

Using the CRC Module on Hercules™-Based Microcontrollers

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ABSTRACT

This application report describes how to use the embedded CRC module found on all Hercules devices, as well as how to calculate a signature for non-volatile memory with the TI ARM® Code Gen Tools Linker.

Project collateral and source code discussed in this application report can be downloaded from the following URL: <http://www.ti.com/lit/zip/spna235>.

NOTE: TI assumes no liability that the discussed implementation and provided code are free from faults, compliant to certain coding guidelines, nor was it developed in accordance with certain standards. The implementer has to ensure and verify that the code conforms to appropriate rules and standards, and he has the sole responsibility to ensure and verify correct functionality in his application.

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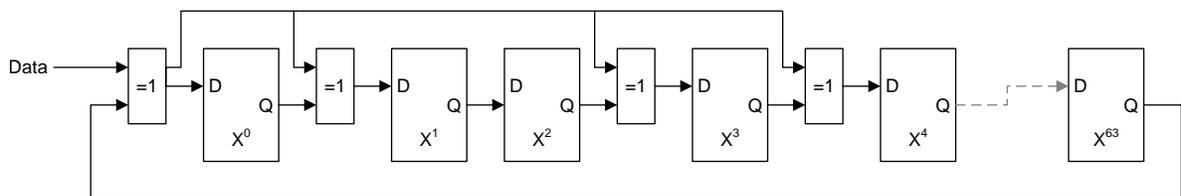
1 Cyclic Redundancy Check (CRC) Controller Module

The CRC module can be used to calculate signatures representing the content of a memory and to compare a calculated signature against a pre-calculated signature. The polynomial used for the signature calculation is a fix 64-bit primitive polynomial. The CRC module support three different modes how to calculate the signature, these differ in the degree of automation or how much CPU involvement is necessary to perform the signature calculation. The modes are called Auto (Section 1.2.4), Semi-CPU (Section 1.2.3) and Full-CPU (Section 1.2.2). The CRC module should be used in conjunction with the on-chip DMA controller for optimal performance and to offload the CPU, the DMA controller is used in modes Auto and Semi-CPU. In addition to the three modes a fourth mode called Software Mode (Section 1.2.1) is introduced in this documentation. The Software Mode does not use the CRC module but performs the signature calculation entirely with the CPU.

1.1 The Used Polynomial

The CRC module uses a fixed 64-bit polynomial. The polynomial can be represented by Equation 1 or the Linear Feedback Shift Register (LFSR) shown in Figure 1.

$$f(x) = x^{64} + x^4 + x^3 + x + 1 \tag{1}$$



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Figure 1. LFSR Diagram

1.2 Modes

1.2.1 Software Mode

This mode does not use the CRC module at all, instead all calculations are performed by the CPU. This mode was added to help to understand how the signature calculation is performed. As this mode is very inefficient and time consuming, it is strongly recommended to use the CRC module to offload the CPU. The example for this mode is described in Section 3.3.

1.2.2 Full-CPU Mode

In Full-CPU mode, no DMA requests and no interrupts are generated at all. The number of data patterns to be compressed is determined by CPU itself. Full-CPU mode is useful when no DMA controller is available at all, or if it isn't available to perform background data patterns transfer. The scheduler or OS can periodically generate an interrupt to CPU and use CPU to accomplish data transfer and signature verification.

In Full-CPU mode, the CPU does the data patterns transfer and signature verification all by itself. The CPU has to perform data patterns transfer by reading data from the memory system and by writing it to the PSA Signature Register (PSA_SIGREGx). After certain number of data patterns is compressed, the CPU can read from the PSA Signature Register and compare the calculated signature to the pre-determined CRC signature value.

For this the CPU has to perform the tasks shown in Figure 2.

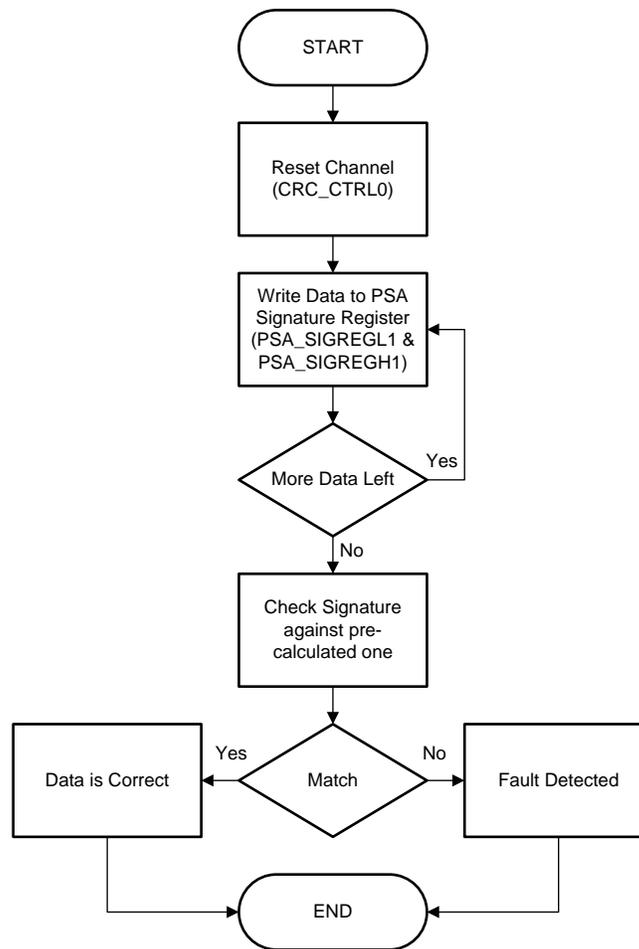


Figure 2. Full-CPU Mode Flowchart

The example for this mode is described in [Section 3.4](#).

1.2.3 Semi-CPU Mode

In semi-CPU mode, the DMA controller is utilized to perform data patterns transfer to the PSA Signature Register. The CRC controller generates a compression complete interrupt to CPU after each sector is compressed. Upon responding to the interrupt the CPU performs the signature verification by reading the calculated signature stored at the PSA Sector Signature Register and compares it to a pre-determined CRC value. There are two different examples using the Semi-CPU Mode, one uses a polling loop ([Section 3.5](#)) and the second one using interrupts ([Section 3.6](#)) to determine when the data compression has been finished.

1.2.4 Auto Mode

In AUTO mode, together the CRC Controller and the DMA controller can perform the data compression without CPU intervention. A sustained transfer of data to both the PSA Signature Register and CRC Value Register are performed in the background of CPU. When a mismatch is detected, an interrupt is generated to CPU. A 16-bit current sector ID register is provided to identify which sector causes a CRC failure.

In Auto Mode, the CRC module expects the memory to be divided in N equal sized sectors, where a pre-calculated CRC signature is associated to each of the N sectors. Two DMA channels are required to work in this mode. One is setup to copy the data values of N sectors into the CRC modules PSA Signature Register and could be triggered by the RTI time as for the Semi-CPU mode. The second DMA channel gets triggered by the DMA controller after a sector has been compressed and is used to copy the next CRC signature into the CRC Value Register (CRC_REGx). As the pre-calculated CRC value gets automatically compared to the compressed data, the CRC module can now independently perform data verification of the entire (for example, program) memory.

However, the CRC Table implementation in the TI Linker (see [Section 2](#)) does not support this use case. Therefore, this is not further described in this document. However, the Semi-CPU Mode method suites most applications.

2 Linker Generated CRC Tables

The TI ARM Code Generation Tools Linker can be used to pre-calculate the signatures for different memory regions. This feature was introduced in 2011 with version 4.9.x of the TI ARM CGT tools. The CRC tables get configured in the Linker Command File (LCF) as part of the configured sections.

2.1 The `crc_table()` Operator

The operator `crc_table()` should be applied to any section in the LCF, which should be verified with a CRC. The Linker support different CRC algorithms can be specified with the `crc_table()` operator. However, the CRC module found in Hercules devices only support the so called TMS570_CRC64_ISO algorithm. The syntax for using the CRC tables in the LCF:

```
crc_table(user_specified_table_name[, algorithm=xxx])
```

The algorithm defaults to TMS570_CRC64_ISO. However, it might be a good idea to explicitly specify this to ensure code compatibility:

```
crc_table(user_specified_table_name, algorithm=TMS570_CRC64_ISO)
```

The following line shows an example on how to apply the `crc_table()` operator to a section in the LCF:

```
.const : { } palign=8, fill=0xffffffff, crc_table(_my_crc_table, algorithm=TMS570_CRC64_ISO)
```

In this case, the `crc_table()` operator is applied to the section `.const` that is used to hold global and static const variables that are explicitly initialized. A CRC table with the name `_my_crc_table` will be created. The same CRC table name can be used for many sections; the resulting CRC table will then hold several entries that can be accessed individually. The additional palign operator ensures that the section starts and ends on a 64-bit boundary. This is important keeping in mind, that the CRC module performs data compression on 64 bits. Furthermore the DMA controller can only read and write to addresses aligned to the read or write size. Thus, the sections should start and end on 64-bit boundaries.

An additional section should be added to the LCF to avoid warnings during the link step:

```
.TI.crctab : { } palign=8
```

The `.TI.crctab` section will hold all CRC tables created within the LCF. Omitting the lines above will cause the Linker to warn that an unknown section will be created. The section should be linked to a constant memory as it should not be modified.

2.2 Accessing the CRC Tables Within C Code

The Code Generation Tools include a header file to help to access the CRC tables within C code as part of the standard library. Include the `crc_tbl.h` file in every C source file, which accesses the CRC tables (`#include "crc_tbl.h"`). This header file holds the description (prototype) of the CRC tables. A CRC table can hold several entries called CRC records.

```

/*****
/* CRC Record Data Structure          */
/* NOTE: The list of fields and the size of each field */
/*      varies by target and memory model.          */
/*****
typedef struct crc_record
{
uint64_t      crc_value;

```

```

uint32_t      crc_alg_ID;    /* CRC algorithm ID */
uint32_t      addr;         /* Starting address */
uint32_t      size;         /* size of data in bytes */
uint32_t      padding;      /* explicit padding so layout is the same */
                                     /* for COFF and ELF */
} CRC_RECORD;

/*****
/* CRC Table Data Structure */
*****/
typedef struct crc_table
{
uint32_t      rec_size;
uint32_t      num_recs;
CRC_RECORD    recs[1];
} CRC_TABLE;

```

There are several ways to define and access the CRC tables created by the linker. The following definition for a CRC table within the C code is recommended:

```
extern const CRC_TABLE _my_crc_table;
```

Note that the `_my_crc_table` name was also used in the example in [Section 2.1](#). The following code can be used to access the CRC table and the individual entries:

```

for (i = 0ul ; i < _my_crc_table.num_recs ; i++)
{
    /* Check for the right algorithm */
    if (TMS570_CRC64_ISO == _my_crc_table.rec[s].crc_alg_ID)
    {
        _my_crc_table.rec[s].crc_value;

        /* Convert Address to 64-bit Pointer */
        (uint64*)_my_crc_table.rec[s].addr;

        /* Adjust the size to be in 64-bit increment rather than bytes */
        _my_crc_table.rec[s].size / 8ul;
    }
    else
    {
        /* Unknown Algorithm */
    }
}

```

3 Implementation

3.1 Example Code

This application report comes with two Code Composer Studio™ projects to show the functionality of the CRC module. The supplied examples cover most of the devices out the Hercules Family. To see which of the two examples are available for which devices, see [Table 1](#). The first example shows the use of all three modes (SW, Full-CPU and Semi-CPU Mode); however, the Semi-CPU mode uses polling in this example and is not meant to be used that way in a production environment. The second example shows the Semi-CPU Mode in an interrupt driven fashion as it is intended to be used.

- Example 1: CRC SW Full-CPU and Semi-CPU Modes
 - Software Mode (see [Section 3.3](#))
 - Full-CPU Mode ([Section 3.4](#))
 - Semi-CPU Mode Polling ([Section 3.5](#))
- Example 2: CRC Semi-CPU Mode IRQ
 - Semi-CPU Mode Interrupt Driven ([Section 3.6](#))

Table 1. Examples Available per Device

	LS04	LS07	LS12	LS31	LC43	RM42	RM44	RM46	RM48	RM57
Example 1	x		x	x	x	x		x	x	x
Example 2			x	x	x			x	x	x

3.2 Linker Generated CRC Table

Linker generated CRC tables, described in [Section 2.1](#), are used in the example projects. For this, a Linker Command File (linker_command_file.cmd) was created. This Linker Command File also shows how to use the Linker Generated ECC feature of the TI Linker (http://processors.wiki.ti.com/index.php/Linker_Generated_ECC).

The generated CRC tables can also be seen in the so called Map file generated by the linker, for example:

```
_my_crc_table @ 00008c00 records: 4, size/record: 24, table size: 104
.intvecs: algorithm=TMS570_CRC64_ISO(ID=10), load addr=00000000, size=00000020,
CRC=d9e7073eca088191
.text: algorithm=TMS570_CRC64_ISO(ID=10), load addr=00000020, size=00008730,
CRC=042202da2e5c3f1d
.const: algorithm=TMS570_CRC64_ISO(ID=10), load addr=00008750, size=00000288,
CRC=f93b08ae6214ed9b
.cinit: algorithm=TMS570_CRC64_ISO(ID=10), load addr=000089d8, size=00000228,
CRC=f7cf30240362a8da
```

3.3 Software Mode

The compression can be performed by the CPU with the following C function:

```
uint64 crc_update_word(uint64 crc64, uint64 data)
{
    int    i, j;
    uint64 nextCrc = 0;

    // for i in 63 to 0 loop
    for(i = 63; i >= 0; i--)
    {
        // NEXT_CRC_VAL(0) := CRC_VAL(63) xor DATA(i);
        nextCrc = (nextCrc & 0xffffffffffffeULL) | ((crc64 >> 63) ^ (data >> i));

        // for j in 1 to 63 loop
        for(j = 1; j < 64; j++)
        {
            //case j is
            // when 1|3|4 =>
            if(j == 1 || j == 3 || j == 4)
            {
                // NEXT_CRC_VAL(j) := CRC_VAL(j - 1) xor CRC_VAL(63) xor DATA(i);
                nextCrc = (nextCrc & ~(1ULL << j)) | (((crc64 >> (j -
1)) ^ (crc64 >> 63) ^ (data >> i)) & 1) << j);
            }
            else
            { // when others =>
                // NEXT_CRC_VAL(j) := CRC_VAL(j - 1);
                nextCrc = (nextCrc & ~(1ULL << j)) | (((crc64 >> (j - 1)) & 1) << j);
            }
            // end case;
        } // end loop;
        crc64 = nextCrc;
    } // end loop

    return crc64;
}
```

The function has to be called for each 64-bit word, the inputs are the previous output or seed value (uint64 crc64) and the new data word (uint64 data). The function will not be very efficient when compiled as shown above, the performance can be improved by using proprietary compiler directives (#pragma). An improved version can be found in the CCS project provided with this document. The file containing the function is *CRC_calc.c*.

3.4 Full-CPU Mode

The full CPU-Mode example utilizes the function provided by HALCoGen to access the DMA module. In this mode, the CPU has to copy the data to be compressed into the CRC modules PSA Signature Register; this can be done with the help of the function *crcSignGen()* supplied with HALCoGen. After this, the CPU has to compare the newly calculated CRC with the pre-calculated CRC. [Figure 3](#) shows the basic program flow.

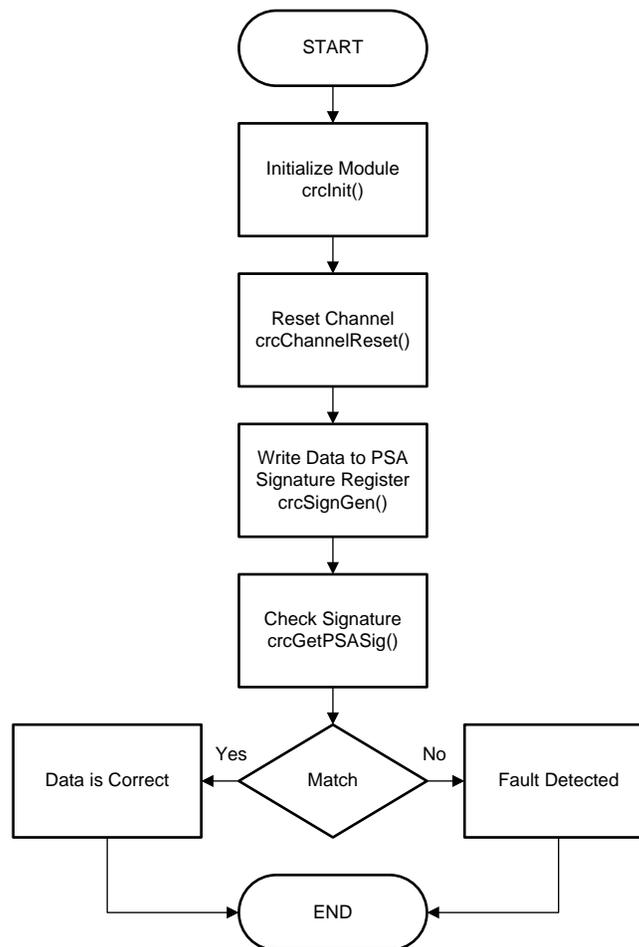


Figure 3. Full-CPU Mode With HALCoGen Flowchart

3.5 Semi-CPU Mode Polling

The Semi-CPU mode requires setting up a DMA packet, this can be done with the help of the DMA function supplied with HALCoGen. Similar to the Full-CPU Mode, HALCoGen generated functions are used to setup the CRC module. In addition to the CRC module setup used for the Full-CPU mode, the pattern and sector counters also have to be configured. The pattern counter is set to the number of double words (64 bit) to be compressed. The sector counter is set to 1 as only one sector at a time will be compressed. The time-out counters are used in this example. [Figure 4](#) shows the program flow for this mode.

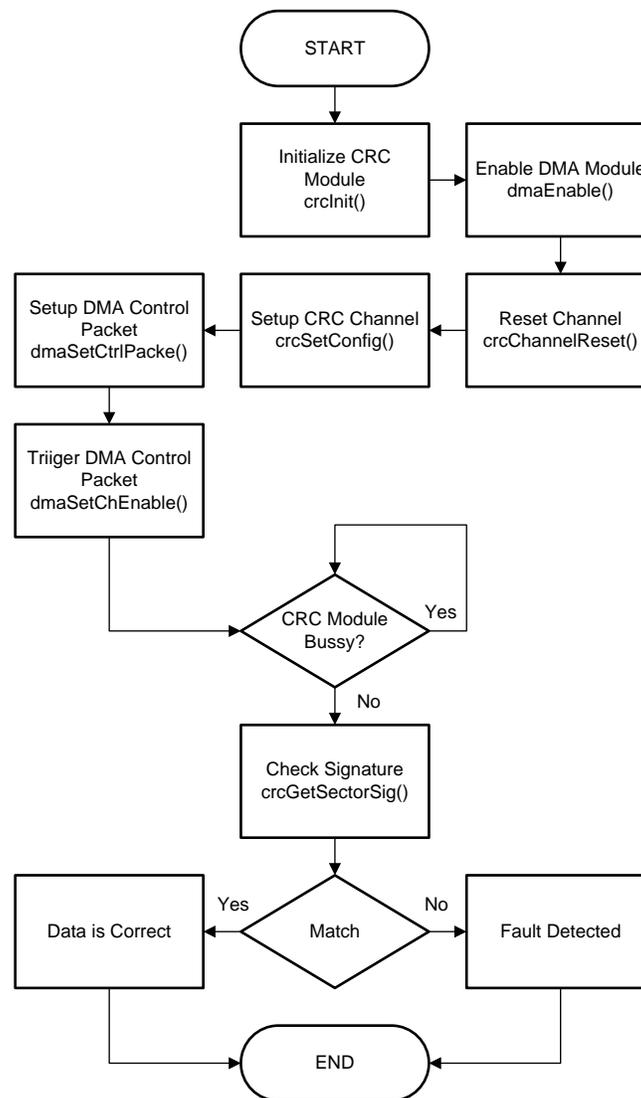


Figure 4. Semi-CPU Mode Polling Flowchart

The DMA control packet is setup by the application to copy the whole memory range to the CRC modules PSA Signature Register. The DMA will be used in software trigger mode, polling the status of the DMA control packet or the status of the CRC module can be used to determine if the data compression has been completed. [Figure 5](#) show the setup with the DMA controller.

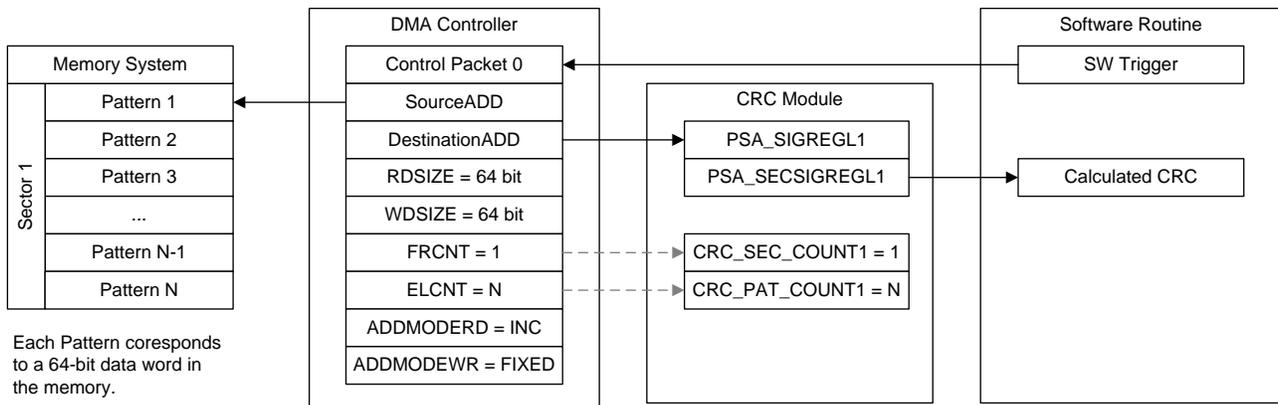


Figure 5. Semi-CPU Mode Polling DMA Setup

The DMA control packet is setup in a way that the DMA controller copies the memory area associated to a CRC table into the CRC modules PSA Signature Registers. The software can poll on the DMA's control packet status or the CRC modules Busy register to determine when the compression has been finished. The CRC modules Busy register is only functional if the Sector and Pattern count was setup in the CRC module. In that case, the CRC can be read from the PSA Sector Signature Registers.

3.6 Semi-CPU Mode Interrupt Driven

The setup for this mode is similar to the one from the Semi-CPU Mode Polling mode described in Section 3.5. The main difference is that the DMA gets triggered by a timer (RTI) and the compression complete interrupt is used to tell the software that the current memory range has been compressed. Figure 6 shows the setup with the DMA controller, RTI trigger and interrupt routine.

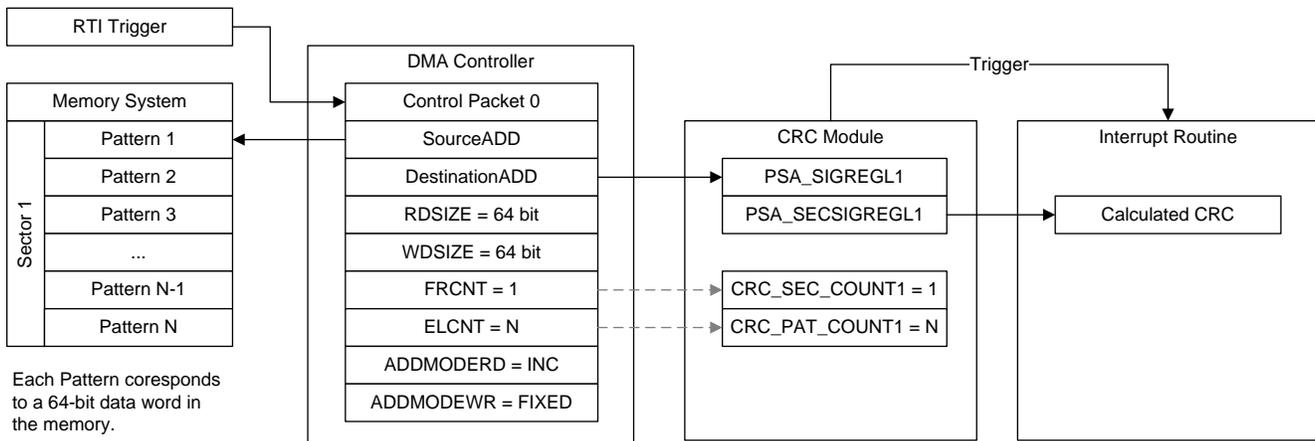


Figure 6. Semi-CPU Mode Interrupt Driven Setup

3.6.1 Using the Time Out Counter

The trigger by the RTI can be used to issue individual 64-bit DMA read and writes. With a proper setup of the trigger frequency, the needed bandwidth can be adjusted to the applications requirements. Also, the duration for completing the compression of a memory range can be pre-calculated and set to the applications requirements. Knowing the expected duration for the compression allows to setup the timers in the CRC module to act as a watchdog for the DMA and signaling timeout events to the application in case the compression takes longer than expected (fault condition).

The timeout counter inside the CRC module is operating on $HCLK / 64$, which means $200 \text{ MHz} / 64 = 3.125 \text{ MHz}$ - in case of the example provided for the RM48. The RTI compare 3 used in the same example operates on $HCLK / 2 / 10 / 10 = 1 \text{ MHz}$ or $1 \mu\text{s}$. This means that the preload value (Block Complete Timeout Preload Register) has to be set at least to:

$$CRC_{BCTOPLDx} = \frac{CRC_{PCOUNT_REGx} \times 10 \times 10 \times 2}{64} \quad (2)$$

Another way to calculate the timeout counter value is:

$$CRC_{BCTOPLDx} = \frac{CRC_{PCOUNT_REGx} \times t_{RTI_{CMPx}} \times f_{HCLK}}{64} \quad (3)$$

The example shown in [Section 3.6.2](#) demonstrates how to calculate the Block Complete Timeout Preload Register value.

3.6.2 Example, Sector Size = 32kB

CRC Channel 1 Pattern Counter Preload Register (note the sector size of 32kB):

$$CRC_{PCOUNT_REG1} = \frac{32\text{kB}}{8 \text{ Byte}} = 4096 \text{ (64 bit words)} \quad (4)$$

CRC Channel 1 Block Complete Timeout Preload Register:

$$CRC_{BCTOPLD1} = \frac{CRC_{PCOUNT_REG1} \times 10 \times 10 \times 2}{64} = \frac{4096 \times 10 \times 10 \times 2}{64} = 12800 \quad (5)$$

or

$$CRC_{BCTOPLD1} = \frac{CRC_{PCOUNT_REG1} \times t_{RTI_{CMP3}} \times f_{HCLK}}{64} = \frac{4096 \times 1\mu\text{s} \times 200\text{MHz}}{64} = 12800 \quad (6)$$

The value 12800 represents about 4 ms:

$$TimeOut = \frac{CRC_{BCTOPLD1} \times 64}{HCLK} = \frac{12800 \times 64}{200 \text{ MHz}} = 4 \text{ ms} \quad (7)$$

Compressing 32kB at a rate of 8 Byte (64-bit word) each microsecond will take:

$$TimeNeeded = \frac{SectorSize}{8 \text{ Byte}} \times t_{RTI_{CMP3}} = \frac{32\text{kB}}{8 \text{ Byte}} \times 1\mu\text{s} = 4 \text{ ms} \quad (8)$$

4 Results and Conclusion

[Table 2](#) shows the measurement results for the RM48 example project (Example1: CRC Software Full-CPU and Semi-CPU Modes). It is visible that the use of the CRC module (see [Section 1.2.2](#)) offers a great performance boost compared to a software-based CRC implementation (see [Section 1.2.1](#), compare first two lines). The performance can be even more optimized by using the DMA instead of the CPU for copying the data from the Flash memory into the CRC module (compare lines two and three). It should also be noted, that the CPU is free (idle in the example) for doing other task most of the time shown in line three (see [Section 1.2.3](#)), this is also true for the interrupt driven mode.

Table 2. Results Captured on RM48 (Example 1, 37kB)

	CPU Cycles	Duration @ 200 MHz	Scaled to kB
Software Mode	23328899	116.6 ms	3152.6 us/kB
Full-CPU Mode	127604	0.6 ms	17.2 us/kB
Semi-CPU Mode (Polling)	47500	0.2 ms	6.4 us/kB

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