (D) 8	95 TUBE	Yes	SN	Level-1-260C-UNLIM	0 to 70	LF356 M
LF356M/NOPB.B	Active	Production	SOIC (D) 8	95 TUBE	Yes	SN	Level-1-260C-UNLIM	0 to 70	LF356 M
LF356MX/NOPB	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	0 to 70	LF356 M
LF356MX/NOPB.B	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	0 to 70	LF356 M
LF356N/NOPB	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	0 to 70	LF 356N
LF356N/NOPB.B	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	0 to 70	LF 356N
LF356N/NOPBG4	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	0 to 70	LF 356N
LF356N/NOPBG4.B	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	0 to 70	LF 356N

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

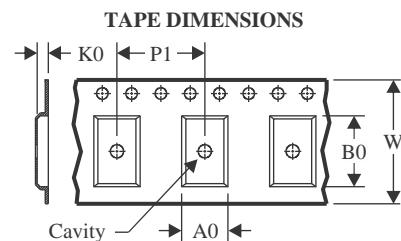
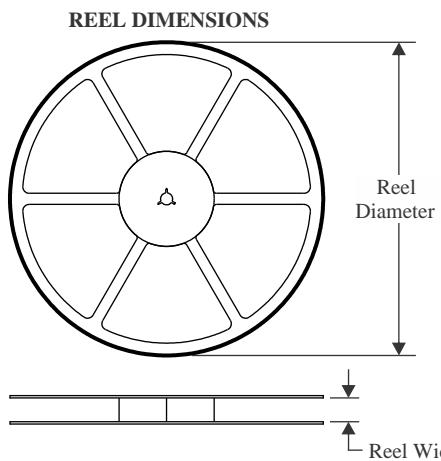
⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

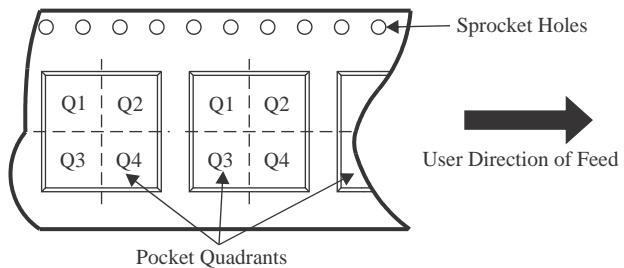
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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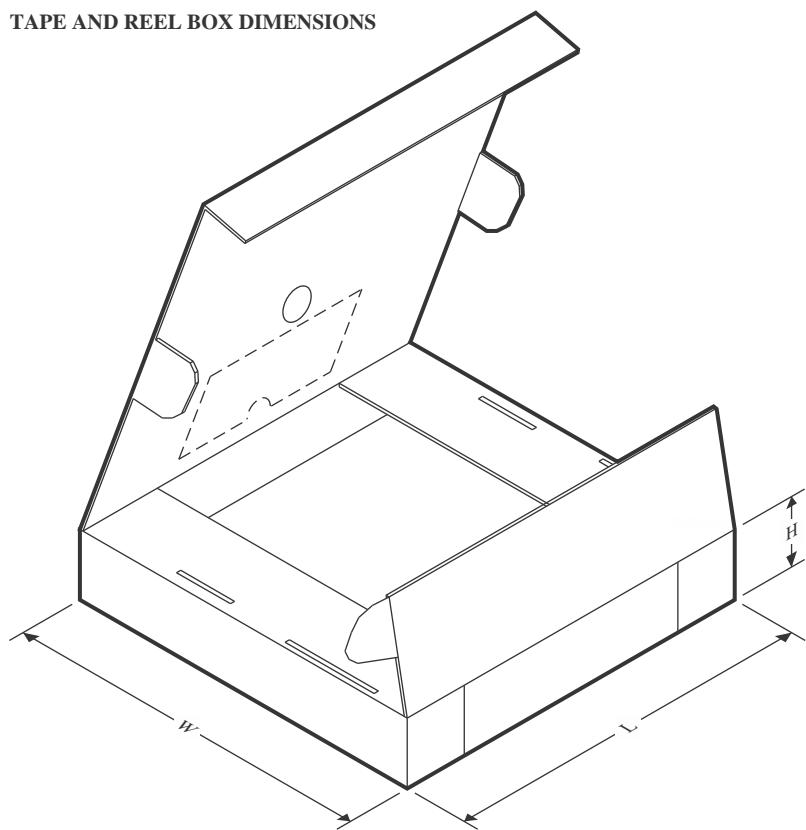
TAPE AND REEL INFORMATION


A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


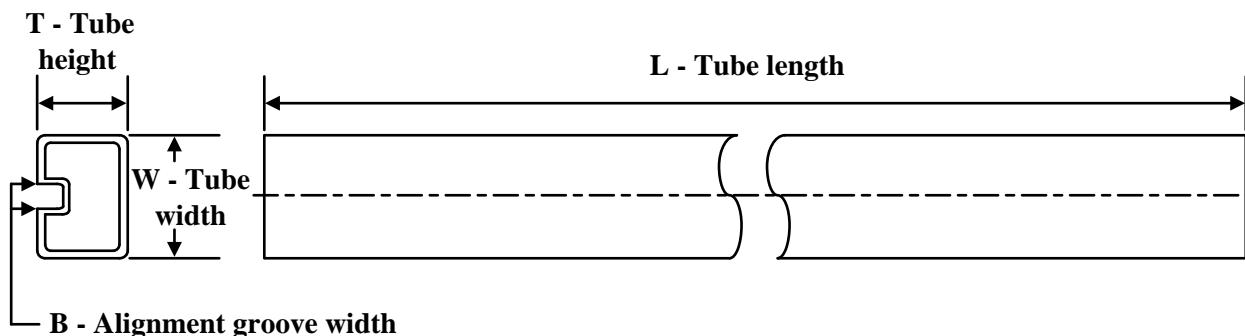
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LF356MX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LF356MX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0

TUBE


*All dimensions are nominal

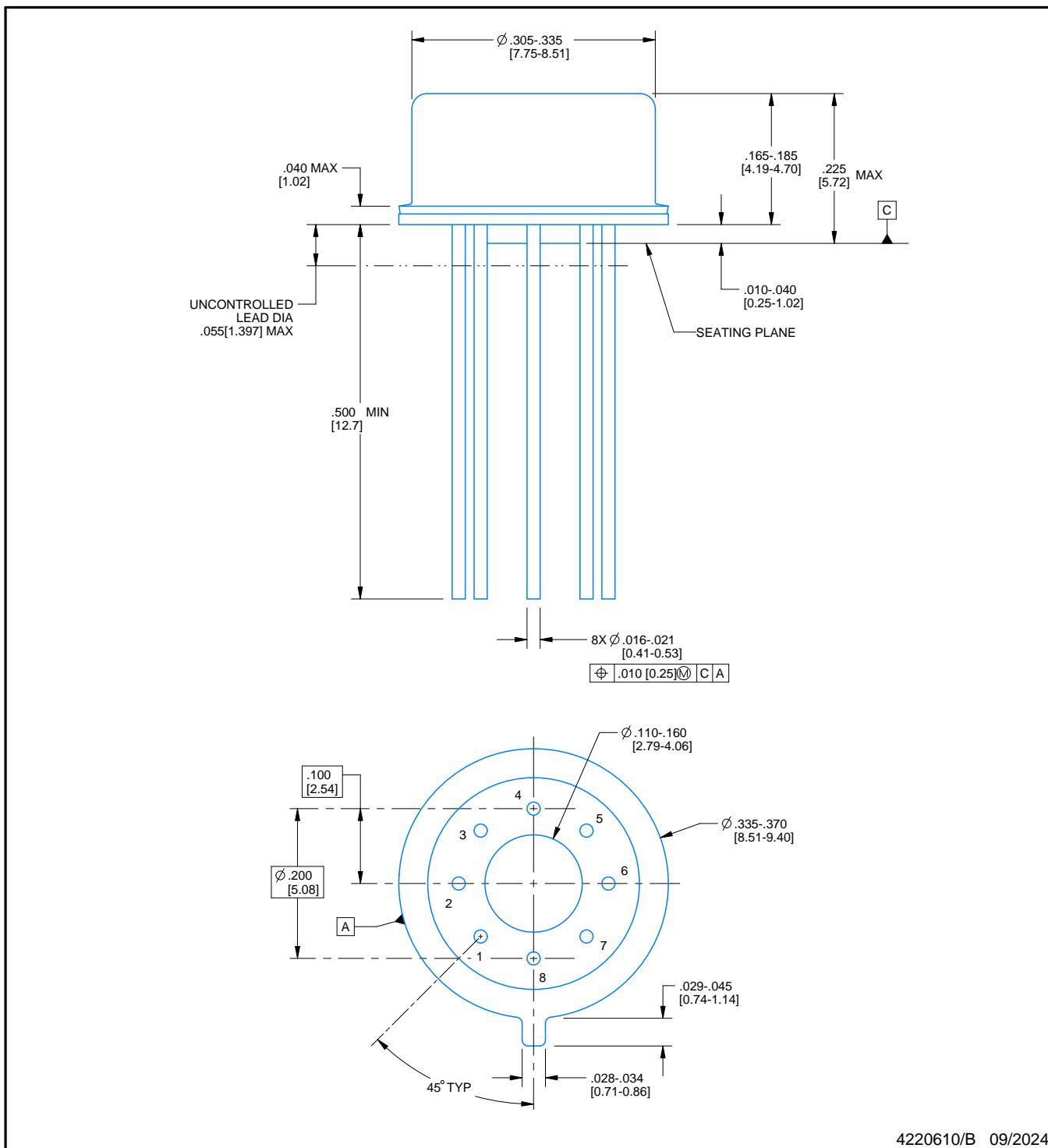
Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
LF356M/NOPB	D	SOIC	8	95	495	8	4064	3.05
LF356M/NOPB.B	D	SOIC	8	95	495	8	4064	3.05
LF356N/NOPB	P	PDIP	8	40	502	14	11938	4.32
LF356N/NOPB.B	P	PDIP	8	40	502	14	11938	4.32
LF356N/NOPBG4	P	PDIP	8	40	502	14	11938	4.32
LF356N/NOPBG4.B	P	PDIP	8	40	502	14	11938	4.32

PACKAGE OUTLINE

LMC0008A

TO-CAN - 5.72 mm max height

TRANSISTOR OUTLINE



4220610/B 09/2024

NOTES:

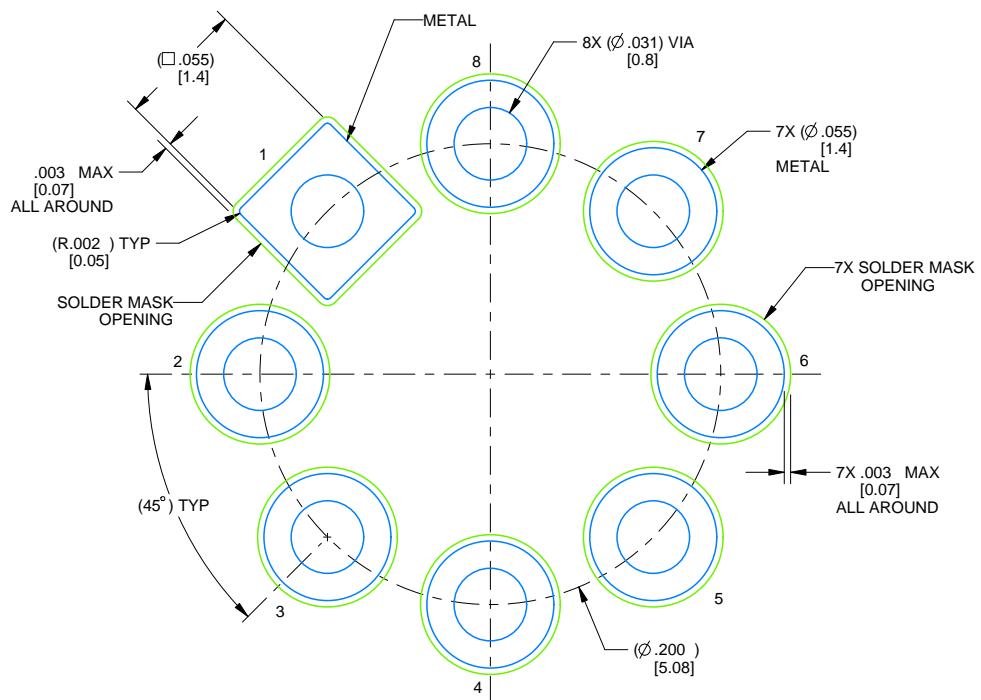
1. All linear dimensions are in inches [millimeters]. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Pin numbers shown for reference only. Numbers may not be marked on package.
4. Reference JEDEC registration MO-002/TO-99.

EXAMPLE BOARD LAYOUT

LMC0008A

TO-CAN - 5.72 mm max height

TRANSISTOR OUTLINE



4220610/B 09/2024

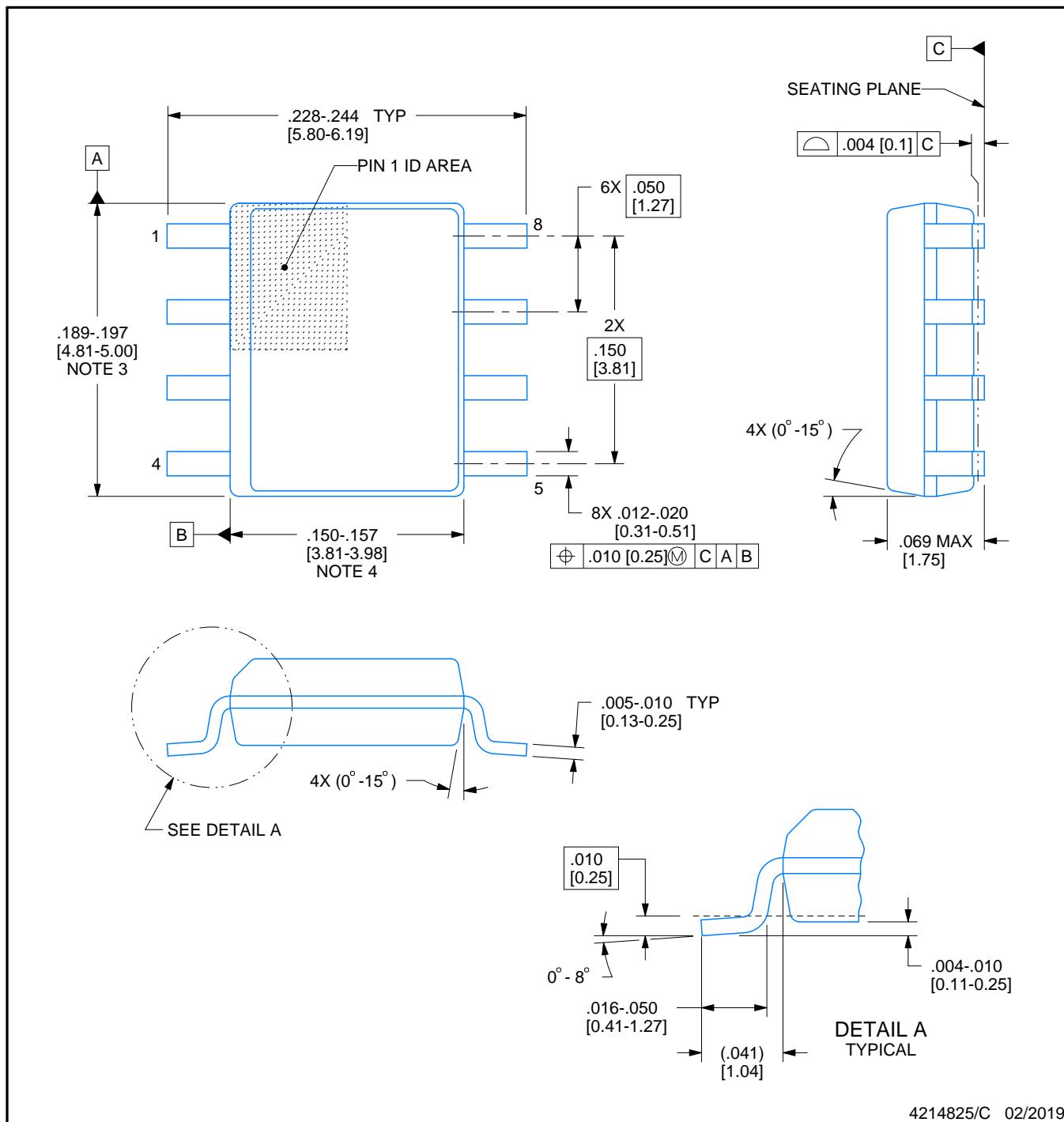


PACKAGE OUTLINE

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES:

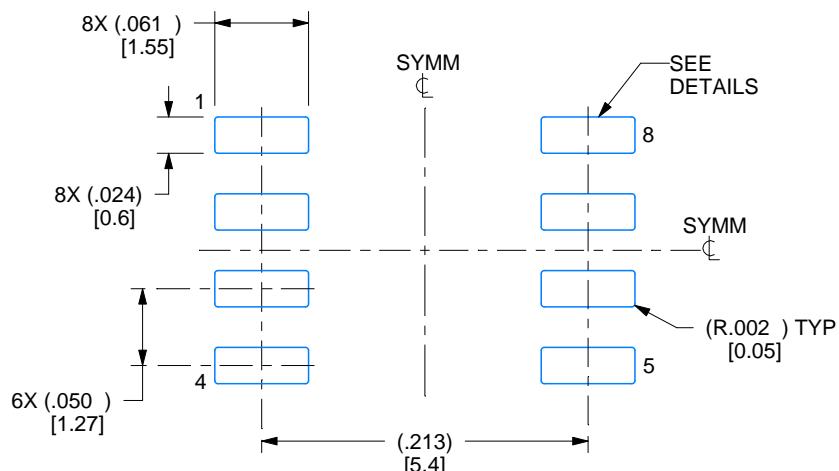
1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

EXAMPLE BOARD LAYOUT

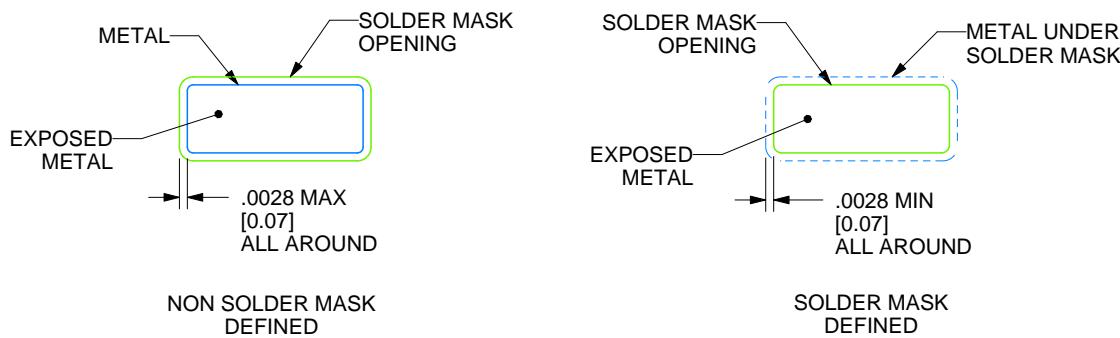
D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X



SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

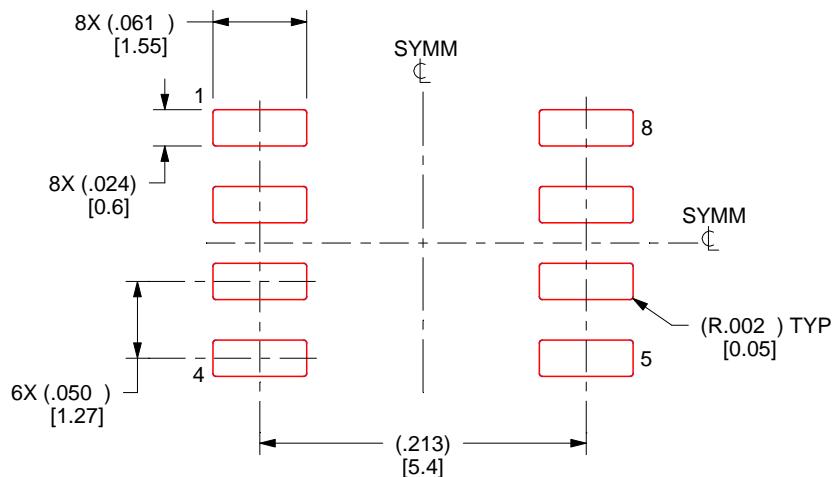
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

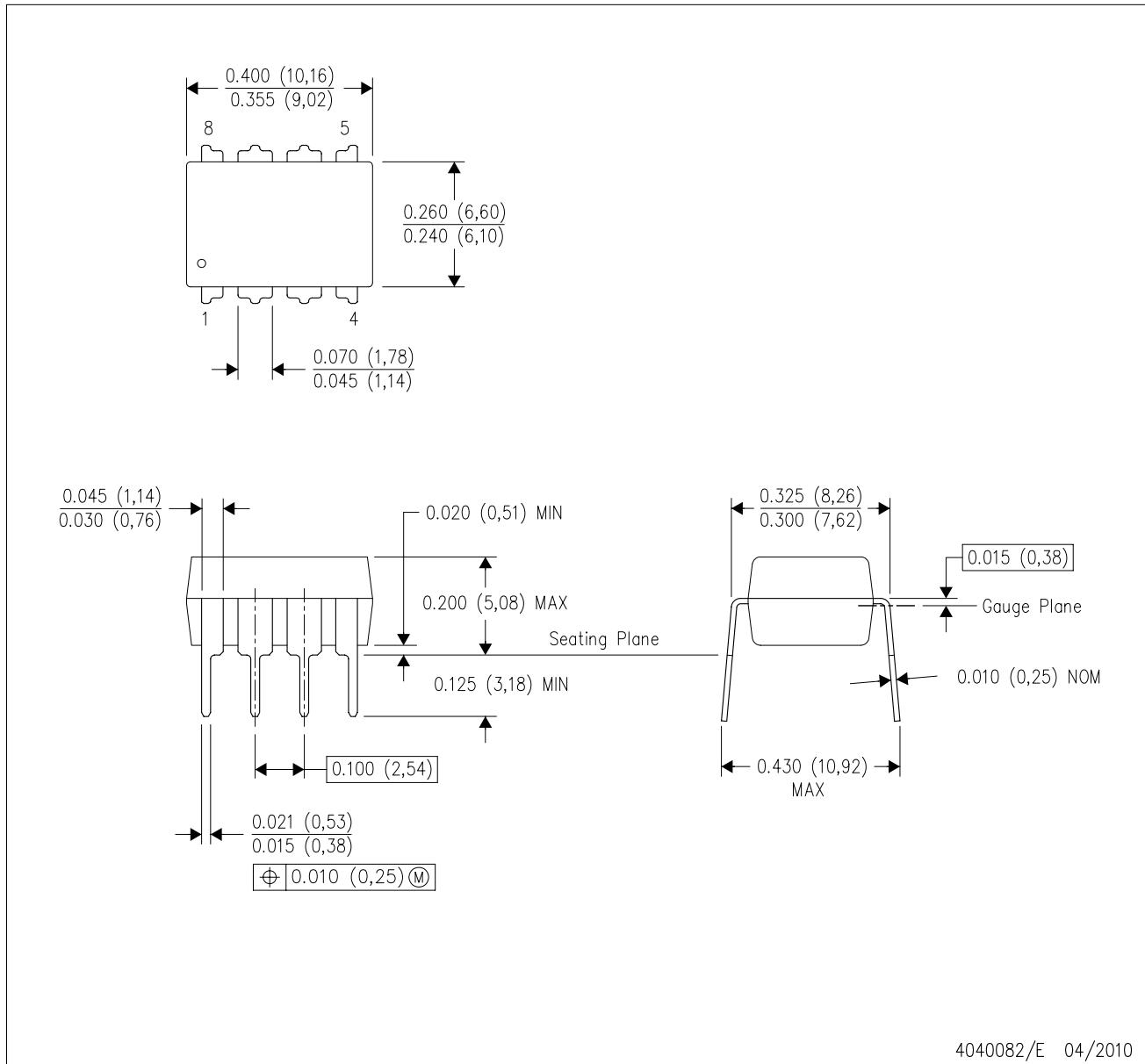
4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

P (R-PDIP-T8)

PLASTIC DUAL-IN-LINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).
 B. This drawing is subject to change without notice.
 C. Falls within JEDEC MS-001 variation BA.

4040082/E 04/2010

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