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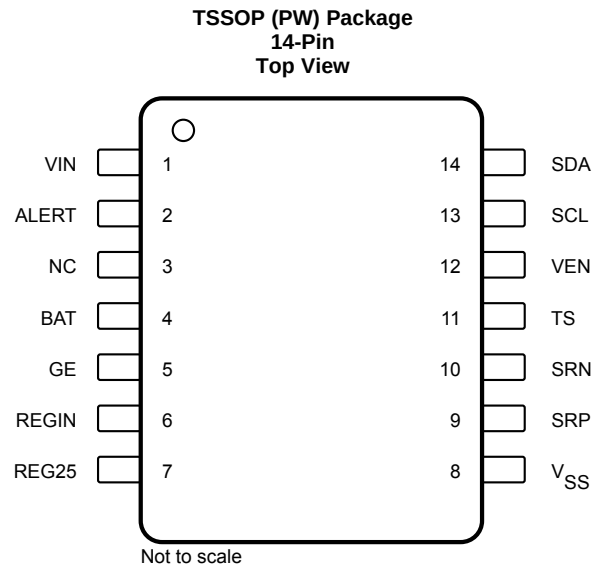
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## 5 Pin Configuration and Functions



### Pin Functions

| NUMBER | NAME                      | I/O               | DESCRIPTION                                                                                                                                                          |
|--------|---------------------------|-------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1      | VIN                       | AI <sup>(1)</sup> | Optional voltage measurement input                                                                                                                                   |
| 2      | $\overline{\text{ALERT}}$ | O                 | Active low interrupt open-drain output. Requires an external pullup                                                                                                  |
| 3      | NC                        | —                 | Not used and should be connected to V <sub>SS</sub> .                                                                                                                |
| 4      | BAT                       | P                 | Voltage measurement input and can be left floating or tied to V <sub>SS</sub> if not used.                                                                           |
| 5      | GE                        | I                 | Gauge enable. Internal LDO is disconnected from RGIN when driven low.                                                                                                |
| 6      | REGIN                     | P                 | Internal integrated LDO input. Decouple with 0.1-μF ceramic capacitor to V <sub>SS</sub> .                                                                           |
| 7      | REG25                     | P                 | 2.5-V output voltage of the internal integrated LDO. Decouple with 1-μF ceramic capacitor V <sub>SS</sub> .                                                          |
| 8      | V <sub>SS</sub>           | P                 | Device ground                                                                                                                                                        |
| 9      | SRP                       | I                 | Analog input pin connected to the internal coulomb-counter peripheral for integrating a small voltage between SRP and SRN where SRP is nearest the BAT– connection.  |
| 10     | SRN                       | I                 | Analog input pin connected to the internal coulomb-counter peripheral for integrating a small voltage between SRP and SRN where SRN is nearest the PACK– connection. |
| 11     | TS                        | I                 | Pack thermistor voltage sense (use 103AT-type thermistor)                                                                                                            |
| 12     | VEN                       | O                 | Optional open-drain external voltage divider control output                                                                                                          |
| 13     | SCL                       | I                 | Slave I <sup>2</sup> C serial communication clock input. Use with a 10-K pullup resistor (typical).                                                                  |
| 14     | SDA                       | I/O               | Open-drain slave I <sup>2</sup> C serial communication data line. Use with a 10-kΩ pullup resistor (typical).                                                        |

(1) P = Power Connection, O = Digital Output, AI = Analog Input, I = Digital Input, I/OD = Digital Input/Output

## 6 Specifications

### 6.1 Absolute Maximum Ratings

Over-operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

|                    |                                      | MIN  | MAX                      | UNIT |
|--------------------|--------------------------------------|------|--------------------------|------|
| V <sub>REGIN</sub> | Regulator Input Range                | −0.3 | 5.5                      | V    |
| V <sub>REG25</sub> | Supply Voltage Range                 | −0.3 | 2.75                     | V    |
| V <sub>IOD</sub>   | Open-drain I/O pins (SDA, SCL, VEN)  | −0.3 | 5.5                      | V    |
|                    | Open-drain I/O pins (ALERT)          | −0.3 | 2.75                     | V    |
| V <sub>BAT</sub>   | BAT Input Pin                        | −0.3 | 5.5                      | V    |
| V <sub>I</sub>     | Input voltage range (SRN, SRP, TS)   | −0.3 | V <sub>REG25</sub> + 0.3 | V    |
| T <sub>A</sub>     | Operating free-air temperature range | −40  | 85                       | °C   |
| T <sub>F</sub>     | Functional Temperature Range         | −40  | 100                      | °C   |
| T <sub>STG</sub>   | Storage temperature range            | −65  | 150                      | °C   |
|                    | Lead temperature (soldering, 10 s)   | −40  | 100                      | °C   |

- (1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute–maximum–rated conditions for extended periods may affect device reliability.

### 6.2 ESD Ratings

|                    |                         | VALUE                                                                              | UNIT  |
|--------------------|-------------------------|------------------------------------------------------------------------------------|-------|
| V <sub>(ESD)</sub> | Electrostatic discharge | Human Body Model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> , BAT pin        | ±1500 |
|                    |                         | Human Body Model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> , all other pins | ±2000 |
|                    |                         | Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>     | ±500  |

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

T<sub>A</sub> = −40°C to 85°C; Typical Values at T<sub>A</sub> = 25°C C<sub>LDO25</sub> = 1.0 μF, and V<sub>REGIN</sub> = 3.6 V (unless otherwise noted)

|                                        |                                                                             |                                                                                                             | MIN                     | NOM  | MAX | UNIT |
|----------------------------------------|-----------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------|-------------------------|------|-----|------|
| V <sub>REGIN</sub>                     | Supply Voltage                                                              | No operating restrictions                                                                                   | 2.7                     |      | 4.5 | V    |
|                                        |                                                                             | No FLASH writes                                                                                             | 2.45                    |      | 2.7 | V    |
| C <sub>REGIN</sub>                     | External input capacitor for internal LDO between REGIN and V <sub>SS</sub> | Nominal capacitor values specified. Recommend a 10% ceramic X5R type capacitor located close to the device. |                         | 0.1  |     | μF   |
| C <sub>LDO25</sub>                     | External output capacitor for internal LDO between V <sub>REG25</sub>       |                                                                                                             | 0.47                    | 1    |     | μF   |
| I <sub>CC_GELow</sub> <sup>(1)</sup>   | Gas gauge in Disabled mode                                                  | GE = Low                                                                                                    |                         | 0.05 |     | μA   |
| I <sub>CC_ACC_AVE</sub> <sup>(1)</sup> | Gas gauge in ACCUMULATOR mode average current                               | Update every 30 minutes otherwise GE = Low                                                                  |                         | 0.3  |     | μA   |
| I <sub>CC_SOH_AVE</sub> <sup>(1)</sup> | State-of-health average current                                             | Update every 8 hours otherwise GE = Low                                                                     |                         | 0.06 |     | μA   |
| I <sub>CC_EOS_AVE</sub> <sup>(1)</sup> | End-of-service average current                                              | Update every 8 hours 3- s Load Pulse otherwise GE = Low                                                     |                         | 0.35 |     | μA   |
| VA1                                    | Input voltage range (VIN, TS)                                               |                                                                                                             | V <sub>SS</sub> − 0.05  |      | 1   | V    |
| VA2                                    | Input voltage range (BAT)                                                   |                                                                                                             | V <sub>SS</sub> − 0.125 |      | 5.0 | V    |

- (1) Not production tested

## Recommended Operating Conditions (continued)

$T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$   $C_{LDO25} = 1.0\ \mu\text{F}$ , and  $V_{\text{REGIN}} = 3.6\ \text{V}$  (unless otherwise noted)

|                   |                                  |  | MIN                     | NOM | MAX   | UNIT          |
|-------------------|----------------------------------|--|-------------------------|-----|-------|---------------|
| VA3               | Input voltage range (SRP, SRN)   |  | $V_{\text{SS}} - 0.125$ |     | 0.125 | V             |
| ILKG              | Input leakage current (I/O pins) |  |                         |     | 0.3   | $\mu\text{A}$ |
| $t_{\text{PUCD}}$ | Power-up communication           |  |                         | 250 |       | ms            |

## 6.4 Thermal Information

| THERMAL METRIC <sup>(1)</sup>        |                                              | BQ35100    | UNIT                 |
|--------------------------------------|----------------------------------------------|------------|----------------------|
|                                      |                                              | TSSOP (PW) |                      |
|                                      |                                              | 14 PINS    |                      |
| $R_{\theta\text{JA}}$ , High K       | Junction-to-ambient thermal resistance       | 103.8      | $^{\circ}\text{C/W}$ |
| $R_{\theta\text{JC}}(\text{top})$    | Junction-to-case(top) thermal resistance     | 31.9       | $^{\circ}\text{C/W}$ |
| $R_{\theta\text{JB}}$                | Junction-to-board thermal resistance         | 46.6       | $^{\circ}\text{C/W}$ |
| $\Psi_{\text{JT}}$                   | Junction-to-top characterization parameter   | 2.0        | $^{\circ}\text{C/W}$ |
| $\Psi_{\text{JB}}$                   | Junction-to-board characterization parameter | 45.9       | $^{\circ}\text{C/W}$ |
| $R_{\theta\text{JC}}(\text{bottom})$ | Junction-to-case(bottom) thermal resistance  | N/A        | $^{\circ}\text{C/W}$ |

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

## 6.5 Power Supply Current Static Modes

over operating free-air temperature range (unless otherwise noted)

| PARAMETER                          | TEST CONDITIONS                                                                                                                                | MIN | TYP  | MAX | UNIT          |
|------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------|-----|------|-----|---------------|
| $I_{\text{CC\_ACCU}}^{(1)}$        | Gas gauge in ACCUMULATOR mode<br>GE = High AND <i>GaugeStart()</i> received and <i>GaugeStop()</i> not Received (GMSEL1,0 = 0,0)               |     | 130  |     | $\mu\text{A}$ |
| $I_{\text{CC\_SOH}}^{(1)}$         | State-of-health operating current<br>GE = High AND <i>GaugeStart()</i> received and <i>GaugeStop()</i> not Received (GMSEL1,0 = 0,1)           |     | 40   |     | $\mu\text{A}$ |
| $I_{\text{CC\_EOS\_Burst}}^{(1)}$  | End-of-service operating current—data burst<br>GE = High AND <i>GaugeStart()</i> received and <i>GaugeStop()</i> not Received (GMSEL1,0 = 1,0) |     | 315  |     | $\mu\text{A}$ |
| $I_{\text{CC\_EOS\_Gather}}^{(1)}$ | End-of-service operating current—data gathering<br>GE = High AND <i>GaugeStart()</i> AND <i>GaugeStop()</i> Received (GMSEL1,0 = 1,0)          |     | 75   |     | $\mu\text{A}$ |
| $I_{\text{CC\_GELOW}}^{(1)}$       | Device Disabled<br>GE = LOW                                                                                                                    |     | 0.05 |     | $\mu\text{A}$ |

(1) Not production tested

## 6.6 Digital Input and Outputs

| PARAMETER                  | TEST CONDITIONS                                                                                        | MIN                                                | TYP | MAX  | UNIT          |
|----------------------------|--------------------------------------------------------------------------------------------------------|----------------------------------------------------|-----|------|---------------|
| $V_{\text{OL}}$            | Output voltage low (SDA, SCL, VEN)<br>$I_{\text{OL}} = 3\ \text{mA}$                                   |                                                    |     | 0.4  | V             |
| $V_{\text{OH}}(\text{PP})$ | Output high voltage<br>$I_{\text{OH}} = -1\ \text{mA}$                                                 | $V_{\text{REG25}} - 0.5$                           |     |      | V             |
| $V_{\text{OH}}(\text{OD})$ | Output high voltage (SDA, SCL, VEN, ALERT)<br>External pullup resistor connected to $V_{\text{REG25}}$ | $V_{\text{REG25}} - 0.5$                           |     |      | V             |
| $V_{\text{IL}}$            | Input voltage low (SDA, SCL)                                                                           | -0.3                                               |     | 0.6  | V             |
| $V_{\text{IH}}$            | Input voltage high (SDA, SCL)                                                                          | 1.2                                                |     | 5.5  | V             |
| $V_{\text{IL}}(\text{GE})$ | GE Low-level input voltage                                                                             | $V_{\text{REGIN}} = 2.8\ \text{to}\ 4.5\ \text{V}$ |     | 0.8  | V             |
| $V_{\text{IH}}(\text{GE})$ | GE High-level input voltage                                                                            |                                                    |     | 2.65 |               |
| $I_{\text{IKG}}$           | Input leakage current (I/O pins)                                                                       |                                                    |     | 0.3  | $\mu\text{A}$ |

## 6.7 Power-On Reset

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{ V}$  (unless otherwise noted)

| PARAMETER                                                      | TEST CONDITIONS | MIN  | TYP  | MAX  | UNIT |
|----------------------------------------------------------------|-----------------|------|------|------|------|
| $V_{\text{IT+}}$ Positive-going battery voltage input at REG25 |                 | 2.05 | 2.20 | 2.31 | V    |
| $V_{\text{HYS}}$ Power-on reset hysteresis                     |                 |      | 115  |      | mV   |

## 6.8 LDO Regulator

 $T_A = 25^{\circ}\text{C}$ ,  $C_{\text{LDO25}} = 1.0\text{ }\mu\text{F}$ ,  $V_{\text{REGIN}} = 3.6\text{ V}$  (unless otherwise noted)<sup>(1)</sup>

| PARAMETER                                            | TEST CONDITIONS                                                                                                                                 | MIN | TYP | MAX | UNIT |
|------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------|-----|-----|-----|------|
| $V_{\text{REG25}}$ Regulator output voltage          | $2.7\text{ V} \leq V_{\text{REGIN}} \leq 4.5\text{ V}$ , $I_{\text{OUT}} \leq 16\text{ mA}$ $T_A = -40^{\circ}\text{C}$ to $85^{\circ}\text{C}$ | 2.3 | 2.5 | 2.7 | V    |
|                                                      | $2.45\text{ V} \leq V_{\text{REGIN}} < 2.7\text{ V}$ , $I_{\text{OUT}} \leq 3\text{ mA}$ $T_A = -40^{\circ}\text{C}$ to $85^{\circ}\text{C}$    | 2.3 |     |     |      |
| $I_{\text{SHORT}}^{(2)}$ Short circuit current limit | $V_{\text{REG25}} = 0\text{ V}$<br>$T_A = -40^{\circ}\text{C}$ to $85^{\circ}\text{C}$                                                          |     |     | 250 | mA   |

(1) LDO output current,  $I_{\text{OUT}}$ , is the sum of internal and external load currents.

(2) Specified by design. Not production tested.

## 6.9 Internal Temperature Sensor

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $2.4\text{ V} < \text{REG25} < 2.6\text{ V}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$  and  $\text{REG25} = 2.5\text{ V}$  (unless otherwise noted)

| PARAMETER                                                  | TEST CONDITIONS | MIN | TYP | MAX | UNIT                   |
|------------------------------------------------------------|-----------------|-----|-----|-----|------------------------|
| $G_{\text{TEMP}}$ Internal temperature sensor voltage gain |                 |     | -2  |     | mV/ $^{\circ}\text{C}$ |

## 6.10 Internal Clock Oscillators

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $2.4\text{ V} < \text{REG25} < 2.6\text{ V}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$  and  $\text{REG25} = 2.5\text{ V}$  (unless otherwise noted)

| PARAMETER                                       | TEST CONDITIONS | MIN | TYP    | MAX | UNIT |
|-------------------------------------------------|-----------------|-----|--------|-----|------|
| $f_{(\text{LOSC})}$ Operating frequency         |                 |     | 32.768 |     | kHz  |
| $f_{(\text{OSC})}$ Operating frequency          |                 |     | 2.097  |     | MHz  |
| $t_{(\text{SXO})}$ Start-up time <sup>(1)</sup> |                 |     | 2.5    | 5   | ms   |

(1) The startup time is defined as the time it takes for the oscillator output frequency to be  $\pm 3\%$ .

## 6.11 Integrating ADC (Coulomb Counter)

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $2.4\text{ V} < \text{REG25} < 2.6\text{ V}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$  and  $\text{REG25} = 2.5\text{ V}$  (unless otherwise noted)

| PARAMETER                                                                        | TEST CONDITIONS                                         | MIN    | TYP           | MAX   | UNIT               |
|----------------------------------------------------------------------------------|---------------------------------------------------------|--------|---------------|-------|--------------------|
| $V_{(\text{SR})}$ Input voltage range, $V_{(\text{SRN})}$ and $V_{(\text{SRP})}$ | $V_{(\text{SR})} = V_{(\text{SRN})} - V_{(\text{SRP})}$ | -0.125 |               | 0.125 | V                  |
| $t_{\text{SR\_CONV}}$                                                            | Conversion time                                         |        | 1             |       | s                  |
|                                                                                  | Resolution                                              | 14     |               | 15    | bits               |
| $V_{\text{OS}(\text{SR})}$ Input offset                                          |                                                         |        | 10            |       | $\mu\text{V}$      |
| INL Integral nonlinearity error                                                  |                                                         |        | $\pm 0.007\%$ |       | FSR <sup>(1)</sup> |
| $Z_{\text{IN}(\text{SR})}$ Effective input resistance <sup>(2)</sup>             |                                                         | 2.5    |               |       | M $\Omega$         |
| $I_{\text{LKG}(\text{SR})}$ Input leakage current <sup>(2)</sup>                 |                                                         |        |               | 0.3   | $\mu\text{A}$      |

(1) Full-scale reference

(2) Specified by design. Not tested in production.

## 6.12 ADC (Temperature and Voltage Measurements)

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $2.4\text{ V} < \text{REG25} < 2.6\text{ V}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$  and  $\text{REG25} = 2.5\text{ V}$  (unless otherwise noted)

| PARAMETER             |                                                | TEST CONDITIONS                   | MIN                     | TYP | MAX                | UNIT |
|-----------------------|------------------------------------------------|-----------------------------------|-------------------------|-----|--------------------|------|
| V <sub>IN(BAT)</sub>  | BAT Input range                                |                                   | V <sub>SS</sub> – 0.125 |     | 5                  | V    |
| V <sub>IN(TSAT)</sub> | TS Input range                                 |                                   | V <sub>SS</sub> – 0.125 |     | V <sub>REG25</sub> | V    |
| t <sub>SR_CONV</sub>  | Conversion time                                | Single conversion                 |                         | 125 |                    | ms   |
|                       | Resolution                                     |                                   | 14                      |     | 15                 | bits |
| V <sub>OS(SR)</sub>   | Input offset                                   |                                   |                         | 1   |                    | μV   |
| Z <sub>ADC1</sub>     | Effective input resistance(TS) <sup>(1)</sup>  | With internal pull-down activated | 5                       |     |                    | kΩ   |
| Z <sub>ADC2</sub>     | Effective input resistance(BAT) <sup>(1)</sup> | When not measuring                | 8                       |     |                    | MΩ   |
|                       |                                                | During measurement                | 100                     |     |                    | kΩ   |
| I <sub>LKG(ADC)</sub> | Input leakage current <sup>(1)</sup>           |                                   |                         |     | 0.3                | μA   |

(1) Specified by design. Not tested in production.

## 6.13 Data Flash Memory

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $2.4\text{ V} < \text{REG25} < 2.6\text{ V}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$  and  $\text{REG25} = 2.5\text{ V}$  (unless otherwise noted)

| PARAMETER             | TEST CONDITIONS                               | MIN    | TYP | MAX | UNIT   |
|-----------------------|-----------------------------------------------|--------|-----|-----|--------|
| t <sub>DR</sub>       | Data retention <sup>(1)</sup>                 | 10     |     |     | Years  |
|                       | Flash-programming write cycles <sup>(1)</sup> | 20,000 |     |     | Cycles |
| t <sub>WORDPROG</sub> | Word programming time <sup>(1)</sup>          |        |     |     | 2ms    |
| I <sub>CCPROG</sub>   | Flash-write supply current <sup>(1)</sup>     | 510    |     |     | mA     |

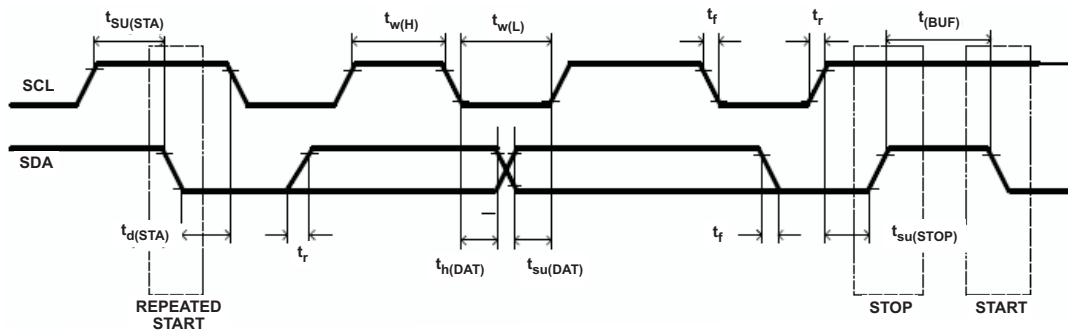
(1) Specified by design. Not tested in production.

## 6.14 I<sup>2</sup>C-Compatible Interface Timing Characteristics

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ,  $2.45\text{ V} < V_{\text{REGIN}} = V_{\text{BAT}} < 5.5\text{ V}$ ; Typical Values at  $T_A = 25^{\circ}\text{C}$  and  $V_{\text{BAT}} = 3.6\text{ V}$  (unless otherwise noted)

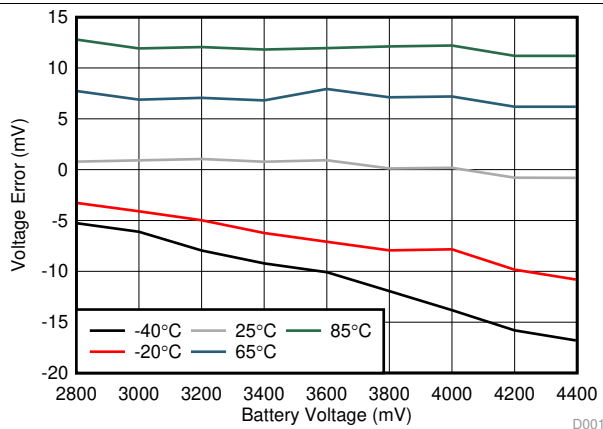
|                       |                                      | MIN | NOM | MAX | UNIT |
|-----------------------|--------------------------------------|-----|-----|-----|------|
| t <sub>R</sub>        | SCL/SDA rise time                    |     |     | 300 | ns   |
| t <sub>F</sub>        | SCL/SDA fall time                    |     |     | 300 | ns   |
| t <sub>W(H)</sub>     | SCL pulse width (high)               | 600 |     |     | ns   |
| t <sub>W(L)</sub>     | SCL pulse width (low)                | 1.3 |     |     | μs   |
| t <sub>SU(STA)</sub>  | Setup for repeated start             | 600 |     |     | ns   |
| t <sub>d(STA)</sub>   | Start to first falling edge of SCL   | 600 |     |     | ns   |
| t <sub>SU(DAT)</sub>  | Data setup time                      | 100 |     |     | ns   |
| t <sub>h(DAT)</sub>   | Data hold time                       | 0   |     |     | ns   |
| t <sub>SU(STOP)</sub> | Setup time for stop                  | 600 |     |     | ns   |
| t <sub>BUF</sub>      | Bus free time between stop and start | 66  |     |     | μs   |
| f <sub>SCL</sub>      | Clock frequency                      |     |     | 400 | kHz  |



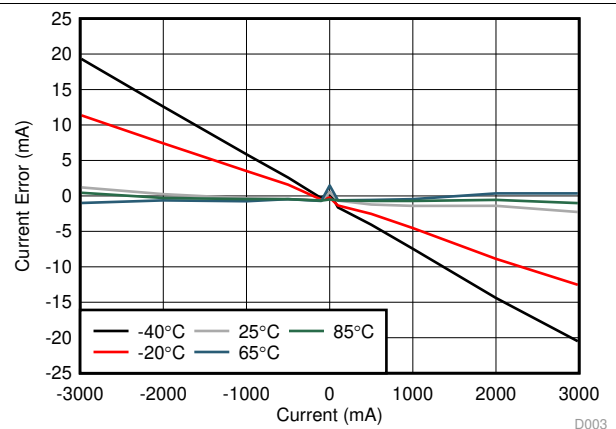


**Figure 1. I²C-Compatible Interface Timing Diagrams**

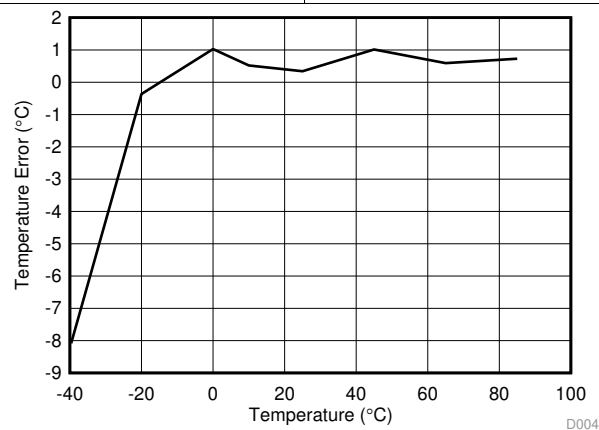
## 6.15 Typical Characteristics



**Figure 2.  $V_{(Err)}$  Across  $V_{IN}$  (0 mA)**



**Figure 3.  $I_{(Err)}$**



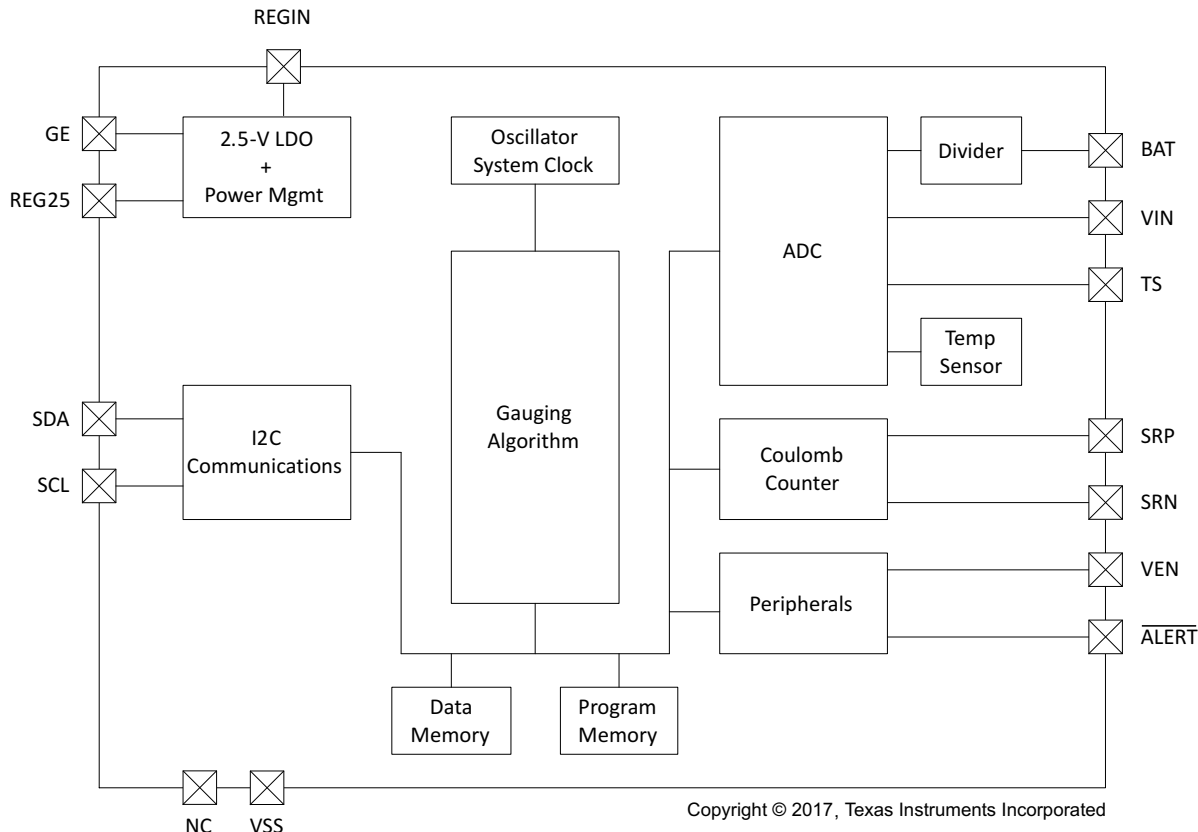
**Figure 4.  $T_{(Err)}$**

## 7 Detailed Description

### 7.1 Overview

The BQ35100 Battery Fuel Gauge and End-Of-Service Monitor provides gas gauging for lithium thionyl chloride (Li-SOCl<sub>2</sub>) and lithium manganese dioxide (Li-MnO<sub>2</sub>) primary batteries without requiring any forced discharge of the battery. The lithium primary gas gauging function uses voltage, current, and temperature data to provide state-of-health (SOH) and end-of-service (EOS) data.

### 7.2 Functional Block Diagram



### 7.3 Feature Description

#### 7.3.1 Basic Measurement Systems

##### 7.3.1.1 Voltage

The device measures the **BAT** input using the integrated delta-sigma ADC, which is scaled by the internal translation network, through the ADC. The translation gain function is determined by a calibration process.

In systems where the battery voltage is greater than  $V_{IN(BAT) \text{ MAX}}$  (for example, 2-series cell or more), then an external voltage scaling circuit is required. The firmware then scales this  $<1 \text{ V}$  value to reflect an average cell value and then again by the number of series cells to reflect the full battery voltage value.

##### 7.3.1.2 Temperature

The device can measure temperature through an integrated temperature sensor or an external NTC thermistor using the integrated delta-sigma ADC. Only one source can be used and the selection is made by setting **Operation Config A [TEMPS]** appropriately. The resulting measured temperature is available through the `Temperature()` command. The internal temperature sensor result is also available through the `InternalTemperature()` command.

## Feature Description (continued)

### 7.3.1.3 Coulombs

The integrating delta-sigma ADC (coulomb counter) in the device measures the discharge flow of the battery by measuring the voltage drop across a small-value sense resistor between the SRP and SRN pins.

The 15-bit integrating ADC measures bipolar signals from –0.125 V to 0.125 V. The device continuously monitors the measured current and integrates this value over time using an internal counter.

### 7.3.1.4 Current

For the primary battery current, the integrating delta-sigma ADC in the device measures the discharge current of the battery by measuring the voltage drop across a small-value sense resistor between the SRP and SRN pins, and is available through the *Current()* command.

The measured current also includes the current consumed by the device. To subtract this value from the reported current, a value programmed in ***EOS Gauge Load Current*** is subtracted for improved accuracy.

## 7.3.2 Battery Gauging

The BQ35100 device can operate in three distinct modes: ACCUMULATOR (ACC) mode, STATE-OF-HEALTH (SOH) mode, and END-OF-SERVICE (EOS) mode. The device can be configured and used for only one of these modes in the field, as it is not intended to be able to actively switch between modes when in normal use.

### 7.3.2.1 ACCUMULATOR (ACC) Mode

In this mode, the BQ35100 device measures and updates cell voltage, cell temperature, and load current every 1 s. This data is provided through the I<sup>2</sup>C interface while *ControlStatus()[GA]* is set. To begin accumulation, the *GAUGE\_START* command should be sent, and when accumulation ends, the *GAUGE\_STOP* command should be sent. To ensure that no data is lost, the host should wait until *G\_DONE* is set before powering down the device.

### 7.3.2.2 STATE-OF-HEALTH (SOH) Mode

This mode is suitable for determining SOH for lithium manganese dioxide (Li-MnO<sub>2</sub>) chemistry. In this mode, cell voltage and temperature are precisely measured immediately after the GE pin is asserted. The gauge uses this data to compute SOH. Once the initial update occurs and the host reads the updated SOH, then the device can be powered down.

#### 7.3.2.2.1 Low State-of-Health Alert

*BatteryStatus()[SOH\_LOW]* is set when *StateOfCharge()* is less than or equal to the value programmed in ***SOHLOW***.

### 7.3.2.3 END-OF-SERVICE (EOS) Mode

This mode is suitable for gauging lithium thionyl chloride (Li-SOCl<sub>2</sub>) cells. The end-of-service (EOS) gauging algorithm uses voltage, current, and temperature data to determine the resistance (R) and rate of change of resistance of the battery. The resistance data is then used to find Depth of Discharge (DOD) = DOD(R). As above, SOH is determined and in turn used to determine the EOS condition.

#### 7.3.2.3.1 Initial EOS Learning

For optimal accuracy, the first event where the device updates its impedance value is required to be when the battery is full (a fresh battery). If the battery is partially discharged, then the accuracy of the EOS detection is compromised.

When a new battery is inserted, then the *NEW\_BATTERY()* command should be sent to the device to ensure the initial learned resistance ***RNEW*** is refreshed correctly.

#### 7.3.2.3.1.1 End-Of-Service Detection

The BQ35100 device can detect when a sharp increase in the trend of tracked impedance occurs, indicating that the battery is reaching its EOS condition.

## Feature Description (continued)

### 7.3.3 Power Control

The BQ35100 device only has one active power mode that is enabled through the GAUGE ENABLE (GE) pin. The power consumption of the BQ35100 device can change significantly based on host commands it receives and its default configuration, specifically with respect to data flash updates.

For information on how to configure the device to influence the average power consumption, see the *Power Control* section in the *BQ35100 Technical Reference Manual* ([SLUUBH1](#)).

### 7.3.4 Battery Condition Warnings

#### 7.3.4.1 Battery Low Warning

The BQ35100 device can indicate and optionally trigger the  $\overline{\text{ALERT}}$  pin when the primary battery voltage falls below a programmable threshold.

#### 7.3.4.2 Temperature Low Warning

The BQ35100 device can indicate and optionally trigger the  $\overline{\text{ALERT}}$  pin when the primary battery temperature falls below a programmable threshold.

#### 7.3.4.3 Temperature High Warning

The BQ35100 device can indicate and optionally trigger the  $\overline{\text{ALERT}}$  pin when the primary battery temperature rises above a programmable threshold.

#### 7.3.4.4 Battery Low SOH Warning

The BQ35100 device can indicate and optionally trigger the  $\overline{\text{ALERT}}$  pin when the primary battery state-of-health (SOH) falls below a programmable threshold.

#### 7.3.4.5 Battery EOS OCV BAD Warning

The device assumes that when GE is asserted the cell is at rest and uses the initialization voltage reading to determine the Open Circuit Voltage (OCV). If the cell were not fully relaxed at that point, then the voltage after the pulse could rise above the OCV. This causes an incorrect impedance to be calculated.

### 7.3.5 $\overline{\text{ALERT}}$ Signal

The  $\overline{\text{ALERT}}$  signal can be configured to be triggered by a variety of status conditions. When the **ALERT Configuration** bit is set AND the corresponding bit in *BatteryStatus()* or *ControlStatus()* is set, then the corresponding *BatteryAlert()* bit is set, triggering the  $\overline{\text{ALERT}}$  signal.

### 7.3.6 Lifetime Data Collection

The BQ35100 device can be enabled by writing to *Control()* 0x002E [*LT\_EN*] to gather data regarding the primary battery and store it to data flash.

The following data is collected in RAM and only written to DF when the host sends the *End* command to the device:

- Max and Min Cell Voltage
- Max and Min Discharge Current
- Max and Min Temperature

### 7.3.7 SHA-1 Authentication

As of March 2012, the latest revision is FIPS 180-4. SHA-1, or secure hash algorithm, is used to compute a condensed representation of a message or data also known as hash. For messages  $< 2^{64}$ , the SHA-1 algorithm produces a 160-bit output called a digest.

## Feature Description (continued)

In a SHA-1 one-way hash function, there is no known mathematical method of computing the input given, only the output. The specification of SHA-1, as defined by FIPS 180-4, states that the input consists of 512-bit blocks with a total input length less than  $2^{64}$  bits. Inputs that do not conform to integer multiples of 512-bit blocks are padded before any block is input to the hash function. The SHA-1 algorithm outputs the 160-bit digest.

The device generates a SHA-1 input block of 288 bits (total input = 160-bit message + 128-bit key). To complete the 512-bit block size requirement of the SHA-1 function, the device pads the key and message with a 1, followed by 159 0s, followed by the 64 bit value for 288 (000...001001000000), which conforms to the pad requirements specified by FIPS 180-4.

- <http://www.nist.gov/itl/>
- <http://csrc.nist.gov/publications/fips>
- [www.faqs.org/rfcs/rfc3174.html](http://www.faqs.org/rfcs/rfc3174.html)

## 7.3.8 Data Commands

### 7.3.8.1 Command Summary

**Table 1. Command Summary Table**

| Cmd         | Mode | Name                       | Format         | Size in Bytes | Min Value | Max Value | Default Value | Unit                        |
|-------------|------|----------------------------|----------------|---------------|-----------|-----------|---------------|-----------------------------|
| 0x00...0x01 | R/W  | <i>Control</i>             | Hex            | 2             | 0x00      | 0xff      | —             | —                           |
| 0x02...0x05 | R    | <i>AccumulatedCapacity</i> | Integer        | 4             | 0         | 4.29e9    | —             | μAh                         |
| 0x06...0x07 | R    | <i>Temperature</i>         | Signed Int     | 2             | –32768    | 32767     | —             | 0.1 K                       |
| 0x08...0x09 | R    | <i>Voltage</i>             | Integer        | 2             | 0         | 65535     | —             | mV                          |
| 0x0A        | R    | <i>BatteryStatus</i>       | Hex            | 1             | 0x00      | 0xff      | —             | —                           |
| 0x0B        | R    | <i>BatteryAlert</i>        | Hex            | 1             | 0x00      | 0xff      | —             | —                           |
| 0x0C...0x0D | R    | <i>Current</i>             | Signed Integer | 2             | –32768    | 32767     | —             | mA                          |
| 0x16...0x17 | R    | <i>Scaled R</i>            | Integer        | 2             | 0         | 65535     | —             | mΩ                          |
| 0x22...0x23 | R    | <i>Measured Z</i>          | Integer        | 2             | 0         | 65535     | —             | mΩ                          |
| 0x28...0x29 | R    | <i>InternalTemperature</i> | Signed Integer | 2             | –32768    | 32767     | —             | 0.1 K                       |
| 0x2E...0x2F | R    | <i>StateOfHealth</i>       | Integer        | 1             | 0         | 100       | —             | %                           |
| 0x3C...0x3D | R    | <i>DesignCapacity</i>      | Integer        | 2             | 0         | 65535     | —             | mAh                         |
| 0x79        | R    | <i>Cal_Count</i>           | Hex            | 1             | 0x00      | 0xff      | —             | —                           |
| 0x7a...0x7B | R    | <i>Cal_Current</i>         | Signed Int     | 2             | 0         | 65535     | —             | mA                          |
| 0x7C...0x7D | R    | <i>Cal_Voltage</i>         | Integer        | 2             | 0         | 65535     | —             | mV or Counts <sup>(1)</sup> |
| 0x7E...0x7F | R    | <i>Cal_Temperature</i>     | Integer        | 2             | 0         | 65535     | —             | K                           |

(1) mV when [EXTVCELL] = 0, and ADC counts when [EXTVCELL] = 1.

### 7.3.8.2 0x00, 0x01 AltManufacturerAccess() and 0x3E, 0x3F AltManufacturerAccess()

*AltManufacturerAccess()* provides a method of reading and writing data in the Manufacturer Access System (MAC). The MAC command is sent via *AltManufacturerAccess()* by a block protocol. The result is returned on *AltManufacturerAccess()* via a block read.

Commands are set by writing to registers 0x00/0x01. On a valid word access, the MAC command state is set, and commands 0x3E and 0x3F are used for MAC commands. These new addresses work the same as 0x00 and 0x01, but are primarily intended for block writes and reads.

### 7.3.8.3 Control(): 0x00/0x01

Issuing a *Control()* command requires a subsequent two-byte subcommand. These additional bytes specify the particular control function desired. The *Control()* command allows the host to control specific features of the device during normal operation, and additional features when the BQ35100 device is in different access modes, as described in [Table 2](#).

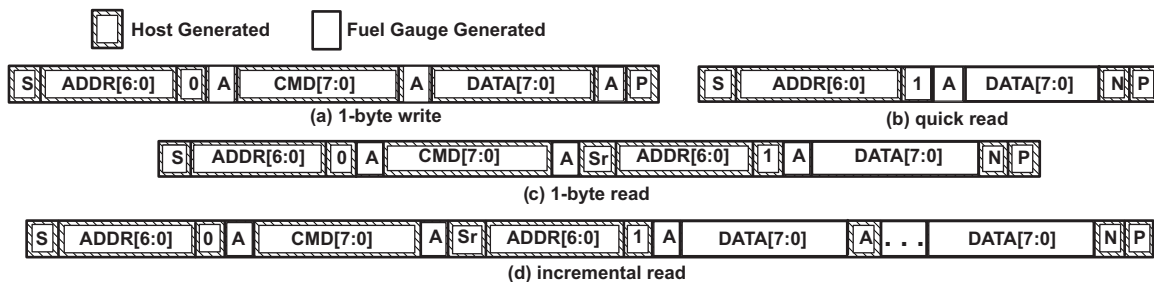
Table 2. Control Functions

| CNTL FUNCTION      | CNTL DATA | SEALED ACCESS | DESCRIPTION                                                                                     |
|--------------------|-----------|---------------|-------------------------------------------------------------------------------------------------|
| CONTROL_STATUS     | 0x0000    | Yes           | Reports the status of key features                                                              |
| DEVICE_TYPE        | 0x0001    | Yes           | Reports the device type of 0x40 (indicating BQ35100)                                            |
| FW_VERSION         | 0x0002    | Yes           | Reports the firmware version on the device type                                                 |
| HW_VERSION         | 0x0003    | Yes           | Reports the hardware version of the device type                                                 |
| STATIC_CHEM_CHKSUM | 0x0005    | Yes           | Calculates chemistry checksum                                                                   |
| CHEM_ID            | 0x0006    | Yes           | Reports the chemical identifier used by the gas gauge algorithms                                |
| PREV_MACWRITE      | 0x0007    | Yes           | Returns previous <i>Control()</i> command code                                                  |
| BOARD_OFFSET       | 0x0009    | Yes           | Forces the device to measure and store the board offset                                         |
| CC_OFFSET          | 0x000A    | Yes           | Forces the device to measure the internal CC offset                                             |
| CC_OFFSET_SAVE     | 0x000B    | Yes           | Forces the device to store the internal CC offset                                               |
| DF_VERSION         | 0x000C    | Yes           | Reports the data flash version on the device                                                    |
| GAUGE_START        | 0x0011    | Yes           | Triggers the device to enter ACTIVE mode                                                        |
| GAUGE_STOP         | 0x0012    | Yes           | Triggers the device to stop gauging and complete all outstanding tasks                          |
| SELAED             | 0x0020    | No            | Places the device in SEALED access mode                                                         |
| CAL_ENABLE         | 0x002D    | No            | Toggle CALIBRATION mode enable                                                                  |
| LT_ENABLE          | 0x002E    | No            | Enables Lifetime Data collection                                                                |
| RESET              | 0x0041    | No            | Forces a full reset of the device                                                               |
| EXIT_CAL           | 0x0080    | No            | Exit CALIBRATION mode                                                                           |
| ENTER_CAL          | 0x0081    | No            | Enter CALIBRATION mode                                                                          |
| NEW_BATTERY        | 0xa613    | Yes           | This is used to refresh the gauge when a new battery is installed and resets all recorded data. |

## 7.3.9 Communications

### 7.3.9.1 I<sup>2</sup>C Interface

The gas gauge supports the standard I<sup>2</sup>C read, incremental read, one-byte write quick read, and functions. The 7-bit device address (ADDR) is the most significant 7 bits of the hex address and is fixed as 1010101. The 8-bit device address is therefore 0xAA or 0xAB for write or read, respectively.



**Figure 5. Supported I<sup>2</sup>C Formats: (a) 1-Byte Write, (b) Quick Read, (c) 1 Byte-read, and (d) Incremental Read (S = Start, Sr = Repeated Start, A = Acknowledge, N = No Acknowledge, and P = Stop).**

The “quick read” returns data at the address indicated by the address pointer. The address pointer, a register internal to the I<sup>2</sup>C communication engine, increments whenever data is acknowledged by the device or the I<sup>2</sup>C master. “Quick writes” function in the same manner and are a convenient means of sending multiple bytes to consecutive command locations (such as 2-byte commands that require two bytes of data).

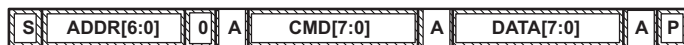


Figure 6. Attempt To Write a Read-Only Address (Nack After Data Sent By Master)

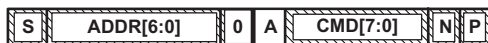


Figure 7. Attempt To Read an Address Above 0x7F (Nack Command)



Figure 8. Attempt at Incremental Writes (Nack All Extra Data Bytes Sent)

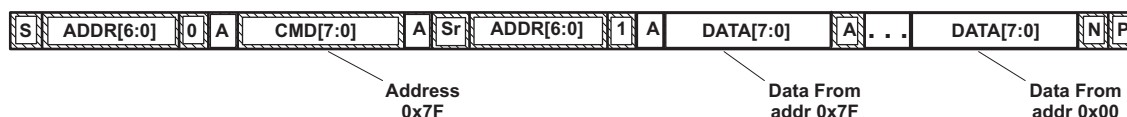


Figure 9. Incremental Read at the Maximum Allowed Read Address

The I<sup>2</sup>C engine releases both SDA and SCL if the I<sup>2</sup>C bus is held low for **Bus Low Time**. If the gas gauge were holding the lines, releasing them frees the master to drive the lines. If an external condition is holding either of the lines low, the I<sup>2</sup>C engine enters the low-power SLEEP mode.

## 7.4 Device Functional Modes

The BQ35100 device is intended for systems where the battery electronics are required to consume a very low average current. To achieve this, the device is intended to be fully powered off when not required through control of the GAUGE ENABLE (GE) pin. When this pin is low, then the device is fully powered down with no measurements being made and no data, unless in flash, is retained.

An example system current profile is shown along with the state of GAUGE ENABLE to reduce the average power consumption of the battery electronics.

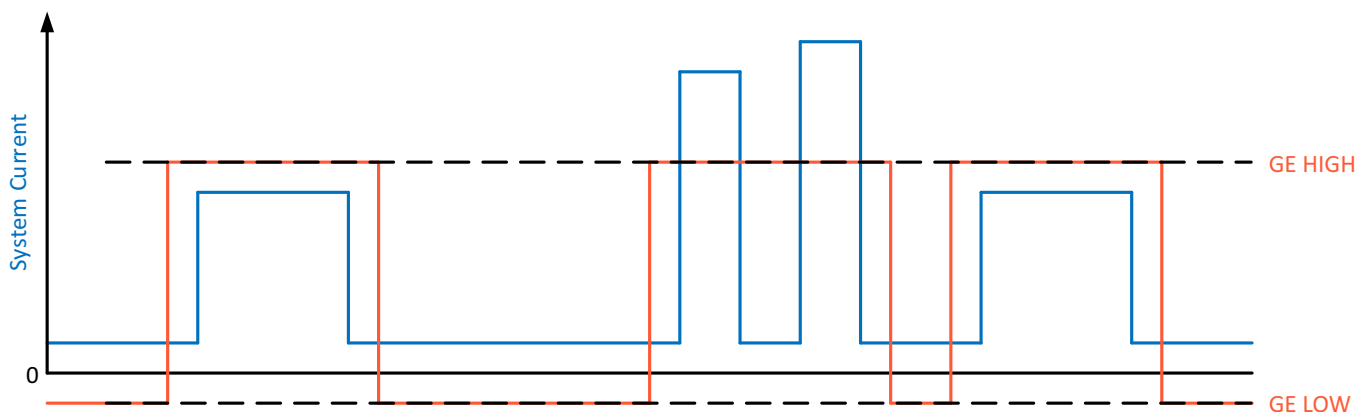


Figure 10. Power Consumption

The average power consumption of the BQ35100 device is an average of the periods where GAUGE ENABLE is high AND low over a given period.

For example, if the system enters a high power state (500  $\mu$ A) for 30 s every 4 hours, the average current will be:  
 $315 \mu\text{A} \times 30 \text{ s} / 4 \text{ h} = 0.66 \mu\text{A}$

## Device Functional Modes (continued)

When GAUGE ENABLE is low (GE = Low), then the device is powered off and the current is nominally  $I_{CC\_GELOW}$ , and is the leakage current into the REGIN pin. Other components connected to this node should also be evaluated to determine the "System Off" current total.

When the device is used for gas gauging, it transitions through several power states based on the selection of **OperationCfgA[GMSEL]**.

Figure 11 highlights the operational flow and conditional decisions.

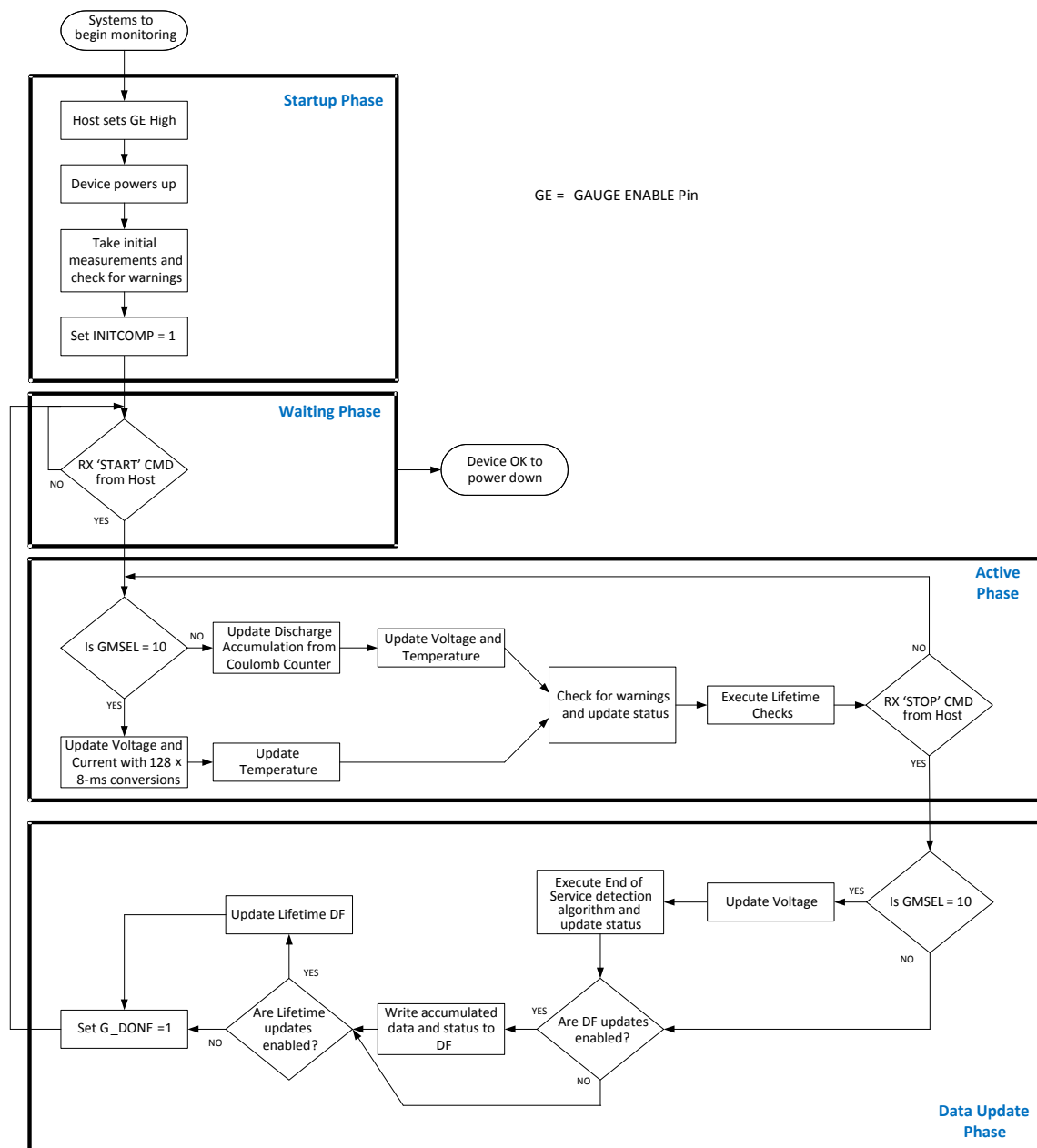


Figure 11. Operational Flow



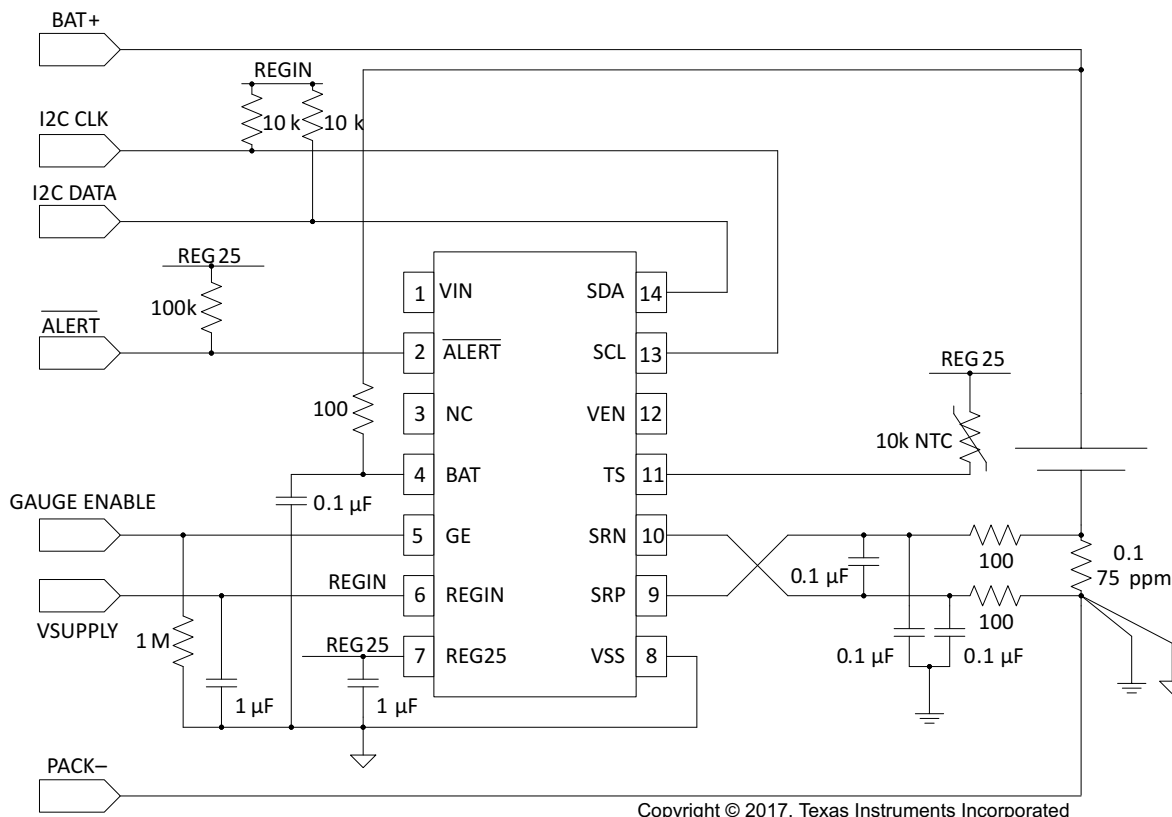
## NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

The BQ35100 device is a highly configurable device with many options. The major configuration choices comprise the battery chemistry and control methods.

## 8.2 Typical Applications

Figure 12 is a simplified diagram of the main features of the BQ35100 device. Specific implementations detailing the main configuration options are shown later in this section.



### Figure 12. BQ35100 Single-Cell Simplified Implementation

## Typical Applications (continued)

### 8.2.1 Design Requirements

For design guidelines, refer to the *BQ35100 EVM User's Guide* (SLUUBH7).

### 8.2.2 Detailed Design Procedure

#### 8.2.2.1 Preparation for Gauging

Before it is ready to gauge a lithium primary battery, a BQ35100 device-based circuit requires several steps, as follows:

1. Provide power to the device via a supply to the BAT pin that is above  $V_{\text{REGIN}}$ , 2.7 V.
2. Power up the device by pulling the GE pin to a supply above  $V_{\text{IH(GE)}}$ , 2.65 V.
3. Use [BQStudio](#) to calibrate the device. The device is calibrated when in ACC Mode (GMSEL = 0x0), which is also the state the device is shipped from TI. The BQ35100 EVM User Guide details the BQStudio software and Calibration Tab operation.
4. Use BQStudio to update the CHEM ID. The **Chemistry Tab** enables the selection and programming of the appropriate CHEM ID for the cell being used.
5. Reset the device once the calibration and CHEM ID programming are complete. To do this, toggle the GE pin Low and then back High or via the **Reset** command in BQStudio.

With these steps complete the next phase of configuration and use is determined by which Gauging Mode is intended to be used.

#### 8.2.2.2 Gauging Mode Selection

The BQ35100 device can be configured to support lithium manganese dioxide (Li-MnO<sub>2</sub>) or lithium thionyl chloride (Li-SOCl<sub>2</sub>) cells, and can also be configured to support any chemistry through the ACCUMULATOR mode. To select the GAUGING mode, set the **GMSEL[1:0]** bits in **Operation Config A** register.

**Table 3. Chemistry**

| Chemistry Supported                              | Gauging Mode                               | Operation Config A [GMSEL] |
|--------------------------------------------------|--------------------------------------------|----------------------------|
| All Chemistries                                  | ACCUMULATOR                                | 0x0                        |
| Lithium Manganese Dioxide (Li-MnO <sub>2</sub> ) | STATE-OF-HEALTH<br>(Voltage Correlation)   | 0x1                        |
| Lithium Thionyl Chloride (Li-SOCl <sub>2</sub> ) | END-OF-SERVICE<br>(Resistance Correlation) | 0x2                        |

#### NOTE

During operation in the field, the BQ35100 fuel gauge should be used in only one mode at a time, and should not be switched between modes.

##### 8.2.2.2.1 ACCUMULATOR Mode

The ACCUMULATOR mode (ACC) is chemistry-independent and accumulates the passed discharge of the battery when the gauge is enabled, but also provides no gas gauging data, such as remaining state-of-health (RSOC), full charge capacity (FCC), or end-of-service (EOS) indication. This is the default configuration as it is also the required mode for the device when it is calibrated. Once calibration is completed, the device can be set to the appropriate gauging mode or left in the default mode.

To configure the BQ35100 fuel gauge to use the ACCUMULATOR mode, the following data flash configuration variables must be configured correctly. For more details, including information on **Operation Config A [GMSEL]**, see the *BQ35100 Technical Reference Manual* (SLUUBH1).

To use ACCUMULATOR mode, follow these steps:

1. Step 1: Set GE high to power up the BQ35100 gauge and wait for  $\overline{\text{ALERT}}$  to go low due to **INITCOMP** = 1.
2. Step 2: Clear  $\overline{\text{ALERT}}$  (read *BatteryStatus()*) and send *GAUGE\_START()*.
3. Step 3: Read *AccumulatedCapacity()* for the latest passed discharge data since *GAUGE\_START()*.

4. Step 4: Send `GAUGE_STOP()` and wait for  $\overline{\text{ALERT}}$  to go low due to **G\_DONE** = 1.
5. Step 5: Read final `AccumulatedCapacity()` value.
6. Step 6: Set GE low to power down the BQ35100 device.

#### 8.2.2.2.1.1 STATE-OF-HEALTH (Voltage Correlation) Mode

STATE-OF-HEALTH mode is typically used with lithium manganese dioxide (Li-MnO<sub>2</sub>) cells as the voltage vs. state-of-health (SOH) profile has a defined slope to enable accuracy.

To configure the BQ35100 gauge to use the STATE-OF-HEALTH mode, the following data flash configuration variables must be configured correctly. For more details, including information on **Operation Config A [GMSEL]**, see the *BQ35100 Technical Reference Manual (SLUUBH1)*.

To use STATE-OF-HEALTH mode, follow these steps:

1. Step 1: Set GE high to power up the BQ35100 gauge and wait for  $\overline{\text{ALERT}}$  to go low due to **INITCOMP** = 1.
2. Step 2: Clear  $\overline{\text{ALERT}}$  (read `BatteryStatus()`).
3. Step 3: Read any required data such as `State-Of-Health()` for the latest battery data.
4. Step 4: Optional: Send `GAUGE_START()`.
5. Step 5: Optional: Send `GAUGE_STOP()`. At this point, Lifetime Data can be stored and any Threshold detection checks are run. This is only needed if these features are desired.
6. Step 6: Set GE low to power down the BQ35100 device.

#### 8.2.2.2.1.2 END-OF-SERVICE (Resistance Correlation) Mode

END-OF-SERVICE mode is only used with lithium thionyl chloride (Li-SOCl<sub>2</sub>) cells. To configure the BQ35100 device to use END-OF-SERVICE mode, the following data flash configuration variables must be configured correctly. For more details, including information on **Operation Config A [GMSEL]**, **R Data Seconds**, see the *BQ35100 Technical Reference Manual (SLUUBH1)*.

To use END-OF-SERVICE mode, follow these steps:

1. Step 1: Set GE high to power up the BQ35100 device and wait for  $\overline{\text{ALERT}}$  to go low due to **INITCOMP** = 1.
2. Step 2: Clear  $\overline{\text{ALERT}}$  (read `BatteryStatus()`).
3. Step 3: Send `GAUGE_START()` 1 s prior to the high load pulse starting.
4. Step 4: Send `GAUGE_STOP()` directly after the high load pulse has stopped. During the time between Step 4 and Step 5 there should be no other pulse load. A low current DC load is acceptable.
5. Step 5: Wait for  $\overline{\text{ALERT}}$  to go low due to **G\_DONE** = 1.
6. Step 6: Read `BatteryStatus()` for an **[EOS]** decision and other data, such as `State-Of-Health()`.
7. Step 7: Set GE low to power down the BQ35100 device.

#### 8.2.2.3 Voltage Measurement Selection

The default configuration is for the BQ35100 device to support 1-series cell with a maximum of 4.5 V. If the battery voltage can be above this level, then **[EXTVCELL]** in **Operation Config A** should be set. In this setting, an external resistor divider is used to scale the voltage so the gauge can measure accurately.

#### 8.2.2.4 Temperature Measurement Selection

There are three options for temperature measurement in the BQ35100 device. By default, the device is configured to use an external 103AT NTC thermistor. However, if **[TEMPS]** = 0, then an internal temperature sensor is used. This requires no external components but for optimal performance in this case, the BQ35100 device should be very close to the cell, preferably thermally connected.

There is one other option that can be used if the system already includes a cell temperature measurement solution: If **WRTEMP** = 1, then the host can write the temperature to the device and the BQ35100 algorithms will use that data.

### 8.2.2.5 Current Sense Resistor Selection

The BQ35100 device calculates current through measuring a voltage across a small resistor in series with the battery. The default value is 100 mΩ. To maximize current measurement accuracy, the ideal value is calculated as:

$$R_{\text{SENSE}} \text{ (m}\Omega\text{)} = V_{\text{(SR)Max}} / \text{Peak Load Current (mA)}$$

Where  $V_{\text{(SR) MAX}} = 125 \text{ mV}$

### 8.2.2.6 Expected Device Usage Profiles

The BQ35100 device is designed to work in a system where there is a period discharge pulse of at least 10 s of mA for 10 s of ms. In ACC mode, any pulse can be measured based on the information the host requires. However, in EOS modes, the battery condition does not change very fast so only pulses that are many hours apart; for example, 24 hours, are needed.

If the time between pulses needing monitoring is less than a minute, then it is recommended not to power down the device. However, if the period is greater than 5 hours, then powering down the device between pulses is expected. Periods in between risk not allowing the battery to rest and any EOS-related data may be compromised. [Battery EOS OCV BAD Warning](#) provides more information on this.

The shorter the period between pulses has a large effect of the overall cumulative power consumption of the battery electronics. See [Device Functional Modes](#) for more details on average power consumption.

### 8.2.2.7 Using the BQ35100 Fuel Gauge with a Battery and Capacitor in Parallel

The BQ35100 device can be used in systems where the lithium primary battery is permanently connected to a bulk capacitor in parallel; for example, an electrolytic or super capacitor.

#### 8.2.2.7.1 ACCUMULATOR Mode

In this mode, the BQ35100 device does not count the leakage of the capacitor, and so the leakage should be added to the data the BQ35100 device counts.

#### 8.2.2.7.2 STATE-OF-HEALTH Mode

In this mode, as the voltage of the capacitor will match that of the battery, there is no impact to the accuracy of the device's gauging performance with the capacitor in the system.

#### 8.2.2.7.3 END-OF-SERVICE Mode

In this mode, the resistance of the capacitor will influence the end-of-service determination, but this does not impact the accuracy as the overall power delivery to the system is determined by the total resistance of the combined battery and capacitor. However, for the resistance to be updated to support the end-of-service feature, there needs to be a large enough delta in voltage between the open circuit voltage and the voltage under load. As the battery is discharged, the resistance increases and so the resistance at a state of charge of < 50% is the most important so that the accuracy will be optimized as the battery is in the second half of its service life.

The minimum delta voltage should be 100 mV to ensure there is no impact to the accuracy; therefore, the high load pulse current when the gauge is active should be:

High Load Pulse Current (mA) = 100 mV / Resistance of the battery and capacitor in parallel at 50% SOC.

### 8.2.3 EOS Mode Load Pulse Synchronization

For correct data updates in EOS mode, the device operation needs to be synchronized with the pulsed load on the battery. Typically, this is managed by the system host MCU, but additionally it can be managed by an external detection circuit. An example of this alternative approach is detailed in *TI Designs: TIDA-01546: Battery and System Health Monitoring of Battery Powered Smart Flow Meters Reference Design (TIDUD05)*.

### 8.2.4 Benefits of the BQ35100 Gauge Compared to Alternative Monitoring Techniques

The BQ35100 gauge offers many capabilities and provides a level of accuracy that alternative monitoring techniques cannot offer. One of the main techniques is to use a voltage lookup table implemented with an MCU and integrated ADC.

Table 4. BQ35100 Compared to MCU + ADC

| Operation                                                                                                                                                                                              | Advantages                                                                                                                                                                                                                                                                                                                                                   | Disadvantages                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Characterize the cells' performance under the expected load condition to create a voltage versus SOH table to measure voltage and temperature and compare the measurements to the characterized table. | <ul style="list-style-type: none"> <li>Easy to implement</li> <li>Accounts for early cell degradation</li> <li>Most system host microcontrollers have a spare ADC channel.</li> <li>Only uses a small amount of memory and CPU operation.</li> <li>The table can be updated if the system load configuration is changed (for example, FW Update).</li> </ul> | <ul style="list-style-type: none"> <li>No simple accounting for cell-to-cell or temperature variation</li> <li>No simple accounting for installation variations, such as radio power due to transmit distances</li> <li>Assumptions and tolerances must be built into the original cell capacity, forcing a much larger, more expensive cell to be used.</li> <li>Cell voltage is very flat so a small voltage measurement error is a very large capacity error. <ul style="list-style-type: none"> <li>LiSoCl<sub>2</sub>: 95% of SOC is 100 mV of voltage.</li> <li>A typical MCU ADC of 10-bit resolution has only seven bits of accurate performance, providing a 36-mV resolution.</li> </ul> </li> </ul> |

In summary, the voltage measurement performance of the measurement system is critical to this technique and that is typically not available from the host MCU.

## 8.2.5 Application Curves

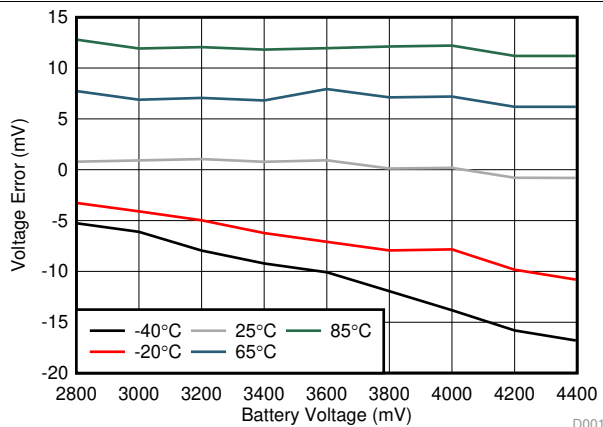


Figure 13.  $V_{(Err)}$  Across VIN (0 mA)

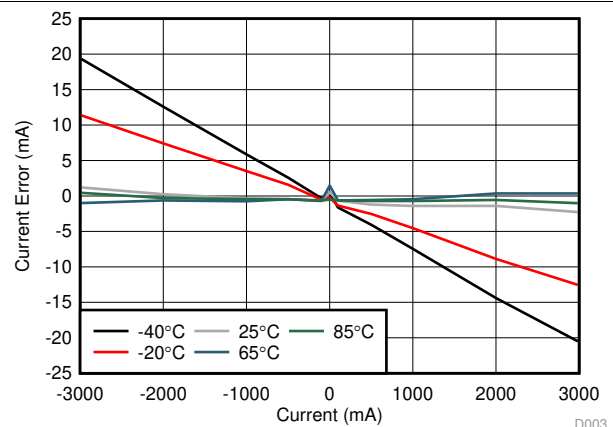


Figure 14.  $I_{(Err)}$

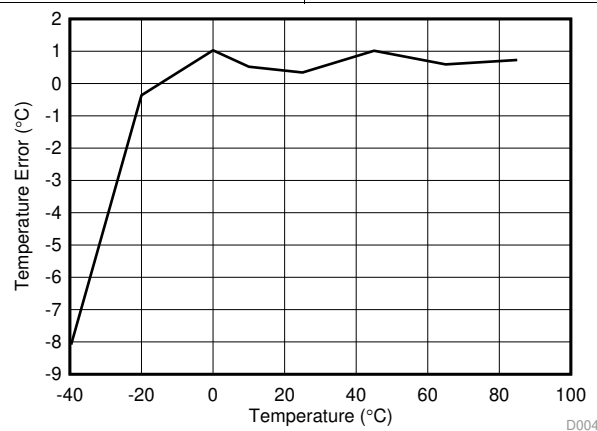


Figure 15.  $T_{(Err)}$

## 9 Power Supply Recommendations

Power supply requirements for the BQ35100 device are simplified due to the presence of the internal LDO voltage regulation. The REGIN pin accepts any voltage level between 2.7 V and 4.5 V, which is optimum for single-cell Li-primary applications.

Decoupling the REGIN pin should be done with a 0.1-μF 10% ceramic X5R capacitor placed close to the device.

REGIN can be powered from an alternate power source, such as, for example, the boost converter output, as long as it is not also connected to the BAT input. In this case, BAT should only remain connected to the top of the cell.

## 10 Layout

### 10.1 Layout Guidelines

#### 10.1.1 Introduction

Attention to layout is critical to the success of any battery management circuit board. The mixture of high-current paths with an ultralow-current microcontroller creates the potential for design issues that are not always trivial to solve. Some of the key areas of concern are described in the following sections, and can help to enable success.

#### 10.1.2 Power Supply Decoupling Capacitor

Power supply decoupling from  $V_{\text{REG25}}$  to ground is important for optimal operation of the gas gauge. To keep the loop area small, place this capacitor next to the IC and use the shortest possible traces. A large loop area renders the capacitor useless and forms a small-loop antenna for noise pickup. Ideally, the traces on each side of the capacitor should be the same length and run in the same direction to avoid differential noise during ESD. If possible, place a via near the  $V_{\text{SS}}$  pin to a ground plane layer.

#### 10.1.3 Capacitors

Power supply decoupling for the gas gauge requires a pair of 0.1- $\mu\text{F}$  ceramic capacitors for (PBAT) and ( $V_{\text{REG25}}$ ) pins. These should be placed reasonably close to the IC without using long traces back to  $V_{\text{SS}}$ . The LDO voltage regulator, whether external or internal to the main IC, requires a 0.47- $\mu\text{F}$  ceramic capacitor to be placed fairly close to the regulation output pin. This capacitor is for amplifier loop stabilization and as an energy well for the 2.5-V supply.

#### 10.1.4 Communication Line Protection Components

The 5.6-V Zener diodes used to protect the communication pins of the gas gauge from ESD should be located as close as possible to the pack connector. The grounded end of these Zener diodes should be returned to the Pack(–) node rather than to the low-current digital ground system. This way, ESD is diverted away from the sensitive electronics as much as possible.

### 10.2 Layout Example

#### 10.2.1 Ground System

The fuel gauge requires a low-current ground system separate from the high-current PACK(–) path. ESD ground is defined along the high-current path from the Pack(–) terminal to the sense resistor. It is important that the low-current ground systems only connect to the PACK(–) path at the sense resistor Kelvin pick-off point. It is recommended to use an optional inner layer ground plane for the low-current ground system.

In [Figure 16](#), the green is an example of using the low-current ground as a shield for the gas gauge circuit. Note how it is kept separate from the high-current ground, which is shown in red. The high-current path is joined with the low-current path only at one point, shown with the small blue connection between the two planes.

## Layout Example (continued)

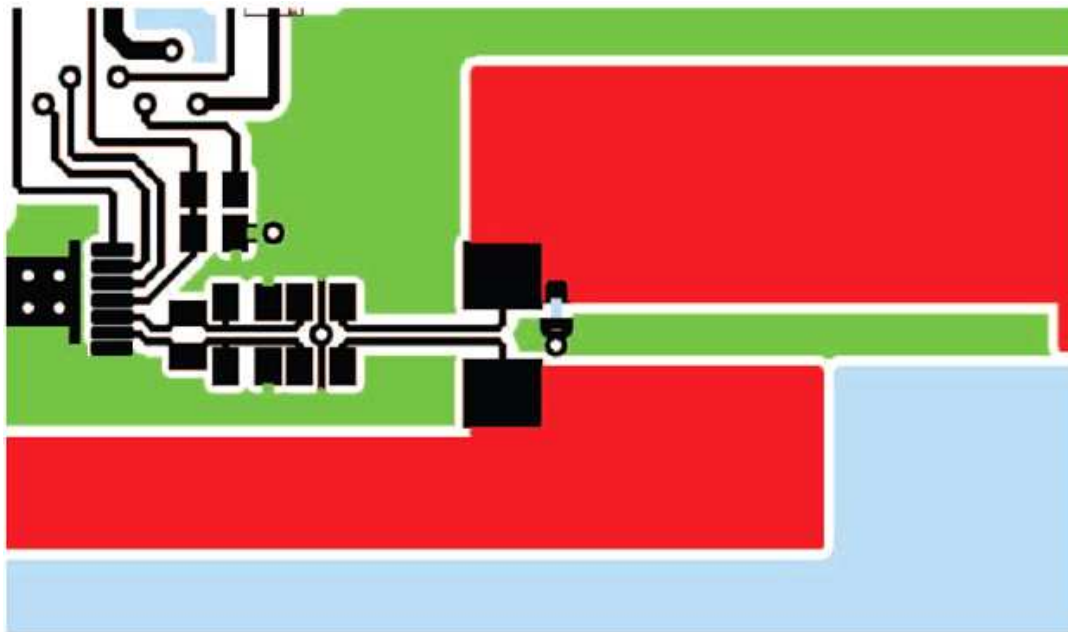


Figure 16. Differential Filter Component with Symmetrical Layout

### 10.2.2 Kelvin Connections

Kelvin voltage sensing is very important to accurately measure current and cell voltage. Note how the differential connections at the sense resistor do not add any voltage drop across the copper etch that carries the high current path through the sense resistor. See [Figure 16](#) and [Figure 17](#).

### 10.2.3 Board Offset Considerations

Although the most important component for board offset reduction is the decoupling capacitor for  $V_{REG25}$ , an additional benefit is possible by using this recommended pattern for the coulomb counter differential low-pass filter network. Maintain the symmetrical placement pattern shown for optimum current offset performance. Use symmetrical shielded differential traces, if possible, from the sense resistor to the 100- $\Omega$  resistors, as shown in [Figure 17](#).



## Layout Example (continued)

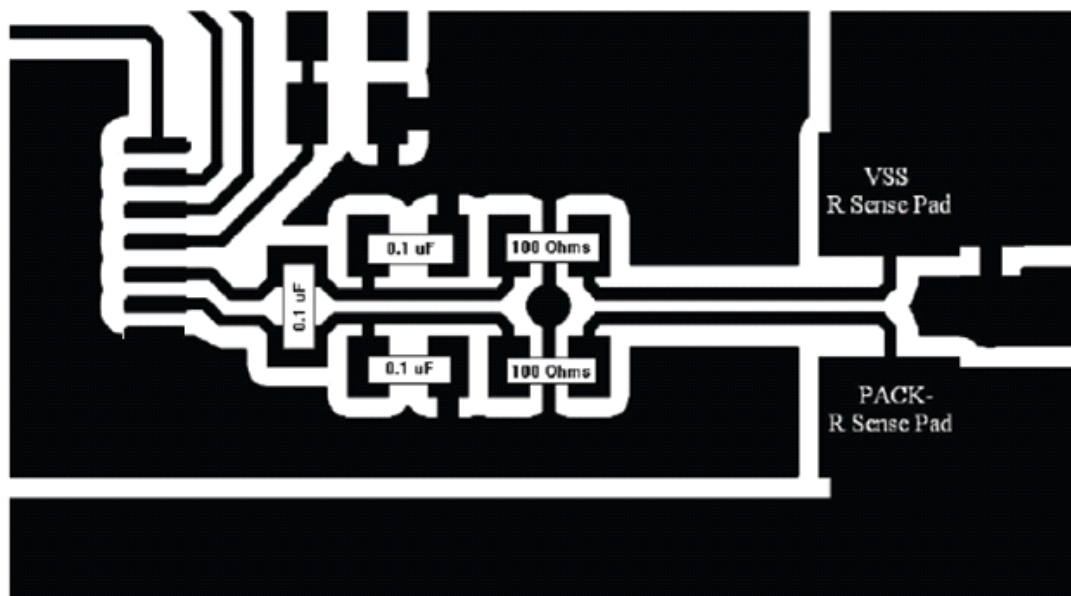


Figure 17. Differential Connection Between SRP and SRN Pins with Sense Resistor

## 10.3 ESD Spark Gap

Protect the communication lines from ESD with a spark gap at the connector. [Figure 18](#) shows the recommended pattern with its 0.2-mm spacing between the points.



Figure 18. Recommended Spark-Gap Pattern Helps Protect Communication Lines from ESD



## 11 器件和文档支持

### 11.1 文档支持

#### 11.1.1 相关文档

请参阅如下相关文档：

- 《BQ35100 技术参考手册》(SLUUBH1)
- 《BQ35100 EVM 用户指南》(SLUUBH7)
- 《使用 I<sup>2</sup>C 与 BQ275xx 系列电量监测计通信》应用报告(SLUA467)

### 11.2 接收文档更新通知

要接收文档更新通知，请导航至 [ti.com](http://ti.com) 上的器件产品文件夹。单击右上角的通知我进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查看任何已修订文档中包含的修订历史记录。

### 11.3 社区资源

下列链接提供到 TI 社区资源的连接。链接的内容由各个分销商“按照原样”提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的《使用条款》。

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ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

### 11.6 术语表

**SLYZ022** — TI 术语表。

这份术语表列出并解释术语、缩写和定义。

## 12 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更，恕不另行通知，且不会对此文档进行修订。如需获取此数据表的浏览器版本，请查阅左侧的导航栏。

## PACKAGING INFORMATION

| Orderable part number      | Status<br>(1) | Material type<br>(2) | Package   Pins  | Package qty   Carrier | RoHS<br>(3) | Lead finish/<br>Ball material<br>(4) | MSL rating/<br>Peak reflow<br>(5) | Op temp (°C) | Part marking<br>(6) |
|----------------------------|---------------|----------------------|-----------------|-----------------------|-------------|--------------------------------------|-----------------------------------|--------------|---------------------|
| <a href="#">BQ35100PW</a>  | Active        | Production           | TSSOP (PW)   14 | 90   TUBE             | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| BQ35100PW.A                | Active        | Production           | TSSOP (PW)   14 | 90   TUBE             | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| BQ35100PW.B                | Active        | Production           | TSSOP (PW)   14 | 90   TUBE             | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| BQ35100PWG4                | Active        | Production           | TSSOP (PW)   14 | 90   TUBE             | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| BQ35100PWG4.A              | Active        | Production           | TSSOP (PW)   14 | 90   TUBE             | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| BQ35100PWG4.B              | Active        | Production           | TSSOP (PW)   14 | 90   TUBE             | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| <a href="#">BQ35100PWR</a> | Active        | Production           | TSSOP (PW)   14 | 2000   LARGE T&R      | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| BQ35100PWR.A               | Active        | Production           | TSSOP (PW)   14 | 2000   LARGE T&R      | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |
| BQ35100PWR.B               | Active        | Production           | TSSOP (PW)   14 | 2000   LARGE T&R      | Yes         | NIPDAU                               | Level-2-260C-1 YEAR               | -40 to 85    | BQ35100             |

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

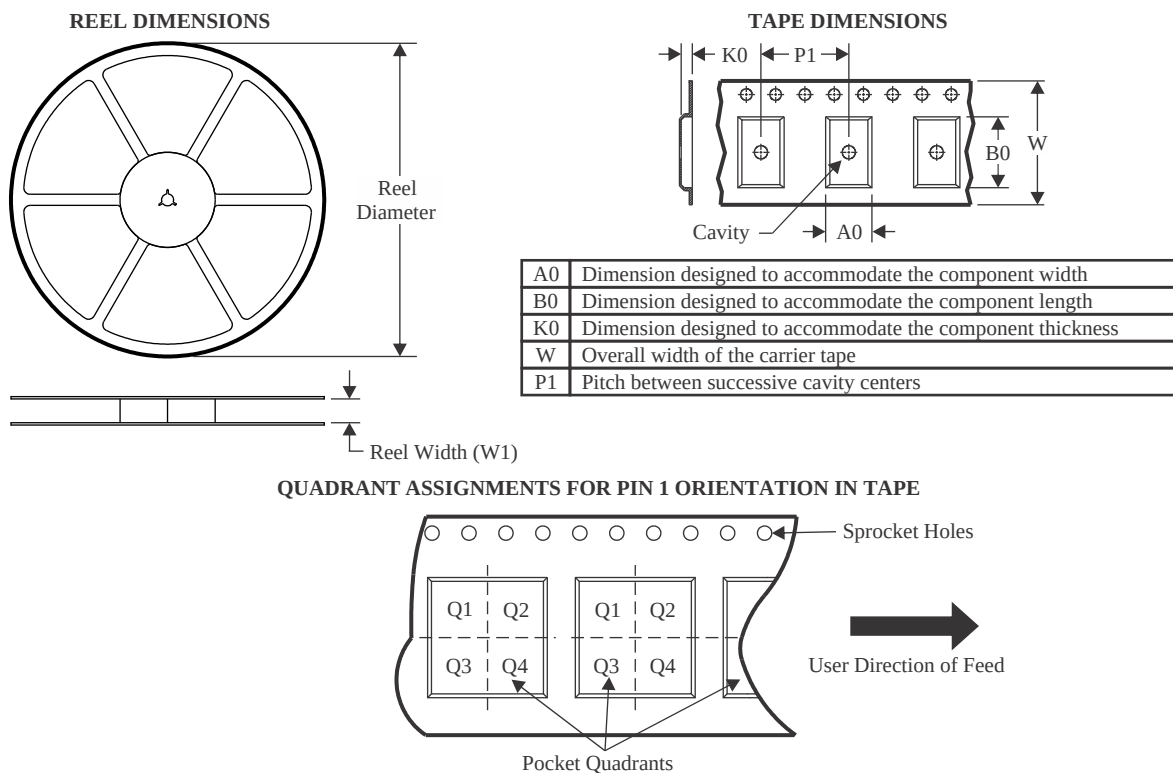
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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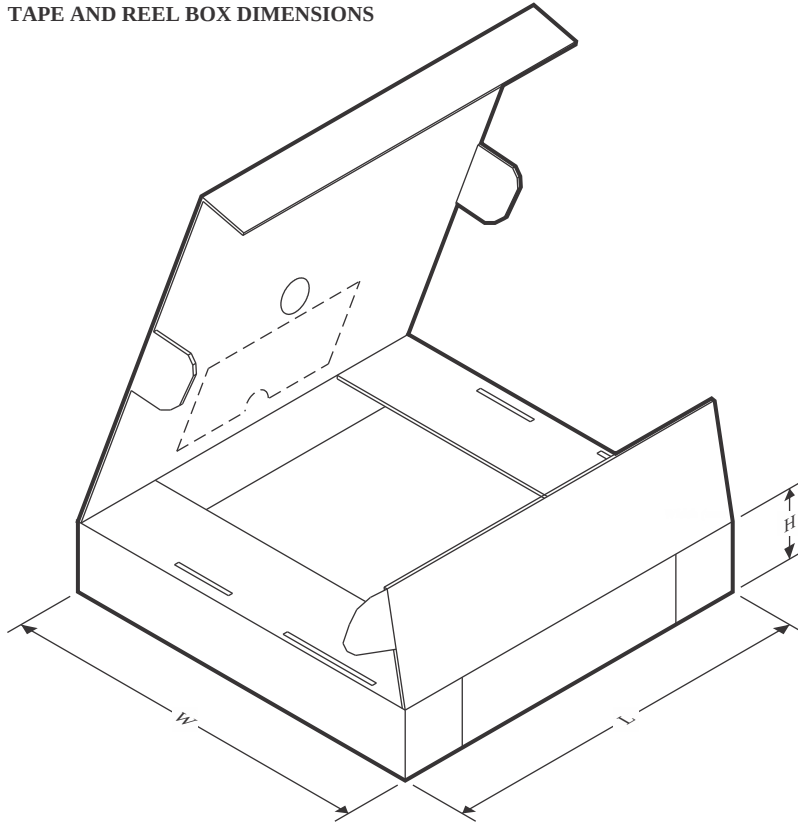
## TAPE AND REEL INFORMATION



\*All dimensions are nominal

| Device     | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| BQ35100PWR | TSSOP        | PW              | 14   | 2000 | 330.0              | 12.4               | 6.9     | 5.6     | 1.6     | 8.0     | 12.0   | Q1            |

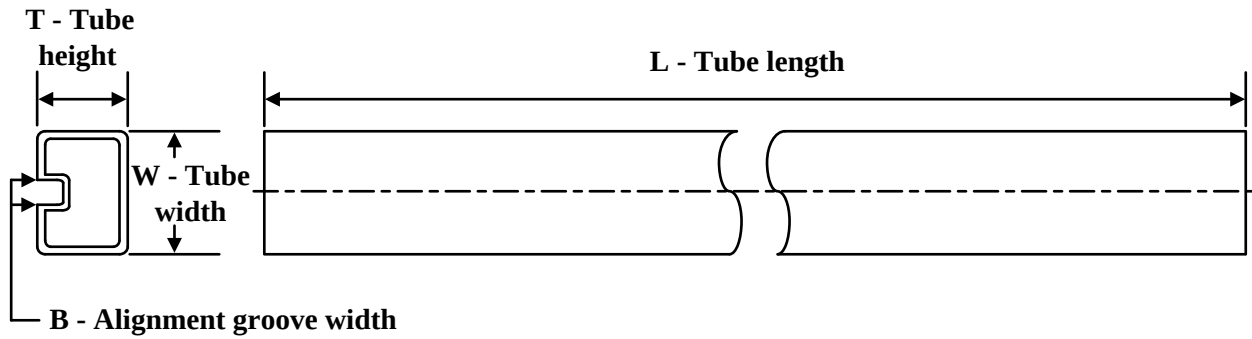
## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

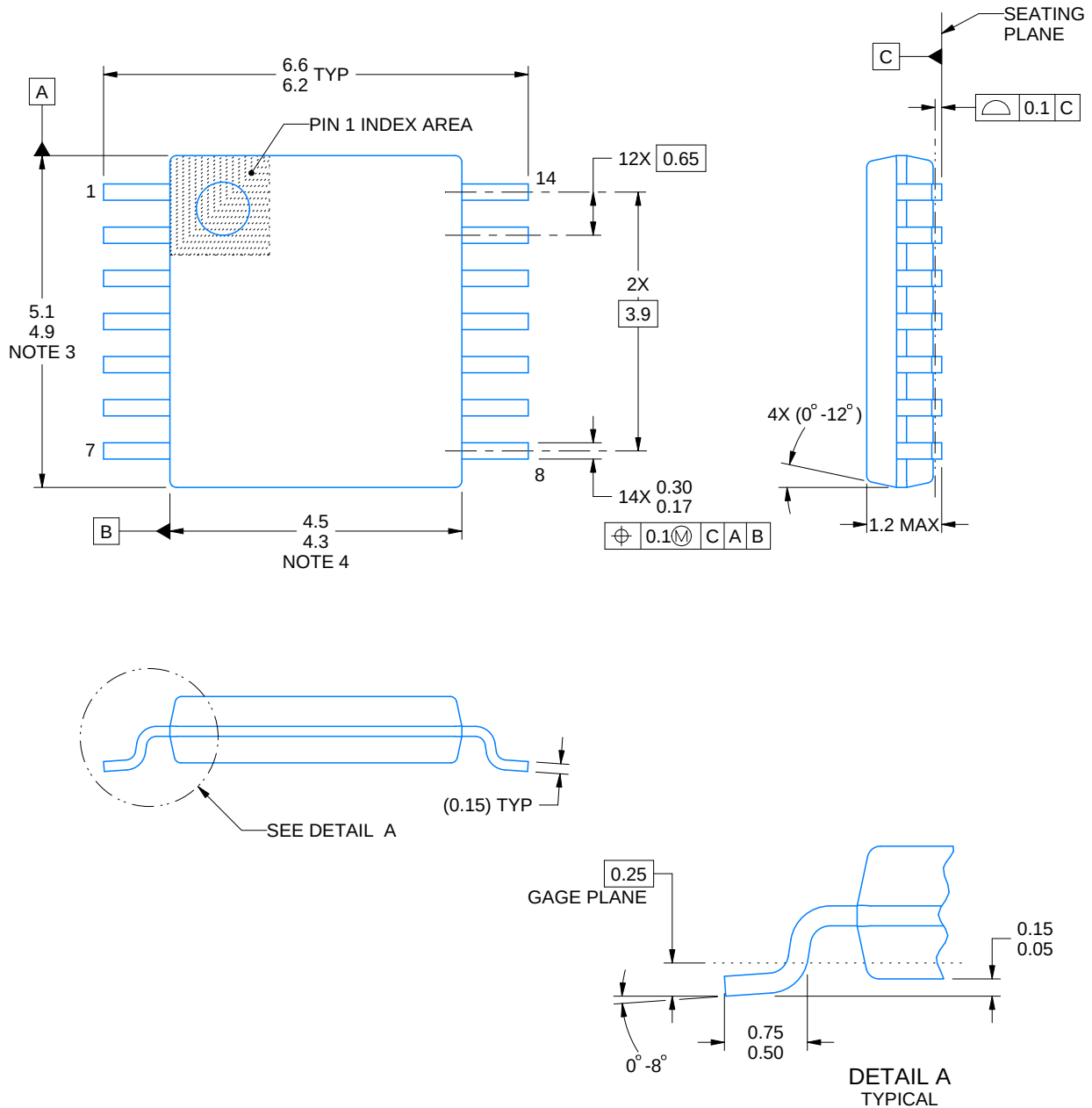
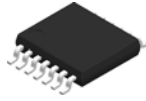
| Device     | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|------------|--------------|-----------------|------|------|-------------|------------|-------------|
| BQ35100PWR | TSSOP        | PW              | 14   | 2000 | 367.0       | 367.0      | 38.0        |

## TUBE



\*All dimensions are nominal

| Device        | Package Name | Package Type | Pins | SPQ | L (mm) | W (mm) | T (μm) | B (mm) |
|---------------|--------------|--------------|------|-----|--------|--------|--------|--------|
| BQ35100PW     | PW           | TSSOP        | 14   | 90  | 530    | 10.2   | 3600   | 3.5    |
| BQ35100PW.A   | PW           | TSSOP        | 14   | 90  | 530    | 10.2   | 3600   | 3.5    |
| BQ35100PW.B   | PW           | TSSOP        | 14   | 90  | 530    | 10.2   | 3600   | 3.5    |
| BQ35100PWG4   | PW           | TSSOP        | 14   | 90  | 530    | 10.2   | 3600   | 3.5    |
| BQ35100PWG4.A | PW           | TSSOP        | 14   | 90  | 530    | 10.2   | 3600   | 3.5    |
| BQ35100PWG4.B | PW           | TSSOP        | 14   | 90  | 530    | 10.2   | 3600   | 3.5    |



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## NOTES:

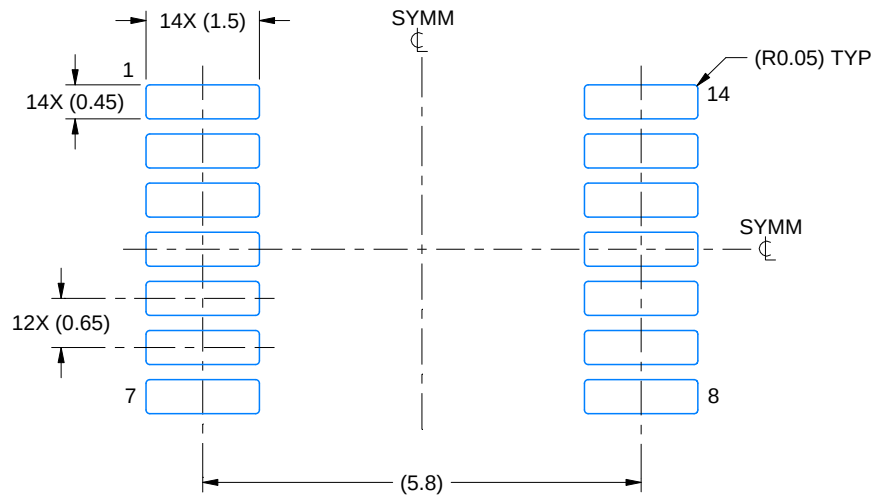
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-153.

# EXAMPLE BOARD LAYOUT

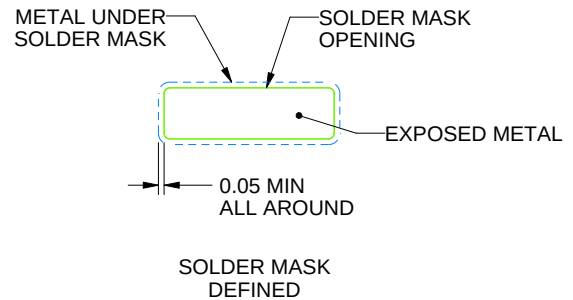
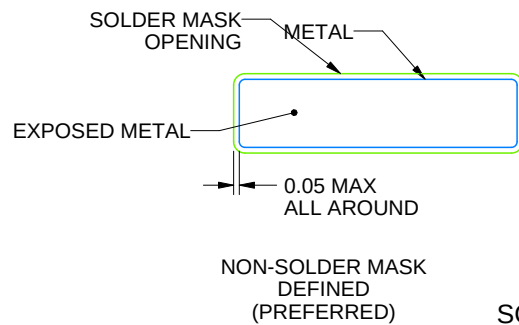
PW0014A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE: 10X



SOLDER MASK DETAILS

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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

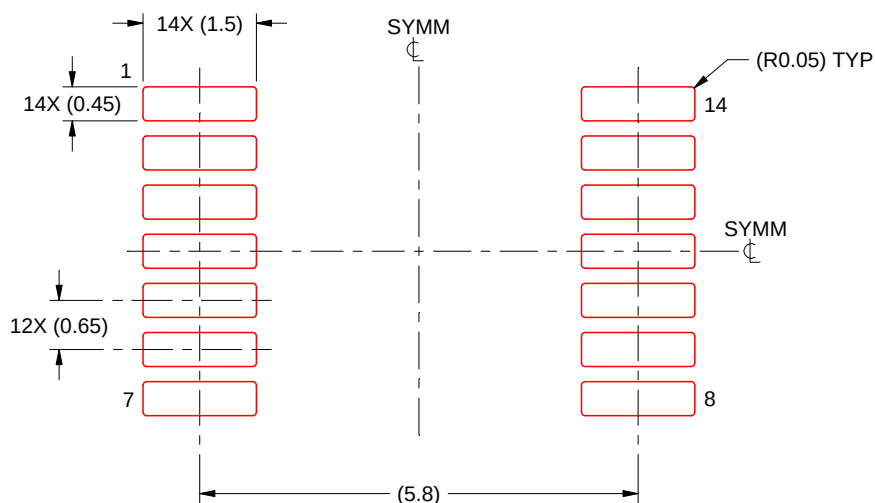


# EXAMPLE STENCIL DESIGN

PW0014A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE: 10X

4220202/B 12/2023

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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最后更新日期：2025 年 10 月