

1 Description

This subsystem demonstrates how to create musical tones on a Piezo buzzer through the use of the digital to analog converter (DAC) of the MSPM0. This process uses predefined frequencies being output to a Piezo to create a tune or jingle, being useful in applications such as home appliance, industrial machinery, or personal electronics.

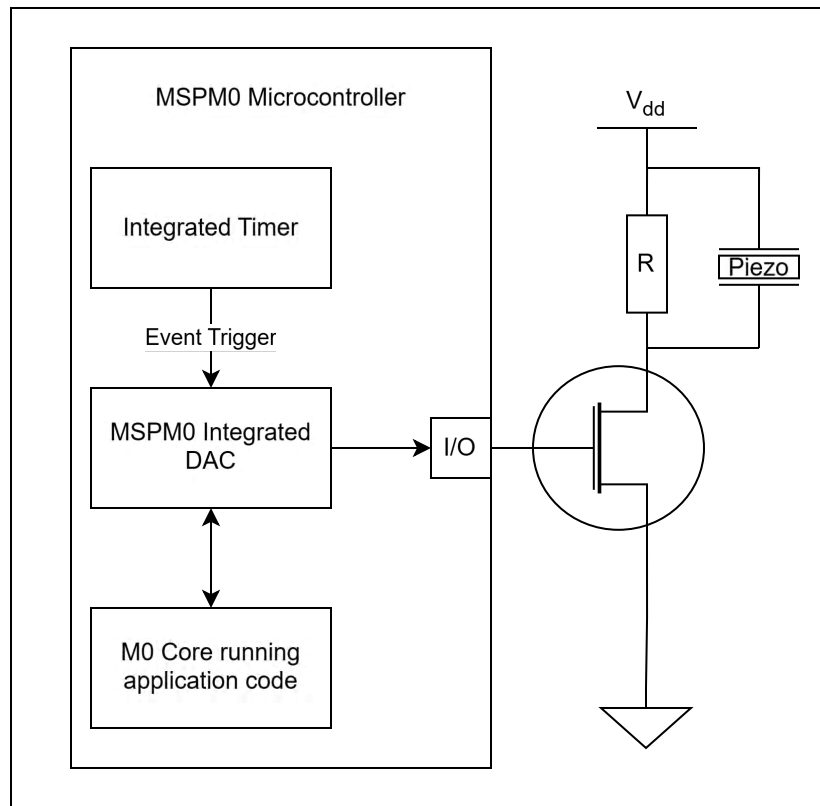


Figure 1-1. DAC to Buzzer Subsystem Block Diagram

2 Required Peripherals

Table 2-1. Required Peripherals

Sub-block Functionality	Peripheral Use	Notes
Tone Generator	DAC (DAC0)	12-bit DAC outputs sine wave samples from 64 point lookup table, generating melodic tones using phase accumulator with 24 fractional bits for frequency generation.
Timing and Sample Rate Control	TimerG (TIMER_0_INST)	Timer triggers DAC based on sample rate (16.39 in the example code to accommodate for 61us period). Timer events trigger DAC FIFO updates.
Melody Sequencing	DAC ISR (FIFO_1_2_EMPTY)	State machine ran through the ISR advances through user-defined melody.
Power Management	SYSCCTL	Sleep-on-exit enabled for low power operation. Device is only in RUN during startup and ISR execution.

3 Compatible Devices

This subsystem was designed using the LP-MSPM0G3507. All MSPM0 devices which meet the features as described by the required peripherals sections are compatible, albeit with changes to the timers, pin selection, and frequency.

Notably, depending on the device used, the API wrapper for DAC_12 can differ, and as such requires slight edits to the ISR, although the functionality won't change.

4 Design Steps

1. Based on the piezo buzzer being implemented, determine the audio parameters, including the sample rate, waveform type, lookup table resolution, and DAC resolution.
2. Define the frequency of which notes are to be played (for example, NOTE_C4 = 262Hz), organize them into a melody, and define the duration of each note in milliseconds.
3. Calculate the timer period to generate the desired sample rate trigger events. For a 10kHz sample rate, the timer must trigger at a frequency of 20kHz.
4. Generate a sine wave lookup table by pre-computing 256 sine values scaled to the onboard DAC 12 bit range (0-4095), with the midpoint at 2048 for proper AC coupling to the buzzer.
5. In SysConfig, configure the timer as an event publisher to trigger the DAC12 module, set the DAC to operate in FIFO mode with interrupts enabled for half-empty events, and route the DAC output to the appropriate GPIO pin connected to the buzzer as displayed in [Figure 1-1](#).
6. Write application code to initialize the sine table, implement the melody state machine which tracks the current note and remaining notes to be played, implement the DAC interrupt handler that outputs sine values and advances the melody sequence, and finally enable sleep-on-exit mode for low-power operation between samples.

5 Design Considerations

- **Piezo and Tone Frequency Selection:** The code must be edited to cater to the attributes of the piezo buzzer attached to the circuit. The piezo buzzer used to design and configure the provided code is the [PS1230P02BT](#). The sample rate, as well as the frequency of the tones themselves must be altered to the frequency characteristics of any piezo.
- **Sine Table Generation:** In the example code, a basic 64 entry sine table is used for creating the output on the DAC. However this creates a lower quality output, and thus can be scaled to a higher resolution to have a clearer output. The recommendation is that the sine table is either a predefined array of constants, or generated once upon startup using the MathACL module.
- **Sample Rate and Timer:** The sample rate of this subsystem, declared in the code as `gSampleRate`, must be equivalent to the period of the timer module. For example, if the desired `gSampleRate` is 20kHz, the timer period must be 0.05ms. Increasing the sample rate can provide better audio quality and smoother sine wave reproduction.

6 Software Flowchart

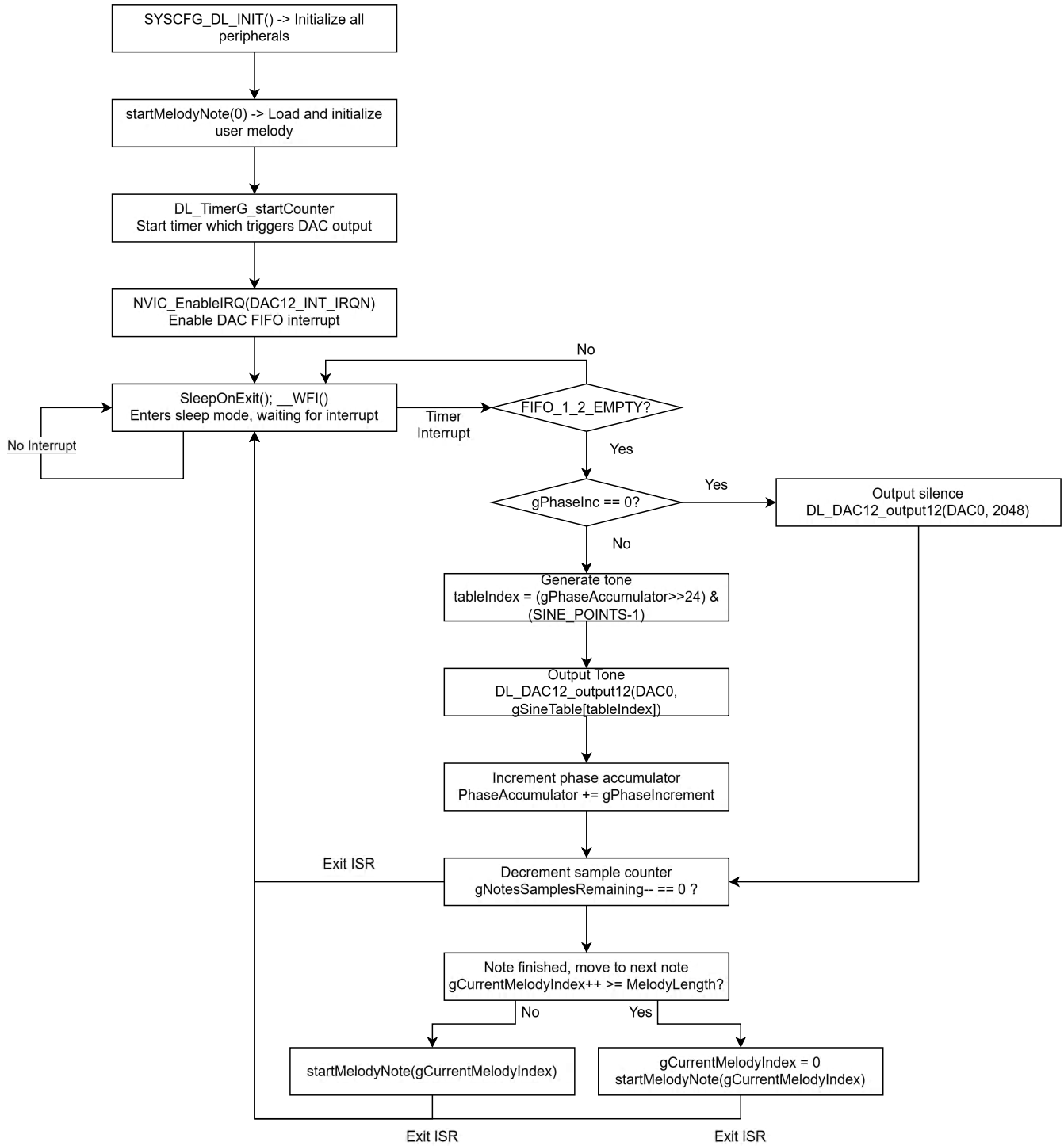


Figure 6-1. Software Flowchart

7 Application Code

```

#include "ti_msp_dl_config.h"

/* musical notes frequencies in Hz - 6th octave */
#define NOTE_C 1047 // C6
#define NOTE_D 1175 // D6
#define NOTE_E 1319 // E6
#define NOTE_F 1397 // F6
#define NOTE_G 1568 // G6
#define NOTE_A 1760 // A6
#define NOTE_B 1976 // B6

/* sine wave lookup table for DAC output */
#define SINE_POINTS 64
const uint16_t gSineTable[] = {2048, 2248, 2447, 2642, 2831, 3013,
    3185, 3347, 3496, 3631, 3750, 3854, 3940, 4007, 4056, 4086, 4095, 4086,
    4056, 4007, 3940, 3854, 3750, 3631, 3496, 3347, 3185, 3013, 2831, 2642,
    2447, 2248, 2048, 1847, 1648, 1453, 1264, 1082, 910, 748, 599, 464, 345,
    241, 155, 88, 39, 9, 0, 9, 39, 88, 155, 241, 345, 464, 599, 748, 910, 1082,
    1264, 1453, 1648, 1847};

/* Variables for tone generation */
#define PHASE_FRAC_BITS 24
uint32_t gPhaseAccumulator = 0;
uint32_t gPhaseIncrement = 0;
/* 16.39kHz sample rate (61us timer period). May require some shifts depending on the piezo used */
uint32_t gSampleRate = 16393;

/* Melody sequence: "BAG BAG GGGAAAA BAG", "Hot crossed buns" */
/* 0u represents a rest, or a tone of "0" */
static const uint32_t gMelodyFreqs[] = {
    NOTE_B, 0u, NOTE_A, 0u, NOTE_G, 0u, 0u,
    NOTE_B, 0u, NOTE_A, 0u, NOTE_G, 0u, 0u,
    NOTE_G, 0u, NOTE_G, 0u, NOTE_G, 0u, NOTE_G, 0u,
    NOTE_A, 0u, NOTE_A, 0u, NOTE_A, 0u, NOTE_A, 0u,
    NOTE_B, 0u, NOTE_A, 0u, NOTE_G, 0u
};

/* durations in milliseconds for each entry above:
full note -> 500ms, half note -> 250ms, short rest -> 80ms, phrase separator rest -> 250ms */
static const uint16_t gMelodyDurMs[] = {
    /* one phrase per line */
    500, 80, 500, 80, 500, 80, 250,
    500, 80, 500, 80, 500, 80, 250,
    250, 80, 250, 80, 250, 80, 250, 80,
    250, 80, 250, 80, 250, 80, 250, 80,
    500, 80, 500, 80, 500, 2000
};

/* defines for melody state machine*/
#define MELODY_LENGTH (sizeof(gMelodyFreqs)/sizeof(gMelodyFreqs[0]))
static uint16_t gCurrentMelodyIndex = 0;
static uint32_t gNoteSamplesRemaining = 0;

/* set the phase increment for a given frequency */
void setToneFrequency(uint32_t frequency) {
    if (frequency == 0) {
        gPhaseIncrement = 0;
        return;
    }
    /* compute increment with 24 fractional bits: inc = freq * SINE_POINTS * 2^PHASE_FRAC_BITS /
sampleRate */
    /* allows for smooth frequency shifting */
    uint64_t inc = (uint64_t)frequency * (uint64_t)SINE_POINTS * ((uint64_t)1 << PHASE_FRAC_BITS);
    inc /= gSampleRate;
    gPhaseIncrement = (uint32_t)inc;
}

/* play each note from the melody based on index (updated by isr) */
static void startMelodyNote(uint16_t idx)
{
    if (idx >= MELODY_LENGTH) {
        idx = 0;
    }

    gCurrentMelodyIndex = idx;
    uint32_t freq = gMelodyFreqs[idx];

```

```

    setToneFrequency(freq);

    /* compute note duration */
    uint32_t durMS = gMelodyDurMS[idx];
    gNoteSamplesRemaining = (durMS * gSampleRate) / 1000u;

    /* if duration is zero, click note for one sample*/
    if (gNoteSamplesRemaining == 0) {
        gNoteSamplesRemaining = 1;
    }
}

int main(void)
{
    SYSCFG_DL_init();
    /* Start the first note of the melody */
    startMelodyNote(0);
    /* Start timer to trigger DAC */
    DL_TimerG_startCounter(TIMER_0_INST);
    /* Enable DAC interrupt to update output */
    NVIC_EnableIRQ(DAC12_INT_IRQN);

    /* Calling WFI after calling DL_SYSCFG_enableSleepOnExit will result in
     * only ISR code to be executed. This is done to showcase the device's
     * low power consumption when sleeping.
     */
    DL_SYSCFG_enableSleepOnExit();
    while (1) {
        __WFI();
    }
}

void DAC12_IRQHandler(void)
{
    switch (DL_DAC12_getPendingInterrupt(DAC0)) {
        case DL_DAC12_IIDX_FIFO_1_2_EMPTY:
            {
                /* code for rest */
                if (gPhaseIncrement == 0) {
                    DL_DAC12_output12(DAC0, 2048);
                } else { /*code for tone, walk through phase table */
                    uint32_t tableIndex = (gPhaseAccumulator >> PHASE_FRAC_BITS) & (SINE_POINTS -
1);
                    DL_DAC12_output12(DAC0, gSineTable[tableIndex]);
                    gPhaseAccumulator += gPhaseIncrement;
                }

                /* state machine forward */
                if (gNoteSamplesRemaining > 0) {
                    gNoteSamplesRemaining--;
                }

                if (gNoteSamplesRemaining == 0) {
                    /* move to next note, wrap around */
                    uint16_t next = gCurrentMelodyIndex + 1;

                    /* causes song to loop*/
                    if (next >= MELODY_LENGTH) {
                        next = 0;
                    }
                    startMelodyNote(next);
                }
            }
            break;
        /* unused */
        case DL_DAC12_IIDX_FIFO_3_4_EMPTY:
        case DL_DAC12_IIDX_NO_INT:
        case DL_DAC12_IIDX_MODULE_READY:
        case DL_DAC12_IIDX_FIFO_FULL:
        case DL_DAC12_IIDX_FIFO_1_4_EMPTY:
        case DL_DAC12_IIDX_FIFO_EMPTY:
        case DL_DAC12_IIDX_FIFO_UNDERRUN:
        case DL_DAC12_IIDX_DMA_DONE:
            break;
    }
}

```

8 Additional Resources

- Texas Instruments, [MSPM0 G-Series 80MHz Microcontrollers](#), technical reference manual.
- Texas Instruments, [MSPM0G350x Mixed-Signal Microcontrollers with CAN-FD Interface](#), datasheet.

9 E2E

See [TI's E2E™](#) support forums to view discussions and post new threads to get technical support for using MSPM0 devices in designs.

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