

## bq40z60 可编程电池管理单元

### 1 特性

- 全集成 2 节至 4 节串联锂离子或锂聚合物电池管理单元
- Pack+ 上的输入电压范围: 2.5V 至 25V
- 电池充电器效率 > 92%
- 电池充电器工作范围: 4V 至 25V
- 针对外部 N 沟道场效应晶体管 (NFET) 的电池充电器 1MHz 同步降压控制器
  - 软启动, 限制浪涌电流
  - 外部开关限流保护
  - 可编程充电
    - 支持 JEITA/增强型充电模式
- 电量监测
  - 用于库伦计数器的 16 位高分辨率积分器
  - 16 位模数转换器 (ADC), 通过 16 通道多路复用器实现电压、电流和温度的精密测量
  - 同步恒流 (CC) 和 ADC 采样支持 (功率转换)
  - 支持两线制 SMBus v2.0 接口, 工作频率选项最高可设定为 400kHz
  - SHA-1 哈希消息验证码 (HMAC) 响应器, 用于提高电池组安全性
    - 存储在安全存储器中的分裂密钥 (Split Key) (2 × 64)
  - 支持字段更新
- 模拟前端 (AFE) 保护
  - 可编程电流保护
    - 放电过流
    - 充电短路
    - 放电短路
- N-FET 高侧保护 FET 驱动
- 支持 4 个发光二极管 (LED)
- 负温度系数 (NTC) 热敏电阻输入
- 32 引脚紧凑型四方扁平无引脚 (QFN) 封装 (RHB)

### 2 应用

- 笔记本电脑、超极本、上网本、平板电脑和超便携移动个人电脑 (UMPC)
- 医疗与测试设备
- 便携式仪表

### 3 说明

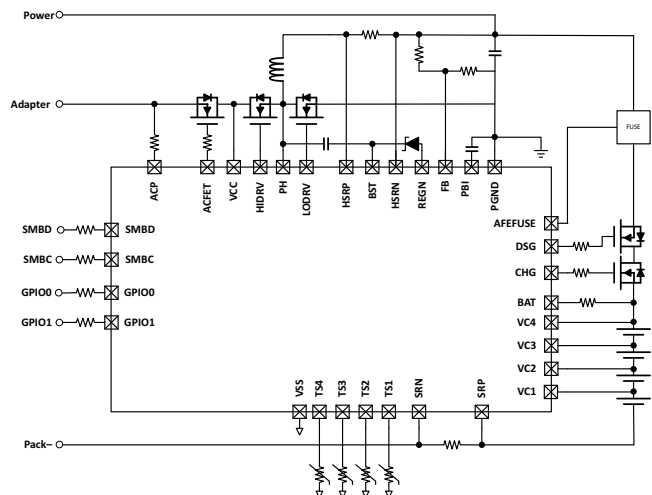
德州仪器 (TI) bq40z60 器件是一款可编程的电池管理单元, 其集成有电池充电控制输出、电量监测和相关保护功能, 能够完全自主地操作 2 至 4 节串联锂离子和锂聚合物电池组。此架构在电量监测处理器与电池充电器控制器之间实现内部通信, 从而在系统负载瞬变和适配器电流限制期间根据外部负载条件和电源路径来源管理来优化充电量。可通过 NFET、电感和感测电阻等外部元件针对具体功率传输情况来调节充电电流效率。

#### 器件信息<sup>(1)</sup>

器件型号	封装	封装尺寸 (标称值)
bq40z60	VQFN (32)	5.00mm × 5.00mm

(1) 如需了解所有可用封装, 请参阅数据表末尾的可订购产品附录。

#### 简化电路原理图



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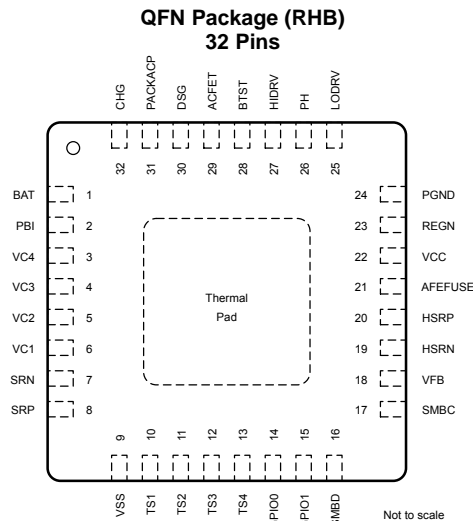
## 修订历史记录 (continued)

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## 5 说明（续）

该器件提供了电池阵列和系统安全功能，包括电池放电过流、充电短路和放电短路保护，以及针对 N 沟道 FET 的 FET 保护、内部 AFE 看门狗和电池断开连接检测。器件可通过固件提供更多保护功能，包括过压、欠压、过热等。

## 6 Pin Configuration and Functions



### Pin Functions

PIN			DESCRIPTION
NAME	NUMBER	I/O <sup>(1)</sup>	
BAT	1	P	Battery input pin. Primary power supply
PBI	2	P	Power supply backup input pin
VC4	3	IA	Sense voltage input pin for the most positive cell, balance current input for the most positive cell, and battery stack measurement input
VC3	4	IA	Sense voltage input pin for the third most positive cell, balance current input for the third most positive cell, and return balance current for the most positive cell
VC2	5	IA	Sense voltage input pin for the second most positive cell, balance current input for the second most positive cell, and return balance current for the most positive cell
VC1	6	IA	Sense voltage input pin for the least positive cell, balance current input for the least positive cell, and return balance current for the second most positive cell
SRN	7	IA	Analog input pin connected to the internal coulomb counter peripheral for integrating a small voltage between SRP and SRN, where SRP is the top of the sense resistor.
SRP	8	IA	Analog input pin connected to the internal coulomb counter peripheral for integrating a small voltage between SRP and SRN, where SRP is the top of the sense resistor.
VSS	9	P	Device ground
TS1	10	IA	Thermistor input for temperature sensor channel 1
TS2	11	IA	Thermistor input for temperature sensor channel 2
TS3	12	IA	Thermistor input for temperature sensor channel 3
TS4	13	IA	Thermistor input for temperature sensor channel 4
GPIO0	14	I/O	Multi-function I/O (open drain). For more information, see <i>IO Configuration</i> in the <i>bq40z60 Technical Reference Manual (SLUUA04)</i> .

(1) P = Power Connection, O = Digital Output, IA = Analog Input, I = Digital Input, I/OD = Digital Input/Output

**Pin Functions (continued)**

PIN			DESCRIPTION
NAME	NUMBER	I/O <sup>(1)</sup>	
GPIO1	15	I/O	Multi-function I/O (open drain). See <i>IO Configuration</i> in the <i>bq40z60 Technical Reference Manual</i> (SLUUA04).
SMBD	16	I/OD	SMBus data pin
SMBC	17	I/OD	SMBus clock pin
VFB	18	IA	Feedback sense input for charger control loop
HSRN	19	IA	High sense resistor negative node input
HSRP	20	IA	High sense resistor positive node input
AFFUSE	21	O	Fuse drive output pin
VCC	22	P	Power supply input
REGN	23	O	Charger FET gate drive regulator
PGND	24	P	Power ground
LODRV	25	O	Low side charging FET gate control output
PH	26	I/O	Charger phase signal input
HIDRV	27	O	High side charging FET gate control output
BTST	28	IA	High side bootstrap capacitor input
ACFET	29	O	AC FET gate control output
DSG	30	O	N-CH FET drive output pin
ACP	31	IA	Adapter input pin
CHG	32	O	N-CH FET drive output pin

## 7 Specifications

### 7.1 Absolute Maximum Ratings

Over-operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	TYP	MAX	UNIT
Supply voltage range, $V_{Supply}$	BAT, VCC, PBI	−0.3		30	V
	REGN	−0.3		7	V
Input voltage range, $V_{IN}$	ACP, SMBC, SMBD, GPIO0, GPIO1	−0.3		30	V
	TS1, TS2, TS3, TS4	−0.3		$V_{REG} + 0.3$	V
	SRP, SRN	−0.3		0.3	V
	HSRP, HSRN	−0.3		30	V
	PH	−0.3		32	V
	VFB	−0.3		16	V
	VC4	$VC3 - 0.3$		$VC3 + 8.5\text{ V}$ , or $VSS + 30$	V
	VC3	$VC2 - 0.3$		$VC2 + 8.5\text{ V}$ , or $VSS + 30$	V
	VC2	$VC1 - 0.3$		$VC1 + 8.5\text{ V}$ , or $VSS + 30$	V
	VC1	$VSS - 0.3$		$VSS + 8.5\text{ V}$ , or $VSS + 30$	V
Output voltage range, $V_O$	CHG, DSG	−0.3		32	V
	HIDRV, BTST, ACFET	−0.3		36	V
	LODRV	−0.3		7	V
	AFFUSE	−0.3		30	V
Maximum VSS current, $I_{SS}$			50		mA
Functional Temperature, $T_{FUNC}$		−40		110	°C

- (1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute–maximum–rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

		VALUE	UNIT
$V_{(ESD)}$ Rating	HBM <sup>(1)</sup>	±2000	V
	CDM <sup>(2)</sup>	±500	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $VCC = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $VCC = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

		MIN	NOM	MAX	UNIT
$V_{Supply}$ Supply voltage	BAT, VCC, PBI	2.2		26	V
	ACFET, BTST	0		35	V
	REGN	0		6.5	V
$V_{SHUTDOWN-}$ Shutdown voltage	$V_{ACP} < V_{SHUTDOWN-}$	1.8	2.0	2.2	V
$V_{SHUTDOWN+}$ Start-up voltage	$V_{ACP} > V_{SHUTDOWN-} + V_{HYS}$	2.05	2.25	2.45	V
$V_{HYS}$ Shutdown voltage hysteresis	$V_{SHUTDOWN+} - V_{SHUTDOWN-}$		250		mV

## Recommended Operating Conditions (continued)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

		MIN	NOM	MAX	UNIT
$V_{IN}$	Input voltage range	ACP, SMBC, SMBD, GPIO0, GPIO1		26	V
		TSx		$V_{REG}$	
		SRP, SRN	-0.2	0.2	
		HSRP, HSRN	-0.5	0.5	
		PH	-2	$V_{ACP}$	
		VFB	0	14	
		VC4	$V_{VC3}$	$V_{VC3} + 5$	
		VC3	$V_{VC2}$	$V_{VC2} + 5$	
		VC2	$V_{VC1}$	$V_{VC1} + 5$	
		VC1	$V_{VSS}$	$V_{VSS} + 5$	
$V_O$	Output voltage range	CHG, DSG, AFEFUSE		26	V
		HIDRV		35	V
		LODRV	0	6.5	V
$C_{PBI}$	External PBI capacitor		2.2		$\mu\text{F}$
$T_{OPR}$	Operating temperature		-40	85	$^\circ\text{C}$

## 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		bq40z60	UNIT
		RHB (VQFN)	
		32 PINS	
$R_{\theta JA, \text{ High K}}$	Junction-to-ambient thermal resistance	36	$^\circ\text{C/W}$
$R_{\theta JC(\text{top})}$	Junction-to-case(top) thermal resistance	31.5	$^\circ\text{C/W}$
$R_{\theta JB}$	Junction-to-board thermal resistance	8	$^\circ\text{C/W}$
$\Psi_{JT}$	Junction-to-top characterization parameter	0.5	$^\circ\text{C/W}$
$\Psi_{JB}$	Junction-to-board characterization parameter	7.9	$^\circ\text{C/W}$
$R_{\theta JC(\text{bot})}$	Junction-to-case(bottom) thermal resistance	2.2	$^\circ\text{C/W}$

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, [SPRA953](#).

## 7.5 Supply Voltage

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{CC}$	Device Operating Range	Operation with charger enabled	4.0	25	V
		Operation with charger disabled	2.5	25	
$V_{CC-UV}$	Undervoltage lock out	VCC falling	2.2	2.45	V

## 7.6 Supply Current

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{\text{NORMAL}}$ NORMAL mode <sup>(1)</sup>	CPU = ACTIVE, HFO = ON, ADC_FILTER = ON, CC_FILTER = ON, LFO = ON, REG18 = ON, CHG = ON, DSG = ON, ADC = ON, CC = ON, Charger Enabled, No Communication		1250	1850	$\mu\text{A}$
	CPU = HALT, HFO = ON, ADC_FILTER = ON, CC_FILTER = ON, LFO = ON, REG18 = ON, CHG = ON, DSG = ON, ADC = ON, CC = ON, Charger Disabled, No Communication		310	445	
$I_{\text{SLEEP}}$ SLEEP mode <sup>(1)</sup>	CPU = HALT, HFO = ON, ADC_FILTER = OFF, CC_FILTER = OFF, LFO = ON, REG18 = ON, CHG = ON, DSG = ON, ADC = OFF, CC = OFF, Charger Disabled, No Communication		122	183	$\mu\text{A}$
	CPU = HALT, HFO = OFF, ADC_FILTER = OFF, CC_FILTER = OFF, LFO = ON, REG18 = ON, CHG = ON, DSG = ON, ADC = OFF, CC = OFF, Charger Disabled, No Communication		92	138	
	CPU = HALT, HFO = ON, ADC_FILTER = OFF, CC_FILTER = OFF, LFO = ON, REG18 = ON, CHG = OFF, DSG = OFF, ADC = OFF, CC = OFF, Charger Disabled, No Communication		82	128	
	CPU = HALT, HFO = OFF, ADC_FILTER = OFF, CC_FILTER = OFF, LFO = ON, REG18 = ON, CHG = OFF, DSG = OFF, ADC = OFF, CC = OFF, Charger Disabled, No Communication		52	83	
$I_{\text{SHUTDOWN}}$ SHUTDOWN mode	CPU = HALT, HFO = OFF, ADC_FILTER = OFF, CC_FILTER = OFF, LFO = OFF, REG18 = OFF, CHG = OFF, DSG = OFF, ADC = OFF, CC = OFF, Charger Disabled, No Communication		0.5	2	$\mu\text{A}$

(1)  $V_{\text{CC}} \leq 20 \text{ V}$  when CHG = ON and DSG = ON

## 7.7 Power Supply Control

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{\text{CC}} = 10.8 \text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{\text{CC}} = 2.2 \text{ V}$  to  $26 \text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{SWITCHOVER-}}$ BAT to VCC switchover voltage	$V_{\text{BAT}} < V_{\text{SWITCHOVER-}}$	2.0	2.1	2.2	V
$V_{\text{SWITCHOVER+}}$ VCC to BAT switchover voltage	$V_{\text{BAT}} > V_{\text{SWITCHOVER-}} + V_{\text{HYS}}$	3.0	3.1	3.2	V
$V_{\text{HYS}}$ Switchover voltage hysteresis	$V_{\text{SWITCHOVER+}} - V_{\text{SWITCHOVER-}}$		1000		mV
$I_{\text{LKG}}$ Input leakage current	BAT pin, BAT = 0 V, VCC = 25 V			1	$\mu\text{A}$
	VCC pin, BAT = 25 V, VCC = 0 V			1	
	BAT and VCC pins, BAT = 0 V, VCC = 0 V, PBI = 25 V			1	
$R_{\text{PD}}$ Internal pulldown resistance	ACP	30	40	50	k $\Omega$

## 7.8 Low-Voltage General Purpose I/O (TSx)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{\text{CC}} = 10.8 \text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{\text{CC}} = 2.2 \text{ V}$  to  $26 \text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{IH}}$ High-level input		$0.65 \times V_{\text{REG}}$			V
$V_{\text{IL}}$ Low-level input			$0.35 \times V_{\text{REG}}$		V
$V_{\text{OH}}$ Output voltage high	$I_{\text{OH}} = -1.0 \text{ mA}$	$0.75 \times V_{\text{REG}}$			V
	$I_{\text{OH}} = -10 \mu\text{A}$				
$V_{\text{OL}}$ Output voltage low	$I_{\text{OL}} = 1.0 \text{ mA}$		$0.2 \times V_{\text{REG}}$		V

## Low-Voltage General Purpose I/O (TSx) (continued)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$C_{IN}$ Input capacitance			5		pF
$I_{LKG}$ Input leakage current				1	$\mu\text{A}$

## 7.9 High-Voltage General Purpose I/O (GPIO0, GPIO1)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IH}$ High-level input		1.3			V
$V_{IL}$ Low-level input				0.55	V
$V_{OH}$ Output voltage high	$V_{BAT} > 5.5\text{ V}$ , $I_{OH} = -0\text{ }\mu\text{A}$	3.5			V
	$V_{BAT} > 5.5\text{ V}$ , $I_{OH} = -10\text{ }\mu\text{A}$	1.8			
$V_{OL}$ Output voltage low	$I_{OL} = 1.5\text{ mA}$			0.4	V
$C_{IN}$ Input capacitance			5		pF
$I_{LKG}$ Input leakage current				1	$\mu\text{A}$
$R_O$ Output reverse resistance	Between GPIO0/1 and PBI	5			k $\Omega$

## 7.10 AFE Power-On Reset

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{REGIT-}$ Negative-going voltage input	$V_{REG}$	1.51	1.55	1.59	V
$V_{HYS}$ Power-on reset hysteresis	$V_{REGIT+} - V_{REGIT-}$	70	100	130	mV
$t_{RST}$ Power-on reset time		200	300	400	$\mu\text{s}$

## 7.11 Internal 1.8-V LDO

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{REG}$ Regulator voltage		1.6	1.8	2.0	V
$\Delta V_{O(TEMP)}$ Regulator output over temperature	$\Delta V_{REG}/\Delta T_A$ , $I_{REG} = 10\text{ mA}$		$\pm 0.25\%$		
$\Delta V_{O(LINE)}$ Line regulation	$\Delta V_{REG}/\Delta V_{BAT}$ , $V_{BAT} = 10\text{ mA}$	-0.6%		0.5%	
$\Delta V_{O(LOAD)}$ Load regulation	$\Delta V_{REG}/\Delta I_{REG}$ , $I_{REG} = 0\text{ mA}$ to $10\text{ mA}$	-1.5%		1.5%	
$I_{REG}$ Regulator output current limit	$V_{REG} = 0.9 \times V_{REG(NOM)}$ , $V_{IN} > 2.2\text{ V}$	20			mA
$I_{SC}$ Regulator short-circuit current limit	$V_{REG} = 0 \times V_{REG(NOM)}$	25	40	50	mA
$PSRR_{REG}$ Power supply rejection ratio	$\Delta V_{BAT}/\Delta V_{REG}$ , $I_{REG} = 10\text{ mA}$ , $V_{IN} > 2.5\text{ V}$ , $f = 10\text{ Hz}$		40		dB
$V_{SLEW}$ Slew rate enhancement voltage threshold		1.58	1.65		V



## 7.12 Current Wake Comparator

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{WAKE}$ Wake voltage threshold	$V_{WAKE} = V_{SRP} - V_{SRN}$	$\pm 0.3$	$\pm 0.625$	$\pm 0.9$	mV
	$V_{WAKE} = V_{SRP} - V_{SRN}$	$\pm 0.6$	$\pm 1.25$	$\pm 1.8$	
	$V_{WAKE} = V_{SRP} - V_{SRN}$	$\pm 1.2$	$\pm 2.5$	$\pm 3.6$	
	$V_{WAKE} = V_{SRP} - V_{SRN}$	$\pm 2.4$	$\pm 5.0$	$\pm 7.2$	
$V_{WAKE(DRIFT)}$ Temperature drift of $V_{WAKE}$ accuracy			0.5%		$^\circ\text{C}$
$t_{WAKE}$ Time from application of current to wake			0.25	0.5	ms
$t_{WAKE(SU)}$ Wake comparator startup time			500	1000	$\mu\text{s}$

## 7.13 Coulomb Counter<sup>(1)</sup>

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input voltage range		-0.1		0.1	V
Full scale range		$-V_{REF1}/10$		$V_{REF1}/10$	V
Integral nonlinearity <sup>(2)</sup>	16-bit, Best fit over input voltage range		$\pm 5.2$	$\pm 22.3$	LSB
Offset error	16-bit, Post-calibration		$\pm 5$	$\pm 10$	$\mu\text{V}$
Offset error drift	15-bit + sign, Post-calibration		0.2	0.3	$\mu\text{V}/^\circ\text{C}$
Gain error	15-bit + sign, Over input voltage range		$\pm 0.2\%$	$\pm 0.8\%$	FSR <sup>(3)</sup>
Gain error drift	15-bit + sign, Over input voltage range			150	PPM/ $^\circ\text{C}$
Effective input resistance		2.5			M $\Omega$

(1) Coulomb counter electrical specifications are assured when battery charging function is disabled.

(2) 1 LSB =  $V_{REF1}/(10 \times 2^N) = 1.215/(10 \times 2^{15}) = 3.71\text{ }\mu\text{V}$

(3) Full-scale reference

## 7.14 CC Digital Filter

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Conversion time	Single conversion		250		ms
Effective resolution	Single conversion	15			Bits

## 7.15 ADC<sup>(1)</sup>

Over-operating free-air temperature range (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input voltage range	Internal reference ( $V_{REF1}$ )	-0.2		1	V
	External reference ( $V_{REG}$ )	-0.2	$0.8 \times V_{REG}$		
Full scale range	$V_{FS} = V_{REF1}$ or $V_{REG}$	$-V_{FS}$		$V_{FS}$	V
Integral nonlinearity <sup>(2)</sup>	16-bit, Best fit, $-0.1\text{ V}$ to $0.8 \times V_{REF1}$			$\pm 6.6$	LSB
	16-bit, Best fit, $-0.2\text{ V}$ to $-0.1\text{ V}$			$\pm 13.1$	
Offset error <sup>(3)</sup>	16-bit, Post-calibration, $V_{FS} = V_{REF1}$		$\pm 67$	$\pm 157$	$\mu\text{V}$

(1) ADC electrical specifications are assured when battery charging function is disabled.

(2) 1 LSB =  $V_{REF1}/(2^N) = 1.225/(2^{15}) = 37.4\text{ }\mu\text{V}$  (when ADCTL[SPEED1, SPEED0] = 0, 0)

(3) For VC1-VSS, VC2-VC1, VC3-VC2, VC3-VSS, ACP-VSS, and  $V_{REF1}/2$ , the offset error is multiplied by (1/ADC multiplexer scaling factor (K)).

## ADC<sup>(1)</sup> (continued)

Over-operating free-air temperature range (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Offset error drift	16-bit, Post-calibration, $V_{FS} = V_{REF1}$		0.6	3	$\mu\text{V}/^{\circ}\text{C}$
Gain error	16-bit, $-0.1\text{ V}$ to $0.8 \times V_{FS}$		$\pm 0.2\%$	$\pm 0.8\%$	FSR
Gain error drift	16-bit, $-0.1\text{ V}$ to $0.8 \times V_{FS}$			150	PPM/ $^{\circ}\text{C}$
Effective input resistance		8			M $\Omega$

## 7.16 ADC Digital Filter

Typical values stated where  $T_A = 25^{\circ}\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Conversion time	ADCTL[SPEED1, SPEED0] = 0, 0		31.25		ms
	ADCTL[SPEED1, SPEED0] = 0, 1		15.63		
	ADCTL[SPEED1, SPEED0] = 1, 0		7.81		
	ADCTL[SPEED1, SPEED0] = 1, 1		1.95		
Resolution	No missing codes, ADCTL[SPEED1, SPEED0] = 0, 0	16			Bits
Effective resolution	With sign, ADCTL[SPEED1, SPEED0] = 0, 0	14	15		Bits
	With sign, ADCTL[SPEED1, SPEED0] = 0, 1	13	14		
	With sign, ADCTL[SPEED1, SPEED0] = 1, 0	11	12		
	With sign, ADCTL[SPEED1, SPEED0] = 1, 1	9	10		

## 7.17 ADC Multiplexer

Typical values stated where  $T_A = 25^{\circ}\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
K      Scaling factor	VC1–VSS, VC2–VC1, VC3–VC2, VC4–VC3	0.1980	0.2000	0.2020	—
	VC4–VSS, ACP–VSS	0.049	0.050	0.051	
	$V_{REF2}$	0.490	0.500	0.510	
	HSRN–VSS	0.049	0.050	0.051	
$V_{IN}$ Input voltage range	VC4–VSS, ACP–VSS	–0.2		20	V
	TSx	–0.2		$0.8 \times V_{REF1}$	
	TSx	–0.2		$0.8 \times V_{REG}$	
$I_{LKG}$ Input leakage current	VC1, VC2, VC3, VC4, cell balancing off, cell detach detection off, ADC multiplexer off			1	$\mu\text{A}$

## 7.18 Cell Balancing Support

Typical values stated where  $T_A = 25^{\circ}\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$R_{CB}$ Internal cell balance resistance	$R_{DS(ON)}$ for internal FET switch at $2\text{ V} < V_{DS} < 4\text{ V}$			200	$\Omega$

## 7.19 Cell Detach Detection

Typical values stated where  $T_A = 25^{\circ}\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{CD}$ Internal cell detach check current	$VCx > VSS + 0.8\text{ V}$	30	50	70	$\mu\text{A}$

## 7.20 Internal Temperature Sensor

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{TEMP}$ Internal temperature sensor voltage drift	$V_{TEMPPP}$	-1.9	-2.0	-2.1	mV/ $^\circ\text{C}$
	$V_{TEMPPP} - V_{TEMPN}$ , assured by design	0.177	0.178	0.179	

## 7.21 NTC Thermistor Measurement Support (ADCx)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$R_{NTC(PU)}$ Internal pullup resistance		14.4	18	21.6	k $\Omega$
$R_{NTC(DRIFT)}$ Resistance drift over temperature		-360	-280	-200	PPM/ $^\circ\text{C}$

## 7.22 High-Frequency Oscillator

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$f_{HFO}$ Operating frequency			16.78		MHz
$f_{HFO(ERR)}$ Frequency error	$T_A = -20^\circ\text{C}$ to $70^\circ\text{C}$ , includes frequency drift	-2.5%	$\pm 0.25\%$	2.5%	
	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$ , includes frequency drift	-3.5%	$\pm 0.25\%$	3.5%	
$t_{HFO(SU)}$ Start-up time	$T_A = -20^\circ\text{C}$ to $85^\circ\text{C}$ , CLKCTL[HFRAMP] = 1, oscillator frequency within $\pm 3\%$ of nominal			4	ms
	CLKCTL[HFRAMP] = 0, oscillator frequency within $\pm 3\%$ of nominal			100	$\mu\text{s}$

## 7.23 Low-Frequency Oscillator

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$f_{LFO}$ Operating frequency			262.144		kHz
$f_{LFO(ERR)}$ Frequency error	$T_A = -20^\circ\text{C}$ to $70^\circ\text{C}$ , includes frequency drift	-1.5%	$\pm 0.25\%$	1.5%	
	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$ , includes frequency drift	-2.5	$\pm 0.25$	2.5	
$f_{LFO(FAIL)}$ Failure detection frequency		30	80	100	kHz

## 7.24 Voltage Reference 1

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{REF1}$ Internal reference voltage	$T_A = 25^\circ\text{C}$ , after trim	1.21	1.215	1.22	V
$V_{REF1(DRIFT)}$ Internal reference voltage drift	$T_A = 0^\circ\text{C}$ to $60^\circ\text{C}$ , after trim		$\pm 50$		PPM/ $^\circ\text{C}$
	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$ , after trim		$\pm 80$		

## 7.25 Voltage Reference 2

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{REF2}$ Internal reference voltage	$T_A = 25^\circ\text{C}$ , after trim	1.22	1.225	1.23	V
$V_{REF2(DRIFT)}$ Internal reference voltage drift	$T_A = 0^\circ\text{C}$ to $60^\circ\text{C}$ , after trim		$\pm 50$		PPM/ $^\circ\text{C}$
	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$ , after trim		$\pm 80$		

## 7.26 Instruction Flash

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Data retention		10			Years
Flash programming write cycles		1000			Cycles
$t_{PROGWORD}$ Word programming time	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			40	$\mu\text{s}$
$t_{MASSERASE}$ Mass-erase time	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			40	ms
$t_{PAGEERASE}$ Page-erase time	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			40	ms
$I_{FLASHREAD}$ Flash-read current	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			2	mA
$I_{FLASHWRITE}$ Flash-write current	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			5	mA
$I_{FLASHERASE}$ Flash-erase current	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			15	mA

## 7.27 Data Flash

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Data retention		10			Years
Flash programming write cycles		20000			Cycles
$t_{PROGWORD}$ Word programming time	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			40	$\mu\text{s}$
$t_{MASSERASE}$ Mass-erase time	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			40	ms
$t_{PAGEERASE}$ Page-erase time	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			40	ms
$I_{FLASHREAD}$ Flash-read current	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			1	mA
$I_{FLASHWRITE}$ Flash-write current	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			5	mA
$I_{FLASHERASE}$ Flash-erase current	$T_A = -40^\circ\text{C}$ to $85^\circ\text{C}$			15	mA

## 7.28 Current Protection Thresholds

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{OCD}$ OCD detection threshold voltage range	$V_{OCD} = V_{SRP} - V_{SRN}$ , PROTECTION_CONTROL[RSNS] = 1	-16.6		-100	mV
	$V_{OCD} = V_{SRP} - V_{SRN}$ , PROTECTION_CONTROL[RSNS] = 0	-8.3		-50	
$\Delta V_{OCD}$ OCD detection threshold voltage program step	$V_{OCD} = V_{SRP} - V_{SRN}$ , PROTECTION_CONTROL[RSNS] = 1		-5.56		mV
	$V_{OCD} = V_{SRP} - V_{SRN}$ , PROTECTION_CONTROL[RSNS] = 0		-2.78		
$V_{SCC}$ SCC detection threshold voltage range	$V_{SCC} = V_{SRP} - V_{SRN}$ , PROTECTION_CONTROL[RSNS] = 1	44.4		200	mV
	$V_{SCC} = V_{SRP} - V_{SRN}$ , PROTECTION_CONTROL[RSNS] = 0	22.2		100	

## Current Protection Thresholds (continued)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$\Delta V_{\text{SCC}}$	SCC detection threshold voltage program step $V_{\text{SCC}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 1		22.2		mV
	$V_{\text{SCC}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 0		11.1		
$V_{\text{SCD1}}$	SCD1 detection threshold voltage range $V_{\text{SCD1}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 1	-44.4		-200	mV
	$V_{\text{SCD1}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 0	-22.2		-100	
$\Delta V_{\text{SCD1}}$	SCD1 detection threshold voltage program step $V_{\text{SCD1}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 1		-22.2		mV
	$V_{\text{SCD1}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 0		-11.1		
$V_{\text{SCD2}}$	SCD2 detection threshold voltage range $V_{\text{SCD2}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 1	-44.4		-200	mV
	$V_{\text{SCD2}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 0	-22.2		-100	
$\Delta V_{\text{SCD2}}$	SCD2 detection threshold voltage program step $V_{\text{SCD2}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 1		-22.2		mV
	$V_{\text{SCD2}} = V_{\text{SRP}} - V_{\text{SRN}}$ , PROTECTION_CONTROL[RSNS] = 0		-11.1		
$V_{\text{OFFSET}}$	OCD, SCC, and SCDx offset error Post-trim	-2.5		2.5	mV
$V_{\text{SCALE}}$	OCD, SCC, and SCDx scale error No trim	-10%		10%	
	Post-trim	-5%		5%	

## 7.29 N-CH FET Drive (CHG, DSG)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Output voltage ratio	$\text{Ratio}_{\text{DSG}} = (V_{\text{DSG}} - V_{\text{BAT}})/V_{\text{BAT}}$ , $2.2\text{ V} < V_{\text{BAT}} < 4.07\text{ V}$ , $10\text{ M}\Omega$ between HSRN and DSG	2.133	2.333	2.533	—
	$\text{Ratio}_{\text{CHG}} = (V_{\text{CHG}} - V_{\text{BAT}})/V_{\text{BAT}}$ , $2.2\text{ V} < V_{\text{BAT}} < 4.07\text{ V}$ , $10\text{ M}\Omega$ between BAT and CHG	2.133	2.333	2.533	
	$\text{Ratio}_{\text{ACFET}} = (V_{\text{ACFET}} - V_{\text{BAT}})/V_{\text{BAT}}$ , $2.2\text{ V} < V_{\text{BAT}} < 4.07\text{ V}$ , $10\text{ M}\Omega$ between ACP and ACFET	2.133	2.333	2.533	
$V_{\text{(FETON)}}$	Output voltage, CHG and DSG on $V_{\text{DSG(ON)}} = V_{\text{DSG}} - V_{\text{BAT}}$ , $V_{\text{BAT}} \geq 4.07\text{ V}$ , $10\text{ M}\Omega$ between $V_{\text{HSRN}}$ and DSG, $V_{\text{BAT}} = 18\text{ V}$	9.0	9.5	10	V
	$V_{\text{CHG(ON)}} = V_{\text{CHG}} - V_{\text{BAT}}$ , $V_{\text{BAT}} \geq 4.07\text{ V}$ , $10\text{ M}\Omega$ between BAT and CHG, $V_{\text{BAT}} = 18\text{ V}$	9.0	9.5	10	
	ACFET $V_{\text{ACFET(ON)}} = V_{\text{ACFET}} - V_{\text{BAT}}$ , $V_{\text{BAT}} \geq 4.07\text{ V}$ , $10\text{ M}\Omega$ between ACP and ACFET, $V_{\text{BAT}} = 18\text{ V}$	9.0	9.5	10	
$V_{\text{(FETOFF)}}$	Output voltage, CHG and DSG off $V_{\text{DSG(OFF)}} = V_{\text{DSG}} - V_{\text{ACP}}$ , $10\text{ M}\Omega$ between HSRN and DSG	-0.4		0.4	V
	$V_{\text{CHG(OFF)}} = V_{\text{CHG}} - V_{\text{BAT}}$ , $10\text{ M}\Omega$ between BAT and CHG	-0.4		0.4	
	ACFET $V_{\text{ACFET(OFF)}} = V_{\text{ACFET}} - V_{\text{ACP}}$ , $V_{\text{BAT}} \geq 4.07\text{ V}$ , $10\text{ M}\Omega$ between ACP and ACFET, $V_{\text{BAT}} = 18\text{ V}$	-0.4		0.4	
$t_R$	Rise time $V_{\text{DSG}}$ from 0% to 35% $V_{\text{DSG(ON)(TYP)}}$ , $V_{\text{ACP}} \geq 2.2\text{ V}$ , $C_L = 4.7\text{ nF}$ between DSG and $V_{\text{HSRN}}$ , $5.1\text{ k}\Omega$ between DSG and $C_L$ , $10\text{ M}\Omega$ between $V_{\text{HSRN}}$ and DSG		200	500	$\mu\text{s}$
	$V_{\text{CHG}}$ from 0% to 35% $V_{\text{CHG(ON)(TYP)}}$ , $V_{\text{ACP}} \geq 2.2\text{ V}$ , $C_L = 4.7\text{ nF}$ between CHG and BAT, $5.1\text{ k}\Omega$ between CHG and $C_L$ , $10\text{ M}\Omega$ between BAT and CHG		200	500	
	$V_{\text{ACFET}}$ from 0% to 35% $V_{\text{ACFET(ON)(TYP)}}$ , $V_{\text{ACP}} \geq 2.2\text{ V}$ , $C_L = 4.7\text{ nF}$ between ACFET and ACP, $5.1\text{ k}\Omega$ between CHG and $C_L$ , $10\text{ M}\Omega$ between ACP and ACFET		200	500	

## N-CH FET Drive (CHG, DSG) (continued)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_F$ Fall time	$V_{DSG}$ from $V_{DSG(ON)(TYP)}$ to $1\text{ V}$ , $V_{ACP} \geq 2.2\text{ V}$ , $C_L = 4.7\text{ nF}$ between DSG and ACP, $5.1\text{ k}\Omega$ between DSG and $C_L$ , $10\text{ M}\Omega$ between ACP and DSG		40	300	$\mu\text{s}$
	$V_{CHG}$ from $V_{CHG(ON)(TYP)}$ to $1\text{ V}$ , $V_{ACP} \geq 2.2\text{ V}$ , $C_L = 4.7\text{ nF}$ between CHG and BAT, $5.1\text{ k}\Omega$ between CHG and $C_L$ , $10\text{ M}\Omega$ between BAT and CHG		40	200	
	$V_{ACFET}$ from $V_{ACFET(ON)(TYP)}$ to $1\text{ V}$ , $V_{ACP} \geq 2.2\text{ V}$ , $C_L = 4.7\text{ nF}$ between ACFET and ACP, $5.1\text{ k}\Omega$ between CHG and $C_L$ , $10\text{ M}\Omega$ between ACP and ACFET		40	200	

## 7.30 FUSE Drive (AFEFUSE)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{OH}$ Output voltage high	$V_{BAT} \geq 8\text{ V}$ , $C_L = 1\text{ nF}$ , $I_{AFEFUSE} = 0\text{ }\mu\text{A}$	6	7	8.65	V
	$V_{BAT} < 8\text{ V}$ , $C_L = 1\text{ nF}$ , $I_{AFEFUSE} = 0\text{ }\mu\text{A}$	$V_{BAT} - 0.1$		$V_{BAT}$	
$V_{IH}$ High-level input		1.5	2.0	2.5	V
$I_{AFEFUSE(PU)}$ Internal pullup current	$V_{BAT} \geq 8\text{ V}$ , $V_{AFEFUSE} = V_{SS}$		150	330	nA
$R_{AFEFUSE}$ Output impedance		2	2.6	3.2	k $\Omega$
$C_{IN}$ Input capacitance			5		pF
$t_{DELAY}$ Fuse trip detection delay		128		256	$\mu\text{s}$
$t_{RISE}$ Fuse output rise time	$V_{BAT} \geq 8\text{ V}$ , $C_L = 1\text{ nF}$ , $V_{OH} = 0\text{ V}$ to $5\text{ V}$		5	20	$\mu\text{s}$

## 7.31 Battery Charger Voltage Regulation (VFB)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{FB}$ Regulation range	Based on internal DAC reference setting	0.61		1.22	V
$V_{FBACC}$ Voltage feedback accuracy	$V_{FB} = 1.22\text{ V}$	-2%		2%	
$V_{FB(STEPS)}$ Programmable regulation steps			2.5		mV
$R_{VFB}$ Total feedback resistor divider range			500	700	k $\Omega$

## 7.32 Battery Charger Current Sense (HSRP, HSRN)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IN(Normal\ range)}$ Differential Input range	DAC range for current measurement	2		100	mV
$V_{ACC}$ Measurement accuracy	$V_{HSRP} - V_{HSRN} = 50\text{ mV}$ , $R_{Sense} = 10\text{ m}\Omega$	-5%		5%	

### 7.33 Battery Charger Precharge Current Sense (HSRP, HSRN)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IN(\text{Normal range})}$ Differential Input range	DAC range for current measurement	2		20	mV
$V_{ACC}$ Measurement accuracy	$V_{HSRP} - V_{HSRN} = 2\text{ mV}$ , $R_{Sense} = 10\text{ m}\Omega$ ( $V_{HSRN} > 2.3\text{ V}$ )	-70%		70%	

### 7.34 AC Adapter Fault Detect (HSRN, VCC)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{HSRN} - V_{CC}$ AC adapter input fault detect	Battery > AC adapter input (Falling)	150	225	300	mV
$V_{Hys}$ Recovery hysteresis	AC adapter input > Battery (Rising)	50	100	150	mV

### 7.35 Battery Charger Overcurrent Detection ( $V_{HSRP}$ , $V_{HSRN}$ )

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{OC(\text{max})}$ Charger overcurrent threshold	Charging current as a percentage of max sense voltage range		180	200	mV
$I_{OC(\text{min})}$ Charger overcurrent threshold	Minimum charging overcurrent detected	45	55		mV

### 7.36 Battery Charger Undercurrent Detection ( $V_{HSRP}$ , $V_{HSRN}$ )

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{UC(\text{Detect})}$ Detect under current for negative inductor current	$V_{HSRP} - V_{HSRN} < 0\text{ mV}$ , for negative inductor current, $V_{HSRP} > 2.3\text{ V}$	1	5	16	mV
$I_{UC(\text{Non-synch})}$ Minimum sense voltage to enter non-synchronous mode			1.7		mV

### 7.37 System Operation Detection ( $V_{HSRN}$ )

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{HSRN}$ Input voltage for operation	$V_{HSRN}$ Falling	2.05	2.15	2.25	V
$V_{Hys}$ Recovery hysteresis	$V_{HSRN}$ Rising	100	150	200	mV

### 7.38 Battery Overvoltage Comparator (VFB)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{OV(\text{max})}$ Battery over-voltage detection	$V_{FB} > \text{Set value}$ (Rising)		106%		
$V_{OV(\text{Recovery})}$ Battery over-voltage recovery	$V_{FB} < V_{OV}$ (Falling)		103%		

### 7.39 Regulator (REGN)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{LODRV}}$	Gate drive for low side charger FET	$V_{CC} > 10\text{ V}$ , $I_{\text{Load}} = 0$ to $60\text{ mA}$	5.7	6.0	6.3	V
$I_{\text{SC}}$	Short circuit current limit	$V_{\text{LODRV}} = 0\text{ V}$	60			mA
$V_{\text{REGN}}$	Power good indicator	$V_{\text{REGN}}$ Rising	3.6	3.68	3.75	V
$V_{\text{Hys}}$	Hysteresis	$V_{\text{REGN}}$ Falling	240	260	280	mV

### 7.40 PWM High-Side Driver (HiDRV)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$R_{\text{ON}}$	Driver turn ON resistance	$V_{\text{BTST}} - V_{\text{PH}} \geq 5.5\text{ V}$		6.0	8.6	$\Omega$
$R_{\text{OFF}}$	Driver turn OFF resistance	$V_{\text{FB}} < V_{\text{OV}}$ (Falling)		2.5	3.3	$\Omega$
$V_{\text{BOOTSTRAP}}$	Bootstrap refresh comparator	$V_{CC} = 4\text{ V}$ to $6\text{ V}$	2.6	2.9		V
		$V_{CC} > 6\text{ V}$	3.9	4.1		V

### 7.41 PWM Low-Side Driver (LoDRV)

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$R_{\text{ON}}$	Driver turn ON resistance	$V_{\text{REGN}} - V_{\text{PGND}} \geq 5.5\text{ V}$	5.2		7.6	$\Omega$
$R_{\text{OFF}}$	Driver turn OFF resistance	$V_{\text{FB}} < V_{\text{OV}}$ (Falling)	1.9		2.4	$\Omega$

### 7.42 PWM Information

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{\text{DEADTIME}}$	Deadtime between FET driver output switching			30		ns
Duty cycle					99.5%	
$f_{\text{SW}}$	PWM switching frequency		0.8	1.0	1.1	MHz

### 7.43 Charger Power-Up Sequence

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{\text{DELAY}}$	Power-up sequence			8		ms
$t_{\text{SS(STEPS)}}$	Soft start steps			8		
$t_{\text{SS(STEP TIME)}}$	Soft start time			2		ms

### 7.44 Thermal Shutdown Comparator

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$T_{\text{SHUTDOWN}}$				135	145	C
$T_{\text{Hys}}$				12		C



## 7.45 SMBus High Voltage I/O

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IH}$	Input voltage high	1.3			V
$V_{IL}$	Input voltage low			0.8	V
$V_{OL}$	Output low voltage			0.4	V
$C_{IN}$	Input capacitance		5		pF
$I_{LKG}$	Input leakage current			1	$\mu\text{A}$
$R_{PD}$	pulldown resistance	0.7	1.0	1.3	$\text{M}\Omega$

## 7.46 SMBus

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$f_{SMB}$	SMBus operating frequency	10		100	kHz
$f_{MAS}$	SMBus master clock frequency		51.2		kHz
$t_{BUF}$	Bus free time between start and stop	4.7			$\mu\text{s}$
$t_{HD(START)}$	Hold time after (repeated) start	4.0			$\mu\text{s}$
$t_{SU(START)}$	Repeated start setup time	4.7			$\mu\text{s}$
$t_{SU(STOP)}$	Stop setup time	4.0			$\mu\text{s}$
$t_{HD(DATA)}$	Data hold time	300			ns
$t_{SU(DATA)}$	Data setup time	250			ns
$t_{TIMEOUT}$	Error signal detect time	25		35	ms
$t_{LOW}$	Clock low period	4.7			$\mu\text{s}$
$t_{HIGH}$	Clock high period	4.0		50	$\mu\text{s}$
$t_R$	Clock rise time	10% to 90%		1000	ns
$t_F$	Clock fall time	90% to 10%		300	ns
$t_{LOW(SEXT)}$	Cumulative clock low slave extend time			25	ms
$t_{LOW(MEXT)}$	Cumulative clock low master extend time			10	ms

## 7.47 SMBus XL

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 14.4\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

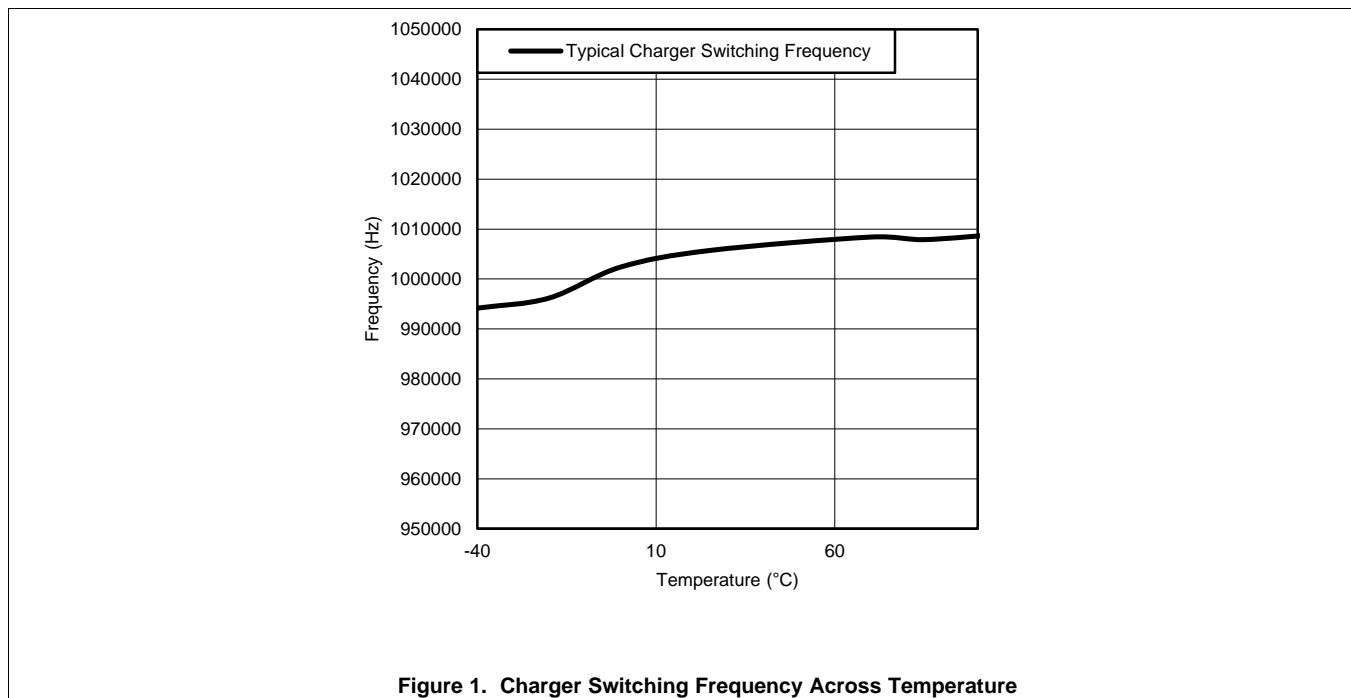
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$f_{SMBXL}$	SMBus XL operating frequency	40		400	kHz
$t_{BUF}$	Bus free time between start and stop	4.7			$\mu\text{s}$
$t_{HD(START)}$	Hold time after (repeated) start	4.0			$\mu\text{s}$
$t_{SU(START)}$	Repeated start setup time	4.7			$\mu\text{s}$
$t_{SU(STOP)}$	Stop setup time	4.0			$\mu\text{s}$
$t_{TIMEOUT}$	Error signal detect time	5		20	ms
$t_{LOW}$	Clock low period			20	$\mu\text{s}$
$t_{HIGH}$	Clock high period			20	$\mu\text{s}$

## 7.48 Timing Requirements

Typical values stated where  $T_A = 25^\circ\text{C}$  and  $V_{CC} = 10.8\text{ V}$ , Min/Max values stated where  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$  and  $V_{CC} = 2.2\text{ V}$  to  $26\text{ V}$  (unless otherwise noted)

			MIN	TYP	MAX	UNIT
<b>CURRENT PROTECTION TIMING</b>						
$t_{\text{OCD}}$	OCD detection delay time		1		31	ms
$\Delta t_{\text{OCD}}$	OCD detection delay time program step			2		ms
$t_{\text{SCC}}$	SCC detection delay time		0		915	$\mu\text{s}$
$\Delta t_{\text{SCC}}$	SCC detection delay time program step			61		$\mu\text{s}$
$t_{\text{SCD1}}$	SCD1 detection delay time	PROTECTION_CONTROL[SCDDx2] = 0	0		915	$\mu\text{s}$
		PROTECTION_CONTROL[SCDDx2] = 1	0		1850	
$\Delta t_{\text{SCD1}}$	SCD1 detection delay time program step	PROTECTION_CONTROL[SCDDx2] = 0		61		$\mu\text{s}$
		PROTECTION_CONTROL[SCDDx2] = 1		121		
$t_{\text{SCD2}}$	SCD2 detection delay time	PROTECTION_CONTROL[SCDDx2] = 0	0		458	$\mu\text{s}$
		PROTECTION_CONTROL[SCDDx2] = 1	0		915	
$\Delta t_{\text{SCD2}}$	SCD2 detection delay time program step	PROTECTION_CONTROL[SCDDx2] = 0		30.5		$\mu\text{s}$
		PROTECTION_CONTROL[SCDDx2] = 1		61		
$t_{\text{DETECT}}$	Current fault detect time	$V_{\text{SRP}} - V_{\text{SRN}} = V_T - 3\text{ mV}$ for OCD, SCD1, and SC2, $V_{\text{SRP}} - V_{\text{SRN}} = V_T + 3\text{ mV}$ for SCC			160	$\mu\text{s}$
$t_{\text{ACC}}$	Current fault delay time accuracy	Max delay setting	-10%		10%	

## 7.49 Typical Characteristics



## 8 Detailed Description

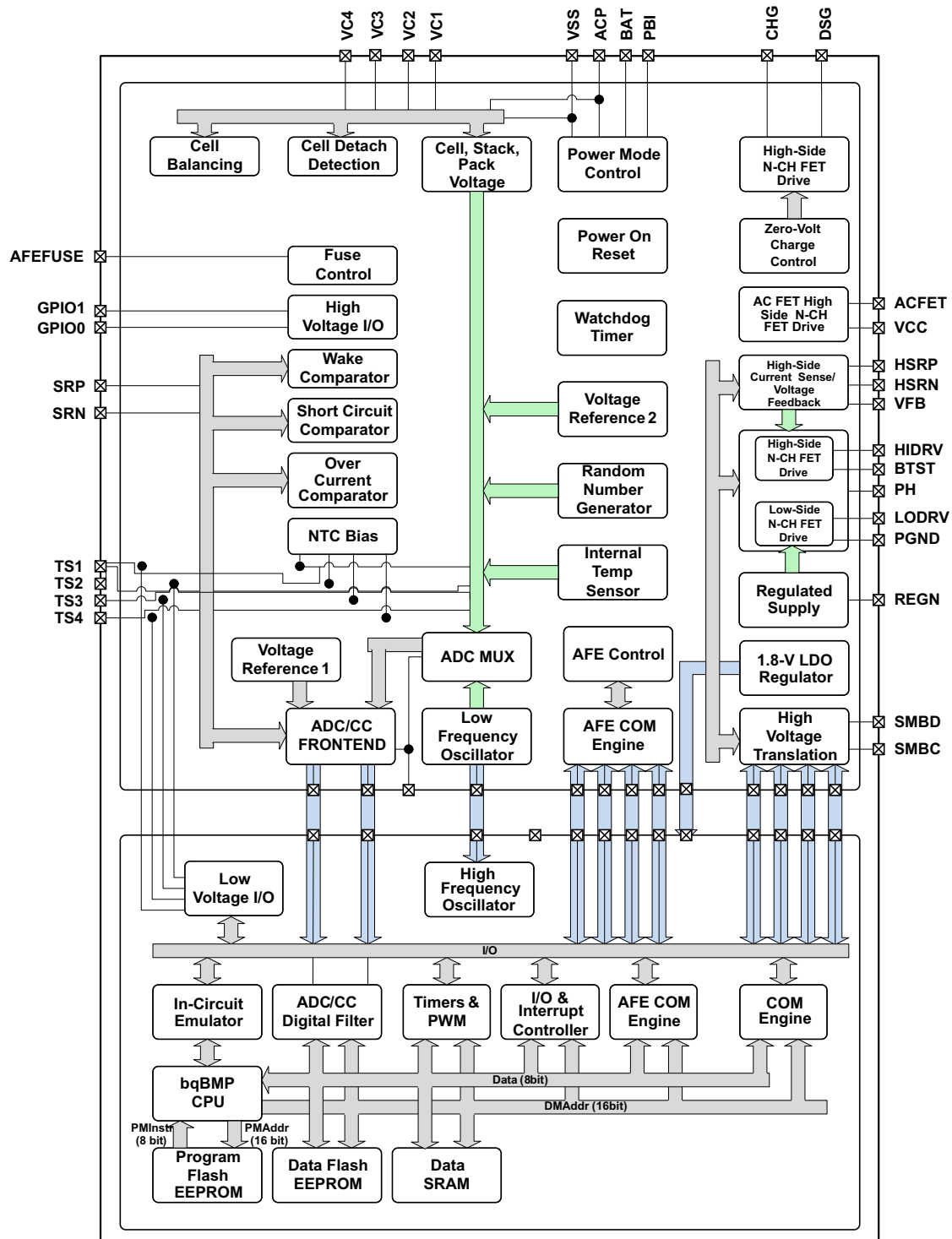
### 8.1 Overview

The bq40z60 is a fully integrated battery manager that employs flash-based firmware and integrated hardware protection to provide a complete solution for 2-series to 4-series cell battery stack architectures. The bq40z60 interfaces with a host system via an SBS v1.1-compliant SMBus interface, and processes instructions and data using a state-of-the-art, ultra-low-power TI bqBMP CPU. High-performance, integrated analog peripherals enable support for a sense resistor down to 5 mΩ, battery charge control, and simultaneous current/voltage data conversion for instant power calculations.

The bq40z60 controls the cell charging profile based on user-programmed data flash parameters for charging current and voltage based on temperature and cell voltage. The gas gauge provides the cell voltage and charging information to the battery charging through an internal communication bus. The charger function is controlled based on cell voltage measurements both on individual cell and total series stack readings.

The analog front end provides this voltage-based information to the charging circuit to set the profiles pre-programmed in the data flash settings, which are useful for zero voltage and PRECHARGE mode operation. The following sections detail all of the major component blocks in the bq40z60 device.

## 8.2 Functional Block Diagram



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## 8.3 Feature Description

The bq40z60 consists of an integrated analog front end, charge controller, and fuel gauge. The following sections provide an overview of the device features. For additional details, refer to the *bq40z60 Technical Reference Manual* (SLUUA04).

### 8.3.1 Safety Features

The bq40z60 provides support for primary safety, including:

- Cell Over/Undervoltage Protection
- Charge and Discharge Overcurrent
- Short Circuit Protection
- Charge and Discharge Overtemperature

The secondary safety features of the bq40z60 can be used to indicate more serious faults via the FUSE pin. This pin can be used to blow an in-line fuse to permanently disable the battery pack from charging or discharging. The secondary safety features provide protection against:

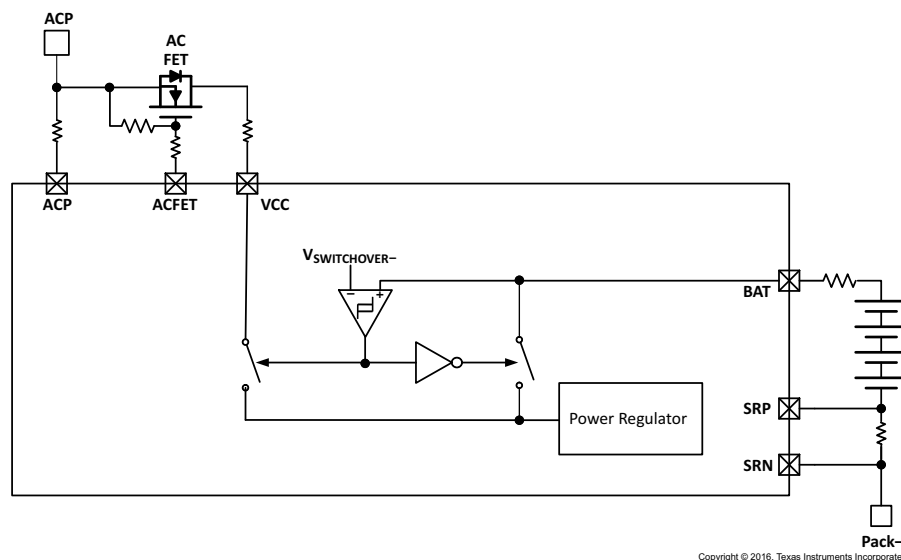
- Safety Over/Undervoltage Permanent Failure
- Safety Overtemperature Permanent Failure
- Safety FET Overtemperature Permanent Failure
- Qmax Imbalance Permanent Failure
- Impedance Imbalance Permanent Failure
- Capacity Degradation Permanent Failure
- Cell Balancing Permanent Failure
- Fuse Failure Permanent Failure
- Voltage Imbalance at Rest Permanent Failure
- Voltage Imbalance Active Permanent Failure
- Charge/Discharge FET Permanent Failure
- Second Level Protector Permanent Failure
- Instruction Flash Checksum Permanent Failure
- Open Cell Connection Permanent Failure
- Data Flash Permanent Failure
- Open Thermistor Permanent Failure

### 8.3.2 Analog Front End (AFE) Details

The analog front end (AFE) consists of circuits responsible for managing internal power and interfacing to outside components for measuring current, voltage, and temperature. The bq40z60 AFE includes an active-high interrupt output connected internally to the fuel gauge to notify it of important changes in some of the AFE registers.

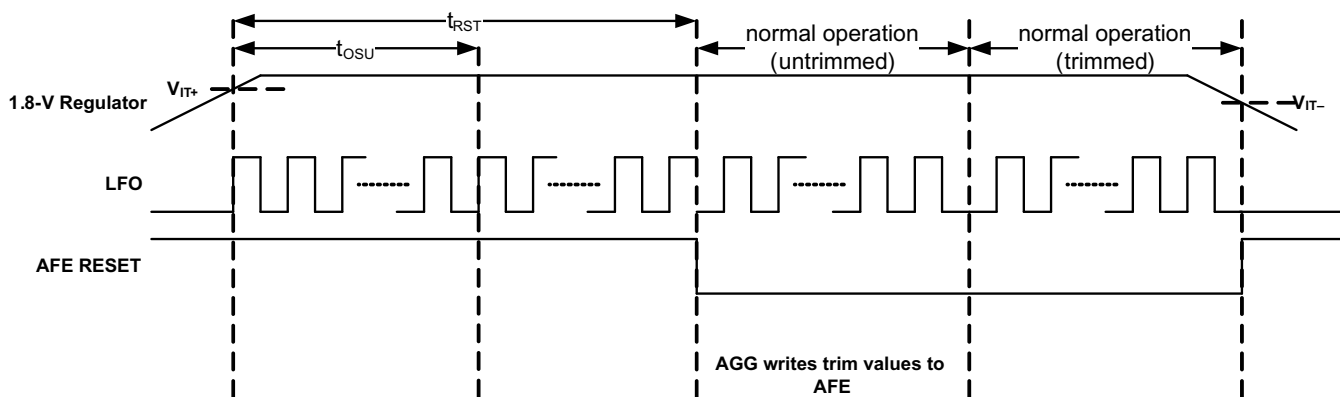
The bq40z60 manages its supply voltage dynamically according to operating conditions. When  $V_{BAT} > V_{SWITCHOVER-} + V_{HYS}$ , the AFE connects an internal switch to BAT and uses this pin to supply power to its internal 1.8-V LDO, which subsequently powers all device logic and flash operations. Once BAT decreases to  $V_{BAT} < V_{SWITCHOVER-}$ , the AFE disconnects its internal switch from BAT and connects another switch to VCC, allowing sourcing of power from a charger (if present). An external capacitor connected to PBI provides a momentary supply voltage to help guard against system brownouts due to transient short-circuit or overload events that pull VBAT below  $V_{SWITCHOVER-}$ .

## Feature Description (continued)



**Figure 2. Internal Power Source Selection**

In the event of a power-cycle, the bq40z60 AFE will hold its internal RESET output pin high for  $t_{RST}$  duration to allow its internal 1.8-V LDO and LFO to stabilize before running the analog gas gauge (AGG). The AFE enters power-on reset when the voltage at  $V_{REG}$  falls below  $V_{REGIT-}$  and exits reset when  $V_{REG}$  rises above  $V_{REGIT-} + V_{HYS}$  for  $t_{RST}$  time. After  $t_{RST}$ , the bq40z60 AGG writes its trim values to the AFE.



**Figure 3. Power-On Reset Operation**

The bq40z60 AFE includes a low frequency oscillator (LFO) running at 262.144 kHz. The AFE monitors the LFO frequency and indicates a failure via LATCH\_STATUS[LFO] if the output frequency is much lower than normal.

The bq40z60 AFE provides two internal voltage references:  $V_{REF1}$ , used by the ADC and CC, and  $V_{REF2}$  used by the LDO, LFO, current wake comparator, and over- and short-current protection circuitry.

### 8.3.2.1 Wake Up Comparator

The internal wake comparator can be used to wake the bq40z60 from a HALT state if a configurable threshold is detected across SRP and SRN.

## Feature Description (continued)

### 8.3.2.2 Cell Balancing Support

The integrated cell balancing FETs included in the bq40z60 device allow the AFE to bypass cell current around a given cell or numerous cells to effectively balance the entire battery stack. External series resistors placed between the cell connections and the VCx input pins set the balancing current magnitude. The cell balancing circuitry can be enabled or disabled via the CELL\_BAL\_DET[CB3, CB2, CB1] control register. Series input resistors between 100  $\Omega$  and 1 k $\Omega$  are recommended for effective cell balancing.

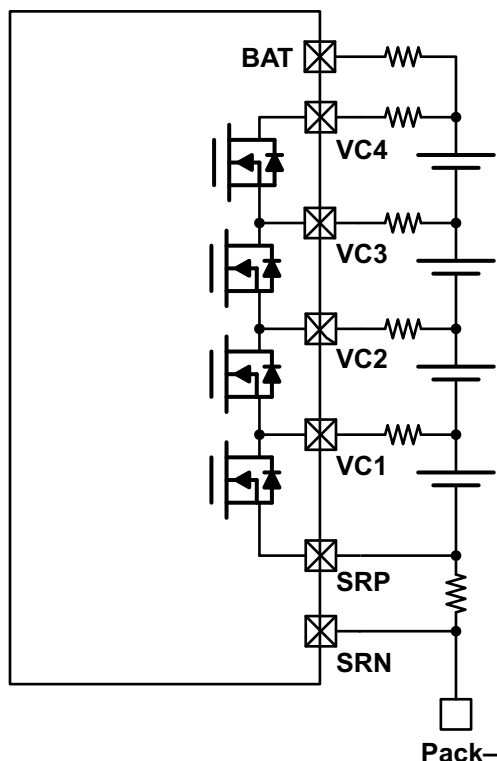


Figure 4. Cell Balancing Configuration

### 8.3.2.3 FET Drive

The bq40z60 controls two external N-CH MOSFETs in a back-to-back configuration for battery protection. The charge (CHG) and discharge (DSG) FETs are automatically disabled if a safety fault is detected and can also be manually turned off using AFE\_CONTROL[CHGEN, DSGEN] = 0, 0. When the gate drive is disabled, an internal circuit discharges CHG to BAT and DSG to HSRN.

The AC FET (N-CH MOSFET) controls power input from the AC adaptor to the battery charging system by monitoring the voltage at the VCC pin, and turning ON the ACFET if the voltage exceeds the  $V_{HSRN}$  voltage. The following register command sets the AC FET gate drive output control, AFE\_STATUS register (0x01) ACFET (Pin 2): Setting this pin to 1 allows the AC FET gate drive to be on if other conditions are satisfied.

### 8.3.2.4 Fuse Drive

The bq40z60 AFE has the ability to blow an external fuse in the event of a permanent failure. The fuse drive itself is supplied from the BAT input pin and its state can be monitored using the AFE\_STATUS[FUSE\_RAW] register. If AFE\_STATUS[FUSE\_RAW] = 1 for  $t_{DELAY}$  duration, then LATCH\_STATUS[FUSE] is set to 1, and after an additional 500 ms, the CHG and DSG FET drive outputs will be disabled if LATCH\_STATUS[FUSE] has not been cleared by then. If the AFEFUSE output is not used, it should be connected to VSS. When AFEFUSE is in the low state, it uses an internal weak pullup to enable detection of disconnection between the AFEFUSE pin and the fuse drive circuitry.

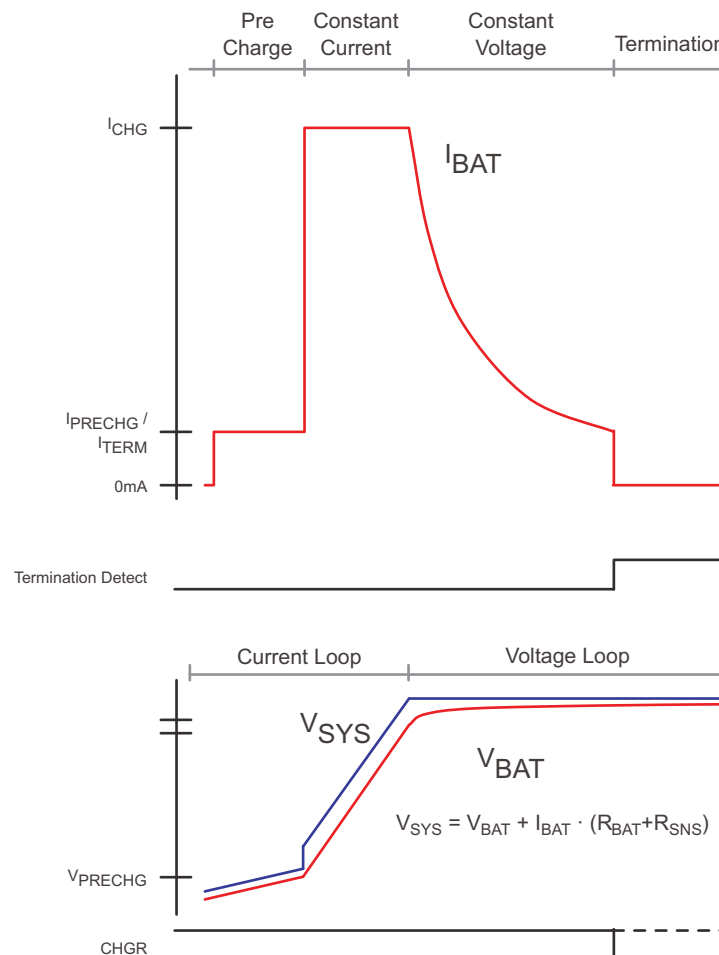
## Feature Description (continued)

### 8.3.3 Charge Controller Details

The charge controller, under control from the fuel gauge's processor, provides autonomous control over the charging of the battery pack. The controller uses a 1-MHz buck architecture using external FETs driven by internal gate drivers. The charge voltage and current can be adjusted via data flash values to account for the temperature and voltage of the battery cells, allowing for a JEITA type charge profile. The voltage and current may also be directly written to the charge controller from an external host, allowing for a user-defined charging profile. The charger runs in Narrow Voltage DC, that is, the output voltage of the charger will only exceed the battery voltage by a small amount; by contrast, a charger that does not run in Narrow Voltage DC mode will output the adapter voltage to the system.

The charger is designed to enable the system to continue to run while the battery is charged. If the system requires more current than the charger is able to provide, the battery supplements the current to the system. The charger can support an external precharge FET, allowing the VSYS to remain above a minimum voltage needed for the system to operate.

The charger supports precharge, constant current/constant voltage, and termination, as shown below. The voltage and current thresholds for precharge and termination are controlled by data flash values. Refer to the *bq40z60 Technical Reference Manual* ([SLUUA04](#)) for more information.



**Figure 5. Normal Charge Profile**

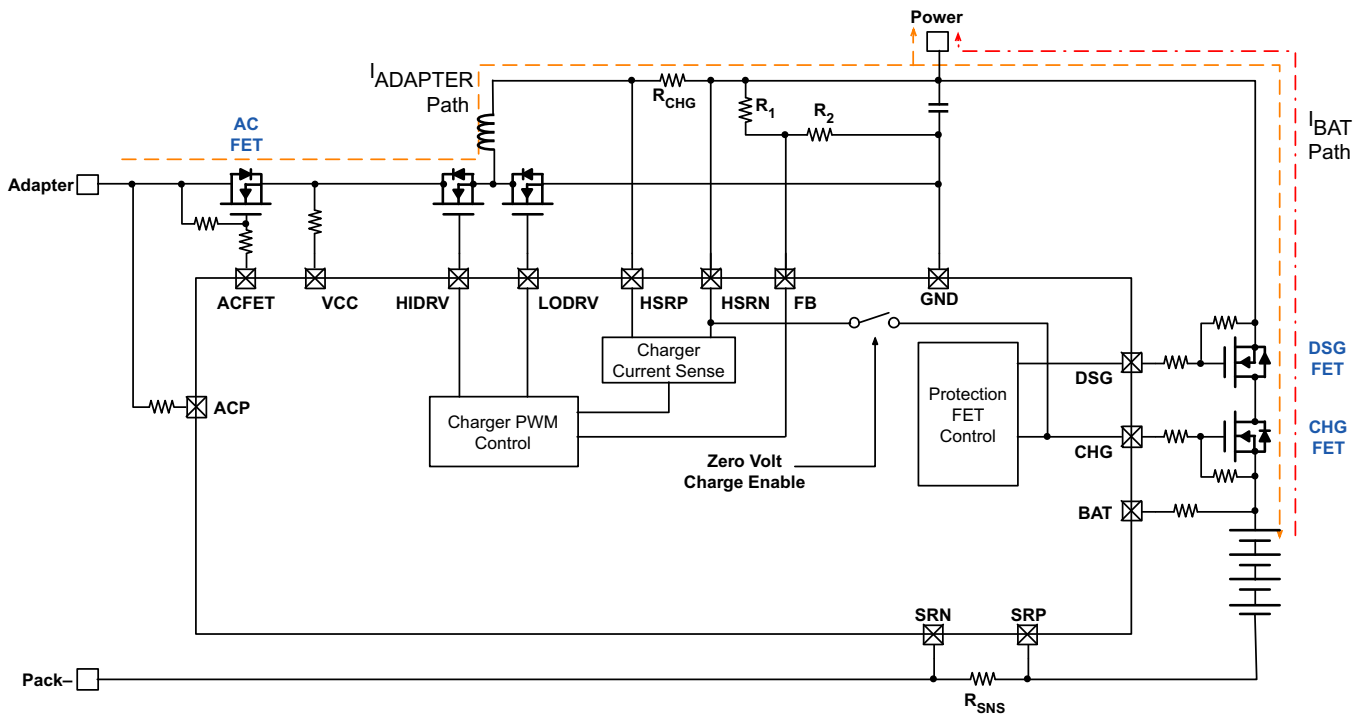


## Feature Description (continued)

The charger maintains a cycle-by-cycle current limit by sensing across a resistor in series with the inductor (shown in Figure 6 as  $R_{CHG}$ ). In precharge and constant voltage, the DC current is regulated by sensing the current across the sense resistor at the bottom on of the cell stack. When the charger is enabled, the initial current is set for either the Precharge or Constant Current/Constant Voltage (CC/CV) value, based on the minimum cell voltage. Once the charger enters CONSTANT CURRENT mode, the temperature and maximum cell voltage-adjusted-charging current is set, and the voltage output of the charger is automatically regulated to maintain the current across  $R_{CHG}$ . Once the temperature-adjusted voltage is reached by the charger output, the current starts to taper.

Throughout the charge cycle, the current available from the charger is limited by the *ChargingCurrent()* value. The system draws more current, however, with the battery supplementing the difference. Once battery charging is terminated, the charger is capable of supplying all of the current defined by the **Advanced Charge Algorithm: Maximum Current** Register value. Refer to the *bq40z60 Technical Reference Manual (SLUUA04)* for more information.

Figure 6 shows the system power path with the adaptor current and battery current overlaid. Further information is available in *Application and Implementation*.



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Figure 6. Power Path Overview

### 8.3.3.1 Precharge Modes

The charge controller is designed to allow for both internal precharge control and external precharge control. The device can operate in precharge with external FETs and a current limiting resistor. Refer to the *bq40z60 Technical Reference Manual (SLUUA04)* for more information.

### 8.3.3.2 Zero-Volt Charge Support

This mode of operation is similar to PRECHARGE mode switched charging, but with the charge FET operation in the saturation region. The NVDC out is connected to the CHG gate drive output internally to allow for precharge current from the charger through the CHG FET. This current is limited based on the value of the external  $R_{sense}$  (10-mΩ resistor the lowest precharge current = 200 mA). This will increase the power dissipation of the charge FET and will require thermal heat management and protection to ensure correct operation.

## Feature Description (continued)

### 8.3.3.3 Charge Termination

Once the highest cell voltage reaches the value specified in the data flash, the charger output voltage will no longer increase and the current will start to taper. Once the highest cell voltage is within the **Charge Term Voltage** window and the measured current is below **Charge Term Taper Current** for 40 s or more, the charger will terminate by disabling the CHG FET and setting the appropriate flags. Refer to the *bq40z60 Technical Reference Manual (SLUUA04)* for more information.

The system can still provide load current from the battery pack if the adaptor current cannot support the system load. The diode of the CHG FET starts to conduct as the system voltage decreases to a point where the pack voltage is greater than the system regulation voltage –  $V_{\text{diode}}$ . If the average discharge current is high, the system can turn ON the CHG FET for improved efficiency and minimized line losses during the discharge phase.

### 8.3.4 Fuel Gauge and Control Details

The bq40z60 uses the Impedance Track™ algorithm to measure and calculate the available capacity in battery cells. The bq40z60 accumulates a measure of charge and discharge currents and compensates the charge current measurement for the temperature and state-of-charge of the battery. The bq40z60 estimates self-discharge of the battery and also adjusts the self-discharge estimation based on temperature. The device also has TURBO BOOST mode support, which enables the bq40z60 to provide the necessary data for the MCU to determine what level of peak power consumption can be applied without causing a system reset or a transient battery voltage level spike to trigger termination flags. See the *bq40z60 Technical Reference Manual (SLUUA04)* for further details.

#### 8.3.4.1 Battery Trip Point (BTP)

Required for WIN8 OS, the Battery Trip Point (BTP) feature indicates when the RSOC of a battery pack has depleted to a certain value set in a DF register. This feature allows a host to program two capacity-based thresholds that govern triggering a BTP interrupt on the BTP\_INT pin, and setting or clearing the *OperationStatus[BTP\_INT]* on the basis of *RemainingCapacity()*.

An internal weak pullup is applied when the BTP feature is active. Depending on the system design, an external pullup may be required to put on the BTP\_INT pin. See [High-Voltage General Purpose I/O \(GPIO0, GPIO1\)](#) for details.

#### 8.3.4.2 Lifetime Data Logging Features

The bq40z60 offers lifetime data logging for several critical battery parameters. The following parameters are updated every 10 hours if a difference is detected between values in RAM and data flash:

- Maximum and Minimum Cell Voltages
- Maximum Delta Cell Voltage
- Maximum Charge Current
- Maximum Discharge Current
- Maximum Average Discharge Current
- Maximum Average Discharge Power
- Maximum and Minimum Cell Temperature
- Maximum Delta Cell Temperature
- Maximum and Minimum Internal Sensor Temperature
- Maximum FET Temperature
- Number of Safety Events Occurrences and the Last Cycle of the Occurrence
- Number of Valid Charge Termination and the Last Cycle of the Valid Charge Termination
- Number of Qmax and Ra Updates and the Last Cycle of the Qmax and Ra Updates
- Number of Shutdown Events
- Cell Balancing Time for Each Cell  
(This data is updated every 2 hours if a difference is detected.)
- Total FW Runtime and Time Spent in Each Temperature Range  
(This data is updated every 2 hours if a difference is detected.)

## Feature Description (continued)

### 8.3.5 Authentication

The bq40z60 supports authentication by the host using SHA-1. More information about the algorithm can be found in the *bq40z60 Technical Reference Manual* (SLUUA04).

### 8.3.6 LED Display

The bq40z60 can drive a 4-segment LED display for remaining capacity indication and/or a permanent fail (PF) error code indication.

### 8.3.7 Internal Temperature Sensor

An internal temperature sensor is available on the bq40z60 to reduce the cost, power, and size of the external components necessary to measure temperature. It is available for connection to the ADC using the multiplexer, and is ideal for determining pack temperature during storage and IC temperature during normal operation.

### 8.3.8 External Temperature Sensor Support

Each of the TSx input pins can be enabled with an 18-k $\Omega$  (Typ.) linearization pullup resistor to support using a 10 k $\Omega$  (25°C) NTC external thermistor, such as the Semitec 103AT–2. One or more thermistors can be connected between VSS and the individual RCx pin. The analog measurement is then taken via the ADC through its input multiplexer. If a different thermistor type is required, then changes to the external support components may be required.

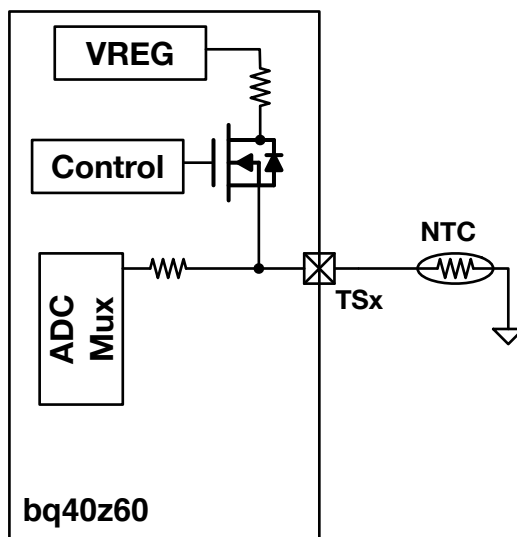


Figure 7. Thermistor Pin Configuration

### 8.3.9 High Frequency Oscillator

The bq40z60 includes a high frequency oscillator (HFO) running at 16.78 MHz. It is synthesized from the LFO output and scaled down to 8.388 MHz with 50% duty cycle. There is no need for external oscillator components.

### 8.3.10 Communications

The bq40z60 uses SMBus v1.1 with MASTER mode and packet error checking (PEC) options per the SBS specification.

## Feature Description (continued)

### 8.3.10.1 SMBus On and Off State

The bq40z60 detects an SMBus off state when SMBC and SMBD are low for two or more seconds. Clearing this state requires that either SMBC or SMBD transition high. The communication bus will resume activity within 1 ms.

### 8.3.10.2 SBS Commands

The *ManufacturerAccess()* Command List shows the supported Manufacturer Access and SBS commands. See the *bq40z60 Technical Reference Manual* ([SLUUA04](#)) for further details.

**Table 1. ManufacturerAccess() Command List**

FUNCTION	MANUFACTURER ACCESS COMMAND	SBS COMMAND	ACCESS	FORMAT	DATA READ ON 0x44 OR 0x23	AVAILABLE IN SEALED MODE
DeviceType	0x0001		R	Block	Yes	Yes
FirmwareVersion	0x0002		R	Block	Yes	Yes
HardwareVersion	0x0003		R	Block	Yes	Yes
IFChecksum	0x0004		R	Block	Yes	Yes
StaticDFSSignature	0x0005		R	Block	Yes	Yes
ChemID	0x0006		R	Block	Yes	Yes
StaticChemDFSSignature	0x0008		R	Block	Yes	Yes
AlIDFSSignature	0x0009		R	Block	Yes	Yes
ShutdownMode	0x0010		W	—	—	Yes
SleepMode	0x0011		W	—	—	—
AutoCCOfset	0x0013		W	—	—	—
FuseToggle	0x001D		W	—	—	—
PrechargeFET	0x001E		W	—	—	—
ChargeFET	0x001F		W	—	—	—
DischargeFET	0x0020		W	—	—	—
Gauging	0x0021		W	—	—	—
FETControl	0x0022		W	—	—	—
LifetimeDataCollection	0x0023		W	—	—	—
PermanentFailure	0x0024		W	—	—	—
BlackBoxRecorder	0x0025		W	—	—	—
Fuse	0x0026		W	—	—	—
LifetimeDataReset	0x0028		W	—	—	—
PermanentFailureData Reset	0x0029		W	—	—	—
LifetimeDataFlush	0x002E		W	—	—	—
LifetimeDataSpeedUp Mode	0x002F		W	—	—	—
BlackBoxRecorderReset	0x002A		W	—	—	—
CalibrationMode	0x002D		W	—	—	—
SealDevice	0x0030		W	—	—	—
SecurityKeys	0x0035		R/W	Block	Yes	—
AuthenticationKey	0x0037		R/W	Block	—	—
DeviceReset	0x0041		W	—	—	—
SafetyAlert	0x0050	0x50	R	Block	Yes	Yes
SafetyStatus	0x0051	0x51	R	Block	Yes	Yes
PFAAlert	0x0052	0x52	R	Block	Yes	Yes
PFStatus	0x0053	0x53	R	Block	Yes	Yes
OperationStatus	0x0054	0x54	R	Block	Yes	Yes
ChargingStatus	0x0055	0x55	R	Block	Yes	Yes
GaugingStatus	0x0056	0x56	R	Block	Yes	Yes

## Feature Description (continued)

**Table 1. ManufacturerAccess() Command List (continued)**

FUNCTION	MANUFACTURER ACCESS COMMAND	SBS COMMAND	ACCESS	FORMAT	DATA READ ON 0x44 OR 0x23	AVAILABLE IN SEALED MODE
ManufacturingStatus	0x0057	0x57	R	Block	Yes	Yes
AFERegister	0x0058	0x58	R	Block	Yes	Yes
LifetimeDataBlock1	0x0060	0x60	R	Block	Yes	Yes
LifetimeDataBlock2	0x0061	0x61	R	Block	Yes	Yes
LifetimeDataBlock3	0x0062	0x62	R	Block	Yes	Yes
ManufacturerInfo	0x0070	0x70	R	Block	Yes	Yes
DAStatus1	0x0071	0x71	R	Block	Yes	Yes
DAStatus2	0x0072	0x72	R	Block	Yes	Yes
GaugeStatus1	0x0073	0x73	R	Block	Yes	Yes
GaugeStatus2	0x0074	0x74	R	Block	Yes	Yes
GaugeStatus3	0x0075	0x75	R	Block	Yes	Yes
StateOfHealth	0x0077		R	Block	Yes	Yes
CHGR_EN	0x00C0		W	—	—	No
CVRD_ARM	0x00C1		W	—	—	Yes
ACFETEST	0x00C2		W	—	—	No
CHGONTEST	0x00C3		W	—	—	No
ROMMode	0x0F00		W	—	—	—
ExitCalibrationOutput	0xF080		R/W	Block	Yes	—
OutputCCandADCfor Calibration	0xF081		R/W	Block	Yes	—
OutputShortedCCand ADCforCalibration	0xF082		R/W	Block	Yes	—

## 9 Application and Implementation

### 注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The bq40z60 is a monolithic charger and gas gauge solution for multi-cell battery packs. By integrating these devices, software control can be handed off from the host microcontroller to the gas gauge controller, providing for potential energy savings that correlate to runtime.

## 9.2 Typical Applications

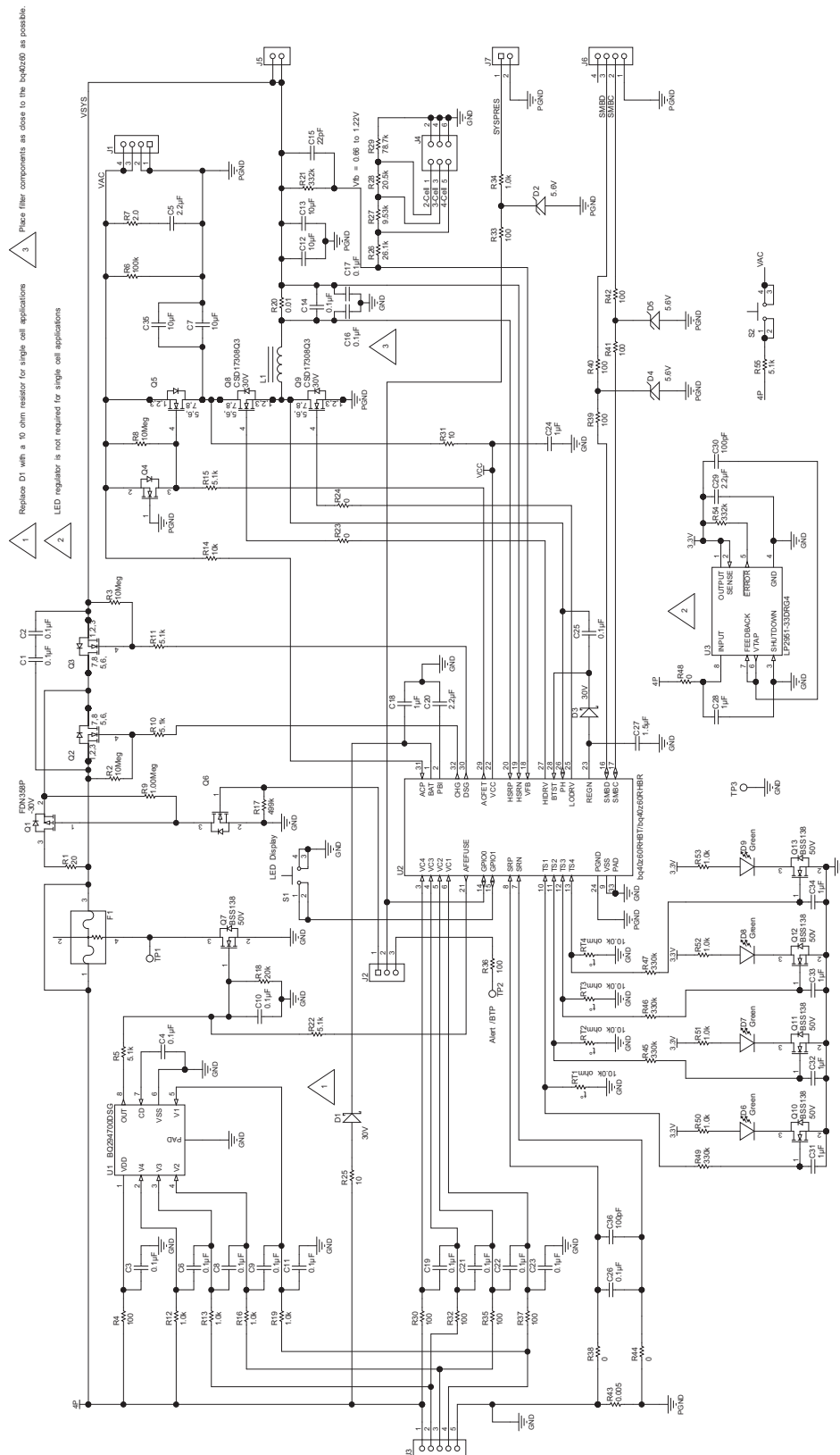


图 8. Typical Application Schematic

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## Typical Applications (接下页)

### 注

The feedback resistor to VFB from charging output will have different values based on the number of series cells configured for charging the pack.

### 9.2.1 Design Requirements

For this design example, use the parameters listed in 表 2 as the input parameters.

**表 2. Design Parameters**

Design Parameter	Example Value
Input Voltage Range	15–22 V
3-Cell Battery Voltage Range	9 V–12.6 V
4-Cell Battery Voltage Range	12 V–16.8 V
Operating Frequency	1000 kHz

### 9.2.2 Detailed Design Procedure

#### 9.2.2.1 Inductor Selection

The bq40z60 has a 1000-kHz switching frequency to allow the use of small inductor and capacitor values. Inductor saturation current should be higher than the charging current ( $I_{CHG}$ ) plus half the ripple current ( $I_{RIPPLE}$ ):

$$I_{SAT} \geq I_{CHG} + (1/2) I_{RIPPLE} \quad (1)$$

The inductor ripple current depends on input voltage ( $V_{IN}$ ), duty cycle ( $D = V_{OUT}/V_{IN}$ ), switching frequency ( $f_s$ ) and inductance ( $L$ ):

$$I_{RIPPLE} = \frac{V_{IN} \times D \times (1 - D)}{f_s \times L} \quad (2)$$

The maximum inductor ripple current happens with  $D = 0.5$  or close to 0.5. For example, the battery charging voltage range is from 9 V to 12.6 V for a 3-cell battery pack. For 20-V adaptor voltage, 10-V battery voltage gives the maximum inductor ripple current. Another example is a 4-cell battery: The battery voltage range is from 12 V to 16.8 V, and 12-V battery voltage gives the maximum inductor ripple current.

Usually inductor ripple is designed in the range of (20%–40%) maximum charging current as a trade-off between inductor size and efficiency for a practical design.

The bq40z60 has cycle-by-cycle charge undercurrent protection (UCP) by monitoring the charging-current sensing resistor to prevent negative inductor current. The typical UCP threshold is 5-mV falling edge corresponding to 0.5-A falling edge for a 10-mΩ charging-current sensing resistor.

#### 9.2.2.2 Input Capacitor

The input capacitor should have enough ripple-current rating to absorb input switching ripple current. The worst-case RMS ripple current is half of the charging current when the duty cycle is 0.5. If the converter does not operate at 50% duty cycle, then the worst-case capacitor RMS current  $I_{CIN}$  occurs where the duty cycle is closest to 50% and can be estimated using the following equation:

$$I_{CIN} = I_{CHG} \times \sqrt{D \times (1-D)} \quad (3)$$

A low-ESR ceramic capacitor such as X7R or X5R is preferred for the input-decoupling capacitor and should be placed to the drain of the high-side MOSFET and source of the low-side MOSFET as close as possible. The voltage rating of the capacitor must be higher than the normal input voltage level. A 25-V or higher-rating capacitor is preferred for 20-V input voltage. 10-μF to 20-μF capacitance is suggested for typical of 3-A to 4-A charging current.

### 9.2.2.3 Output Capacitor

Output capacitor also should have enough ripple-current rating to absorb the output switching ripple current. The output capacitor RMS current  $I_{\text{COUT}}$  is given:

$$I_{\text{COUT}} = \frac{I_{\text{RIPPLE}}}{2 \times \sqrt{3}} \approx 0.29 \times I_{\text{RIPPLE}} \quad (4)$$

The output capacitor voltage ripple can be calculated as follows:

$$\Delta V_o = \frac{1}{8LCf_s^2} \left( V_{\text{BAT}} - \frac{V_{\text{BAT}}^2}{V_{\text{IN}}} \right) \quad (5)$$

At a certain input/output voltage and switching frequency, the voltage ripple can be reduced by increasing the output filter LC. The bq40z60 has an internal loop compensator. To get good loop stability, the resonant frequency of the output inductor and output capacitor should be designed between 21 kHz and 27 kHz. The preferred ceramic capacitor has a 25-V or higher rating, X7R or X5R for a 4-cell application.

### 9.2.2.4 Power MOSFETs Selection

Two external N-CH MOSFETs are used for a synchronous switching battery charger. The gate drivers are internally integrated into the IC with 6 V of gate drive voltage. 30-V or higher voltage rating MOSFETs are preferred for 20-V input voltage, and 40 V or higher-rating MOSFETs are preferred for 20-V to 28-V input voltage.

Figure-of-merit (FOM) is usually used for selecting the proper MOSFET based on a tradeoff between the conduction loss and switching loss. For a top-side MOSFET, FOM is defined as the product of the MOSFET on-resistance,  $r_{\text{DS(on)}}$ , and the gate-to-drain charge,  $Q_{\text{GD}}$ . For a bottom-side MOSFET, FOM is defined as the product of the MOSFET on-resistance,  $r_{\text{DS(on)}}$ , and the total gate charge,  $Q_{\text{G}}$ .

$$\text{FOM}_{\text{top}} = R_{\text{DS(on)}} \times Q_{\text{GD}} \quad \text{FOM}_{\text{bottom}} = R_{\text{DS(on)}} \times Q_{\text{G}} \quad (6)$$

The lower the FOM value, the lower the total power loss. Usually a lower  $r_{\text{DS(on)}}$  has a higher cost with the same package size.

The top-side MOSFET loss includes conduction loss and switching loss. It is a function of duty cycle ( $D = V_{\text{OUT}}/V_{\text{IN}}$ ), charging current ( $I_{\text{CHG}}$ ), the MOSFET on-resistance ( $r_{\text{DS(on)}}$ ), input voltage ( $V_{\text{IN}}$ ), switching frequency ( $f_s$ ), turn-on time ( $t_{\text{on}}$ ), and turn-off time ( $t_{\text{off}}$ ):

$$P_{\text{top}} = D \times I_{\text{CHG}}^2 \times R_{\text{DS(on)}} + \frac{1}{2} \times V_{\text{IN}} \times I_{\text{CHG}} \times (t_{\text{on}} + t_{\text{off}}) \times f_s \quad (7)$$

The first item represents the conduction loss. Usually MOSFET  $r_{\text{DS(on)}}$  increases by 50% with 100°C junction temperature rise. The second term represents the switching loss. The MOSFET turn-on and turn-off times are given by:

$$t_{\text{on}} = \frac{Q_{\text{SW}}}{I_{\text{on}}}, \quad t_{\text{off}} = \frac{Q_{\text{SW}}}{I_{\text{off}}} \quad (8)$$

where  $Q_{\text{sw}}$  is the switching charge,  $I_{\text{on}}$  is the turn-on gate-driving current, and  $I_{\text{off}}$  is the turn-off gate driving current. If the switching charge is not given in the MOSFET data sheet, it can be estimated by gate-to-drain charge ( $Q_{\text{GD}}$ ) and gate-to-source charge ( $Q_{\text{GS}}$ ):

$$Q_{\text{SW}} = Q_{\text{GD}} + \frac{1}{2} \times Q_{\text{GS}} \quad (9)$$

Total gate-driving current can be estimated by the REGN voltage ( $V_{\text{REGN}}$ ), MOSFET plateau voltage ( $V_{\text{plt}}$ ), total turn-on gate resistance ( $R_{\text{on}}$ ), and turn-off gate resistance ( $R_{\text{off}}$ ) of the gate driver:

$$I_{\text{on}} = \frac{V_{\text{REGN}} - V_{\text{plt}}}{R_{\text{on}}}, \quad I_{\text{off}} = \frac{V_{\text{plt}}}{R_{\text{off}}} \quad (10)$$

The conduction loss of the bottom-side MOSFET is calculated with the following equation when it operates in synchronous continuous-conduction mode:

$$P_{\text{bottom}} = (1 - D) \times I_{\text{CHG}}^2 \times R_{\text{DS(on)}} \quad (11)$$



If the HSRP–HSRN voltage decreases below 5 mV (the charger is also forced into non-synchronous mode when the average HSRP–HSRN voltage is lower than 1.7 mV), the low-side FET is turned off for the remainder of the switching cycle to prevent negative inductor current. As a result, all the freewheeling current goes through the body diode of the bottom-side MOSFET. The maximum charging current in non-synchronous mode can be up to 1.6 A (0.5 A typ) for a 10-mΩ charging-current sensing resistor, considering IC tolerance. Choose the bottom-side MOSFET with either an internal Schottky or body diode capable of carrying the maximum non-synchronous mode charging current.

MOSFET gate-driver power loss contributes to the dominant losses on the controller IC when the buck converter is switching. The combined high side and low side MOSFET gate charge,  $Q_{g\_total}$ , is proportional to the power dissipation of the IC, as shown in 公式 12:

$$P_{CLoss\_driver} = V_{IN} \cdot Q_{g\_total} \cdot f_s \quad (12)$$

Choosing FETs with a lower  $Q_{g\_total}$  will reduce power loss.

### 9.2.2.5 Input Filter Design

During adaptor hot plug-in, the parasitic inductance and input capacitor from the adaptor cable form a second-order system. The voltage spike at the VCC pin may be beyond the IC maximum voltage rating and damage the IC. The input filter must be carefully designed and tested to prevent an overvoltage event on the VCC pin.

There are several methods for damping or limiting the overvoltage spike during adaptor hot plug-in. An electrolytic capacitor with high ESR as an input capacitor can damp the overvoltage spike well below the IC maximum pin voltage rating. A high-current-capability TVS Zener diode can also limit the overvoltage level to an IC safe level. However, these two solutions may not have low cost or small size.

图 9 shows a cost-effective and small size solution. The R1 and C1 are composed of a damping RC network to damp the hot plug-in oscillation. As a result, the overvoltage spike is limited to a safe level. D1 is used for reverse voltage protection for the VCC pin (it can be the body diode of input ACFET). C2 is a VCC pin-decoupling capacitor and it should be placed as close as possible to the VCC pin. R2 and C2 form a damping RC network to further protect the IC from high dv/dt and high-voltage spike. The C2 value should be less than the C1 value so R1 can be dominant over the ESR of C1 to get enough of a damping effect for hot plug-in. The R1 and R2 packages must be sized to handle inrush-current power loss according to the resistor manufacturer's datasheet. The filter component values always must be verified with the real application, and minor adjustments may be needed to fit in the real application circuit.

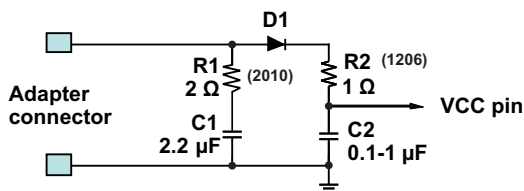
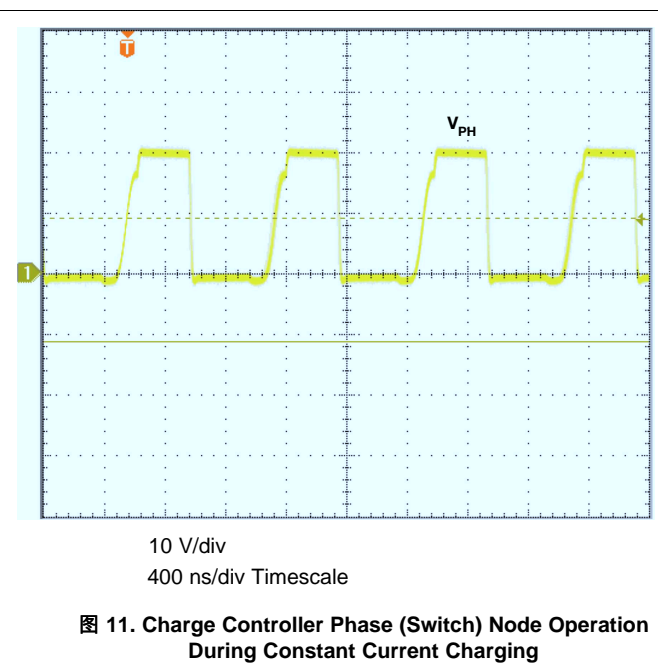
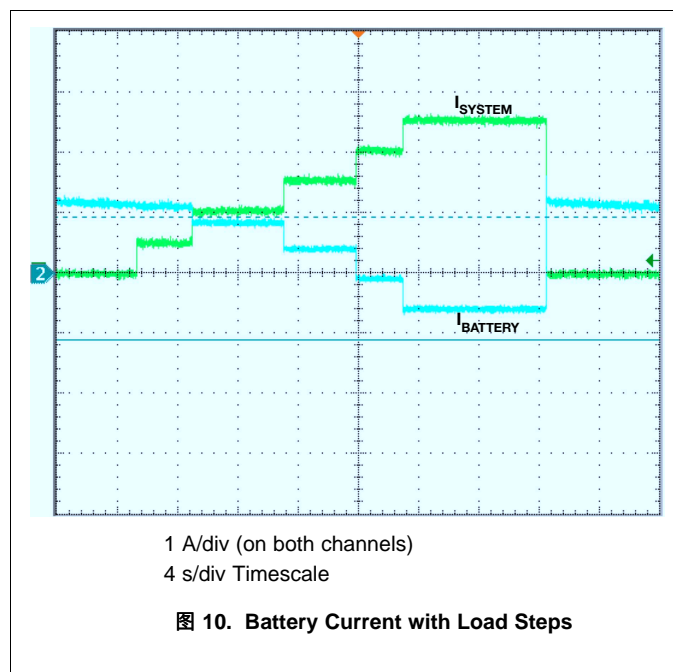


图 9. Input Filter

## 9.2.3 Application Curves



## 10 Power Supply Recommendations

The bq40z60 is designed to operate from a well-regulated input voltage supply range between 4.0 V and 25 V; however, with a multi-cell pack, the input voltage should be a minimum of 1 V above the maximum stack voltage. If the input supply is more than a few inches from the bq40z60, additional bulk capacitance in the form of a 47- $\mu$ F electrolytic capacitor should be used.

## 11 Layout

### 11.1 Layout Guidelines

The following information is related to external component selection and guidelines for PCB layout.

#### 11.1.1 PCB Layout

The switching node rise and fall times should be minimized for minimum switching loss. Proper layout of the components to minimize high-frequency current-path loop (see 图 12) is important to prevent electrical and magnetic field radiation and high-frequency resonant problems. The following is a PCB layout priority list for proper layout. Layout of the PCB according to this specific order is essential.

1. Place the input capacitor as close as possible to the switching MOSFET supply and ground connections and use the shortest possible copper trace connection. The capacitors should be placed on the same layer as the FETs instead of using vias to connect the capacitor and the FETs. Additionally, any vias connecting the input capacitor to the adaptor node should not be placed between the capacitor and the FETs; the capacitor should have a solid copper path to the FET.
2. The IC should be placed close to the switching MOSFET gate pins to keep the gate-drive signal traces short for a clean MOSFET drive. The IC can be placed on the other side of the PCB from the switching MOSFETs.
3. Place the inductor input pin as close as possible to the switching MOSFET output pin. Minimize the copper area of this trace to lower electrical and magnetic field radiation, but make the trace wide enough to carry the charging current. Do not use multiple layers in parallel for this connection. Minimize parasitic capacitance from this area to any other trace or plane.
4. The charging-current sensing resistor should be placed right next to the inductor output. Route the sense leads connected across the sensing resistor back to the IC in same layer, close to each other (minimize loop).

## Layout Guidelines (接下页)

- area) and do not route the sense leads through a high-current path (see 图 13 for Kelvin connection for best current accuracy). Place the decoupling capacitor on these traces next to the IC.
- Place the output capacitor next to the sensing resistor output and ground.
  - Output capacitor ground connections must be tied to the same copper that connects to the input capacitor ground before connecting to system ground.
  - Place the sense resistor and filter components, R1, C2, and C3, as close as possible to the IC and directly adjacent to the decoupling capacitor between HSRN and HSRP.
  - Route the analog ground separately from the power ground and use a single ground connection to tie the charger power ground to the charger analog ground. Just beneath the IC, use the copper-pour for analog ground, but avoid power pins to reduce inductive and capacitive noise coupling. Connect analog ground to GND. Connect analog ground and power ground together using the thermal pad as the single ground connection point. Or use a 0-Ω resistor to tie analog ground to power ground (thermal pad should tie to analog ground in this case). A star connection under the thermal pad is highly recommended.
  - It is critical that the exposed thermal pad on the back side of the IC package be soldered to the PCB ground. Ensure that there are sufficient thermal vias directly under the IC connecting to the ground plane on the other layers.
  - Place decoupling capacitors next to the IC pins and make the trace connection as short as possible.
  - Size and number of all vias should be enough for a given current path.

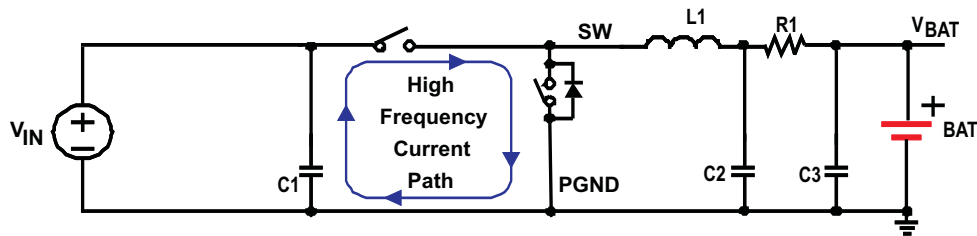


图 12. High-Frequency Current Path

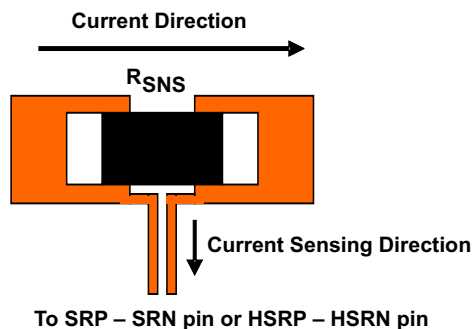


图 13. Sensing Resistor PCB Layout

For the recommended component placement with trace and via locations, see the *bq40z60EVM SBS 1.1 Impedance Track™ Technology Enabled Battery Management Solution Evaluation Module User's Guide (SLUUB71)*.

For the QFN information, see the *Quad Flatpack No-Lead Logic Packages Application Note (SCBA017)* and the *QFN/SON PCB Attachment Application Note (SLUA271)*.

## 11.2 Layout Example

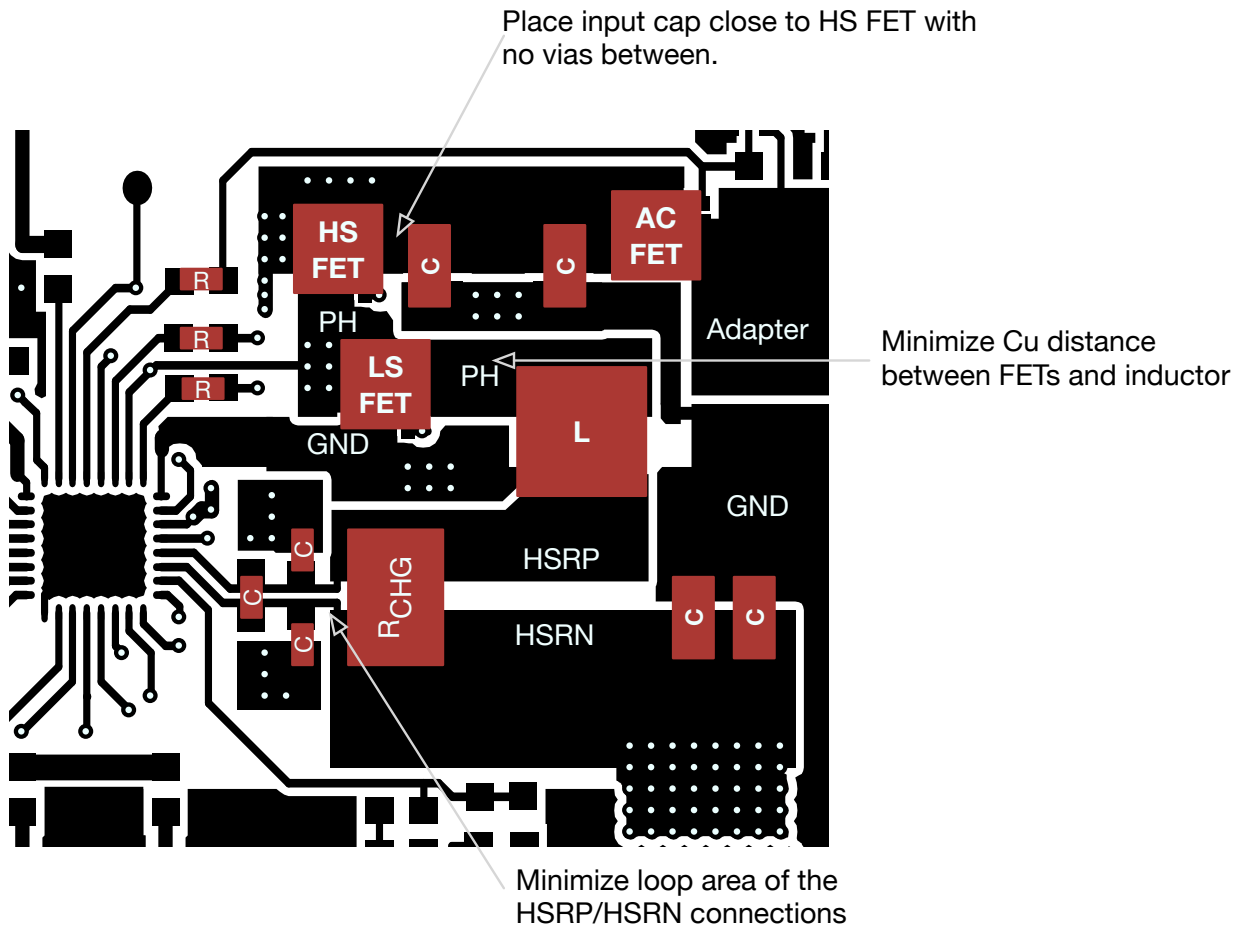


图 14. Board Layout Example

## 12 器件和文档支持

### 12.1 相关文档

如需相关文档，请参阅《bq40z60 技术参考手册》（文献编号：SLUUA04）。

### 12.2 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At [e2e.ti.com](#), you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 12.3 商标

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### 12.4 静电放电警告



ESD 可能会损坏该集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理措施和安装程序，可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

### 12.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 13 机械、封装和可订购信息

以下页面包括机械、封装和可订购信息。这些信息是指定器件的最新可用数据。这些数据发生变化时，我们可能不会另行通知或修订此文档。如欲获取此产品说明书的浏览器版本，请参见左侧的导航栏。

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">BQ40Z60RHBR</a>	Active	Production	VQFN (RHB)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	BQ40Z60
BQ40Z60RHBR.A	Active	Production	VQFN (RHB)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	BQ40Z60
BQ40Z60RHBRG4	Active	Production	VQFN (RHB)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	BQ40Z60
BQ40Z60RHBRG4.A	Active	Production	VQFN (RHB)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	BQ40Z60
<a href="#">BQ40Z60RHBT</a>	Active	Production	VQFN (RHB)   32	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	BQ40Z60
BQ40Z60RHBT.A	Active	Production	VQFN (RHB)   32	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	BQ40Z60

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ40Z60RHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
BQ40Z60RHBRG4	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
BQ40Z60RHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2



## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ40Z60RHBR	VQFN	RHB	32	3000	346.0	346.0	33.0
BQ40Z60RHBRG4	VQFN	RHB	32	3000	346.0	346.0	33.0
BQ40Z60RHBT	VQFN	RHB	32	250	182.0	182.0	20.0

## GENERIC PACKAGE VIEW

**RHB 32**

**VQFN - 1 mm max height**

5 x 5, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4224745/A

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

**RHB0032E**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE  
SCALE:18X



## SOLDER MASK DETAILS

4223442/B 08/2019

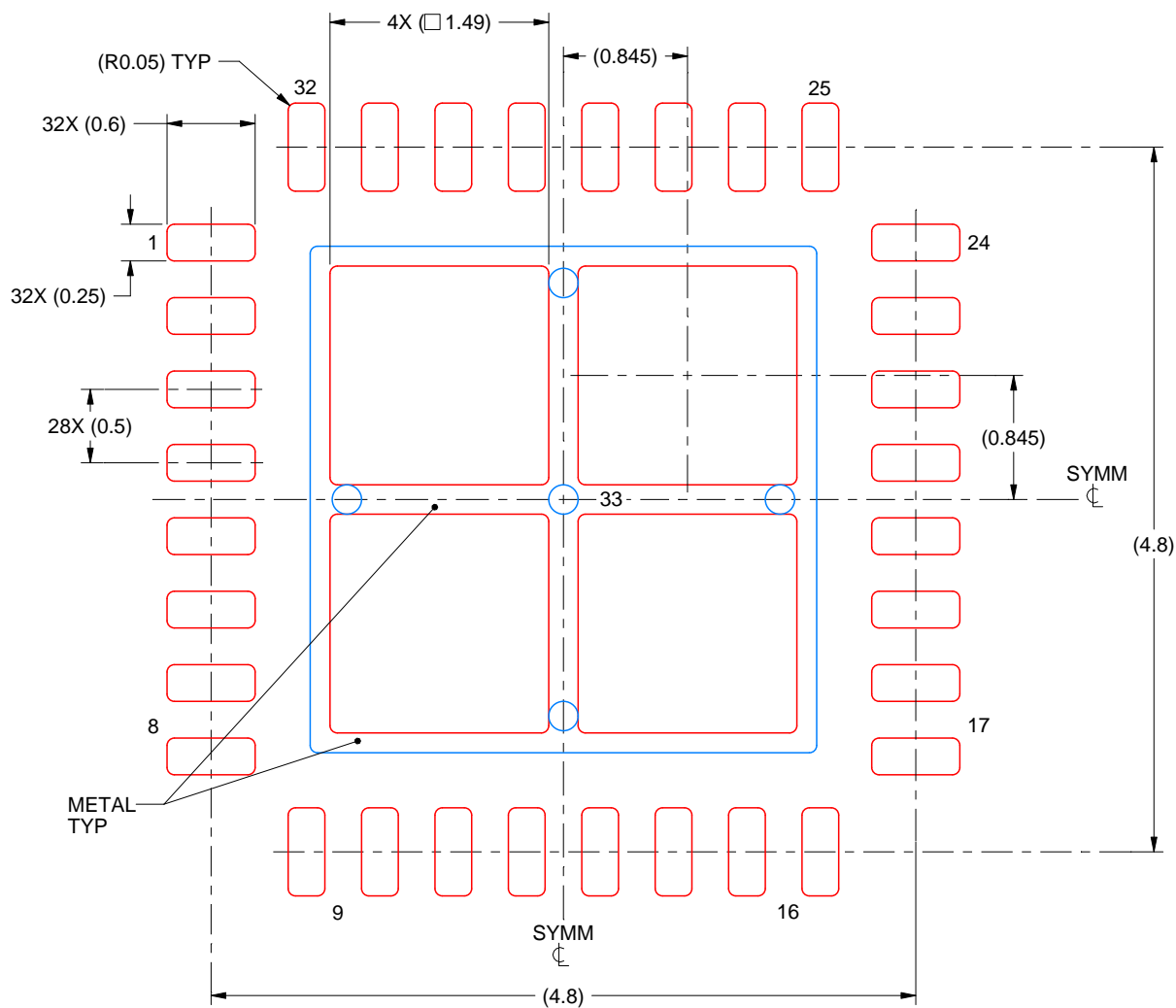
NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slua271](http://www.ti.com/lit/slua271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

**RHB0032E**

### VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



## SOLDER PASTE EXAMPLE BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 33:  
75% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE  
SCALE:20X

4223442/B 08/2019

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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最后更新日期：2025 年 10 月