

# ADS1278-SP Radiation Hardened 8-Ch Simultaneous-Sampling 24-Bit Analog-to-Digital Converter

## 1 Features

- Radiation Hardened
  - TID 75 krad(Si)
  - TID Radiation Lot Acceptance Test (RLAT) TBD
  - Single Event Latchup (SEL) Immune to LET 68 MeV-cm<sup>2</sup>/mg @ 125°C
- Simultaneously Samples Eight Channels
- Up to 128-kSPS Data Rate
- AC Performance:
  - 63-kHz Bandwidth
  - 111-dB SNR (High-Resolution Mode)
  - –108-dB THD
- DC Accuracy:
  - 0.8- $\mu$ V/°C Offset Drift
  - 1.3-ppm/°C Gain Drift
- Selectable Operating Modes:
  - High-Speed: 128 kSPS, 106-dB SNR
  - High-Resolution: 52 kSPS, 111-dB SNR
  - Low-Power: 52 kSPS, 31 mW/ch
  - Low-Speed: 10 kSPS, 7 mW/ch
- Linear Phase Digital Filter
- SPI™ or Frame-Sync Serial Interface
- Low Sampling Aperture Error
- Modulator Output Option (Digital Filter Bypass)
- Analog Supply: 5 V
- Digital Core: 1.8 V
- I/O Supply: 1.8 V to 3.3 V

## 2 Applications

- Space Systems (Satellite, Shuttles, Stations)
  - Satellite Temperature and Position Sensing
  - Orbital Observation Systems
  - Precision and Scientific Applications
  - High-Accuracy Instrumentation

## 3 Description

The ADS1278-SP (octal) is a 24-bit, delta-sigma ( $\Delta\Sigma$ ) analog-to-digital converter (ADC) with data rates up to 128k samples per second (SPS), allowing simultaneous sampling of eight channels.

Traditionally, industrial delta-sigma ADCs offering good drift performance use digital filters with large passband droop. As a result, they have limited signal bandwidth and are mostly suited for dc measurements. High-resolution ADCs in audio applications offer larger usable bandwidths, but the offset and drift specifications are significantly weaker than respective industrial counterparts. The ADS1278-SP combines these types of converters, allowing high-precision industrial measurement with excellent dc and ac specifications.

The high-order, chopper-stabilized modulator achieves very low drift with low in-band noise. The onboard decimation filter suppresses modulator and signal out-of-band noise. These ADCs provide a usable signal bandwidth up to 90% of the Nyquist rate with less than 0.005 dB of ripple.

### Device Information<sup>(1)</sup>

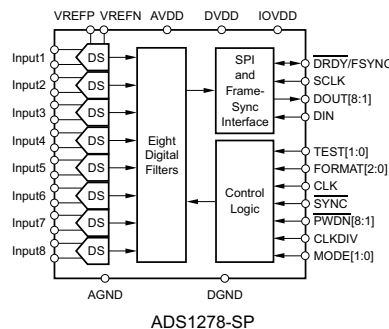
PART NUMBER	GRADE	PACKAGE
ADS1278MHFQ-MLS	Flight Grade 75 krad(Si); –55°C to 125°C	84-Pin HFQ Weight: 4.46 g <sup>(3)</sup>
ADS1278WHFQ-MLS	Flight Grade 75 krad(Si); –55°C to 115°C	
ADS1278HFQ/EM	Engineering Samples <sup>(2)</sup>	
ADS1278EVM-CVAL	Ceramic Evaluation Board	EVM

(1) For all available packages, see the orderable addendum at the end of the data sheet.

(2) These units are intended for engineering evaluation only. They are processed to a noncompliant flow. These units are not suitable for qualification, production, radiation testing or flight use. Parts are not warranted for performance over the full MIL specified temperature range of –55°C to 125°C or operating life.

(3) Weight is accurate to  $\pm 10\%$ .

### Simplified Schematic



## Table of Contents

<b>1 Features</b> ..... 1 <b>2 Applications</b> ..... 1 <b>3 Description</b> ..... 1 <b>4 Revision History</b> ..... 2 <b>5 Description (continued)</b> ..... 3 <b>6 Pin Configuration and Functions</b> ..... 3 <b>7 Specifications</b> ..... 6 7.1 Absolute Maximum Ratings ..... 6 7.2 ESD Ratings..... 6 7.3 Recommended Operating Conditions ..... 6 7.4 Thermal Information ..... 6 7.5 Electrical Characteristics..... 7 7.6 Timing Requirements: SPI Format..... 9 7.7 Timing Requirements: Frame-Sync Format..... 11 7.8 Quality Conformance Inspection ..... 11 7.9 Typical Characteristics ..... 13 <b>8 Detailed Description</b> ..... 22 8.1 Overview ..... 22	8.2 Functional Block Diagram ..... 23 8.3 Feature Description..... 23 8.4 Device Functional Modes..... 45 <b>9 Application and Implementation</b> ..... 46 9.1 Application Information..... 46 9.2 Typical Application ..... 46 <b>10 Power Supply Recommendations</b> ..... 49 <b>11 Layout</b> ..... 50 11.1 Layout Guidelines ..... 50 11.2 Layout Example ..... 51 <b>12 Device and Documentation Support</b> ..... 52 12.1 Receiving Notification of Documentation Updates 52 12.2 Community Resources..... 52 12.3 Trademarks ..... 52 12.4 Electrostatic Discharge Caution..... 52 12.5 Glossary ..... 52 <b>13 Mechanical, Packaging, and Orderable Information</b> ..... 53
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## 4 Revision History

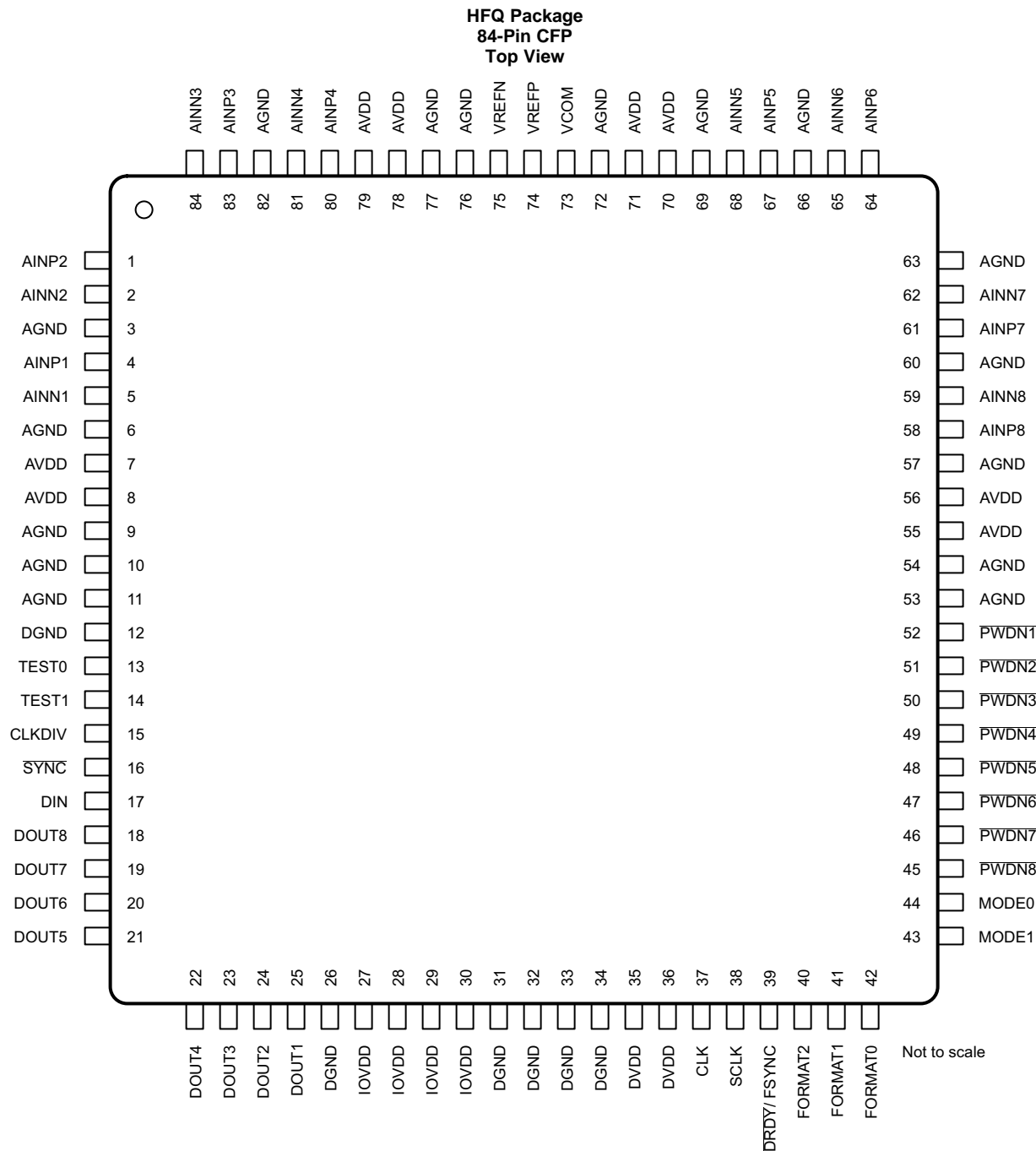
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision A (December 2018) to Revision B	Page
<ul style="list-style-type: none"> <li>• Changed Advance Information to Production Data ..... 1</li> </ul>	1

### 5 Description (continued)

Four operating modes allow for optimization of speed, resolution, and power. All operations are controlled directly by pins; there are no registers to program. The device is fully specified over the extended temperature range of –55°C to 125°C and is available in an 84-pin HFQ package.

### 6 Pin Configuration and Functions



**Pin Functions**

PIN		I/O	DESCRIPTION
NAME	NO.		
AGND	3, 6, 9, 10, 11, 53, 54, 57, 60, 63, 66, 69, 72, 76, 77, 82	Analog ground	Analog ground; connect to DGND using a single plane.
AINP1	4	Analog input	AINP[8:1] Positive analog input, channels 8 through 1.
AINP2	1	Analog input	
AINP3	83	Analog input	
AINP4	80	Analog input	
AINP5	67	Analog input	
AINP6	64	Analog input	
AINP7	61	Analog input	
AINP8	58	Analog input	
AINN1	5	Analog input	AINN[8:1] Negative analog input, channels 8 through 1.
AINN2	2	Analog input	
AINN3	84	Analog input	
AINN4	81	Analog input	
AINN5	68	Analog input	
AINN6	65	Analog input	
AINN7	62	Analog input	
AINN8	59	Analog input	
AVDD	7, 8, 55, 56, 70, 71, 78, 79	Analog power supply	Analog power supply (4.75 V to 5.25 V).
VCOM	73	Analog output	AVDD / 2 Unbuffered voltage output.
VREFN	75	Analog input	Negative reference input.
VREFP	74	Analog input	Positive reference input.
CLK	37	Digital input	Master clock input.
CLKDIV	15	Digital input	CLK input divider control: 1 = 32.768 MHz (High-Speed mode only) / 27 MHz 0 = 13.5 MHz (low-power) / 5.4 MHz (low-speed)
DGND	12, 26, 31, 32, 33, 34	Digital ground	Digital ground power supply.
DIN	17	Digital input	Daisy-chain data input.
DOUT1	25	Digital output	DOUT[8:1] Data output for channels 8 through 1. DOUT1 is TDM data output (TDM mode).
DOUT2	24	Digital output	
DOUT3	23	Digital output	
DOUT4	22	Digital output	
DOUT5	21	Digital output	
DOUT6	20	Digital output	
DOUT7	19	Digital output	
DOUT8	18	Digital output	
$\overline{\text{DRDY}}$ / FSYNC	39	Digital input/output	Frame-Sync protocol: frame clock input; SPI protocol: data ready output.
DVDD	35, 36	Digital power supply	Digital core power supply (+1.65 V to +1.95 V).
FORMAT0	42	Digital input	FORMAT[2:0] Selects Frame-Sync/SPI protocol, TDM/discrete data outputs, fixed/dynamic position TDM data, and modulator mode/normal operating mode.
FORMAT1	41	Digital input	
FORMAT2	40	Digital input	
IOVDD	27, 28, 29, 30	Digital power supply	I/O power supply (+1.65 V to +3.6 V).



## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
AVDD to AGND		−0.3	6	V
AGND to DGND		−0.3	0.3	V
DVDD, IOVDD to DGND		−0.3	3.6	V
Input current	Momentary	100		mA
	Continuous	10		
Analog input to AGND		−0.3	AVDD + 0.3	V
Digital input or output to DGND		−0.3	DVDD + 0.3	V
Junction temperature	HFQ and HKP Packages	−55	217	°C
	D Package	−55	175	
Storage temperature, T <sub>stg</sub>		−60	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	TBD	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	TBD	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
T <sub>J</sub> Operating junction temperature	ADS1278MHFQ-MLS	−55		125	°C
	ADS1278WHFQ-MLS	−55		115	

### 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		ADS1278-SP	UNIT
		HFQ (CFP)	
		84 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	23.7	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	9.6	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	11.5	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	3.0	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	10.9	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	7.7	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 7.5 Electrical Characteristics

All specifications at  $T_A = -55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $\text{AVDD} = 5\text{ V}$ ,  $\text{DVDD} = 1.8\text{ V}$ ,  $\text{IOVDD} = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $\text{VREFP} = 2.5\text{ V}$ ,  $\text{VREFN} = 0\text{ V}$ , and all channels active, unless otherwise noted.

PARAMETER	TEST CONDITIONS	SUBGROUP (1)(2)	–55°C to +125°C (ADS1278MHFQ-MLS)			–55°C to +115°C (ADS1278WHFQ-MLS)			UNIT
			MIN	TYP	MAX	MIN	TYP	MAX	
<b>ANALOG INPUTS</b>									
Full-scale input voltage (FSR <sup>(3)</sup> )	$V_{\text{IN}} = (\text{AINP} - \text{AINN})$		$\pm V_{\text{REF}}$			$\pm V_{\text{REF}}$			V
Absolute input voltage	AINP or AINN to AGND	1, 2, 3	AGND – 0.1		AVDD + 0.1	AGND – 0.1		AVDD + 0.1	V
Common-mode input voltage ( $V_{\text{CM}}$ )	$V_{\text{CM}} = (\text{AINP} + \text{AINN}) / 2$		2.5			2.5			V
Differential input impedance	High-Speed mode		14			14			kΩ
	High-Resolution mode		14			14			
	Low-Power mode		28			28			
	Low-Speed mode		140			140			
<b>DC PERFORMANCE</b>									
Resolution	No missing codes	1, 2, 3	24			24			Bits
Maximum data rate ( $f_{\text{DATA}}$ )	High-Speed mode	$f_{\text{CLK}} = 32.768\text{ MHz}^{(4)}$	128,000			128,000			SPS <sup>(5)</sup>
		$f_{\text{CLK}} = 27\text{ MHz}$	105,469			105,469			
	High-Resolution mode	52,734			52,734				
	Low-Speed mode	10,547			10,547				
Integral nonlinearity (INL) <sup>(6)</sup>	Differential input, $V_{\text{CM}} = 2.5\text{ V}$	1, 2, 3	$\pm 0.0003$	$\pm 0.001_2$	$\pm 0.0003$	$\pm 0.001_2$	% FSR <sup>(3)</sup>		
Offset error		1, 2, 3	0.25	2	0.25	2	mV		
Offset drift			0.8			0.8			$\mu\text{V}/^{\circ}\text{C}$
Gain error		1, 2, 3	0.1	0.5	0.1	0.5	% FSR		
Gain drift			1.3			1.3			$\text{ppm}/^{\circ}\text{C}$
Noise	High-Speed mode	Shorted input	1, 2, 3	8.5	23	8.5	21	$\mu\text{V}$ , rms	
	High-Resolution mode	Shorted input	1, 2, 3	5.5	14	5.5	13		
	Low-Power mode	Shorted input	1, 2, 3	8.5	23	8.5	21		
	Low-Speed mode	Shorted input	1, 2, 3	8.0	23	8.0	21		
Common-mode rejection	$f_{\text{CM}} = 60\text{ Hz}$	1, 2, 3	90	108	90	108	dB		
Power-supply rejection	AVDD	$f_{\text{PS}} = 60\text{ Hz}$	80			80			dB
	DVDD		85			85			
	IOVDD		105			105			
$V_{\text{COM}}$ output voltage	No load		$\text{AVDD} / 2$			$\text{AVDD} / 2$			V
<b>AC PERFORMANCE</b>									
Crosstalk	$f = 1\text{ kHz}$ , $-0.5\text{ dBFS}^{(7)}$		–107			–107			dB
Signal-to-noise ratio (SNR) <sup>(8)</sup> (unweighted)	High-Speed mode		4, 5, 6	98	106	98	106	dB	
	High-Resolution mode	$V_{\text{REF}} = 2.5\text{ V}$	4, 5, 6	101	110	101	110		
		$V_{\text{REF}} = 3\text{ V}$			111		111		
	Low-Speed mode		4, 5, 6	98	106	98	106		
Total harmonic distortion (THD) <sup>(9)</sup>	$V_{\text{IN}} = 1\text{ kHz}$ , $-0.5\text{ dBFS}$	4, 5, 6	–108	–96	–108	–96	dB		
Spurious-free dynamic range			109			109			dB

(1) For subgroup definitions, please see [Quality Conformance Inspection](#) table.

(2) Subgroups apply to **–55°C to +125°C** column only.

(3) FSR = full-scale range =  $2 V_{\text{REF}}$ .

(4)  $f_{\text{CLK}} = 32.768\text{-MHz}$  max for High-Speed mode and 27-MHz max for all other modes. When  $f_{\text{CLK}} > 27\text{ MHz}$ , operation is limited to Frame-Sync mode and  $V_{\text{REF}} \leq 2.6\text{ V}$ .

(5) SPS = samples per second.

(6) Best fit method.

(7) Worst-case channel crosstalk between one or more channels.

(8) Minimum SNR is ensured by the limit of the *DC noise* specification.

(9) THD includes the first nine harmonics of the input signal; Low-Speed mode includes the first five harmonics.

**Electrical Characteristics (continued)**

All specifications at  $T_A = -55^\circ\text{C}$  to  $125^\circ\text{C}$ ,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $V_{\text{REFP}} = 2.5\text{ V}$ ,  $V_{\text{REFN}} = 0\text{ V}$ , and all channels active, unless otherwise noted.

PARAMETER	TEST CONDITIONS	SUBGROUP (1)(2)	-55°C to +125°C (ADS1278MHFQ-MLS)			-55°C to +115°C (ADS1278WHFQ-MLS)			UNIT
			MIN	TYP	MAX	MIN	TYP	MAX	
Passband ripple			±0.005			±0.005			dB
Passband			0.453 $f_{\text{DATA}}$			0.453 $f_{\text{DATA}}$			Hz
-3-dB bandwidth			0.49 $f_{\text{DATA}}$			0.49 $f_{\text{DATA}}$			Hz
Stop band attenuation	High-Resolution mode	4, 5, 6	95			95			dB
	All other modes	4, 5, 6	100			100			dB
Stop band	High-Resolution mode	4, 5, 6	0.547 $f_{\text{DATA}}$		127.45 3 $f_{\text{DATA}}$	0.547 $f_{\text{DATA}}$		127.45 3 $f_{\text{DATA}}$	Hz
	All other modes	4, 5, 6	0.547 $f_{\text{DATA}}$		63.453 $f_{\text{DATA}}$	0.547 $f_{\text{DATA}}$		63.453 $f_{\text{DATA}}$	Hz
Group delay	High-Resolution mode		39/ $f_{\text{DATA}}$			39/ $f_{\text{DATA}}$			s
	All other modes		38/ $f_{\text{DATA}}$			38/ $f_{\text{DATA}}$			
Settling time (latency)	High-Resolution mode	Complete settling	78/ $f_{\text{DATA}}$			78/ $f_{\text{DATA}}$			s
	All other modes	Complete settling	76/ $f_{\text{DATA}}$			76/ $f_{\text{DATA}}$			
<b>VOLTAGE REFERENCE INPUTS</b>									
Reference input voltage ( $V_{\text{REF}}$ ) ( $V_{\text{REF}} = V_{\text{REFP}} - V_{\text{REFN}}$ )	$f_{\text{CLK}} = 27\text{ MHz}$	1, 2, 3	0.5	2.5	3.1	0.5	2.5	3.1	V
	$f_{\text{CLK}} = 32.768\text{ MHz}^{(4)}$	1, 2, 3	0.5	2.5	2.6	0.5	2.5	2.6	
Negative reference input ( $V_{\text{REFN}}$ )		1, 2, 3	AGND – 0.1		AGND + 0.1	AGND – 0.1		AGND + 0.1	V
Positive reference input ( $V_{\text{REFP}}$ )		1, 2, 3	VREFN + 0.5		AVDD + 0.1	VREFN + 0.5		AVDD + 0.1	V
Reference Input impedance	High-Speed mode		0.65			0.65			kΩ
	High-Resolution mode		0.65			0.65			
	Low-Power mode		1.3			1.3			
	Low-Speed mode		6.5			6.5			
<b>DIGITAL INPUT/OUTPUT (<math>IOVDD = 1.8\text{ V}</math> to <math>3.6\text{ V}</math>)</b>									
$V_{\text{IH}}$		4, 5, 6	0.7 $IOVDD$		$IOVDD$	0.7 $IOVDD$		$IOVDD$	V
$V_{\text{IL}}$		4, 5, 6	DGND		0.3 $IOVDD$	DGND		0.3 $IOVDD$	V
$V_{\text{OH}}$	$I_{\text{OH}} = 4\text{ mA}$	4, 5, 6	0.8 $IOVDD$		$IOVDD$	0.8 $IOVDD$		$IOVDD$	V
$V_{\text{OL}}$	$I_{\text{OL}} = 4\text{ mA}$	4, 5, 6	DGND		0.2 $IOVDD$	DGND		0.2 $IOVDD$	V
Input leakage	$0 < V_{\text{IN DIGITAL}} < IOVDD$	4, 5, 6	±11			±10			μA
Master clock rate ( $f_{\text{CLK}}$ )	High-Speed mode <sup>(4)</sup>	4, 5, 6	0.1		32.768	0.1		32.768	MHz
	Other modes	1, 2, 3	0.1		27	0.1		27	
<b>POWER SUPPLY</b>									
AVDD		1, 2, 3	4.75	5	5.25	4.75	5	5.25	V
DVDD		1, 2, 3	1.65	1.8	1.95	1.65	1.8	1.95	V
IOVDD		1, 2, 3	1.65		3.6	1.65		3.6	V
Power-down current	AVDD	1, 2, 3	1		11	1		10	μA
	DVDD	1, 2, 3	1		52	1		50	
	IOVDD	1, 2, 3	1		12	1		11	
AVDD current	High-Speed mode	1, 2, 3	97		148	97		145	mA
	High-Resolution mode	1, 2, 3	97		148	97		145	
	Low-Power mode	1, 2, 3	44		66	44		64	
	Low-Speed mode	1, 2, 3	9		15	9		14	

## Electrical Characteristics (continued)

All specifications at  $T_A = -55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $\text{AVDD} = 5\text{ V}$ ,  $\text{DVDD} = 1.8\text{ V}$ ,  $\text{IOVDD} = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $\text{VREFP} = 2.5\text{ V}$ ,  $\text{VREFN} = 0\text{ V}$ , and all channels active, unless otherwise noted.

PARAMETER		TEST CONDITIONS	SUBGROUP (1)(2)	-55°C to +125°C (ADS1278MHFQ-MLS)			-55°C to +115°C (ADS1278WHFQ-MLS)			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
DVDD current	High-Speed mode		1, 2, 3		23	31		23	30	mA
	High-Resolution mode		1, 2, 3		16	21		16	20	
	Low-Power mode		1, 2, 3		12	18		12	17	
	Low-Speed mode		1, 2, 3		2.5	5		2.5	4.5	
IOVDD current	High-Speed mode		1, 2, 3		0.25	1.5		0.25	1	mA
	High-Resolution mode		1, 2, 3		0.125	0.8		0.125	0.6	
	Low-Power mode		1, 2, 3		0.125	0.8		0.125	0.6	
	Low-Speed mode		1, 2, 3		0.035	0.5		0.035	0.3	
Power dissipation	High-Speed mode		1, 2, 3		530	805		530	785	mW
	High-Resolution mode		1, 2, 3		515	785		515	765	
	Low-Power mode		1, 2, 3		245	370		245	355	
	Low-Speed mode		1, 2, 3		50	85		50	80	

## 7.6 Timing Requirements: SPI Format<sup>(1)</sup>

For  $T_A = -55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $\text{IOVDD} = 1.65\text{ V}$  to  $3.6\text{ V}$ , and  $\text{DVDD} = 1.65\text{ V}$  to  $1.95\text{ V}$ .

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
$t_{\text{CLK}}$	CLK period ( $1 / f_{\text{CLK}}$ ) <sup>(2)</sup>	37		10,000	ns
$t_{\text{CPW}}$	CLK positive or negative pulse width	15			ns
$t_{\text{CONV}}$	Conversion period ( $1 / f_{\text{DATA}}$ ) <sup>(3)</sup>	256		2560	$t_{\text{CLK}}$
$t_{\text{CD}}$ <sup>(4)</sup>	Falling edge of CLK to falling edge of $\overline{\text{DRDY}}$		22		ns
$t_{\text{DS}}$ <sup>(4)</sup>	Falling edge of $\overline{\text{DRDY}}$ to rising edge of first SCLK to retrieve data	1			$t_{\text{CLK}}$
$t_{\text{MSBPD}}$	$\overline{\text{DRDY}}$ falling edge to DOUT MSB valid (propagation delay)			16	ns
$t_{\text{SD}}$ <sup>(4)</sup>	Falling edge of SCLK to rising edge of $\overline{\text{DRDY}}$		18		ns
$t_{\text{SCLK}}$ <sup>(5)</sup>	SCLK period	1			$t_{\text{CLK}}$
$t_{\text{SPW}}$	SCLK positive or negative pulse width	0.4			$t_{\text{CLK}}$
$t_{\text{DOHD}}$ <sup>(4)(6)</sup>	SCLK falling edge to new DOUT invalid (hold time)	10			ns
$t_{\text{DOPD}}$ <sup>(4)</sup>	SCLK falling edge to new DOUT valid (propagation delay)			32	ns
$t_{\text{DIST}}$	New DIN valid to falling edge of SCLK (setup time)	6			ns
$t_{\text{DIHD}}$ <sup>(6)</sup>	Old DIN valid to falling edge of SCLK (hold time)	6			ns

(1) Timing parameters are characterized or assured by design for specified temperature but not production tested.

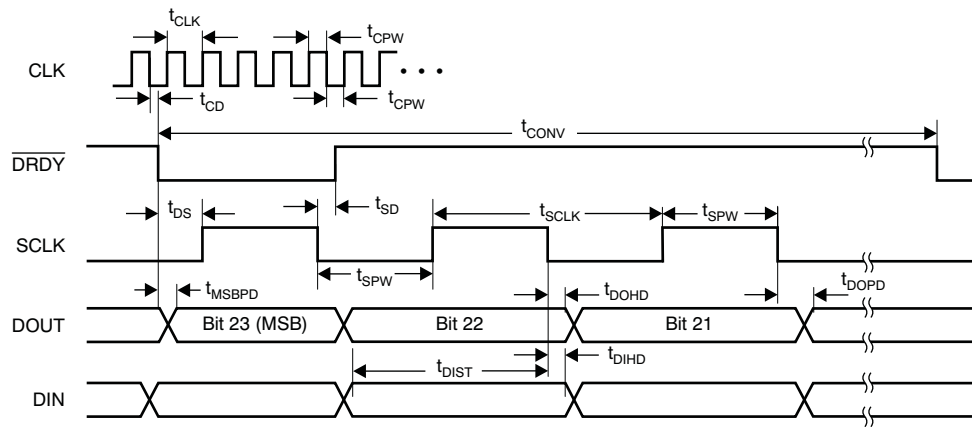
(2)  $f_{\text{CLK}} = 27\text{-MHz}$  maximum.

(3) Depends on  $\text{MODE}[1:0]$  and  $\text{CLKDIV}$  selection. See [Table 5](#) ( $f_{\text{CLK}} / f_{\text{DATA}}$ ).

(4) Load on  $\overline{\text{DRDY}}$  and DOUT = 20 pF.

(5) For best performance, limit  $f_{\text{SCLK}} / f_{\text{CLK}}$  to ratios of 1, 1/2, 1/4, 1/8, etc..

(6)  $t_{\text{DOHD}}$  (DOUT hold time) and  $t_{\text{DIHD}}$  (DIN hold time) are specified under opposite worst-case conditions (digital supply voltage and ambient temperature). Under equal conditions, with DOUT connected directly to DIN, the timing margin is > 4 ns.



**Figure 1. SPI Format Timing Characteristics**

### 7.7 Timing Requirements: Frame-Sync Format<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT	
t <sub>CLK</sub>	CLK period (1 / f <sub>CLK</sub> )	All modes		37	10,000	ns
		High-Speed mode only		30.5		ns
t <sub>CPW</sub>	CLK positive or negative pulse width	12			ns	
t <sub>CS</sub>	Falling edge of CLK to falling edge of SCLK	-0.25		0.25	t <sub>CLK</sub>	
t <sub>FRAME</sub>	Frame period (1 / f <sub>DATA</sub> ) <sup>(2)</sup>	256		2560	t <sub>CLK</sub>	
t <sub>FPW</sub>	FSYNC positive or negative pulse width	1			t <sub>SCLK</sub>	
t <sub>FS</sub>	Rising edge of FSYNC to rising edge of SCLK	5			ns	
t <sub>SF</sub>	Rising edge of SCLK to rising edge of FSYNC	5			ns	
t <sub>SCLK</sub>	SCLK period <sup>(3)</sup>	1			t <sub>CLK</sub>	
t <sub>SPW</sub>	SCLK positive or negative pulse width	0.4			t <sub>CLK</sub>	
t <sub>DOHD</sub> <sup>(4)</sup> (5)	SCLK falling edge to old DOUT invalid (hold time)	10			ns	
t <sub>DOPD</sub> <sup>(5)</sup>	SCLK falling edge to new DOUT valid (propagation delay)			31	ns	
t <sub>MSBPD</sub>	FSYNC rising edge to DOUT MSB valid (propagation delay)			31	ns	
t <sub>DIST</sub>	New DIN valid to falling edge of SCLK (setup time)	6			ns	
t <sub>DIHD</sub> <sup>(4)</sup>	Old DIN valid to falling edge of SCLK (hold time)	6			ns	

- (1) Timing parameters are characterized or assured by design for specified temperature but not production tested.
- (2) Depends on MODE[1:0] and CLKDIV selection. See Table 5 (f<sub>CLK</sub> / f<sub>DATA</sub>).
- (3) SCLK must be continuously running and limited to ratios of 1, 1/2, 1/4, and 1/8 of f<sub>CLK</sub>.
- (4) t<sub>DOHD</sub> (DOUT hold time) and t<sub>DIHD</sub> (DIN hold time) are specified under opposite worst-case conditions (digital supply voltage and ambient temperature). Under equal conditions, with DOUT connected directly to DIN, the timing margin is > 4 ns.
- (5) Load on DOUT = 20 pF.

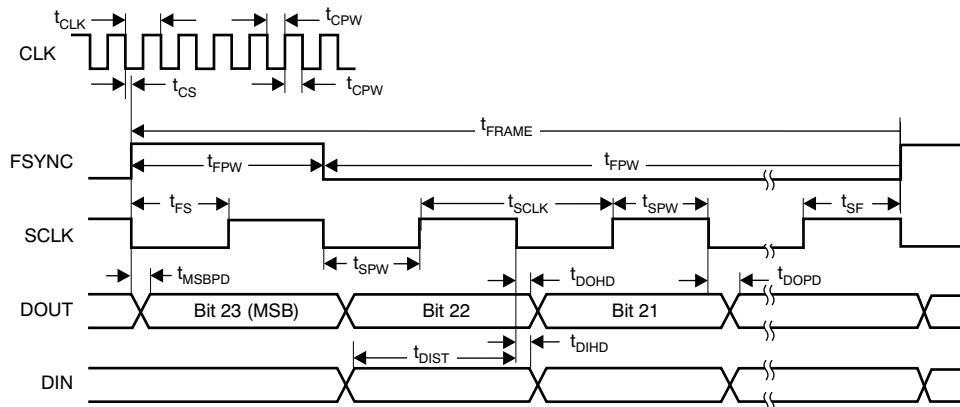


Figure 2. Frame-Sync Format Timing Characteristics

### 7.8 Quality Conformance Inspection

MIL-STD-883, Method 5005 - Group A

SUBGROUP	DESCRIPTION	TEMP (°C)
1	Static tests at	25
2	Static tests at	125
3	Static tests at	-55
4	Dynamic tests at	25
5	Dynamic tests at	125
6	Dynamic tests at	-55
7	Functional tests at	25

**Quality Conformance Inspection (continued)**

SUBGROUP	DESCRIPTION	TEMP (°C)
8A	Functional tests at	125
8B	Functional tests at	-55
9	Switching tests at	25
10	Switching tests at	125
11	Switching tests at	-55
12	Setting time at	25
13	Setting time at	125
14	Setting time at	-55

### 7.9 Typical Characteristics

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $V_{\text{REFP}} = 2.5\text{ V}$ , and  $V_{\text{REFN}} = 0\text{ V}$ , unless otherwise noted.

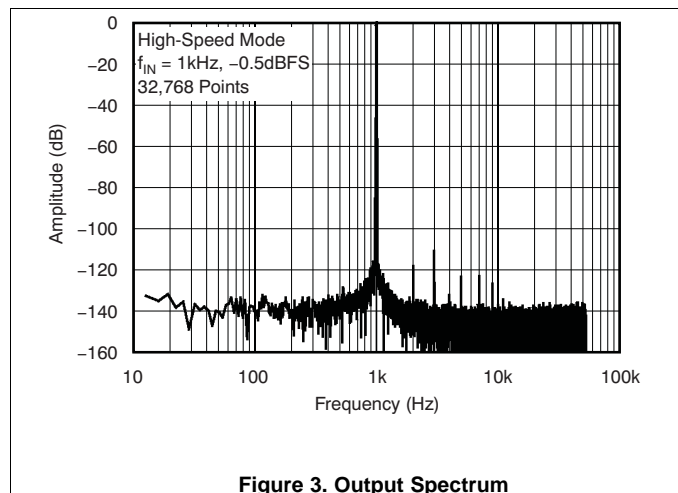


Figure 3. Output Spectrum

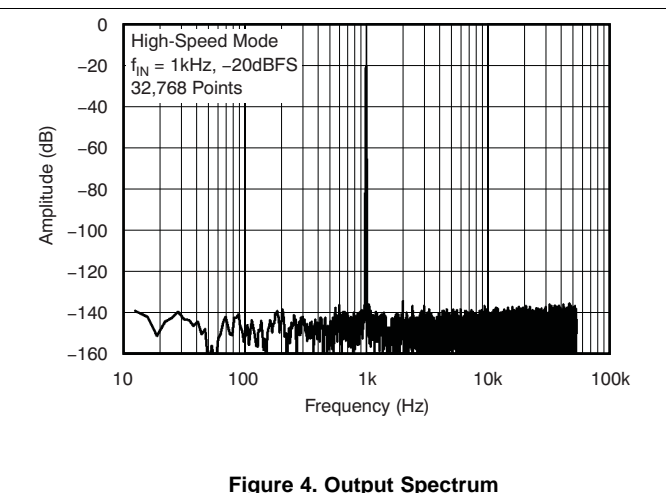


Figure 4. Output Spectrum

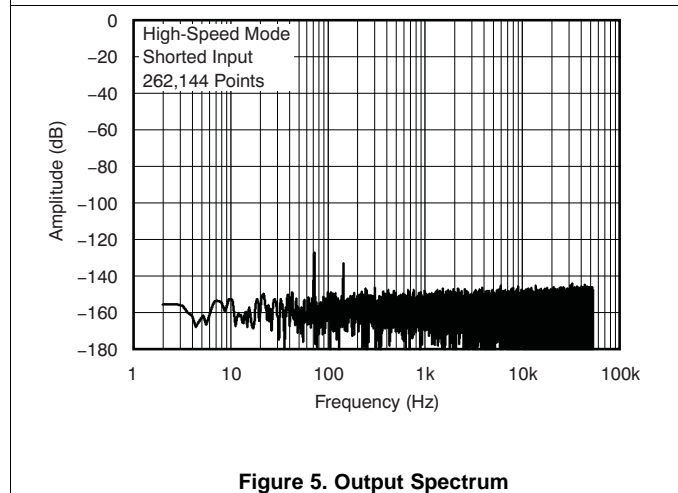


Figure 5. Output Spectrum

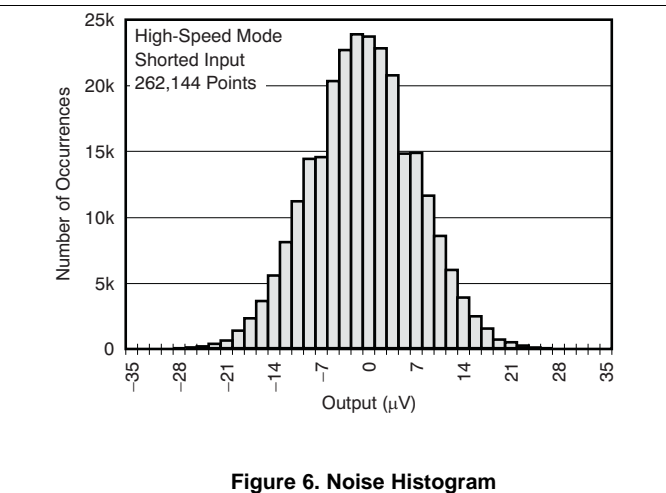


Figure 6. Noise Histogram

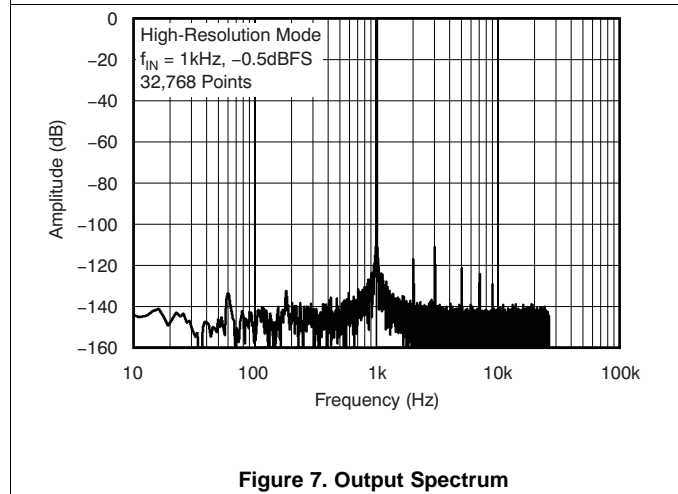


Figure 7. Output Spectrum

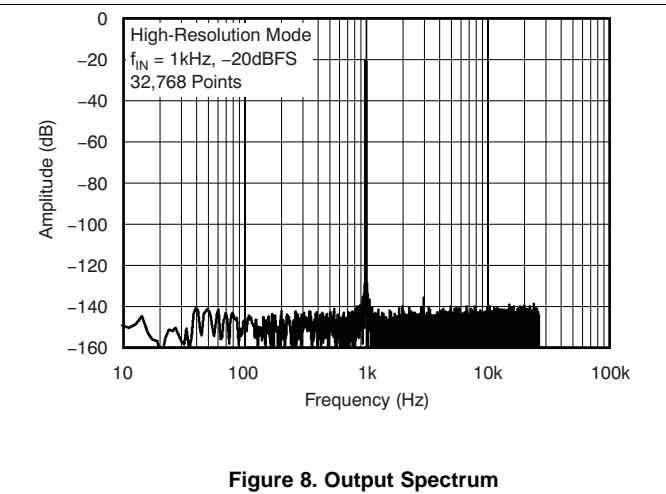


Figure 8. Output Spectrum

Typical Characteristics (continued)

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $VREFP = 2.5\text{ V}$ , and  $VREFN = 0\text{ V}$ , unless otherwise noted.

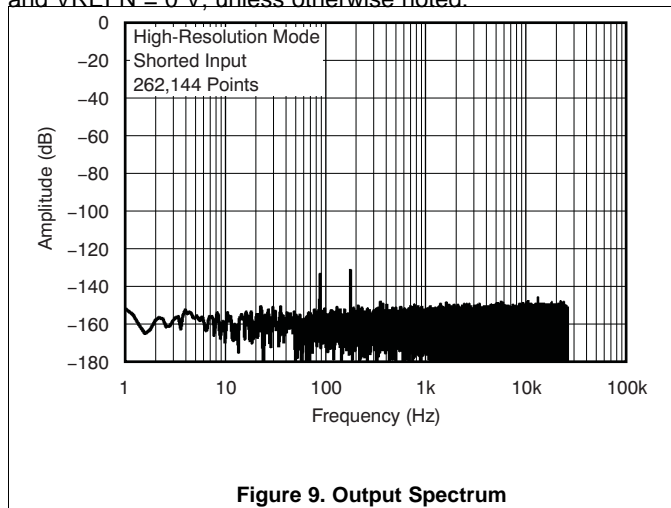


Figure 9. Output Spectrum

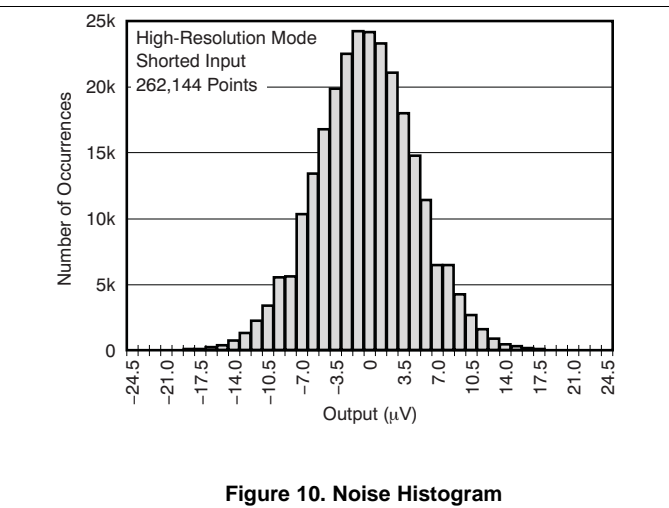


Figure 10. Noise Histogram

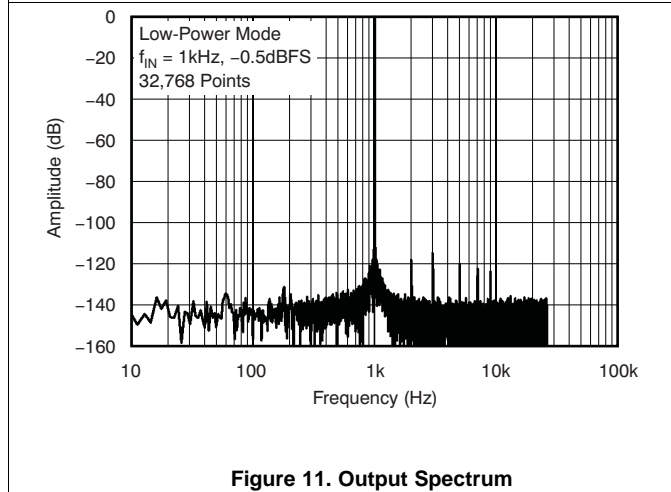


Figure 11. Output Spectrum

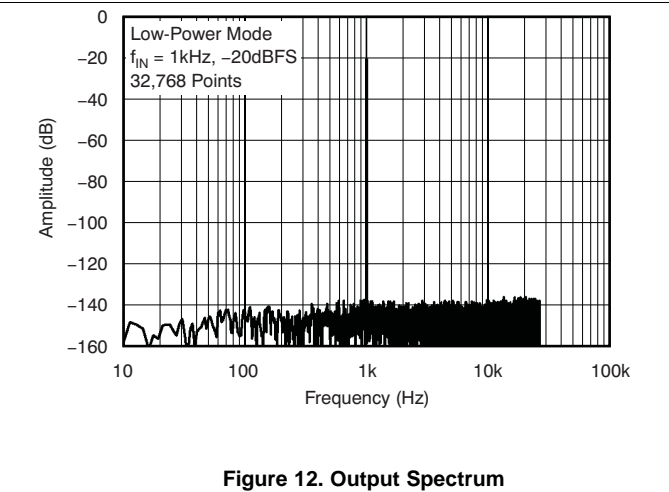


Figure 12. Output Spectrum

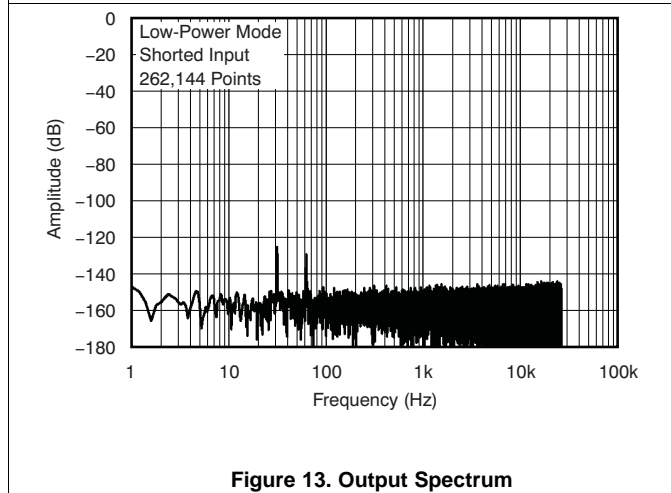


Figure 13. Output Spectrum

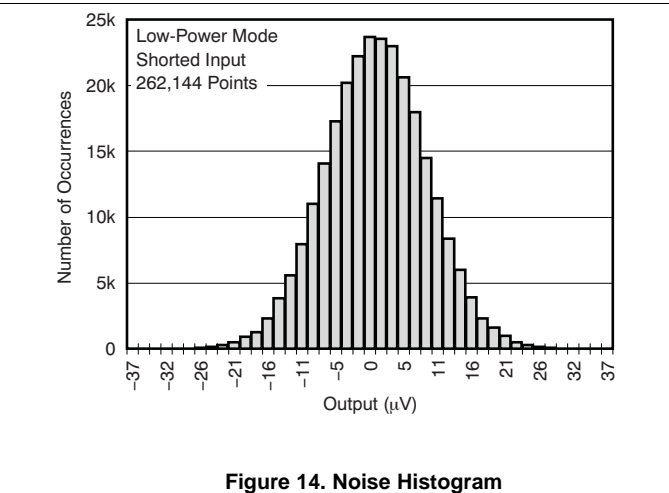


Figure 14. Noise Histogram

Typical Characteristics (continued)

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IOV_{DD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

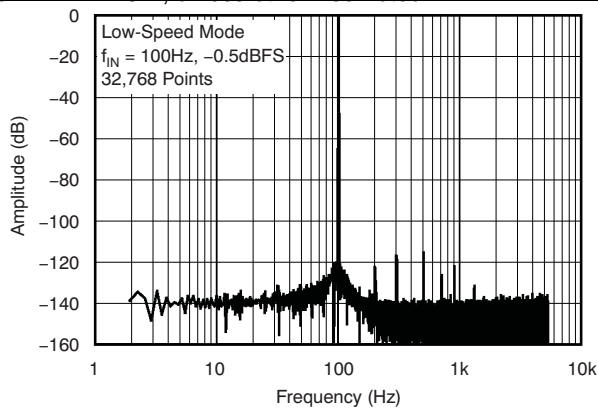


Figure 15. Output Spectrum

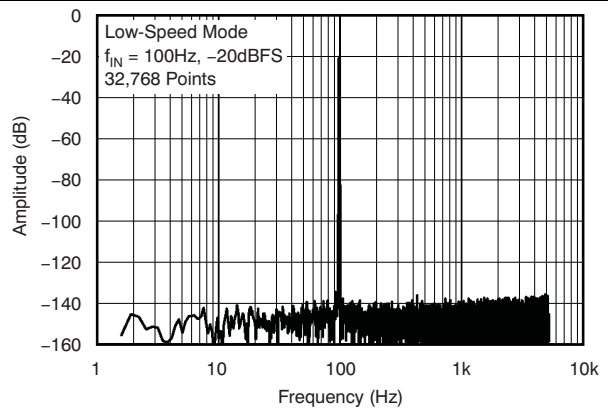


Figure 16. Output Spectrum

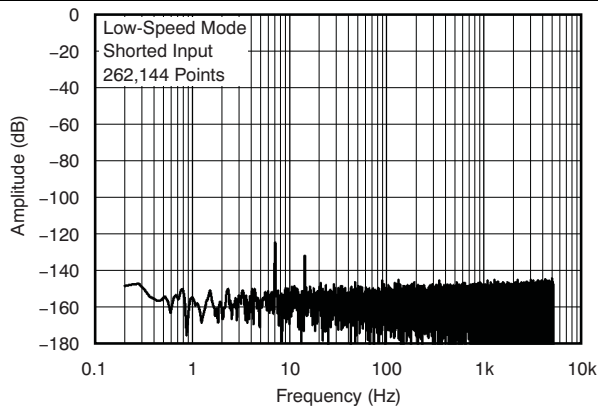


Figure 17. Output Spectrum

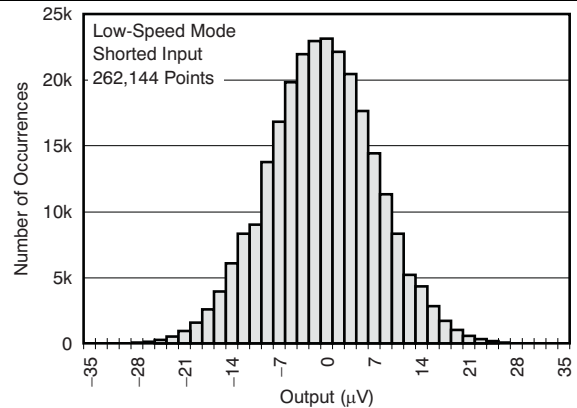


Figure 18. Noise Histogram

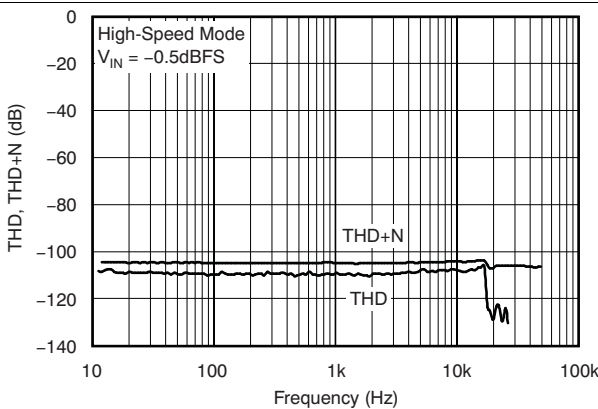


Figure 19. Total Harmonic Distortion vs Frequency

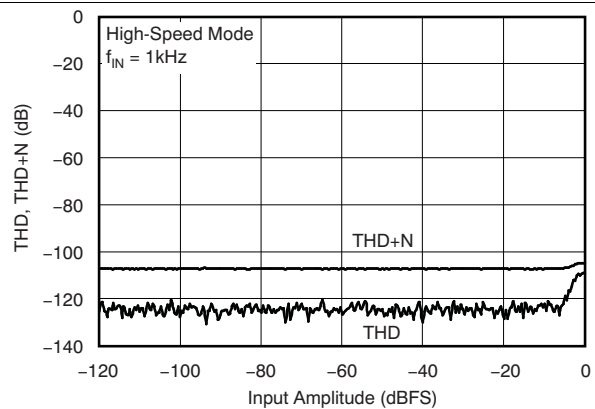


Figure 20. Total Harmonic Distortion vs Input Amplitude

**Typical Characteristics (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IOV_{DD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

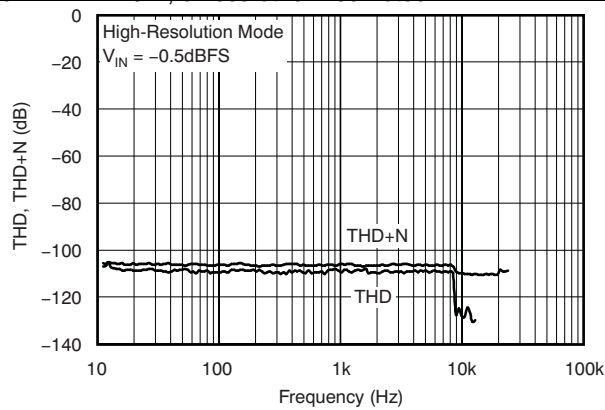


Figure 21. Total Harmonic Distortion vs Frequency

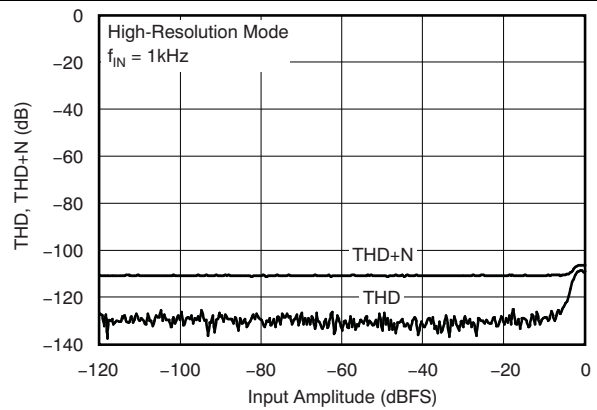


Figure 22. Total Harmonic Distortion vs Input Amplitude

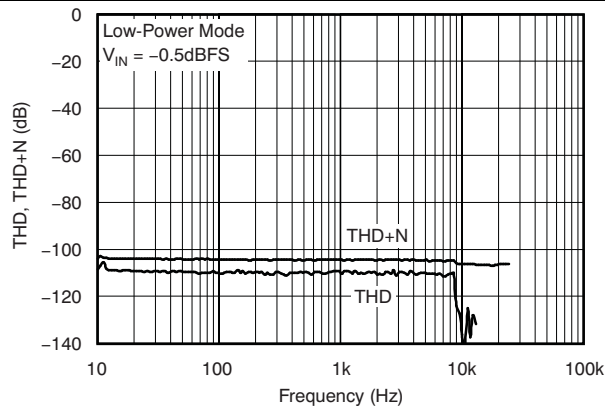


Figure 23. Total Harmonic Distortion vs Frequency

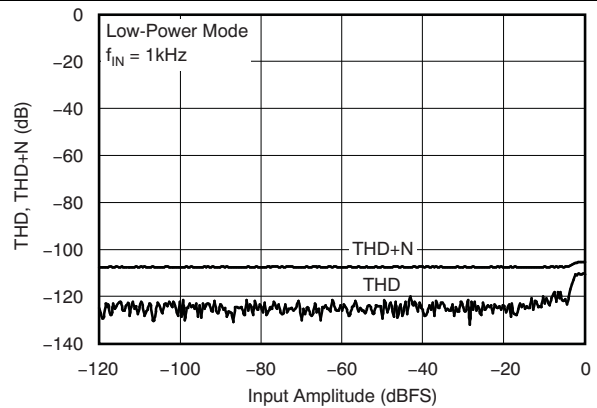


Figure 24. Total Harmonic Distortion vs Input Amplitude

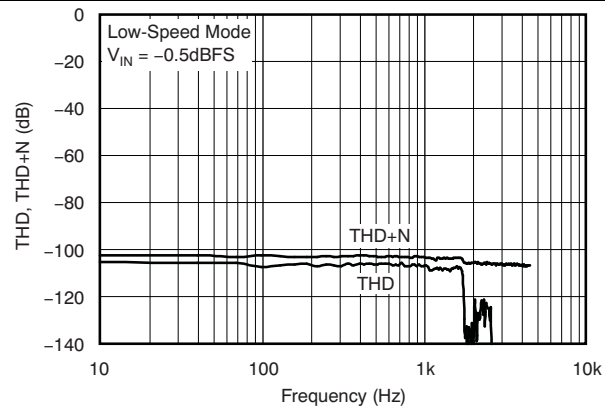


Figure 25. Total Harmonic Distortion vs Frequency

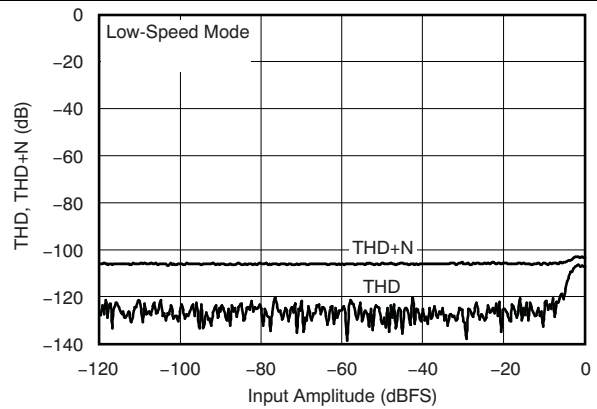


Figure 26. Total Harmonic Distortion vs Input Amplitude

Typical Characteristics (continued)

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $V_{\text{REFP}} = 2.5\text{ V}$ , and  $V_{\text{REFN}} = 0\text{ V}$ , unless otherwise noted.

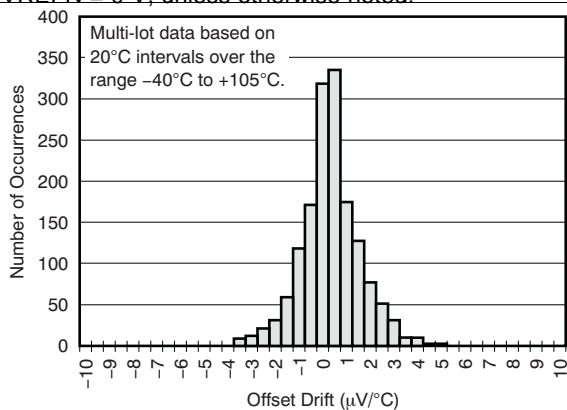


Figure 27. Offset Drift Histogram

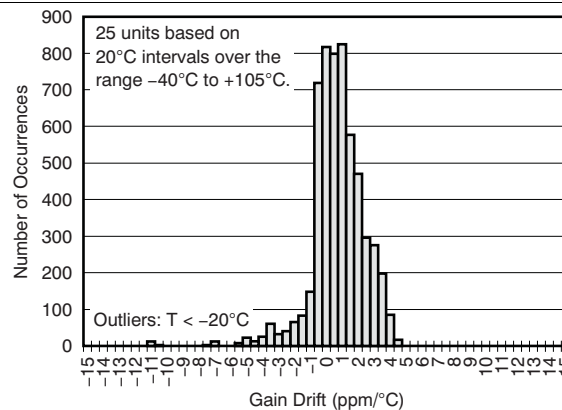


Figure 28. Gain Drift Histogram

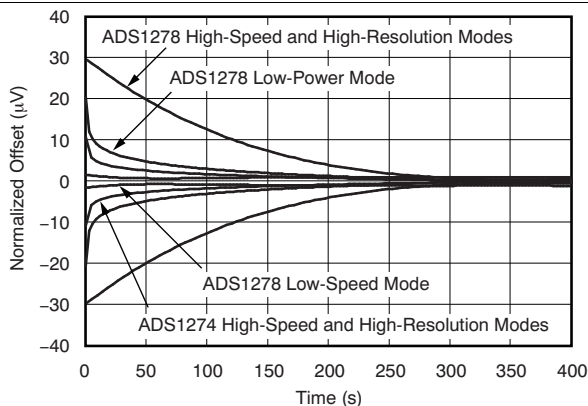


Figure 29. Offset Warmup Drift Response Band

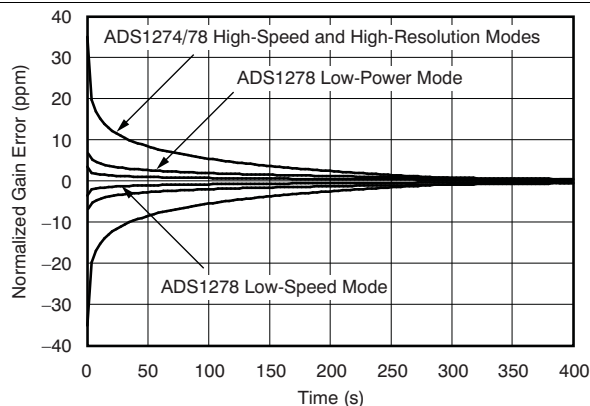


Figure 30. Gain Warmup Drift Response Band

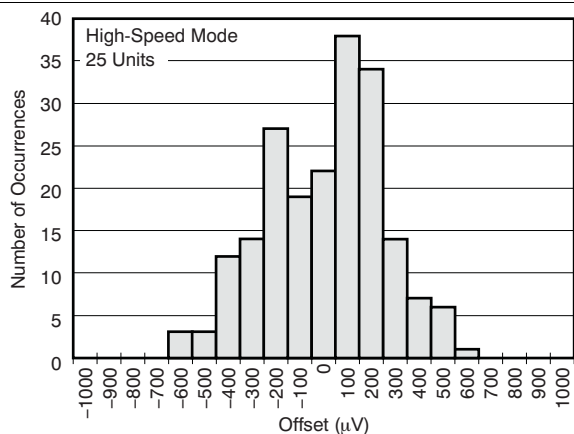


Figure 31. Offset Error Histogram

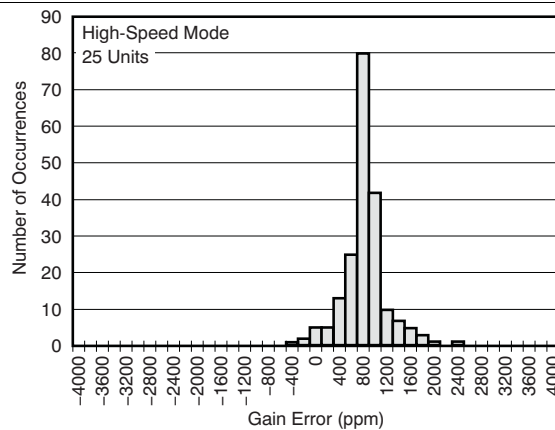


Figure 32. Gain Error Histogram

Typical Characteristics (continued)

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $V_{\text{REFP}} = 2.5\text{ V}$ , and  $V_{\text{REFN}} = 0\text{ V}$ , unless otherwise noted.

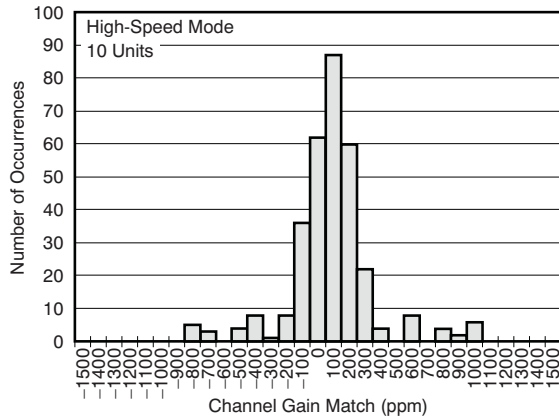


Figure 33. Channel Gain Match Histogram

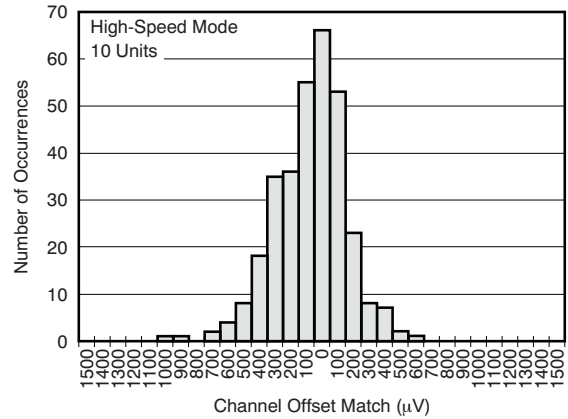


Figure 34. Channel Offset Match Histogram

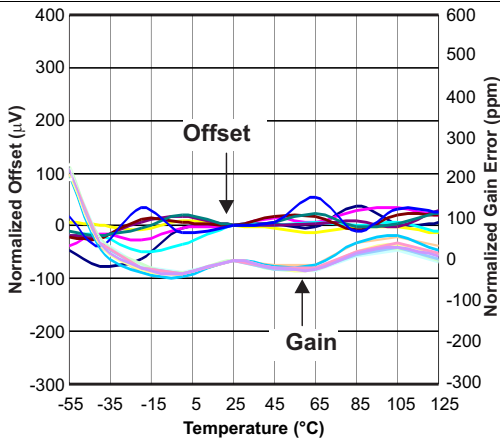


Figure 35. Offset and Gain vs Temperature

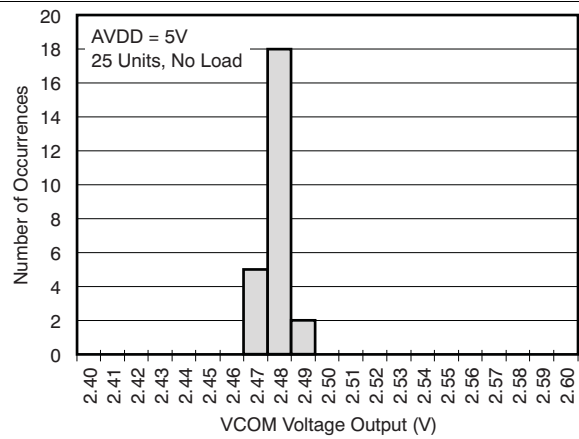


Figure 36. VCOM Voltage Output Histogram

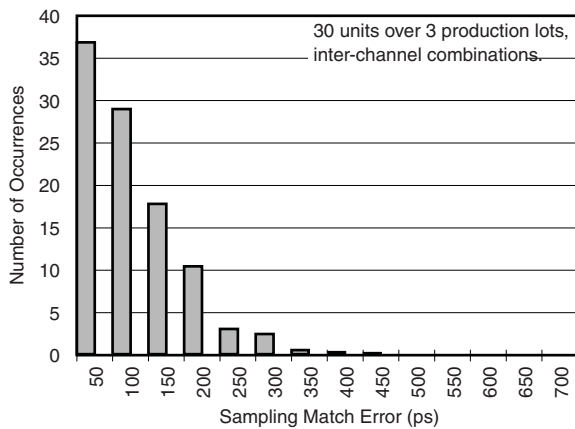


Figure 37. Sampling Match Error Histogram

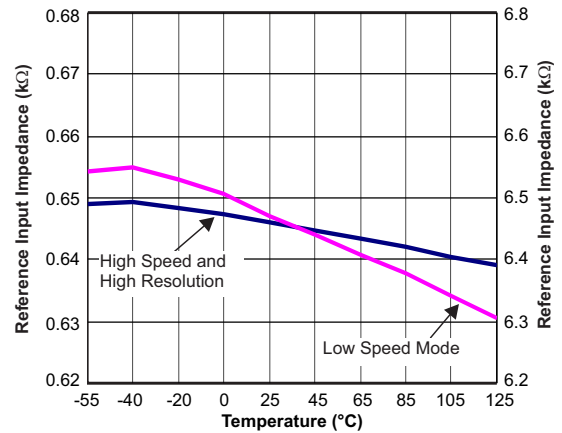


Figure 38. Reference Input Differential Impedance vs Temperature

Typical Characteristics (continued)

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IO_{VDD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

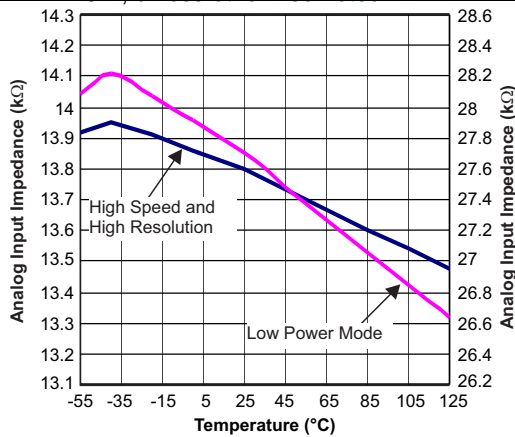


Figure 39. Analog Input Differential Impedance vs Temperature

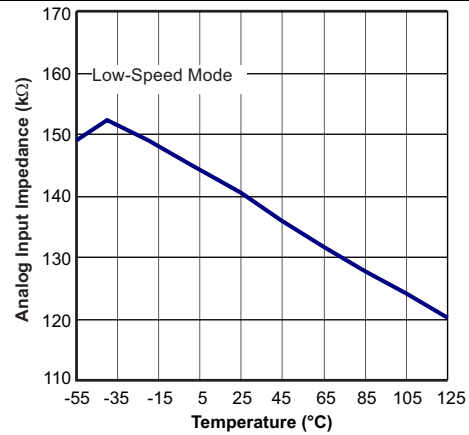


Figure 40. Analog Input Differential Impedance vs Temperature

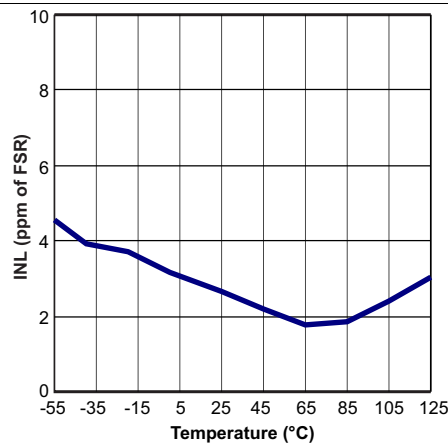


Figure 41. Integral Nonlinearity vs Temperature

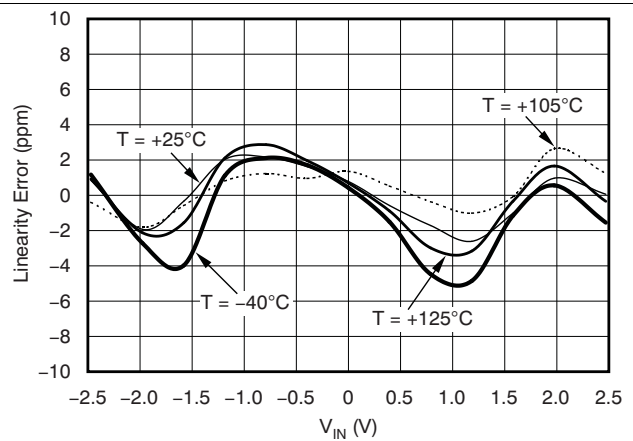


Figure 42. Linearity Error vs Input Level

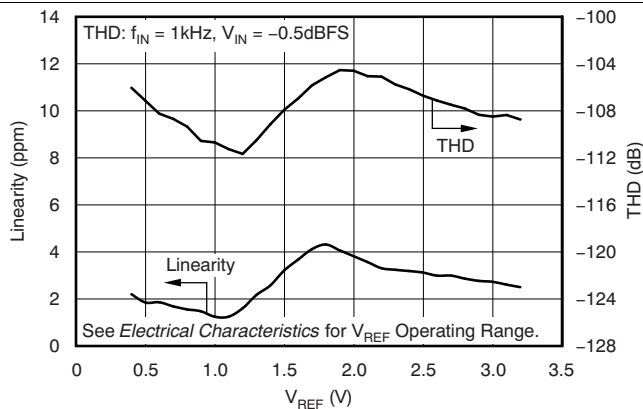


Figure 43. Linearity and Total Harmonic Distortion vs Reference Voltage

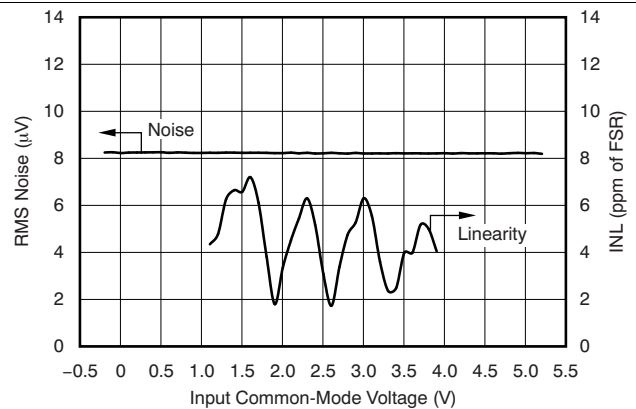


Figure 44. Noise and Linearity vs Input Common-Mode Voltage

ADS1278-SP

SBAS937B – SEPTEMBER 2018 – REVISED DECEMBER 2018

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Typical Characteristics (continued)

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $V_{\text{REFP}} = 2.5\text{ V}$ , and  $V_{\text{REFN}} = 0\text{ V}$ , unless otherwise noted.

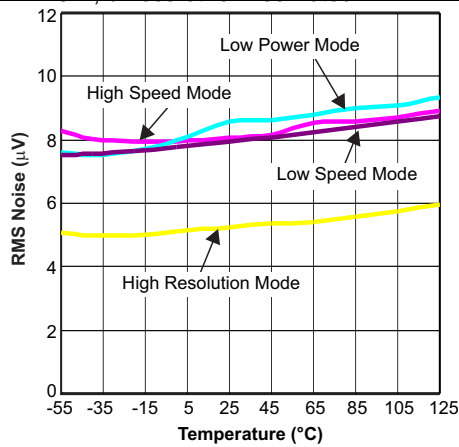


Figure 45. Noise vs Temperature

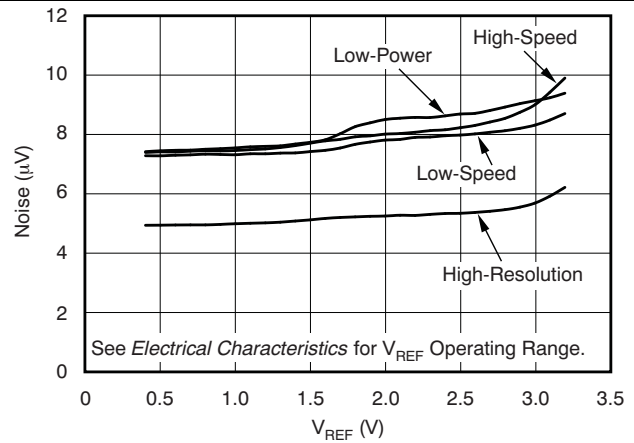


Figure 46. Noise vs Reference Voltage

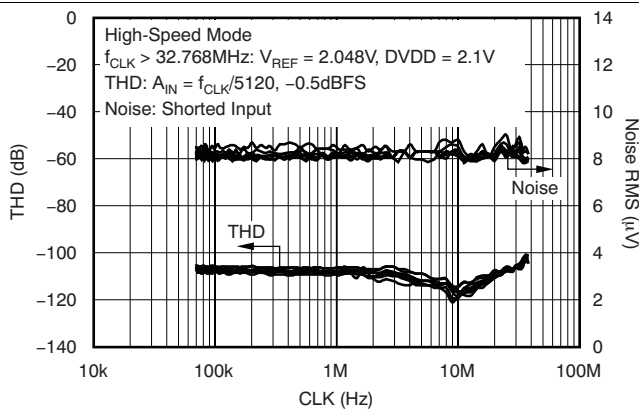


Figure 47. Total Harmonic Distortion and Noise vs CLK

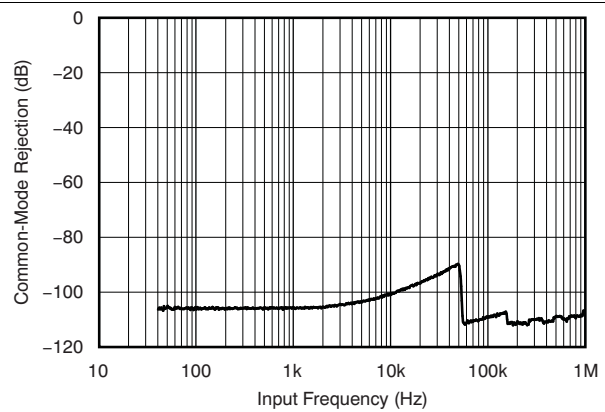


Figure 48. Common-Mode Rejection vs Input Frequency

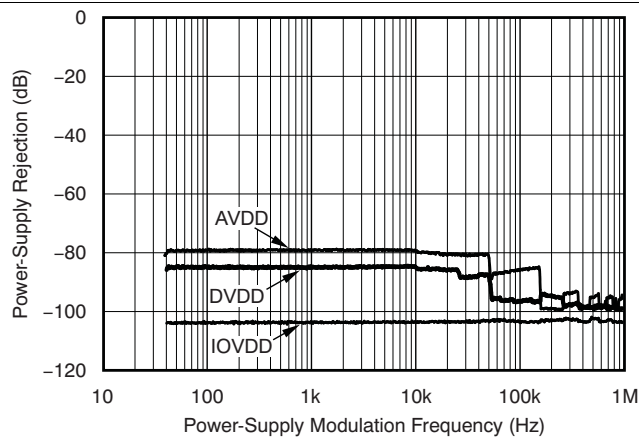


Figure 49. Power-Supply Rejection vs Power-Supply Frequency

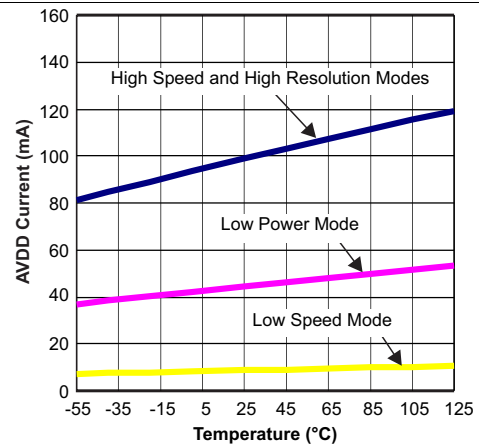
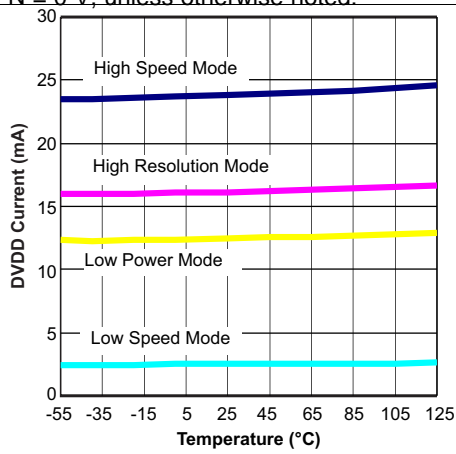


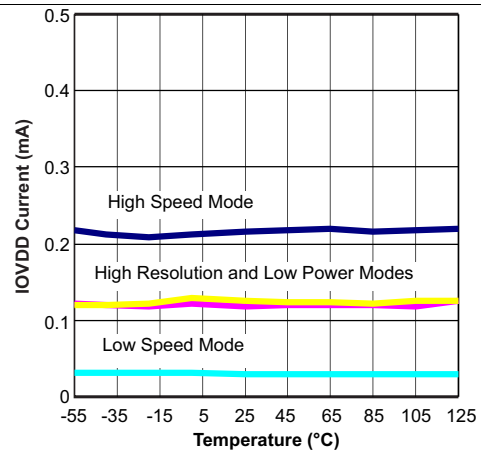
Figure 50. AVDD Current vs Temperature

**Typical Characteristics (continued)**

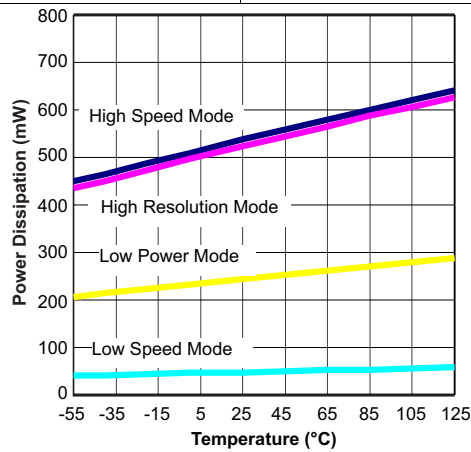
At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $VREFP = 2.5\text{ V}$ , and  $VREFN = 0\text{ V}$ , unless otherwise noted.



**Figure 51. DVDD Current vs Temperature**



**Figure 52. IOVDD Current vs Temperature**



**Figure 53. Power Dissipation vs Temperature**

## 8 Detailed Description

### 8.1 Overview

The ADS1278-SP is a delta-sigma ADC consisting of eight independent converters that digitize eight input signals in parallel.

The converter is composed of two main functional blocks to perform the ADC conversions: the modulator and the digital filter. The modulator samples the input signal together with sampling the reference voltage to produce a 1-s density output stream. The density of the output stream is proportional to the analog input level relative to the reference voltage. The pulse stream is filtered by the internal digital filter where the output conversion result is produced.

In operation, the input signal is sampled by the modulator at a high rate (typically 64x higher than the final output data rate). The quantization noise of the modulator is moved to a higher frequency range where the internal digital filter removes it. Oversampling results in very low levels of noise within the signal passband.

Since the input signal is sampled at a very high rate, input signal aliasing does not occur until the input signal frequency is at the modulator sampling rate. This architecture greatly relaxes the requirement of external antialiasing filters because of the high modulator sampling rate.

The ADS1278-SP is an octal 24-bit, delta-sigma ADC. It offers the combination of outstanding dc accuracy and superior ac performance. [Functional Block Diagram](#) section shows the block diagram. The converter is comprised of eight advanced, 6th-order, chopper-stabilized, delta-sigma modulators followed by low-ripple, linear phase FIR filters. The modulators measure the differential input signal,  $V_{IN} = (AINP - AINN)$ , against the differential reference,  $V_{REF} = (VREFP - VREFN)$ . The digital filters receive the modulator signal and provide a low-noise digital output. To allow tradeoffs among speed, resolution, and power, four operating modes are supported:

High-Speed, High-Resolution, Low-Power, and Low-Speed. [Table 15](#) summarizes the performance of each mode.

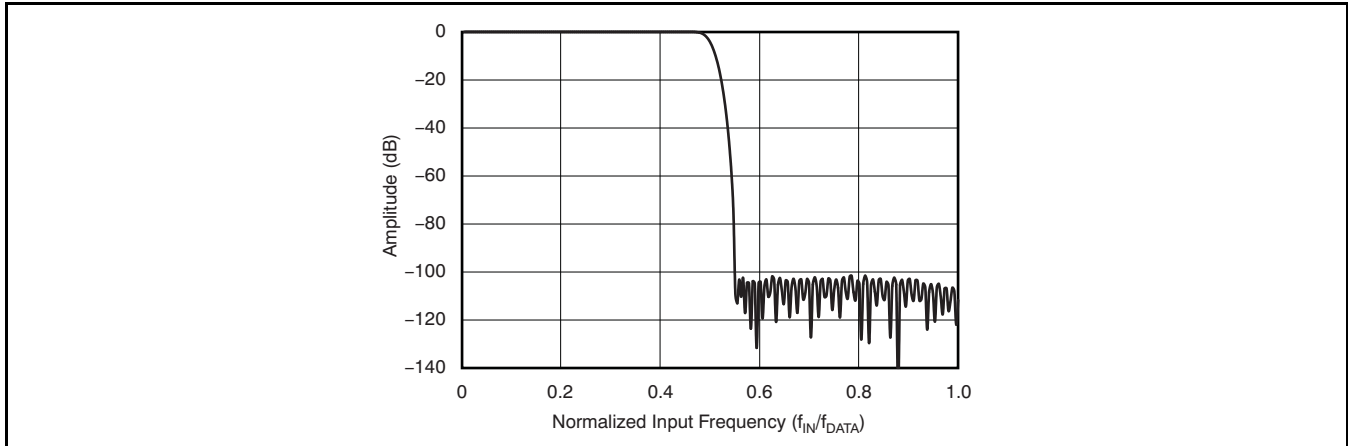
In High-Speed mode, the maximum data rate is 128 kSPS (when operating at 128 kSPS, Frame-Sync format must be used). In High-Resolution mode, the SNR = 111 dB ( $V_{REF} = 3.0$  V); in Low-Power mode, the power dissipation is 31 mW/channel; and in Low-Speed mode, the power dissipation is only 7 mW/channel at 10.5 kSPS. The digital filters can be bypassed, enabling direct access to the modulator output.

The ADS1278-SP is configured by simply setting the appropriate I/O pins—there are no registers to program. Data are retrieved over a serial interface that supports both SPI and Frame-Sync formats. The ADS1278-SP has a daisy-chainable output and the ability to synchronize externally, so it can be used conveniently in systems requiring more than eight channels.

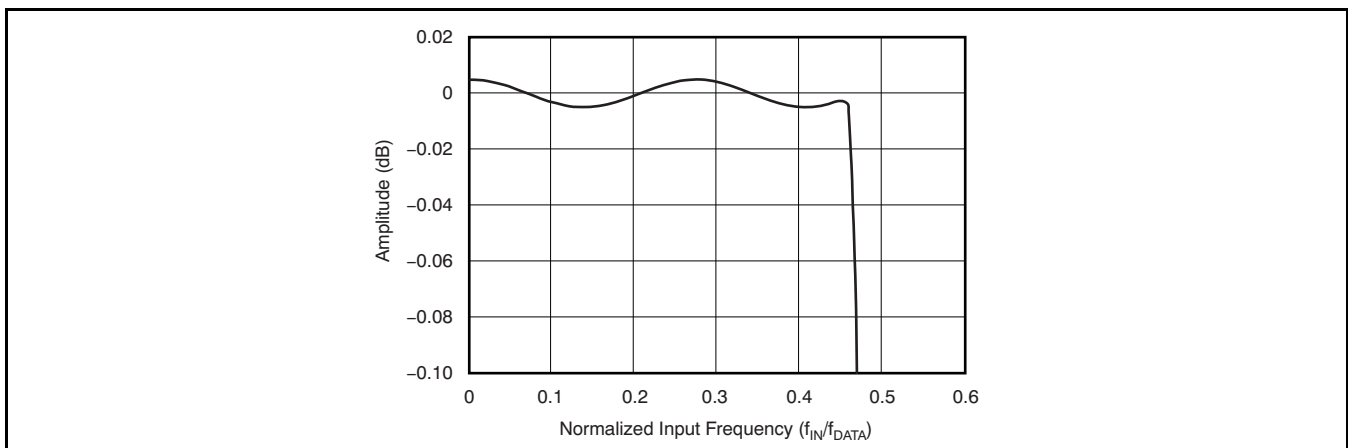


### 8.3.2.1 High-Speed, Low-Power, And Low-Speed Modes

The digital filter configuration is the same in High-Speed, Low-Power, and Low-Speed modes with the oversampling ratio set to 64. [Figure 54](#) shows the frequency response in High-Speed, Low-Power, and Low-Speed modes normalized to  $f_{\text{DATA}}$ . [Figure 55](#) shows the passband ripple. The transition from passband to stop band is shown in [Figure 56](#). The overall frequency response repeats at 64x multiples of the modulator frequency  $f_{\text{MOD}}$ , as shown in [Figure 57](#).



**Figure 54. Frequency Response For High-Speed, Low-Power, And Low-Speed Modes**



**Figure 55. Passband Response For High-Speed, Low-Power, And Low-Speed Modes**

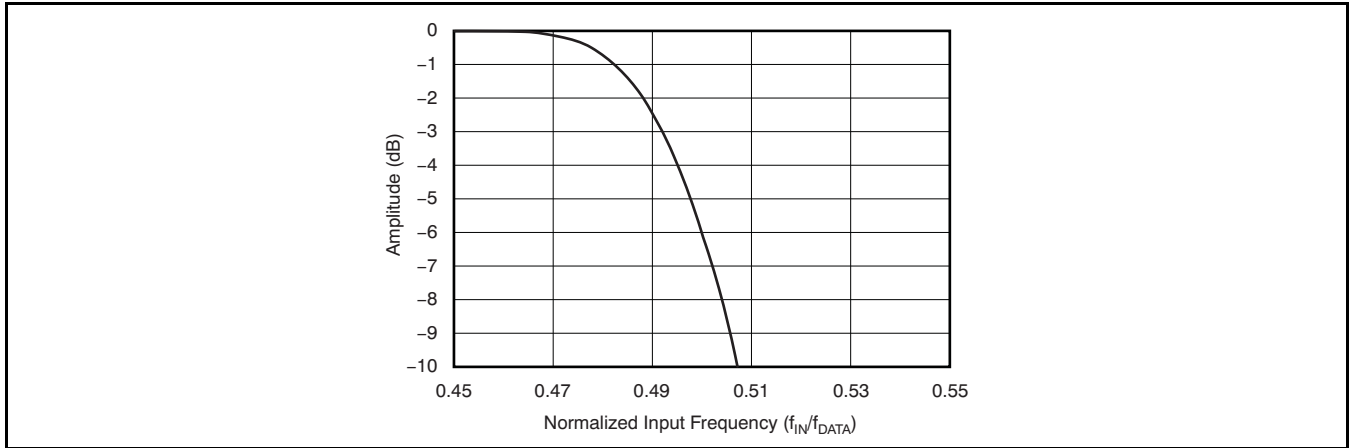


Figure 56. Transition Band Response For High-Speed, Low-Power, and Low-Speed Modes

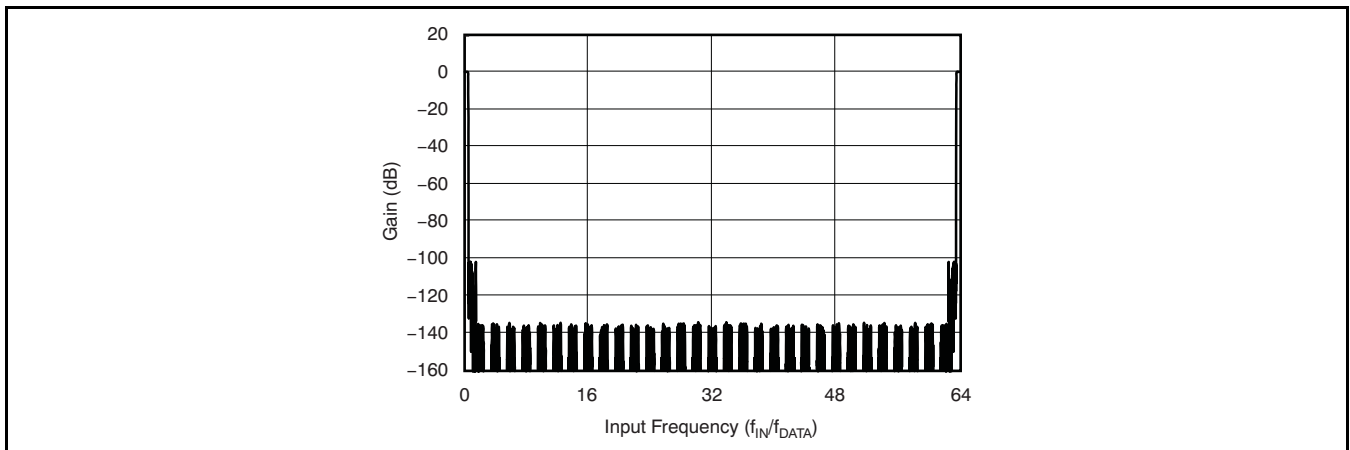


Figure 57. Frequency Response Out To  $F_{MOD}$  For High-Speed, Low-Power, And Low-Speed Modes

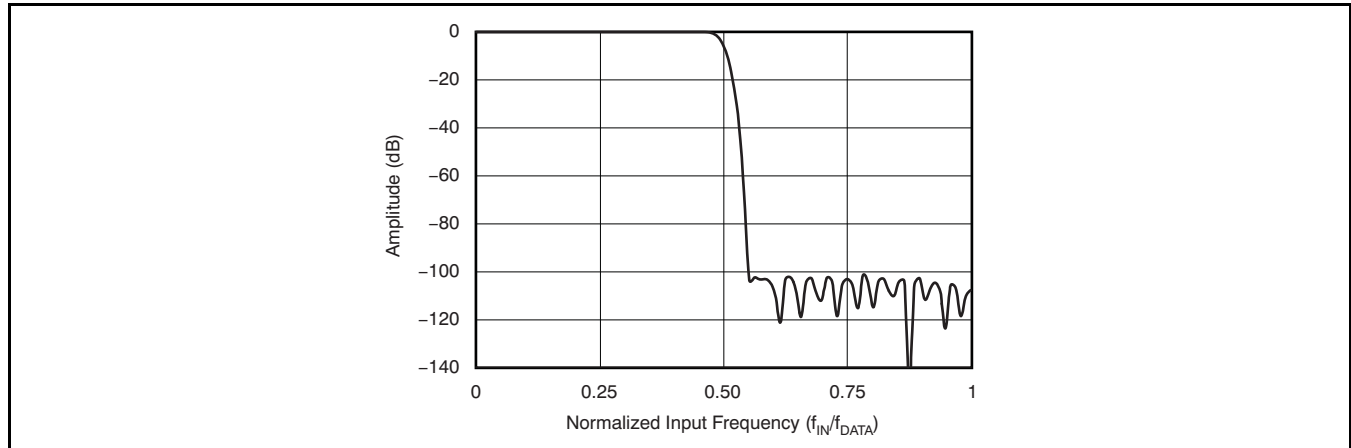
These image frequencies, if present in the signal and not externally filtered, will fold back (or alias) into the passband, causing errors. The stop band of the ADS1278-SP provides 100-dB attenuation of frequencies that begin just beyond the passband and continue out to  $f_{MOD}$ . Placing an anti-aliasing, low-pass filter in front of the ADS1278-SP inputs is recommended to limit possible high-amplitude, out-of-band signals and noise. Often, a simple RC filter is sufficient. Table 2 lists the image rejection versus external filter order.

Table 2. Antialiasing Filter Order Image Rejection

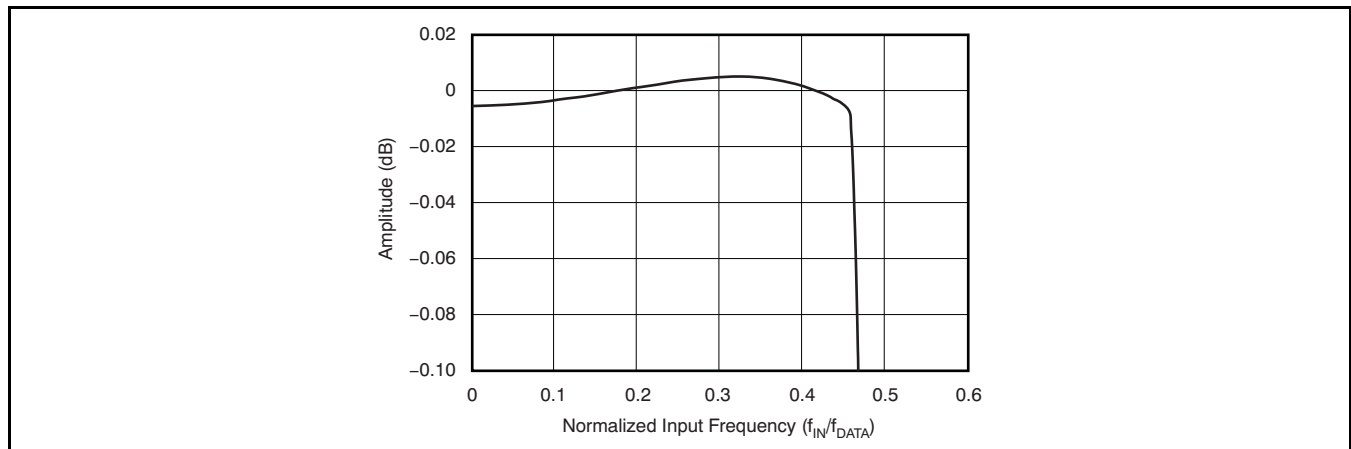
ANTIALIASING FILTER ORDER	IMAGE REJECTION (dB) ( $f_{-3dB}$ at $f_{DATA}$ )	
	HS, LP, LS	HR
1	39	45
2	75	87
3	111	129

### 8.3.2.2 High-Resolution Mode

The oversampling ratio is 128 in High-Resolution mode. [Figure 58](#) shows the frequency response in High-Resolution mode normalized to  $f_{\text{DATA}}$ . [Figure 59](#) shows the passband ripple, and the transition from passband to stop band is shown in [Figure 60](#). The overall frequency response repeats at multiples of the modulator frequency  $f_{\text{MOD}}$  ( $128 \times f_{\text{DATA}}$ ), as shown in [Figure 61](#). The stop band of the ADS1278-SP provides 100-dB attenuation of frequencies that begin just beyond the passband and continue out to  $f_{\text{MOD}}$ . Placing an antialiasing, low-pass filter in front of the ADS1278-SP inputs is recommended to limit possible high-amplitude out-of-band signals and noise. Often, a simple RC filter is sufficient. [Table 2](#) lists the image rejection versus external filter order.



**Figure 58. Frequency Response For High-Resolution Mode**



**Figure 59. Passband Response For High-Resolution Mode**

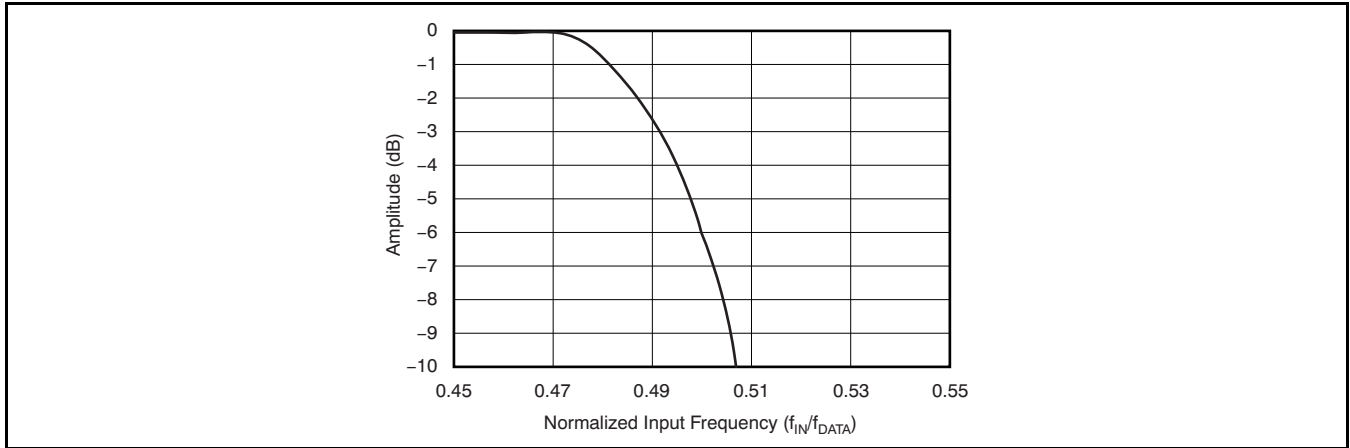


Figure 60. Transition Band Response For High-Resolution Mode

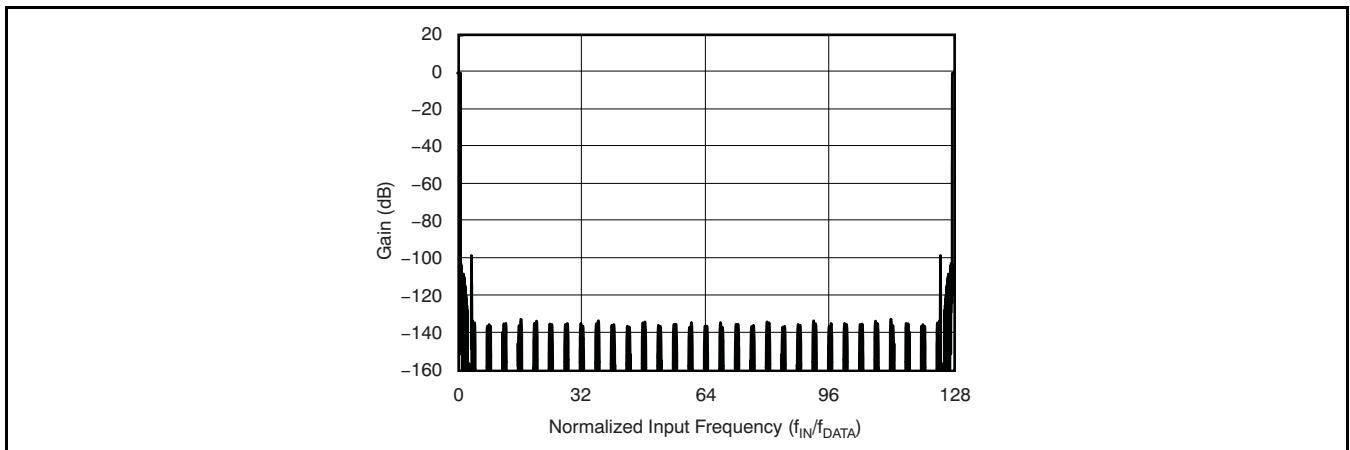


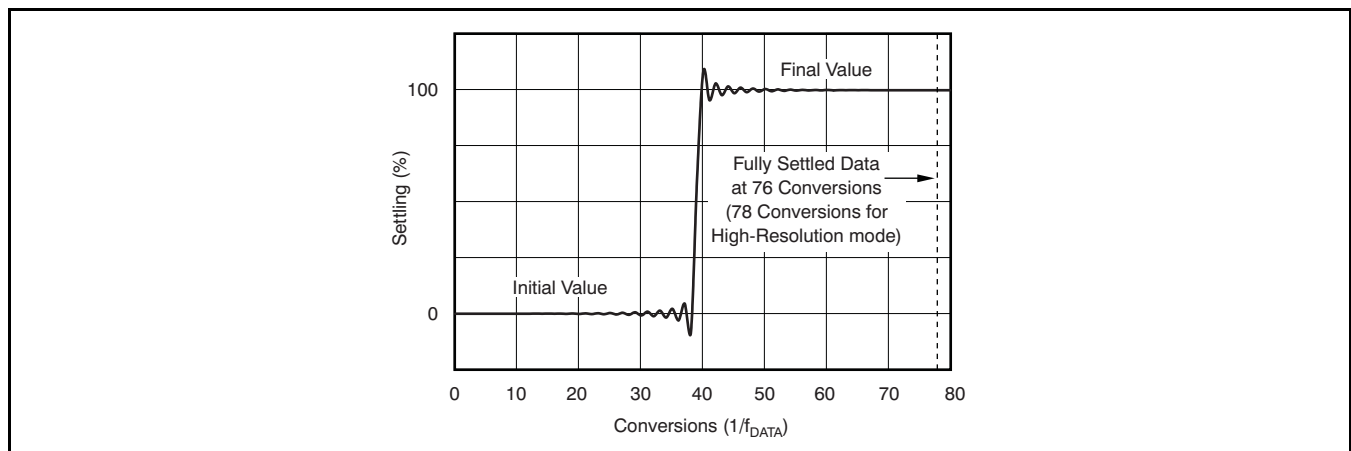
Figure 61. Frequency Response Out To  $F_{MOD}$  For High-Resolution Mode

### 8.3.3 Phase Response

The ADS1278-SP incorporates a multiple stage, linear phase digital filter. Linear phase filters exhibit constant delay time versus input frequency (constant group delay). This characteristic means the time delay from any instant of the input signal to the same instant of the output data is constant and is independent of input signal frequency. This behavior results in essentially zero phase errors when analyzing multi-tone signals.

### 8.3.4 Settling Time

As with frequency and phase response, the digital filter also determines settling time. [Figure 62](#) shows the output settling behavior after a step change on the analog inputs normalized to conversion periods. The X-axis is given in units of conversion. Note that after the step change on the input occurs, the output data change very little prior to 30 conversion periods. The output data are fully settled after 76 conversion periods for High-Speed and Low-Power modes, and 78 conversion periods for High-Resolution mode.



**Figure 62. Step Response**

### 8.3.5 Data Format

The ADS1278-SP outputs 24 bits of data in twos complement format.

A positive full-scale input produces an ideal output code of 7FFFFFFh, and the negative full-scale input produces an ideal output code of 800000h. The output clips at these codes for signals exceeding full-scale. [Table 3](#) summarizes the ideal output codes for different input signals.

**Table 3. Ideal Output Code Versus Input Signal**

INPUT SIGNAL $V_{IN}$ ( $A_{INP} - A_{INN}$ )	IDEAL OUTPUT CODE <sup>(1)</sup>
$\geq +V_{REF}$	7FFFFFFh
$\frac{+V_{REF}}{2^{23} - 1}$	000001h
0	000000h
$\frac{-V_{REF}}{2^{23} - 1}$	FFFFFFh
$\leq -V_{REF} \left( \frac{2^{23}}{2^{23} - 1} \right)$	800000h

(1) Excludes effects of noise, INL, offset, and gain errors.

### 8.3.6 Analog Inputs (AINP, AINN)

The ADS1278-SP measures each differential input signal  $V_{IN} = (AINP - AINN)$  against the common differential reference  $V_{REF} = (VREFP - VREFN)$ . The most positive measurable differential input is  $+V_{REF}$ , which produces the most positive digital output code of 7FFFFFFh. Likewise, the most negative measurable differential input is  $-V_{REF}$ , which produces the most negative digital output code of 800000h.

For optimum performance, the inputs of the ADS1278-SP are intended to be driven differentially. For single-ended applications, one of the inputs (AINP or AINN) can be driven while the other input is fixed (typically to AGND or 2.5 V). Fixing the input to 2.5 V permits bipolar operation, thereby allowing full use of the entire converter range.

While the ADS1278-SP measures the differential input signal, the absolute input voltage is also important. This value is the voltage on either input (AINP or AINN) with respect to AGND. The range for this voltage is:

$$-0.1 \text{ V} < (\text{AINN or AINP}) < \text{AVDD} + 0.1 \text{ V}$$

If either input is taken below  $-0.4 \text{ V}$  or above  $(\text{AVDD} + 0.4 \text{ V})$ , ESD protection diodes on the inputs may turn on. If these conditions are possible, external Schottky clamp diodes or series resistors may be required to limit the input current to safe values (see the [Absolute Maximum Ratings](#) table).

The ADS1278-SP is a very high-performance ADC. For optimum performance, it is critical that the appropriate circuitry be used to drive the ADS1278-SP inputs. See the [Application Information](#) section for several recommended circuits.

The ADS1278-SP uses switched-capacitor circuitry to measure the input voltage. Internal capacitors are charged by the inputs and then discharged. Figure 63 shows a conceptual diagram of these circuits. Switch  $S_2$  represents the net effect of the modulator circuitry in discharging the sampling capacitor; the actual implementation is different. The timing for switches  $S_1$  and  $S_2$  is shown in Figure 64. The sampling time ( $t_{SAMPLE}$ ) is the inverse of modulator sampling frequency ( $f_{MOD}$ ) and is a function of the mode, the CLKDIV input, and CLK frequency, as shown in Table 4.

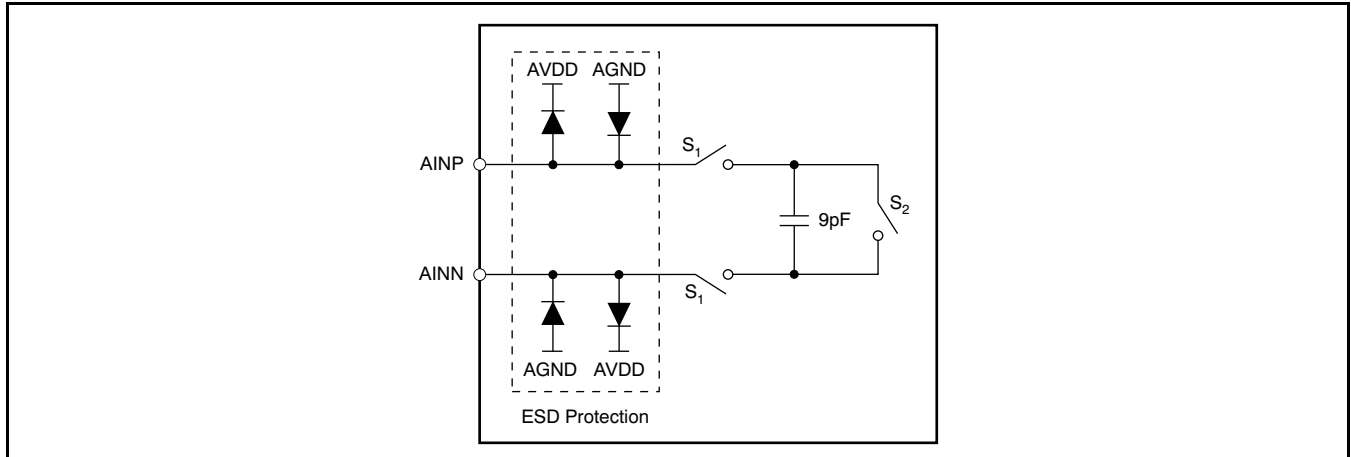


Figure 63. Equivalent Analog Input Circuitry

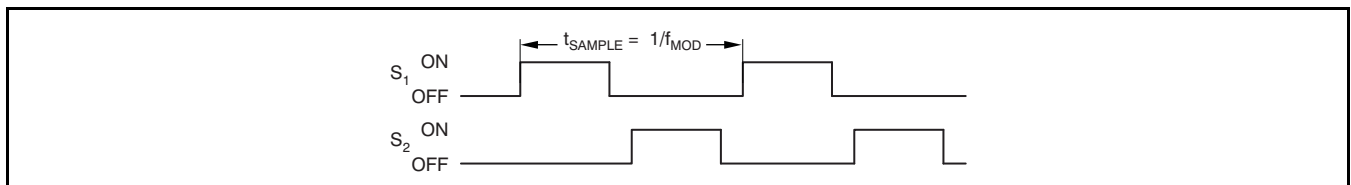


Figure 64.  $S_1$  and  $S_2$  Switch Timing for Figure 63

Table 4. Modulator Frequency ( $F_{MOD}$ ) Mode Selection

MODE SELECTION	CLKDIV	$f_{MOD}$
High-Speed	1	$f_{CLK} / 4$
High-Resolution	1	$f_{CLK} / 4$
Low-Power	1	$f_{CLK} / 8$
	0	$f_{CLK} / 4$
Low-Speed	1	$f_{CLK} / 40$
	0	$f_{CLK} / 8$

The average load presented by the switched capacitor input can be modeled with an effective differential impedance, as shown in Figure 65. Note that the effective impedance is a function of  $f_{MOD}$ .

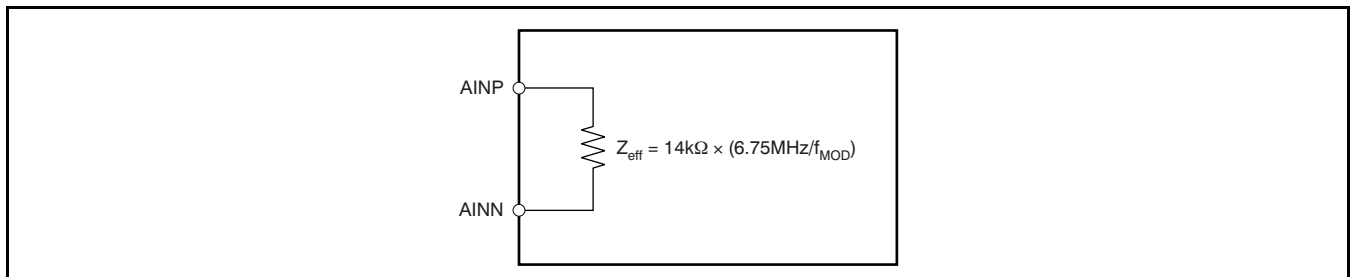


Figure 65. Effective Input Impedances

### 8.3.7 Voltage Reference Inputs (VREFP, VREFN)

The voltage reference for the ADS1278-SP ADC is the differential voltage between VREFP and VREFN:  $V_{REF} = (VREFP - VREFN)$ . The voltage reference is common to all channels. The reference inputs use a structure similar to that of the analog inputs with the equivalent circuitry on the reference inputs shown in Figure 66. As with the analog inputs, the load presented by the switched capacitor can be modeled with an effective impedance, as shown in Figure 67. However, the reference input impedance depends on the number of active (enabled) channels in addition to  $f_{MOD}$ . As a result of the change of reference input impedance caused by enabling and disabling channels, the regulation and setting time of the external reference should be noted, so as not to affect the readings.

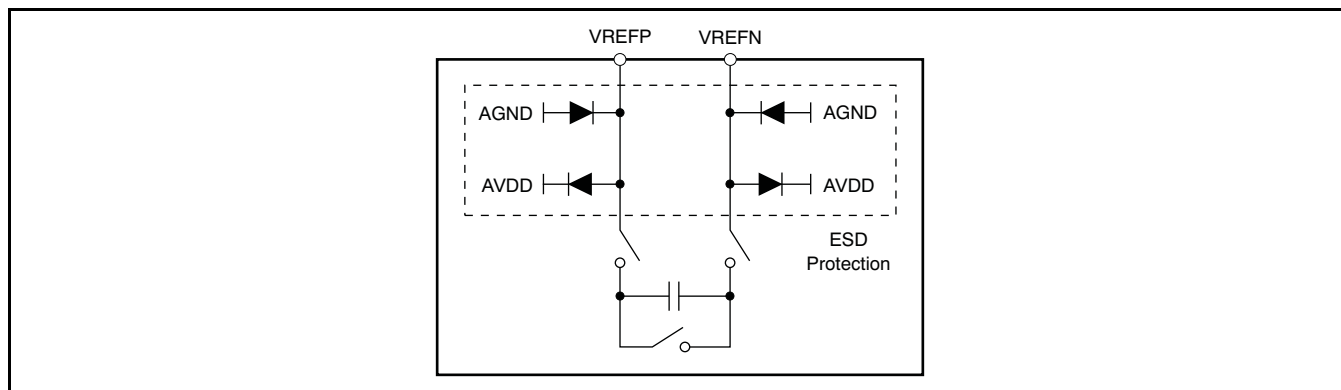


Figure 66. Equivalent Reference Input Circuitry

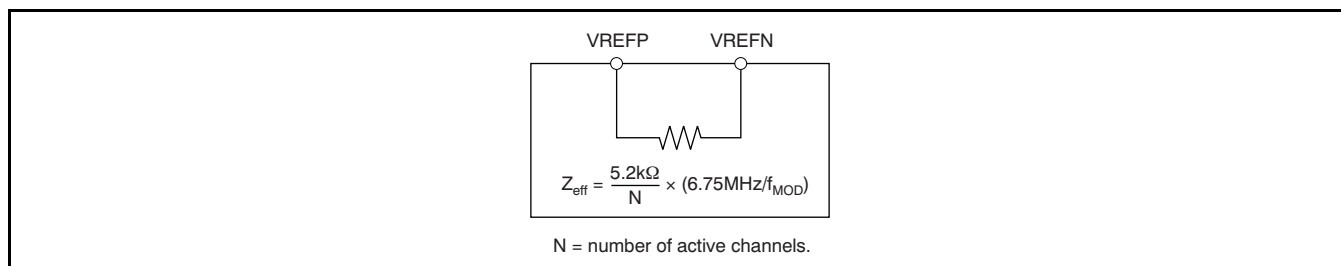


Figure 67. Effective Reference Impedance

ESD diodes protect the reference inputs. To keep these diodes from turning on, make sure the voltages on the reference pins do not go below AGND by more than 0.4 V, and likewise do not exceed AVDD by 0.4 V. If these conditions are possible, external Schottky clamp diodes or series resistors may be required to limit the input current to safe values (see the [Absolute Maximum Ratings](#) table).

Note that the valid operating range of the reference inputs is limited to the following parameters:

$$-0.1 \text{ V} \leq VREFN \leq +0.1 \text{ V}$$

$$VREFN + 0.5 \text{ V} \leq VREFP \leq AVDD + 0.1 \text{ V}$$

### 8.3.8 Clock Input (CLK)

The ADS1278-SP requires a clock input for operation. The individual converters of the ADS1278-SP operate from the same clock input. At the maximum data rate, the clock input can be either 27 MHz or 13.5 MHz for Low-Power mode, or 27MHz or 5.4 MHz for Low-Speed mode, determined by the setting of the CLKDIV input. For High-Speed mode, the maximum CLK input frequency is 32.768 MHz. For High-Resolution mode, the maximum CLK input frequency is 27 MHz. The selection of the external clock frequency ( $f_{CLK}$ ) does not affect the resolution of the ADS1278-SP. Use of a slower  $f_{CLK}$  can reduce the power consumption of an external clock buffer. The output data rate scales with clock frequency, down to a minimum clock frequency of  $f_{CLK} = 100 \text{ kHz}$ . Table 5 summarizes the ratio of the clock input frequency ( $f_{CLK}$ ) to data rate ( $f_{DATA}$ ), maximum data rate and corresponding maximum clock input for the four operating modes.

As with any high-speed data converter, a high-quality, low-jitter clock is essential for optimum performance. Crystal clock oscillators are the recommended clock source. Make sure to avoid excess ringing on the clock input; keeping the clock trace as short as possible, and using a 50-Ω series resistor placed close to the source end, often helps.

**Table 5. Clock Input Options**

MODE SELECTION	MAX $f_{CLK}$ (MHz)	CLKDIV	$f_{CLK}/f_{DATA}$	DATA RATE (SPS)
High-Speed	32.768	1	256	128,000
High-Resolution	27	1	512	52,734
Low-Power	27	1	512	52,734
	13.5	0	256	
Low-Speed	27	1	2,560	10,547
	5.4	0	512	

### 8.3.9 Mode Selection (MODE)

The ADS1278-SP supports four modes of operation: High-Speed, High-Resolution, Low-Power, and Low-Speed. The modes offer optimization of speed, resolution, and power. Mode selection is determined by the status of the digital input MODE[1:0] pins, as shown in [Table 6](#). The ADS1278-SP continually monitors the status of the MODE pin during operation.

**Table 6. Mode Selection**

MODE[1:0]	MODE SELECTION	MAX $f_{DATA}$ <sup>(1)</sup>
00	High-Speed	128,000
01	High-Resolution	52,734
10	Low-Power	52,734
11	Low-Speed	10,547

(1)  $f_{CLK}$  = 27-MHz max (32.768-MHz max in High-Speed mode).

When using the SPI protocol,  $\overline{DRDY}$  is held high after a mode change occurs until settled (or valid) data are ready; see [Figure 68](#) and [Table 7](#).

In Frame-Sync protocol, the DOUT pins are held low after a mode change occurs until settled data are ready; see [Figure 68](#) and [Table 7](#). Data can be read from the device to detect when DOUT changes to logic 1, indicating that the data are valid.

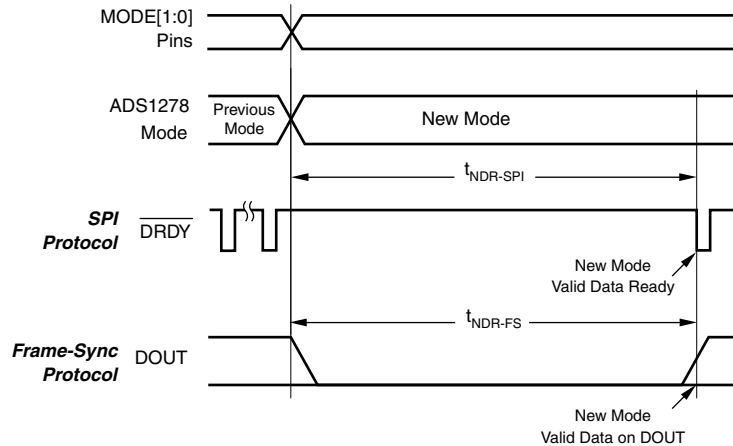


Figure 68. Mode Change Timing

Table 7. New Data After Mode Change

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{\text{NDR-SPI}}$	Time for new data to be ready (SPI)			129	Conversions ( $1/f_{\text{DATA}}$ )
$t_{\text{NDR-FS}}$	Time for new data to be ready (Frame-Sync)	127		128	Conversions ( $1/f_{\text{DATA}}$ )

### 8.3.10 Synchronization ( $\overline{\text{SYNC}}$ )

The ADS1278-SP can be synchronized by pulsing the  $\overline{\text{SYNC}}$  pin low and then returning the pin high. When the pin goes low, the conversion process stops, and the internal counters used by the digital filter are reset. When the  $\overline{\text{SYNC}}$  pin returns high, the conversion process restarts. Synchronization allows the conversion to be aligned with an external event, such as the changing of an external multiplexer on the analog inputs, or by a reference timing pulse.

Because the ADS1278-SP converters operate in parallel from the same master clock and use the same  $\overline{\text{SYNC}}$  input control, they are always in synchronization with each other. The aperture match among internal channels is typically less than 500 ps. However, the synchronization of multiple devices is somewhat different. At device power-on, variations in internal reset thresholds from device to device may result in uncertainty in conversion timing.

The  $\overline{\text{SYNC}}$  pin can be used to synchronize multiple devices to within the same CLK cycle. Figure 69 illustrates the timing requirement of  $\overline{\text{SYNC}}$  and CLK in SPI format.

See Figure 70 for the Frame-Sync format timing requirement.

After synchronization, indication of valid data depends on whether SPI or Frame-Sync format was used.

In the SPI format,  $\overline{\text{DRDY}}$  goes high as soon as  $\overline{\text{SYNC}}$  is taken low; see Figure 69. After  $\overline{\text{SYNC}}$  is returned high,  $\overline{\text{DRDY}}$  stays high while the digital filter is settling. Once valid data are ready for retrieval,  $\overline{\text{DRDY}}$  goes low.

In the Frame-Sync format, DOUT goes low as soon as  $\overline{\text{SYNC}}$  is taken low; see Figure 70. After  $\overline{\text{SYNC}}$  is returned high, DOUT stays low while the digital filter is settling. Once valid data are ready for retrieval, DOUT begins to output valid data. For proper synchronization, FSYNC, SCLK, and CLK must be established before taking  $\overline{\text{SYNC}}$  high, and must then remain running. If the clock inputs (CLK, FSYNC or SCLK) are subsequently interrupted or reset, re-assert the  $\overline{\text{SYNC}}$  pin.

For consistent performance, re-assert  $\overline{\text{SYNC}}$  after device power-on when data first appear.

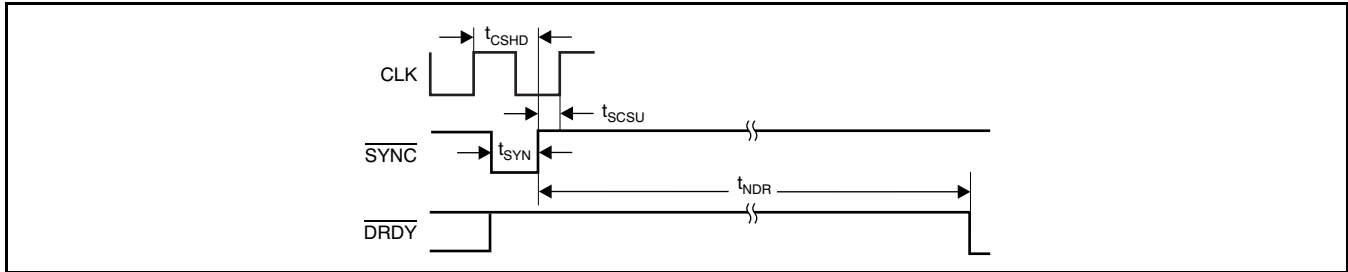


Figure 69. Synchronization Timing (SPI Protocol)

Table 8. SPI Protocol

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{CSHD}$	CLK to $\overline{SYNC}$ hold time	10			ns
$t_{SCSU}$	$\overline{SYNC}$ to CLK setup time	5			ns
$t_{SYN}$	Synchronize pulse width	1			CLK periods
$t_{NDR}$	Time for new data to be ready			129	Conversions ( $1/f_{DATA}$ )

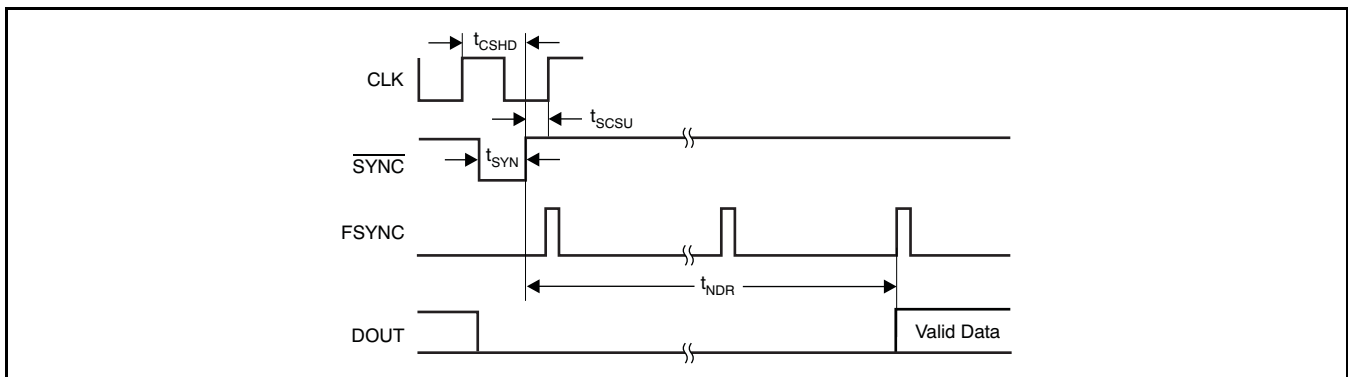


Figure 70. Synchronization Timing (Frame-Sync Protocol)

Table 9. Frame-Sync Protocol

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{CSHD}$	CLK to $\overline{SYNC}$ hold time	10			ns
$t_{SCSU}$	$\overline{SYNC}$ to CLK setup time	5			ns
$t_{SYN}$	Synchronize pulse width	1			CLK periods
$t_{NDR}$	Time for new data to be ready	127		128	Conversions ( $1/f_{DATA}$ )

### 8.3.11 Power-Down ( $\overline{\text{PWDN}}$ )

The channels of the ADS1278-SP can be independently powered down by use of the  $\overline{\text{PWDN}}$  inputs. To enter the power-down mode, hold the respective  $\overline{\text{PWDN}}$  pin low for at least two CLK cycles. To exit power-down, return the corresponding  $\overline{\text{PWDN}}$  pin high. Note that when all channels are powered down, the ADS1278-SP enters a microwatt ( $\mu\text{W}$ ) power state where all internal biasing is disabled. In this state, the TEST[1:0] input pins must be driven; all other input pins can float. The ADS1278-SP outputs remain driven.

As shown in [Figure 71](#) and [Table 10](#), a maximum of 130 conversion cycles must elapse for SPI interface, and 129 conversion cycles must elapse for Frame-Sync, before reading data after exiting power-down. Data from channels already running are not affected. The user software can perform the required delay time in any of the following ways:

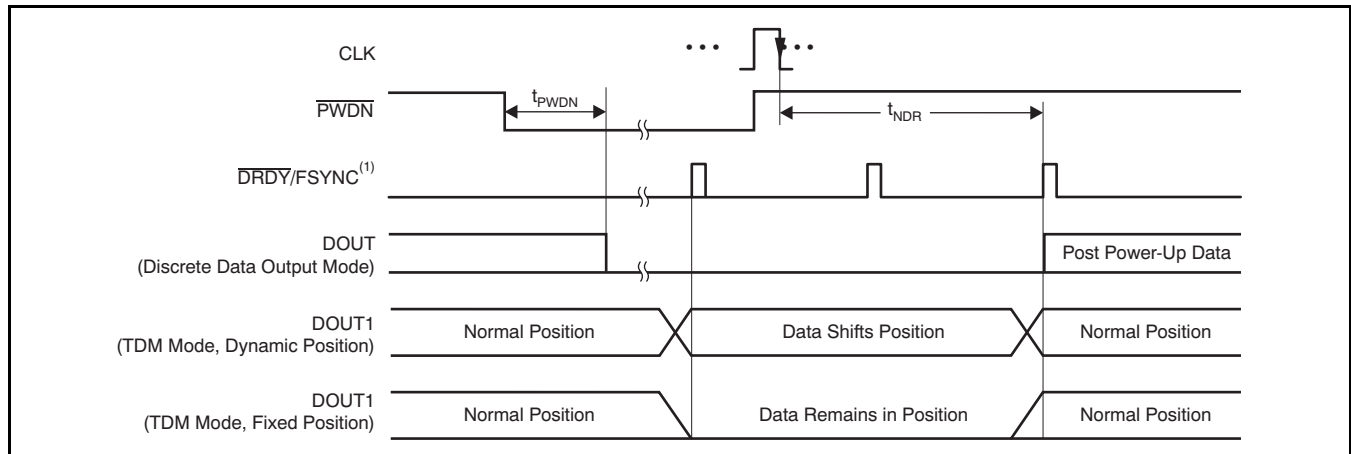
1. Count the number of data conversions after taking the  $\overline{\text{PWDN}}$  pin high.
2. Delay  $129/f_{\text{DATA}}$  or  $130/f_{\text{DATA}}$  after taking the  $\overline{\text{PWDN}}$  pins high, then read data.

### 3. Detect for non-zero data in the powered-up channel.

After powering up one or more channels, the channels are synchronized to each other. It is not necessary to use the SYNC pin to synchronize them.

When a channel is powered down in TDM data format, the data for that channel are either forced to zero (fixed-position TDM data mode) or replaced by shifting the data from the next channel into the vacated data position (dynamic-position TDM data mode).

In Discrete data format, the data are always forced to zero. When powering-up a channel in dynamic-position TDM data format mode, the channel data remain packed until the data are ready, at which time the data frame is expanded to include the just-powered channel data. See the [Data Format](#) section for details.



**Figure 71. Power-Down Timing**

**Table 10. Power-Down Timing**

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{PVDN}$	PWDN pulse width to enter Power-Down mode	2			CLK periods
$t_{NDR}$	Time for new data ready (SPI)	129		130	Conversions ( $1/f_{DATA}$ )
$t_{NDR}$	Time for new data ready (Frame-Sync)	128		129	Conversions ( $1/f_{DATA}$ )

### 8.3.12 Format[2:0]

Data can be read from the ADS1278-SP with two interface protocols (SPI or Frame-Sync) and several options of data formats (TDM/Discrete and Fixed/Dynamic data positions). The FORMAT[2:0] inputs are used to select among the options. Table 11 lists the available options. See the *DOUT Modes* section for details of the DOUT Mode and Data Position.

Table 11. Data Output Format

FORMAT[2:0]	INTERFACE PROTOCOL	DOUT MODE	DATA POSITION
000	SPI	TDM	Dynamic
001	SPI	TDM	Fixed
010	SPI	Discrete	—
011	Frame-Sync	TDM	Dynamic
100	Frame-Sync	TDM	Fixed
101	Frame-Sync	Discrete	—
110	Modulator Mode	—	—

### 8.3.13 Serial Interface Protocols

Data are retrieved from the ADS1278-SP using the serial interface. Two protocols are available: SPI and Frame-Sync. The same pins are used for both interfaces: SCLK,  $\overline{\text{DRDY}}$ /FSYNC, DOUT[8:1], and DIN. The FORMAT[2:0] pins select the desired interface protocol.

#### 8.3.14 SPI Serial Interface

The SPI-compatible format is a read-only interface. Data ready for retrieval are indicated by the falling  $\overline{\text{DRDY}}$  output and are shifted out on the falling edge of SCLK, MSB first. The interface can be daisy-chained using the DIN input when using multiple devices. See the *Daisy-Chaining* section for more information.

NOTE: The SPI format is limited to a CLK input frequency of 27 MHz, maximum. For CLK input operation above 27 MHz (High-Speed mode only), use Frame-Sync format.

##### 8.3.14.1 SCLK

The serial clock (SCLK) features a Schmitt-triggered input and shifts out data on DOUT on the falling edge. It also shifts in data on the falling edge on DIN when this pin is being used for daisy-chaining. The device shifts data out on the falling edge and the user normally shifts this data in on the rising edge.

Even though the SCLK input has hysteresis, it is recommended to keep SCLK as clean as possible to prevent glitches from accidentally shifting the data.

SCLK may be run as fast as the CLK frequency. SCLK may be either in free-running or stop-clock operation between conversions. Note that one  $f_{\text{CLK}}$  is required after the falling edge of  $\overline{\text{DRDY}}$  until the first rising edge of SCLK. For best performance, limit  $f_{\text{SCLK}} / f_{\text{CLK}}$  to ratios of 1, 1/2, 1/4, 1/8, etc. When the device is configured for modulator output, SCLK becomes the modulator clock output (see the *Modulator Output* section).

##### 8.3.14.2 $\overline{\text{DRDY}}$ /FSYNC (SPI Format)

In the SPI format, this pin functions as the  $\overline{\text{DRDY}}$  output. It goes low when data are ready for retrieval and then returns high on the falling edge of the first subsequent SCLK. If data are not retrieved (that is, SCLK is held low),  $\overline{\text{DRDY}}$  pulses high just before the next conversion data are ready, as shown in Figure 72. The new data are loaded within one CLK cycle before  $\overline{\text{DRDY}}$  goes low. All data must be shifted out before this time to avoid being overwritten.

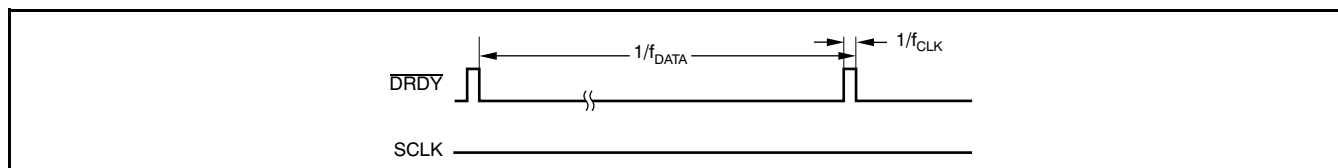


Figure 72.  $\overline{\text{DRDY}}$  Timing With No Readback

### 8.3.14.3 DOUT

The conversion data are output on DOUT[8:1]. The MSB data are valid on DOUT[8:1] after  $\overline{\text{DRDY}}$  goes low. Subsequent bits are shifted out with each falling edge of SCLK. If daisy-chaining, the data shifted in using DIN appear on DOUT after all channel data have been shifted out. When the device is configured for modulator output, DOUT[8:1] becomes the modulator data output for each channel (see the [Modulator Output](#) section).

### 8.3.14.4 DIN

This input is used when multiple ADS1278-SPs are to be daisy-chained together. The DOUT1 pin of the first device connects to the DIN pin of the next, etc. It can be used with either the SPI or Frame-Sync formats. Data are shifted in on the falling edge of SCLK. When using only one ADS1278-SP, tie DIN low. See the [Daisy-Chaining](#) section for more information.

### 8.3.15 Frame-Sync Serial Interface

Frame-Sync format is similar to the interface often used on audio ADCs. It operates in slave fashion—the user must supply framing signal FSYNC (similar to the *left/right clock* on stereo audio ADCs) and the serial clock SCLK (similar to the *bit clock* on audio ADCs). The data are output MSB first or *left-justified* on the rising edge of FSYNC. When using Frame-Sync format, the FSYNC and SCLK inputs must be continuously running with the relationships shown in the [Timing Requirements: Frame-Sync Format](#) table.

#### 8.3.15.1 SCLK

The serial clock (SCLK) features a Schmitt-triggered input and shifts out data on DOUT on the falling edge. It also shifts in data on the falling edge on DIN when this pin is being used for daisy-chaining. Even though SCLK has hysteresis, it is recommended to keep SCLK as clean as possible to prevent glitches from accidentally shifting the data. When using Frame-Sync format, SCLK must run continuously. If it is shut down, the data readback will be corrupted. The number of SCLKs within a frame period (FSYNC clock) can be any power-of-2 ratio of CLK cycles (1, 1/2, 1/4, etc), as long as the number of cycles is sufficient to shift the data output from all channels within one frame. When the device is configured for modulator output, SCLK becomes the modulator clock output (see the [Modulator Output](#) section).

#### 8.3.15.2 $\overline{DRDY}$ /FSYNC (Frame-Sync Format)

In Frame-Sync format, this pin is used as the FSYNC input. The frame-sync input (FSYNC) sets the frame period, which must be the same as the data rate. The required number of  $f_{CLK}$  cycles to each FSYNC period depends on the mode selection and the CLKDIV input. [Table 5](#) indicates the number of CLK cycles to each frame ( $f_{CLK}/f_{DATA}$ ). If the FSYNC period is not the proper value, data readback will be corrupted.

#### 8.3.15.3 DOUT

The conversion data are shifted out on DOUT[8:1]. The MSB data become valid on DOUT[8:1] after FSYNC goes high. The subsequent bits are shifted out with each falling edge of SCLK. If daisy-chaining, the data shifted in using DIN appear on DOUT[8:1] after all channel data have been shifted out. When the device is configured for modulator output, DOUT becomes the modulator data output (see the [Modulator Output](#) section).

#### 8.3.15.4 DIN

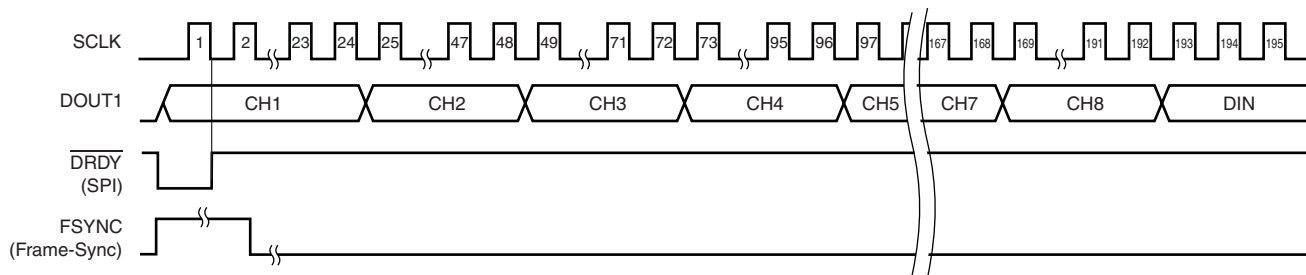
This input is used when multiple ADS1278-SPs are to be daisy-chained together. It can be used with either SPI or Frame-Sync formats. Data are shifted in on the falling edge of SCLK. When using only one ADS1278-SP, tie DIN low. See the [Daisy-Chaining](#) section for more information.

### 8.3.16 DOUT Modes

For both SPI and Frame-Sync interface protocols, the data are shifted out either through individual channel DOUT pins, in a parallel data format (Discrete mode), or the data for all channels are shifted out, in a serial format, through a common pin, DOUT1 (TDM mode).

#### 8.3.16.1 TDM Mode

In TDM (time-division multiplexed) data output mode, the data for all channels are shifted out, in sequence, on a single pin (DOUT1). As shown in [Figure 73](#), the data from channel 1 are shifted out first, followed by channel 2 data, etc. After the data from the last channel are shifted out, the data from the DIN input follow. The DIN is used to daisy-chain the data output from an additional ADS1278-SP or other compatible device. Note that when all channels of the ADS1278-SP are disabled, the interface is disabled, rendering the DIN input disabled as well. When one or more channels of the device are powered down, the data format of the TDM mode can be fixed or dynamic.


**Figure 73. TDM Mode (All Channels Enabled)**

### 8.3.16.2 TDM Mode, Fixed-Position Data

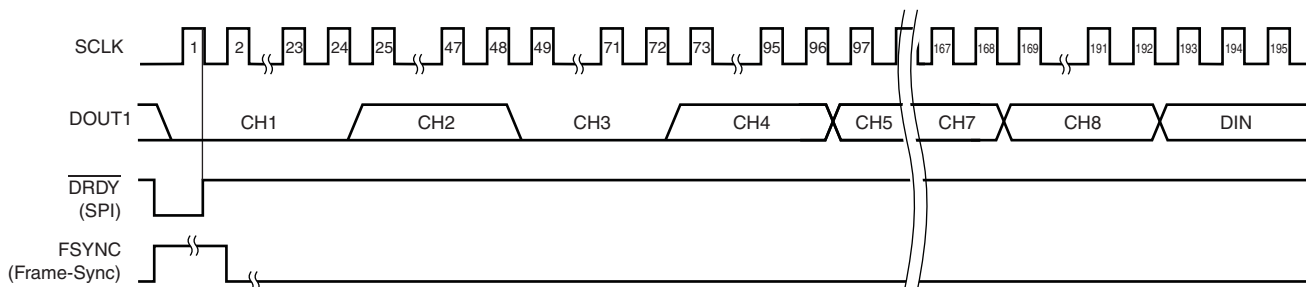
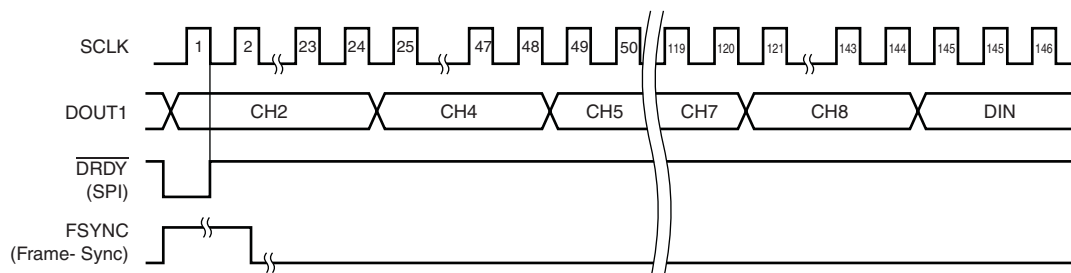
In this TDM data output mode, the data position of the channels remain fixed, regardless of whether the channels are powered down. If a channel is powered down, the data are forced to zero but occupy the same position within the data stream. [Figure 74](#) shows the data stream with channel 1 and channel 3 powered down.

### 8.3.16.3 TDM Mode, Dynamic Position Data

In this TDM data output mode, when a channel is powered down, the data from higher channels shift one position in the data stream to fill the vacated data slot. [Figure 75](#) shows the data stream with channel 1 and channel 3 powered down.

### 8.3.16.4 Discrete Data Output Mode

In Discrete data output mode, the channel data are shifted out in parallel using individual channel data output pins DOUT[8:1]. After the 24th SCLK, the channel data are forced to zero. The data are also forced to zero for powered down channels. [Figure 76](#) shows the discrete data output format.


**Figure 74. TDM Mode, Fixed-Position Data (Channels 1 And 3 Shown Powered Down)**

**Figure 75. TDM Mode, Dynamic Position Data (Channels 1 And 3 Shown Powered Down)**

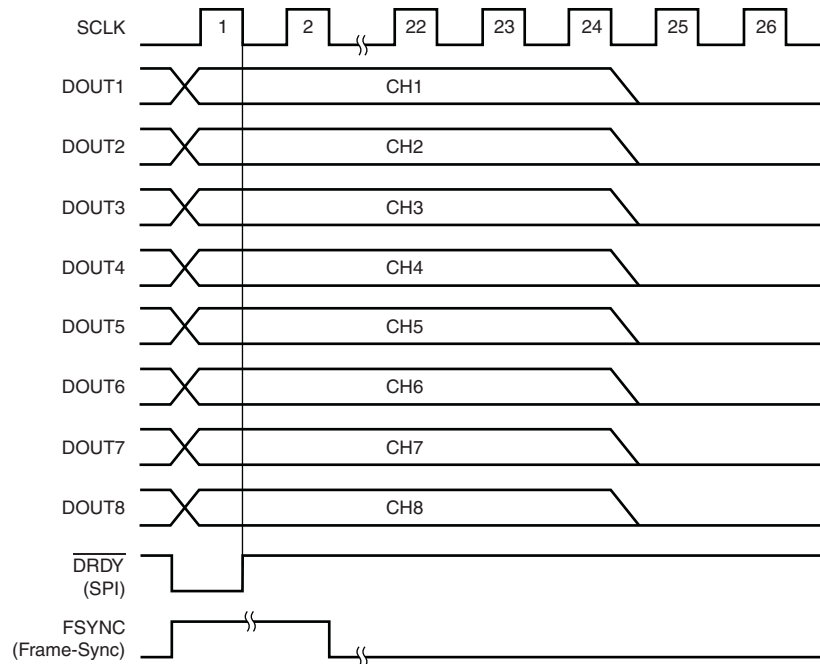


Figure 76. Discrete Data Output Mode

### 8.3.17 Daisy-Chaining

Multiple ADS1278-SPs can be daisy-chained together to output data on a single pin. The DOUT1 data output pin of one device is connected to the DIN of the next device. As shown in Figure 77, the DOUT1 pin of device 1 provides the output data to a controller, and the DIN of device 2 is grounded. Figure 78 shows the data format when reading back data.

The maximum number of channels that may be daisy-chained in this way is limited by the frequency of  $f_{SCLK}$ , the mode selection, and the CLKDIV input. The frequency of  $f_{SCLK}$  must be high enough to completely shift the data out from all channels within one  $f_{DATA}$  period. Table 12 lists the maximum number of daisy-chained channels when  $f_{SCLK} = f_{CLK}$ .

To increase the number of data channels possible in a chain, a segmented DOUT scheme may be used, producing two data streams. Figure 79 illustrates four ADS1278-SPs, with pairs of ADS1278-SPs daisy-chained together. The channel data of each daisy-chained pair are shifted out in parallel and received by the processor through independent data channels.

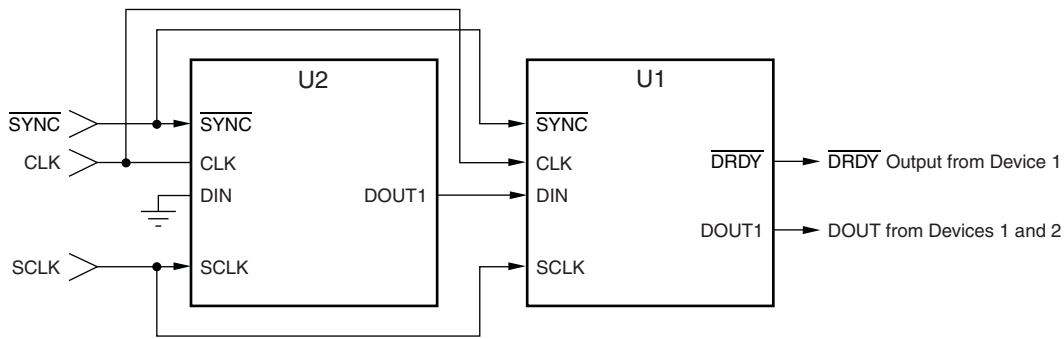
Table 12. Maximum Channels In A Daisy-Chain ( $F_{SCLK} = F_{CLK}$ )

MODE SELECTION	CLKDIV	MAXIMUM NUMBER OF CHANNELS
High-Speed	1	10
High-Resolution	1	21
Low-Power	1	21
	0	10
Low-Speed	1	106
	0	21

Whether the interface protocol is SPI or Frame-Sync, it is recommended to synchronize all devices by tying the SYNC inputs together. When synchronized in SPI protocol, it is only necessary to monitor the DRDY output of one ADS1278-SP.

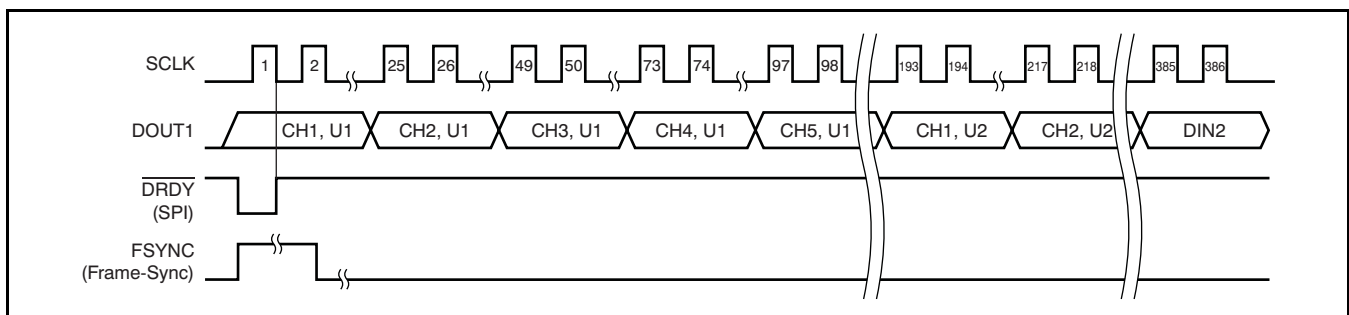
In Frame-Sync interface protocol, the data from all devices are ready after the rising edge of FSYNC.

Since DOUT1 and DIN are both shifted on the falling edge of SCLK, the propagation delay on DOUT1 creates a setup time on DIN. Minimize the skew in SCLK to avoid timing violations.

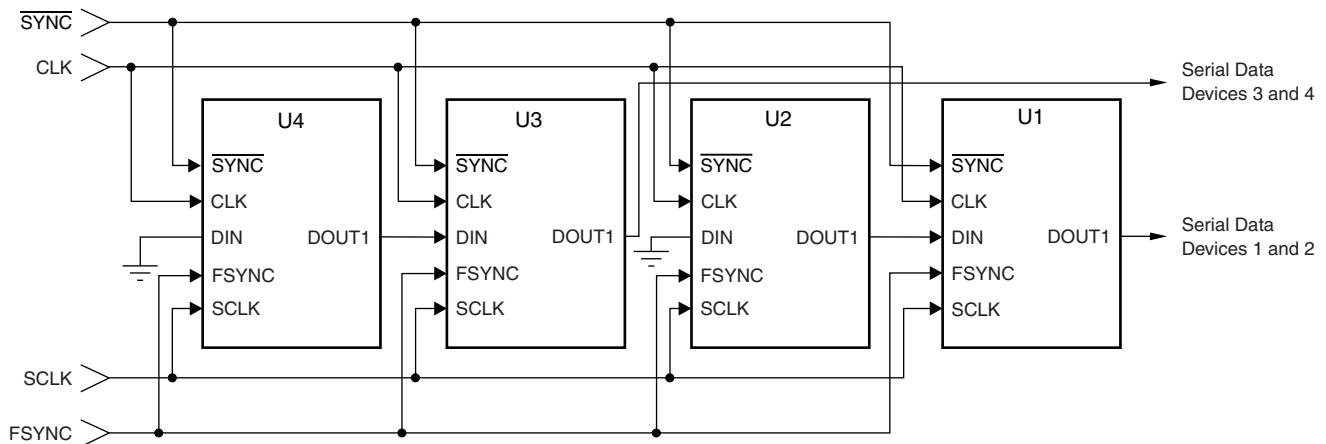


Note: The number of chained devices is limited by the SCLK rate and device mode.

**Figure 77. Daisy-Chaining of Two Devices, SPI Protocol (Format[2:0] = 000 or 001)**



**Figure 78. Daisy-Chain Data Format of Figure 77**



Note: The number of chained devices is limited by the SCLK rate and device mode.

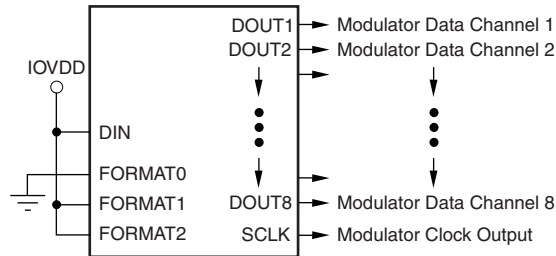
**Figure 79. Segmented DOUT Daisy-Chain, Frame-Sync Protocol (Format[2:0] = 011 or 100)**

### 8.3.18 Modulator Output

The ADS1278-SP incorporates a 6th-order, single-bit, chopper-stabilized modulator followed by a multi-stage digital filter that yields the conversion results. The data stream output of the modulator is available directly, bypassing the internal digital filter. The digital filter is disabled, reducing the DVDD current, as shown in Table 13. In this mode, an external digital filter implemented in an ASIC, FPGA, or similar device is required. To invoke the modulator output, tie FORMAT[2:0], as shown in Figure 80. DOUT[8:1] then becomes the modulator data stream outputs for each channel and SCLK becomes the modulator clock output. The DRDY/FSYNC pin becomes an unused output and can be ignored. The normal operation of the Frame-Sync and SPI interfaces is disabled, and the functionality of SCLK changes from an input to an output, as shown in Figure 80.

**Table 13. Modulator Output Clock Frequencies**

MODE [1:0]	CLKDIV	MODULATOR CLOCK OUTPUT (SCLK)	DVDD (mA)
00	1	$f_{CLK} / 4$	8
01	1	$f_{CLK} / 4$	7
10	1	$f_{CLK} / 8$	4
	0	$f_{CLK} / 4$	4
11	1	$f_{CLK} / 40$	1
	0	$f_{CLK} / 8$	1

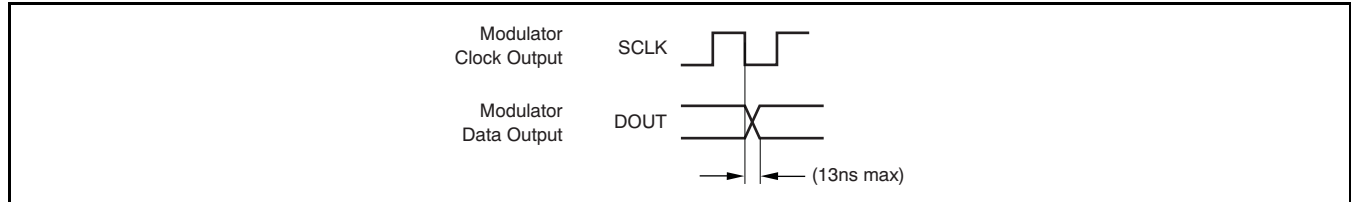


**Figure 80. Modulator Output**

In modulator output mode, the frequency of the modulator clock output (SCLK) depends on the mode selection of the ADS1278-SP. [Table 13](#) lists the modulator clock output frequency and DVDD current versus device mode.

[Figure 81](#) shows the timing relationship of the modulator clock and data outputs.

The data output is a modulated 1s density data stream. When  $V_{IN} = +V_{REF}$ , the 1s density is approximately 80% and when  $V_{IN} = -V_{REF}$ , the 1s density is approximately 20%.



**Figure 81. Modulator Output Timing**

### 8.3.19 Pin Test Using Test[1:0] Inputs

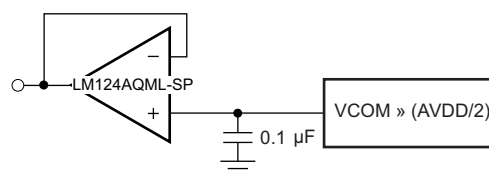
The test mode feature of the ADS1278-SP allows continuity testing of the digital I/O pins. In this mode, the normal functions of the digital pins are disabled and routed to each other as pairs through internal logic, as shown in [Table 14](#). The pins in the left column drive the output pins in the right column. **Note:** some of the digital input pins become outputs; these outputs must be accommodated in the design. The analog input, power supply, and ground pins all remain connected as normal. The test mode is engaged by setting the pins TEST [1:0] = 11. For normal converter operation, set TEST[1:0] = 00. Do not use '01' or '10'.

**Table 14. Test Mode Pin Map (Test[1:0] = 11)**

TEST MODE PIN MAP	
INPUT PINS	OUTPUT PINS
$\overline{\text{PWDN1}}$	DOUT1
$\overline{\text{PWDN2}}$	DOUT2
$\overline{\text{PWDN3}}$	DOUT3
$\overline{\text{PWDN4}}$	DOUT4
$\overline{\text{PWDN5}}$	DOUT5
$\overline{\text{PWDN6}}$	DOUT6
$\overline{\text{PWDN7}}$	DOUT7
$\overline{\text{PWDN8}}$	DOUT8
MODE0	DIN
MODE1	$\overline{\text{SYNC}}$
FORMAT0	CLKDIV
FORMAT1	$\overline{\text{FSYNC/DRDY}}$
FORMAT2	SCLK

### 8.3.20 VCOM Output

The VCOM pin provides a voltage output equal to  $AVDD / 2$ . The intended use of this output is to set the output common-mode level of the analog input drivers. The drive capability of the output is limited; therefore, the output should only be used to drive high-impedance nodes ( $> 1 \text{ M}\Omega$ ). In some cases, an external buffer may be necessary. A 0.1- $\mu\text{F}$  bypass capacitor is recommended to reduce noise pickup.



**Figure 82. VCOM Output**

## 8.4 Device Functional Modes

**Table 15. Operating Mode Performance Summary**

MODE	MAX DATA RATE (SPS)	PASSBAND (kHz)	SNR (dB)	NOISE ( $\mu\text{V}_{\text{RMS}}$ )	POWER/CHANNEL (mW)
High-Speed	128,000	57,984	106	8.5	70
High-Resolution	52,734	23,889	110	5.5	64
Low-Power	52,734	23,889	106	8.5	31
Low-Speed	10,547	4,798	107	8.0	7



## Typical Application (continued)

**Table 16. ADS1278-SP Configuration Modes**

Mode	CLKDIV	fCLK/fMOD	fCLKIN_max (MHz)	Oversampling (fMOD/fDATA)	fMOD (MHz)	fDATA_max (SPS)	fCLKIN/fMOD
High-Speed	1	4	32.768	64	8.192	128000	4
High-Speed	1	4	32.768	64	8.192	128000	4
<i>High-Speed</i>	<i>1</i>	<i>4</i>	<i>27</i>	<i>64</i>	<i>6.75</i>	<i>105469</i>	<i>4</i>
High Resolution	1	4	27	128	6.75	52734	4
Low-Power	1	8	27	64	3.375	52734	8
Low-Power	0	4	13.5	64	3.375	52734	4
Low-Speed	1	40	27	64	0.675	10547	40
Low-Speed	0	8	5.4	64	0.675	10547	8

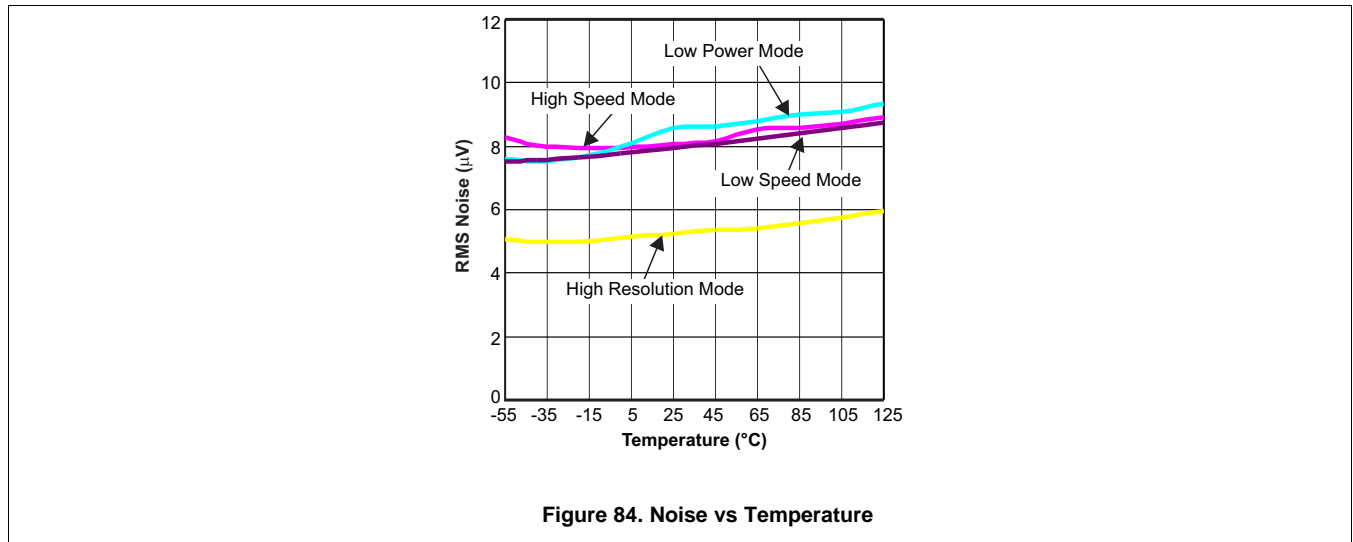
### 9.2.2 Detailed Design Procedure

To obtain the specified performance from the ADS1278-SP, the following layout and component guidelines should be considered.

- Power Supplies:** The device requires three power supplies for operation: DVDD, IOVDD, and AVDD. The allowed range for DVDD is 1.65 V to 1.95 V; the range of IOVDD is 1.65 V to 3.6 V; AVDD is restricted to 4.75 V to 5.25 V. For all supplies, use a 10- $\mu$ F tantalum capacitor, bypassed with a 0.1- $\mu$ F ceramic capacitor, placed close to the device pins. Alternatively, a single 10- $\mu$ F ceramic capacitor can be used. The supplies should be relatively free of noise and should not be shared with devices that produce voltage spikes (such as relays, LED display drivers, etc.). If a switching power-supply source is used, the voltage ripple should be low (less than 2 mV) and the switching frequency outside the passband of the converter.
- Ground Plane:** A single ground plane connecting both AGND and DGND pins can be used. If separate digital and analog grounds are used, connect the grounds together at the converter.
- Digital Inputs:** It is recommended to source-terminate the digital inputs to the device with 50- $\Omega$  series resistors. The resistors should be placed close to the driving end of digital source (oscillator, logic gates, DSP, etc.) This placement helps to reduce ringing on the digital lines (ringing may lead to degraded ADC performance).
- Analog/Digital Circuits:** Place analog circuitry (input buffer, reference) and associated tracks together, keeping them away from digital circuitry (DSP, microcontroller, logic). Avoid crossing digital tracks across analog tracks to reduce noise coupling and crosstalk.
- Reference Inputs:** It is recommended to use a minimum 10- $\mu$ F tantalum with a 0.1- $\mu$ F ceramic capacitor directly across the reference inputs, VREFP and VREFN. The reference input should be driven by a low-impedance source. For best performance, the reference should have less than 3- $\mu$ V<sub>RMS</sub> in-band noise. For references with noise higher than this level, external reference filtering may be necessary.
- Analog Inputs:** The analog input pins must be driven differentially to achieve specified performance. A true differential driver or transformer (ac applications) can be used for this purpose. Route the analog input tracks (AINP, AINN) as a pair from the buffer to the converter using short, direct tracks and away from digital tracks. A 1-nF to 10-nF capacitor should be used directly across the analog input pins, AINP and AINN. A low-k dielectric (such as COG or film type) should be used to maintain low THD. Capacitors from each analog input to ground can be used. They should be no larger than 1/10 the size of the difference capacitor (typically 100 pF) to preserve the ac common-mode performance.
- Component Placement:** Place the power supply, analog input, and reference input bypass capacitors as close as possible to the device pins. This layout is particularly important for small-value ceramic capacitors. Larger (bulk) decoupling capacitors can be located farther from the device than the smaller ceramic capacitors.

### 9.2.3 Application Curve

Figure 84 illustrates how the noise of the device, and thus, the SNR, is determined by the mode that is utilized.



## 10 Power Supply Recommendations

The ADS1278-SP has three power supplies: AVDD, DVDD, and IOVDD. AVDD is the analog supply that powers the modulator, DVDD is the digital supply that powers the digital core, and IOVDD is the digital I/O power supply. The IOVDD and DVDD power supplies can be tied together if desired (1.8 V). To achieve rated performance, it is critical that the power supplies are bypassed with 0.1- $\mu$ F and 10- $\mu$ F capacitors placed as close as possible to the supply pins. A single 10- $\mu$ F ceramic capacitor may be substituted in place of the two capacitors.

Figure 85 shows the start-up sequence of the ADS1278-SP. At power-on, bring up the DVDD supply first, followed by IOVDD and then AVDD. Check the power-supply sequence for proper order, including the ramp rate of each supply. DVDD and IOVDD may be sequenced at the same time if the supplies are tied together. Each supply has an internal reset circuit whose outputs are summed together to generate a global power-on reset. After the supplies have exceeded the reset thresholds,  $2^{18}$   $f_{CLK}$  cycles are counted before the converter initiates the conversion process. Following the CLK cycles, the data for 129 conversions are suppressed by the ADS1278-SP to allow output of fully-settled data. In SPI protocol,  $\overline{DRDY}$  is held high during this interval. In frame-sync protocol, DOUT is forced to zero. The power supplies should be applied before any analog or digital pin is driven. For consistent performance, assert SYNC after device power-on when data first appear.

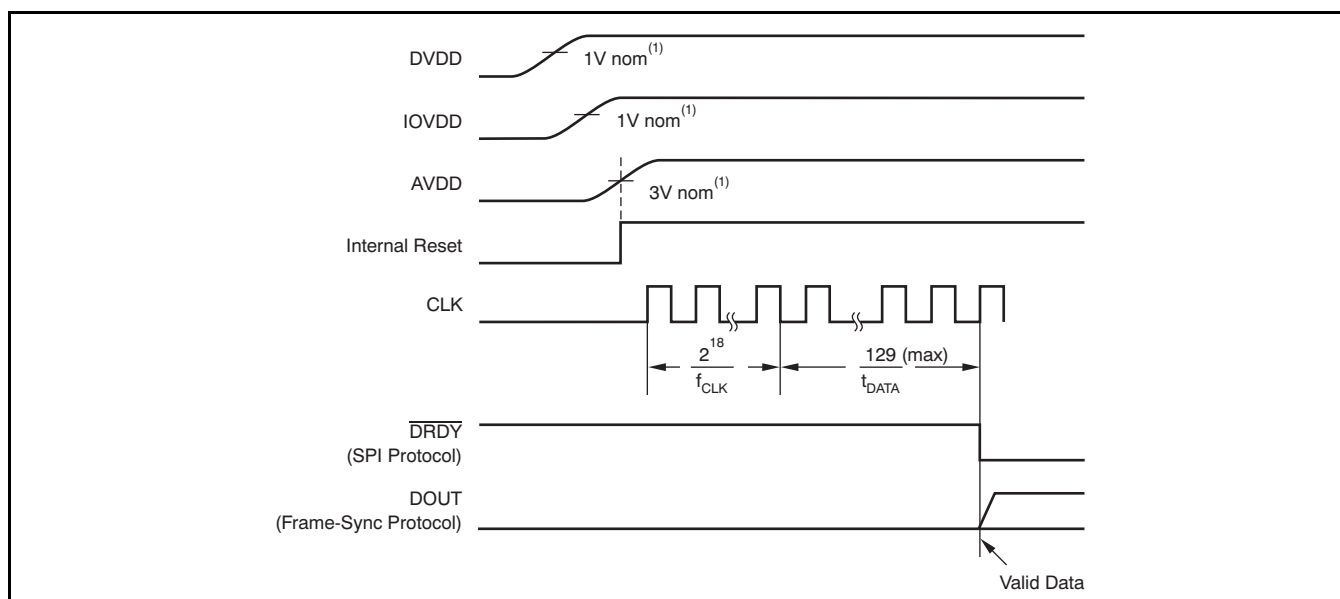


Figure 85. Start-Up Sequence

## 11 Layout

### 11.1 Layout Guidelines

In any mixed-signal system design, the power-supply and grounding design plays a significant role. The device distinguishes between two different grounds: AVSS (analog ground) and DGND (digital ground). In low frequency applications such as temperature sensing with thermocouples, laying out the printed circuit board (PCB) to use a single ground plane is adequate but care must be taken so that ground loops are avoided. Ground loops act as loop antennas picking up interference currents which transform into voltage fluctuations. These fluctuations are effectively noise which can degrade system performance in high resolution applications. When placing components and routing over the ground plane, pay close attention to the path that ground currents will take. Avoid having return currents for digital functions pass close to analog sensitive devices or traces.

Additionally, the proximity of digital devices to an analog signal chain has the potential to induce unwanted noise into the system. One primary source of noise is the switching noise from any digital circuitry such as the data output serializer or the microprocessor receiving the data. For the device, care must be taken to ensure that the interaction between the analog and digital supplies within the device is kept to a minimal amount. The extent of noise coupled and transmitted from the digital and analog sections depends on the effective inductances of each of the supply and ground connections. Smaller effective inductances of the supply and ground pins results in better noise suppression. For this reason, multiple pins are used to connect to the digital ground. Low inductance properties must be maintained throughout the design of the PCB layout by use of proper planes and layer thickness.

To avoid noise coupling through supply pins, TI recommends to keep sensitive input pins away from the DVDD and DGND planes. Do not route the traces or vias connected to these pins across these planes; that is, avoid the digital power planes under the analog input pins. Care should be taken to minimize inductance and route digital signals away from analog section.

The analog inputs represent the most sensitive node of the ADC as the total system accuracy depends on the how well the integrity of this signal is maintained. The analog differential inputs to the ADC should be routed tightly coupled and symmetrical for common mode rejection. These inputs should be as short in length as possible to minimize exposure to potential sources of noise.

## 11.2 Layout Example

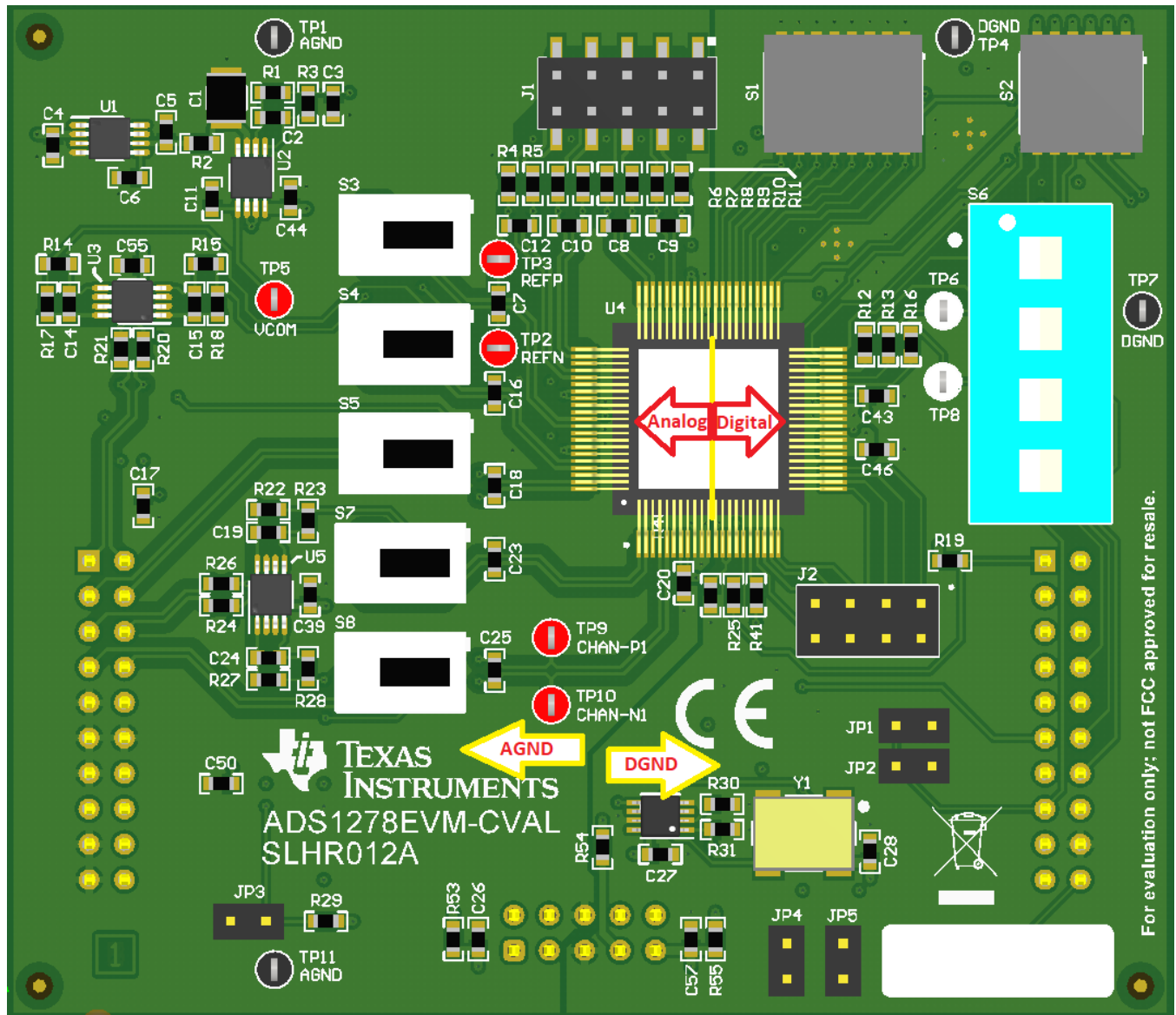


Figure 86. ADS1278-SP Layout Example

## 12 Device and Documentation Support

### 12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

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ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 12.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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