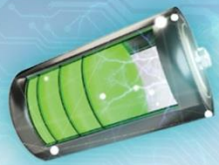




# How to implement maximum power point tracking for low power solar charging

# Agenda

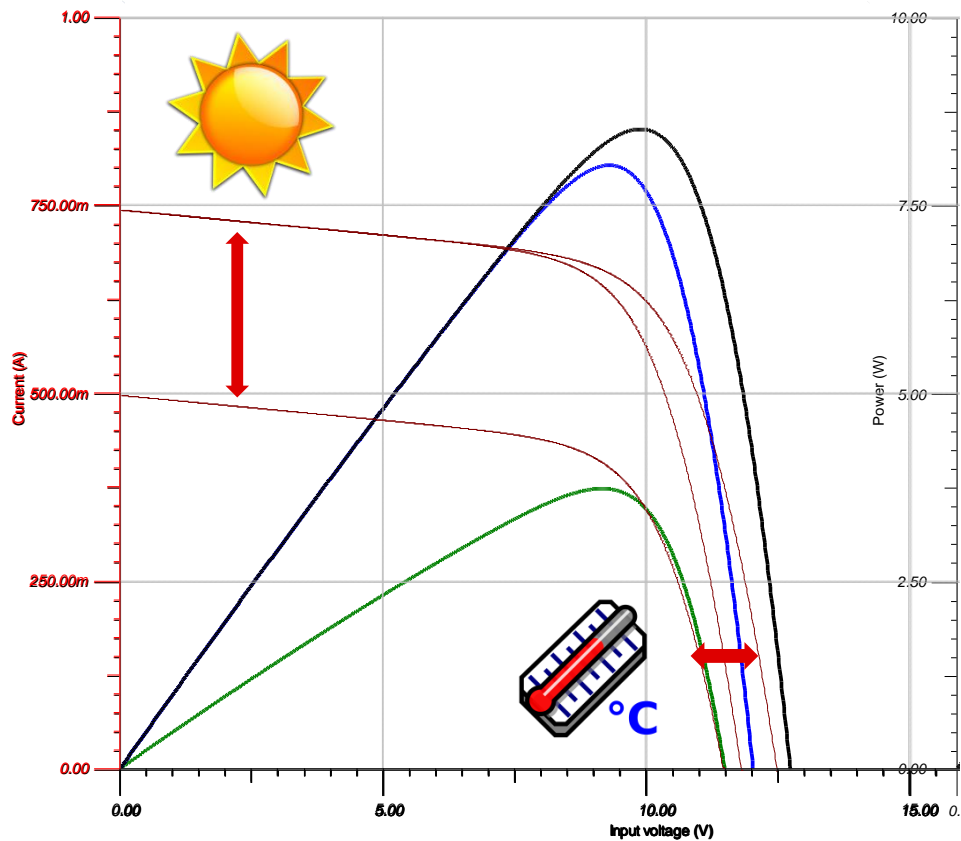
- **Application definition and solution**
- **MPPT algorithm implementation**



# Solar panel application definition

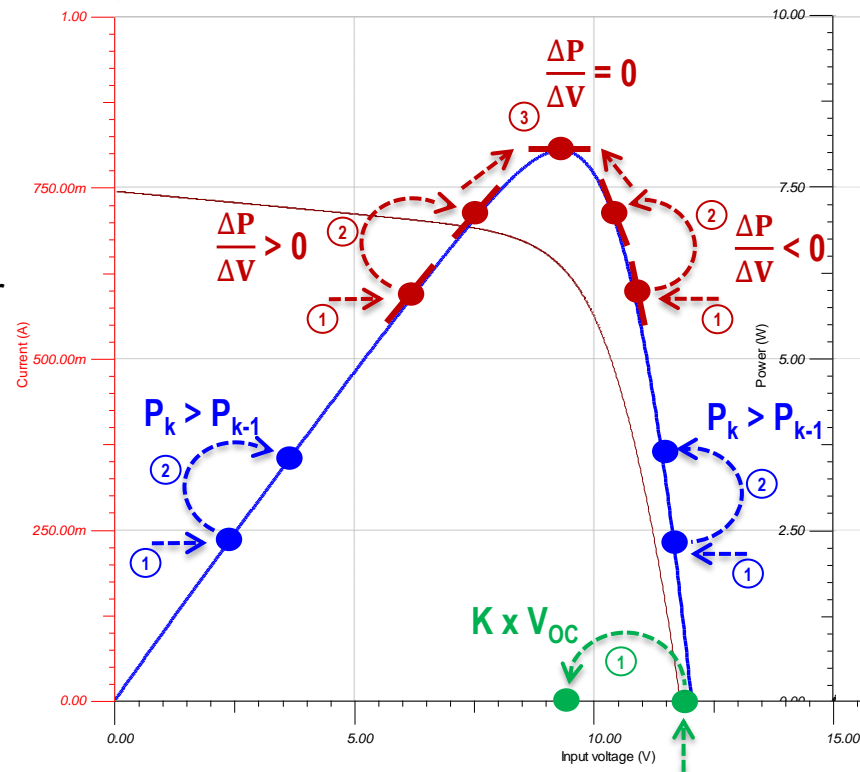
# The solar problem

- I-V Characteristic
  - High Impedance Source
  - Non-ideal parameters affect curve
    - Resistive losses
    - Diode leakage
    - Material properties
- Maximum Power Point
  - Irradiance
    - Affects short circuit current
  - Temperature
    - Shifts open circuit voltage
  - Causes MPP to move



# The Solar Solution

- Maximum Power Point Tracking Algorithm
  - Fractional Open Circuit Voltage (F.OCV)
    - Fixed ratio of the instantaneous open-circuit
  - Perturb & Observe (P&O)
    - Manipulates load and monitors change in power continuously
  - Incremental Conductance (IC)
    - Manipulates load and monitors change in conductance



# Solution Comparisons

- Algorithm/Controller Considerations

- Software

- Calculation | Measurement | Storage
- Processing | Power | Speed

- Hardware

- Sensing | Memory | Control
- Cost | Size | Speed | Efficiency

- Tracking Ability

- Accuracy | Adaptability | Timing

MPPT	Software Complexity	Hardware Complexity	Tracking Ability
P&O	<ul style="list-style-type: none"> <li>• Calculate (P)</li> <li>• Store Previous States</li> </ul>	<ul style="list-style-type: none"> <li>• (V) and (I) Sensors</li> <li>• Multiplier</li> <li>• Memory or State Machine</li> </ul>	<ul style="list-style-type: none"> <li>• Continuously tracks power</li> <li>• Suffers from oscillation</li> <li>• Step size determines tracking time</li> </ul>
IC	<ul style="list-style-type: none"> <li>• Calculate (I), (V) Slope and (P)</li> <li>• Store Previous States</li> </ul>	<ul style="list-style-type: none"> <li>• (V) and (I) Sensors</li> <li>• Controller (memory, multiplier)</li> </ul>	<ul style="list-style-type: none"> <li>• Can suffer from oscillation under certain conditions</li> <li>• Step size determines tracking time</li> </ul>
F.OCV	<ul style="list-style-type: none"> <li>• Calculate <math>K \cdot V_{OC}</math></li> </ul>	<ul style="list-style-type: none"> <li>• Resistor divider</li> </ul>	<ul style="list-style-type: none"> <li>• Ratiometrically follows open circuit voltage</li> <li>• Estimate of power point; good for single solar cell</li> <li>• Partial shading affects estimate</li> </ul>

# The Solar Charging Solution – 3M Approach

- Basic Functions for a Solar Charger

- Monitor

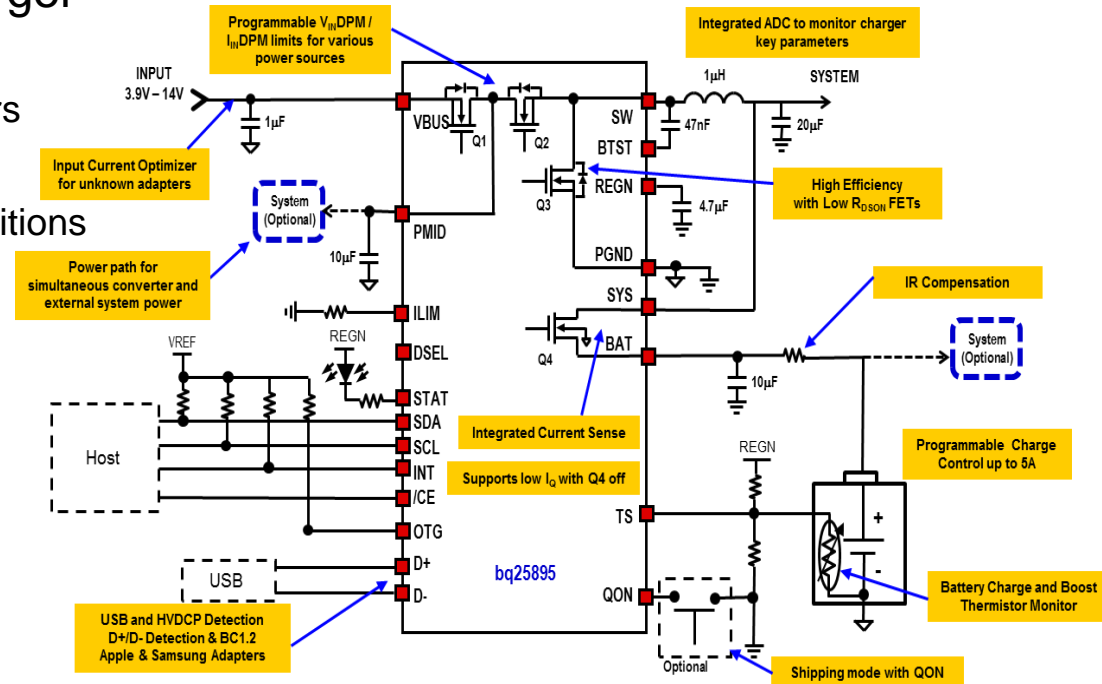
- Key Charging and Input Parameters

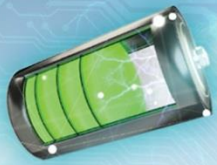
- Manipulate

- Operating Point and Loading Conditions

- Maximize

- Input Power and Charging Current



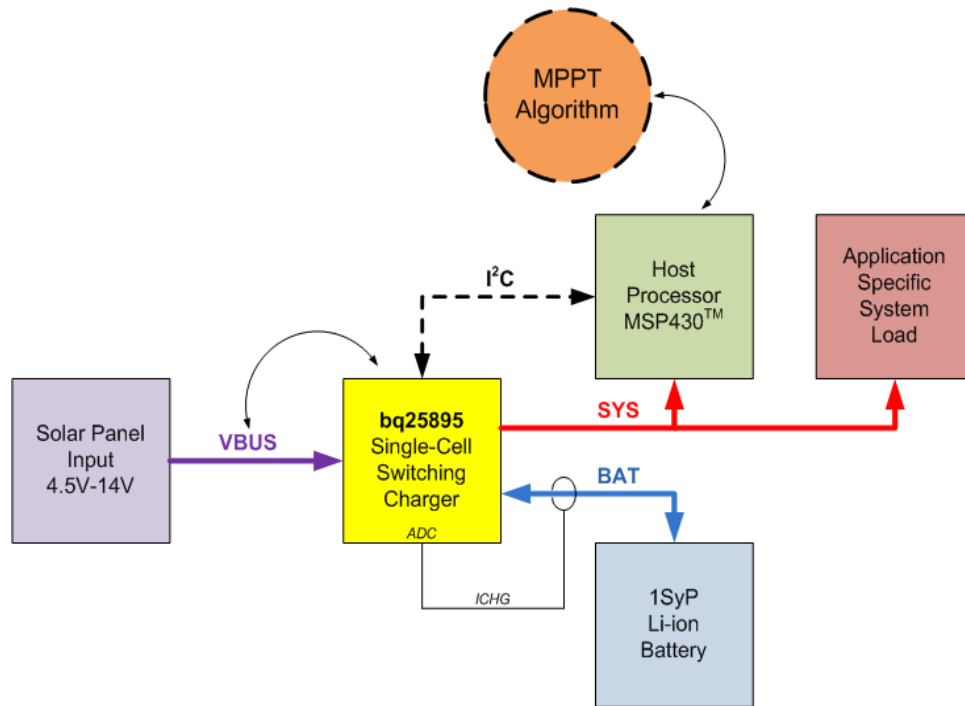


# MPPT Algorithm Implementation



# Maximizing Charging Current

- Implementation
  - Prioritize battery charging
  - Adjust operating point to get max charge
- Assumptions
  - Battery voltage constant
    - CC Charge
  - Low/constant System Load
    - $I_{SYS} < I_{CHG} \ll I_{IN,DPM} \rightarrow$  Supplement Mode
- Goals
  - Time
    - Tracking within 5s
  - Accuracy
    - $\pm 50\text{mA}$  of  $I_{MPP}$
    - $\pm 300\text{mV}$  of  $V_{MPP}$



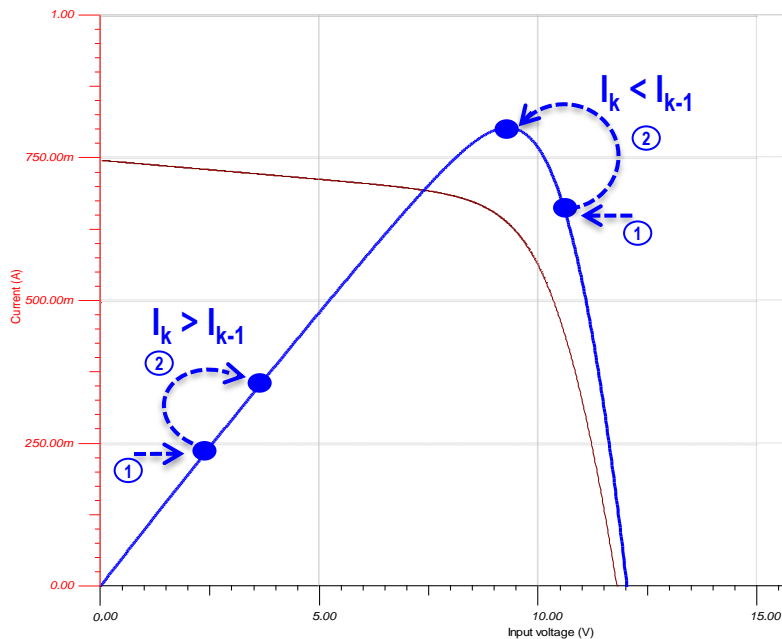
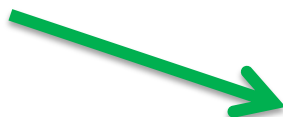
# Algorithm Methodology

- Working Principle

- With given  $V_{BAT}$  and  $I_{SYS}$  → **charge current will move proportionally with input power**

- Neglect efficiency
- Neglect dynamic loading

- Based on **P&O MPPT**



# Algorithm Flow Diagram

- Core Blocks

- Device Initialization

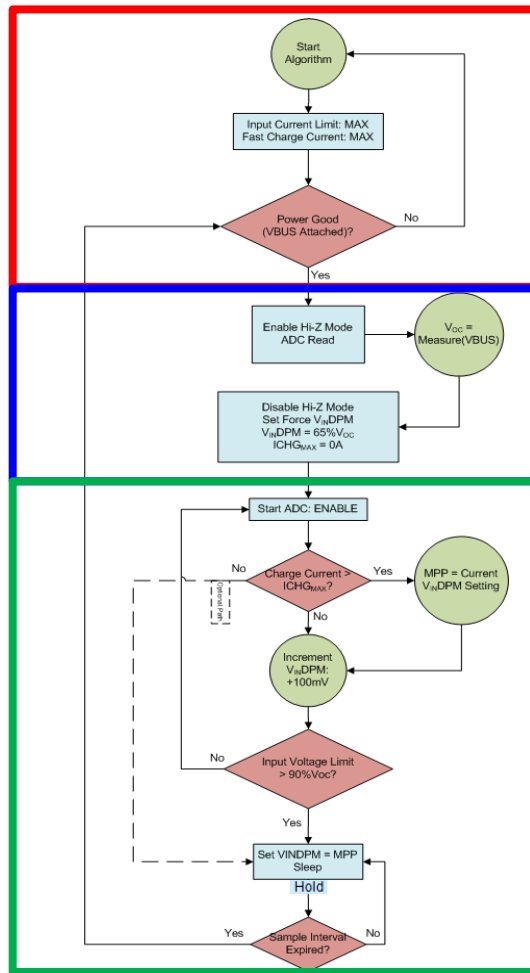
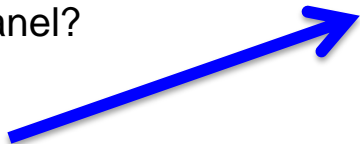
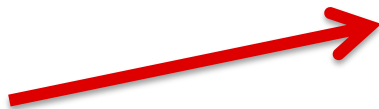
- Setting Preconditions
- Is there power from the Panel?

- MPPT Initialization

- Setting Limits to the Algorithm
- Redefining Parameters

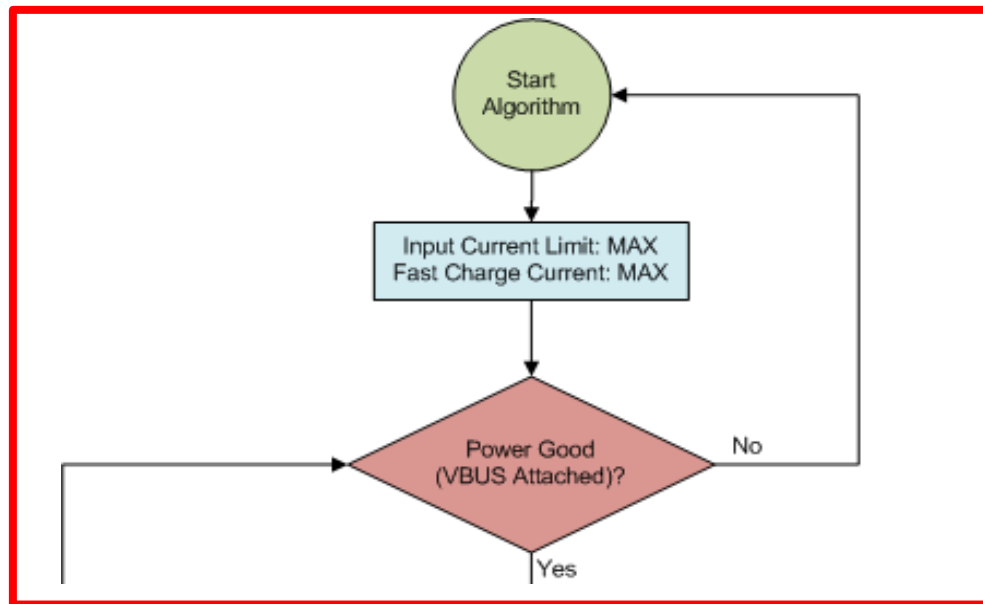
- MPP Tracker

- **Manipulate** the operating point
- **Monitor** outputs
- **Maximize** charging current



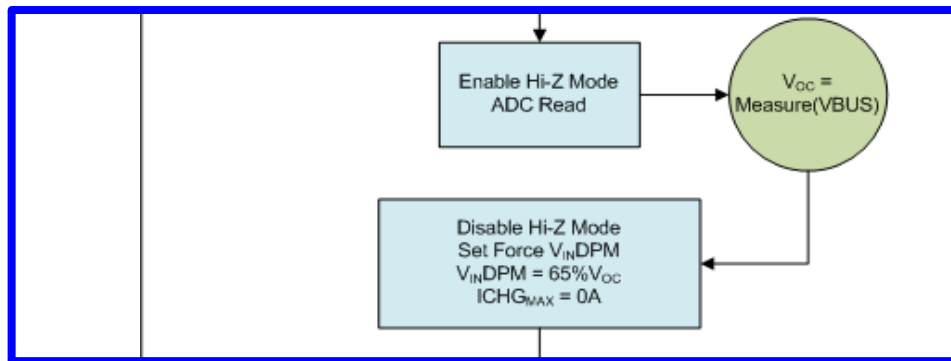
# Core Sub-Blocks

- Device Initialization
  - Unclamped Power Point
    - $I_{IN}DPM$
    - Charge Current
    - FORCE\_VINDPM
  - Power Good
    - Heavily shaded?
    - Damaged?
    - Power Not Good
      - Default Hi-Z



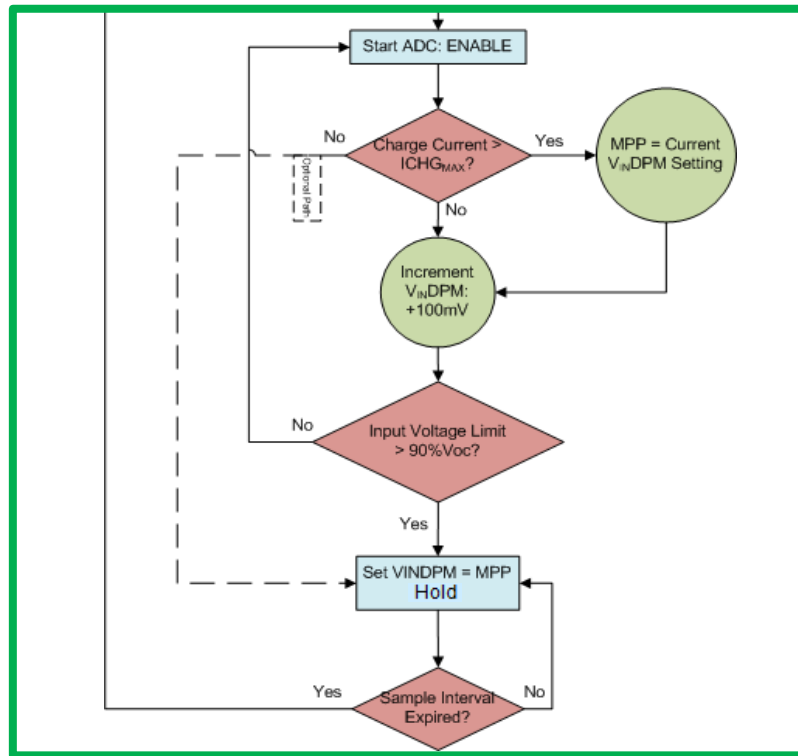
# Core Sub-Blocks

- MPPT Initialization
  - Hi-Z mode for  $V_{OC}$
  - $65\%V_{OC}$ 
    - Definable
    - Optimize
      - Tracking Time
      - IV Curve
    - Start Condition
  - $ICHG_{MAX}$ 
    - Compare to instant  $ICHG$
    - Update



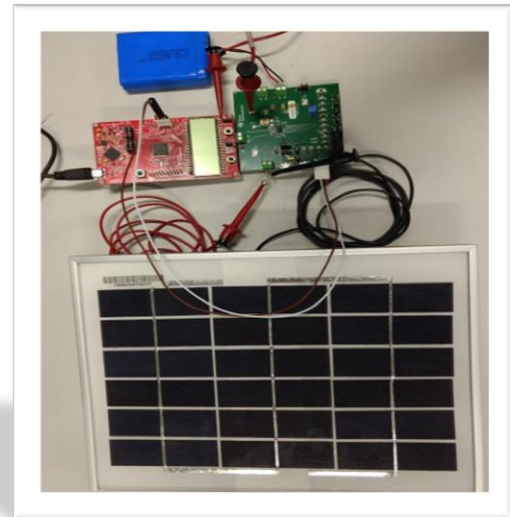
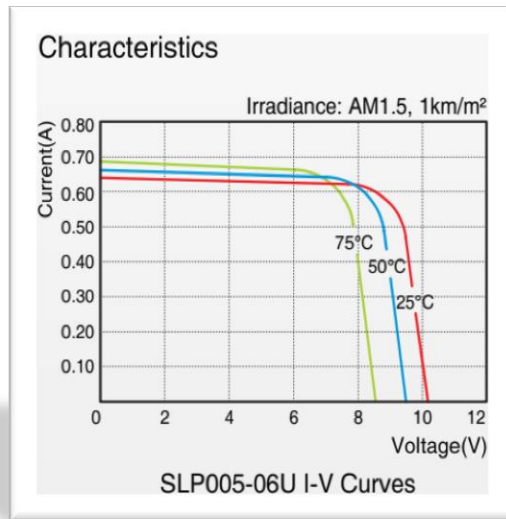
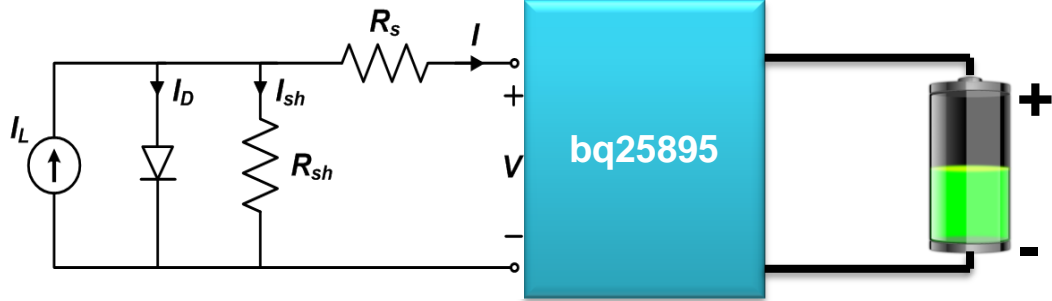
# Core Sub-Blocks

- MPP Tracker
  - ADC Read
    - Burst Mode
    - Multiple reads = Precision
  - Charge Current >  $ICHG_{MAX}$ ?
    - Current increasing/decreasing
    - Update Max Charge
  - Increment  $V_{IN}DPM$ 
    - Step Size
  - Optional: Stop after decrease
    - Improves speed of algorithm
  - Sample Interval
    - Sunlight variance



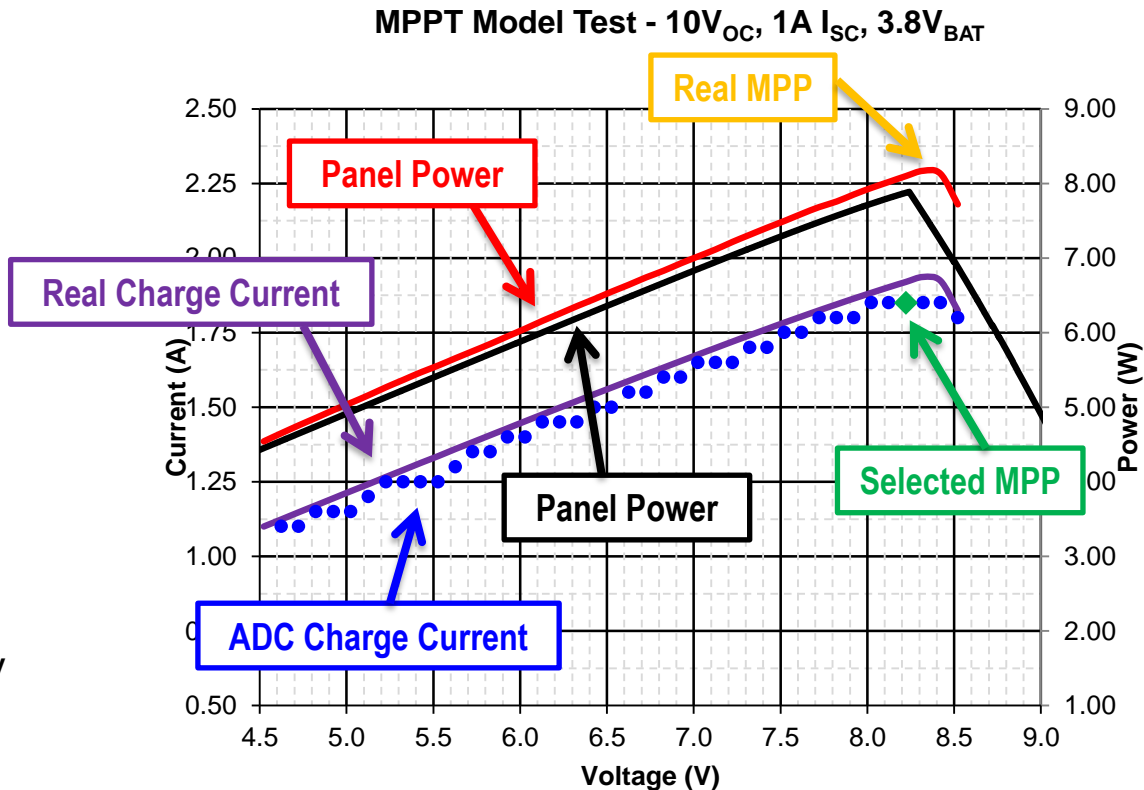
# Test Conditions

- Model (Simulated Panel)
  - Standard 4-Component Model
- Outdoor (Real Panel)
  - *SolarLand Model #*: SLP005-06U
  - Polycrystalline
  - 5W, 6V, 10.5V  $V_{OC}$ , 0.67A  $I_{SC}$
  - 3.1V  $V_{BAT}$ , 6Ah capacity
- Testing Conditions
  - 4.5V –  $V_{MPP+1}$
  - Stop after Max Power



# High Irradiance Model: 1A Short Circuit Current

- High Irradiance Test
- Results
  - Charge current = Max
    - Stop Tracking
  - Similar  $I_{CHG}$  readings
    - Near  $V_{MPP}$
    - Could affect reading
    - Select Midpoint as Max
  - $V_{MPP(Real)} - V_{MPP(Selected)} = 100mV$
  - $P_{MPP(Real)} - P_{MPP(Selected)} = 70mW$

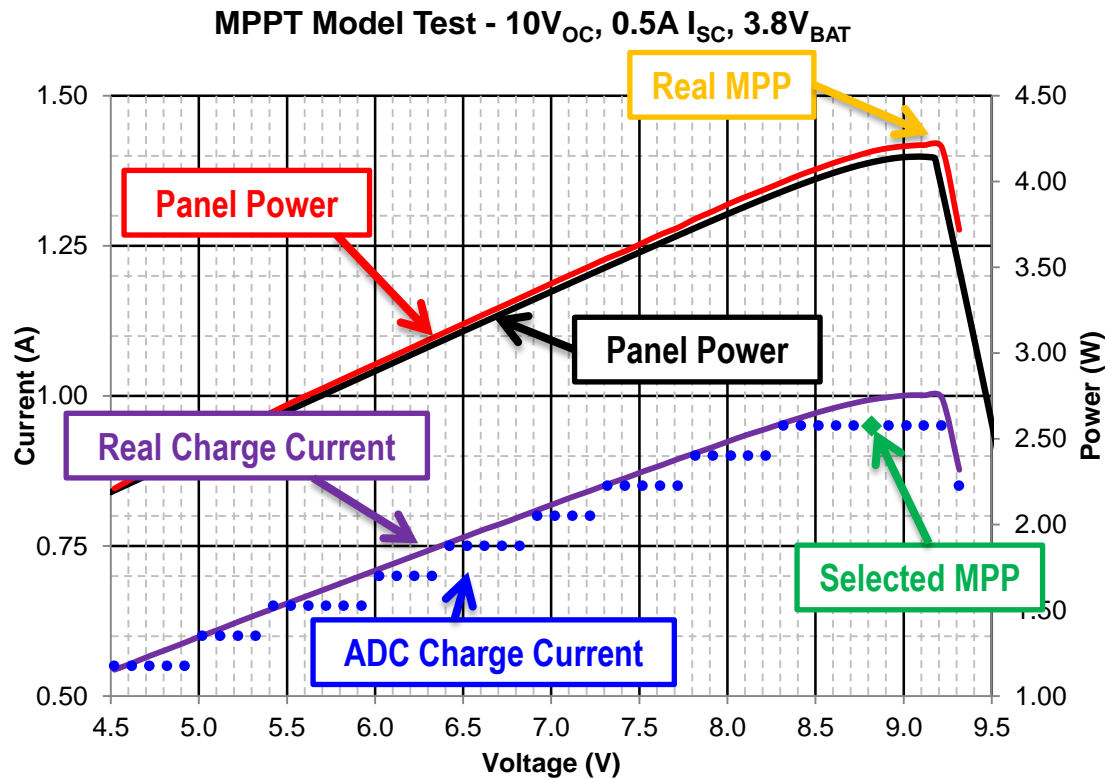




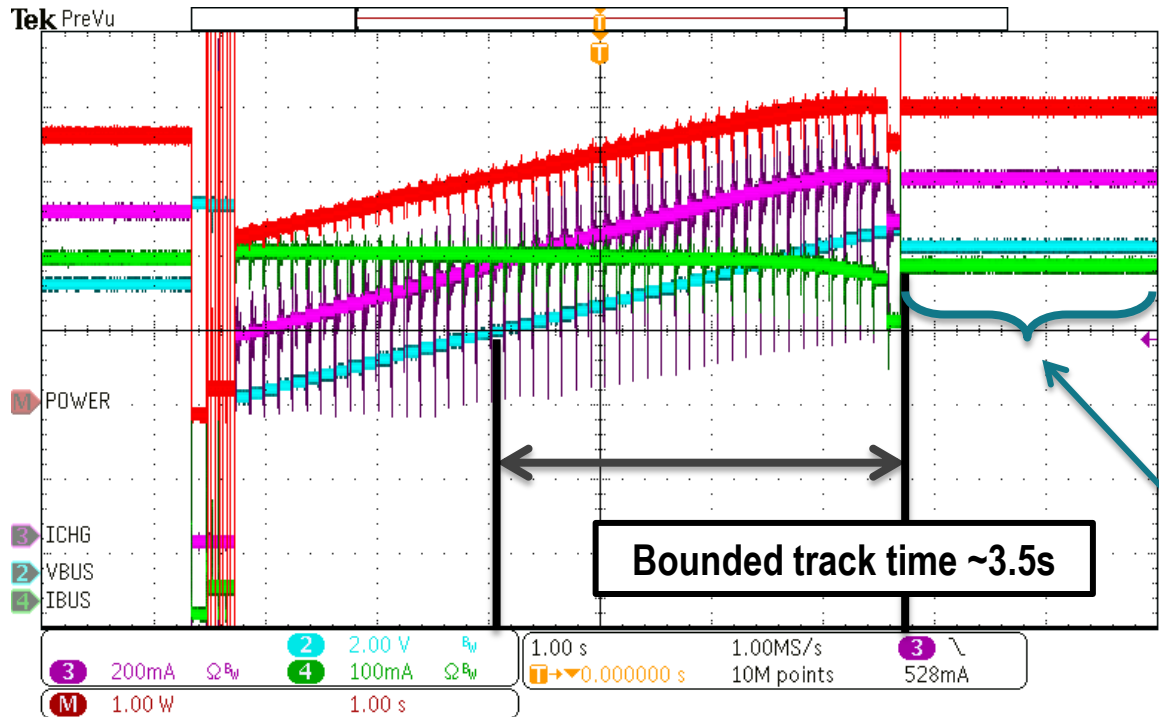
# Low Irradiance Model: 0.5A Short Circuit Current

- Low Irradiance Test
- Results
  - Similar behavior to 1A  $I_{SC}$
  - Power has sharp corner
    - Non-ideal Solar Model

- $V_{MPP(Real)} - V_{MPP(Selected)} = 300mV$
- $P_{MPP(Real)} - P_{MPP(Selected)} = 40mW$



# Test Results - Model



## Results

- Sweeps/Tracks in 6.4s
  - Faster if 65-90% $V_{OC}$
- Near  $V_{OC}$ , sharp corner in power
  - No effect on tracking
- Customizable hold time

Input Power

Charge Current

Input Voltage

Input Current

# Test Results – Outdoor: Real Panel

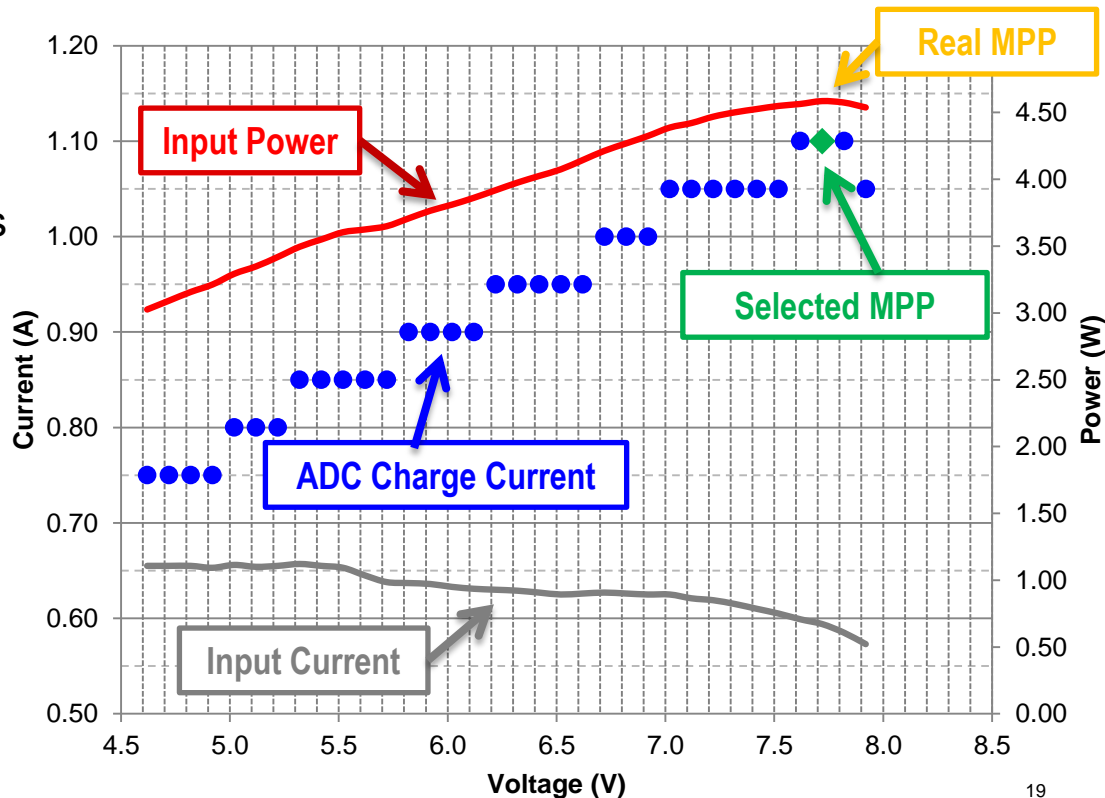
MPPT Outdoor Test - 9.5V<sub>OC</sub>, 0.65A<sub>ISC</sub>, 3.1V<sub>BAT</sub>, 6Ah

- Results

- $P_{MPP(Selected)} = P_{MPP(Real)}$

- Sunlight can change in seconds

- Affects Temperature
    - Shifts Power curve



## Features

- Integrated 7-Bit ADC to Monitor Input Voltage, Battery Voltage, and Charge Current
- Adjustable Input Voltage Power Management threshold with 100 mV Resolution
- High Charge Efficiency with 93% @ 2 A and 91% @ 3 A
- Wide Input Voltage Operating Range from 3.9 V to 14 V
- Integrated Reverse Blocking at Input

## Applications

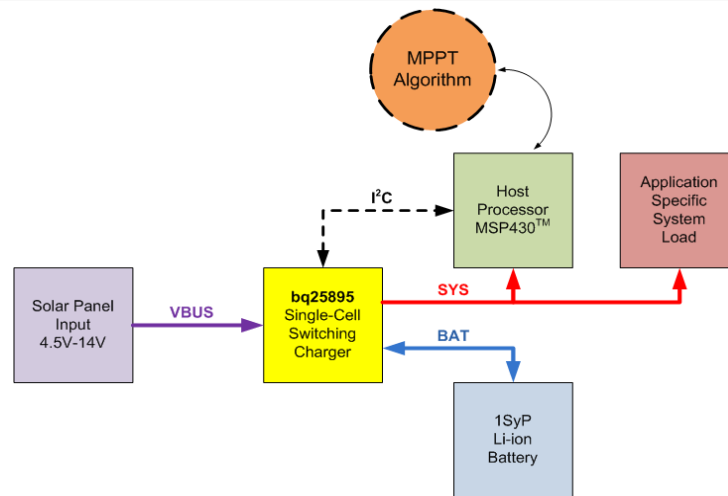
- [Smart Shared Bikes](#)
- [IP Cameras](#)
- [Portable Speakers](#)

## Tools & Resources

- **TIDA-01556 Tools Folder**
- **Design Guide**
- **Design Files:** Software
- **Device Datasheets:**
  - bq25895
  - MSP430FR4133

## Benefits

- Measure Solar Panel Open-Circuit Voltage with 100mV resolution, Charging Current with 50mA resolution, and Battery Voltage with 20mV resolution
- Adjust Solar Panel Power Point through VINDPM
- Optimized Input Power Conversion for Maximum Charge
- Operate with High Voltage Solar Panels up to 14V
- Provide Reverse Current Protection to the Solar Panel



# Conclusion / Summary

- Solar Power Tracking
  - Max Power moves with Sunlight and Temperature
    - Algorithms: F.OCV | P&O | IC
    - Trackers: Software | Hardware | Accuracy
  - 3M: Monitor | Manipulate | Maximize
  
- Simple MPPT Implementation
  - Max ICHG  $\rightarrow$   $P_{MPP}$ 
    - P&O approach
    - Reflected  $P_{IN}$
  
- TIDA-01556: *µC Controlled Single Cell 5-A Charger with Power Management for MPPT with Solar Input*



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