











**bq500511**ZHCSEA5A –AUGUST 2015–REVISED OCTOBER 2015

# bq500511 适用于 WPC v1.2 A11 发送器的

低成本 5V 无线电源发送器控制器

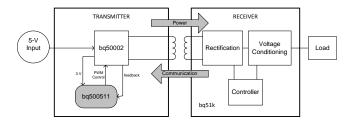
## 1 特性

- 符合无线充电联盟 v1.2 A11 规范的数字控制器
- 专为与 bq50002 模拟前端搭配使用而设计
- 适用于无线充电联盟 (WPC) 和 5V 专用无线电源发 送器
- 支持高达 5W 的接收功率
- 双芯片解决方案实现了效率超过 75% 的高效发送器设计
- 超低待机功耗,即使在数字 Ping 过程中也可实现 (< 30mW)
- 动态电源限制 (DPL)™ 通过功率受限的输入源实现 正常运行
- 系统发光二极管 (LED) 指示充电状态和故障状态
- 精准的外来物体检测方法 (FOD) 可防止发送器和接收器线圈之间的物体过热

# 2 应用

- 适用于智能手机和可穿戴应用且符合 WPC 标准的 无线充电器
- 专用无线充电器
- 医疗和工业应用
- 汽车及其他车辆配件
- 有关 TI 无线电源解决方案的更多信息,请访问 www.ti.com/wirelesspower

## 简化电路原理图



# 3 说明

bq500511 是一款无线电源发送器控制器。在与bq50002 模拟前端器件搭配使用时,该器件集成了创建符合 Qi 标准或 5V 专用发送器所需的全部功能。bq500511 和 bq50002 共同构成一款紧凑型无线充电器解决方案。bq500511 对周围环境执行 ping 操作来寻找需要供电的接收器器件,之后会与 Rx 器件安全接合、接收充电器件传输的通信数据包以及根据 WPC v1.2 规范管理功率传输。

bq500511 特有的 Dynamic Power Limiting™ (DPL) 功能可最大限度地提升无线电源控制应用的灵活性。对于功率受限的输入电源,DPL 对其可用功率进行无缝优化来改善用户体验。

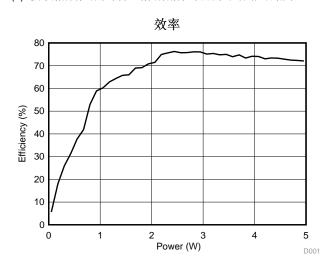
通过持续监测已建立电源传输的效率,该系统支持外来物体检测 (FOD),以防因在无线电源传输场中错误放置金属物体而产生功率损耗。 如果在电源传输过程中出现任何异常情况,bq500511 将对其进行处理并提供指示输出。 综合状态和故障监视特性可实现一款经 Qi认证的低成本且稳健耐用的无线电源系统设计方案。

bq500511 采用 6mm x 6mm 耐热增强型 40 引脚超薄四方扁平无引线 (VQFN) 封装。

器件信息(1)

| 部件号      | 封装        | 封装尺寸 (标称值)      |  |  |
|----------|-----------|-----------------|--|--|
| bq500511 | VQFN (40) | 6.00mm x 6.00mm |  |  |

(1) 要了解所有可用封装,请见数据表末尾的可订购产品附录。



A

Changes from Original (August 2015) to Revision A

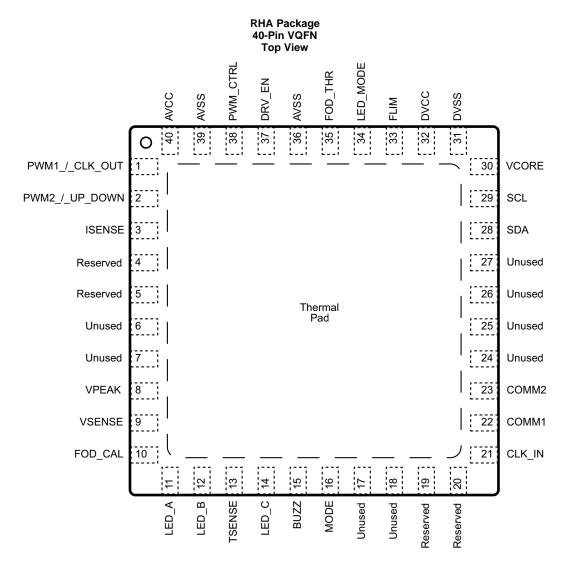
Page



| 1 | 特性1                                  |    | 7.4 Device Functional Modes    | 12              |
|---|--------------------------------------|----|--------------------------------|-----------------|
| 2 | 应用 1                                 | 8  | Application and Implementation | 14              |
| 3 | 说明 1                                 |    | 8.1 Application Information    | 14              |
| 4 | 修订历史记录 2                             |    | 8.2 Typical Application        | 14              |
| 5 | Pin Configuration and Functions3     | 9  | Power Supply Recommendations   | 18              |
| 6 | Specifications5                      | 10 | Layout                         | 18              |
|   | 6.1 Absolute Maximum Ratings 5       |    | 10.1 Layout Guidelines         | 18              |
|   | 6.2 ESD Ratings                      |    | 10.2 Layout Examples           | 19              |
|   | 6.3 Recommended Operating Conditions | 11 | 器件和文档支持                        | <mark>22</mark> |
|   | 6.4 Thermal Information6             |    | 11.1 器件支持                      | 22              |
|   | 6.5 Electrical Characteristics       |    | 11.2 文档支持                      | <mark>22</mark> |
|   | 6.6 Typical Characteristics          |    | 11.3 社区资源                      | <mark>22</mark> |
| 7 | Detailed Description 7               |    | 11.4 商标                        | 22              |
|   | 7.1 Overview                         |    | 11.5 静电放电警告                    | <u>22</u>       |
|   | 7.2 Functional Block Diagram 7       |    | 11.6 Glossary                  | 22              |
|   | 7.3 Feature Description              | 12 | 机械、封装和可订购信息                    | <mark>22</mark> |



# 5 Pin Configuration and Functions



**Pin Functions** 

| PIN     |        | 1/0 | DESCRIPTION  |
|---------|--------|-----|--|
| NAME    | NO.    | 1/0 | DESCRIPTION  |
| AVCC    | 40     | _   | Analog I power supply.   |
| AVSS    | 36, 39 | _   | Analog ground.   |
| BUZZ    | 15     | 0   | DC buzzer output. A 400-ms DC pulse when charging begins. This could also be connected to an LED via $1-k\Omega$ resistor.   |
| CLK_IN  | 21     | I   | CLK_OUT signal from the internal oscillator of the bq50002 Analog Front End.   |
| COMM1   | 22     | I   | Communication channel 1. Typically generated by the bq50002 Analog Front End.  |
| COMM2   | 23     | I   | Communication channel 2. Typically generated by the bq50002 Analog Front End.  |
| DRV_EN  | 37     | 0   | Driver enable.   |
| DVCC    | 32     | _   | Digital power supply.  |
| DVSS    | 31     | _   | Digital ground.  |
| FLIM    | 33     | I   | Leave floating to conform to the WPC specification 205-kHz maximum operating frequency. Pull down with a 10-k $\Omega$ resistor to limit the maximum frequency to 190 kHz. |
| FOD_CAL | 10     | I   | FOD calibration.   |
| FOD_THR | 35     | I   | FOD threshold.   |



# Pin Functions (continued)

| PIN               |                  |     |  |
|-------------------|------------------|-----|--|
| NAME              | NO.              | I/O | DESCRIPTION  |
| ISENSE            | 3                | ı   | Input current sense.   |
| LED_A             | 11               | 0   | Connect to a LED via 1-kΩ resistor for status indication. Typically GREEN.   |
| LED_B             | 12               | 0   | Connect to a LED via 1-kΩ resistor for status indication. Typically RED.   |
| LED_C             | 14               | 0   | Connect to a LED via 1-kΩ resistor for status indication. Typically ORANGE.  |
| LED_MODE          | 34               | I   | LED mode selection.  |
| MODE              | 16               | 0   | MODE is an output intended for use by the bq50002 Analog Front End indicating whether adjustments should be made using frequency (when MODE is low) or duty-cycle (when MODE is high).   |
| PWM1 /<br>CLK_OUT | 1                | 0   | If PWM_CTRL is high, this pin outputs PWM1 signal. If PWM_CTRL is low, this pin outputs clock signal. The rising edge of the clock is used to adjust frequency (MODE low) or duty cycle (MODE high) output of the bq50002 Analog Front End.  |
| PWM_CTRL          | 38               | 0   | PWM_CTRL is an output intended for use by the bq50002 Analog Front End to select whether its PWM outputs are generated internally within the bq50002 itself (PWM_CTRL HIGH), or whether they are simply passed through from external signals (PWM_CTRL LOW).   |
| PWM2 /<br>UP_DOWN | 2                | 0   | If PWM_CTRL is high, this pin outputs PWM2 signal. If PWM_CTRL is low, this pin is used to adjust the frequency (MODE low) or duty cycle (MODE high) of the external PWM output. If this signal is high, it decrease frequency or increase duty cycle. If this signal is low, it increases frequency or decreases duty cycle output of the bq50002 Analog Front End. |
| Reserved          | 4                | I   | Leave this pin open.   |
| Reserved          | 5                | I   | Unused   |
| Reserved          | 19               | I   | Reserved. Leave this pin open.   |
| Reserved          | 20               | I/O | Reserved. Leave this pin open.   |
| SCL               | 29               | I/O | 10-kΩ pull-up resistor to 3-V supply. I <sup>2</sup> C Clock.  |
| SDA               | 28               | I/O | 10-kΩ pull-up resistor to 3-V supply. I <sup>2</sup> C Data.   |
| TSENSE            | 13               | I   | Temperature sensing for safety shutdown. Connect to 3 V via 10-k $\Omega$ resistor if unused.  |
| Unused            | 6                | I   | Leave this pin open.   |
| Unused            | 7                | I/O | Leave this pin open.   |
| Unused            | 17, 18,<br>24–27 | I/O | Leave this pin open.   |
| VCORE             | 30               | _   | Regulated internal core power supply. Connect via 0.4-µF capacitor to ground.  |
| VPEAK             | 8                | I   | Peak coil voltage.   |
| VSENSE            | 9                | I   | Input voltage sense.   |



# 6 Specifications

# 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

|  |   | MIN         | MAX               | UNIT |
|--|---|-------------|-------------------|------|
| \  | Applied at VCC to VSS                               | -0.3        | 4.1               | V    |
| Voltage                                      | Applied to any pin (excluding VCORE) <sup>(2)</sup> | -0.3        | VCC + 0.3         | V    |
| Diode cu                                     | rrent at any device pin                             | -2          | 2                 | mA   |
| Maximum junction temperature, T <sub>J</sub> |   |             | 95 <sup>(3)</sup> | °C   |
| Storage                                      | temperature, T <sub>stg</sub>                       | <b>–</b> 55 | 95                | ů    |

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltages referenced to V<sub>SS</sub>. VCORE is for internal device use only. No external DC loading or voltage should be applied.

6.2 ESD Ratings

|                    |                         |  | VALUE | UNIT |
|--------------------|-------------------------|--|-------|------|
|                    |                         | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)                         | 1000  |      |
| V <sub>(ESD)</sub> | Electrostatic discharge | Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup> | 250   | V    |

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

# 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

|                         |   | MIN | NOM | MAX | UNIT |
|-------------------------|---|-----|-----|-----|------|
| V <sub>CC</sub>         | Supply voltage during program execution and FRAM programming (AVCC = DVCC) <sup>(1)</sup> | 2   |     | 3.6 | V    |
| V <sub>SS</sub>         | Supply voltage (AVSS = DVSS)  |     | 0   |     | V    |
| T <sub>A</sub>          | Operating free-air temperature  | -40 |     | 85  | °C   |
| T <sub>J</sub>          | Operating free-air temperature  | -40 |     | 85  | °C   |
| C <sub>(VCORE)</sub>    | Required capacitor at VCORE (2)   |     | 470 |     | nF   |
| $C_{(VCC)}/C_{(VCORE)}$ | Capacitor ratio of VCC to VCORE   | 10  |     |     | nF   |

It is recommended to power AVCC and DVCC from the same source. A maximum difference of 0.3 V between AVCC and DVCC can be tolerated during power up and operation.

<sup>(3)</sup> It is recommended to follow the current JEDEC J-STD-020 specification with peak reflow temperatures not higher than classified on the device label on the shipping boxes or reels. In general, hand soldering is not recommended. However, if hand soldering is required for application prototyping, peak temperature must not exceed 250°C for longer than 30 seconds durations. In addition, during storage, the maximum storage temperature of 95°C should not be exceeded.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

<sup>(2)</sup> A capacitor tolerance of ±20% or better is required.



## 6.4 Thermal Information

|                       |  | bq500511   |      |
|-----------------------|--|------------|------|
|                       | THERMAL METRIC <sup>(1)</sup>                | RHA (VQFN) | UNIT |
|                       |  | 40 PINS    |      |
| $R_{\theta JA}$       | Junction-to-ambient thermal resistance       | 31.8       | °C/W |
| R <sub>0JC(top)</sub> | Junction-to-case (top) thermal resistance    | 18.5       | °C/W |
| $R_{\theta JB}$       | Junction-to-board thermal resistance         | 6.8        | °C/W |
| ΨЈТ                   | Junction-to-top characterization parameter   | 0.2        | °C/W |
| ΨЈВ                   | Junction-to-board characterization parameter | 6.7        | °C/W |
| R <sub>0JC(bot)</sub> | Junction-to-case (bottom) thermal resistance | 1.8        | °C/W |

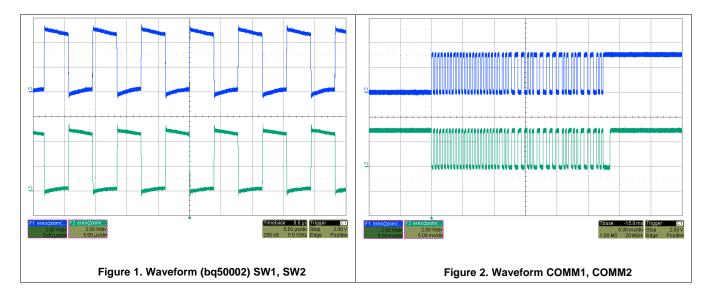
<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

# 6.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

|                   | PARAMETER  |     | TEST CONDITIONS | MIN | TYP  | MAX | UNIT |
|-------------------|--|-----|-----------------|-----|------|-----|------|
| I <sub>(AM)</sub> | Active Mode Supply Current into V <sub>CC</sub>    | 3 V |                 |     | 3.45 | 4.3 | mA   |
|                   | Low-Power Mode Supply Current into V <sub>CC</sub> | 3 V | -40°C           |     | 274  |     | μΑ   |
|                   |  |     | 25°C            |     | 285  | 340 | μΑ   |
| L(LPM)            |  |     | 60°C            |     | 315  |     | μΑ   |
|                   |  |     | 85°C            |     | 340  | 455 | μA   |

# 6.6 Typical Characteristics





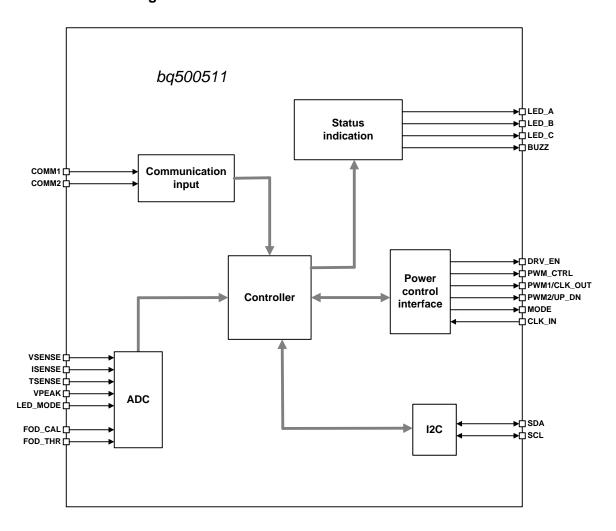
# 7 Detailed Description

#### 7.1 Overview

The principle of wireless power transfer is simply an open-cored transformer consisting of transmitter and receiver coils. The transmitter coil and electronics are typically built into a charger pad and the receiver coil and electronics are typically built into a portable device, such as a cell phone. When the receiver coil is positioned on the transmitter coil, magnetic coupling occurs when the transmitter coil is driven. The flux is coupled into the secondary coil, which induces a voltage and current flows. The secondary voltage is rectified, and power can be transferred effectively to a load, wirelessly. Power transfer can be managed through various closed loop control schemes.

After power is applied and the transmitter device comes out of reset, it will automatically begin the process of detecting and powering a receiver. The bq500511 sends a ping to detect the presence of a receiver on the pad. After a receiver is detected, the bq500511 attempts to establish communication and begin power transfer. The bq500511 is designed to operate with the bq50002 Wireless Power Transmitter Analog Front End to control a full-bridge power stage to drive the primary coil. Through a simple interface the bq500511 instructs the bq50002 how much to increase or decrease power. The full bridge power stage allows for higher power delivery for a given supply voltage.

# 7.2 Functional Block Diagram





## 7.3 Feature Description

### 7.3.1 A11 Coil Specification

The bq500511 controller supports the A11 transmitter coil type for which the coil and matching capacitor specification has been established by the WPC Standard although the device can be used in a proprietary (non-WPC) system. This is fixed and cannot be changed on the transmitter side.

For a current list of coil vendors, see bqTESLA Transmitter Coil Vendors, SLUA649.

#### 7.3.2 Option Select Pins

There are three option select pins on the bq500511. Two (FOD\_CAL and FOD\_THR) are used to calibrate the foreign object detection algorithm. The third (LED\_MODE) selects the LED output behavior. The voltages on these pins will be read by bq500511 at power-up.

For LED MODE, the selected bin determines the LED behavior based on Table 1.

See section Foreign Object Detection (FOD) and FOD Calibration for more information on the remaining option select pins.

#### 7.3.3 LED Modes

The bq500511 can directly drive three LED outputs (pin 11, pin 12, and pin 14) through a simple current limit resistor (typically 470  $\Omega$ ), based on the mode selected. The three current limit resistors can be individually adjusted to tune or match the brightness of the LEDs. Do not exceed the maximum output current rating of the device.

Several predefined LED display schemes are selectable via the voltage on the LED\_MODE pin at startup. Any means of setting the LED\_MODE voltage can be used; if a resistor divider between 3 V and ground is used as shown in Figure 3, relatively large values should be used to minimize the idle power loss. With 100 k $\Omega$  used for the upper resistor values for the lower resister, RLED selects one of the desired LED indication schemes presented in Table 1.

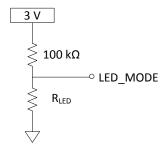


Figure 3. LED\_MODE Selection

**Table 1. LED Control** 

| LED               | R <sub>LED</sub>              |                               |                |         |                                  | OPERATION          | AL STATES               |                               |                    |
|-------------------|-------------------------------|-------------------------------|----------------|---------|----------------------------------|--------------------|-------------------------|-------------------------------|--------------------|
| CONTROL<br>OPTION | SELECTION<br>RESISTOR<br>(kΩ) | DESCRIPTION                   | LED            | STANDBY | POWER<br>TRANSFER <sup>(1)</sup> | CHARGE<br>COMPLETE | FAULT <sup>(1)(2)</sup> | FOD<br>WARNING <sup>(2)</sup> | DPL <sup>(1)</sup> |
|                   |                               |                               | LED_A (green)  | off     | blink slow                       | on                 | off                     | off                           | blink slow         |
| 1                 | 1 24.9                        | 2-LED option #1               | LED_B (red)    | off     | off                              | off                | on                      | blink fast                    | blink slow         |
|                   |                               |                               | LED_C (orange) | -       | -                                | _                  | -                       | -                             | -                  |
|                   |                               | 2-LED option<br>Standby LED's | LED_A (green)  | on      | blink slow                       | on                 | off                     | off                           | blink slow         |
| 2                 | 36.5                          |                               | LED_B (red)    | on      | off                              | off                | on                      | blink fast                    | blink slow         |
|                   |                               |                               | LED_C (orange) | -       | -                                | -                  | -                       | -                             | -                  |
|                   |                               | Single LED option             | LED_A (green)  | off     | on                               | off                | blink fast              | on                            | on                 |
| 3                 | 49.9                          |                               | LED_B (red)    | -       | -                                | -                  | -                       | -                             | -                  |
|                   |                               |                               | LED_C (orange) | -       | -                                | -                  | -                       | -                             | -                  |

- (1) blink slow = 1.25 Hz
- (2) blink fast = 5 Hz



# **Feature Description (continued)**

**Table 1. LED Control (continued)** 

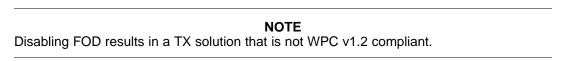
| LED R <sub>LED</sub> |                               |                 |                |         |                                  | OPERATION          | AL STATES               |                               |                    |
|----------------------|-------------------------------|-----------------|----------------|---------|----------------------------------|--------------------|-------------------------|-------------------------------|--------------------|
| CONTROL<br>OPTION    | SELECTION<br>RESISTOR<br>(kΩ) | DESCRIPTION     | LED            | STANDBY | POWER<br>TRANSFER <sup>(1)</sup> | CHARGE<br>COMPLETE | FAULT <sup>(1)(2)</sup> | FOD<br>WARNING <sup>(2)</sup> | DPL <sup>(1)</sup> |
|                      |                               |                 | LED_A (green)  | off     | on                               | off                | off                     | off                           | -                  |
| 4                    | 66.5                          | 2-LED option #2 | LED_B (red)    | off     | off                              | off                | on                      | blink fast                    | blink slow         |
|                      |                               |                 | LED_C (orange) | -       | -                                | _                  | -                       | -                             | -                  |
|                      |                               |                 | LED_A (green)  | off     | off                              | on                 | off                     | off                           |                    |
| 5                    | 86.6                          | 3-LED option #1 | LED_B (red)    | off     | on                               | off                | on                      | on                            | on                 |
|                      |                               |                 | LED_C (orange) | off     | off                              | off                | off                     | off                           | off                |
|                      |                               |                 | LED_A (green)  | off     | blink slow                       | on                 | off                     | off                           | off                |
| 6                    | 113                           | 3-LED option #2 | LED_B (red)    | off     | off                              | off                | on                      | blink fast                    | off                |
|                      |                               |                 | LED_C (orange) | off     | off                              | off                | off                     | off                           | blink slow         |
|                      |                               | 3-LED option #3 | LED_A (green)  | off     | blink slow                       | off                | off                     | off                           | off                |
| 7                    | 147                           |                 | LED_B (red)    | off     | off                              | on                 | off                     | off                           | off                |
|                      |                               |                 | LED_C (orange) | off     | off                              | off                | on                      | blink fast                    | blink slow         |
|                      |                               |                 | LED_A (green)  | off     | off                              | on                 | blink slow              | off                           | off                |
| 8                    | 200                           | 2-LED option #3 | LED_B (red)    | off     | on                               | off                | blink slow              | on                            | on                 |
|                      |                               |                 | LED_C (orange) | -       | -                                | -                  | =                       | -                             | -                  |
|                      |                               |                 | LED_A (green)  | off     | blink slow                       | on                 | off                     | off                           | blink slow         |
| 9                    | 274                           | 2-LED option #4 | LED_B (red)    | off     | off                              | off                | on                      | blink fast                    | blink slow         |
|                      |                               |                 | LED_C (orange) | -       | -                                | -                  | -                       | -                             | -                  |
|                      |                               |                 | LED_A (green)  | off     | on                               | off                | blink fast              | on                            | blink slow         |
| 10                   | 392                           | 2-LED option #5 | LED_B (red)    | off     | off                              | on                 | off                     | off                           | off                |
|                      |                               |                 | LED_C (orange) | -       | -                                | _                  | -                       | -                             | -                  |

## 7.3.4 Foreign Object Detection (FOD) and FOD Calibration

The bq500511 supports FOD in order to meet the requirements of the WPC v1.2 specification and to protect against the heating of metal objects between coils. Continuously monitoring input power, known losses, and the value of power reported by the receiver device being charged, the bq500511 can estimate how much power is unaccounted for and presumed lost due to metal objects placed in the wireless power transfer path. If this unexpected loss exceeds the threshold set by the FOD resistors, a fault is indicated and power transfer is halted

As the default, the FOD resistors should set a threshold of 400 mW which has been empirically determined using standard WPC FOD test objects (disc, ring and foil). Some tuning might be required as every system will be slightly different. This tuning is best done by trial and error: increase or decrease the loss threshold and retry the system with the standard test objects. The ultimate goal of the FOD feature is safety; to protect misplaced metal objects from becoming hot. Reducing the loss threshold and making the system too sensitive may lead to a false object detection and a bad user experience. Find the balance which best suits the application.

If the application requires disabling FOD, it is possible by tying the FOD THR pin to 3 V.



The FOD\_CAL input, can be used to compensate for any load-dependent effect on the power loss. Using a calibrated FOD reference receiver with no foreign objects present, FOD\_CAL should be selected such that the calculated loss across the load range is substantially constant (within approximately 100 mW). After correcting for the load dependence, the FOD thresholds should be re-set above the resulting average by approximately 400 mW for the transmitter to satisfy the WPC requirements on tolerated heating.



Similarly to the LED\_MODE selection, FOD\_THR and FOD\_CAL are set based on the voltage of their inputs (pins 35 and 10 respectively) measured when the device is powered up.

$$FOD_{threshold} = FOD_{THR} \times 400 \tag{1}$$

#### Where:

FOD\_threshold is the maximum allowed loss in mW, above which a FOD fault is triggered.

FOD\_THR is the voltage on pin 35 in volts (between 0 and 2.5 Volts).

For example, to set the recommended starting threshold of 400 mW, 1 V should be applied to FOD\_THR; this could be accomplished with a resistor divider between 3 V and ground consisting of 200 k $\Omega$  over 100 k $\Omega$ .

The value for FOD\_CAL is calculated with an offset to allow a correction which either increases or decreases with load.

$$FOD\_correction = -1000 + FOD\_CAL \times 800$$
 (2)

#### Where:

FOD correction is load dependent correction in mW/Amp.

FOD\_CAL is the voltage on pin 10 in volts (between 0 and 2.5 Volts).

For both the FOD\_THR and FOD\_CAL inputs, an internal analog to digital converter with a range of 0 V - 2.5 V is used to measure the input. The combined range and gain provide attainable ranges of 0 mW to 1000 mW for FOD threshold, and -1000 mW/A to +1000 mW/A for FOD correction.

Contact TI for the TX tuning tool to set appropriate FOD THR and FOD CAL values for your design.

### 7.3.5 Shut Down Through External Thermal Sensor or Trigger

Typical applications of the bq500511 do not require additional thermal protection. This shutdown feature is provided for enhanced applications and is not limited to thermal shutdown. The key parameter is the 1 V threshold on pin 13, TSENSE. Voltage below 1 V on pin 13 causes the device to shut down. The application of thermal monitoring through a negative temperature coefficient (NTC) sensor, for example, is straightforward. The NTC forms the lower leg of a temperature-dependent voltage divider. The NTC leads are connected to the bq500511 device, pin 13 and GND. The threshold on pin 13 is set to 1 V, below which the system shuts down and indicates a fault (indication depending on LED mode chosen).

To implement this feature follow these steps:

- Consult the NTC data sheet and find the resistance versus temperature curve.
- 2. Determine the actual temperature where the NTC will be placed by using a thermal probe.
- 3. Read the NTC resistance at that temperature in the NTC datasheet, that is R NTC.
- 4. Use the following formula to determine the upper leg resistor (R\_Setpoint):

$$R_{\text{Setpoint}} = 2.3 \times R_{\text{NTC}} \tag{3}$$

The system restores normal operation after approximately five minutes or if the receiver is removed. If the feature is not used, this pin must be pulled high.

#### **NOTE**

Pin 13, TSENSE, must always be terminated; otherwise, erratic behavior may occur.



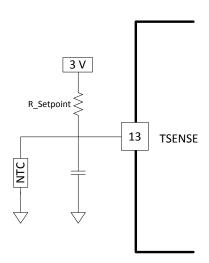


Figure 4. NTC Application (optional)

# 7.3.6 Fault Handling and Indication

Table 2 shows end power transfer (EPT) packet responses, fault conditions, and the duration of how long the condition lasts until a retry in attempted. The LED mode selected determines how the LED indicates the condition or fault.

| rable 2.1 date flatiding and maleution    |   |  |  |  |  |  |  |  |
|---|---|--|--|--|--|--|--|--|
| DURATION <sup>(1)</sup><br>(before retry) | COMMENTS IMMEDIATE <sup>(2)</sup>   |  |  |  |  |  |  |  |
|   | unknown   |  |  |  |  |  |  |  |
| 5 seconds                                 | charge complete   |  |  |  |  |  |  |  |
| Infinite                                  | internal fault  |  |  |  |  |  |  |  |
| 5 minutes                                 | over temperature  |  |  |  |  |  |  |  |
| Immediate                                 | over voltage  |  |  |  |  |  |  |  |
| Immediate                                 | over current  |  |  |  |  |  |  |  |
| Infinite                                  | battery failure   |  |  |  |  |  |  |  |
| Not applicable                            | reconfigure   |  |  |  |  |  |  |  |
| Immediate                                 | no response   |  |  |  |  |  |  |  |
| Immediate                                 | TX over voltage   |  |  |  |  |  |  |  |
| 5 minutes                                 | TX over temperature   |  |  |  |  |  |  |  |
| 12 seconds                                | buzzer and LED  |  |  |  |  |  |  |  |
| 5 minutes                                 | same as over temp   |  |  |  |  |  |  |  |
|   | DURATION <sup>(1)</sup> (before retry)  5 seconds Infinite 5 minutes Immediate Immediate Infinite Not applicable Immediate Immediate Immediate 5 minutes 12 seconds |  |  |  |  |  |  |  |

**Table 2. Fault Handling and Indication** 

# 7.3.7 Power Transfer Start Signal

The bq500511 provides an output signal to indicate that power transfer has begun. Pin 15, BUZZ, outputs a 400-ms duration, 4-kHz square wave appropriate to drive a low cost AC type ceramic buzzers. If not used, this pin should be left open.

# 7.3.8 Power-On Reset

The bq500511 has an integrated power-on reset (POR) circuit which monitors the supply voltage and handles the correct device startup sequence. Additional supply voltage supervisor or reset circuits are not needed.

<sup>(1)</sup> After a FAULT, the magnetic field is re-characterized to improve the ability to detect the removal of the at-fault receiver. If the receiver is removed in the first second immediately following the detection of this fault (before the re-characterization is complete), the field corresponding to an empty pad may be associated with the faulty receiver and the LED indication may continue to indicate a fault state even though no receiver is present. This indication persists until either the HOLDOFF time expires or a new receiver disturbs the field, at which time normal operation, with proper LED indication, is resumed.

<sup>(2) &</sup>quot;Immediate" is less than 1 second.



## 7.3.9 Trickle Charge and CS100

The WPC specification provides an EPT message (EPT-01) to indicate charge complete. Upon receipt of the charge complete message, the bq500511 disables the output and changes the LED indication. The exact indication depends on the LED\_MODE chosen. In some battery charging applications, there is a benefit to continue the charging process in trickle-charge mode to top off the battery. The WPC specification provides for an informational 'Charge Status' packet that conveys the level of battery charger. The bq500511 uses this command to enable top-off charging. The bq500511 changes the LED indication to reflect charge complete when a Charge Status message indicating 100% is received, but unlike the response to an EPT, it will not halt power transfer even though the LED indicates charge complete. The mobile device can use a CS100 packet to enable trickle charge mode. If the reported charge status drops below 90%, normal charging indication is resumed.

#### 7.4 Device Functional Modes

#### 7.4.1 Power Transfer

Power transfer efficiency and robustness depends on coil coupling. Coupling depends on the distance between coils, alignment, coil dimensions, coil materials, number of turns, magnetic shielding, impedance matching, frequency, and duty cycle. Most importantly, the receiver and transmitter coils must be aligned for best coupling and efficient power transfer. The smaller the space between the coils is, the better the coupling. Shielding is added as a backing to both the transmitter and receiver coils to direct the magnetic field to the coupled zone. Magnetic fields outside the coupled zone do not transfer power. Thus, shielding also serves to contain the fields to avoid coupling to other adjacent system components.

Regulation can be achieved by controlling any one of the coil coupling parameters. However, for WPC compatibility, the transmitter-side coils and capacitance are specified and the resonant frequency point is fixed. Power transfer is regulated by changing the operating frequency between 110 kHz to 205 kHz. The higher the frequency, the further from resonance and the lower the power. Duty cycle remains constant at 50% throughout the power band and is reduced only once 205 kHz is reached.

## 7.4.1.1 Dynamic Power Limiting™

Dynamic Power Limiting<sup>™</sup> (DPL) allows operation from a 5-V supply with limited current capability (such as a USB port). When the input voltage is observed drooping, the output power is dynamically limited to reduce the load and provides margin relative to the supply's capability.

Anytime the DPL control loop is regulating the operating point of the transmitter, the LED will indicate that DPL is active. The LED color and flashing pattern are determined by the LED Table. If the receiver sends a Control Error Packet (CEP) with a negative value, (for example, to reduce power to the load), the bq500511 in DPL mode will return to normal operation and respond to this CEP via the standard WPC control loop behavior.

#### 7.4.1.2 Operating Frequency Limiting

Pin-33, FLIM, can be used to set an upper operating frequency limit of 190 kHz by pulling down with a 10-k $\Omega$  resistor. Regulatory bodies in some countries have proposed that wireless power transmitters limit operation at this point. While not required anywhere today, this forward looking option provides the means for a simple design modification to address that possible future requirement. A weak internal pull-up allows normal operation without any applied bias.

Note that this feature may prevent WPC certification.

#### 7.4.2 Communication

Communication within the WPC v1.2 specification is from the receiver to the transmitter. For example, in order to regulate the output of the transmitter, the receiver sends messages requesting the transmitter to increase or decrease power. The receiver communicates by modulating the rectifier voltage and using amplitude modulation (AM) sends packets of information to the transmitter. A packet is comprised of a preamble, a header, the actual message, and a checksum, as defined by the WPC standard.



# **Device Functional Modes (continued)**

The receiver sends a packet by modulating an impedance network. This AM signal reflects back as a change in the voltage amplitude on the transmitter coil. In the bq500511/bq50002 system, the bq50002 performs the demodulation function and passes a digitized version of the message to the bq500511 where the message is decoded and processed. For example in response to a Control Error Packet, the bq500511 calculates the required change in output power and in turn controls the bq50002 through the CLK\_OUT, UP\_DOWN, and MODE pins to adjust the operating point and thus its output power.

The modulation impedance network on the receiver can either be resistive or capacitive. Figure 5 shows the resistive modulation approach, where a resistor is periodically added to the load, resulting in an amplitude change in the transmitter voltage. Figure 6 shows the corresponding capacitive modulation approach.

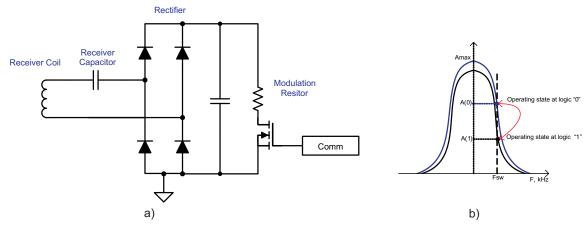


Figure 5. Receiver Resistive Modulation Circuit

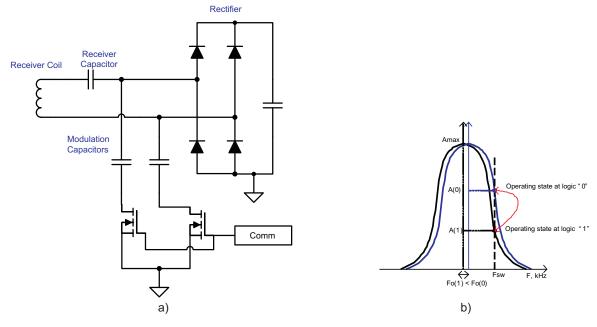


Figure 6. Receiver Capacitive Modulation Circuit



# 8 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

# 8.1 Application Information

The bq500511 device is a wireless power transmitter controller designed for 5W WPC compliant applications when paired with the bq50002. The pair integrates all functions required to control wireless power transfer to a WPC v1.2 compliant receiver. Several tools are available for the design of the system. See the product folder on www.ti.com for more details. The following sections highlight some of the system design considerations.

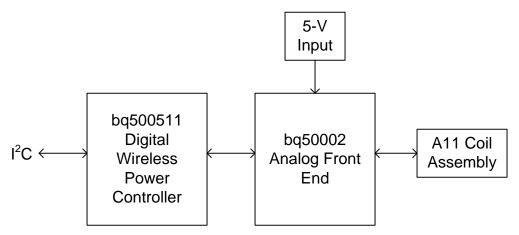


Figure 7. bg500511 System Block Diagram

The I<sup>2</sup>C port is accessed by the FOD tuning tool and can provide a level of system monitoring and evaluation.

The SDA and SCL lines of the  $I^2C$  bus must be pulled up (as shown in the Figure 8) if the  $I^2C$  port is utilized. They may be left floating if no  $I^2C$  function is required. The logic reference generated by the bq50002 Analog Front End is 3 V, so care should be taken to ensure that if the Master  $I^2C$  device also has pull-up resistors to a higher reference, that the the 3-V reference to the bq500511 is not affected. Specifically, only one set of pull-up resistors should be populated, either on the  $I^2C$  Master bus or on the bq500511 system board, but not both.

Additional details on I<sup>2</sup>C use and capabilities can be obtained by contacting TI.

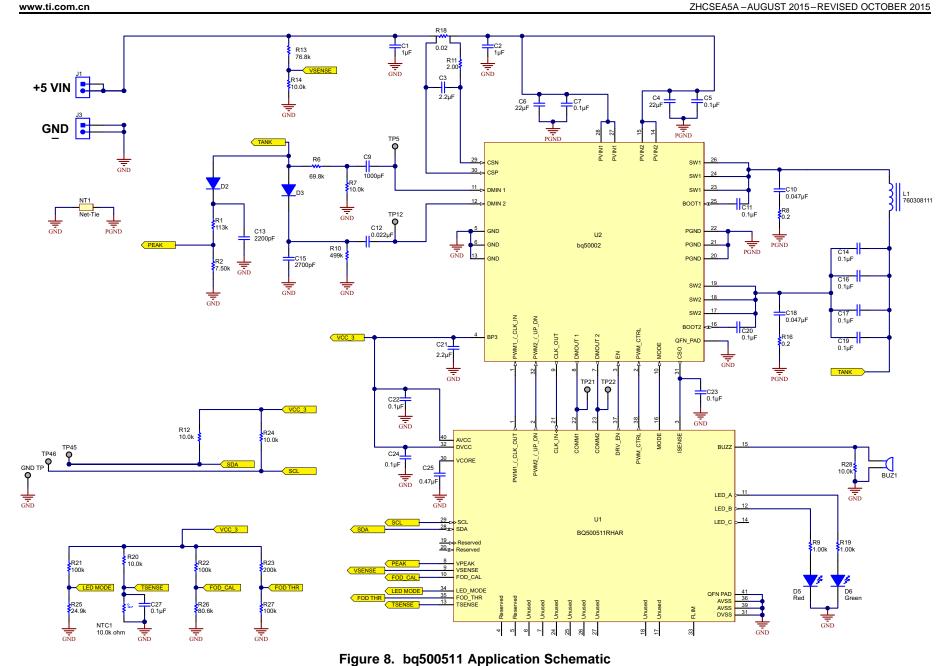
## 8.2 Typical Application

The bq500511 controller, when paired with bq50002 integrated Analog Front End device, requires a minimum of external components to implement a WPC 1.2 Wireless Power Transmitter system.

As shown in the application schematic, external components are used to implement the following functions:

- · Resonant tank circuit
- Demodulator input signal conditioning
- · Human interface (LED and Buzzer)
- Current sensing
- Voltage sensing
- Temperature sensing
- System Configuration: Foreign Objection Detection (FOD) threshold and calibration, LED mode





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#### 8.2.1 Design Requirements

| DESIGN PARAMETER | VALUE |
|------------------|-------|
| WPC coil type    | A11   |

## 8.2.2 Detailed Design Procedure

#### 8.2.2.1 Capacitor Selection

Capacitor selection is critical to proper system operation. The total capacitance value of  $4 \times 100$  nF is required in the resonant tank. This is the WPC system compatibility requirement, not a guideline.

#### NOTE

A total capacitance value of  $4 \times 100$  nF (C0G dielectric type, 50-V rating) is required in the resonant tank to achieve the correct resonance frequency. The capacitors chosen must be rated for at least 50 V and must be of a high-quality C0G dielectric (sometimes also called NP0). These are typically available in a 5% tolerance, which is adequate. TI does **not** recommend the use of X7R types or below if WPC compliance is required because critical WPC Certification Testing, such as the minimum modulation or guaranteed power test, might fail. The designer can combine capacitors to achieve the desired capacitance value. Various combinations can work depending on market availability. All capacitors must be of C0G types (not mixed with any other dielectric types).

# 8.2.2.2 Current Monitoring Requirements

The bq500511 is WPC v1.2 ready. To enable the FOD feature, current monitoring is provided in the bq50002 Analog Front End. For proper scaling of the current monitor signal, the current sense resistor should be 20 m $\Omega$ . For FOD accuracy, the current sense resistor must be a quality component with 0.5% tolerance, at least 1/4-W rating, and a temperature stability of ±200 PPM.

### 8.2.2.3 Input Voltage Monitoring

The VSENSE input is used to calculate power for the FOD function, and to detect the supply drooping when the bq500511 is receiving power from an insufficient adapter (for example from a weak USB port). The VSENSE input should reflect the input source voltage and should be scaled with a resistor divider comprising a 76.8 k $\Omega$  over 10 k $\Omega$ .

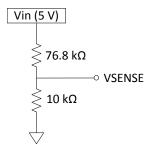


Figure 9. VSENSE Signal Conditioning

## 8.2.2.4 Tank Voltage Monitoring

The VPEAK input is used to estimate losses in the power components for the FOD function. The VPEAK input should reflect the envelope of the tank voltage (i.e. the node directly between the resonant capacitors and the primary coil) and should be buffered with a diode (100 V, 0.2 A) and scaled with a resistor divider comprising a 113 k $\Omega$  over 7.5 k $\Omega$ , with a 2200-pF filter capacitor.



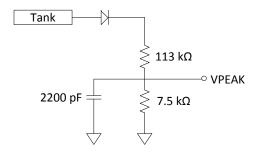


Figure 10. VPEAK Signal Conditioning

### 8.2.2.5 All Unused Pins

All unused pins can be left open unless otherwise indicated. Refer to the table in the *Pin Configuration and Functions* section. To improve PCB layout, ground unused pins, if it is an option.

## 8.2.2.6 Input Regulation

The bq500511 requires 3 VDC to operate. The regulator in the bq50002 provides this voltage rail eliminating the need for any external regulation.

# 8.2.2.7 System Input Power Requirements

The design works with 5-V input voltage to the bq50002. The WPC defined A11 TX type requires 5-V system voltage in order to deliver 5 W of output power from the receiver.

#### 8.2.2.8 LED Modes

The bq500511 can directly drive three LED outputs (pin 11 (LED-A), pin 12 (LED-B), and pin 14 (LED-C)). Select one of the desired LED indication schemes through the voltage on LED\_MODE (pin 34) by choosing appropriate values for the resistor divider.

#### 8.2.3 Application Curves

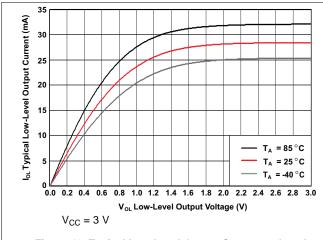


Figure 11. Typical Low-Level Output Current vs Low-Level Output Voltage

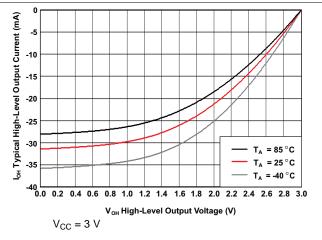


Figure 12. Typical High-Level Output Current vs High-Level Output Voltage



# 9 Power Supply Recommendations

The A11 TX type requires a 5-V system voltage.

# 10 Layout

## 10.1 Layout Guidelines

Careful PCB layout practice is critical to proper system operation. Many references are available on proper PCB layout techniques. A few good tips are as follows.

The TX layout requires a 4-layer PCB layout for best ground plane technique. A 2-layer PCB layout can be achieved though not as easily. Ideally, the approach to the layer stack-up is:

- · Layer 1 component placement and as much ground plane as possible
- · Layer 2 clean ground
- Layer 3 finish routing
- · Layer 4 clean ground

Thus, the circuitry is virtually sandwiched between grounds. This minimizes EMI noise emissions and also provides a noise-free voltage reference plane for device operation.

Keep as much copper as possible. Make sure the bq500511 GND pins have a continuous flood connection to the ground plane. The power pad of the bq50002 should also be stitched to the ground plane, which also acts as a heat sink. A good GND reference is necessary for proper system operation, such as analog-digital conversion, clock stability, and best overall EMI performance. Separate the analog ground plane from the power ground plane and use only **one** tie point to connect grounds. Having several tie points defeats the purpose of separating the grounds. See the bg500511 EVM for an example of a good layout technique.

# 10.1.1 Layout Notes

Make sure the bypass capacitors intended for the bq500511 3.3-V supply are actually bypassing these supply pins (pin 32, DVCC, and pin 40, AVCC) to solid ground plane (see Figure 13). This means they need to be placed as close to the device as possible and the traces must be as wide as possible.

Make sure the bq500511 has a continuous flood connection to the ground plane (see Figure 14).

The full-bridge power stage that drives the TX coil is composed of two half-bridge power stages (integrated in bq50002) and resonant capacitors. Inputs bypass capacitors should be placed as close as possible to the bq50002 PVIN1 pins (pin 27, 28) and PVIN2 pins (pin 14, 15). The input and ground pours and traces should be made as wide as possible for better current flow. The trace to the coil and resonant capacitors should also be made as wide as possible (see Figure 15).

To ensure proper operation, grounds conducting a large amount of current and switching noise must be isolated from low current, quiet grounds. Separate the ground pours for the power stages and the bq500511 IC. Connect all grounds to a single point at the main ground terminal (see Figure 16).

Proper current sensing layout technique is very important, as it directly affects the FOD and PMOD performance. When sampling the very-low voltages generated across a current sense resistor, be sure to use the so called 4-wire or Kelvin-connection technique. This is important to avoid introducing false voltage drops from adjacent pads and copper power routes. It is a common power-supply layout technique. Some high-accuracy sense resistors have dedicated sense pins (see Figure 17).

The trace from bq50002 CSP pin to sense resistor must be minimized to avoid unwanted offset in the application. This trace should be limited to less than  $20\text{-m}\Omega$  resistance.



# 10.2 Layout Examples

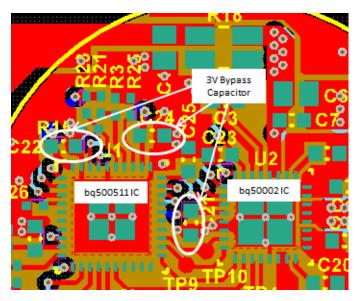


Figure 13. Bypass Capacitors Layout

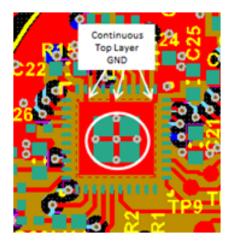


Figure 14. Continuous GND Layout

# **Layout Examples (continued)**

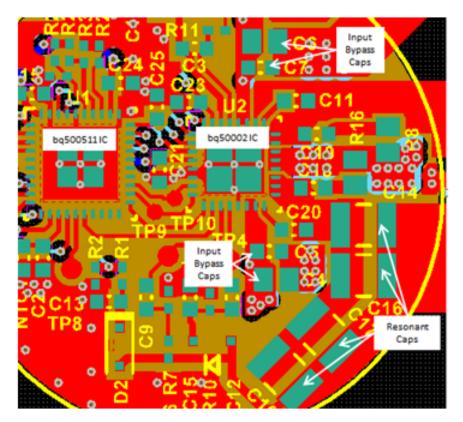


Figure 15. Ground Layout

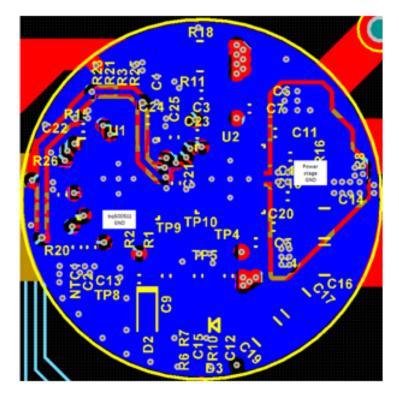


Figure 16. Ground Layout



# **Layout Examples (continued)**

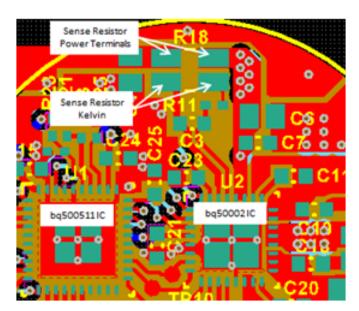


Figure 17. Current Sensing Layout



# 11 器件和文档支持

### 11.1 器件支持

### 11.1.1 Third-Party Products Disclaimer

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# 11.2 文档支持

## 11.2.1 相关文档

- 1. 技术类文档《无线充电联盟》,www.wirelesspowerconsortium.com
- 2. 模拟应用期刊,《无线充电联盟标准和 TI 兼容解决方案介绍》,Bill Johns,SLYT401
- 3. 数据表《bq51011/bq51013 符合 Qi (WPC) 标准的集成无线电源接收器》, SLVSAT9
- 4. 应用手册, 《构建一个无线电源发射器》, SLUA635
- 5. 应用手册,《bqTESLA 发送器线圈供应商》,SLUA649
- 6. 用户指南《bq50002 和 bq500511 无线电源 Tx EVM》, SLVUAJ7

## 11.3 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use

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**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

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这些装置包含有限的内置 ESD 保护。 存储或装卸时,应将导线一起截短或将装置放置于导电泡棉中,以防止 MOS 门极遭受静电损伤。

# 11.6 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

# 12 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。 这些信息是针对指定器件可提供的最新数据。 这些数据会在无通知且不 对本文档进行修订的情况下发生改变。 欲获得该数据表的浏览器版本,请查阅左侧的导航栏 www.ti.com 10-Nov-2025

#### PACKAGING INFORMATION

| Orderable part number | Status | Material type | Package   Pins  | Package qty   Carrier | RoHS | Lead finish/  | MSL rating/         | Op temp (°C) | Part marking |
|-----------------------|--------|---------------|-----------------|-----------------------|------|---------------|---------------------|--------------|--------------|
|                       | (1)    | (2)           |                 |                       | (3)  | Ball material | Peak reflow         |              | (6)          |
|                       |        |               |                 |                       |      | (4)           | (5)                 |              |              |
| BQ500511RHAR          | NRND   | Production    | VQFN (RHA)   40 | 2500   LARGE T&R      | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 85    | BQ500511     |
| BQ500511RHAR.A        | NRND   | Production    | VQFN (RHA)   40 | 2500   LARGE T&R      | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 85    | BQ500511     |
| BQ500511RHAT          | NRND   | Production    | VQFN (RHA)   40 | 250   SMALL T&R       | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 85    | BQ500511     |
| BQ500511RHAT.A        | NRND   | Production    | VQFN (RHA)   40 | 250   SMALL T&R       | Yes  | NIPDAU        | Level-3-260C-168 HR | -40 to 85    | BQ500511     |

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

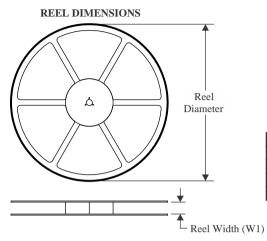
<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

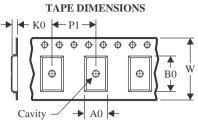
<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 24-Jul-2025

# TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width     |
|----|---|
| В0 | Dimension designed to accommodate the component length    |
| K0 | Dimension designed to accommodate the component thickness |
| W  | Overall width of the carrier tape                         |
| P1 | Pitch between successive cavity centers                   |

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

| Device       | Package<br>Type | Package<br>Drawing |    | SPQ  | Reel<br>Diameter<br>(mm) | Reel<br>Width<br>W1 (mm) | A0<br>(mm) | B0<br>(mm) | K0<br>(mm) | P1<br>(mm) | W<br>(mm) | Pin1<br>Quadrant |
|--------------|-----------------|--------------------|----|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| BQ500511RHAR | VQFN            | RHA                | 40 | 2500 | 330.0                    | 16.4                     | 6.3        | 6.3        | 1.1        | 12.0       | 16.0      | Q2               |
| BQ500511RHAT | VQFN            | RHA                | 40 | 250  | 180.0                    | 16.4                     | 6.3        | 6.3        | 1.1        | 12.0       | 16.0      | Q2               |

**PACKAGE MATERIALS INFORMATION** 

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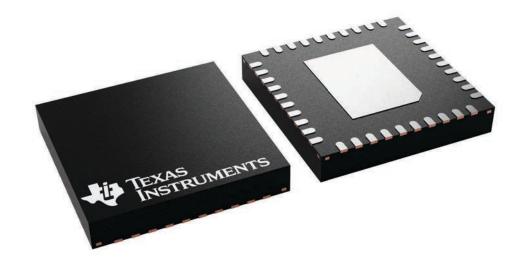
# \*All dimensions are nominal

| Device       | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|--------------|--------------|-----------------|------|------|-------------|------------|-------------|
| BQ500511RHAR | VQFN         | RHA             | 40   | 2500 | 353.0       | 353.0      | 32.0        |
| BQ500511RHAT | VQFN         | RHA             | 40   | 250  | 213.0       | 191.0      | 35.0        |

6 x 6, 0.5 mm pitch

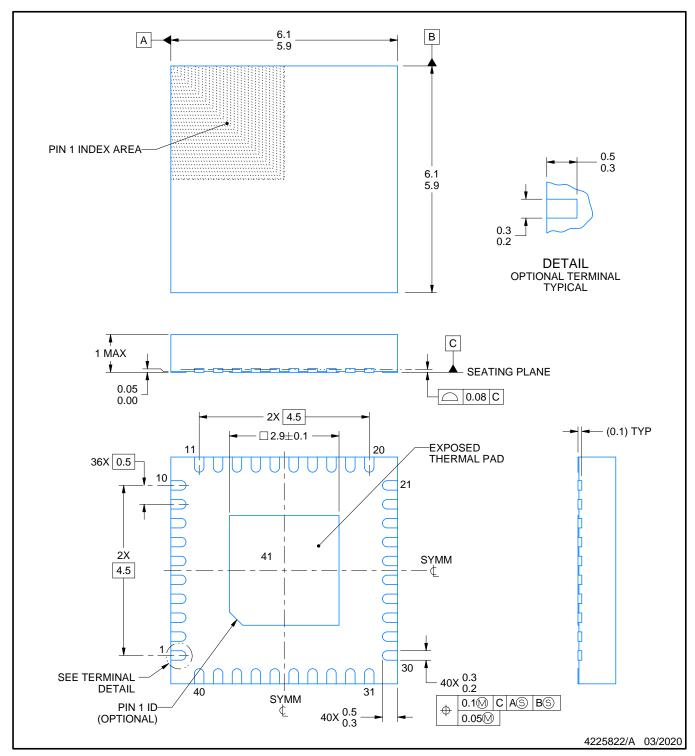
PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.





PLASTIC QUAD FLATPACK - NO LEAD

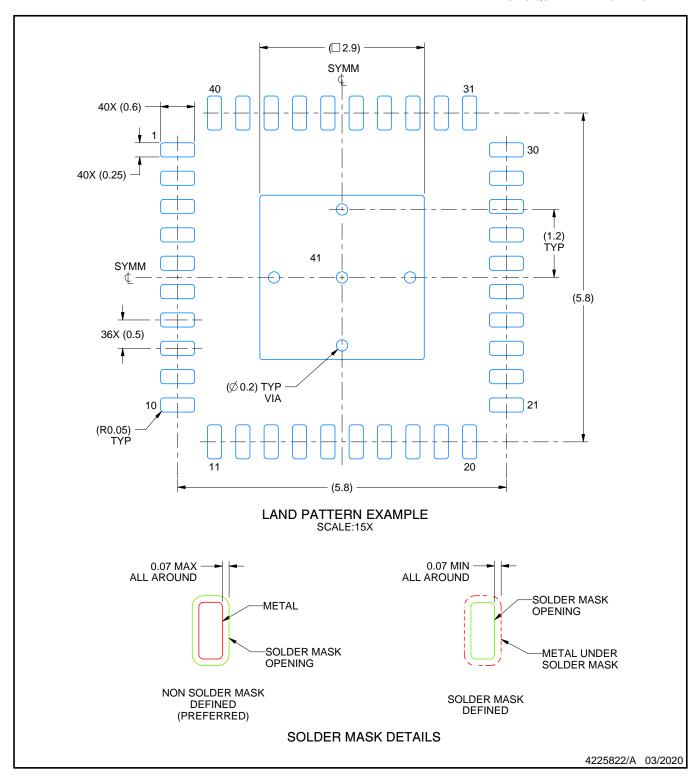


### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



PLASTIC QUAD FLATPACK - NO LEAD

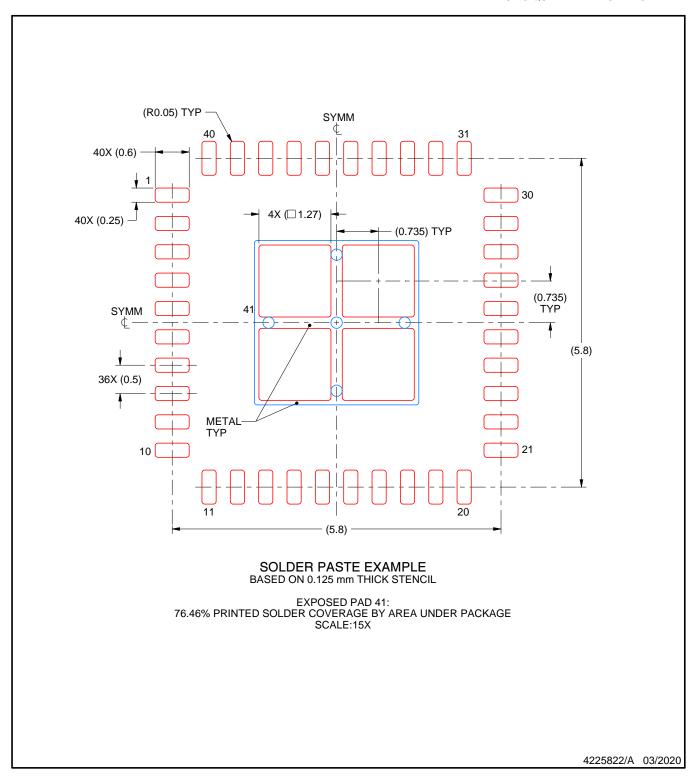


NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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