

EVM Application #6

Measuring the Period of an Input Square Wave Using the TMS320F240 EVM

APPLICATION REPORT: SPRA415

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*Digital Signal Processing Solutions
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Measuring the Period of an Input Square Wave Using the TMS320F240 EVM

Abstract

This EVM application measures the elapsed time between two rising edges of an input square wave using the capture input module in the Event Manager. The elapsed time (in microseconds) is output to a variable that can be viewed in the debugger environment. This application is written in C2xx Assembly code. The algorithm described in this application report was implemented using the Texas Instruments (TI™) TMS320F240 Evaluation Module (EVM).

The specific topics discussed include:

- PLL module
- Digital I/O ports
- Event Manager



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Overview

This application measures the elapsed time between two rising edges of an input square wave using the capture input module in the Event Manager. The elapsed time (in microseconds) is output to a variable that can be viewed in the debugger environment. This application is written in C2xx Assembly code. The algorithm described in this application report was implemented using the TI TMS320F240 EVM.

To view the results, the following commands need to be entered into the debugger environment when the program is loaded.

- 1) `ba STOP`
- 2) `wa *USPERIOD,,u`

The measured period will appear in a watch window for the variable USPERIOD.

Modules Used

- Event Manager
- General Purpose Timer 2
- Capture Input 1

Input

CAP1/QEP1

Output

None



Background and Methodology

The initial setup of the program is similar to previous applications. The PLL module, digital I/O ports, and the Event Manager all need to be configured before the program can be executed.

Because this program calculates the period of a signal, the PLL module needs to be set up so that the time base for the calculation of the period can be done correctly. The digital I/O port needs to be configured because the Event Manager Capture inputs share their pins with general I/O pins.

PLL Module

The PLL module is set up as in Application #1 (PWM0.ASM). The frequency that the CPUCLK is set to be is important in order to determine the period of the input square wave. The PLL divide by 2 is enabled and the multiplication ratio is set to 4; as a result, with a CLKIN (crystal oscillator) value of 10MHz, the CPUCLK is 20MHz. Therefore, the CPUCLK period is 0.05 μ s.

Digital I/O Ports

Similar to the PWM applications where Output Control Register A (OCRA) had to be set so that the PWM signal could be output on the proper pins, Output Control Register B (OCRB) has to be set so the pins that the capture inputs share with the I/O pins are configured as capture inputs.

Event Manager

Once the digital I/O port and the PLL module have been set, then the Event Manager module registers can be configured to capture the rising edges of an input square wave. Since only one input capture port will be used, only one GP Timer in the Event Manager will be needed. In this application, the input will be placed into capture input 1. Since the capture units of the event manager can only use GP Timer 2 or 3, one of the timers needs to be selected. For this application, GP Timer 2 was selected as the timer that the capture input 1 will use.



Once the Capture and Timer units of the Event Manager have been set, the program can be executed. To obtain a reliable period measurement, 5 measurements are captured. The first value is discarded because of synchronization error that typically occurs. In the first capture, the timer is started and then the interrupts are enabled; as a result, the delay in enabling the interrupts after starting the timer could result in an invalid value because a rising edge could have occurred during the latency. The next four values are summed and averaged. The resulting average value is multiplied by the equivalent Q15 value for the period of the 20MHz CPUCLK. The final product is stored into the location USPERIOD and can be viewed in a watch window.

Since only one timer module will be used, the resolution that this application will be able to perform is limited by the size of the counter. In theory, the range of the frequencies that this application will be able to work with is bounded by the maximum and minimum value of the counter. Therefore, with a 16bit counter, the theoretical resolution of this application with a 20MHz CPUCLK running the counter, will be 20MHz (20Mhz/1) to 305Hz (20MHz/FFFFh).



However, because there is latency (28 cycles) associated with the interrupt service routine, the maximum frequency that can be measured is about 700kHz.

Event manager interrupt			1 cycle
Flush Pipeline, Check Vector Table			4 cycles
Branch to ISR			4 cycles
CAP_ISR	LDP	#232	2 cycles
	LACC	CAP1FIFO	1 cycle
	MAR	*,AR1	1 cycle
	SACL	*+,0,AR2	1 cycle
	LACC	*	1 cycle
	SUB	#1	1 cycle
	SACL	*,0,AR1	1 cycle
	BCND	LEAVE,EQ	2 cycles
	SPLK	#0000h,T2CNT	2 cycles
	LACC	EVIFRC	1 cycle
	SACL	EVIFRC	1 cycle
	CLRC	INTM	1 cycle
	RET		4 cycle

Latency = 28 cycles

$$\text{Max Frequency} = \frac{1}{\text{cycles} \times \text{CPUCLK period}} = \frac{1}{28 \times 50\text{ns}} \approx 714,000\text{Hz}$$

Using this application to measure the period at the maximum and minimum frequencies becomes somewhat unreliable. At the maximum frequency, the interrupt service latency becomes a problem. At the minimum frequency, the rollover of the 16 bit counter becomes an issue. This application can measure with some accuracy periods equivalent to the frequencies in the range of 500Hz to 10kHz; however, as one measures higher frequencies, the accuracy decreases because of the ISR latency.

Once this program is executed, it will stop at the break point that was set at STOP. By restarting the program in debugger environment, another measurement can be taken. The results will show up in the watch window next to USPERIOD.



```
*****
; File Name:          cap0.asm
; Originator:        Digital control systems Apps group - Houston
; Target System:     'C24x Evaluation Board
;
; Description:       Capture Input of the Event Manager Module
;                   is set up to measure the time elapsed between 2
;                   rising edges of an input square wave
;
;                   To view the results in the debugger environment the
;                   following commands need to be entered before the
;                   program is run
;                   ba STOP
;                   wa *USPERIOD,,u
;
;                   The value in USPERIOD is the length of the period
;                   in us. The value will be in base 10.
;
; Last Updated:     20 June 1997
;
*****
                .include f240regs.h
```



```
-----  
; Vector address declarations  
-----  
                .sect ".vectors"  
  
RSVECT          B    START    ; Reset Vector  
INT1            B    PHANTOM  ; Interrupt Level 1  
INT2            B    PHANTOM  ; Interrupt Level 2  
INT3            B    PHANTOM  ; Interrupt Level 3  
INT4            B    CAP_ISR   ; Interrupt Level 4  
INT5            B    PHANTOM  ; Interrupt Level 5  
INT6            B    PHANTOM  ; Interrupt Level 6  
RESERVED        B    PHANTOM  ; Reserved  
SW_INT8         B    PHANTOM  ; User S/W Interrupt  
SW_INT9         B    PHANTOM  ; User S/W Interrupt  
SW_INT10        B    PHANTOM  ; User S/W Interrupt  
SW_INT11        B    PHANTOM  ; User S/W Interrupt  
SW_INT12        B    PHANTOM  ; User S/W Interrupt  
SW_INT13        B    PHANTOM  ; User S/W Interrupt  
SW_INT14        B    PHANTOM  ; User S/W Interrupt  
SW_INT15        B    PHANTOM  ; User S/W Interrupt  
SW_INT16        B    PHANTOM  ; User S/W Interrupt  
TRAP            B    PHANTOM  ; Trap vector  
NMINT           B    PHANTOM  ; Non-maskable Interrupt  
EMU_TRAP        B    PHANTOM  ; Emulator Trap  
SW_INT20        B    PHANTOM  ; User S/W Interrupt  
SW_INT21        B    PHANTOM  ; User S/W Interrupt  
SW_INT22        B    PHANTOM  ; User S/W Interrupt  
SW_INT23        B    PHANTOM  ; User S/W Interrupt
```



```

;=====
; M A I N   C O D E   -  starts here
;=====
                .text
                NOP
START:          SETC  INTM           ;Disable interrupts
                SPLK  #0008h,IMR     ;Mask all core interrupts
                                   ;except INT4

                LACC  IFR           ;Read Interrupt flags
                SACL  IFR           ;Clear all interrupt flags

                CLRC  SXM           ;Clear Sign Extension Mode
                CLRC  OVM           ;Reset Overflow Mode
                CLRC  CNF           ;Config Block B0 to Data mem

;-----
; Set up PLL Module
;-----
                LDP   #00E0h

;The following line is necessary if a previous program set the PLL
;to a different setting than the settings which the application
;uses. By disabling the PLL, the CKCR1 register can be modified so
;that the PLL can run at the new settings when it is re-enabled.

                SPLK  #000000001000001b,CKCR0
                                   ;CLKMD=PLL Disable, SYSCLK=CPUCLK/2

;                5432109876543210
                SPLK  #0000000010111011b,CKCR1
;                ;CLKIN(OSC)=10MHz, CPUCLK=20MHz

;CKCR1 - Clock Control Register 1
;Bits 7-4      (1011)CKINF(3)-CKINF(0) - Crystal or Clock-In
;              Frequency
;              Frequency = 10MHz
;Bit 3        (1)  PLLDIV(2) - PLL divide by 2 bit
;              Divide PLL input by 2
;Bits 2-0     (011) PLLFB(2)-PLLFB(0) - PLL multiplication ratio
;              PLL Multiplication Ratio = 4

;                5432109876543210
                SPLK  #0000000011000001b,CKCR0
                                   ;CLKMD=PLL Enable, SYSCLK=CPUCLK/2

;CKCR0 - Clock Control Register 0
;Bits 7-6     (11)  CLKMD(1),CLKMD(0) - Operational mode of Clock
;              Module PLL Enabled
;              Run on CLKIN on exiting low power mode
;Bits 5-4     (00)  PLLOCK(1),PLLOCK(0) - PLL Status. READ ONLY
;Bits 3-2     (00)  PLLPM(1),PLLPM(0) - Low Power Mode

```



```
;
;          LPM0
;Bit 1      (0)  ACLKENA - 1MHz ACLK Enable
;          ACLK Disabled
;Bit 0      (1)  PLLPS - System Clock Prescale Value
;          f(sysclk)=f(cpuclk)/2

;          5432109876543210
SPLK #0100000011000000b,SYSCR ;CLKOUT=CPUCLK

;SYSCR - System Control Register
;Bit 15-14  (01)  RESET1,RESET0 - Software Reset Bits
;          No Action
;Bits 13-8   (000000) Reserved
;Bit 7-6     (11)  CLKSRC1,CLKSRC0 - CLKOUT-Pin Source Select
;          CPUCLK: CPU clock output mode
;Bit 5-0     (000000) Reserved

SPLK #006Fh, WDCR ;Disable WD if VCCP=5V (JP5
;                ;in pos. 2-3)
KICK_DOG          ;Reset Watchdog

;-----
; Set up Digital I/O Port
;-----
LDP #225 ;DP=225, Data Page to Configure OCRA
;          5432109876543210
SPLK #0011100000000000b,OCRA

;OCRA - Output Control Register A
;          Bit 15 (0)  CRA.15 - IOPB7
;          Bit 14 (0)  CRA.14 - IOPB6
;          Bit 13 (1)  CRA.13 - T3PWM/T3CMP
;          Bit 12 (1)  CRA.12 - T2PWM/T2CMP
;          Bit 11 (1)  CRA.11 - T1PWM/T1CMP
;          Bit 10 (0)  CRA.10 - IOPB2
;          Bit 9 (0)   CRA.9 - IOPB1
;          Bit 8 (0)   CRA.8 - IOPB0
;          Bits 7-4 (0000) Reserved
;          Bit 3 (0)   CRA.3 - IOPA3
;          Bit 2 (0)   CRA.2 - IOPA2
;          Bit 1 (0)   CRA.1 - IOPA1
;          Bit 0 (0)   CRA.0 - IOPA0

;          76543210
SPLK #11110000b,OCRB

;OCRB - Output Control Register B
;          Bit 7 (1)  CRB.7 - CAP4
;          Bit 6 (1)  CRB.6 - CAP3
;          Bit 5 (1)  CRB.5 - CAP2/QEP2
;          Bit 4 (1)  CRB.4 - CAP1/QEP1
```




```
.text
LDP #232 ;DP=232, Data Page for
;Event Manager Addresses

SPLK #T2COMPARE,T2CMPR ;T2CMPR = T2PERIOD/2

;
; 2109876543210
SPLK #0000001010101b,GPTCON

;GPTCON - GP Timer Control Register
; Bit 15 (0) T3STAT - GP Timer 3 Status. READ ONLY
; Bit 14 (0) T2STAT - GP Timer 2 Status. READ ONLY
; Bit 13 (0) T1STAT - GP Timer 1 Status. READ ONLY
; Bits 12-11 (00) T3TOADC - ADC start by event of GP Timer 3
; No event starts ADC
; Bits 10-9 (00) T2TOADC - ADC start by event of GP Timer 2
; No event starts ADC
; Bits 8-7 (00) T1TOADC - ADC start by event of GP Timer 1
; No event starts ADC
; Bit 6 (1) TCOMPOE - Compare output enable
; Enable all three GP timer compare outputs
; Bits 5-4 (01) T3PIN - Polarity of GP Timer 3 compare output
; Active Low
; Bits 3-2 (01) T2PIN - Polarity of GP Timer 2 compare output
; Active Low
; Bits 1-0 (01) T1PIN - Polarity of GP Timer 1 compare output
; Active Low

SPLK #T2PERIOD,T2PR ; T2PR = FFFFh
SPLK #0000h,T2CNT ; Initialize Timer 2

;
; 5432109876543210
SPLK #00000000000000100b,T1CON ;Not Used

;T1CON - GP Timer 1 Control Register
; Bits 15-14 (00) FREE,SOFT - Emulation Control Bits
; Stop immediately on emulation suspend
; Bits 13-11 (000) TMODE2-TMODE0 - Count Mode Selection
; Stop/Hold
; Bits 10-8 (000) TPS2-TPS0 - Input Clock Prescaler
; Divide by 1
; Bit 7 (0) Reserved
; Bit 6 (0) TENABLE - Timer Enable
; Disable timer operations
; Bits 5-4 (00) TCLKS1,TCLKS0 - Clock Source Select
; Internal Clock Source
; Bits 3-2 (00) TCLD1,TCLD0 - Timer Compare Register
; Reload Condition
; When counter is 0
; Bit 1 (0) TECMPR - Timer compare enable
; Disable timer compare operation
```



```

;      Bit 0      (0)  Reserved

;
;              5432109876543210
;          SPLK #0001000000000110b,T2CON

;T2CON - GP Timer 2 Control Register
;      Bits 15-14 (00)  FREE,SOFT - Emulation Control Bits
;
;              Stop immediately on emulation suspend
;      Bits 13-11 (010) TMODE2-TMODE0 - Count Mode Selection
;
;              Continuous Count-Up Mode
;      Bits 10-8  (000) TPS2-TPS0 - Input Clock Prescaler
;
;              Divide by 1
;      Bit 7      (0)   TSWT1 - GP Timer 1 timer enable bit
;
;              Use own TENABLE bit
;      Bit 6      (0)   TENABLE - Timer Enable
;
;              Disable timer operations
;      Bits 5-4  (00)  TCLKS1,TCLKS0 - Clock Source Select
;
;              Internal Clock Source
;      Bits 3-2  (01)  TCLD1,TCLD0 - Timer Compare Register
;
;              Reload Condition
;
;              When counter is 0 or equals period
;              register value
;      Bit 1      (1)   TECMPR - Timer compare enable
;
;              Enable timer compare operation
;      Bit 0      (0)   SELT1PR - Period Register select
;
;              Use own period register

;
;              5432109876543210
;          SPLK #0000000000000000b,T3CON ;Not Used

;T3CON - GP Timer 3 Control Register
;      Bits 15-14 (00)  FREE,SOFT - Emulation Control Bits
;
;              Stop immediately on emulation suspend
;      Bits 13-11 (000) TMODE2-TMODE0 - Count Mode Selection
;
;              Stop/hold
;      Bits 10-8  (000) TPS2-TPS0 - Input Clock Prescaler
;
;              Divide by 1
;      Bit 7      (0)   TSWT1 - GP Timer 1 timer enable bit
;
;              Use own TENABLE bit
;      Bit 6      (0)   TENABLE - Timer Enable
;
;              Disable timer operations
;      Bits 5-4  (00)  TCLKS1,TCLKS0 - Clock Source Select
;
;              Internal Clock
;      Bits 3-2  (00)  TCLD1,TCLD0 - Timer Compare Register
;
;              Reload Condition
;
;              When counter is 0
;      Bit 1      (0)   TECMPR - Timer compare enable
;
;              Disable timer compare operation
;      Bit 0      (0)   SELT1PR - Period Register select
;
;              Use own period register

```



```
;
                                5432109876543210
                                SPLK #10111110001010101b,CAPCON

;CAPCON - Capture Control Register
;   Bit 15      (0)  CAPRES - Capture Reset
;                   Clear all registers of capture units and
;                   QEP circuits to 0
;   Bits 14-13 (01) CAPQEPN - Capture Units 1 & 2 and QEP Circuit
;                   Control
;                   Enable Capture Units 1 & 2. Disable QEP
;                   Circuit
;   Bit 12      (1)  CAP3EN - Capture Unit 3 Control
;                   Enable Capture Unit 3
;   Bit 11      (1)  CAP4EN - Capture Unit 4 Control
;                   Enable Capture Unit 4
;   Bit 10      (1)  CAP34TSEL - GP Timer Selection for Capture
;                   Units 3 & 4
;                   Select GP Timer 3
;   Bit 9       (0)  CAP12TSEL - GP Timer Selection for Capture
;                   Units 1 & 2
;                   Select GP Timer 2
;   Bit 8       (0)  CAP4TOADC - Capture Unit 4 starts ADC
;                   No Action
;   Bits 7-6    (01) CAP1EDGE - Edge Detection for Capture Unit 1
;                   Detect Rising Edge
;   Bits 5-4    (01) CAP2EDGE - Edge Detection for Capture Unit 2
;                   Detect Rising Edge
;   Bits 3-2    (01) CAP3EDGE - Edge Detection for Capture Unit 3
;                   Detect Rising Edge
;   Bits 0-1    (01) CAP4EDGE - Edge Detection for Capture Unit 4
;                   Detect Rising Edge

;
                                876543210
                                SPLK #011111111b,CAPFIFO

;CAPFIFO - Capture FIFO Status Register
;   Bits 15-14      CAP4FIFO Status - READ ONLY
;   Bits 13-12      CAP3FIFO Status - READ ONLY
;   Bits 11-10      CAP2FIFO Status - READ ONLY
;   Bits 9-8        CAP1FIFO Status - READ ONLY
;   Bit 7           (1)  CAPFIFO15 - CAP4FIFO bit 15 Clear
;                   Clear Bit 15 of CAPFIFO
;   Bit 6           (1)  CAPFIFO14 - CAP4FIFO bit 14 Clear
;                   Clear Bit 14 of CAPFIFO
;   Bit 5           (1)  CAPFIFO13 - CAP3FIFO bit 13 Clear
;                   Clear Bit 13 of CAPFIFO
;   Bit 4           (1)  CAPFIFO12 - CAP3FIFO bit 12 Clear
;                   Clear Bit 12 of CAPFIFO
;   Bit 3           (1)  CAPFIFO11 - CAP2FIFO bit 11 Clear
;                   Clear Bit 11 of CAPFIFO
;   Bit 2           (1)  CAPFIFO10 - CAP2FIFO bit 10 Clear
;                   Clear Bit 10 of CAPFIFO
```



```

;      Bit 1      (1)  CAPFIFO9 - CAP1FIFO bit 9 Clear
;                  Clear Bit 9 of CAPFIFO
;      Bit 0      (1)  CAPFIFO8 - CAP1FIFO bit 8 Clear
;                  Clear Bit 8 of CAPFIFO

;
;                  3210
;                  SPLK #0001b,EVIMRC

;EVIMRC - EV Interrupt Mask Register C
;      Bits 15-4      Reserved
;      Bit 3          (0)  CAP4INT Enable
;                  Disable
;      Bit 2          (0)  CAP3INT Enable
;                  Disable
;      Bit 1          (0)  CAP2INT Enable
;                  Disable
;      Bit 0          (1)  CAP1INT Enable
;                  Enable

;-----
;                  VARIABLES FOR CAP_ISR
;-----

.bss      VALUE1,1      ;1st timer value for 1st rising edge
.bss      VALUE2,1      ;2nd timer value for 2nd rising edge
.bss      VALUE3,1      ;3rd timer value for 3rd rising edge
.bss      VALUE4,1      ;4nd timer value for 4nd rising edge
.bss      VALUE5,1      ;5nd timer value for 5nd rising edge
.bss      AVERAGE,1    ;Average of VALUE2 through VALUE5
.bss      COUNTER,1     ;Counter to acquire 5 values
.bss      USPERIOD,1    ;Period of the 2 rising edges
.bss      CLKPERIOD,1   ;Q15 value for the period of the CPUCLK

.text

LAR       AR1,#VALUE1    ;AR1 = address of VALUE1
LAR       AR2,#COUNTER   ;AR2 = address of COUNTER

LDP       #0
SPLK     #0000h,VALUE1   ;Initialize VALUE1
SPLK     #0000h,VALUE2   ;Initialize VALUE2
SPLK     #0000h,VALUE3   ;Initialize VALUE3
SPLK     #0000h,VALUE4   ;Initialize VALUE4
SPLK     #0000h,VALUE5   ;Initialize VALUE5
SPLK     #0000h,AVERAGE ;Initialize AVERAGE
SPLK     #0005h,COUNTER  ;Counter set to acquire 5 values
SPLK     #0000h,USPERIOD ;Initialize USPERIOD
SPLK     #0666h,CLKPERIOD
;Q15 value of 0.05us = T => 20MHz CPUCLK

```



```
LDP      #232
LACC     EVIFRC      ;ACC = Interrupt Flags of EVIFRC
SACL     EVIFRC      ;EVIFRC = ACC => clears all flags

LDP      #0
LACC     IFR         ;ACC = Interrupt Flags of IFR
SACL     IFR         ;IFR = ACC => clears all flags

LDP      #232
SBIT1    T2CON,B6_MSK ;Sets Bit 6 of T2CON

;TxCON - GP Timer x Control Register
;   Bit 6      (1)  TENABLE - Timer Enable
;
;                   Enable Timer Operations

CLRC     INTM        ;Enable Interrupts

WAIT     B           WAIT      ;Wait for an interrupt

;-----
; CAPTURE INTERRUPT SERVICE ROUTINE
;-----

CAP_ISR  LDP      #232      ;DP = 232, Data Page for Event
;                   ;Manager Registers
LACC     CAP1FIFO     ;ACC = value of GP Timer at capture
MAR      *,AR1       ;ARP = AR1
SACL     *,0,AR2     ;VALUEx= value of GP Timer from
;                   ;CAP1FIFO, ARP = AR2
LACC     *           ;ACC = COUNTER
SUB      #1          ;Decrement Counter
SACL     *,0,AR1     ;Store new value of Counter, APR = AR1
BCND     LEAVE,EQ    ;Exit if all values have been captured

SPLK     #0000h,T2CNT ;Else, Clear the counter
LACC     EVIFRC      ;Clear the EVIFRC interrupt flags
SACL     EVIFRC

CLRC     INTM        ;Enable interrupts

RET      ;Return to capture the next rising edge

LEAVE    LDP      #0      ;DP = 0, Data Page for the acquired values
LACC     VALUE2      ;ACC = VALUE2
ADD      VALUE3      ;ACC = VALUE2 + VALUE3
ADD      VALUE4      ;ACC = VALUE2 + VALUE3 + VALUE4
ADD      VALUE5      ;ACC = VALUE2 + VALUE3 + VALUE4 + VALUE5

SFR      ;Shift ACC right = Divide by 2
SFR      ;Shift ACC right = Divide by 2
```



```
SACL    AVERAGE    ;Store value into AVERAGE

LT      AVERAGE    ;TREG = AVERAGE
MPYU    CLKPERIOD  ;PREG = AVERAGE(Q0)*CLKPERIOD(Q15)
PAC     ;ACC = PREG
SACH    USPERIOD,1 ;USPERIOD = ACC(30:15),Shift left to
           ; remove the extra sign bit

STOP    B          STOP    ;End the Program
```

```
=====
; I S R - PHANTOM
;
; Description:   Dummy ISR, used to trap spurious interrupts.
;
; Modifies:     Nothing
;
; Last Update:  16 June 95
=====
PHANTOM    KICK_DOG    ;Resets WD counter
           B PHANTOM
```