



Consumer products with moving parts have undergone a transformation from being purely mechanical to electromechanical products with electronic controls using integrated circuits (ICs). One evolutionary example is the washing machine having had its humble beginnings as a stick – a paddle-shaped stick – that pounded the grime right out of the clothes laid against a river rock. Since medieval times, the washing machine has gone from a stick, to a tub and washboard, to adding a wringer, to motorizing the tub and wringer, and eventually to the automatic washer in 1947 that resembles today's product.

Today's appliances use many types of sensors to measure things like water level, knob selectors, and temperature. The introduction of the microcontroller (MCU) in 1990 made it possible to gather sensor information from appliances, to make informed decisions based on this new set of data. For example, when vibrations cause clothes to shift to one side of a washing machine drum during the spin cycle, the MCU slowly rotates the drum in oscillating motions until the clothes are evenly distributed before proceeding with high-speed spinning. This prevents damage to the washing machine and to its surroundings.

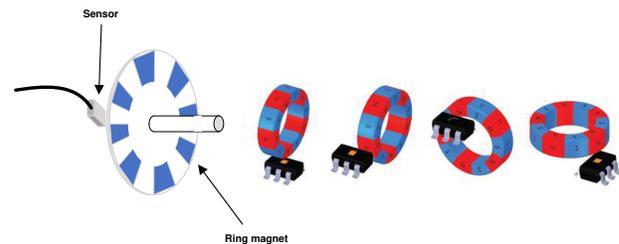
This application brief shares the three sensing innovations enabled by Hall-effect and inductive position sensors that can improve functionality, reliability, accuracy, and system flexibility.

## Sensing Solution No. 1 – Rotary Encoding with Added Placement Flexibility

In washing machines and dryers, rotary encoding determines the speed and direction of the spinning drum – information that is essential for the MCU to manage different wash modes and spin cycles. Implementing rotary encoding with a single device that integrates true 2D latches provides higher flexibility in sensor placement compared to sensors with two Hall-effect latches. 2D latches have the capability to monitor all three sensitivity axes, allowing a designer to choose the specific device with the two direction sensitivities needed depending on the orientation of the magnet.

Without this capability, two separate sensors would pose a challenge in a system design, because in some cases you may have to orient one sensor in one direction and the other sensor in another direction.

Although rotary encoding is not new, having the ability to place the IC where it is most convenient is an advantage that many dual-latch Hall-effect sensors do not possess. Additionally, having 2D latches onboard enables further flexibility in ring magnet pole widths, as shown in [Figure 1](#). Check out the [TMAG5110](#) and [TMAG5111](#) dual 2D latches that are suited to provide digital quadrature signatures with ease and flexibility.



**Figure 1. Rotary Encoding Using Ring Magnets, and Various Sensor Placements**

## Sensing Solution No. 2 – Touch Buttons with Force Detection

It should not come as a surprise that home appliances work in not-so-clean environments. If you are like most people, you make a mess when cooking! A hermetically sealed touch button is the best solution for environments prone to food spills (cook top) and grease buildup (range hood). Inductive technology, which indirectly, but very precisely, measures the distance from the sensor coil to a metal touch button, is a great option for this use case because it is possible to create the touch buttons using a solid sheet of metal, isolating the exterior environment from the sensor. Due to this technology's inherent capability to measure targets in micrometer range, this allows for very precise force detection that offers additional button functionality beyond the simple ON/OFF. [Figure 2](#) shows how the implementation of inductive technology can create a seamless interface.



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