

Bq501210 输出功率为 15W 的 WPC v1.2 无线电源发射器管理器

1 特性

- 通过 Qi 认证的无线充电联盟 (WPC) v1.2 解决方案实现 15W 运行
 - 缩短充电时间
 - 向后兼容现有的 5W WPC 接收器
- 12V 至 19V 输入, 固定频率, 电源轨电压控制架构
 - 15V 至 19V 电压下可实现 15W 功率
 - 高压专用充电端口 (HVDCP) 支持 9V 和 12V 电压
 - 动态功率限制 (DPL), 允许器件由弱电源供电运行
- 符合 WPC MP-A5 发射器类型技术规范
- 通过 FOD Ping 实现增强型外来物体检测 (FOD), 可在电源传输前检测金属物体
- 空闲和“充电完成”期间低待机功耗
- 双向通信
- 数字解调减少了组件数量并简化了电路
- 支持对兼容的接收器进行快速充电
- 10 种可配置 LED 模式, 可指示充电状态和故障状态

2 应用

- WPC v1.2 无线充电器:
 - Qi 认证智能手机、平板电脑和其它手持设备
 - 销售点设备
 - 定制无线电源 应用

3 说明

bq501210 是一款符合无线充电联盟 (WPC) v1.2 标准的无线电源数字控制器。该器件集成了符合 WPC 的接收器无线传输功率所需的逻辑功能, 最高能够传输 15W 功率。bq501210 也是一款智能器件, 定期向周围环境发出 ping 以搜索需要供电的设备、检测充电板上是否存在外来金属物体、为正在进行无线供电的设备监视所有通信以及根据从被供电设备收到的反馈调整施加到发射器线圈的功率。bq501210 还可以处理与功率输出相关的故障条件并控制运行模式状态指示灯。bq501210 使用电源电压控制机制代替传统的频率控制调节传送到接收器的功率。

通过与高压专用充电端口 (HVDCP) 适配器进行协商, bq501210 可选择提供 5W WPC 低功率或 15W 中等功率。

此外, 还可以凭借快速充电支持为兼容的接收器提供更高功率。

有关 TI 无线充电解决方案的更多信息, 请访问

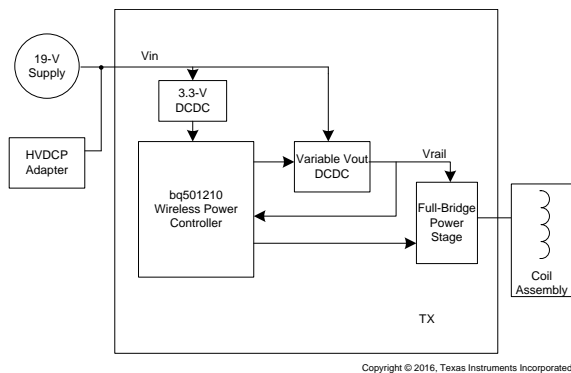
www.ti.com.cn/wirelesspower

器件信息⁽¹⁾

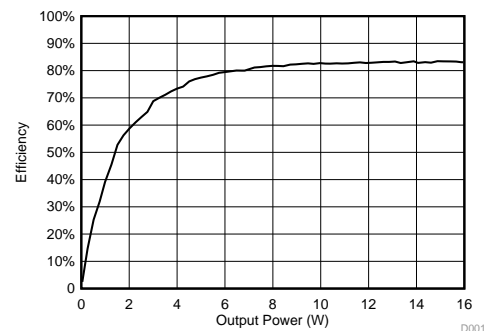
器件型号	封装	封装尺寸 (标称值)
bq501210	VQFN (64)	9.00mm x 9.00mm

(1) 要了解所有可用封装, 请见数据表末尾的可订购产品附录。

发射器解决方案简化框图



系统效率与 WPC 15W 典型接收器的关系



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4 修订历史记录

Changes from Original (April 2016) to Revision A

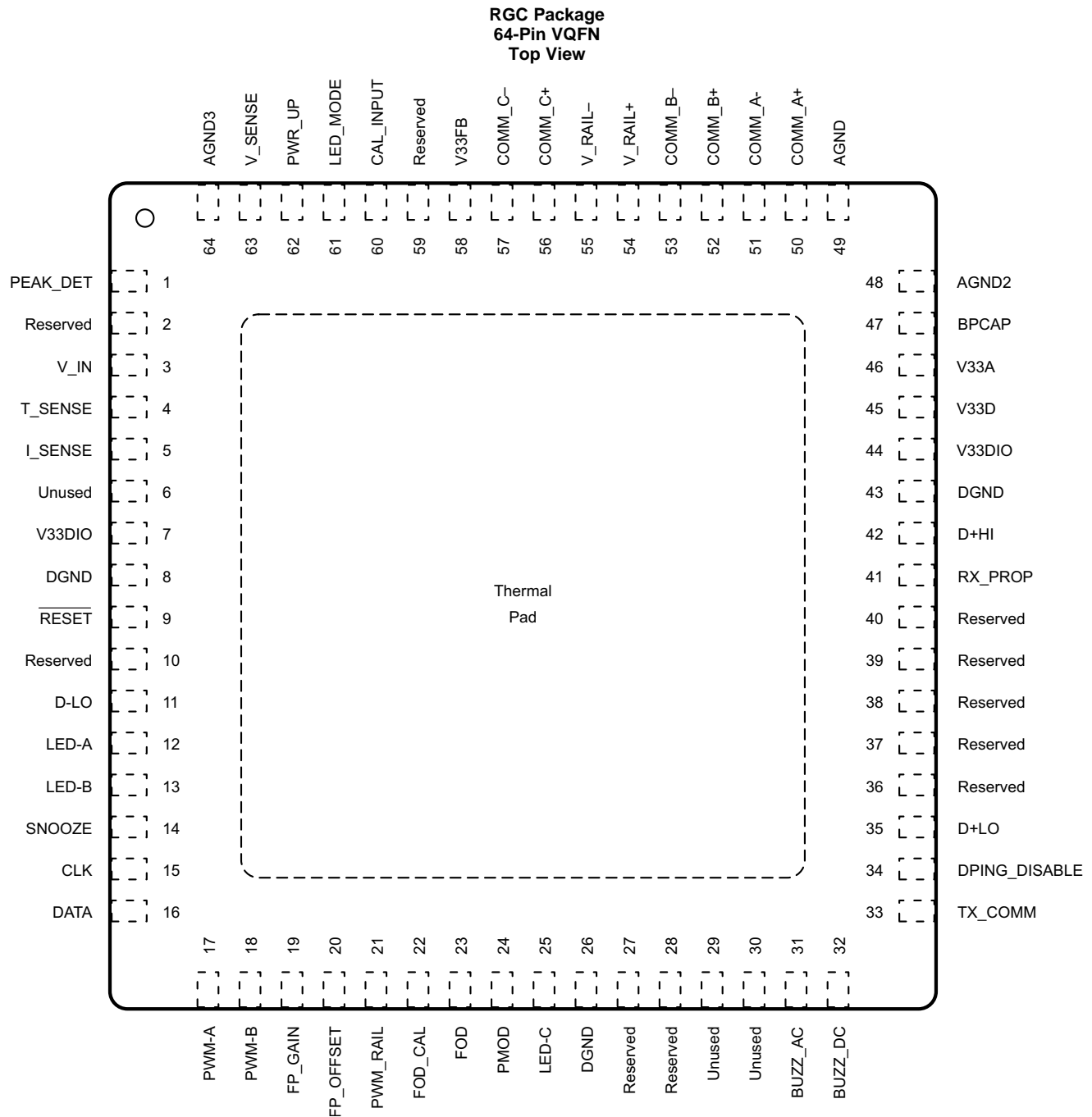
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• 已从“产品预览”更改为“量产数据”	1
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5 Device Comparison

DEVICE	FUNCTION	SYSTEM VIN	PROTOCOL	MAXIMUM DELIVERED POWER	NOTE
bq500212A	Wireless Power Transmitter Manager	5 V	WPC v1.1	5 W	1 Coil
bq500215	Wireless Power Transmitter Manager	12 V	WPC v1.1	10 W	1 Coil, 5 W or 10 W operation
bq500412	Wireless Power Transmitter Manager	5 V, 12 V	WPC v1.1	5 W	1, 2 or 3 Coils
bq500414Q	Wireless Power Transmitter Manager	12 V	WPC v1.1	5 W	1, 2 or 3 Coils, Automotive
bq500511 bq50002	Wireless Power Transmitter Controller Wireless Power Transmitter Analog Front End	5 V	WPC v1.1	5 W	1 Coil
bq501210	Wireless Power Transmitter Manager	12 V – 19 V	WPC v1.2	15 W	1 Coil

6 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
PEAK_DET	1	I	Input from peak detect circuit
Reserved	2	—	This pin must be connected to GND.
V_IN	3	I	Transmitter Input Voltage Sense
T_SENSE	4	I	Sensor input. Device shuts down when below 1 V. If not used, keep above 1 V by simply connecting to 3.3-V supply
I_SENSE	5	I	Full bridge input current sense
Unused	6, 29, 30	—	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.
V33DIO	7, 44	—	3.3-V IO power supply
DGND	8, 26, 43	—	GND
RESET	9	I	Device reset. Use 10- to 100-k Ω pullup resistor to 3.3-V supply
Reserved	10	—	This pin must be left open.
D-LO	11	O	HVDCP interface
LED-A	12	O	Connect to an LED with a 470- Ω resistor for status indication.
LED-B	13	O	Connect to an LED with a 470- Ω resistor for status indication.
SNOOZE	14	O	Force SNOOZE (500 ms low power)
CLK	15	I	I ² C interface, Clock
DATA	16	I/O	I ² C interface, Data
PWM-A	17	O	PWM output A, controls one half of the full bridge in a phase-shifted full bridge. Switching dead times must be externally generated.
PWM-B	18	O	PWM output B, controls other half of the full bridge in a phase-shifted full bridge. Switching dead times must be externally generated.
FP_GAIN	19	O	Output to select the FOD ping calibration gain
FP_OFFSET	20	O	Output to select the FOD ping calibration offset
PWM_RAIL	21	O	PWM control signal for full bridge rail voltage
FOD_CAL	22	O	Output to select the FOD calibration
FOD	23	O	Output to select the foreign object detection (FOD) threshold
PMOD	24	O	Output to select the PMOD threshold
LED-C	25	O	Connect to an LED with a 470- Ω resistor for status indication.
Reserved	27, 28	—	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.
BUZZ_AC	31	O	AC buzzer output. A 400-ms, 4-kHz AC pulse train when charging begins
BUZZ_DC	32	O	DC buzzer output. A 400-ms DC pulse when charging begins. This could also be connected to an LED with a 470- Ω resistor.
TX_COMM	33	O	Debug only. This pin echoes all TX_COMM
DPING_DISABLE	34	I	Disable periodic ping backup
D+LO	35	O	HVDCP interface
Reserved	36, 37, 38, 39	—	These pins must be left open.
Reserved	40	—	Reserved, connect to 10-k Ω resistor to GND
RX_PROP	41	O	Indicates RX proprietary packet received
D+HI	42	O	HVDCP interface
V33D	45	—	Digital core 3.3-V supply. Be sure to decouple with bypass capacitors as close to the part as possible.
V33A	46	—	Analog 3.3-V supply. This pin can be derived from V33D supply, decouple with 22- Ω resistor and additional bypass capacitors.
BPCAP	47	—	Connect to 1uF bypass capacitors to 3.3-V supply and GND
AGND2	48	—	GND
AGND	49	—	GND

Pin Functions (continued)

PIN		I/O	DESCRIPTION
NAME	NO.		
COMM_A+	50	I	Digital demodulation non-inverting input A. Connect parallel to input B+
COMM_A-	51	I	Digital demodulation inverting input A. Connect parallel to input B-
COMM_B+	52	I	Digital demodulation non-inverting input B. Connect parallel to input A+
COMM_B-	53	I	Digital demodulation inverting input B. Connect parallel to input A-
V_RAIL+	54	I	Feedback for full bridge rail voltage control +
V_RAIL-	55	I	Feedback for full bridge rail voltage control -
COMM_C+	56	I	Digital demodulation non-inverting input C. Connect parallel to input A+
COMM_C-	57	I	Digital demodulation inverting input C. Connect parallel to input A-
V33FB	58	I	Reserved, leave this pin open
Reserved	59	—	This pin must be connected to GND.
CAL_INPUT	60	I	Input for FOD configuration
LED_MODE	61	I	LED mode select
PWR_UP	62	I	First power-up indicator (pull high if unused)
V_SENSE	63	I	Transmitter rail voltage sense
AGND3	64	—	GND
PAD	--	—	Flood with copper GND plane and stitch vias to PCB internal GND plane

7 Specifications

7.1 Absolute Maximum Ratings⁽¹⁾

over operating free-air temperature (unless otherwise noted)

	MIN	MAX	UNIT
Voltage applied at V33D to DGND	−0.3	3.8	V
Voltage applied at V33A to AGND	−0.3	3.8	
Voltage applied to any pin ⁽²⁾	−0.3	3.8	
Storage temperature, T _{stg}	−40	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltages referenced to GND.

7.2 ESD Ratings

			MAX	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	±2000	V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾	±750	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V	Supply voltage during operation, V33D, V33A	3.0	3.3	3.6	V
T _A	Operating free-air temperature range	−40		85	°C
T _J	Junction temperature			125	

7.4 Thermal Information

THERMAL METRIC ⁽¹⁾		bq501210 RGC (VQFN)	UNIT
		64 Pins	
R _{θJA}	Junction-to-ambient thermal resistance	29.5	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	15.1	°C/W
R _{θJB}	Junction-to-board thermal resistance	8.4	°C/W
ψ _{JT}	Junction-to-top characterization parameter	0.2	°C/W
ψ _{JB}	Junction-to-board characterization parameter	8.3	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	1.2	°C/W

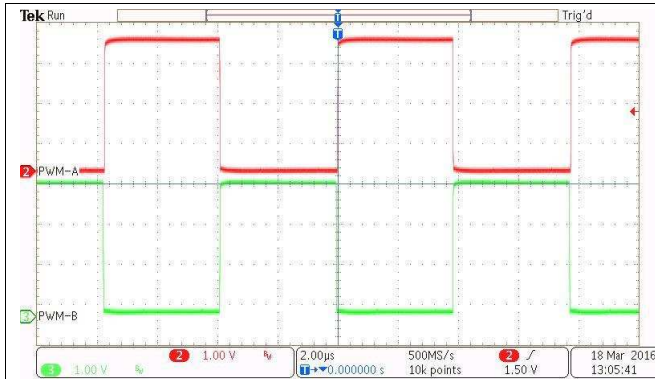
- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

7.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

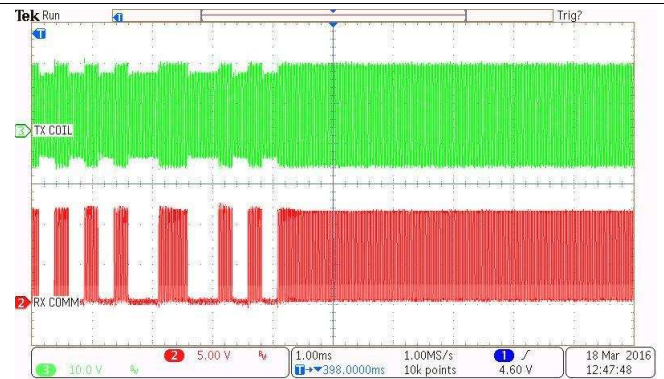
PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
SUPPLY CURRENT							
I _{V33A}	Supply current	V33A = 3.3 V			8	15	mA
I _{V33D}		V33D = 3.3 V			44	55	
I _{Total}		V33D = V33A = 3.3 V			52	70	
EXTERNALLY SUPPLIED 3.3 V POWER							
V33D	Digital 3.3-V power	T _A = 25°C		3		3.6	V
V33A	Analog 3.3-V power	T _A = 25°C		3		3.6	
V33Slew	3.3-V slew rate	3.3-V slew rate between 2.3 and 2.9 V, V33A = V33D		0.25			V/ms
DIGITAL DEMODULATION INPUTS: COMM_A+, COMM_A–, COMM_B+, COMM_B–, COMM_C+, COMM_C–							
V _{CM}	Common mode voltage each pin			–0.15		1.631	V
COMM+, COMM–	Modulation voltage digital resolution				1		mV
R _{EA}	Input Impedance	Ground reference		0.5	1.5	3	MΩ
I _{OFFSET}	Input offset current	1-kΩ source impedance		–5		5	μA
ANALOG INPUTS: V_SENSE, I_SENSE, T_SENSE, LED_MODE, CAL_INPUT, V_IN							
V _{ADC_OPEN}	Voltage indicating open pin	LED_MODE, CAL_INPUT open		2.37			V
V _{ADC_SHOR T}	Voltage indicating pin shorted to GND	LED_MODE, CAL_INPUT shorted to ground				0.36	
V _{ADC_RANG E}	Measurement range for voltage monitoring	All analog inputs		0		2.5	
INL	ADC integral nonlinearity			–2.5		2.5	mV
I _{lk}	Input leakage current	3 V applied to pin				100	nA
R _{IN}	Input impedance	Ground reference		8			MΩ
C _{IN}	Input capacitance					10	pF
DIGITAL INPUTS/OUTPUTS							
V _{OL}	Low-level output voltage	I _{OL} = 6 mA , V33D = 3 V				DGND1 + 0.25	V
V _{OH}	High-level output voltage	I _{OH} = –6 mA , V33D = 3 V		V33D – 0.6 V			
V _{IH}	High-level input voltage	V33D = 3 V		2.1		3.6	
V _{IL}	Low-level input voltage	V33D = 3.5 V				1.4	
I _{OH} (MAX)	Output high-source current					4	mA
I _{OL} (MAX)	Output low-sink current					4	
SYSTEM PERFORMANCE							
V _{RESET}	Voltage where device comes out of reset	V33D pin				2.4	V
t _{RESET}	Pulse duration needed for reset	RESET pin		2			μs
f _{SW}	Switching frequency (wireless power transfer)	System input power at startup	> 6 V		130		kHz
			< 6 V		110		
			< 6 V, HVD _{CP} to 9 or 12 V		130		
t _{detect}	Time to detect presence of device requesting power					0.5	s
Write_Cycles	Number of nonvolatile erase/write cycles	T _J = 25°C		20			k cycles
PWM RAIL							
f _{SW_RAIL}	Switching frequency				4 * f _{SW}		kHz

7.6 Typical Characteristics



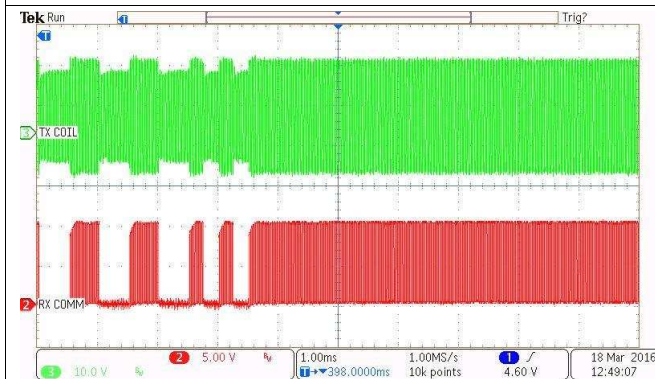
CH2 = PWM-A (1 V / Division)
CH3 = PWM-B (1 V / Division)

Figure 1. Typical PWM-A and PWM-B Signals



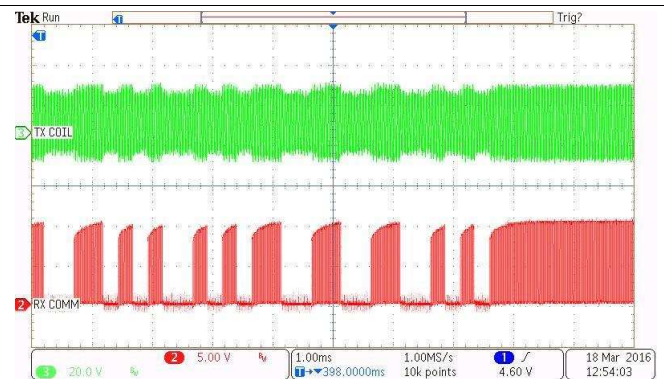
CH2 = RX communication signal (5 V / Division)
CH3 = TX coil voltage (10 V / Division)

Figure 2. TX Coil and RX Communication Signals With RX No Load



CH2 = RX communication signal (5 V / Division)
CH3 = TX coil voltage (10 V / Division)

Figure 3. TX Coil and RX Communication Signals With RX 5-W Load



CH2 = RX communication signal (5 V / Division)
CH3 = TX coil voltage (20 V / Division)

Figure 4. TX Coil and RX Communication Signals With RX 15-W Load

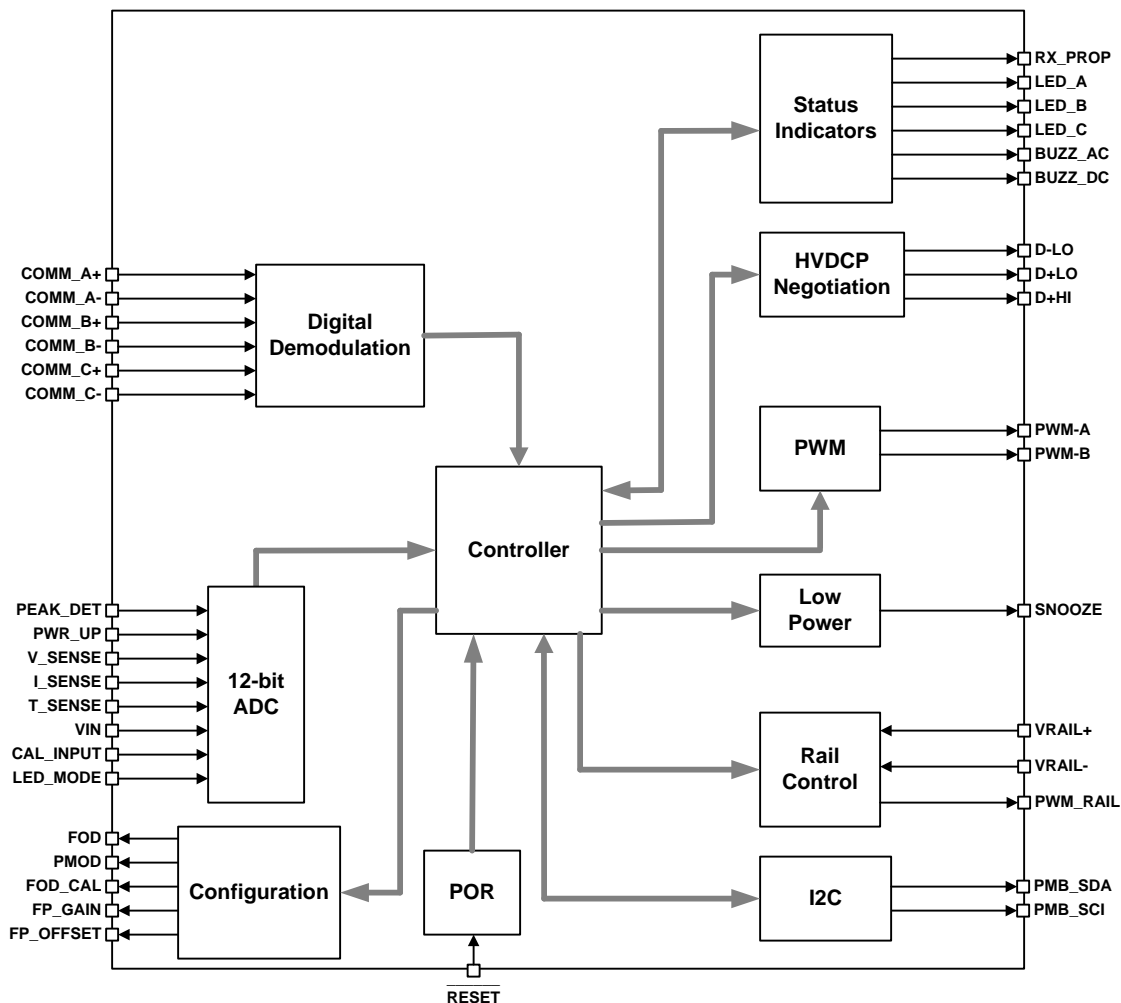
8 Detailed Description

8.1 Overview

The principle of wireless power transfer is simply an open-cored transformer consisting of transmitter and receiver coils. The transmitter coil and electronics are typically built into a charger pad and the receiver coil and electronics are typically built into a portable device, such as a cell phone. When the receiver coil is positioned on the transmitter coil, magnetic coupling occurs when the transmitter coil is driven. The flux is coupled into the secondary coil, which induces a voltage and current flows. The secondary voltage is rectified, and power can be transferred effectively to a load, wirelessly. Power transfer can be managed through any of the various closed-loop control schemes.

After power is applied and the device comes out of reset, it can automatically begin the process of detecting and powering a receiver. The bq501210 sends a ping to detect the presence of a receiver on the pad. After a receiver is detected, the bq501210 attempts to establish communication and begin power transfer. If the transmitter detects a v1.2 medium power WPC compliant receiver, it negotiates a maximum power with the receiver and provides the requested power (up to 15 W). If the transmitter detects the bq51025 receiver through its proprietary authentication protocol, the transmitter allows 10-W operation. If a standard 5-W WPC compliant receiver is detected, the transmitter allows 5-W of delivered power as per WPC specification. The bq501210 controls a full-bridge power stage to drive the primary coil. It regulates the power being delivered to the receiver by modulating the supply voltage of the power stage while operating at a constant frequency. The full bridge power stage allows for higher power delivery for a given supply voltage.

8.2 Functional Block Diagram



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8.3 Feature Description

8.3.1 MP-A5 Coil Specification

The bq501210 controller supports MP-A5 TX coil type. The coil and matching capacitor specification for MP-A5 transmitter has been established by the WPC Standard. This is fixed and cannot be changed on the transmitter side.

For a current list of coil vendors, see *bqTESLA Transmitter Coil Vendors*, [SLUA649](#).

8.3.2 High Voltage Dedicated Charging Port (HVDCP) Negotiation

If the system input voltage is detected to be < 6 V at startup, the bq501210 attempts to negotiate for higher input voltage.

8.3.3 Fast Charge Support

The bq501210 attempts to negotiate with receiver devices supporting Fast Charge operation to provide additional power for rapid charging.

8.3.4 Option Select Pins

There are two option select pins (pin 60, CAL_INPUT, and pin 61, LED_MODE) on the bq501210 and five selector outputs (pins 19, 20, 22, 23, and 24) used to read multiple voltage thresholds. All the pin voltages will be read by bq501210 at power-up.

- Pin 60 (CAL_INPUT) is used to program the FOD algorithms.
- Pin 61 (LED_MODE) is used to select the LED mode of the device.
- Pins 19, 20, 22, 23, and 24 are used to sequentially bias the five programming resistors shown in [Figure 5](#).

At power-up, a bias current is applied to pins LED_MODE and CAL_INPUT, and the resulting voltage is measured to identify the value of the attached programming resistor. For LED_MODE, the selected bin determines the LED behavior based on [Table 3](#). For the CAL_INPUT, the FP_GAIN, FP_OFFSET, FOD_CAL, FOD and PMOD pins are biased sequentially to measure each pins resistance. The selected bin sets various calibration parameters based on [Table 1](#). See [FOD and Parasitic Metal Object Detect \(PMOD\) Calibration](#) for more information.

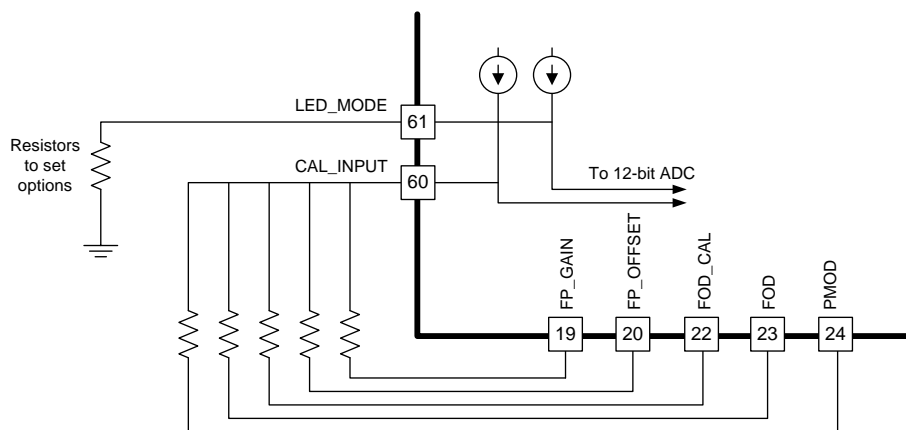


Figure 5. Pin Connections for CAL_INPUT and LED_MODE

8.3.5 FOD and Parasitic Metal Object Detect (PMOD) Calibration

The bq501210 supports multiple levels of protection against heating metal objects placed in the magnetic field. An initial analysis of the impulse response to a short ping (FOD ping) detects most metal objects before any power transfer is initiated. If a foreign metallic object is detected by the FOD ping, an FOD warning is issued (see [Table 3](#)) for up to 6 seconds after the object is removed. If a potential foreign object is detected, the bq501210 transmitter will postpone the FOD determination until the receiver sends the WPC standard "FOD Status Packet" during WPC v1.2 negotiations. After power transfer has started, improved FOD (WPC v1.2) and enhanced

Feature Description (continued)

PMOD (WPC v1.0) features continuously monitor input power, known losses, and the value of power reported by the RX device being charged. Using these inputs, the bq501210 can estimate how much power is unaccounted for and presumed lost due to metal objects placed in the wireless power transfer path. If this unexpected loss exceeds the threshold set by the FOD or PMOD resistors, a fault is indicated and power transfer is halted. The ID packet of the receiver being charged determines whether the FOD or PMOD algorithm is used. The ultimate goal of the FOD feature is safety, to protect misplaced metal objects from becoming hot. Reducing the loss threshold and making the system too sensitive leads to false trips and a bad user experience. Find the balance which best suits the application. If the application requires disabling one function or the other (or both), it is possible by leaving the respective FOD/PMOD terminal open. For example, to selectively disable the PMOD function, PMOD should be left open. A final level of protection is provided with an optional temperature sensor to detect any large increase in temperature in the system (see [Shut Down Through External Thermal Sensor or Trigger](#)).

NOTE

Disabling FOD results in a TX solution that is not WPC v1.1 or WPC v1.2 compliant.

Resistors of 1% tolerance should be used for a reliable selection of the desired threshold. Resistors on the FOD and PMOD pins program the permitted power loss for the FOD and PMOD algorithms respectively. The FOD_CAL resistor can be used to compensate for any load-dependent effect on the power loss. Using a calibrated FOD reference receiver with no foreign objects present, the FOD_CAL resistor should be selected such that the calculated loss across the load range is substantially constant (within approximately 100 mW). After correcting for the load dependence, the FOD and PMOD thresholds should be re-set above the resulting average by approximately 400 mW for the transmitter to satisfy the WPC requirements on tolerated heating.

Contact TI for the TX tuning tool to set appropriate FOD, PMOD, and FOD_CAL resistor values for your design.

Table 1. Option Select Bins

Bin Number	Resistance (k Ω)	Loss Threshold (mW)
0	<36.5	250
1	42.2	300
2	48.7	350
3	56.2	400
4	64.9	450
5	75.0	500
6	86.6	550
7	100	600
8	115	650
9	133	700
10	154	750
11	178	800
12	205	850
13	>237	Feature disabled

8.3.6 FOD Ping Calibration

The bq501210 is able to detect most metal objects in the charging pad by analyzing the impulse response to a short ping (FOD ping) sent before any power transfer is initiated. The bq501210 does this analysis by measuring the change in resonant frequency and decay of the pulse response and comparing it to given threshold values that are set by resistor in FP_GAIN and FP_OFFSET pins.

Resistors of 1% tolerance should be used for a reliable selection of the desired threshold. The FP_GAIN and FP_OFFSET resistors program the boundary conditions to determine if a receiver or a metal object is detected. The recommended resistor value for both FP_GAIN and FP_OFFSET pins is 86.6 kΩ.

Contact TI for inquiries regarding FOD ping calibration.

NOTE

Removing resistors from FP_OFFSET and FP_GAIN pins disables FOD ping and hence foreign object detection prior to power transfer. The Received Power calibration relies on this detection, and thus, the FOD ping is required for WPC v1.2 Medium Power transmitter designs.

8.3.7 Shut Down Through External Thermal Sensor or Trigger

Typical applications of the bq501210 do not require additional thermal protection. This shutdown feature is provided for enhanced applications and is not limited to thermal shutdown. The key parameter is the 1-V threshold on the T_SENSE pin. A voltage below 1 V on T_SENSE causes the device to shut down.

The application of thermal monitoring through a negative temperature coefficient (NTC) sensor, for example, is straightforward. The NTC forms the lower leg of a temperature-dependant voltage divider. The NTC leads are connected to the bq501210 device between T_SENSE and GND. The threshold on T_SENSE is set to 1 V, below which the system shuts down and a fault is indicated (depending on LED mode chosen).

To implement this feature follow these steps:

1. Consult the NTC data sheet and find the resistance versus temperature curve.
2. Determine the actual temperature where the NTC will be placed by using a thermal probe.
3. Read the NTC resistance at that temperature in the NTC data sheet, that is R_NTC.
4. Use the following formula to determine the upper leg resistor (R_Setpoint):

$$R_Setpoint = 2.3 \times R_NTC \quad (1)$$

The system restores normal operation after approximately five minutes or if the receiver is removed. If the feature is not used, this pin must be pulled high (typically to V33A).

NOTE

T_SENSE must always be terminated; otherwise, erratic behavior may occur.

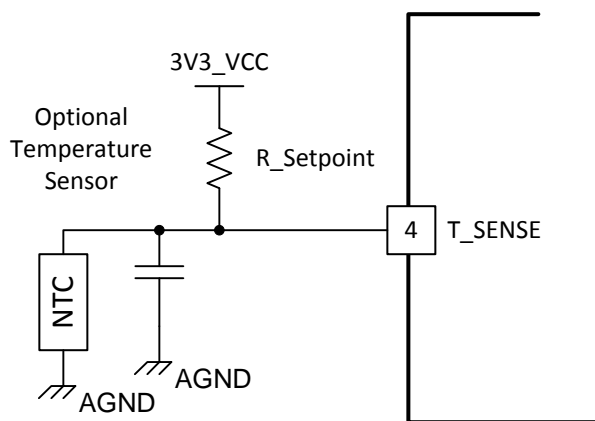


Figure 6. NTC Application

8.3.8 Fault Handling and Indication

Table 2 shows end power transfer (EPT) packet responses, fault conditions, and the duration of how long the condition lasts until a retry is attempted. The LED mode selected determines how the LED indicates the condition or fault.

Table 2. Fault Handling and Indication

CONDITION	TYPICAL DURATION ⁽¹⁾ (BEFORE RETRY)	HANDLING
EPT-00	Immediate ⁽²⁾	Unknown
EPT-01	up to 5 seconds ⁽³⁾	Charge complete
EPT-02	Infinite	Internal fault
EPT-03	5 minutes	Over temperature
EPT-04	Immediate ⁽²⁾	Over voltage
EPT-05	Immediate ⁽²⁾	Over current
EPT-06	Infinite	Battery failure
EPT-07	Not applicable	Reserved
EPT-08	Immediate ⁽²⁾	No response
EPT-09	Not applicable	Reserved
EPT-0A	Immediate	Negotiation Failure
EPT-0B	Immediate	Restart Power Transfer
OVP (over voltage)	Immediate ⁽²⁾	
OC (over current)	1 minute	
NTC (external sensor)	5 minutes	
PMOD/FOD warning	6 seconds	0 to 4 seconds LED only, 4 to 6 seconds LED + AC and DC buzzers
PMOD/FOD	5 minutes	

- (1) After a FAULT, the magnetic field is recharacterized to improve the ability to detect the removal of the at-fault receiver. If the receiver is removed in the first second immediately following the detection of this fault (before the re-characterization is complete), the field corresponding to an empty pad may be associated with the faulty receiver and the LED indication may continue to indicate a fault state even though no receiver is present. This indication persists until either the HOLDOFF time expires or a new receiver disturbs the field, at which time normal operation, with proper LED indication, is resumed.
- (2) Immediate is <1 s.
- (3) The TX may retry immediately (<1 s) to start power after first EPT-01 is received. If the receiver is continuously sending EPT-01, the TX holdoff time will be 5 seconds

8.3.9 Power Transfer Start Signal

The bq501210 features two signal outputs to indicate that power transfer has begun. BUZZ_AC outputs a 400-ms duration, 4-kHz square wave for driving low cost AC type ceramic buzzers. BUZZ_DC outputs logic high, also for 400-ms, which is suitable for DC type buzzers with built-in tone generators, or as a trigger for any type of customized indication scheme. Do not exceed 4-mA loading from either of these pins which is more than adequate for small signaling and actuation. If not used, these pins should be left open.

8.3.10 Power-On Reset

The bq501210 has an integrated power-on reset (POR) circuit which monitors the supply voltage and handles the correct device startup sequence. Additional supply voltage supervisor or reset circuits are not needed.

8.3.11 External Reset, $\overline{\text{RESET}}$ Pin

The bq501210 can be forced into a reset state by an external circuit connected to the $\overline{\text{RESET}}$ pin. A logic low voltage on this pin holds the device in reset. For normal operation, this pin is pulled up to 3.3-V supply (V33A) with a 10-k Ω pullup resistor.

8.3.12 Trickle Charge and CS100

The WPC specification provides an EPT message (EPT-01) to indicate charge complete. Upon receipt of the charge complete message, the bq501210 disables the output and changes the LED indication. The exact indication depends on the LED_MODE chosen.

In some battery charging applications, there is a benefit to continue the charging process in trickle-charge mode to top off the battery. The WPC specification provides for an informational 'Charge Status' packet that conveys the level of battery charger. The bq501210 uses this command to enable top-off charging. The bq501210 changes the LED indication to reflect charge complete when a Charge Status message is 100% received, but unlike the response to an EPT, it will not halt power transfer while the LED indicates charge complete. The mobile device can use a CS100 packet to enable trickle charge mode.

If the reported charge status drops below 90%, normal charging indication is resumed.

8.4 Device Functional Modes

8.4.1 LED Modes

The bq501210 can directly drive three LED outputs (LED-A, LED-B, and LED-C, refer to the table in [Pin Configuration and Functions](#)) through a simple current limit resistor (typically 475 Ω), based on the mode selected. The three current limit resistors can be individually adjusted to tune or match the brightness of the LEDs. Do not exceed the maximum output current rating of the device.

The selection resistor, connected between pin 61 and GND, selects one of the desired LED indication schemes presented in [Table 3](#). Note that some options require fewer LEDs to implement than others.

Table 3. LED Modes

LED CONTROL OPTION	LED SELECTION RESISTOR	LED	OPERATIONAL STATES					
			STANDBY	POWER TRANSFER	CHARGE COMPLETE	FAULT	FOD Warning	High Power Transfer ⁽¹⁾
0	<36.5 k Ω	LED_A	LED CONTROL OPTION 0 disables SNOOZE - Used in system debug only.					
		LED_B						
		LED_C						
1	42.2 k Ω	LED_A	Off	Blink slow ⁽²⁾	On	Off	Off	Blink fast ⁽³⁾
		LED_B	Off	Off	Off	On	Blink fast ⁽³⁾	Off ⁽³⁾
		LED_C	—	—	—	—	—	—
2	48.7 k Ω	LED_A	On	Blink slow ⁽²⁾	On	Off	Off	Blink fast ⁽³⁾
		LED_B	On	Off	Off	On	Blink fast ⁽³⁾	Off ⁽³⁾
		LED_C	—	—	—	—	—	—
3 ⁽⁴⁾	56.2 k Ω	LED_A	Off	On	Off	Blink fast ⁽³⁾	On	On
		LED_B	—	—	—	—	—	—
		LED_C	—	—	—	—	—	—
4	64.9 k Ω	LED_A	Off	On	Off	Off	Off	On
		LED_B	Off	Off	Off	On	Blink fast ⁽³⁾	Off
		LED_C	—	—	—	—	—	—
5	75 k Ω	LED_A	Off	Off	On	Off	Off	Off
		LED_B	Off	On	Off	Off	On	On
		LED_C	Off	Off	Off	Blink slow ⁽²⁾	Off	Off
6	86.6 k Ω	LED_A	Off	Blink slow ⁽²⁾	On	Off	Off	Blink fast ⁽³⁾
		LED_B	Off	Off	Off	On	Blink fast ⁽³⁾	Off
		LED_C	Off	Off	Off	Off	Off	Off
7	100 k Ω	LED_A	Off	Blink slow ⁽²⁾	Off	Off	Off	Blink fast ⁽³⁾
		LED_B	Off	Off	On	Off	Off	Off
		LED_C	Off	Off	Off	On	Blink fast ⁽³⁾	Off
8	115 k Ω	LED_A	Off	Off	On	Blink slow ⁽²⁾	Off	Off
		LED_B	Off	On	Off	Blink slow ⁽²⁾	On	On
		LED_C	—	—	—	—	—	—
9	133 k Ω	LED_A	Off	Blink slow ⁽²⁾	On	Off	Off	Blink fast ⁽³⁾
		LED_B	Off	OFF	Off	On	Blink fast ⁽³⁾	Off
		LED_C	—	—	—	—	—	—
10	154 k Ω	LED_A	Off	On	Off	Blink fast ⁽³⁾	On	On
		LED_B	Off	Off	On	Off	Off	Off
		LED_C	—	—	—	—	—	—

(1) Power transfer when operating with bq51025 wireless power receiver in 10-W mode.

(2) Blink slow = 0.625 Hz

(3) Blink fast = 2.5 Hz

(4) The indication of the shutdown after an negative temperature coefficient (NTC) event may experience a delay in the rapid LED blinking even though the power transfer has been disabled. The indication delay may persist up to as long as the entire NTC FAULT holdoff time.

8.4.2 Power Transfer

Power transfer depends on coil coupling. Coupling depends on the distance between coils, alignment, coil dimensions, coil materials, number of turns, magnetic shielding, impedance matching, frequency, and duty cycle.

Most importantly, the receiver and transmitter coils must be aligned for best coupling and efficient power transfer. The smaller the space between the coils, the better the coupling.

Shielding is added as a backing to both the transmitter and receiver coils to direct the magnetic field to the coupled zone. Magnetic fields outside the coupled zone do not transfer power. Thus, shielding also serves to contain the fields to avoid coupling to other adjacent system components.

Regulation can be achieved by controlling any one of the coil coupling parameters. However, for WPC v1.2 compatibility, the transmitter-side coils and capacitance are specified and the resonant frequency point is fixed. Power transfer is regulated by changing the supply voltage to the full-bridge power stage; higher voltage delivers more power. Duty cycle remains constant at 50% throughout the power band and frequency also remains constant at 130 kHz.

The WPC standard describes the dimensions, materials of the coils, and information regarding the tuning of the coils to resonance. The value of the inductor and resonant capacitor are critical to proper operation and system efficiency.

8.4.3 Communication

Most communication within the WPC is from the receiver to the transmitter, where the receiver tells the transmitter to send power and how much. To regulate, the receiver must communicate with the transmitter whether to increase or decrease the power level. The receiver monitors the rectifier output and using amplitude modulation (AM), sends packets of information to the transmitter. A packet is comprised of a preamble, a header, the actual message, and a checksum, as defined by the WPC standard.

The receiver sends a packet by modulating an impedance network. This AM signal reflects back as a change in the voltage amplitude on the transmitter coil. The signal is demodulated and decoded by the transmitter-side electronics and the voltage on the inverter is adjusted to close the regulation loop. The bq501210 features internal digital demodulation circuitry.

The modulated impedance network on the receiver can either be resistive or capacitive. [Figure 7](#) shows the resistive modulation approach, where a resistor is periodically added to the load, and the resulting amplitude change in the transmitter voltage. [Figure 8](#) shows the capacitive modulation approach, where a capacitor is periodically added to the load and the resulting amplitude change in the transmitter voltage.

In the WPC v1.2 specification, transmitter to receiver communication is introduced to allow a medium power receiver to negotiate for higher power while maintaining backward compatibility with low power (v1.1) devices.

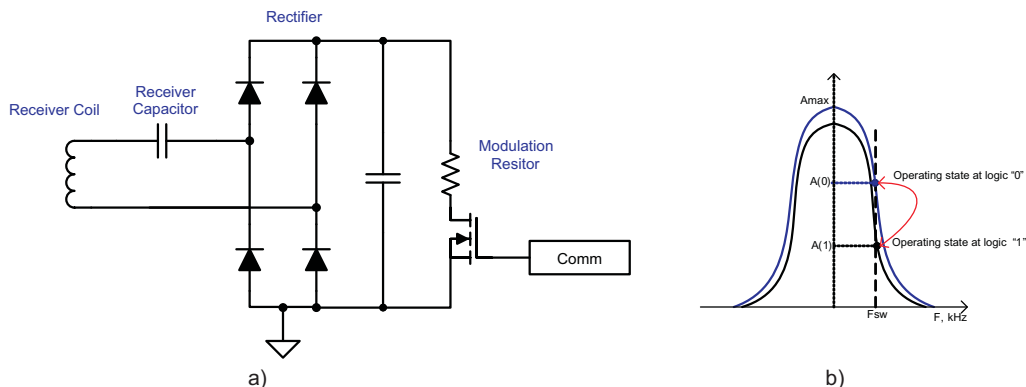


Figure 7. Receiver Resistive Modulation Circuit

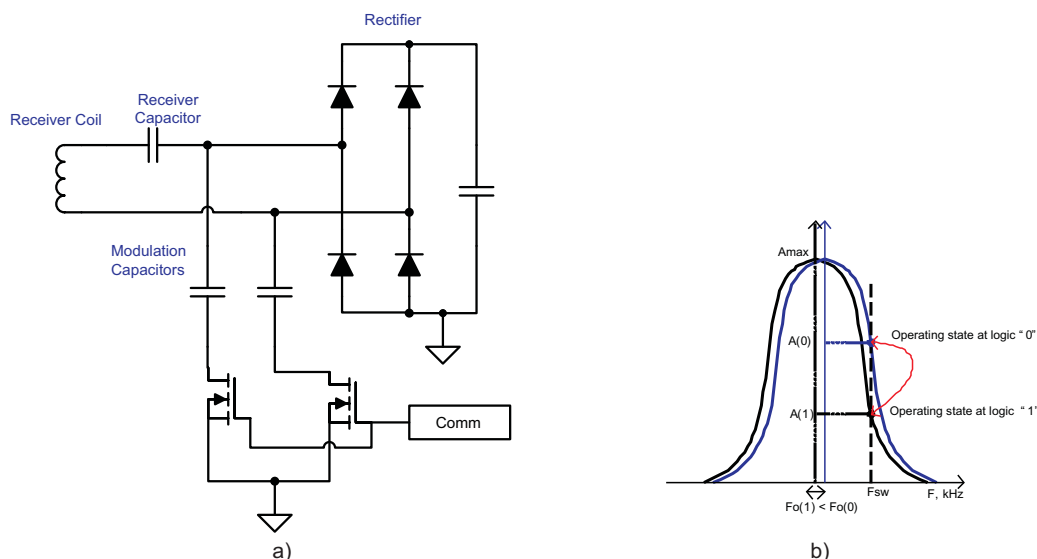


Figure 8. Receiver Capacitive Modulation Circuit

The bq501210 also supports a proprietary handshake with the bq51025 in which minimal communication from the TX to the RX is used. This proprietary handshake enables the bq501210 to deliver power to the bq51025 receiver at levels higher than 5 W. The transmitter-to-receiver communication is achieved through frequency modulation of the power signal.

8.4.4 Power Trains

The bq501210 drives a full-bridge power stage, which drives the coil assembly. TI recommends the bq500101 (SLPS585) as the driver-plus-MOSFET device for this application. The supply voltage (Vrail) is controlled by the bq501210 device.

8.4.5 Power Train Voltage Control

The bq501210 controls power delivery by modulating the supply voltage (Vrail) of the power stage driving the coil assembly. The bq501210 device generates a PWM control signal in the PWM_RAIL terminal that controls an external power stage circuit (TI recommends bq500101). The switching frequency for this DC-DC controller signal is 520 kHz.

8.4.6 Signal Processing Components

The COMM signal used to control power transfer is derived from the coil voltage. The AC coupled coil voltage is scaled down to a manageable level and biased to a 1-V offset. Series connected diodes are provided for protection from any possible transients.

9 Application and Implementation

NOTE

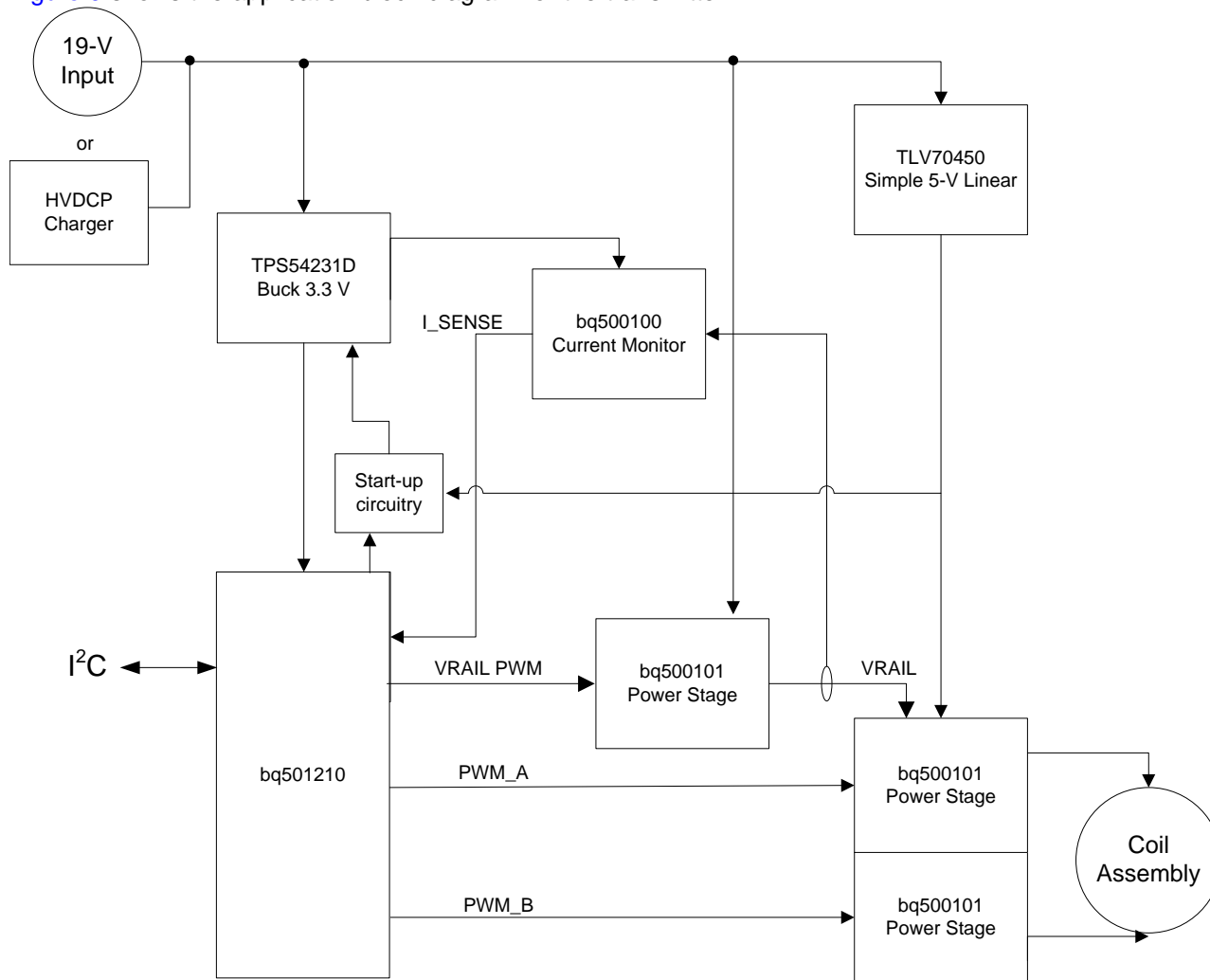
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The bq501210 device is a wireless power transmitter controller designed for 15-W WPC compliant applications and 5-W applications with WPC v1.1 low power receivers. It integrates all functions required to control wireless power transfer to a WPC v1.2 compliant receiver. Several tools are available for the design of the system. See the product folder (www.ti.com/product/bq501210) for more details. The following sections highlight some of the system design considerations.

9.2 Typical Application

Figure 9 shows the application block diagram for the transmitter.



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Figure 9. bq501210 System Diagram

Typical Application (continued)

9.2.1 Design Requirements

Table 4. Design Parameters

DESIGN PARAMETER	VALUE
WPC coil type	MP-A5
Input voltage	15 V to 19 V provides full 15-W operation. HVDCP negotiated 9 V or 12 V provides < 15 W 5 V provides up to 4.5 W

9.2.2 Detailed Design Procedure

9.2.2.1 Capacitor Selection

Capacitor selection is critical to proper system operation. The total capacitance value of $2 \times 100 \text{ nF} + 47 \text{ nF}$ is required in the resonant tank. This is the WPC system compatibility requirement, not a guideline.

NOTE

A total capacitance value of $2 \times 100 \text{ nF} + 47 \text{ nF}$ (C0G dielectric type, 100-V rating) is required in the resonant tank to achieve the correct resonance frequency.

The capacitors chosen must be rated for at least 100 V and must be of a high-quality C0G dielectric (sometimes also called NP0). These are typically available in a 5% tolerance, which is adequate. TI does not recommend the use of X7R types or below if WPC compliance is required because critical WPC Certification Testing, such as the minimum modulation or guaranteed power test, might fail.

The designer can combine capacitors to achieve the desired capacitance value. Various combinations can work depending on market availability. All capacitors must be of C0G types (not mixed with any other dielectric types).

9.2.2.2 Current Monitoring Requirements

The bq501210 is WPC v1.2 ready. To enable the PMOD or FOD features, provide current monitoring in the design.

For proper scaling of the current monitor signal, the current sense resistor should be $20 \text{ m}\Omega$ and the current shunt amplifier should have a gain of 50, such as the bq500100 ([SBOS765](#)). For FOD accuracy, the current sense resistor must be a quality component with 0.5% tolerance, at least 1/4-W rating, and a temperature stability of $\pm 200 \text{ PPM}$. Proper current sensing techniques in the application hardware should also be observed.

9.2.2.3 All Unused Pins

All unused pins can be left open unless otherwise indicated. Refer to the table in [Pin Configuration and Functions](#). To improve PCB layout, ground unused pins, if it is an option.

9.2.2.4 Input Regulators

The bq501210 requires $3.3 \text{ V}_{\text{DC}}$ to operate. A buck converter is used to step down from the supply voltage, such as the TPS54231D used in this design.

9.2.2.5 Input Power Requirements

The bq501210 system works with 5-V to 19-V input voltage. Levels between 15 V and 19 V will deliver 15 W, which is required for a WPC Extended Power Profile (EPP) transmitter.

5-V input supplies are aimed to negotiate to HVDCP voltages of 9 V or 12 V which enables Fast Charging of capable receivers. The system may also deliver power as a normal 5-V transmitter, however, the power level will be reduced and providing power to higher voltage receivers may not be successful. A typical 5-V receiver has shown to produce 4.5 W consistently. Coupling and other factors will greatly influence the results of each system.

9.2.2.6 LED Mode

The bq501210 can directly drive three LED outputs (LED-A, LED-B, and LED-C). Select one of the desired LED indication schemes by choosing the selection resistor connected between LED_MODE and GND.

9.2.3 Application Curves

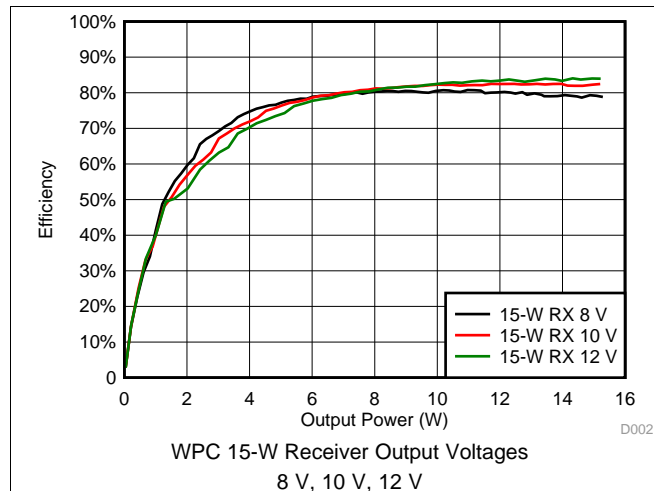


Figure 10. bq501210 System Efficiency with 15-W RX

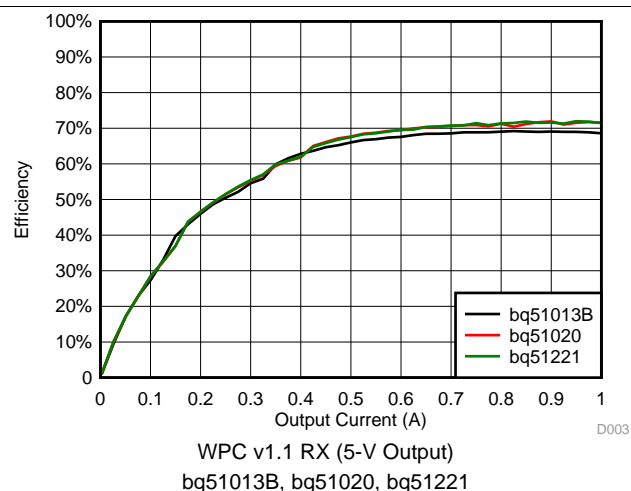


Figure 11. bq501210 + v1.1 RX System Efficiency

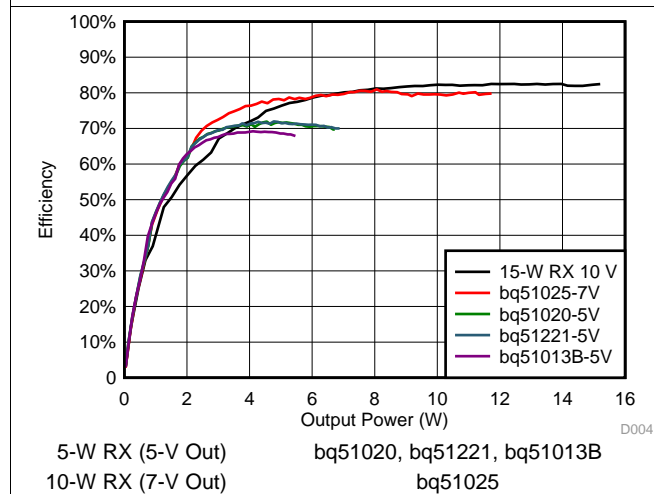


Figure 12. System Efficiency Comparison: 15-W WPC v1.2 RX and Multiple WPC v1.1 RX

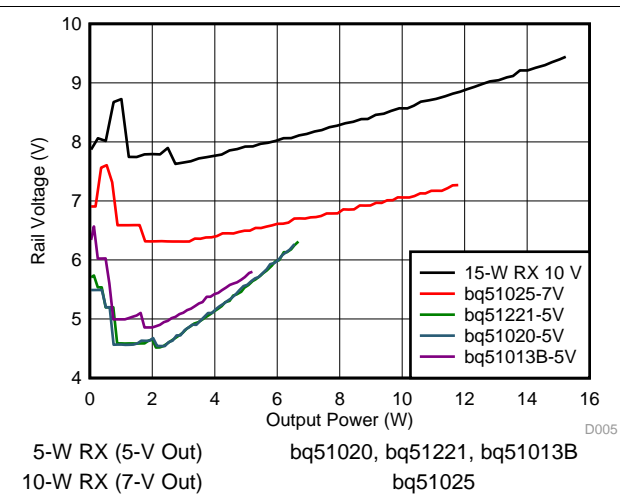


Figure 13. VRAIL Voltage Level vs WPC RX Load

10 Power Supply Recommendations

This device is designed to operate from an input voltage supply range between 3- to 3.6-V, nominal 3.3-V. The design works with 12-V to 19-V input voltage. Levels between 15 V and 19 V will deliver 15 W.

11 Layout

11.1 Layout Guidelines

Careful PCB layout practice is critical to proper system operation. Many references are available on proper PCB layout techniques. A few good tips are as follows:

The TX layout requires a 4-layer PCB layout for best ground plane technique. A 2-layer PCB layout can be achieved though not as easily. Ideally, the approach to the layer stack-up is:

- Layer 1 component placement and as much ground plane as possible
- Layer 2 clean ground
- Layer 3 finish routing
- Layer 4 clean ground

Thus, the circuitry is virtually sandwiched between grounds. This minimizes EMI noise emissions and also provides a noise-free voltage reference plane for device operation.

Keep as much copper as possible. Make sure the bq501210 GND pins and the EPAD GND power pad have a continuous flood connection to the ground plane. The power pad should also be stitched to the ground plane, which also acts as a heat sink for the bq501210. A good GND reference is necessary for proper bq501210 operation, such as analog-digital conversion, clock stability, and best overall EMI performance.

Separate the analog ground plane from the power ground plane and use only **one** tie point to connect grounds. Having several tie points defeats the purpose of separating the grounds.

The COMM return signal from the resonant tank should be routed as a differential pair. This is intended to reduce stray noise induction. The frequencies of concern warrant low-noise analog signaling techniques, such as differential routing and shielding, but the COMM signal lines do not need to be impedance matched.

The DC-DC buck regulator used from the 19-V input supplies the bq501210 with 3.3-V. Typically, the designer uses a single-chip controller solution with integrated power FET and synchronous rectifier or outboard diode. Pull in the buck inductor and power loop as close as possible to create a tight loop. Likewise, the power-train, full-bridge components should be pulled together as tight as possible. See the bq501210EVM-756 for an example of a good layout technique.

11.2 Layout Example

A DC-DC buck regulator is used to step down the system voltage to the 3.3-V supply to the bq501210. The system voltage is 19-V; with such a step-down ratio, switching duty-cycle is low and the regulator is mostly freewheeling. Therefore, place the freewheeling diode current loop as close to the switching regulator as possible and use wide traces. Place the buck inductor and power loop as close to that as possible to minimize current path.

Place 3.3-V buck regulator input bypass capacitors as close as possible to the buck IC.

Layout Example (continued)

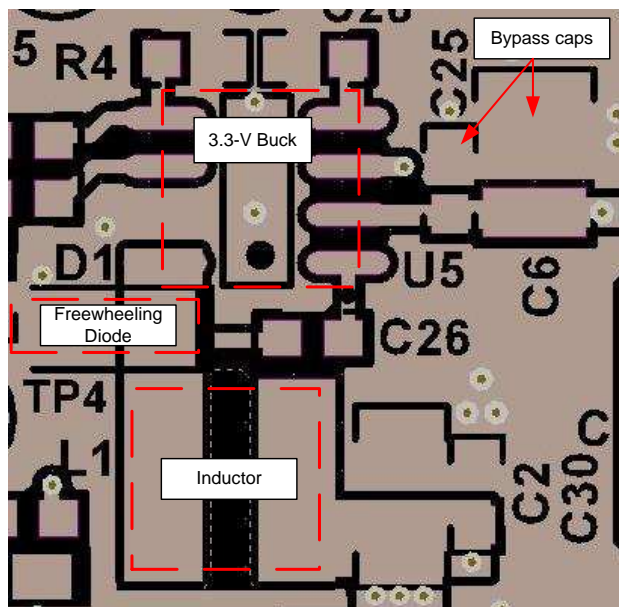


Figure 14. 3.3-V DC-DC Buck Regulator Layout

Make sure the bypass capacitors intended for the bq501210 3.3-V supply are actually bypassing these supply pins (pin 44, V33DIO, pin 45, V33D, and pin 46, V33A) to solid ground plane. This means they need to be placed as close to the device as possible and the traces must be as wide as possible.

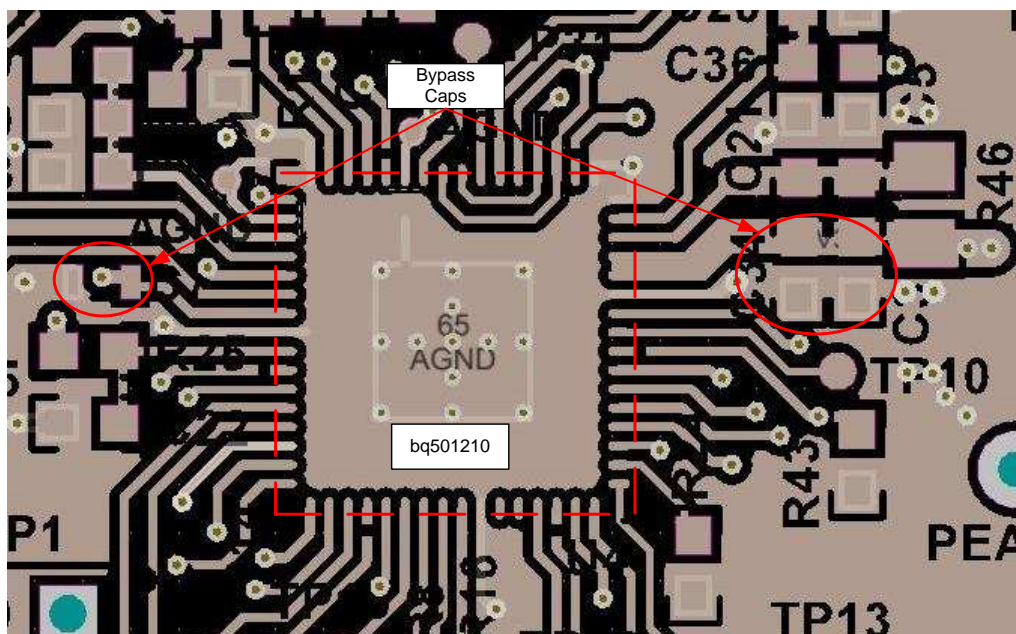


Figure 15. Bypass Capacitors Layout

Layout Example (continued)

Make sure the bq501210 has a continuous flood connection to the ground plane.

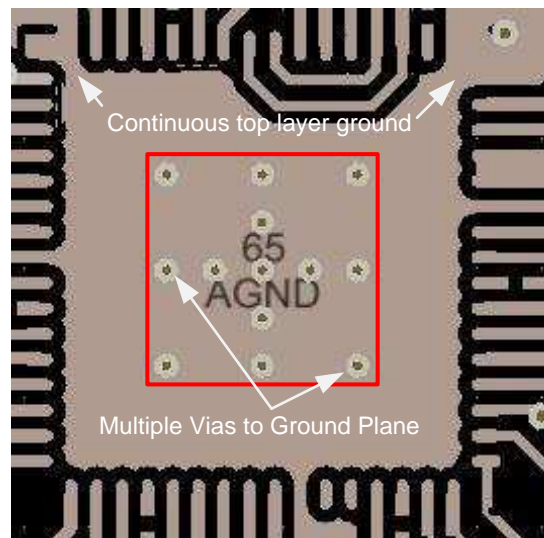


Figure 16. Continuous GND Layout

A buck regulator is used to regulate the supply voltage to the full bridge. The buck power stage IC is controlled by a PWM signal generated by the bq501210 IC, and it is directly powered from the input supply. Because the buck output voltage can operate at a wide voltage range, significant current flow is expected in both the buck power stage input and ground connections. Make sure wide traces and continuous pours are used for input and ground. Place input bypass capacitors, output capacitor and inductor as close as possible to the buck power stage to make the current loop as small as possible.

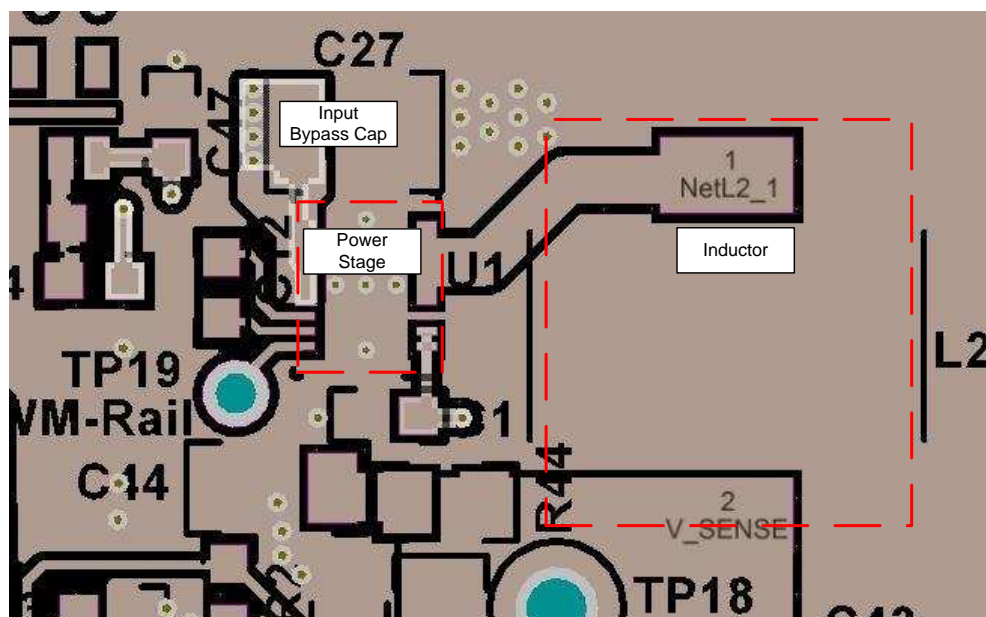


Figure 17. V_RAIL Power Stage Layout

The full-bridge power stage that drives the TX coil is composed of two half-bridge power stages and resonant capacitors. Inputs bypass capacitors should be placed as close as possible to the power stage ICs. The input and ground pours and traces should be made as wide as possible for better current flow. The trace to the coil and resonant capacitors should also be made as wide as possible.

Layout Example (continued)

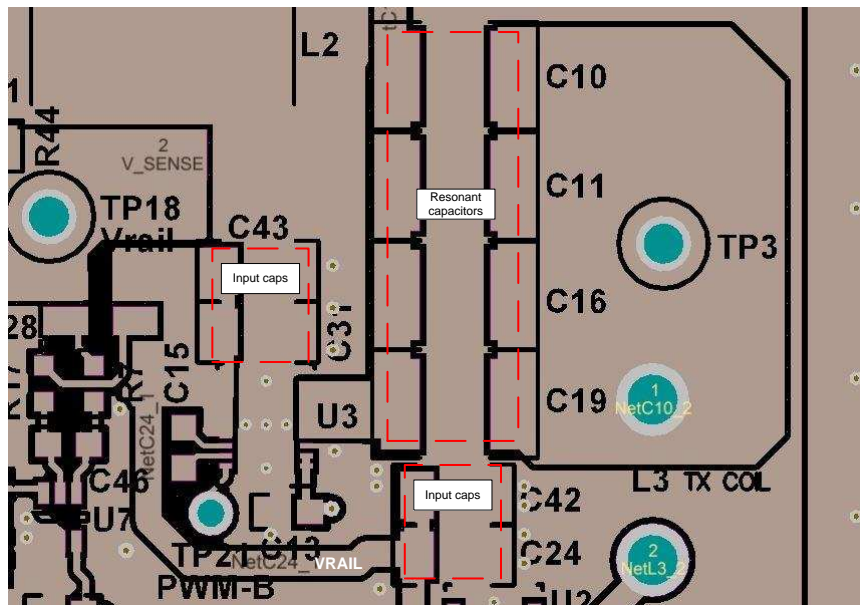


Figure 18. Ground Layout

To ensure proper operation, grounds conducting a large amount of current and switching noise must be isolated from low current, quiet grounds. Separate the ground pours for the power stages and the bq501210 IC. Connect all grounds to a single point at the main ground terminal.

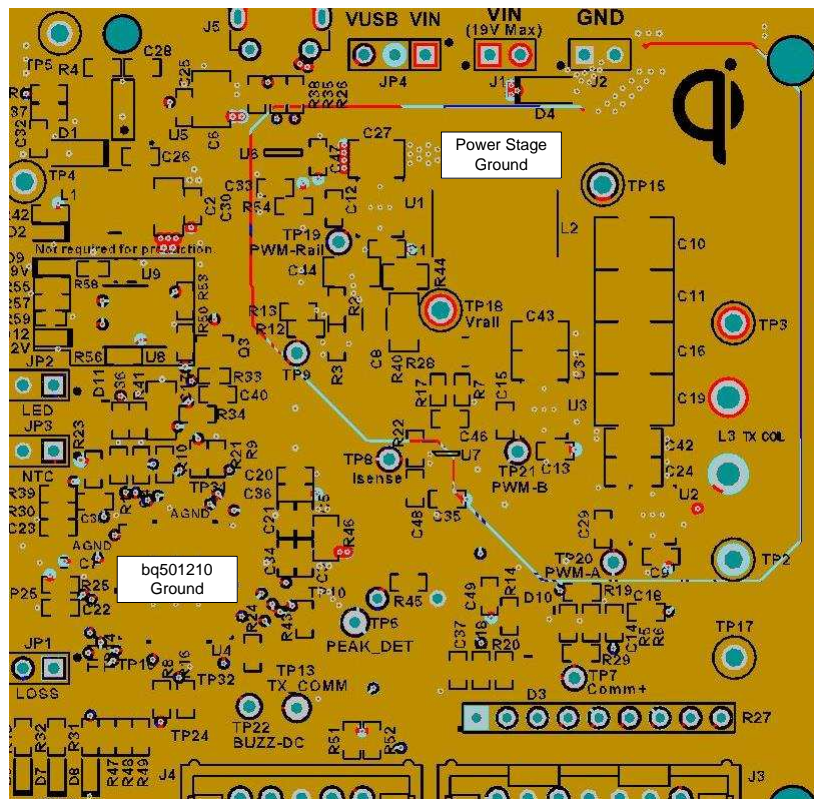


Figure 19. Ground Layout

Layout Example (continued)

Proper current sensing layout technique is very important, as it directly affects the FOD and PMOD performance. When sampling the very-low voltages generated across a current sense resistor, be sure to use the so called 4-wire or Kelvin-connection technique. This is important to avoid introducing false voltage drops from adjacent pads and copper power routes. It is a common power-supply layout technique. Some high-accuracy sense resistors have dedicated sense pins.

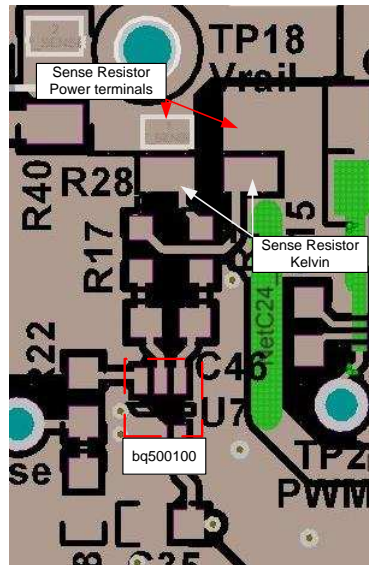


Figure 20. Current Sensing Layout

The COMM+/COMM– sense lines should be run as a balanced or differential pair. For communication, the WPC packet information runs at 2 kHz, which is essentially audio frequency content, and this balancing reduces noise pickup from the surrounding switching power electronics. The designer does not need to tune or impedance-match these lines as would be the case in RF signaling. It is important to keep this lines isolated from any fast switching signal such as PWM, to prevent noise from being injected into the line.

The V_RAIL+/VRAIL– sense lines should also run as differential pair. [Figure 21](#) shows a layout example for a differential pair layout.

Layout Example (continued)

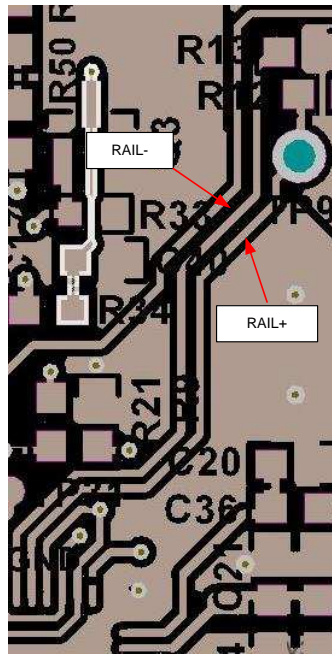


Figure 21. Balanced Differential Signal Layout

A bypass capacitor needs to be connected between the point where the 3.3-V bias supply is connected to the COMM+ resistor divider and the divider/COMM– ground connection.

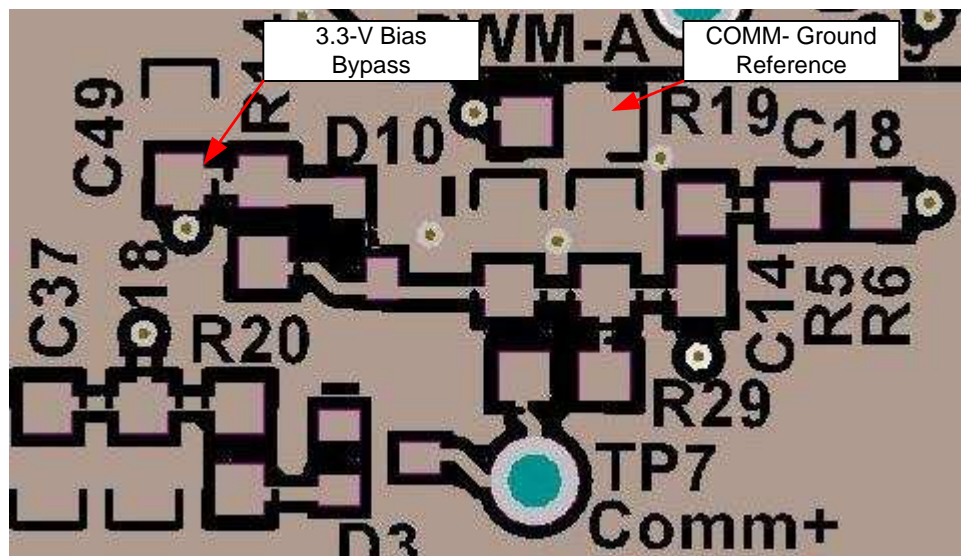


Figure 22. Bypass Capacitors Layout for COMM+ Resistor Divider 3.3-V Bias

12 器件和文档支持

12.1 器件支持

1. 技术， 无线电源联盟， www.wirelesspowerconsortium.com/
2. 数据表， 《bq51025 兼容 WPC v1.1 并专有 10W 功率输出的单芯片无线电源接收器》， [SLUSBX7](#)
3. 数据表， 《bq500100 无线充电电流监测计》， [SBOS765](#)
4. 数据表， 《bq500101 NexFET 功率级》， [SLPS585](#)
5. 数据表， 《TLV70450 24V 输入电压、150mA、超低 I_Q 低压降稳压器》， [SBVS148](#)
6. 数据表， 《TPS54231 具有 Eco-mode 的 2A、28V 输入、降压 DC-DC 转换器》， [SLUS851](#)
7. 应用手册， 《构建一个无线电源发射器》， [SLUA635](#)
8. 应用手册， 《bqTESLA 发送器线圈供应商》， [SLUA649](#)

12.2 接收文档更新通知

要接收文档更新通知，请访问 www.ti.com.cn 您器件对应的产品文件夹。点击右上角的提醒我 (Alert me) 注册后，即可每周定期收到已更改的产品信息。有关更改的详细信息，请查阅已修订文档的修订历史记录。

12.3 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

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Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

12.4 商标

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12.5 静电放电警告



这些装置包含有限的内置 ESD 保护。存储或装卸时，应将导线一起截短或将装置放置于导电泡棉中，以防止 MOS 门极遭受静电损伤。

12.6 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。这些信息是针对指定器件可提供的最新数据。这些数据会在无通知且不对本文档进行修订的情况下发生改变。欲获得该数据表的浏览器版本，请查阅左侧的导航栏。

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
BQ501210RGCR	NRND	Production	VQFN (RGC) 64	3000 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	BQ501210
BQ501210RGCR.A	NRND	Production	VQFN (RGC) 64	3000 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	BQ501210
BQ501210RGCT	NRND	Production	VQFN (RGC) 64	250 SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	BQ501210
BQ501210RGCT.A	NRND	Production	VQFN (RGC) 64	250 SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	BQ501210

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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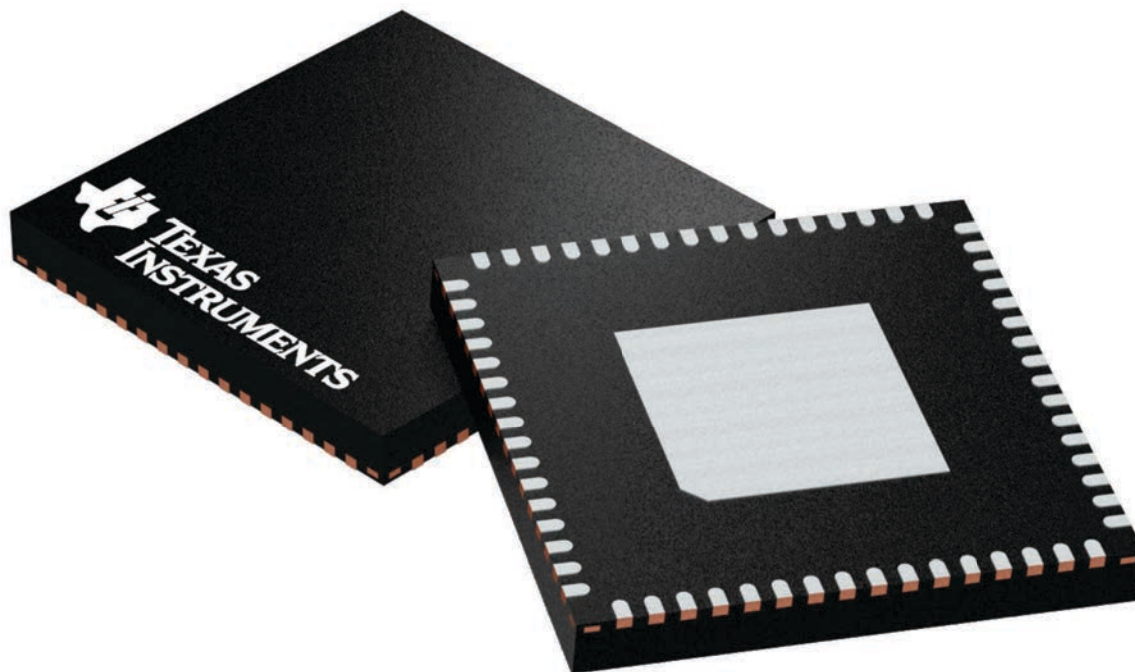
GENERIC PACKAGE VIEW

RGC 64

VQFN - 1 mm max height

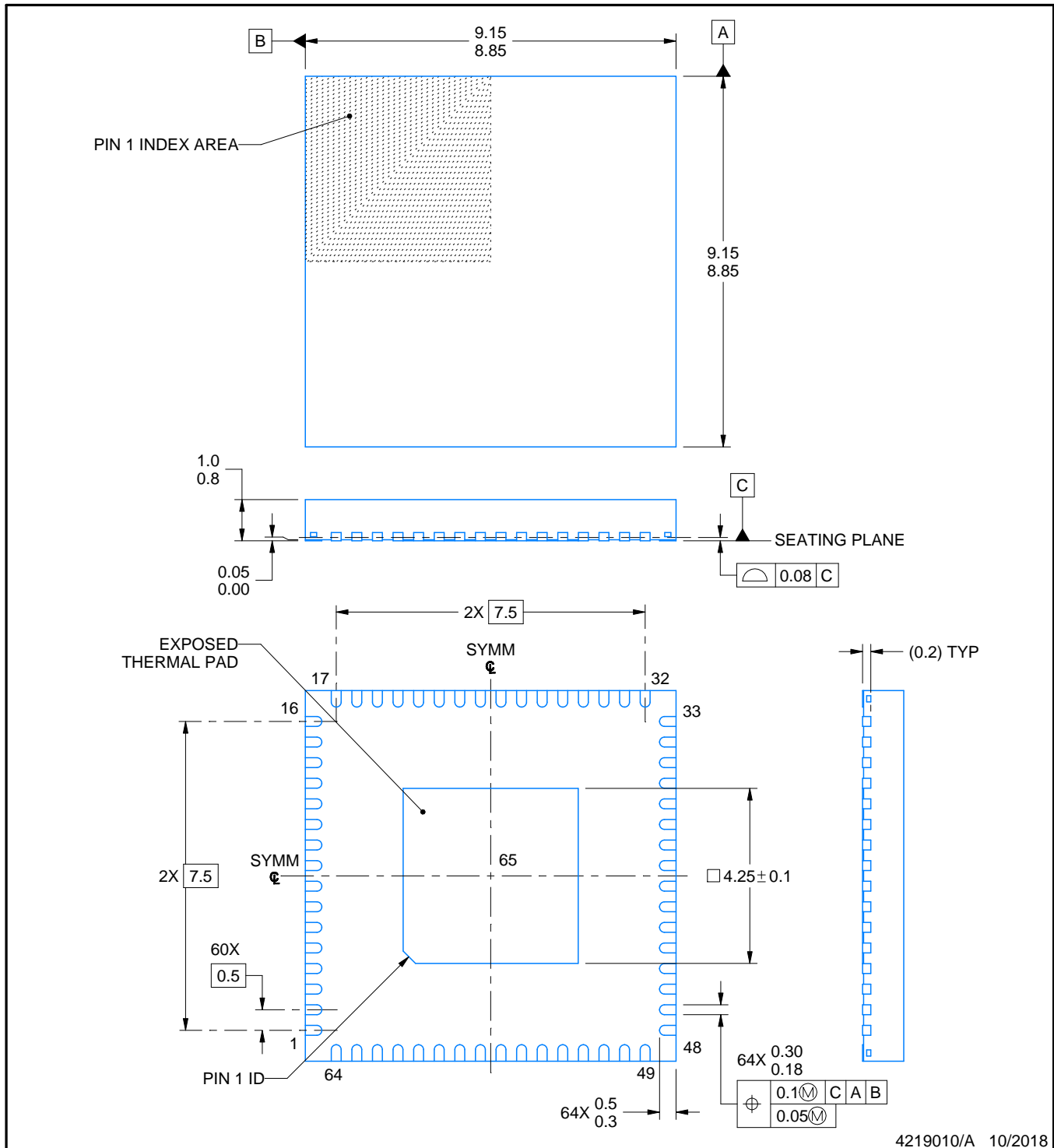
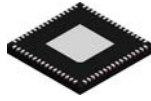
9 x 9, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4224597/A



NOTES:

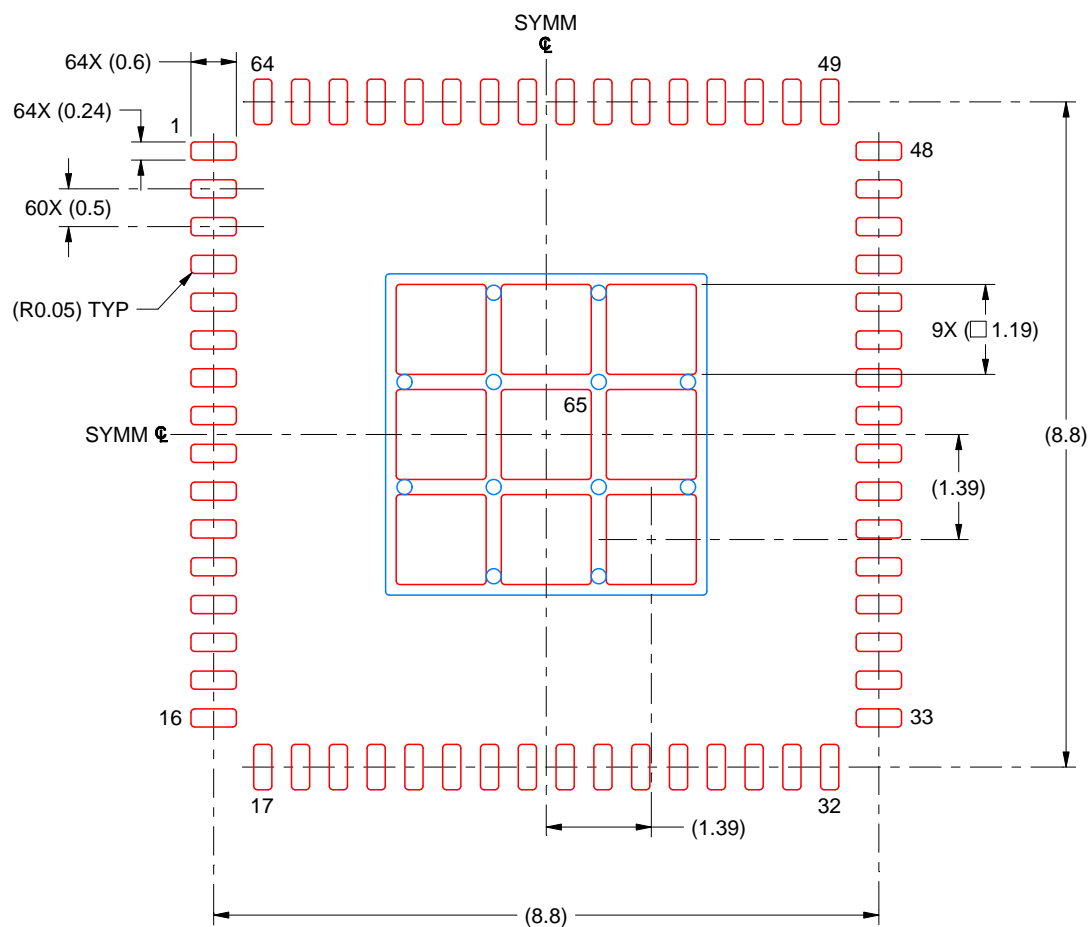
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

EXAMPLE STENCIL DESIGN

RGC0064B

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE
 BASED ON 0.125 MM THICK STENCIL
 SCALE: 10X

EXPOSED PAD 65
 71% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE

4219010/A 10/2018

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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