

DLP3030-Q1 0.3-Inch WVGA DMD for Automotive Interior Display

1 Features

- Automotive qualified
- 0.3-inch diagonal micromirror array
 - 7.6- μm micromirror pitch
 - $\pm 12^\circ$ micromirror tilt angle (relative to flat state)
 - Side illumination for optimized efficiency
- WVGA (864 × 480) resolution
- Polarization independent spatial light modulator
 - Compatible with LED or laser light sources
 - Image viewable with polarized glasses
- Low-power consumption: 105-mW (typical)
- Operating temperature range: -40°C to 105°C
- Hermetic package with 2.5 $^\circ\text{C/W}$ thermal efficiency
- JTAG boundary scan to allow in-system validation
- Compatible with the DLPC120-Q1 automotive DMD controller
- 78-MHz DDR DMD interface

2 Applications

- Wide field of view and augmented reality head-up display (HUD)
- High resolution headlight
- Interior projection display and lighting

3 Description

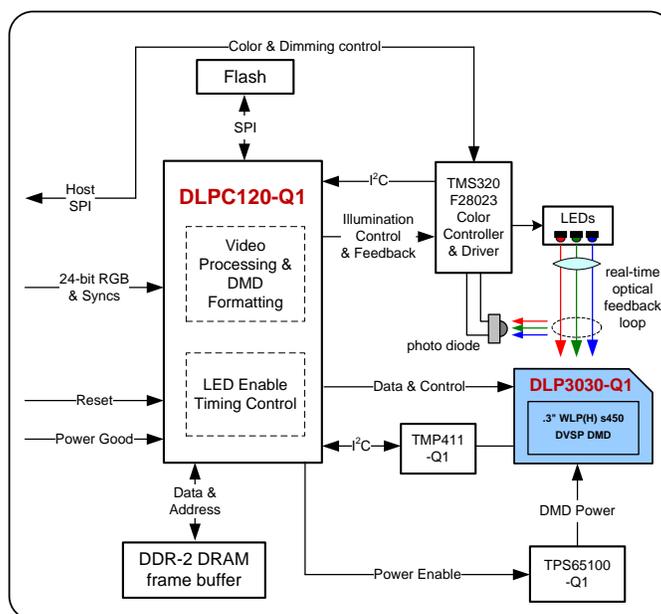
The DLP3030-Q1 Automotive DMD is primarily targeted for automotive head-up display (HUD) applications with very large field of view or augmented reality capability requiring long focal distances. This chipset can be coupled with LEDs or lasers to create deep saturated colors with over 125% NTSC color gamut with support for 24-bit RGB video input. In addition, the chipset enables high brightness (15,000-cd/m² typical) HUD systems with wide dynamic range, and fast switching speeds that do not vary with temperature. As used in the TI reference design, very high dynamic range over 5000:1 can be achieved to meet the operating range of an automotive HUD system for bright daylight and dark night time driving conditions.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
DLP3030-Q1	FYJ (149)	22.30 mm × 32.20 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

DLP® DLP3030-Q1 Block System Diagram



Copyright © 2017, Texas Instruments Incorporated



Table of Contents

1	Features	1	7.5	DMD Image Quality Specification	28
2	Applications	1	7.6	Definition of Micromirror Landed-On/Landed-Off Duty Cycle	28
3	Description	1	8	Application and Implementation	29
4	Revision History	2	8.1	Application Information	29
5	Pin Configuration and Functions	4	8.2	Typical Application	29
6	Specifications	7	8.3	Application Mission Profile Consideration	30
6.1	Absolute Maximum Ratings	7	9	Power Supply Recommendations	31
6.2	Storage Conditions	7	9.1	Power Supply Sequencing Requirements	31
6.3	ESD Ratings	7	10	Layout	33
6.4	Recommended Operating Conditions	8	10.1	Layout Guidelines	33
6.5	Thermal Information	10	10.2	Temperature Diode Pins	33
6.6	Electrical Characteristics	10	10.3	Layout Example	33
6.7	Timing Requirements	12	11	Device and Documentation Support	34
6.8	Switching Characteristics	16	11.1	Device Support	34
6.9	System Mounting Interface Loads	16	11.2	Documentation Support	35
6.10	Physical Characteristics of the Micromirror Array	17	11.3	Receiving Notification of Documentation Updates	35
6.11	Optical Characteristics of the Micromirror Array	18	11.4	Community Resources	35
6.12	Window Characteristics	19	11.5	Trademarks	35
6.13	Chipset Component Usage Specification	19	11.6	Electrostatic Discharge Caution	35
7	Detailed Description	20	11.7	Device Handling	35
7.1	Overview	20	11.8	Glossary	35
7.2	Functional Block Diagram	20	12	Mechanical, Packaging, and Orderable Information	35
7.3	Feature Description	20			
7.4	Optical Performance	27			

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

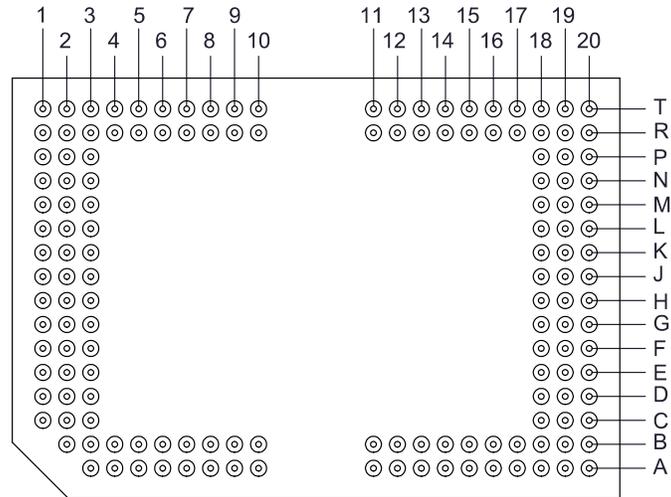
Changes from Revision A (March 2018) to Revision B	Page
• Added illumination overfill maximum allowable heat load specifications, table notes, and figure in <i>Recommended Operating Conditions</i>	9
• Added calculation for array width and height with respect to number of active columns and rows in the Physical Characteristics of the Micromirror Array table	17
• Deleted axis-of-rotation specification from Optical Characteristics of the Micromirror Array table, as it was deemed unnecessary for customer designs	18
• Deleted illumination overfill row and corresponding table note in the Window Characteristics table	19
• Changed description of illumination overfill in the <i>Illumination Overfill and Alignment</i> section and added reference to <i>Recommended Operating Conditions</i> overfill specification	27
• Added the <i>Device Handling</i> section	35

Changes from Original (November 2017) to Revision A	Page
• Changed the device status from <i>Advance Information</i> to <i>Production Data</i>	1
• Changed package designator from CPGA to FYJ	1
• Added comment to ground V_{CCH} and V_{SSH} pins	6
• Changed maximum DMD storage temperature from 105°C to 125°C in <i>Storage Conditions</i> table	7
• Changed I_{OFFSET} from 2.16 mA to 2.93 mA in <i>Electrical Characteristics</i> table	10
• Changed I_{RESET} from 1.5 mA to -2.00 mA in <i>Electrical Characteristics</i> table	10
• Changed P_{OFFSET} from 13.2 mW to 25.64 mW in <i>Electrical Characteristics</i> table	11
• Changed P_{BIAS} from 37.3 mW to 37.95 mW in <i>Electrical Characteristics</i> table	11

- Changed P_{RESET} from 15.8 mW to 21.00 mW in *Electrical Characteristics* table 11
- Changed P_{TOTAL} from 236.6 mW to 254.77 mW in *Electrical Characteristics* table 11
- Added table note in *Optical Parameters* table..... 18
- Changed device marking number in *Device Markings* section..... 34

5 Pin Configuration and Functions

**FYJ Package
149-Pin CPGA
Bottom View**



Pin Configurations and Functions

PIN		I/O	DESCRIPTION	TRACE, mm ⁽¹⁾					
NAME	NO.								
DATA(0)	F18	LVCMOS input	Data bus. Synchronous to rising edge and falling edge of DCLK.	8.059					
DATA(1)	F20								
DATA(2)	G20								
DATA(3)	G19								
DATA(4)	H19								
DATA(5)	G18								
DATA(6)	J20								
DATA(7)	H20								
DATA(8)	J19								
DATA(9)	K18								
DATA(10)	K19								
DATA(11)	L20								
DATA(12)	L18								
DATA(13)	K20								
DATA(14)	M18				LVCMOS output	Data clock.	10.939		
DCLK	N18								
LOADB	M20	Parallel latch load enable. Synchronous to rising edge and falling edge of DCLK.	6.596						
SCTRL	N19	Serial control (sync). Synchronous to rising edge and falling edge of DCLK.							
TRC	M19	Toggle rate control. Synchronous to rising edge and falling edge of DCLK.							
DAD_BUS	A7	Reset control serial bus. Synchronous to rising edge of SAC_CLK.		10.413					
RESET_OEZ	A5	Active low. Output enable signal for internal reset driver circuitry.							
RESET_STROBE	A10	Rising edge on RESET_STROBE latches in the control signals.							
SAC_BUS	B9	Stepped address control serial bus. Synchronous to rising edge of SAC_CLK.							
SAC_CLK	A8	Stepped address control clock.						12.586	
TCK	M2	JTAG clock.							
TDI	N3	JTAG data input. Synchronous to rising edge of TCK. Bond pad connects to internal pull up resistor.							
TDO	M3	JTAG data output. Synchronous to falling edge of TCK. Tri-state failsafe output buffer.							12.668
TMS	R5	JTAG mode select. Synchronous to rising edge of TCK. Bond pad connects to internal pull up resistor.							
TEMP_MINUS	T10	Analog Input							
TEMP_PLUS	T11								
No Connect (Unused)	A3, A18, A19, A20, B2, B10, B18, B19, B20, C1, C20, D18, D19, D20, E18, E19, E20, N20, P20, R18, R19, R20, T18, T19, T20	N/A			N/A	N/A			

(1) Propagation delay is 10.24 ps/mm for the DMD Series 450 ceramic package trace lengths.

Pin Configurations and Functions (continued)

PIN		I/O	DESCRIPTION	TRACE, mm ⁽¹⁾
NAME	NO.			
V _{BIAS} ⁽²⁾	F3, K3, L3	Power	Power supply for positive bias level of mirror reset signal.	N/A
V _{CC} ⁽²⁾	A9, A12, A14, A16, B13, B16, R12, R13, R16, R17, T13, T14, T16		Power supply for low voltage CMOS logic. Power supply for normal high voltage at mirror address electrodes. Power supply for offset level of mirror reset signal during power down.	N/A
V _{CCH}	P3, R3, T3, T4, T5, T6	Connect to GND	Reserved pin.	N/A
V _{OFFSET} ⁽²⁾	D1, E1, M1, N1	Power	Power supply for high voltage CMOS logic. Power supply for stepped high voltage at mirror address electrodes. Power supply for offset level of mirror reset signal.	N/A
V _{REF} ⁽²⁾	B11, B12		Power supply for low voltage CMOS DDR interface.	N/A
V _{RESET} ⁽²⁾	B3, C3, E3		Power supply for negative reset level of mirror reset signal.	N/A
V _{SS} ⁽²⁾	A6, A11, A13, A15, A17, B4, B5, B8, B14, B15, B17, C2, C18, C19, F1, F2, F19, H1, H2, H3, H18, J18, K1, K2, L19, N2, P18, P19, R4, R14, R15, T7, T9, T12, T15, T17		Common return for all power.	N/A
V _{SSH}	P1, P2, R1, R2, T1, T2	Connect to GND	Reserved pin.	N/A
RESERVED_BIM	T8	Connect to GND	Bond pad connects to internal pull down resistor.	N/A
RESERVED_DT	R7			N/A
RESERVED_RM	E2			N/A
RESERVED_R(0)	G1	Do not connect	Bond pad connects to 250k pull down resistor. Manufacturing test.	N/A
RESERVED_R(1)	G2			N/A
RESERVED_R(2)	G3			N/A
RESERVED_R(3)	J1			N/A
RESERVED_R(4)	J2			N/A
RESERVED_R(5)	J3			N/A
RESERVED_R(6)	L1			N/A
RESERVED_R(7)	L2			N/A
RESERVED_PFE	R6	Connect to GND	Bond pad connects to internal pull down resistor.	N/A
RESERVED_RA(0)	B6			N/A
RESERVED_RA(1)	D3			N/A
RESERVED_RA(2)	B7			N/A
RESERVED_RS(0)	A4			N/A
RESERVED_RS(1)	D2			N/A
RESERVED_SO	R9	Do not connect	Tri-state failsafe output buffer.	N/A
RESERVED_TP(0)	R8	Connect to GND	Manufacturing test.	N/A
RESERVED_TP(1)	R10			N/A
RESERVED_TP(2)	R11			N/A

(2) The following power supplies are required to operate the DMD: V_{BIAS}, V_{CC}, V_{OFFSET}, V_{REF}, V_{RESET}, V_{SS}.

6 Specifications

6.1 Absolute Maximum Ratings

See ⁽¹⁾

		MIN	MAX	UNIT
SUPPLY VOLTAGE				
V _{REF}	LVC MOS logic supply voltage ⁽²⁾	−0.5	4	V
V _{CC}	LVC MOS logic supply voltage ⁽²⁾	−0.5	4	V
V _{OFFSET}	Mirror electrode and HVCMOS voltage ⁽²⁾	−0.5	8.75	V
V _{BIAS}	Mirror electrode voltage	−0.5	17	V
V _{BIAS} − V _{OFFSET}	Supply voltage delta ⁽³⁾		8.75	V
V _{RESET}	Mirror electrode voltage	−11	0.5	V
Input voltage: other Inputs	See ⁽²⁾	−0.5	V _{REF} + 0.3	V
f _{DCLK}	Clock frequency	60	80	MHz
I _{TEMP_DIODE}	Temperature diode current		500	μA
ENVIRONMENTAL				
Operating DMD array temperature (T _{ARRAY}) (monitored by TMP411-Q1 via DLPC120-Q1)	See ⁽⁴⁾ and <i>Active Array Temperature</i>	−40	105	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. Unless otherwise indicated, these are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to GND (V_{SS}). V_{BIAS}, V_{CC}, V_{OFFSET}, V_{REF}, V_{RESET}, and V_{SS} are required to operate the DMD.
- (3) To prevent excess current, the supply voltage delta |V_{BIAS} − V_{OFFSET}| must be less than or equal to 8.75 V.
- (4) Contact TI application engineering for more details about the DMD modeled use profile.

6.2 Storage Conditions⁽¹⁾

Applicable for the DMD as a component or non-operating in a system.

		MIN	MAX	UNIT
T _{stg}	DMD storage temperature	−40	125	°C

- (1) As a best practice, TI recommends storing the DMD in a temperature and humidity controlled environment.

6.3 ESD Ratings⁽¹⁾

		VALUE	UNIT	
V _(ESD) Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽²⁾	±2000	V	
	Charged-device model (CDM), per JESD22-C101 ⁽³⁾	All pins		±500
		Corner pins		±750

- (1) All CMOS devices require proper electrostatic discharge (ESD) handling procedures.
- (2) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (3) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.4 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
SUPPLY VOLTAGE RANGE					
V _{REF}	LVC MOS interface power supply voltage ⁽¹⁾	1.65	1.8	1.95	V
V _{CC}	LVC MOS logic power supply voltage ⁽¹⁾	2.25	2.5	2.75	V
V _{OFFSET}	Mirror electrode and HVCMOS voltage ⁽¹⁾	8.25	8.5	8.75	V
V _{BIAS}	Mirror electrode voltage	15.5	16	16.5	V
V _{BIAS} – V _{OFFSET}	Supply voltage delta ⁽²⁾			8.75	V
V _{RESET}	Mirror electrode voltage	–9.5	–10	–10.5	V
V _P VT+	Positive going threshold voltage	0.4 × V _{REF}		0.7 × V _{REF}	V
V _N VT–	Negative going threshold voltage	0.3 × V _{REF}		0.6 × V _{REF}	V
V _H ΔVT	Hysteresis voltage (V _p – V _n)	0.1 × V _{REF}		0.4 × V _{REF}	V
I _{OH_TDO}	High level output current @ V _{oh} = 2.25 V, TDO, V _{cc} = 2.25 V			–2	mA
I _{OL_TDO}	Low level output current @ V _{ol} = 0.4 V, TDO, V _{cc} = 2.25 V			2	mA
TEMPERATURE DIODE					
I _{TEMP_DIODE}	Max current source into temperature diode ⁽³⁾			120	μA
ENVIRONMENTAL					
ILL _{UV} ⁽⁴⁾	Illumination, wavelength < 395 nm		0.68	2.0	mW/cm ²
ILL _{IR}	Illumination, wavelength > 800 nm			10	mW/cm ²
T _{ARRAY}	Operating DMD array temperature (monitored by TMP411-Q1 via DLPC120-Q1) ⁽⁵⁾⁽⁶⁾⁽⁷⁾	–40		105	°C

(1) V_{BIAS}, V_{CC}, V_{OFFSET}, V_{REF}, V_{RESET}, V_{SS} are required to operate the DMD.

(2) To prevent excess current, the supply voltage delta |V_{BIAS} – V_{OFFSET}| must be less than or equal to 8.75 V.

(3) Temperature Diode is to allow accurate measurement of the DMD array temperature during operation.

(4) The maximum operation conditions for operating temperature and illumination UV shall not be implemented simultaneously.

(5) DMD active array temperature can be calculated as shown in [Active Array Temperature](#) section. Additionally, the DMD array temperature is monitored in the system using the TMP411-Q1 and DLPC120-Q1 as shown in the system block diagram.

(6) For applications that are higher brightness (> 1000 lumens) or underfill the active array optically, the TMP411-Q1 and temperature sensing diode are not sufficient to determine maximum array temperature. Contact TI Applications Engineering for array temperature calculation methods for this application.

(7) TI assumes a normal automotive operating profile without continuous operation at either minimum or maximum temperatures. Operating profile information for device duty cycle and temperature may be provided if requested.

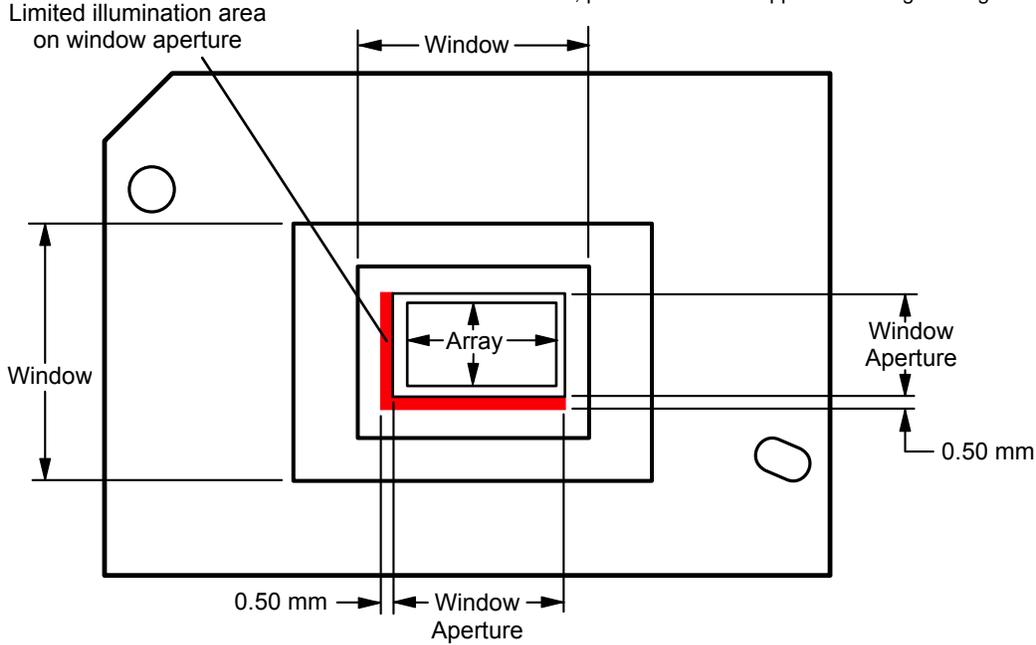
Recommended Operating Conditions (continued)

Over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
ILL _{OVERFILL} ⁽⁸⁾	Illumination overfill maximum allowable heat load on left and bottom sides of the aperture, T _{ARRAY} < 75°C ⁽⁹⁾			26	mW/mm ²
	Illumination overfill maximum allowable heat load on left and bottom sides of the aperture, T _{ARRAY} > 75°C ⁽⁹⁾			20	mW/mm ²

(8) See *Illumination Overfill and Alignment* section.

(9) Heat load outside the aperture in the red areas shown in the figure below should not exceed the values listed in the table. These values assume a uniform distribution. For a non-uniform distribution, please contact TI Applications Engineering for additional information.



6.5 Thermal Information

THERMAL METRIC ⁽¹⁾		DLP3030-Q1	UNIT
		FYJ (CPGA)	
		149 PINS	
Thermal resistance	Active area to test point 1 (TP1) ⁽¹⁾⁽²⁾	2.5	°C/W

- (1) The total heat load on the DMD is a combination of the incident light absorbed by the active area and electrical power dissipation of the array. See [Active Array Temperature](#) section. Optical systems should be designed to minimize the light energy falling outside the active array area since any additional thermal load in this area can significantly degrade the reliability of the device.
- (2) Thermal resistance assumes 16.3% optical overfill of the active array. Contact TI Applications Engineering for thermal resistance with an optically underfilled array.

6.6 Electrical Characteristics

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

PARAMETER		TEST CONDITIONS ⁽²⁾	MIN	TYP	MAX	UNIT
V _{OH}	High level output voltage	V _{CC} = 2.25 V I _{OH} = -8 mA	1.7			V
V _{OH2}	High level output voltage ⁽³⁾	V _{REF} = 1.8 V I _{OH} = -2 mA	1.44			V
V _{OL}	Low level output voltage	V _{CC} = 2.75 V I _{OL} = 8 mA			0.4	V
V _{OL2}	Low level output voltage ⁽³⁾	V _{REF} = 1.8 V I _{OL} = 2 mA			0.36	V
I _{OZ}	Output high impedance current	V _{REF} = 1.95 V V _{OL} = 0 V	-10			μA
		V _{REF} = 1.95 V V _{OH} = V _{REF}			10	
I _{IL}	Low level input current ⁽⁴⁾	V _{REF} = 1.95 V V _I = 0 V	-5			μA
I _{IH}	High level input current ⁽⁴⁾	V _{REF} = 1.95 V V _I = V _{REF}			6	μA
I _{IL2}	Low level input current ⁽⁵⁾	V _{REF} = 1.95 V V _I = 0 V	-785			μA
I _{IH2}	High level input current ⁽⁵⁾	V _{REF} = 1.95 V V _I = V _{REF}			6	μA
I _{IL3}	Low level input current ⁽⁶⁾	V _{REF} = 1.95 V V _I = 0 V	-5			μA
I _{IH3}	High level input current ⁽⁶⁾	V _{REF} = 1.95 V V _I = V _{REF}			785	μA
CURRENT						
I _{REF}	Current at V _{REF} = 1.95 V	f _{DCLK} = 80 MHz			2.80	mA
I _{CC}	Current at V _{CC} = 2.75 V	f _{DCLK} = 80 MHz			59.90	mA
I _{OFFSET}	Current at V _{OFFSET} = 8.75 V				2.93	mA
I _{BIAS}	Current at V _{BIAS} = 16.5 V				2.30	mA
I _{RESET}	Current at V _{RESET} = -10.5 V				-2.00	mA

- (1) Device electrical characteristics are over [Recommended Operating Conditions](#) unless otherwise noted.
- (2) All voltage values are with respect to the ground pins (V_{SS}).
- (3) Specification is for LVCMOS JTAG output pin TDO.
- (4) Specification is for LVCMOS input pins, which do not have pull up or pull down resistors. See [Pin Configuration and Functions](#) section.
- (5) Specification is for LVCMOS input pins which do have pull up resistors (JTAG: TDI, TMS). See [Pin Configuration and Functions](#) section.
- (6) Specification is for LVCMOS input pins which do have pull down resistors. See [Pin Configuration and Functions](#) section.

Electrical Characteristics (continued)

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

PARAMETER		TEST CONDITIONS ⁽²⁾	MIN	TYP	MAX	UNIT
POWER⁽⁷⁾						
P _{REF}	Power at V _{REF} = 1.95 V	f _{DCLK} = 80 MHz			5.46	mW
P _{CC}	Power at V _{CC} = 2.75 V	f _{DCLK} = 80 MHz			164.73	mW
P _{OFFSET}	Power at V _{OFFSET} = 8.75 V				25.64	mW
P _{BIAS}	Power at V _{BIAS} = 16.5 V				37.95	mW
P _{RESET}	Power at V _{RESET} = -10.5 V				21.00	mW
P _{TOTAL}	Total power at nominal conditions	f _{DCLK} = 80 MHz		105	254.77	mW
CAPACITANCE						
C _{IN}	Input pin capacitance	f = 1 MHz			20	pF
C _A	Analog pin capacitance (TEMP_PLUS and TEMP_MINUS pins)	f = 1 MHz			65	pF
C _O	Output pin capacitance	f = 1 MHz			20	pF

(7) The following power supplies are all required to operate the DMD: V_{DD}, V_{DDI}, V_{OFFSET}, V_{BIAS}, V_{RESET}. All V_{SS} connections are also required.

6.7 Timing Requirements

Over *Recommended Operating Conditions* unless otherwise noted.

		MIN	NOM	MAX	UNIT
DMD MIRROR AND SRAM CONTROL LOGIC SIGNALS					
t_{SU}	Setup time SAC_BUS low before SAC_CLK \uparrow	1.0			ns
t_H	Hold time SAC_BUS low after SAC_CLK \uparrow	1.0			ns
t_{SU}	Setup time DAD_BUS high before SAC_CLK \uparrow	1.0			ns
t_H	Hold time DAD_BUS after SAC_CLK \uparrow	1.0			ns
t_C	Cycle time SAC_CLK	12.5		16.67	ns
t_W	Pulse width 50% to 50% reference points: SAC_CLK high or low	5.0			ns
t_R	Rise time 20% to 80% reference points: SAC_CLK			2.5	ns
t_F	Fall time 80% to 20% reference points: SAC_CLK			2.5	ns
DMD DATA PATH AND LOGIC CONTROL SIGNALS					
t_{SU}	Setup time DATA(14:0) before DCLK \uparrow or DCLK \downarrow	1.0			ns
t_H	Hold time DATA(14:0) after DCLK \uparrow or DCLK \downarrow	1.0			ns
t_{SU}	Setup time SCTRL before DCLK \uparrow or DCLK \downarrow	1.0			ns
t_H	Hold time SCTRL after DCLK \uparrow or DCLK \downarrow	1.0			ns
t_{SU}	Setup time TRC before DCLK \uparrow or DCLK \downarrow	1.0			ns
t_H	Hold time TRC after DCLK \uparrow or DCLK \downarrow	1.0			ns
t_{SU}	Setup time LOADB low before DCLK \uparrow	1.0			ns
t_H	Hold time LOADB low after DCLK \downarrow	1.0			ns
t_{SU}	Setup time RESET_STROBE high before DCLK \uparrow	1.0			ns
t_H	Hold time RESET_STROBE after DCLK \uparrow	3.5			ns
t_C	Cycle time DCLK	12.5		16.67	ns
t_W	Pulse width 50% to 50% reference points: DCLK high or low	5.0			ns
$t_{W(L)}$	Pulse width 50% to 50% reference points: LOADB low	7.0			ns
$t_{W(H)}$	Pulse width 50% to 50% reference points: RESET_STROBE high	7.0			ns
t_R	Rise time 20% to 80% reference points: DCLK, DATA, SCTRL, TRC, LOADB			2.5	ns
t_F	Fall time 80% to 20% reference points: DCLK, DATA, SCTRL, TRC, LOADB			2.5	ns
JTAG BOUNDARY SCAN CONTROL LOGIC SIGNALS					
f_{TCK}	Clock frequency TCK			10	MHz
t_C	Cycle time TCK	100			ns
t_W	Pulse width 50% to 50% reference points: TCK high or low	10			ns
t_{SU}	Setup time TDI valid before TCK \uparrow	5			ns
t_H	Hold time TDI valid after TCK \uparrow	25			ns
t_{SU}	Setup time TMS valid before TCK \uparrow	5			ns
t_H	Hold time TMS valid after TCK \uparrow	25			ns
t_R	Rise time 20% to 80% reference points: TCK, TDI, TMS			2.5	ns
t_F	Fall time 80% to 20% reference points: TCK, TDI, TMS			2.5	ns

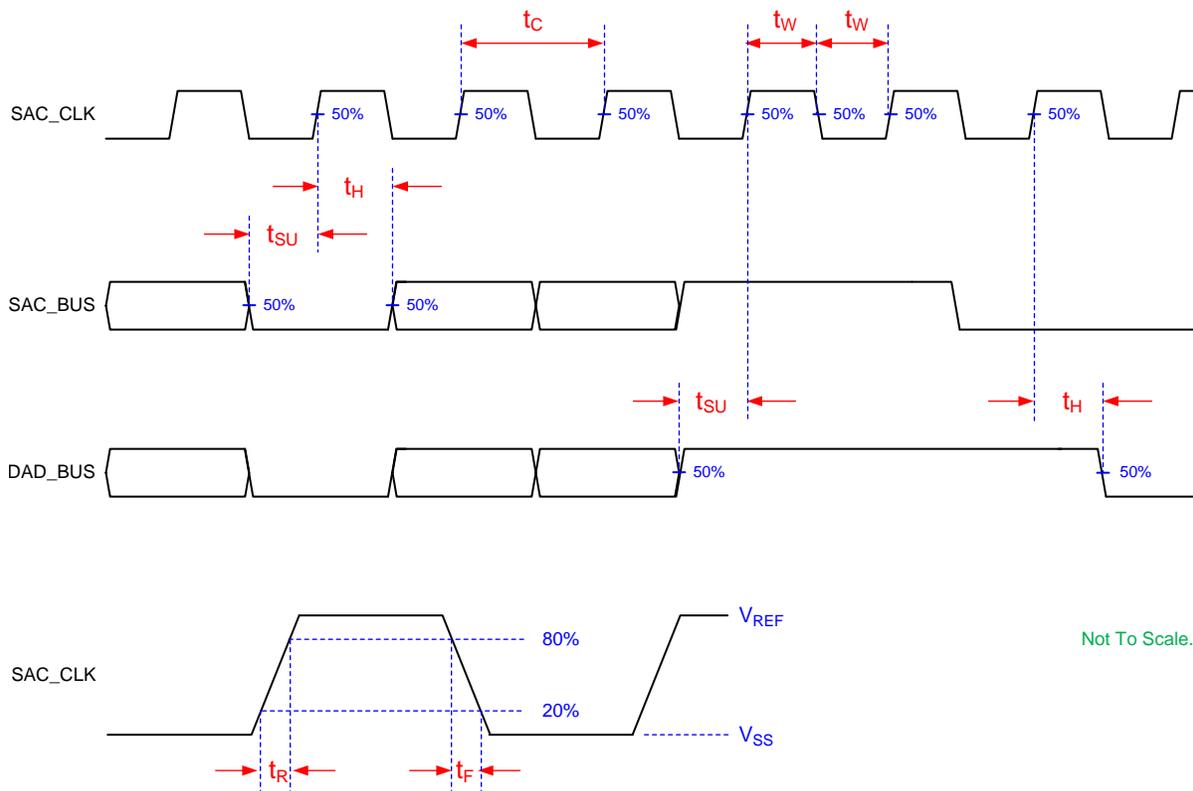


Figure 1. DMD Mirror and SRAM Control Logic Timing Requirements

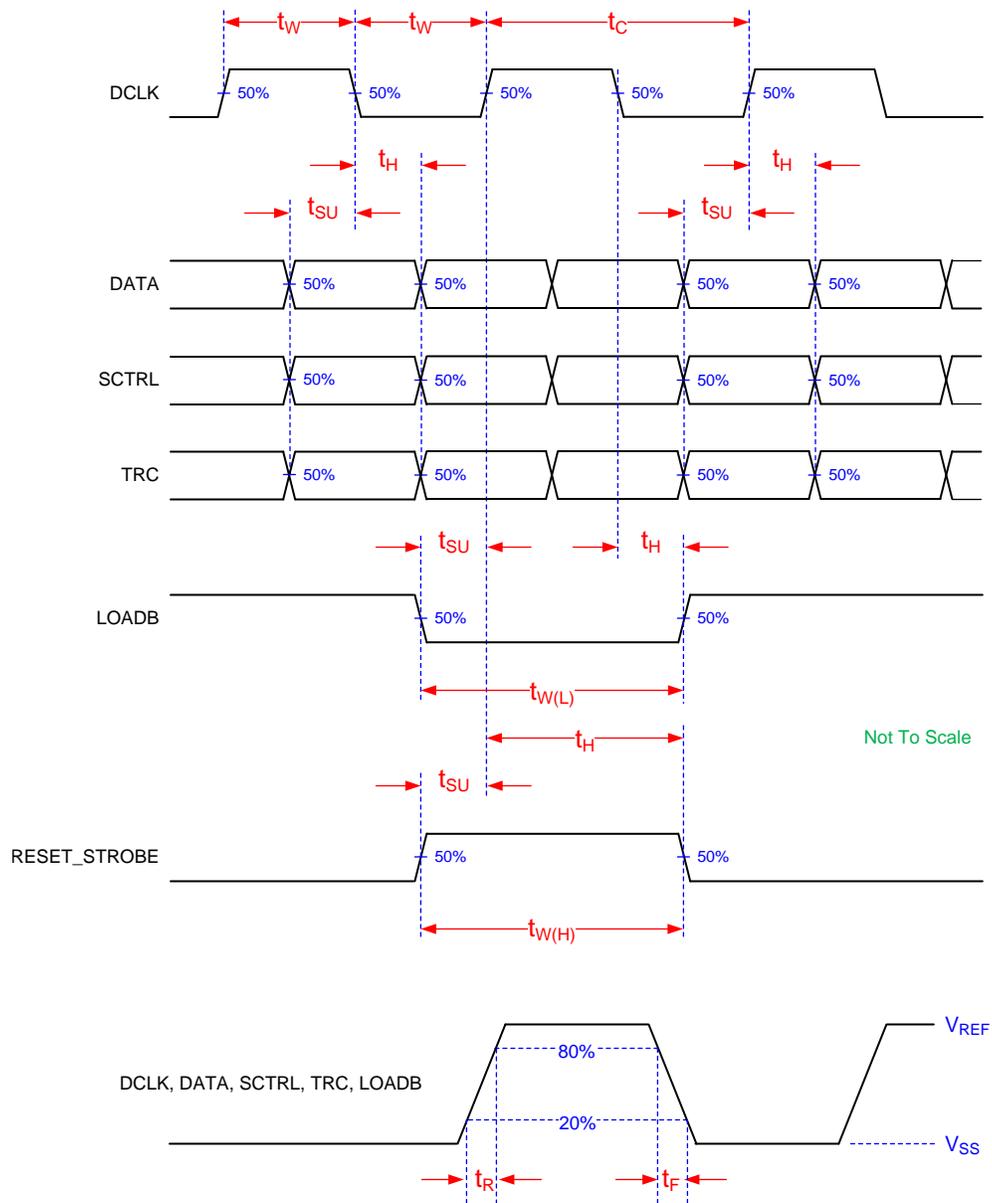


Figure 2. DMD Data Path and Control Logic Timing Requirements

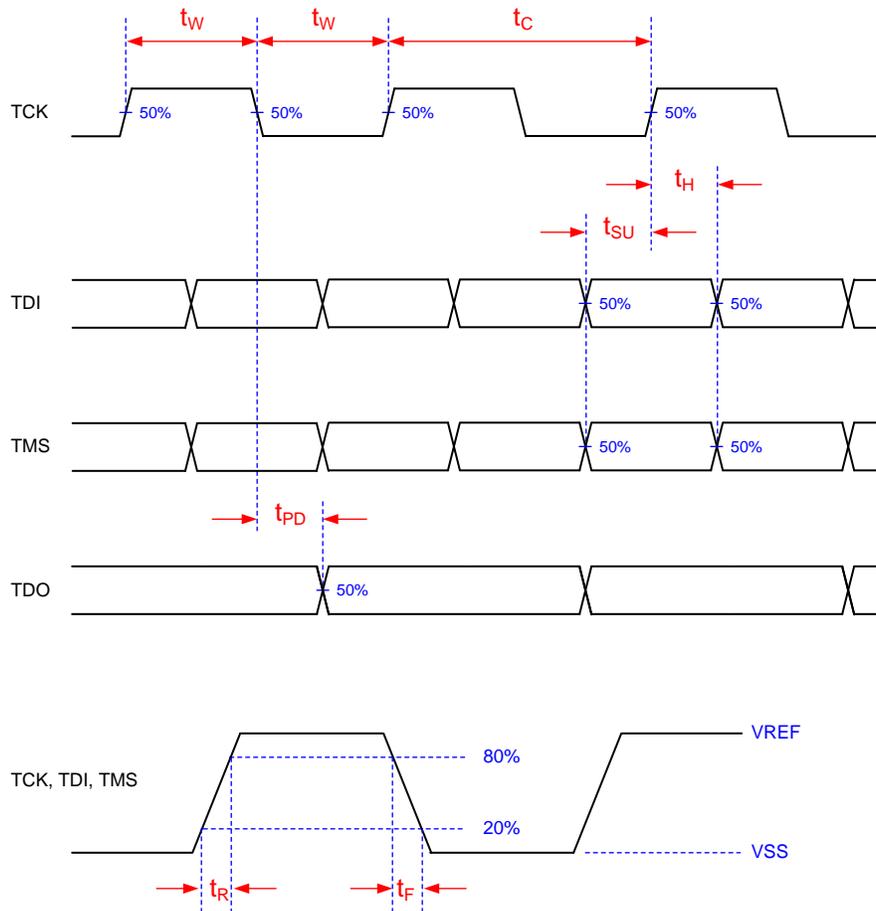


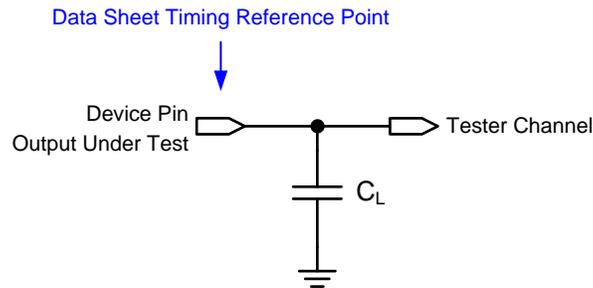
Figure 3. JTAG Boundary Scan Control Logic Timing Requirements

6.8 Switching Characteristics⁽¹⁾

Over operating free-air temperature range (unless otherwise noted).

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_{PD} Output propagation, clock to Q (see Figure 3)	$C_L = 11$ pF, from (Input) falling edge of TCK to (Output) TDO. See Figure 3.	3		25	ns

(1) Device electrical characteristics are over *Recommended Operating Conditions* unless otherwise noted.



See *Micromirror Array* section for more information.

Figure 4. Test Load Circuit for Output Propagation Measurement

6.9 System Mounting Interface Loads

PARAMETER	MIN	NOM	MAX	UNIT
Condition 1:				
Uniformly distributed within the Thermal Interface Area shown in Figure 5			11.30	kg
Uniformly distributed within the Electrical Interface Area shown in Figure 5			11.34	kg
Condition 2:				
Uniformly distributed within the Thermal Interface Area shown in Figure 5			0	kg
Uniformly distributed within the Electrical Interface Area shown in Figure 5			22.64	kg

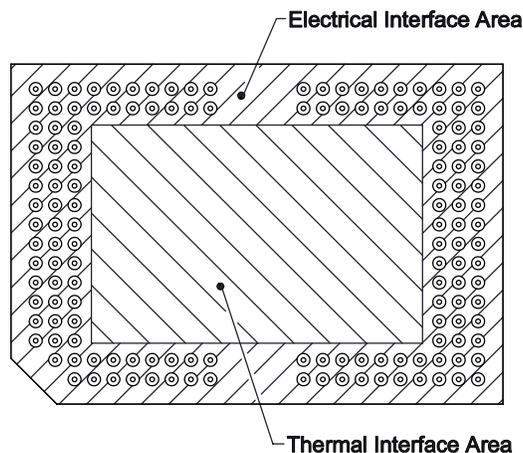


Figure 5. System Interface Loads

6.10 Physical Characteristics of the Micromirror Array

PARAMETER		VALUE	UNIT																
N	Number of active columns	See Figure 6	684	micromirrors															
M	Number of active rows	See Figure 6	608	micromirrors															
ϵ	Micromirror (pixel) pitch – diagonal	See Figure 7	7.6	μm															
P	Micromirror (pixel) pitch – horizontal and vertical	See Figure 7	10.8	μm	Micromirror active array width		$P \times M + P / 2$; see Figure 6	6.5718	mm	Micromirror active array height		$(P \times N) / 2 + P / 2$; see Figure 6	3.699	mm	Micromirror active border		Pond of micromirror (POM) ⁽¹⁾	10	micromirrors/side
Micromirror active array width		$P \times M + P / 2$; see Figure 6	6.5718	mm															
Micromirror active array height		$(P \times N) / 2 + P / 2$; see Figure 6	3.699	mm															
Micromirror active border		Pond of micromirror (POM) ⁽¹⁾	10	micromirrors/side															

(1) The structure and qualities of the border around the active array includes a band of partially functional micromirrors called the POM. These micromirrors are structurally and/or electrically prevented from tilting toward the bright or ON state, but still require an electrical bias to tilt toward OFF.

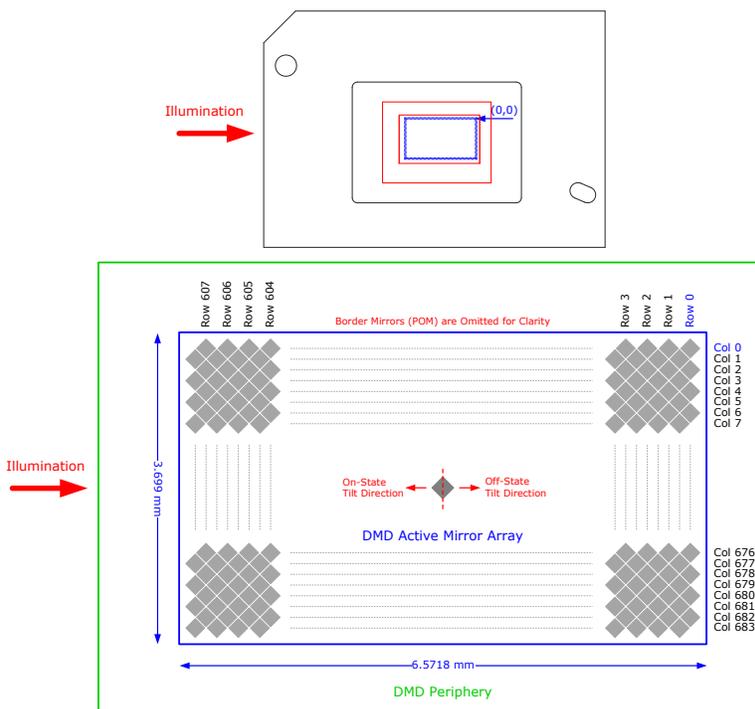


Figure 6. Micromirror Array Physical Characteristics

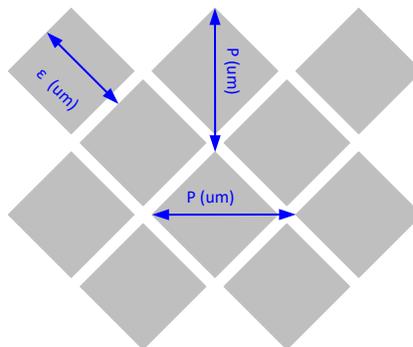


Figure 7. Mirror (Pixel) Pitch

6.11 Optical Characteristics of the Micromirror Array

Table 1. Optical Parameters⁽¹⁾

PARAMETER	MIN	NOM	MAX	UNIT
α Micromirror Tilt Angle, landed (on-state or off-state) (see ⁽²⁾ and Figure 8)		12		°
β Micromirror Tilt Angle Variation, device to device (see ⁽²⁾ and Figure 8)	-1		1	°
DMD Efficiency, 420 nm – 680 nm (see ⁽³⁾)		66%		

- (1) Optical parameters are characterized at 25°C.
- (2) Mirror Tilt: Limits on variability of mirror tilt are critical in the design of the accompanying optical system. Variations in tilt angle within a device may result in apparent non-uniformities, such as line pairing and image mottling, across the projected image especially at higher system F/#. Variations in the average tilt angle between devices may result in colorimetry, brightness, and system contrast variations.
- (3) DMD efficiency is measured photopically under the following conditions: 24° illumination angle, F/2.4 illumination and collection apertures, uniform source spectrum (halogen), uniform pupil illumination, the optical system is telecentric at the DMD, and the efficiency numbers are measured with 100% electronic mirror duty cycle and do not include system optical efficiency or overfill loss. Note that this number is measured under conditions described above and deviations from these specified conditions could result in a different efficiency value in a different optical system. The factors that can influence the DMD efficiency related to system application include: light source spectral distribution and diffraction efficiency at those wavelengths (especially with discrete light sources such as LEDs or lasers), and illumination and collection apertures (F/#) and diffraction efficiency. The interaction of these system factors as well as the DMD efficiency factors that are not system dependent are described in detail in the *DMD Optical Efficiency Application Note*, which can be accessed by contacting TI Applications Engineering.

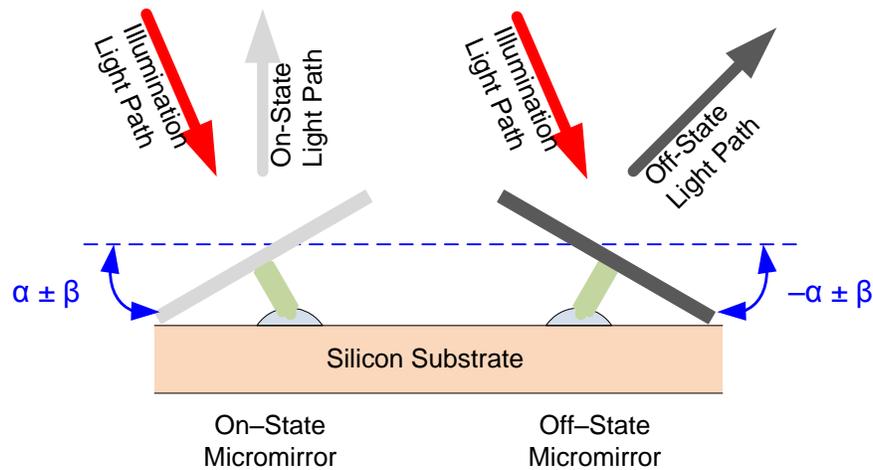


Figure 8. Micromirror Tilt Angle

6.12 Window Characteristics

PARAMETER		MIN	NOM	MAX	UNIT
Window material designation		Corning Eagle XG			
Window refractive index	at wavelength 546.1 nm	1.5119			
Window aperture ⁽¹⁾					See ⁽¹⁾

(1) See the package mechanical ICD for details regarding the size and location of the window aperture.

6.13 Chipset Component Usage Specification

The DLP3030-Q1 DMD is a component of the DLP® chipset including the DLPC120-Q1 DMD controller. Reliable function and operation of the DMD requires that it be used in conjunction with DLPC120-Q1 controller.

NOTE

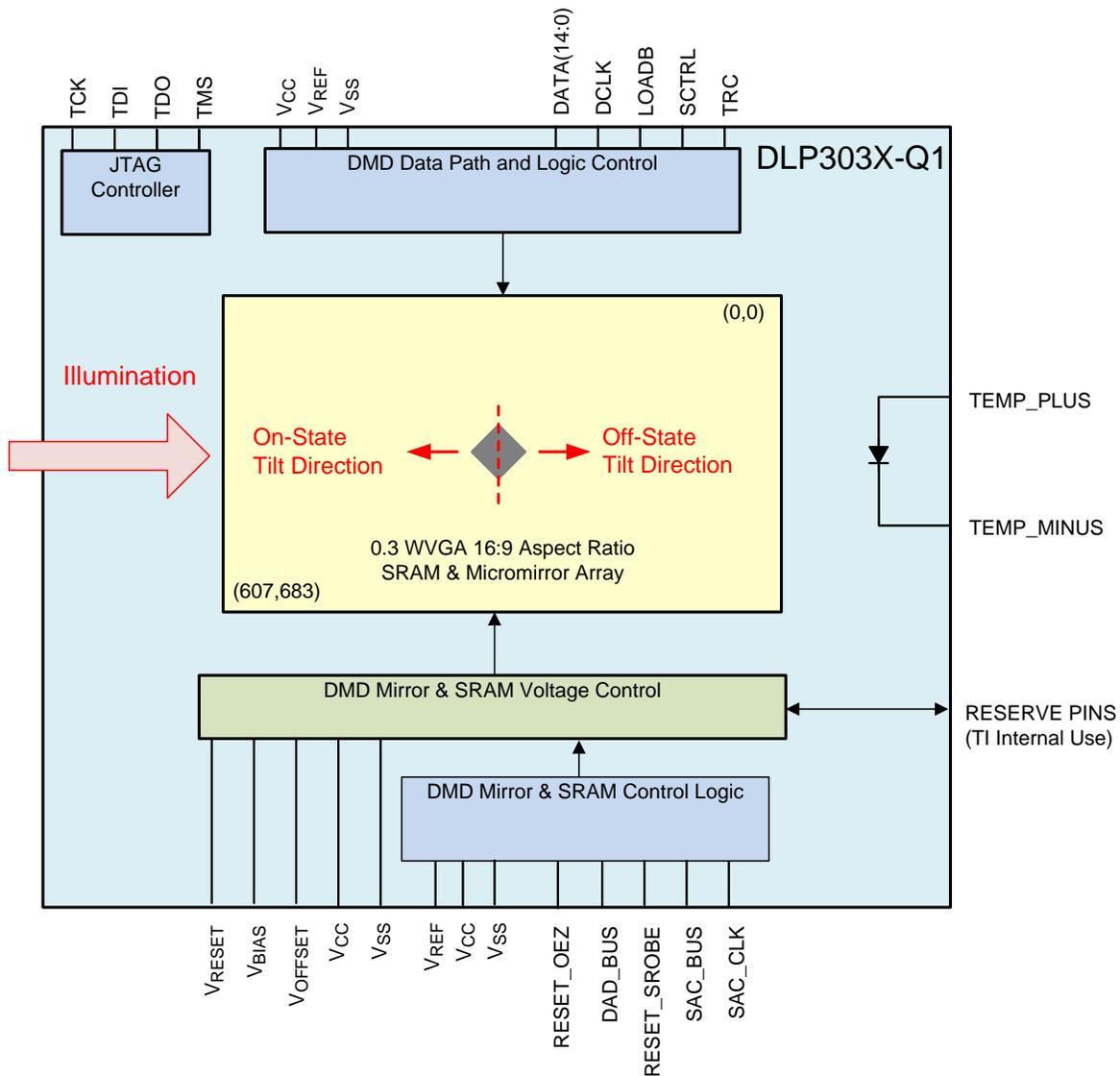
TI assumes no responsibility for image quality artifacts or DMD failures caused by optical system operating conditions exceeding limits described previously

7 Detailed Description

7.1 Overview

The DLP3030-Q1 DMD has a resolution of 608 × 684 mirrors configured in a diamond format that results in an aspect ratio of 16:9, which combined with the DLPC120-Q1 image processing creates an effective resolution of 864 × 480 square pixels. By configuring the pixels in a diamond format, the illumination input to the DMD enters from the side allowing for smaller mechanical packaging of the optical system. Additionally, side illumination can also enable increased optical efficiency compared to a corner illuminated square pixel design.

7.2 Functional Block Diagram



7.3 Feature Description

To ensure reliable operation, the DLP3030-Q1 DMD must be used with the DLPC120-Q1 DMD Display controller.

Feature Description (continued)

7.3.1 Micromirror Array

The DLP3030-Q1 DMD consists of a two-dimensional array of 1-bit CMOS memory cells that determine the state of each of the 608 × 684 micromirrors in the array. Refer to [Physical Characteristics of the Micromirror Array](#) for a calculation of how the 608 × 684 micromirror array represents a 16:9 dimensional aspect ratio to the user. Each micromirror is either “ON” (tilted +12°) or “OFF” (tilted –12°). Combined with appropriate projection optical system the DMD can be used to create clear, colorful, and vivid digital images.

7.3.2 Double Data Rate (DDR) Interface

Each DMD micromirror and its associated SRAM memory cell is loaded with data from the DLPC120-Q1 via the DDR interface (DATA(14:0), DCLK, LOADB, SCRTL, and TRC). These signals are low voltage CMOS nominally operating at 1.8-V level to reduce power and switching noise. This high speed data input to the DMD allows for a maximum update rate of the entire micromirror array to be nearly 5 kHz, enabling the creation of seamless digital images using Pulse Width Modulation (PWM).

7.3.3 Micromirror Switching Control

Once data is loaded onto the DMD, the mirrors are caused to switch position (+12° or –12°) based on the timing signal sent to the DMD Mirror and SRAM control logic. The DMD mirrors will be switched from OFF to ON or ON to OFF, or stay in the same position based on control signals DAD_BUS, RESET_STROBE, SAC_BUS, and SAC_CLK, which are coordinated with the data loading by the DLPC120-Q1. In general, the DLPC120-Q1 loads the DMD SRAM memory cells over the DDR interface, and then commands to the micromirrors to switch position.

At power down, the DMD Mirrors are commanded by the DLPC120-Q1 to move to a near flat (0°) position as shown in [Power Supply Recommendations](#) section. The flat state position of the DMD mirrors are referred to as the “Parked” state. To maintain long term DMD reliability, the DMD must be properly “Parked” prior to every power down of the DMD power supplies. Refer to the *DLPC120-Q1 Programmer's Guide* for information about properly parking the DMD.

7.3.4 DMD Voltage Supplies

The micromirrors switching requires unique voltage levels to control the mechanical switching. These voltages levels are nominally 16 V, 8.5 V, and –10 V (V_{BIAS} , V_{OFFSET} , and V_{RESET}). The specification values for V_{BIAS} , V_{OFFSET} , and V_{RESET} are shown in [Recommended Operating Conditions](#).

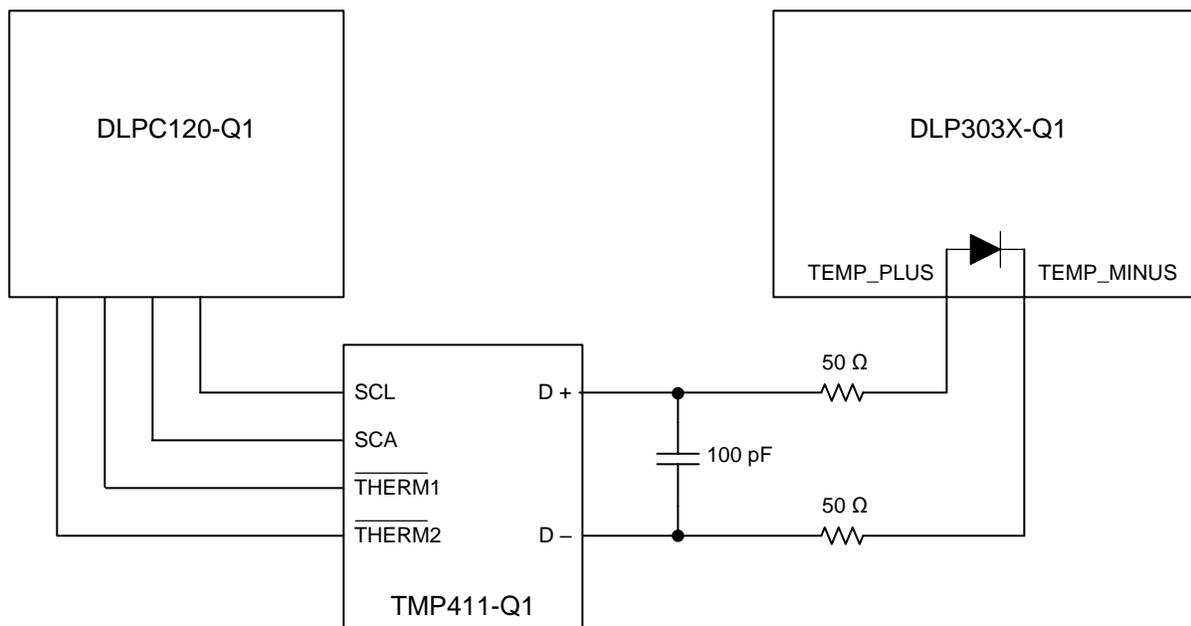
7.3.5 Logic Reset

Reset of the DMD is required and controlled by the DLPC120-Q1.

7.3.6 Temperature Sensing Diode

The DMD includes a temperature sensing diode designed to be used with the TMP411-Q1 temperature monitoring device. The DLPC120-Q1 monitors the DMD array temperature via the TMP411-Q1 and temperature sense diode. The DLPC120-Q1 operation of the DMD is based in part on the DMD array temperature, and therefore, this connection is essential to ensure reliable operation of the DMD.

[Figure 9](#) shows the typical connection between the DLPC120-Q1, TMP411-Q1, and the DLP3030-Q1 DMD. The signals to the temperature sense diode are sensitive to system noise, therefore, care should be taken in the routing and implementation of this circuit. See the [TMP411-Q1 Data Sheet](#) for detailed PCB layout recommendations.

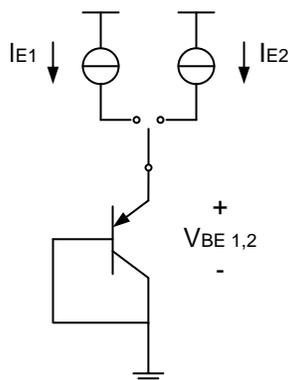
Feature Description (continued)

Figure 9. Temperature Sense Diode Typical Circuit Configuration

The DLPC120-Q1 automatically controls the DMD parking based on the temperature measured from the temperature sense diode; however, it is recommended that the host controller manage the parking via the proper methods described in the *DLPC120-Q1 Programmer's Guide*.

7.3.6.1 Temperature Sense Diode Theory

A temperature sensing diode is based on the fundamental current and temperature characteristics of a transistor. The diode is formed by connecting the transistor base to the collector. Two different known currents flow through the diode and the resulting diode voltage is measured in each case. The difference in their base-emitter voltages is proportional to the absolute temperature of the transistor.

Refer to the [TMP411-Q1 Data Sheet](#) for detailed information about temperature diode theory and measurement. [Figure 10](#) and [Figure 11](#) illustrate the relationship between the current and voltage through the diode.


Figure 10. Temperature Measurement Theory

Feature Description (continued)

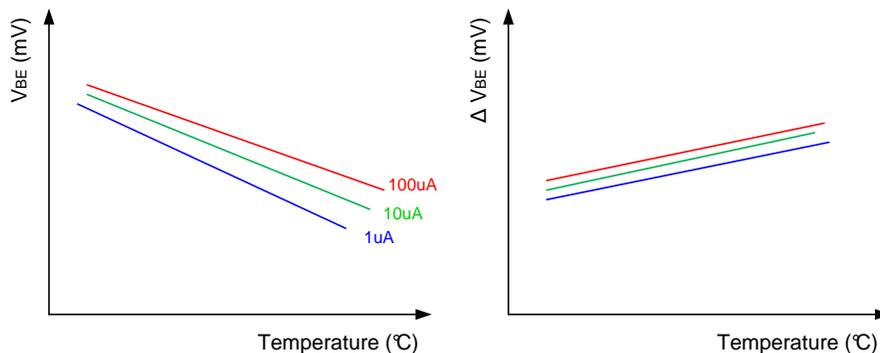


Figure 11. Example of Delta VBE vs Temperature

7.3.7 Active Array Temperature

NOTE

Calculation is not valid for a headlight application utilizing an optically underfilled active array. Contact TI Applications Engineering for array temperature calculation methods for headlight applications.

Active array temperature can be computed analytically from measurement points on the outside of the package, the package thermal resistance, the electrical power, and the illumination heat load.

Relationship between array temperature and the reference ceramic temperature (thermocouple location TP1 in Figure 12) is provided by the following equations.

$$T_{\text{ARRAY}} = T_{\text{CERAMIC}} + (Q_{\text{ARRAY}} \times R_{\text{ARRAY-TO-CERAMIC}}) \quad (1)$$

$$Q_{\text{ARRAY}} = Q_{\text{ELECTRICAL}} + Q_{\text{ILLUMINATION}}$$

where

- T_{ARRAY} = computed DMD array temperature (°C)
- T_{CERAMIC} = measured ceramic temperature (TP1 location in Figure 12) (°C)
- $R_{\text{ARRAY-TO-CERAMIC}}$ = DMD package thermal resistance from array to TP1 (°C/watt) (see [Thermal Information](#))
- Q_{ARRAY} = total power, electrical plus absorbed, on the DMD array (watts)
- $Q_{\text{ELECTRICAL}}$ = nominal electrical power dissipation by the DMD (watts)
- $Q_{\text{ILLUMINATION}} = (C_{\text{L2W}} \times S_{\text{L}})$
- C_{L2W} = conversion constant for screen lumens to power on the DMD (watts/lumen)
- S_{L} = measured screen lumens (lm) (2)

Electrical power dissipation of the DMD is variable and depends on the voltages, data rates and operating frequencies.

Absorbed power from the illumination source is variable and depends on the operating state of the mirrors and the intensity of the light source.

Equations shown previous are valid for a 1-Chip DMD system with total projection efficiency from DMD to the screen of 87%.

The constant C_{L2W} is based on the DMD array characteristics. It assumes a spectral efficiency of 300 lumens/watt for the projected light and illumination distribution of 83.7% on the active array, and 16.3% on the array border.

Sample calculation:

- $S_{\text{L}} = 50 \text{ lm}$
- $C_{\text{L2W}} = 0.00293$
- $Q_{\text{ELECTRICAL}} = 0.105 \text{ W}$

Feature Description (continued)

- $R_{\text{ARRAY-TO-CERAMIC}} = 2.5^{\circ}\text{C/W}$

- $T_{\text{CERAMIC}} = 55^{\circ}\text{C}$

$$Q_{\text{ARRAY}} = 0.105 \text{ W} + (0.00293 \times 50 \text{ lm}) = 0.252 \text{ W} \quad (3)$$

$$T_{\text{ARRAY}} = 55^{\circ}\text{C} + (0.252 \text{ W} \times 2.5^{\circ}\text{C/W}) = 55.6^{\circ}\text{C} \quad (4)$$

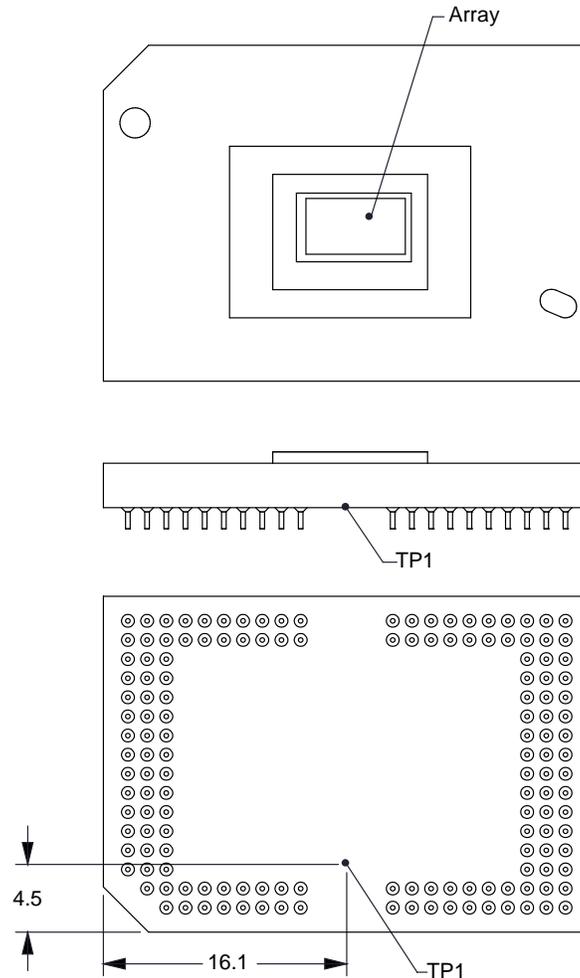


Figure 12. Thermocouple Locations

7.3.8 DMD JTAG Interface

The DMD uses 4 standard JTAG signals for sending and receiving boundary scan test data. TCK is the test clock used to drive an IEEE 1149.1 TAP state machine and logic. TMS directs the next state of the TAP state machine. TDI is the scan data input and TDO is the scan data output.

The DMD does not support IEEE 1149.1 signals TRST (Test Logic Reset) and RTCK (Returned Test Clock). Boundary scan cells on the DMD are Observe-Only. To initiate the JTAG boundary scan operation on the DMD, a minimum of 6 TCK clock cycles are required after TMS is set to logic high.

Refer to [Figure 13](#) for a JTAG system board routing example. The DLPC120-Q1 can be enabled to perform an in system boundary scan test. See *DLPC120-Q1 Programmer's Guide* for information about this test.

Feature Description (continued)

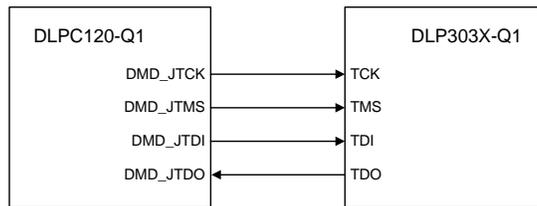


Figure 13. System Interface Connection to DLPC120-Q1

The DMD Device ID can be read via the JTAG interface. The ID and 32-bit shift order is shown in Figure 14.



Figure 14. DMD Device ID and 32-bit Shift Order

Refer to Figure 15 for a JTAG boundary scan block diagram for the DMD. These show the pins and the scan order that are observed during the JTAG boundary scan.

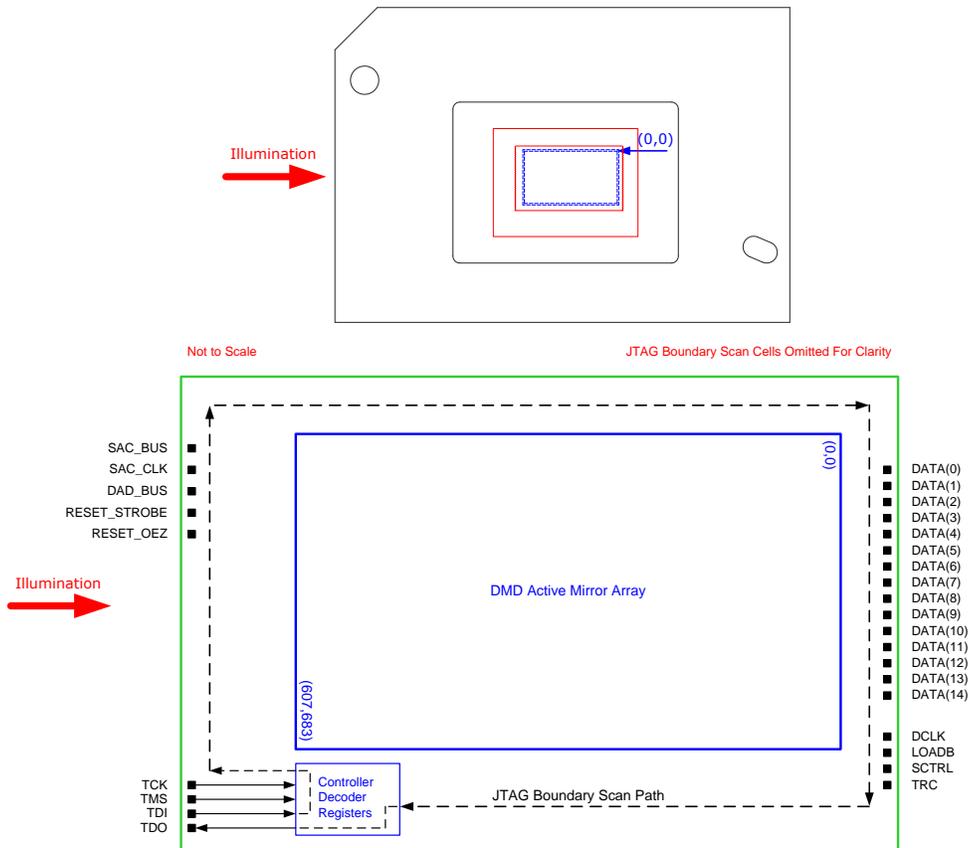


Figure 15. JTAG Boundary Scan Path

Refer to Figure 16 for a functional block diagram of the JTAG control logic.

Feature Description (continued)

Not to Scale.

BSC = Boundary Scan Cell [Observe Only]

Note 1: Signal Routing Omitted for Clarity.

TAP = Test Access Port

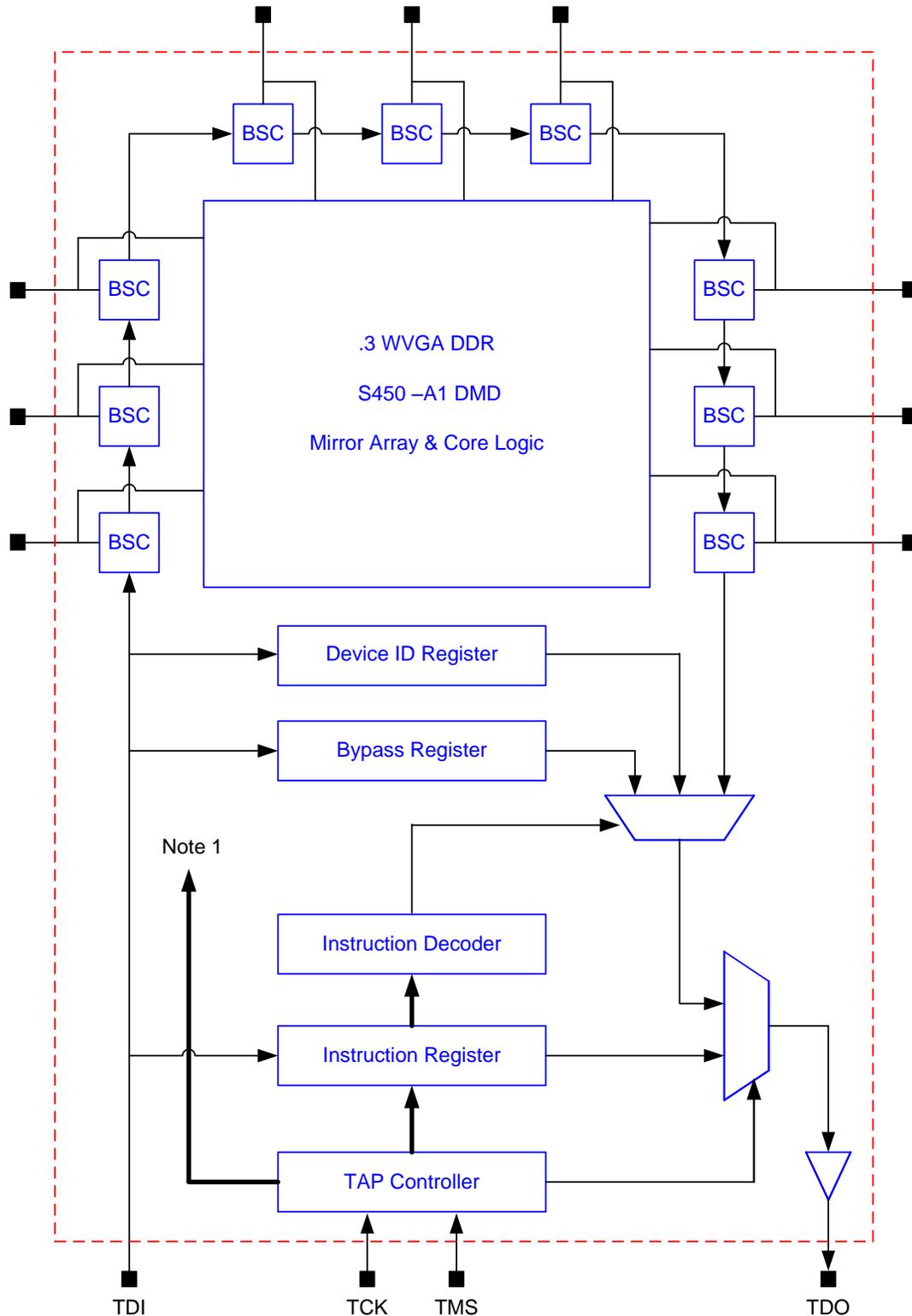


Figure 16. JTAG Functional Block Diagram

7.4 Optical Performance

Optimizing system optical performance and image quality strongly relates to optical system design parameter trades. Although it is not possible to anticipate every conceivable application, projector image quality and optical performance is contingent on compliance to the optical system operating conditions described below.

7.4.1 Numerical Aperture and Stray Light Control

The angle defined by the numerical aperture of the illumination and projection optics at the DMD optical area should be the same. This angle should not exceed the nominal device mirror tilt angle unless appropriate apertures are added in the illumination and/or projection pupils to block flat-state and stray light from passing through the projection lens. The mirror tilt angle defines DMD capability to separate the "On" optical path from any other light path, including undesirable flat-state specular reflections from the DMD window, DMD border structures, or other system surfaces near the DMD such as prism or lens surfaces. If the numerical aperture exceeds the mirror tilt angle, or if the projection numerical aperture angle is more than two degrees larger than the illumination numerical aperture angle, contrast ratio can be reduced and objectionable artifacts in the image border and/or active area could occur.

7.4.2 Pupil Match

TI's optical and image quality specifications assume that the exit pupil of the illumination optics is nominally centered within two degrees of the entrance pupil of the projection optics. Misalignment of pupils can create objectionable artifacts in the image border and/or active area, which may require additional system apertures to control, especially if the numerical aperture of the system exceeds the pixel tilt angle.

7.4.3 Illumination Overfill and Alignment

Overfill light illuminating the area outside the active array can create artifacts from the mechanical features and other surfaces that surround the active array. These artifacts may be visible in the projected image. The illumination optical system should be designed to minimize light flux incident outside the active array and on the window aperture. Depending on the particular system's optical architecture and assembly tolerances, this amount of overfill light on the area outside of the active array may still cause artifacts to be visible. Illumination light and overfill can also induce undesirable thermal conditions on the DMD, especially if illumination light impinges directly on the DMD window aperture or near the edge of the DMD window. Refer to [Recommended Operating Conditions](#) for a specification on this maximum allowable heat load due to illumination overfill.

NOTE

TI ASSUMES NO RESPONSIBILITY FOR IMAGE QUALITY ARTIFACTS OR DMD FAILURES CAUSED BY OPTICAL SYSTEM OPERATING CONDITIONS EXCEEDING LIMITS DESCRIBED ABOVE.

7.5 DMD Image Quality Specification

PARAMETER ⁽¹⁾	MIN	NOM	MAX	UNIT
Dark Blemishes ⁽²⁾			4	
Light Blemishes ⁽³⁾			4	
Border Artifacts ⁽⁴⁾			Allowed	
Minor Blemishes ⁽⁴⁾			Allowed	
Bright Pixels ⁽³⁾			0	
Dark Pixels ⁽⁵⁾⁽⁶⁾			4	
Pixel Clusters (Dark) ⁽⁶⁾			0	
Dark Pixels (Adjacent) ⁽⁶⁾⁽⁵⁾			0	
Unstable Pixels ⁽⁴⁾			0	
Optical Performance	See Optical Performance			
Ambient Lighting Conditions	See ⁽⁷⁾			

- (1) Blemish counts do not include reflections or shadows of the same artifact. Gray 10 linear gamma graphic is the darkest screen that can be used for IQ evaluation. Any artifact that is not specifically addressed in this table is acceptable unless mutually agreed to between DLP® Products and the customer. Viewing distance must be > 48 inches. Screen size should be similar to application image size. All values referenced are in linear gamma. Non-linear gamma curves may be running by default, and it should be ensured with a TI applications engineer that the equivalent linear gamma value as specified is used to judge artifacts.
- (2) Determined on Blue 60 linear gamma screen. Blemish cannot be darker than background.
- (3) Determined on Gray 10 linear gamma screen. Blemish cannot be lighter than background.
- (4) A Minor light blemish is any blemish that can be seen on a black screen but not a Gray 10 linear gamma screen. A Minor dark blemish is any blemish that can be seen on a white screen but not a Blue 60 linear gamma screen. Border artifacts, unstable pixels, and Active area shading are allowed unless visible on a screen brighter than Gray 10 linear gamma.
- (5) Dark pixels must be at least fifty (50) mirrors apart.
- (6) Determined on a White screen.
- (7) The parameters stated in [DMD Image Quality Specification](#) assume that the viewed images are set with a nominally adjusted brightness for ambient lighting condition. For example, if the ambient lighting conditions are very dark, such as night time conditions, then the image brightness level will be matched to nominal expected value as used in the end application. Similarly, if the ambient lighting conditions are very bright, such as day time viewing conditions, then the image brightness may be adjusted to the nominal brightness level as would be expected in the end application.

7.6 Definition of Micromirror Landed-On/Landed-Off Duty Cycle

The micromirror landed-on/landed-off duty cycle (landed duty cycle) denotes the amount of time (as a percentage) that an individual micromirror is landed in the ON state versus the amount of time the same micromirror is landed in the OFF state.

As an example, assuming a fully-saturated white pixel, a landed duty cycle of 90/10 indicates that the referenced pixel is in the ON state 90% of the time (and in the OFF state 10% of the time), whereas 10/90 would indicate that the pixel is in the OFF state 90% of the time. Likewise, 50/50 indicates that the pixel is ON 50% of the time and OFF 50% of the time.

Note that when assessing landed duty cycle, the time spent switching from one state (ON or OFF) to the other state (OFF or ON) is considered negligible and is thus ignored.

Since a micromirror can only be landed in one state or the other (ON or OFF), the two numbers (percentages) always add to 100.

8 Application and Implementation

NOTE

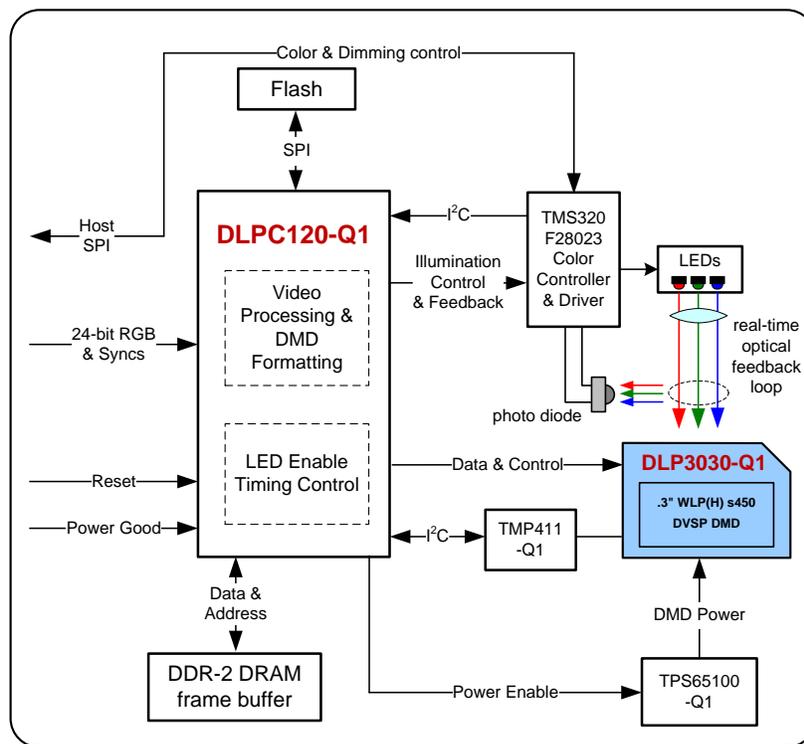
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The DLP3030-Q1 DMD was designed to be used in automotive applications such as head-up display (HUD) . The information shown in this section describes the HUD application based on the TI reference design. Contact TI application engineer for information on this design.

8.2 Typical Application

The DLP3030-Q1 DMD combined with the DLPC120-Q1 are the primary devices that make up the reference design for a HUD system as shown in the block diagram [Figure 17](#).



Copyright © 2017, Texas Instruments Incorporated

Figure 17. HUD Reference Design Block Diagram

The DLPC120-Q1 accepts input video over the parallel RGB data interface up to 8 bits per color from a Video Graphics processor. The DLPC120-Q1 then processes the video data (864 × 480 manhattan orientation) by scaling the image to match the DMD resolution (608 × 684 diamond pixel), applies de-gamma correction, bezel adjustment, and then formats the data into DMD bit plane information and stores the data into the DDR2 DRAM. The DMD bit planes are read from DDR2 DRAM, and are then displayed on the DMD using Pulse Width Modulation (PWM) timing. The DLPC120-Q1 synchronizes the DMD bit plane data with the RGB enable timing for the LED color controller and Driver circuit. Finally, the DMD accepts the bit plane formatted data from the DLPC120-Q1 and displays the data according to the timing controlled by the DLPC120-Q1.

Typical Application (continued)

Due to the mechanical nature of the micromirrors, the latency of the DLP3030-Q1 and DLPC120-Q1 chipset is fixed across all temperature and operating conditions. The observed video latency is one frame, or 16.67 ms at an input frame rate of 60 Hz. However, please note that the use of the DLPC120-Q1 bezel adjustment feature, if enabled by the host controller, requires an additional frame of processing.

The DLPC120-Q1 is configured at power up by data stored in the flash file which stores configuration data, DMD and sequence timing information, LED drive information, and other information related to the system functions. See the *DLPC120-Q1 Programmer's Guide* for information about the this flash configuration data.

The HUD reference design from TI includes the TMS320F28023 Microcontroller (Piccolo) which is used to control the color point by adjusting the RGB flux levels, and drives each RGB LED. This circuit also manages the dimming function for the HUD system. The dimming level of a HUD system requires very large dynamic range of over 5000:1. For example, on a bright day, the HUD system may require a brightness level as high as 15,000 cd/m² and conversely at night time the minimum brightness level desired may only be 3 cd/m².

8.2.1 HUD Reference Design and LED Controller Reference Design

The complete HUD reference design is available from TI, including electronics (Schematic) and PCB (Gerber) design, opto-mechanical design (CAD and Zemax models), sample software, and other system reference design documentation. Additionally, there are application notes describing the Piccolo LED driver and color control circuit. **Contact TI application engineering for access to these application notes and design information.**

8.3 Application Mission Profile Consideration

Each application is anticipated to have different mission profiles, or number of operating hours at different temperatures. To assist in evaluation, the Application Report *Reliability Lifetime Estimates for the DLP3030-Q1 DMD in Automotive Applications* may be provided if requested.

9 Power Supply Recommendations

9.1 Power Supply Sequencing Requirements

- V_{BIAS} , V_{CC} , V_{OFFSET} , V_{REF} , V_{RESET} , V_{SS} are required to operate the DMD.

CAUTION

- For reliable operation of the DMD, the following power supply sequencing requirements must be followed. Failure to adhere to the prescribed power up and power down procedures may affect device reliability.
- The V_{CC} , V_{REF} , V_{OFFSET} , V_{BIAS} , and V_{RESET} power supplies have to be coordinated during power up and power down operations. Failure to meet any of the below requirements will result in a significant reduction in the DMD's reliability and lifetime. Refer to [Figure 18](#). V_{SS} must also be connected.

DMD Power Supply Power Up Procedure:

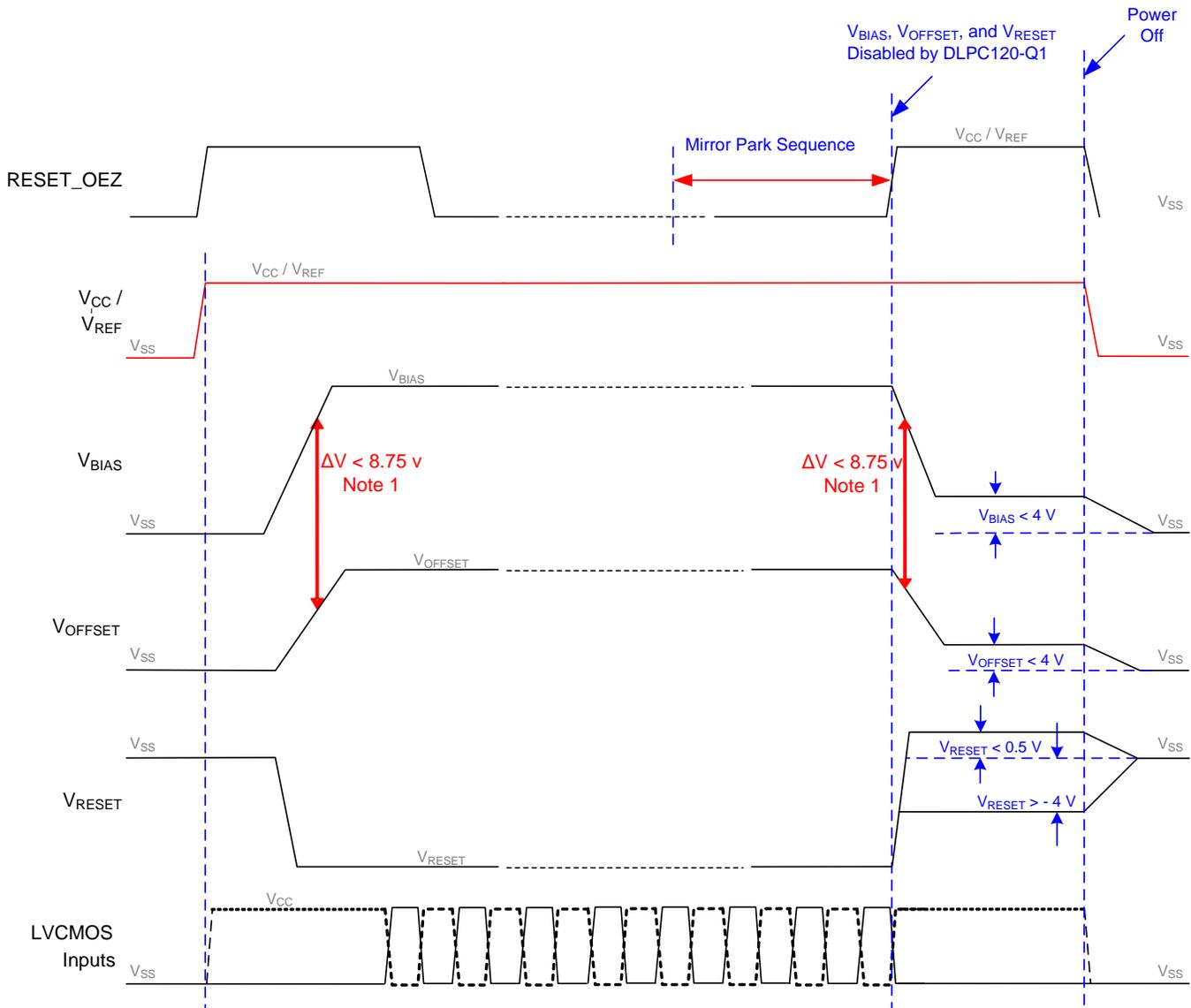
- During power up, V_{CC} and V_{REF} must always start and settle before V_{OFFSET} , V_{BIAS} and V_{RESET} voltages are applied to the DMD.
- During power up, V_{BIAS} does not have to start after V_{OFFSET} . However, it is a strict requirement that the delta between V_{BIAS} and V_{OFFSET} must be within ± 8.75 V (refer to Note 1 for [Figure 18](#)).
- During power up, the DMD's LVCMOS input pins shall not be driven high until after V_{CC} and V_{REF} have settled at operating voltage.
- During power up, there is no requirement for the relative timing of V_{RESET} with respect to V_{OFFSET} and V_{BIAS} .
- Power supply slew rates during power up are flexible, provided that the transient voltage levels follow the requirements listed above and in [Recommended Operating Conditions](#) and in [Figure 18](#).

DMD Power Supply Power Down Procedure

- V_{CC} and V_{REF} must be supplied until after V_{BIAS} , V_{RESET} and V_{OFFSET} are discharged to within 4 V of ground.
- During power down it is not mandatory to stop driving V_{BIAS} prior to V_{OFFSET} , but it is a strict requirement that the delta between V_{BIAS} and V_{OFFSET} must be within ± 8.75 V (refer to Note 1 for [Figure 18](#)).
- During power down, the DMD's LVCMOS input pins must be less than $V_{REF} + 0.3$ V.
- During power down, there is no requirement for the relative timing of V_{RESET} with respect to V_{OFFSET} and V_{BIAS} .
- Power supply slew rates during power down are flexible, provided that the transient voltage levels follow the requirements listed above in [Recommended Operating Conditions](#) and in [Figure 18](#).

Power Supply Sequencing Requirements (continued)

9.1.1 Power Up and Power Down



- (1) $\pm 8.75\text{-V}$ delta, ΔV , shall be considered the max operating delta between V_{BIAS} and V_{OFFSET} . Customers may find that the most reliable way to ensure this is to power V_{OFFSET} prior to V_{BIAS} during power up and to remove V_{BIAS} prior to V_{OFFSET} during power down.

Figure 18. Power Supply Sequencing Requirements (Power Up and Power Down)

10 Layout

10.1 Layout Guidelines

Refer to *DLPC120-Q1 Data Sheet* for specific PCB layout and routing guidelines. For specific DMD PCB guidelines, use the following:

- V_{CC} should have at least one 2.2- μ F and four 0.1- μ F capacitors evenly distributed among the 13 V_{CC} pins.
- A 0.1- μ F, X7R rated capacitor should be placed near every pin for the V_{REF} , V_{BIAS} , V_{RSET} , and V_{OFF} .

10.2 Temperature Diode Pins

The DMD has an internal diode (PN junction) that is intended to be used with an external TI TMP411-Q1 temperature sensing IC. PCB traces from the DMD's temperature diode pins to the TMP411-Q1 are sensitive to noise. See the *TMP411-Q1 Data Sheet* for specific routing recommendations.

Avoid routing the temperature diodes signals near other traces to avoid coupling of noise onto these signals.

10.3 Layout Example

Contact TI Application Engineering for access to the complete TI reference design PCB layout.

11 Device and Documentation Support

11.1 Device Support

11.1.1 Device Nomenclature

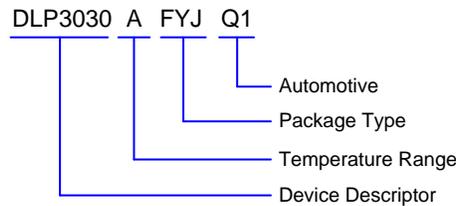


Figure 19. Part Number Description

11.1.2 Device Markings

The device marking is shown below. The marking will include both human-readable information and a 2-dimensional matrix code.

The human-readable information is described below. The 2-dimensional matrix code is an alpha-numeric character string that contains the DMD part number, part 1 of serial number, and part 2 of serial number.

The first character of the DMD serial number (part 1) is the manufacturing year. The second character of the DMD serial number (part 1) is the manufacturing month. The last character of the DMD serial number (part 2) is the bias voltage bin letter.

Example: *DLP3030AFYJQ1 GHXXXXX LLLLLLM

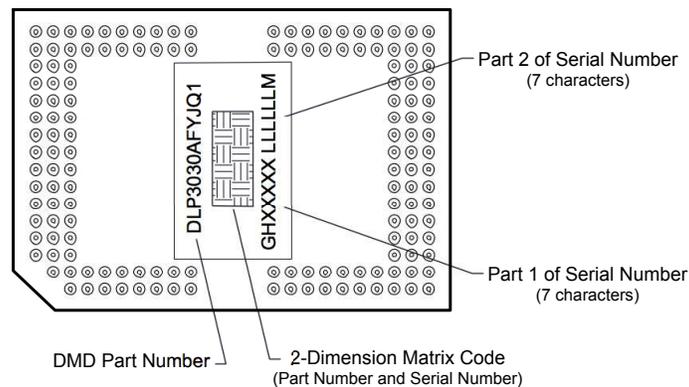


Figure 20. DMD Marking

A 3-dimensional modeled depiction of the DLP3030-Q1 device is shown below.

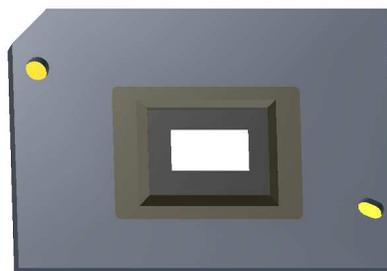


Figure 21. Image of DLP3030-Q1

11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following:

- [DLPC120-Q1 product folder](#) for the *DLPC120-Q1 Data Sheet*
- [TMS320F2802x Piccolo™ Microcontrollers](#)
- [TMP411-Q1 ±1°C Remote and Local Temperature Sensor With N-Factor and Series Resistance Correction](#)

11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.4 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.5 Trademarks

E2E is a trademark of Texas Instruments.

DLP is a registered trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

11.6 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.7 Device Handling

The DMD is an optical device so precautions should be taken to avoid damaging the glass window. Please see the [DMD Handling application note](#) for instructions on how to properly handle the DMD.

11.8 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

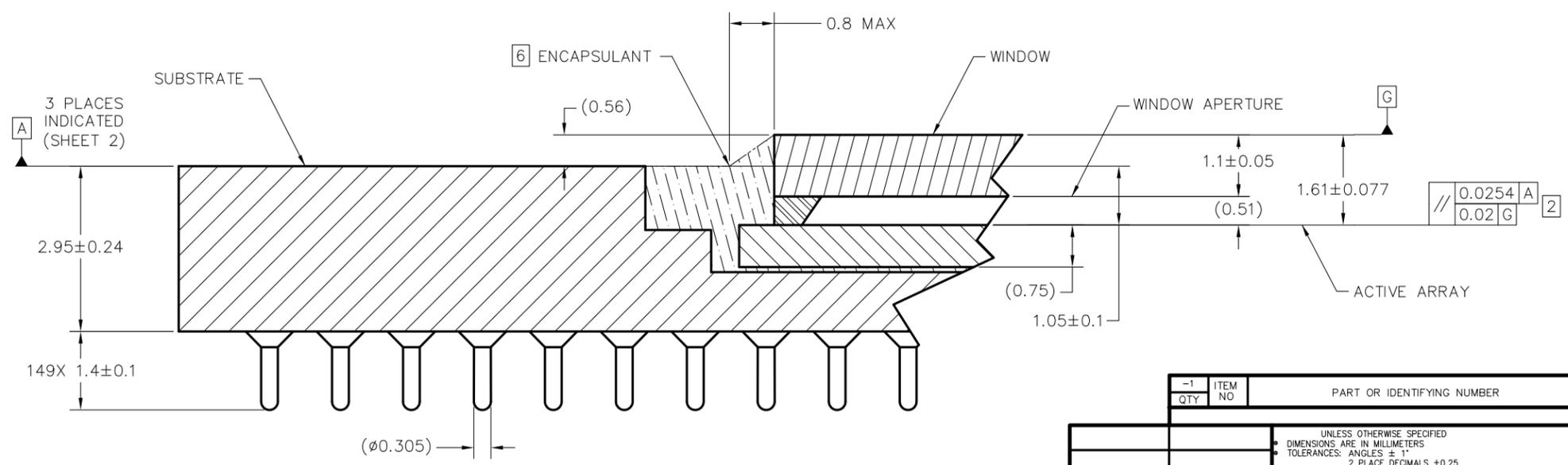
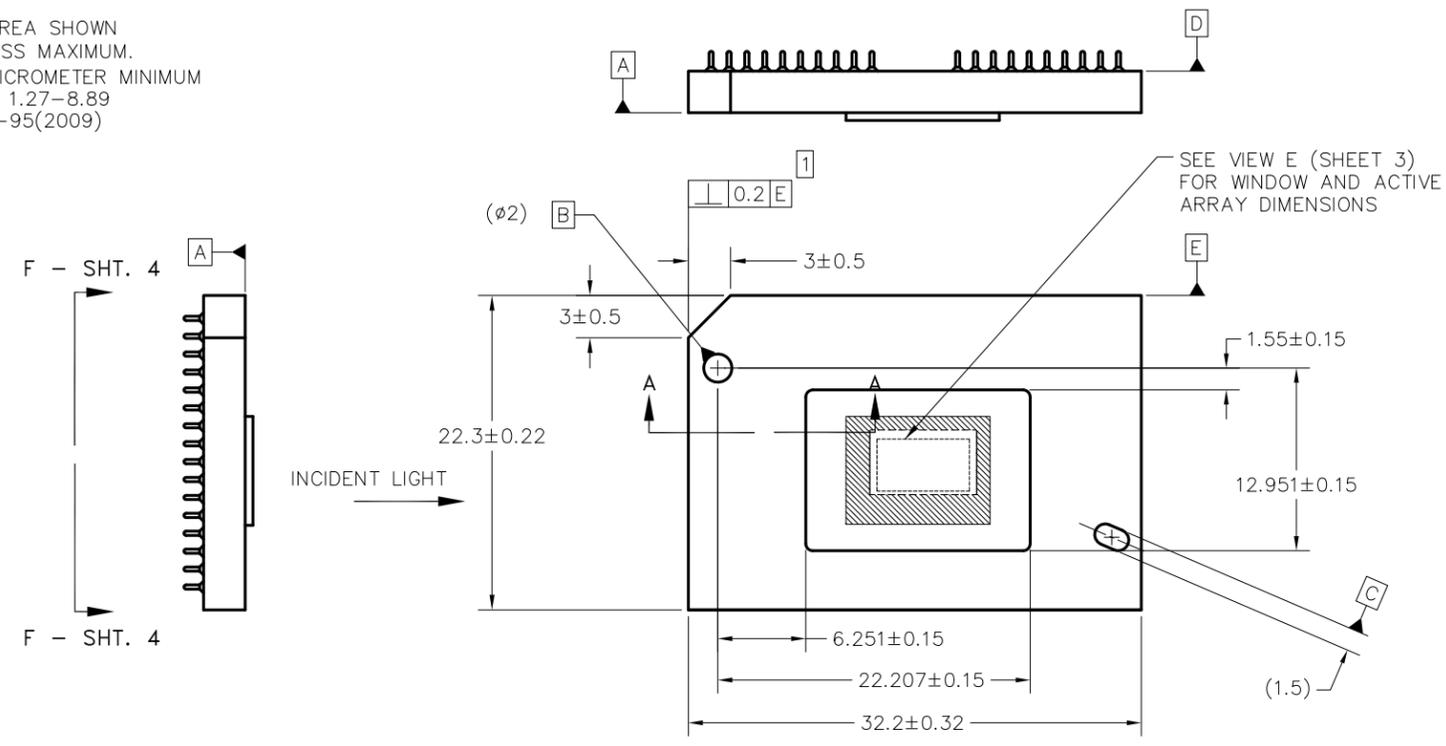
12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

REVISIONS			
REV	DESCRIPTION	DATE	APPROVED
A	ECO 2142364, INITIAL RELEASE	06/03/2014	M. AVERY
B	ECO 2153319, UPDATE PACKAGE DESIGNATOR IN TITLE BLOCK, NOTE 8 FIXED FOR Ni/Pd/Au, MOVED SUPPLIER CODE IN VIEW F-F.	09/11/2015	M. AVERY
C	ECO 2158233, UPDATE VIEW F-F 3 DIGIT P/N	05/18/2016	M. AVERY
D	ECO 2168572, CHG DIE HEIGHT TOL, WAS ± 0.08	08/25/2017	M. AVERY

NOTES: UNLESS OTHERWISE SPECIFIED:

- 1 SUBSTRATE EDGE PERPENDICULARITY TOLERANCE APPLIES TO ENTIRE SURFACE
- 2 DIE PARALLELISM TOLERANCE APPLIES TO DMD ACTIVE ARRAY ONLY
- 3 ROTATION ANGLE OF DMD ACTIVE ARRAY IS A REFINEMENT OF THE LOCATION TOLERANCE AND HAS A MAXIMUM ALLOWED VALUE OF 0.8 DEGREES
- 4 SUBSTRATE SYMBOLIZATION PAD AND PLATING AT BOTTOM OF DATUMS B AND C HOLES TO BE ELECTRICALLY CONNECTED TO VSS PLANE WITHIN THE SUBSTRATE BOUNDARY MIRRORS SURROUNDING THE DMD ACTIVE AREA
- 5 MAXIMUM ENCAPSULANT PROFILE SHOWN
- 6 ENCAPSULANT ALLOWED ON THE SURFACE OF THE CERAMIC IN THE AREA SHOWN IN VIEW B (SHEET 2). ENCAPSULANT SHALL NOT EXCEED 0.2 THICKNESS MAXIMUM.
- 7 INDICATED CERAMIC SUBSTRATE FEATURES TO BE PLATED WITH 0.3 MICROMETER MINIMUM ELECTROLYTIC GOLD OVER 0.1 MICROMETER MINIMUM PALLADIUM OVER 1.27-8.89 MICROMETERS ELECTROLYTIC NICKEL PER ASTM B488-01, ASTM B679-95(2009) AND AMS-QQ-N-290, RESPECTIVELY.

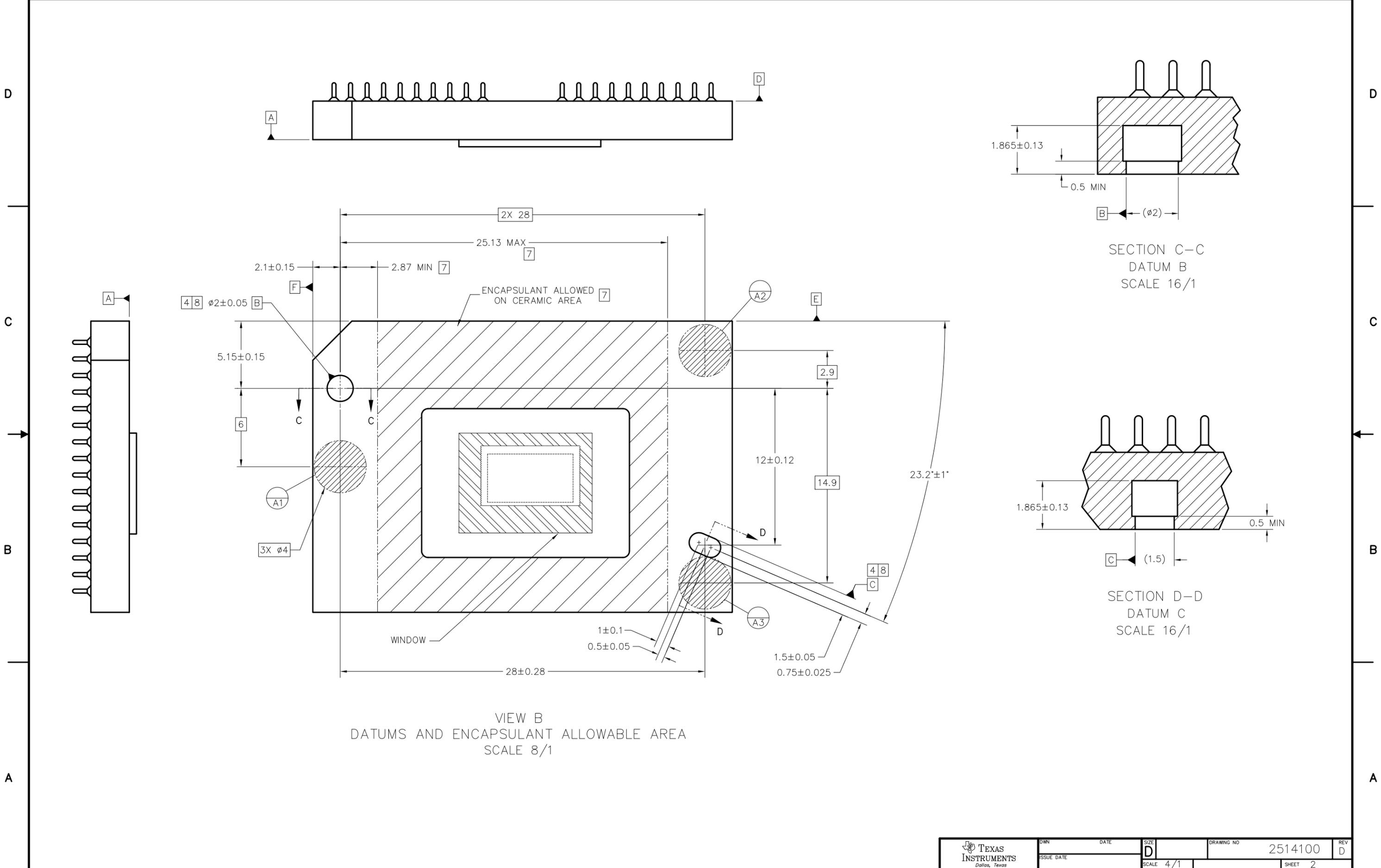


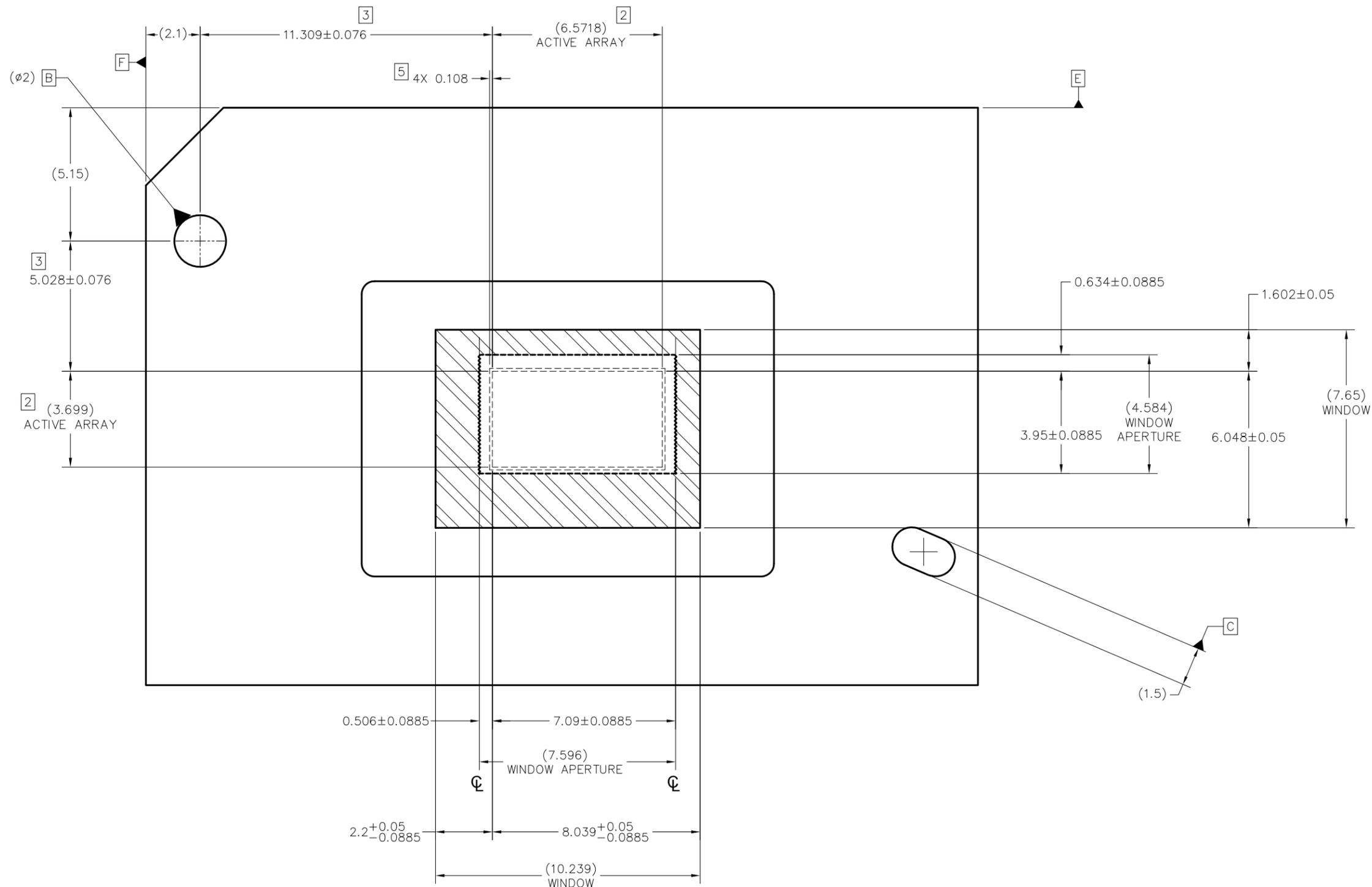
SECTION A-A
SCALE 20/1

QTY	ITEM NO	PART OR IDENTIFYING NUMBER	NOMENCLATURE OR DESCRIPTION	NOTES
-1				

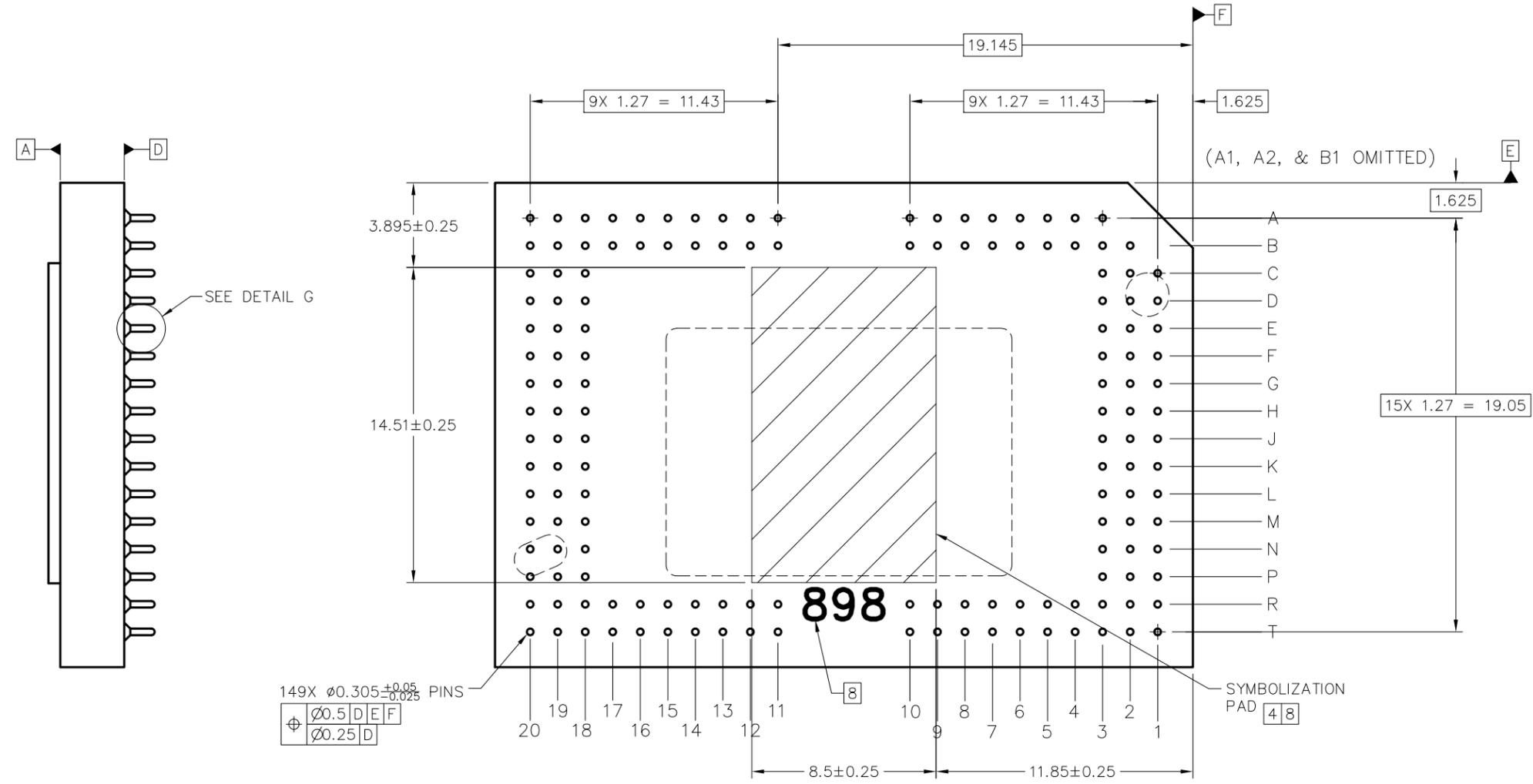
PARTS LIST		DATE	
DWN	M. AVERY	6/3/14	
ENGR	M. AVERY	6/3/14	
QA	B. HASKETT	6/5/14	
	P. KONRAD	6/13/14	
	R. LONG	6/20/14	
COE	M. DORAK	6/23/14	
	S. SUSI	6/18/14	

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MILLIMETERS TOLERANCES: ANGLES ± 1° 2 PLACE DECIMALS ± 0.25 3 PLACE DECIMALS ± 0.50	REMOVE ALL BURRS AND SHARP EDGES— INTERPRET DIMENSIONS IN ACCORDANCE WITH ASME Y14.5-1994 DIMENSIONAL LIMITS APPLY BEFORE PROCESSES— PARENTHEetical INFO FOR REF ONLY	TEXAS INSTRUMENTS Dallas, Texas
ICD, MECHANICAL, DMD .3 WVGA DDR SERIES 450 -A1 (FYJ PACKAGE)		
THIRD ANGLE PROJECTION	NONE 0314DA	SIZE D
NEXT ASSY USED ON	APPLICATION	DRAWING NO 2514100
		SCALE 4/1
		SHEET 1 OF 4

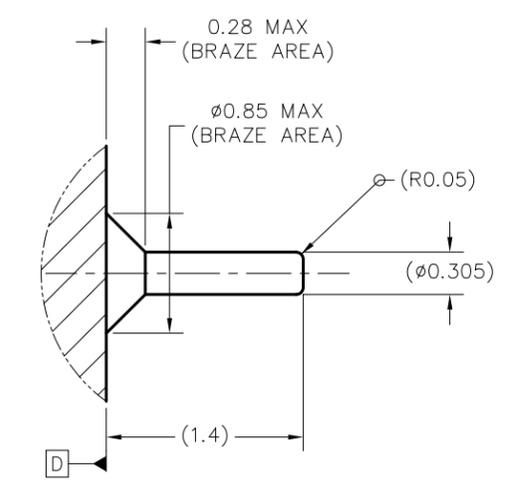




VIEW E (SHEET 1)
 DMD WINDOW AND ACTIVE ARRAY
 SCALE 12:1



VIEW F-F (SHEET 1)
PINS AND SYMBOLIZATION PAD
SCALE 8/1



DETAIL G (149 PLACES) [8]
PIN & BRAZE DIMENSIONS
SCALE 40/1

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
DLP3030AFYJQ1	ACTIVE	CPGA	FYJ	149	33	RoHS & Green	Call TI	N / A for Pkg Type	-40 to 105		Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSELETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer:The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2021, Texas Instruments Incorporated