具有 42V 最大输入电压、针对军事和坚固耐用应用的 LMZ14201EXT 1A SIMPLE SWITCHER® 电源模块

查询样品: LMZ14201EXT

特性

- **-55°C** 至 **125°C** 的结温范围
- 集成屏蔽式电感器
- 简单印刷电路板 **(PCB)** 布局布线
- 使用外部软启动和精密使能的灵活启动排序
- 防止涌入电流和诸如输入欠压闭锁 **(UVLO)** 和输出短路等故障
- 用于简单装配和制造的单个外露垫和标准引脚分配
- 针对现场可编程门阵列 **(FPGA)** 和特定用途集成电路 **(ASIC)** 供电的快速瞬态响应
- 低输出电压纹波
- 引脚到引脚兼容系列
  - **LMZ14203EXT/2EXT/1EXT**（**42V** 最大值 **3A**，**2A**，**1A**）
  - **LMZ14203/2/1**（**42V** 最大值 **3A**，**2A**，**1A**）
  - **LMZ12003/2/1**（**20V** 最大值 **3A**，**2A**，**1A**）
- 针对 **Webench®** 电源设计工具完全启用

应用范围

- 从 **12V** 和 **24V** 输入电源轨的负载点转换
- 时间关键项目
- 空间受限**/**高热量要求应用
- 负输出电压应用（请见 **AN-2027**SNVA425）



图 **1.** 易于使用的 **7** 引脚封装
PFM 7 引脚封装
10.16 x 13.77 x 4.57mm（**0.4 x 0.542 x 0.18** 英寸）
θ_{JA}**= 20°C/W**，θ_{JC}**= 1.9°C/W**
与无铅 **(RoHS)** 认证标准兼容

说明

LMZ14201EXT SIMPLE SWITCHER 电源模块是一款易于使用的降压直流至直流 (DC-DC) 解决方案，此解决方案能够以出色的功率转换效率、线路和负载调节和输出精度驱动高达 1A 的负载。 LMZ14201EXT 采用创新型封装，此封装可提高热性能并可实现手工或机器焊接。

LMZ14201EXT 可接受 6V 到 42V 之间的输入电压轨，提供低至 0.8V 的可调且高精确度输出电压。 LMZ14201EXT 只需 3 个外部电阻器和 4 个外部电容器即可完成电源解决方案。 LMZ14201EXT 是一款具有以下保护特性的可靠且稳定耐用的设计：热关断、输入欠压闭锁、输出过压保护、短路保护、输出电流限制并允许启动至一个预偏置输出。 一个单个电阻器将开关频率调节至 1MHz。

电气规范

- **6W** 最大总输出功率
- 高达 **1A** 输出电流
- 输入电压范围 **6V** 至 **42V**
- 输出电压范围为 **0.8V** 至 **6V**
- 效率高达 **90%**

性能优势

- 低辐射**/**高辐射抗扰度
- 通过振动标准 **MIL-STD-883** 方法 **2007.2** 条件 **A** **JESD22–B103B** 条件 **1**
- 通过摔落标准 **MIL-STD-883** 方法 **2002.3** 条件 **B** **JESD22–B110** 条件 **B**

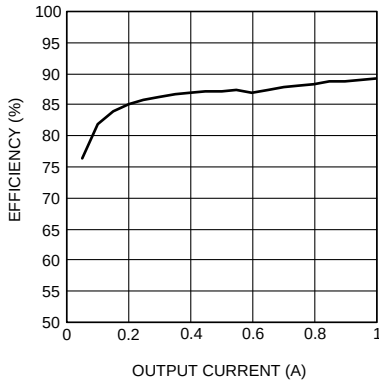
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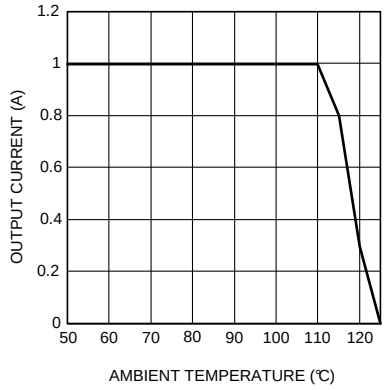
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System Performance

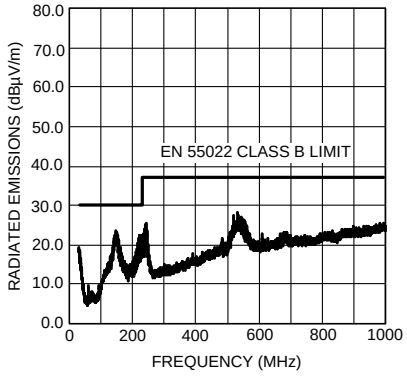
Efficiency V_{IN} = 24V V_{OUT} = 5.0V



Thermal Derating Curve
V_{IN} = 24V, V_{OUT} = 5.0V



Radiated Emissions (EN 55022 Class B)
from Evaluation Board



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Connection Diagram

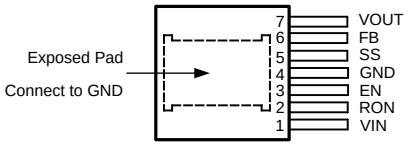
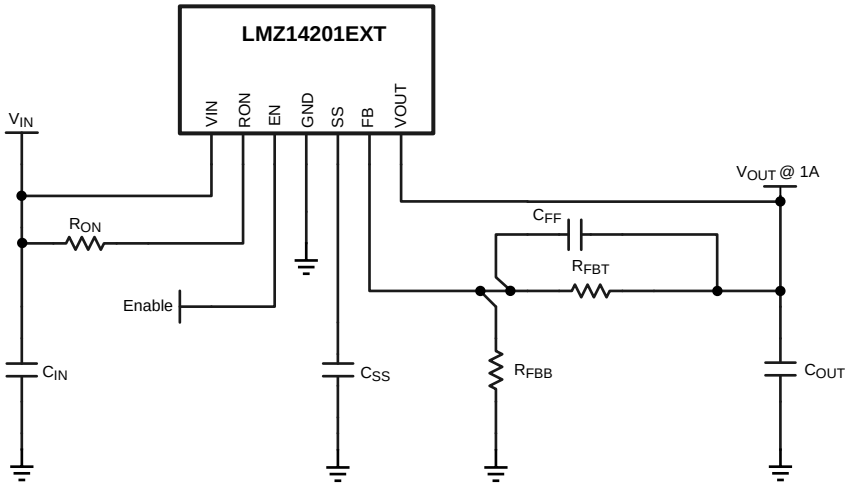


Figure 2. Top View
7-pin PFM

PIN DESCRIPTIONS

Pin	Name	Description
1	VIN	Supply input — Nominal operating range is 6V to 42V . A small amount of internal capacitance is contained within the package assembly. Additional external input capacitance is required between this pin and exposed pad.
2	RON	On Time Resistor — An external resistor from V_{IN} to this pin sets the on-time of the application. Typical values range from 25k to 124k ohms.
3	EN	Enable — Input to the precision enable comparator. Rising threshold is 1.18V nominal; 90 mV hysteresis nominal. Maximum recommended input level is 6.5V.
4	GND	Ground — Reference point for all stated voltages. Must be externally connected to EP.
5	SS	Soft-Start — An internal 8 µA current source charges an external capacitor to produce the soft-start function. This node is discharged at 200 µA during disable, over-current, thermal shutdown and internal UVLO conditions.
6	FB	Feedback — Internally connected to the regulation, over-voltage, and short-circuit comparators. The regulation reference point is 0.8V at this input pin. Connected the feedback resistor divider between the output and ground to set the output voltage.
7	VOUT	Output Voltage — Output from the internal inductor. Connect the output capacitor between this pin and exposed pad.
EP	EP	Exposed Pad — Internally connected to pin 4. Used to dissipate heat from the package during operation. Must be electrically connected to pin 4 external to the package.

Simplified Application Schematic



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

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Absolute Maximum Ratings(1)

VIN, RON to GND	-0.3V to 43.5V
EN, FB, SS to GND	-0.3V to 7V
Junction Temperature	150°C
Storage Temperature Range	-65°C to 150°C
ESD Susceptibility(2)	± 2 kV
Peak Reflow Case Temperature (30 sec)	245°C
For soldering specifications, refer to the following document: www.ti.com/lit/snoa549c	

(1) Absolute Maximum Ratings are limits beyond which damage to the device may occur. Operating Ratings are conditions under which operation of the device is intended to be functional. For ensured specifications and test conditions, see the Electrical Characteristics.
(2) The human body model is a 100pF capacitor discharged through a 1.5 kΩ resistor into each pin. Test method is per JESD-22-114.

Operating Ratings(1)

V_{IN}	6V to 42V
EN	0V to 6.5V
Operation Junction Temperature	−55°C to 125°C

(1) Absolute Maximum Ratings are limits beyond which damage to the device may occur. Operating Ratings are conditions under which operation of the device is intended to be functional. For ensured specifications and test conditions, see the Electrical Characteristics.

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Electrical Characteristics

Limits in standard type are for T_J = 25°C only; limits in boldface type apply over the junction temperature (T_J) range of -55°C to +125°C. Minimum and Maximum limits are ensured through test, design or statistical correlation. Typical values represent the most likely parametric norm at T_J = 25°C, and are provided for reference purposes only. Unless otherwise stated the following conditions apply: V_{IN} = 24V, Vout = 3.3V

Symbol	Parameter	Conditions	Min (1)	Typ (2)	Max (1)	Units
SYSTEM PARAMETERS						
Enable Control (3)						
V_{EN}	EN threshold trip point	V_{EN} rising	**1.10**	1.18	**1.26**	V
V_{EN-HYS}	EN threshold hysteresis	V_{EN} falling		90		mV
Soft-Start						
I_{SS}	SS source current	V_{SS} = 0V	**4.9**	8	**11**	µA
I_{SS-DIS}	SS discharge current			-200		µA
Current Limit						
I_{CL}	Current limit threshold	d.c. average	**1.4**	1.95	**3.0**	A
ON/OFF Timer						
t_{ON-MIN}	ON timer minimum pulse width			150		ns
t_{OFF}	OFF timer pulse width			260		ns
Regulation and Over-Voltage Comparator						
V_{FB}	In-regulation feedback voltage	V_{SS} >+ 0.8V T_J = -55°C to 125°C I_O = 1A	**.777**	0.798	**0.818**	V
		V_{SS} >+ 0.8V T_J = 25°C I_O = 10 mA	0.786	0.802	0.818	V
V_{FB-OV}	Feedback over-voltage protection threshold			0.92		V
I_{FB}	Feedback input bias current			5		nA
I_Q	Non Switching Input Current	V_{FB}= 0.86V		1		mA
I_{SD}	Shut Down Quiescent Current	V_{EN}= 0V		25		µA
Thermal Characteristics						
T_{SD}	Thermal Shutdown	Rising		165		°C
$T_{SD-HYST}$	Thermal shutdown hysteresis	Falling		15		°C
θ_{JA}	Junction to Ambient (4)	4 layer JEDEC Printed Circuit Board, 100 vias, No air flow		19.3		°C/W
		2 layer JEDEC Printed Circuit Board, No air flow		21.5		°C/W
θ_{JC}	Junction to Case	No air flow		1.9		°C/W
PERFORMANCE PARAMETERS (3)						
ΔV_O	Output Voltage Ripple			8		mV_{PP}
$\Delta V_O/\Delta V_{IN}$	Line Regulation	V_{IN} = 12V to 42V, I_O= 1A		.01		%
$\Delta V_O/I_{OUT}$	Load Regulation	V_{IN} = 24V		1.5		mV/A
η	Efficiency	V_{IN} = 24V V_O = 3.3V I_O = 1A		92		%

(1) Min and Max limits are 100% production tested at 25°C. Limits over the operating temperature range are ensured through correlation using Statistical Quality Control (SQC) methods. Limits are used to calculate Average Outgoing Quality Level (AOQL).
(2) Typical numbers are at 25°C and represent the most likely parametric norm.
(3) EN 55022:2006, +A1:2007, FCC Part 15 Subpart B: 2007. See AN-2024 and layout for information on device under test.
(4) θ_{JA} measured on a 1.705" x 3.0" four layer board, with one ounce copper, thirty five 12 mil thermal vias, no air flow, and 1W power dissipation. Refer to PCB layout diagrams

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Typical Performance Characteristics

Unless otherwise specified, the following conditions apply: V_{IN} = 24V; Cin = 10uF X7R Ceramic; C_O = 100uF X7R Ceramic; Tambient = 25 C for efficiency curves and waveforms.

Efficiency 6V Input @ 25°C

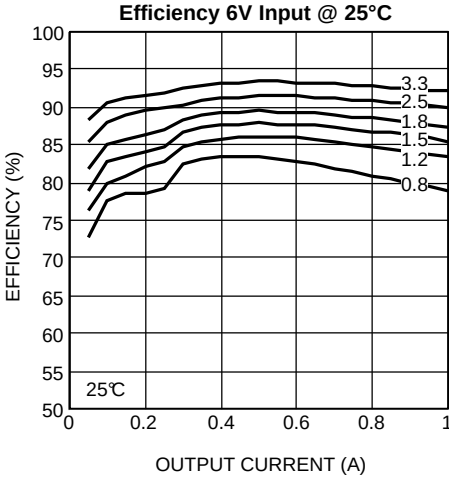


Figure 3.

Dissipation 6V Input @ 25°C

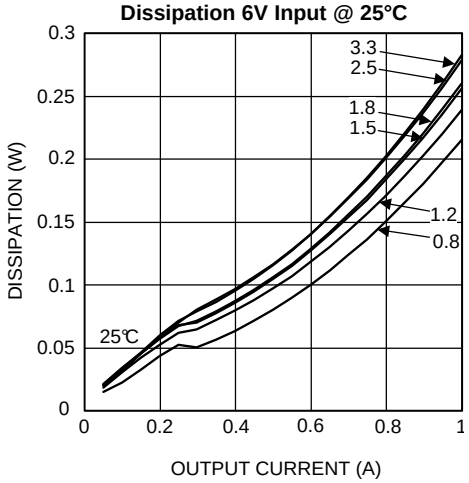


Figure 4.

Efficiency 12V Input @ 25°C

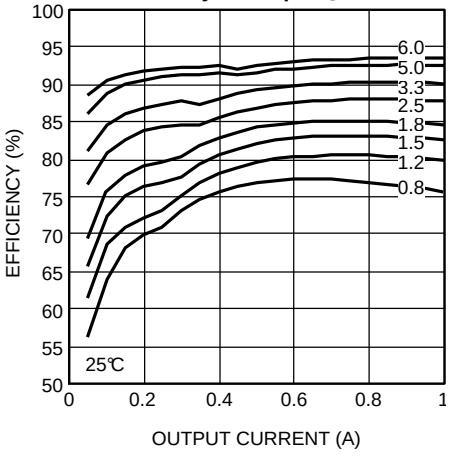


Figure 5.

Dissipation 12V Input @ 25°C

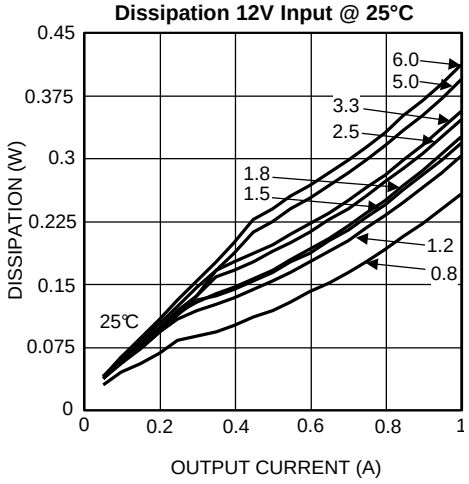


Figure 6.

Efficiency 24V Input @ 25°C

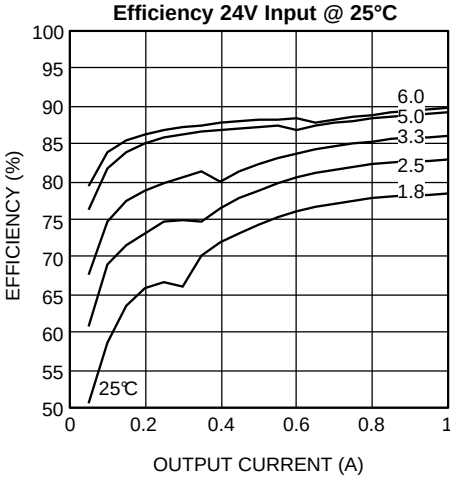


Figure 7.

Dissipation 24V Input @ 25°C

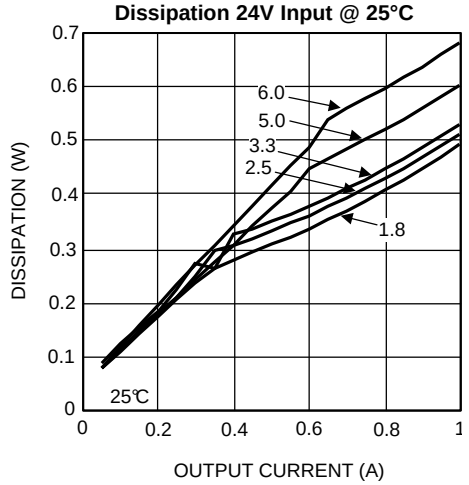


Figure 8.

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Typical Performance Characteristics (continued)

Unless otherwise specified, the following conditions apply: V_{IN} = 24V; Cin = 10uF X7R Ceramic; C_O = 100uF X7R Ceramic; Tambient = 25 C for efficiency curves and waveforms.

Efficiency 36V Input @ 25°C

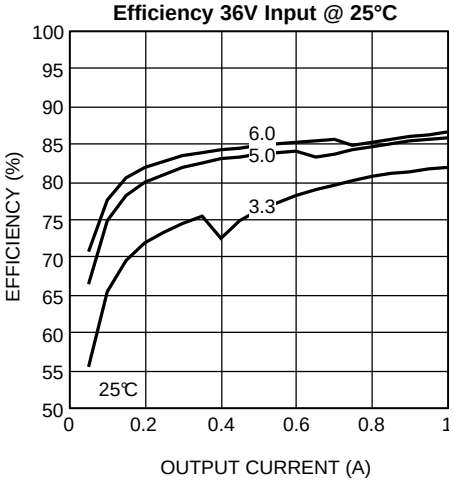


Figure 9.

Dissipation 36V Input @ 25°C

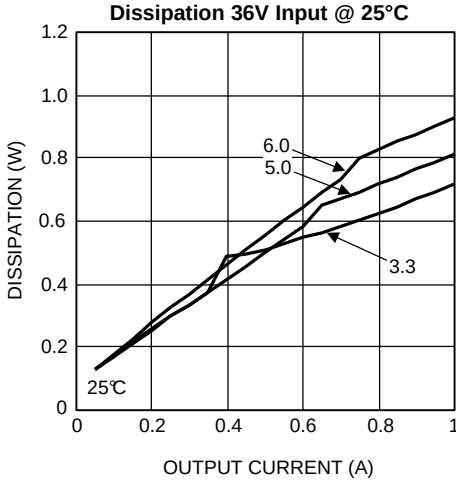


Figure 10.

Efficiency 42V Input @ 25°C

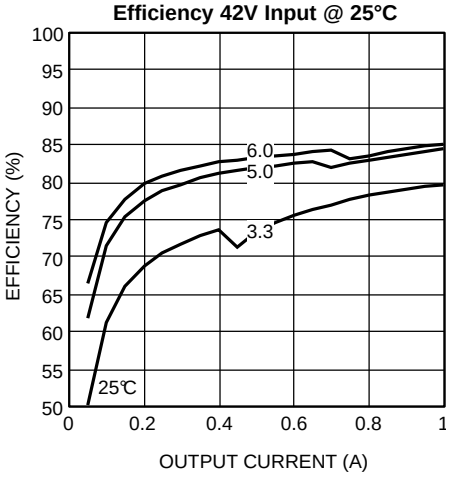


Figure 11.

Dissipation 42V Input @ 25°C

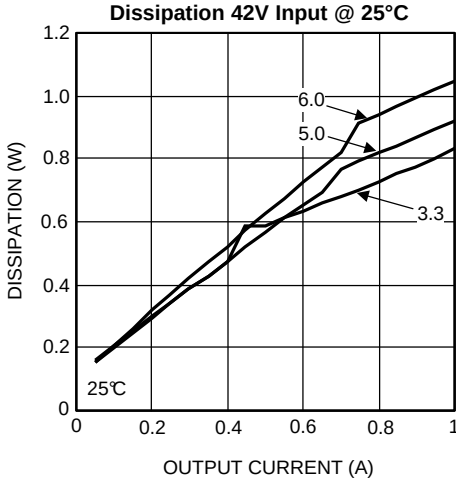


Figure 12.

Efficiency 6V Input @ 85°C

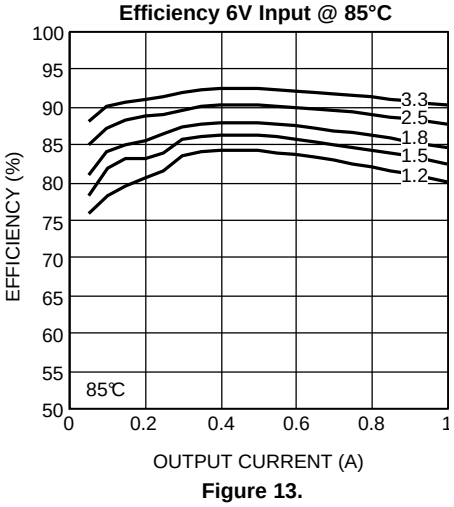


Figure 13.

Dissipation 6V input @ 85°C

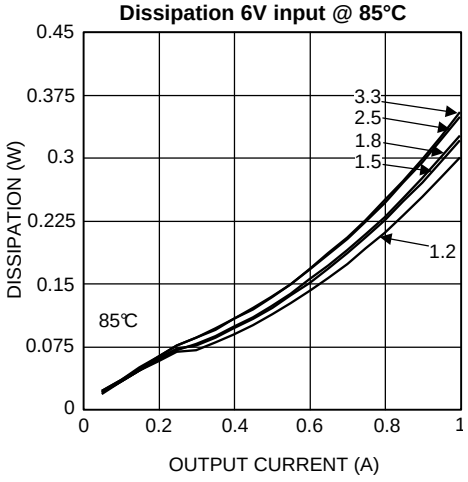


Figure 14.

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Typical Performance Characteristics (continued)

Unless otherwise specified, the following conditions apply: V_{IN} = 24V; Cin = 10uF X7R Ceramic; C_O = 100uF X7R Ceramic; Tambient = 25 C for efficiency curves and waveforms.

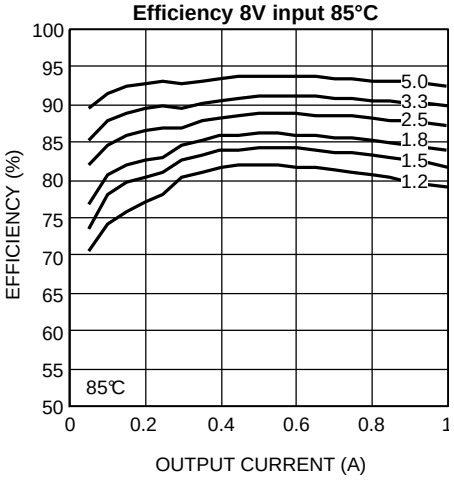


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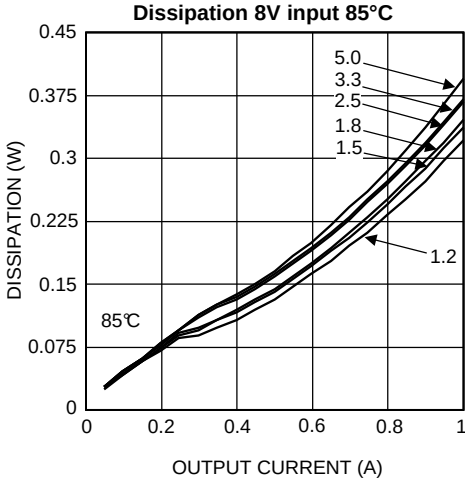


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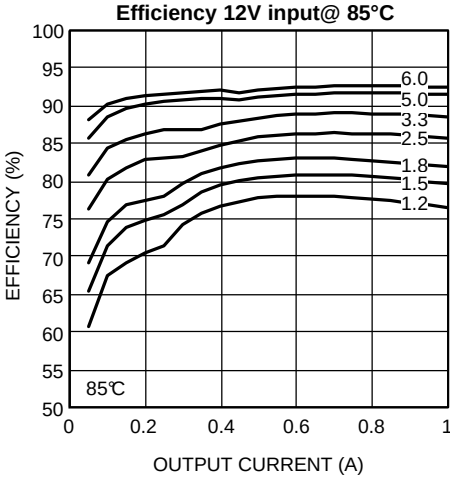


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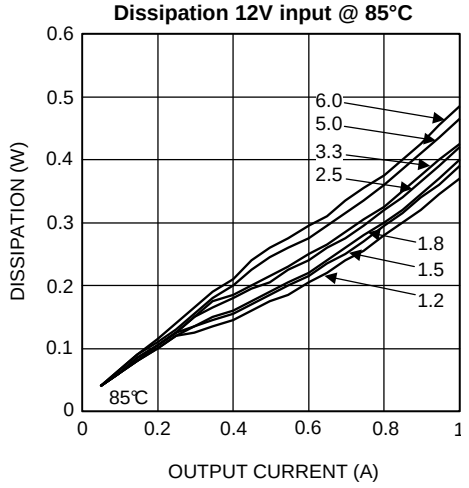


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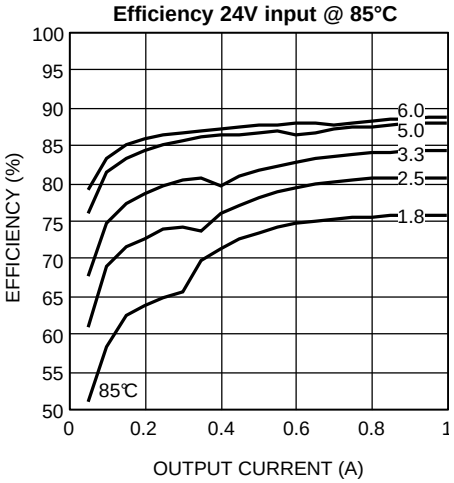


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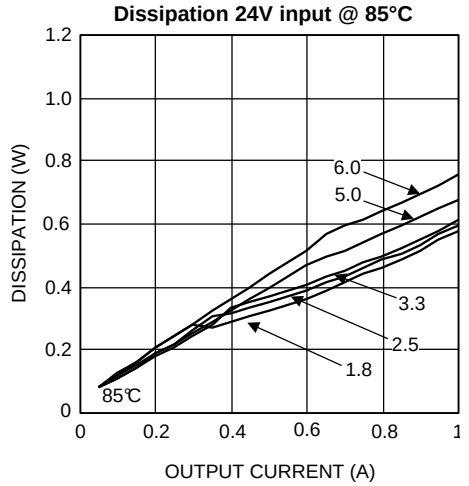


Figure 20.

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Typical Performance Characteristics (continued)

Unless otherwise specified, the following conditions apply: V_{IN} = 24V; Cin = 10uF X7R Ceramic; C_O = 100uF X7R Ceramic; Tambient = 25 C for efficiency curves and waveforms.

Efficiency 36V input @ 85°C

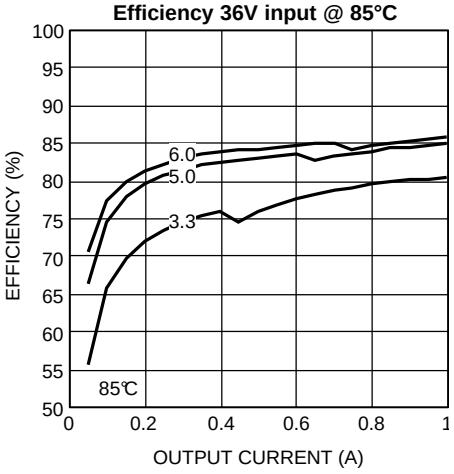


Figure 21.

Dissipation 36V input @ 85°C

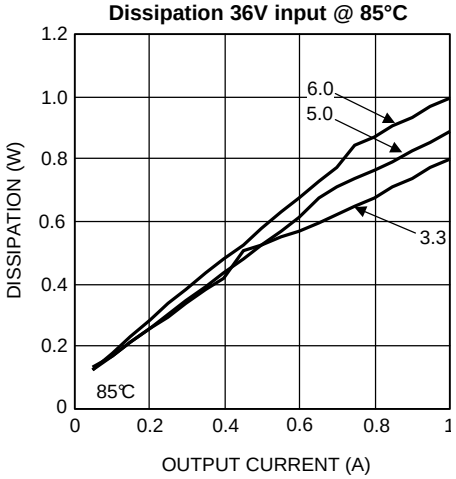


Figure 22.

Efficiency 42V Input @ 85°C

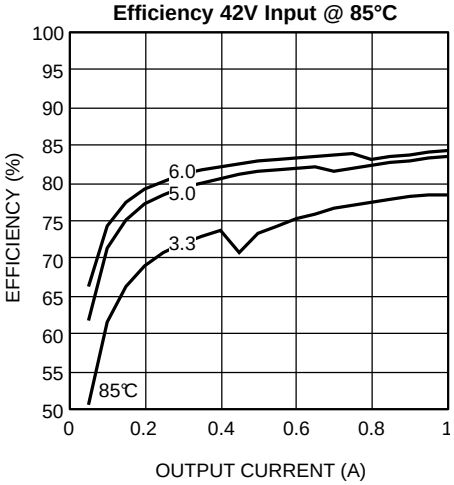


Figure 23.

Dissipation 42V Input @ 85°C

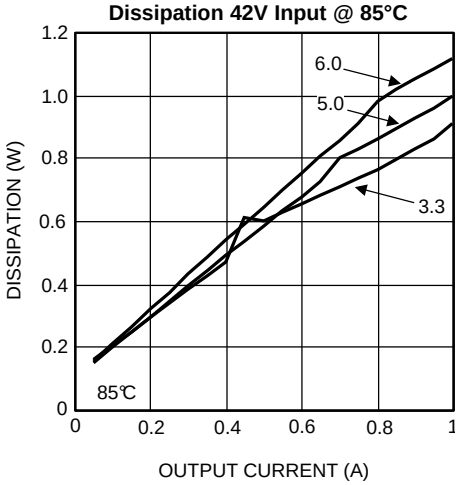


Figure 24.

Line and Load Regulation @ 25°C

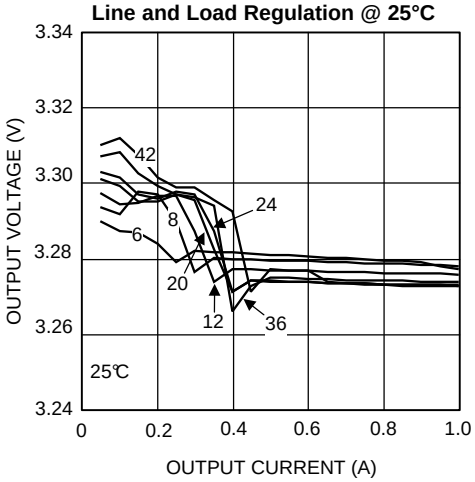


Figure 25.

Line and Load Regulation @ 85°C

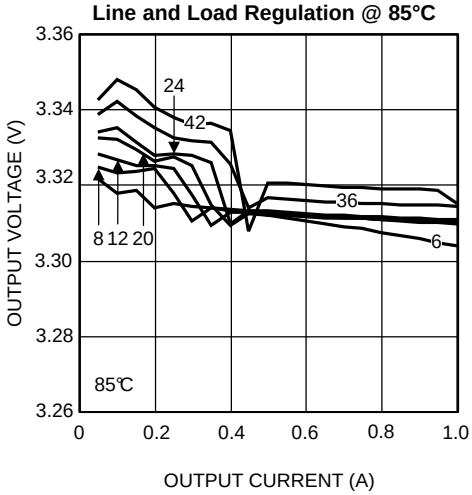


Figure 26.

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Typical Performance Characteristics (continued)

Unless otherwise specified, the following conditions apply: V_{IN} = 24V; Cin = 10uF X7R Ceramic; C_O = 100uF X7R Ceramic; Tambient = 25 C for efficiency curves and waveforms.

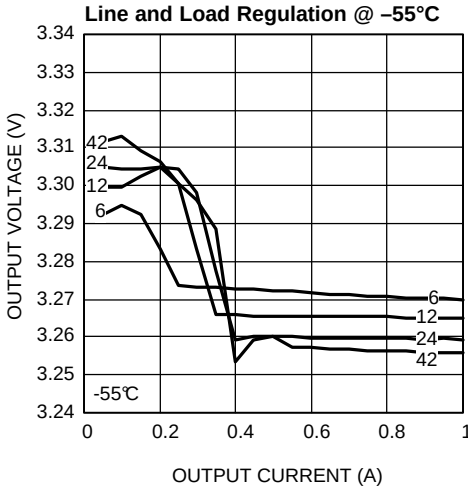


Figure 27.

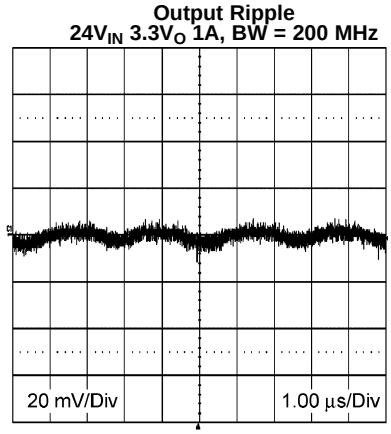


Figure 28.

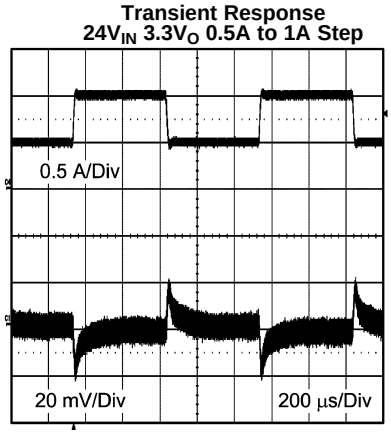


Figure 29.

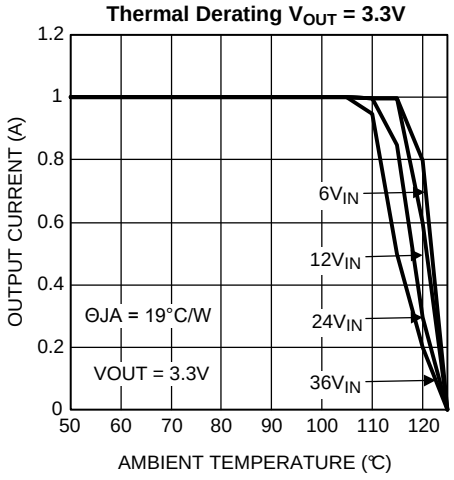


Figure 30.

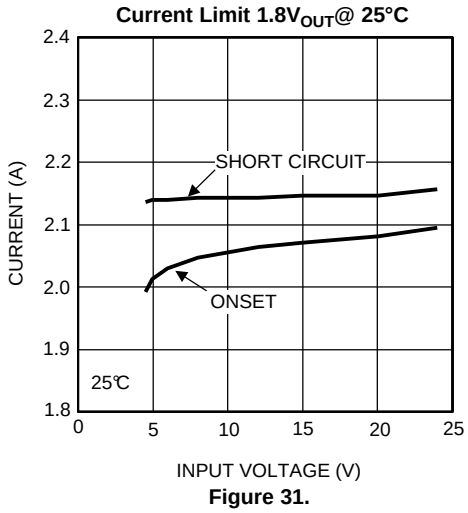


Figure 31.

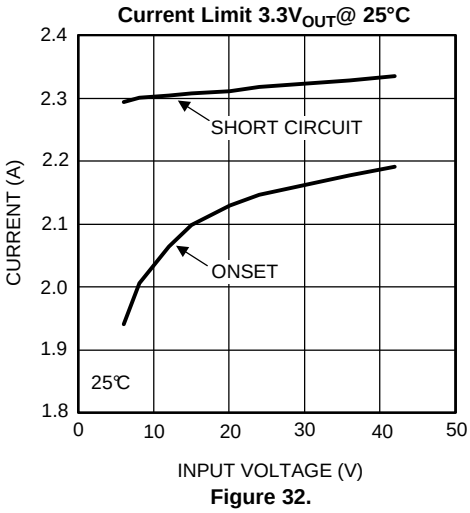


Figure 32.

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Typical Performance Characteristics (continued)

Unless otherwise specified, the following conditions apply: V_{IN} = 24V; Cin = 10uF X7R Ceramic; C_O = 100uF X7R Ceramic; Tambient = 25 C for efficiency curves and waveforms.

Current Limit 3.3V_{OUT}@ 85°C

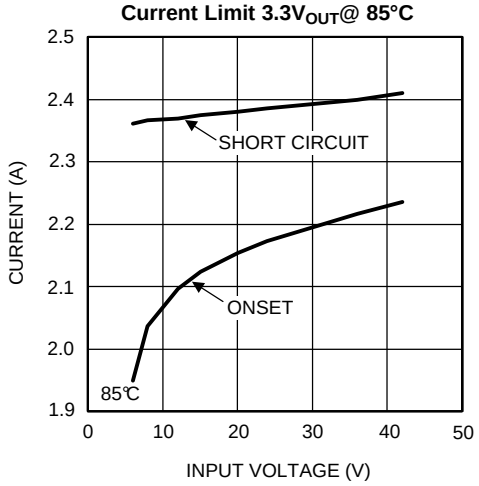


Figure 33.

Current Limit 3.3V_{OUT}@ –55°C

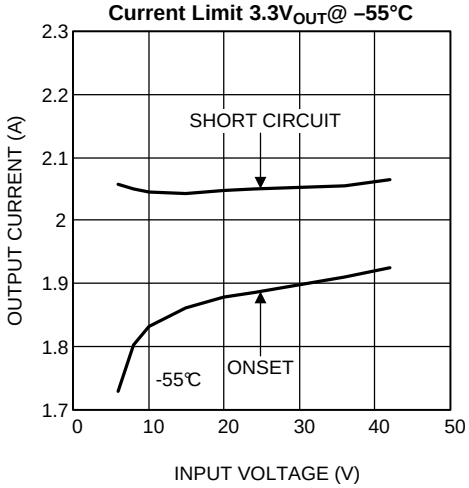
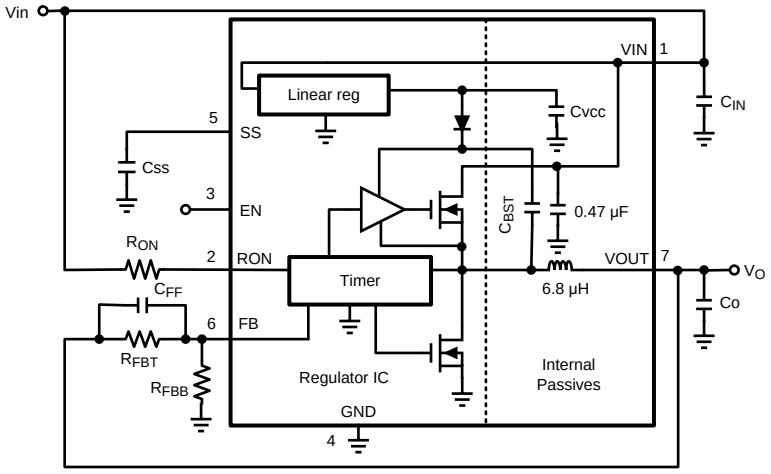


Figure 34.

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APPLICATION BLOCK DIAGRAM



COT Control Circuit Overview

Constant On Time control is based on a comparator and an on-time one shot, with the output voltage feedback compared with an internal 0.8V reference. If the feedback voltage is below the reference, the main MOSFET is turned on for a fixed on-time determined by a programming resistor R_{ON}. R_{ON} is connected to V_{IN} such that on-time is reduced with increasing input supply voltage. Following this on-time, the main MOSFET remains off for a minimum of 260 ns. If the voltage on the feedback pin falls below the reference level again the on-time cycle is repeated. Regulation is achieved in this manner.

Design Steps for the LMZ14201EXT Application

The LMZ14201EXT is fully supported by Webench® and offers the following: Component selection, electrical and thermal simulations as well as the build-it board for a reduction in design time. The following list of steps can be used to manually design the LMZ14201EXT application.

- Select minimum operating V_{IN} with enable divider resistors
- Program V_O with divider resistor selection
- Program turn-on time with soft-start capacitor selection
- Select C_O
- Select C_{IN}
- Set operating frequency with R_{ON}
- Determine module dissipation
- Layout PCB for required thermal performance

ENABLE DIVIDER, R_{ENT} AND R_{ENB} SELECTION

The enable input provides a precise 1.18V band-gap rising threshold to allow direct logic drive or connection to a voltage divider from a higher enable voltage such as V_{IN}. The enable input also incorporates 90 mV (typ) of hysteresis resulting in a falling threshold of 1.09V. The maximum recommended voltage into the EN pin is 6.5V. For applications where the midpoint of the enable divider exceeds 6.5V, a small zener can be added to limit this voltage.

The function of this resistive divider is to allow the designer to choose an input voltage below which the circuit will be disabled. This implements the feature of programmable under voltage lockout. This is often used in battery powered systems to prevent deep discharge of the system battery. It is also useful in system designs for sequencing of output rails or to prevent early turn-on of the supply as the main input voltage rail rises at power-up. Applying the enable divider to the main input rail is often done in the case of higher input voltage systems such as 24V AC/DC systems where a lower boundary of operation should be established. In the case of sequencing supplies, the divider is connected to a rail that becomes active earlier in the power-up cycle than the LMZ14201EXT output rail. The two resistors should be chosen based on the following ratio:

$$R_{ENT} / R_{ENB} = (V_{IN\ UVLO} / 1.18V) - 1 \quad (1)$$

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The LMZ14201EXT demonstration and evaluation boards use 11.8kΩ for R_{ENB} and 68.1kΩ for R_{ENT} resulting in a rising UVLO of 8V. This divider presents 6.25V to the EN input when the divider input is raised to 42V.

OUTPUT VOLTAGE SELECTION

Output voltage is determined by a divider of two resistors connected between V_O and ground. The midpoint of the divider is connected to the FB input. The voltage at FB is compared to a 0.8V internal reference. In normal operation an on-time cycle is initiated when the voltage on the FB pin falls below 0.8V. The main MOSFET on-time cycle causes the output voltage to rise and the voltage at the FB to exceed 0.8V. As long as the voltage at FB is above 0.8V, on-time cycles will not occur.

The regulated output voltage determined by the external divider resistors RFBT and RFBB is:

$$V_O = 0.8V * (1 + R_{FBT} / R_{FBB}) \quad (2)$$

Rearranging terms; the ratio of the feedback resistors for a desired output voltage is:

$$R_{FBT} / R_{FBB} = (V_O / 0.8V) - 1$$

These resistors should be chosen from values in the range of 1.0 kohm to 10.0 kohm.

For V_O = 0.8V the FB pin can be connected to the output directly so long as an output preload resistor remains that draws more than 20uA. Converter operation requires this minimum load to create a small inductor ripple current and maintain proper regulation when no load is present.

A feed-forward capacitor is placed in parallel with R_{FBT} to improve load step transient response. Its value is usually determined experimentally by load stepping between DCM and CCM conduction modes and adjusting for best transient response and minimum output ripple.

A table of values for R_{FBT} , R_{FBB} , C_{FF} and R_{ON} is included in the applications schematic.

SOFT-START CAPACITOR SELECTION

Programmable soft-start permits the regulator to slowly ramp to its steady state operating point after being enabled, thereby reducing current inrush from the input supply and slowing the output voltage rise-time to prevent overshoot.

Upon turn-on, after all UVLO conditions have been passed, an internal 8uA current source begins charging the external soft-start capacitor. The soft-start time duration to reach steady state operation is given by the formula:

$$t_{SS} = V_{REF} * C_{SS} / Iss = 0.8V * C_{SS} / 8uA \quad (3)$$

This equation can be rearranged as follows:

$$C_{SS} = t_{SS} * 8\ \mu A / 0.8V$$

Use of a 0.022µF results in 2.2 msec soft-start interval which is recommended as a minimum value.

As the soft-start input exceeds 0.8V the output of the power stage will be in regulation. The soft-start capacitor continues charging until it reaches approximately 3.8V on the SS pin. Voltage levels between 0.8V and 3.8V have no effect on other circuit operation. Note that the following conditions will reset the soft-start capacitor by discharging the SS input to ground with an internal 200 µA current sink.

- The enable input being “pulled low”
- Thermal shutdown condition
- Over-current fault
- Internal Vcc UVLO (Approximately 4V input to V_{IN})

C_O SELECTION

None of the required C_O output capacitance is contained within the module. At a minimum, the output capacitor must meet the worst case minimum ripple current rating of 0.5 * $I_{LR\ P-P}$, as calculated in Equation 14 below. Beyond that, additional capacitance will reduce output ripple so long as the ESR is low enough to permit it. A minimum value of 10 µF is generally required. Experimentation will be required if attempting to operate with a minimum value. Ceramic capacitors or other low ESR types are recommended. See AN-2024 SNVA422for more detail.

The following equation provides a good first pass approximation of C_O for load transient requirements:

$$C_O \geq I_{STEP} * V_{FB} * L * V_{IN} / (4 * V_O * (V_{IN} — V_O) * V_{OUT-TRAN}) \quad (4)$$

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Solving:

$C_O \geq 1A*0.8V*10\mu H*24V / (4*3.3V*(24V - 3.3V)*33mV) \geq 21.3\mu F$

The LMZ14201EXT demonstration and evaluation boards are populated with a 100 uF 6.3V X5R output capacitor. Locations for other output capacitors are provided.

C_{IN} SELECTION

The LMZ14201EXT module contains an internal 0.47 µF input ceramic capacitor. Additional input capacitance is required external to the module to handle the input ripple current of the application. This input capacitance should be located in very close proximity to the module. Input capacitor selection is generally directed to satisfy the input ripple current requirements rather than by capacitance value. Worst case input ripple current rating is dictated by the equation:

$I(C_{IN(RMS)}) \cong 1/2 * I_O * \sqrt{(D / 1-D)}$

where

- $D \cong V_O / V_{IN}$ (5)

(As a point of reference, the worst case ripple current will occur when the module is presented with full load current and when $V_{IN} = 2 * V_O$).

Recommended minimum input capacitance is 10uF X7R ceramic with a voltage rating at least 25% higher than the maximum applied input voltage for the application. It is also recommended that attention be paid to the voltage and temperature deratings of the capacitor selected. It should be noted that ripple current rating of ceramic capacitors may be missing from the capacitor data sheet and you may have to contact the capacitor manufacturer for this rating.

If the system design requires a certain minimum value of input ripple voltage ΔV_{IN} be maintained then the following equation may be used.

$C_{IN} \geq I_O * D * (1-D) / f_{SW-CCM} * \Delta V_{IN}$ (6)

If ΔV_{IN} is 1% of V_{IN} for a 24V input to 3.3V output application this equals 240 mV and f_{SW} = 400 kHz.

$C_{IN} \geq 1A * 3.3V/24V * (1 - 3.3V/24V) / (400000 * 0.240 V)$

$\geq 0.9\mu F$

Additional bulk capacitance with higher ESR may be required to damp any resonant effects of the input capacitance and parasitic inductance of the incoming supply lines.

R_{ON} RESISTOR SELECTION

Many designs will begin with a desired switching frequency in mind. For that purpose the following equation can be used.

$f_{SW(CCM)} \cong V_O / (1.3 * 10^{-10} * R_{ON})$ (7)

This can be rearranged as

$R_{ON} \cong V_O / (1.3 * 10^{-10} * f_{SW(CCM)})$ (8)

The selection of RON and $f_{SW(CCM)}$ must be confined by limitations in the on-time and off-time for the COT control section.

The on-time of the LMZ14201EXT timer is determined by the resistor R_{ON} and the input voltage V_{IN}. It is calculated as follows:

$t_{ON} = (1.3 * 10^{-10} * R_{ON}) / V_{IN}$ (9)

The inverse relationship of t_{ON} and V_{IN} gives a nearly constant switching frequency as V_{IN} is varied. R_{ON} should be selected such that the on-time at maximum V_{IN} is greater than 150 ns. The on-timer has a limiter to ensure a minimum of 150 ns for t_{ON}. This limits the maximum operating frequency, which is governed by the following equation:

$f_{SW(MAX)} = V_O / (V_{IN(MAX)} * 150 \text{ nsec})$ (10)

This equation can be used to select R_{ON} if a certain operating frequency is desired so long as the minimum on-time of 150 ns is observed. The limit for R_{ON} can be calculated as follows:

$R_{ON} \geq V_{IN(MAX)} * 150 \text{ nsec} / (1.3 * 10^{-10})$ (11)

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If R_{ON} calculated in Equation 8 is less than the minimum value determined in Equation 11 a lower frequency should be selected. Alternatively, $V_{IN(MAX)}$ can also be limited in order to keep the frequency unchanged.

Additionally note, the minimum off-time of 260 ns limits the maximum duty ratio. Larger R_{ON} (lower F_{SW}) should be selected in any application requiring large duty ratio.

Discontinuous Conduction and Continuous Conduction Modes

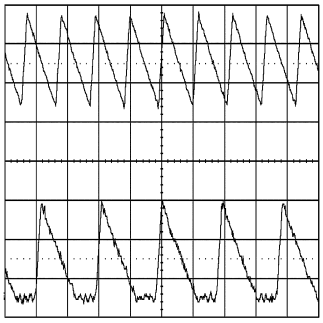
At light load the regulator will operate in discontinuous conduction mode (DCM). With load currents above the critical conduction point, it will operate in continuous conduction mode (CCM). When operating in DCM the switching cycle begins at zero amps inductor current; increases up to a peak value, and then recedes back to zero before the end of the off-time. Note that during the period of time that inductor current is zero, all load current is supplied by the output capacitor. The next on-time period starts when the voltage on the at the FB pin falls below the internal reference. The switching frequency is lower in DCM and varies more with load current as compared to CCM. Conversion efficiency in DCM is maintained since conduction and switching losses are reduced with the smaller load and lower switching frequency. Operating frequency in DCM can be calculated as follows:

$$f_{SW(DCM)} \cong V_O*(V_{IN}-1)*10\mu H*1.18*10^{20}*I_O/(V_{IN}-V_O)*R_{ON}^2 \quad (12)$$

In CCM, current flows through the inductor through the entire switching cycle and never falls to zero during the off-time. The switching frequency remains relatively constant with load current and line voltage variations. The CCM operating frequency can be calculated using Equation 7 above.

Following is a comparison pair of waveforms of the showing both CCM (upper) and DCM operating modes.

Figure 35. CCM and DCM Operating Modes
V_{IN} = 12V, V_O = 3.3V, I_O = 1 A / 0.25 A

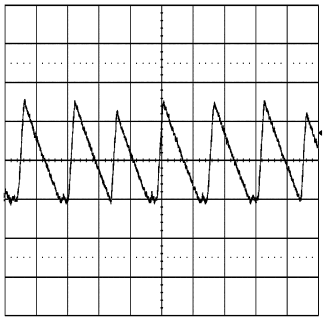


The approximate formula for determining the DCM/CCM boundary is as follows:

$$I_{DCB} \cong V_O*(V_{IN}-V_O)/(2*10\ \mu H*f_{SW(CCM)}*V_{IN}) \quad (13)$$

Following is a typical waveform showing the boundary condition.

Figure 36. Transition Mode Operation
V_{IN} = 24V, V_O = 3.3V, I_O = 0.29 A



The inductor internal to the module is 10 µH. This value was chosen as a good balance between low and high input voltage applications. The main parameter affected by the inductor is the amplitude of the inductor ripple current (I_{LR}). I_{LR} can be calculated with:

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$I_{LR\ P-P}=V_O*(V_{IN}- V_O)/(10\mu H*f_{SW}*V_{IN})$

where

- V_{IN} is the maximum input voltage
- f_{SW} is determined from Equation 7 (14)

If the output current I_O is determined by assuming that $I_O = I_L$, the higher and lower peak of I_{LR} can be determined. Be aware that the lower peak of I_{LR} must be positive if CCM operation is required.

POWER DISSIPATION AND BOARD THERMAL REQUIREMENTS

For the design case of V_{IN} = 24V, V_O = 3.3V, I_O = 1A, $T_{AMB(MAX)}$ = 85°C , and $T_{JUNCTION}$ = 125°C, the device must see a thermal resistance from case to ambient of less than:

$$\theta_{CA} < (T_{J\text{-}MAX} — T_{AMB(MAX)}) / P_{IC\text{-}LOSS} - \theta_{JC} \quad (15)$$

Given the typical thermal resistance from junction to case to be 1.9 °C/W. Use the 85°C power dissipation curves in the Typical Performance Characteristics section to estimate the $P_{IC\text{-}LOSS}$ for the application being designed. In this application it is 0.52W.

$$\theta_{CA} = (125 — 85) / 0.52W — 1.9 = 75$$

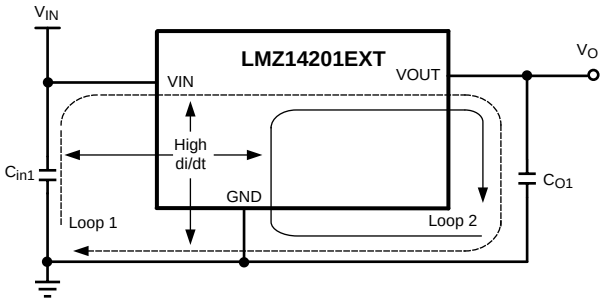
To reach θ_{CA} = 75, the PCB is required to dissipate heat effectively. With no airflow and no external heat, a good estimate of the required board area covered by 1 oz. copper on both the top and bottom metal layers is:

$$\text{Board Area_cm}^2 = 500°C \text{ x cm}^2/W / \theta_{JC} \quad (16)$$

As a result, approximately 6 square cm of 1 oz copper on top and bottom layers is required for the PCB design. Additional area will decrease die temperature proportionately. The PCB copper heat sink must be connected to the exposed pad. Approximately thirty six, 10mils (254 µm) thermal vias spaced 59mils (1.5 mm) apart must connect the top copper to the bottom copper. For an example of a high thermal performance PCB layout of approximately 31 square cm area. Refer to the Evaluation Board application note AN-2024 SNVA422. For more information on thermal design see AN-2020 SNVA419 and AN-2026 SNVA424.

PC BOARD LAYOUT GUIDELINES

PC board layout is an important part of DC-DC converter design. Poor board layout can disrupt the performance of a DC-DC converter and surrounding circuitry by contributing to EMI, ground bounce and resistive voltage drop in the traces. These can send erroneous signals to the DC-DC converter resulting in poor regulation or instability. Good layout can be implemented by following a few simple design rules.



1. Minimize area of switched current loops.

From an EMI reduction standpoint, it is imperative to minimize the high di/dt paths during PC board layout. The high current loops that do not overlap have high di/dt content that will cause observable high frequency noise on the output pin if the input capacitor (Cin1) is placed at a distance away from the LMZ14201EXT. Therefore place C_{IN1} as close as possible to the LMZ14201EXT VIN and GND exposed pad. This will minimize the high di/dt area and reduce radiated EMI. Additionally, grounding for both the input and output capacitor should consist of a localized top side plane that connects to the GND exposed pad (EP).

2. Have a single point ground.

The ground connections for the feedback, soft-start, and enable components should be routed to the GND pin of the device. This prevents any switched or load currents from flowing in the analog ground traces. If not properly handled, poor grounding can result in degraded load regulation or erratic output voltage ripple behavior. Provide the single point ground connection from pin 4 to EP.

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3. Minimize trace length to the FB pin.

Both feedback resistors, R_{FBT} and R_{FBB}, and the feed forward capacitor C_{FF}, should be located close to the FB pin. Since the FB node is high impedance, maintain the copper area as small as possible. The trace are from R_{FBT}, R_{FBB}, and C_{FF} should be routed away from the body of the LMZ14201EXT to minimize noise.

4. Make input and output bus connections as wide as possible.

This reduces any voltage drops on the input or output of the converter and maximizes efficiency. To optimize voltage accuracy at the load, ensure that a separate feedback voltage sense trace is made to the load. Doing so will correct for voltage drops and provide optimum output accuracy.

5. Provide adequate device heat-sinking.

Use an array of heat-sinking vias to connect the exposed pad to the ground plane on the bottom PCB layer. If the PCB has a plurality of copper layers, these thermal vias can also be employed to make connection to inner layer heat-spreading ground planes. For best results use a 6 x 6 via array with minimum via diameter of 10mils (254 µm) thermal vias spaced 59mils (1.5 mm). Ensure enough copper area is used for heat-sinking to keep the junction temperature below 125°C.

Additional Features

OUTPUT OVER-VOLTAGE COMPARATOR

The voltage at FB is compared to a 0.92V internal reference. If FB rises above 0.92V the on-time is immediately terminated. This condition is known as over-voltage protection (OVP). It can occur if the input voltage is increased very suddenly or if the output load is decreased very suddenly. Once OVP is activated, the top MOSFET on-times will be inhibited until the condition clears. Additionally, the synchronous MOSFET will remain on until inductor current falls to zero.

CURRENT LIMIT

Current limit detection is carried out during the off-time by monitoring the current in the synchronous MOSFET. Referring to the Functional Block Diagram, when the top MOSFET is turned off, the inductor current flows through the load, the PGND pin and the internal synchronous MOSFET. If this current exceeds 2.0 (typical) the current limit comparator disables the start of the next on-time period. The next switching cycle will occur only if the FB input is less than 0.8V and the inductor current has decreased below 2.0A. Inductor current is monitored during the period of time the synchronous MOSFET is conducting. So long as inductor current exceeds 2.0A, further on-time intervals for the top MOSFET will not occur. Switching frequency is lower during current limit due to the longer off-time. It should also be noted that current limit is dependent on both duty cycle and temperature as illustrated in the graphs in the typical performance section.

THERMAL PROTECTION

The junction temperature of the LMZ14201EXT should not be allowed to exceed its maximum ratings. Thermal protection is implemented by an internal Thermal Shutdown circuit which activates at 165 °C (typ) causing the device to enter a low power standby state. In this state the main MOSFET remains off causing V_O to fall, and additionally the CSS capacitor is discharged to ground. Thermal protection helps prevent catastrophic failures for accidental device overheating. When the junction temperature falls back below 145 °C (typ Hyst = 20 °C) the SS pin is released, V_O rises smoothly, and normal operation resumes.

Applications requiring maximum output current especially those at high input voltage may require application derating at elevated temperatures.

ZERO COIL CURRENT DETECTION

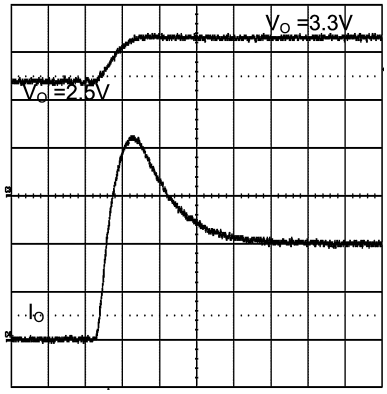
The current of the lower (synchronous) MOSFET is monitored by a zero coil current detection circuit which inhibits the synchronous MOSFET when its current reaches zero until the next on-time. This circuit enables the DCM operating mode, which improves efficiency at light loads.

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PRE-BIASED STARTUP

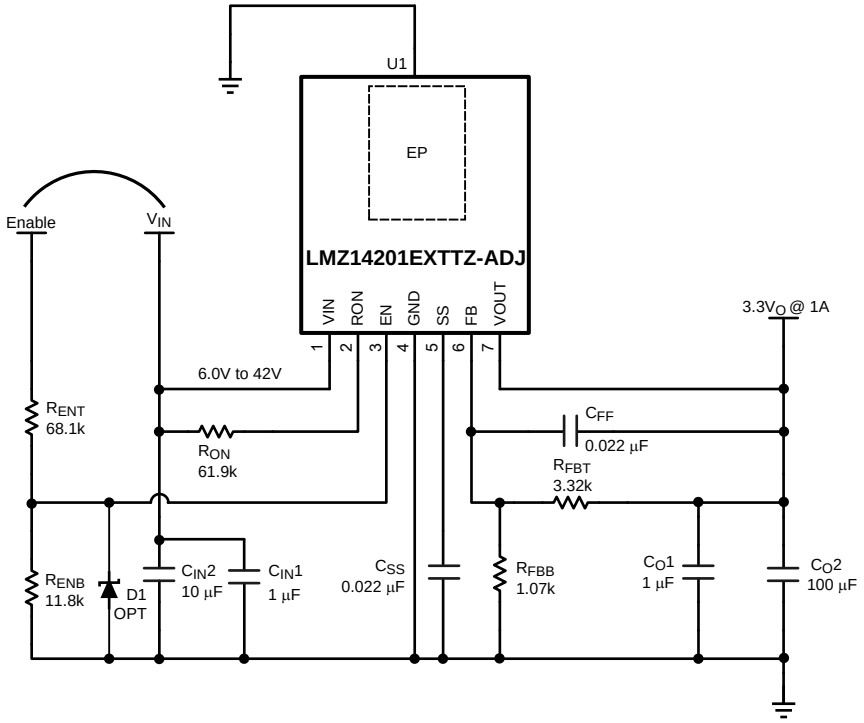
The LMZ14201EXT will properly start up into a pre-biased output. This startup situation is common in multiple rail logic applications where current paths may exist between different power rails during the startup sequence. The following scope capture shows proper behavior during this event.

Figure 37. Pre-Biased Startup



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Evaluation Board Schematic Diagram and BOM



Ref Des	Description	Case Size	Manufacturer	Manufacturer P/N
U1	SIMPLE SWITCHER ®	PFM-7	Texas Instruments	LMZ14201EXTTZ-ADJ
C_{in1}	1 µF, 50V, X7R	1206	Taiyo Yuden	UMK316B7105KL-T
C_{in2}	10 µF, 50V, X7R	1210	Taiyo Yuden	UMK325BJ106MM-T
C_{O1}	1 µF, 50V, X7R	1206	Taiyo Yuden	UMK316B7105KL-T
C_{O2}	100 µF, 6.3V, X7R	1210	Taiyo Yuden	JMK325BJ107MM-T
R_{FBT}	3.32 kΩ	0603	Vishay Dale	CRCW06033K32FKEA
R_{FBB}	1.07 kΩ	0603	Vishay Dale	CRCW06031K07FKEA
R_{ON}	61.9 kΩ	0603	Vishay Dale	CRCW060361k9FKEA
R_{ENT}	68.1 kΩ	0603	Vishay Dale	CRCW060368k1FKEA
R_{ENB}	11.8 kΩ	0603	Vishay Dale	CRCW060311k8FKEA
C_{FF}	22 nF, ±10%, X7R, 16V	0603	TDK	C1608X7R1H223K
C_{SS}	22 nF, ±10%, X7R, 16V	0603	TDK	C1608X7R1H223K
D1	5.1V	SOD-23	—	Optional

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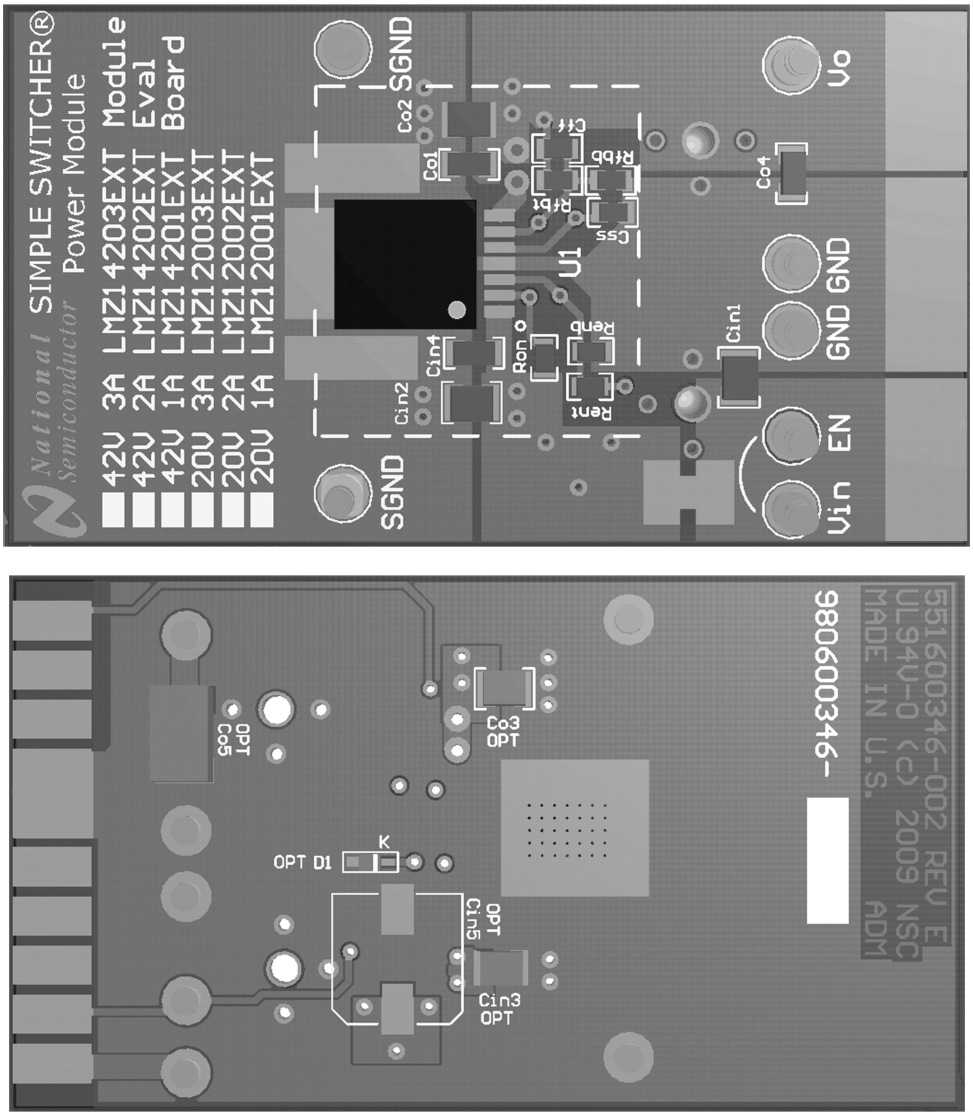


Figure 38. Top View and Bottom View of Evaluation PCB

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REVISION HISTORY

Changes from Revision D (April 2013) to Revision E	Page
• Changed layout of National Data Sheet to TI format	20

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PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LMZ14201EXTTZ/NOPB	Active	Production	TO-PMOD (NDW) | 7	250 | SMALL T&R	Yes	SN	Level-3-245C-168 HR	-55 to 125	LMZ14201 EXT
LMZ14201EXTTZ/NOPB.A	Active	Production	TO-PMOD (NDW) | 7	250 | SMALL T&R	Yes	SN	Level-3-245C-168 HR	-55 to 125	LMZ14201 EXT
LMZ14201EXTTZE/NO.A	Active	Production	TO-PMOD (NDW) | 7	45 | TUBE	Yes	SN	Level-3-245C-168 HR	-55 to 125	LMZ14201 EXT
LMZ14201EXTTZE/NOPB	Active	Production	TO-PMOD (NDW) | 7	45 | TUBE	Yes	SN	Level-3-245C-168 HR	-55 to 125	LMZ14201 EXT
LMZ14201EXTTZX/NO.A	Active	Production	TO-PMOD (NDW) | 7	500 | LARGE T&R	Yes	SN	Level-3-245C-168 HR	-55 to 125	LMZ14201 EXT
LMZ14201EXTTZX/NOPB	Active	Production	TO-PMOD (NDW) | 7	500 | LARGE T&R	Yes	SN	Level-3-245C-168 HR	-55 to 125	LMZ14201 EXT

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

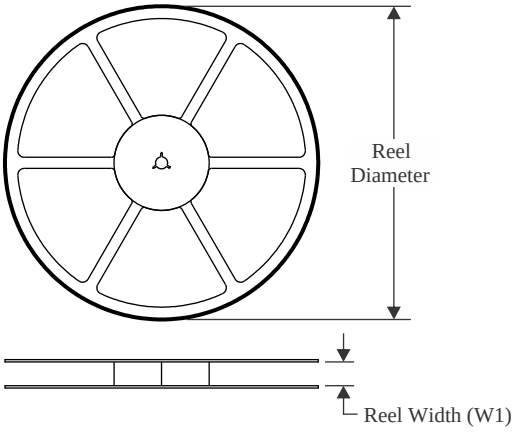
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

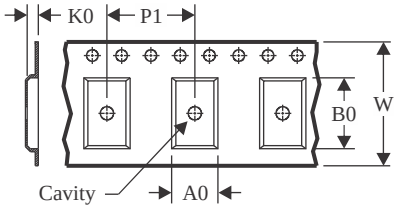
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

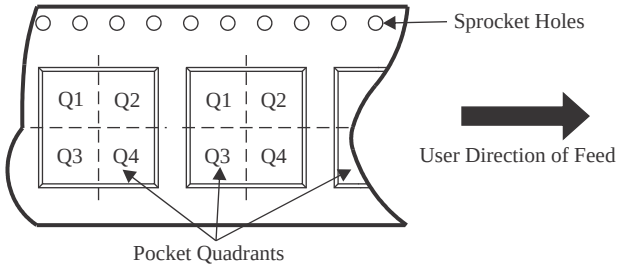


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

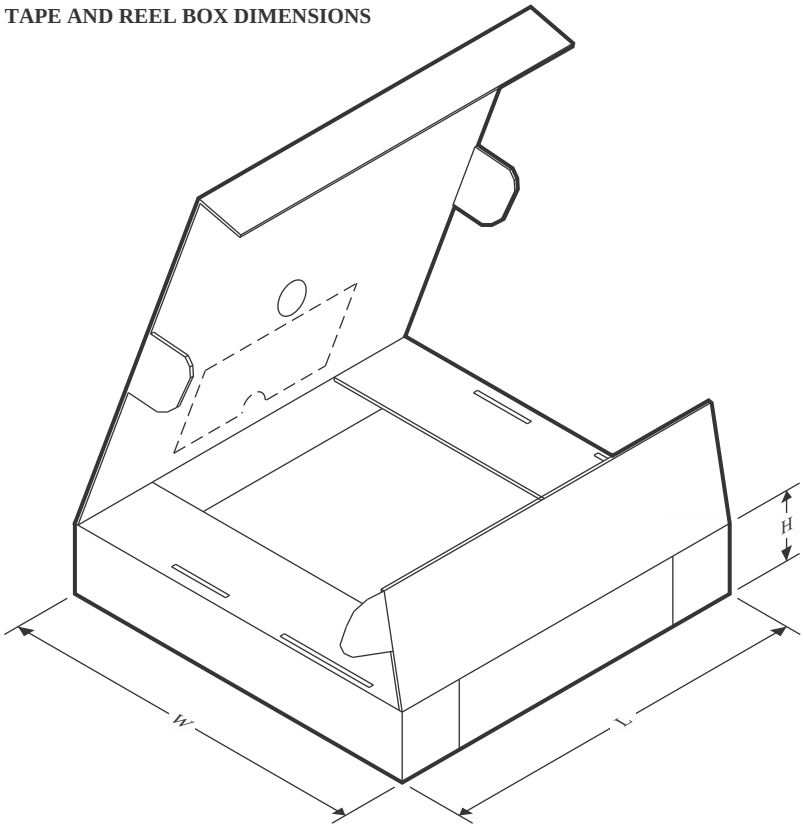
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMZ14201EXTTZ/NOPB	TO-PMOD	NDW	7	250	330.0	24.4	10.6	14.22	5.0	16.0	24.0	Q2
LMZ14201EXTTZX/NOPB	TO-PMOD	NDW	7	500	330.0	24.4	10.6	14.22	5.0	16.0	24.0	Q2

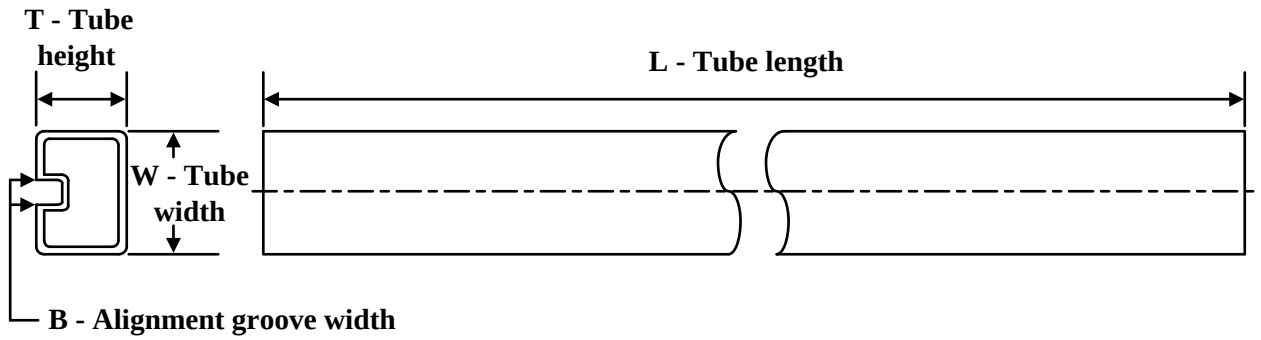
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMZ14201EXTTZ/NOPB	TO-PMOD	NDW	7	250	356.0	356.0	45.0
LMZ14201EXTTZX/NOPB	TO-PMOD	NDW	7	500	356.0	356.0	45.0

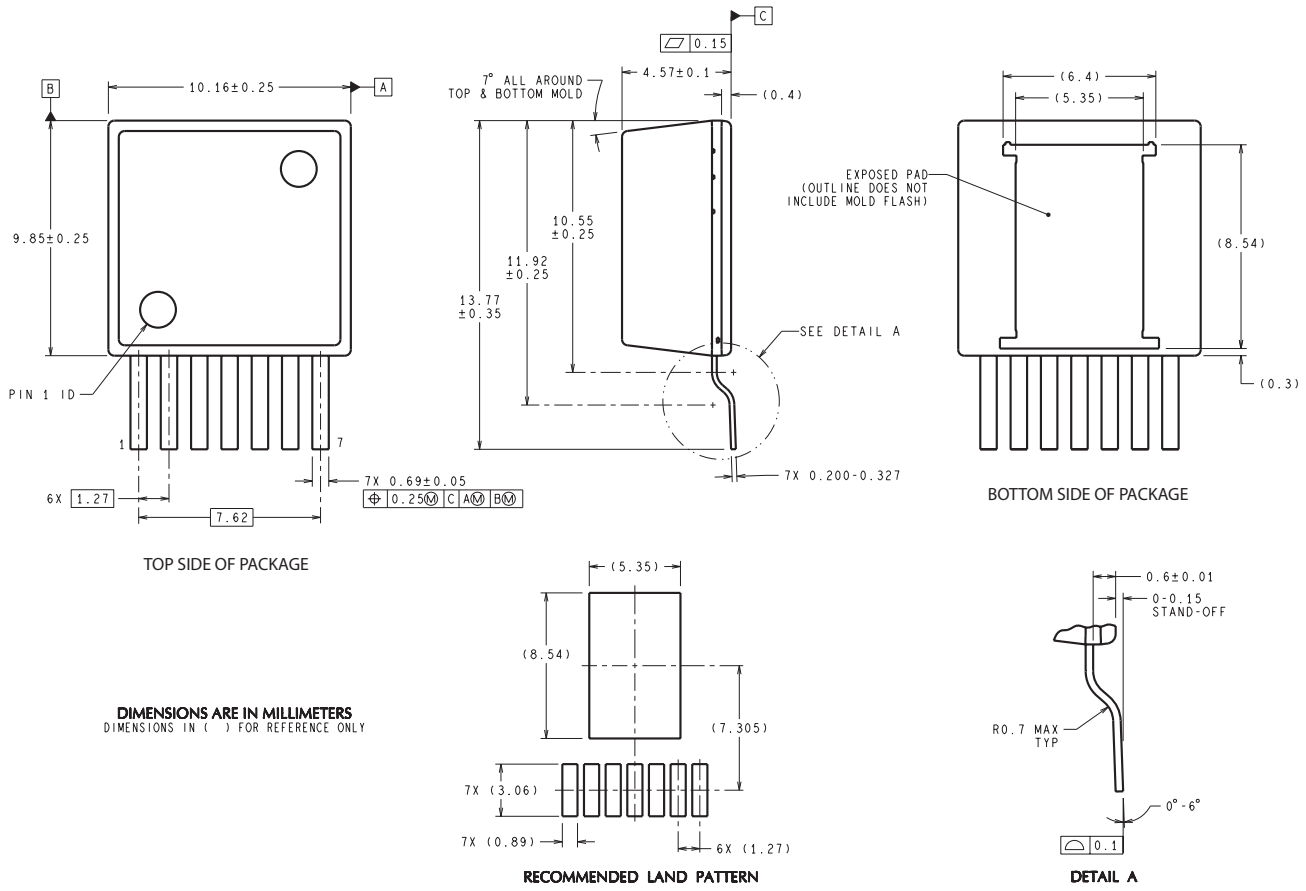
TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
LMZ14201EXTTZE/NO.A	NDW	TO-PMOD	7	45	502	17	6700	8.4
LMZ14201EXTTZE/NOPB	NDW	TO-PMOD	7	45	502	17	6700	8.4

NDW0007A



TZA07A (Rev D)

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