Contents

Preface ................................................................................................................................................. 10

1 Introduction to the Software Development Tools ......................................................................... 13
  1.1 Software Development Tools Overview ................................................................................... 14
  1.2 Tools Descriptions ..................................................................................................................... 15

2 Introduction to Object Modules ..................................................................................................... 17
  2.1 Object File Format Specifications .............................................................................................. 18
  2.2 Executable Object Files .............................................................................................................. 18
  2.3 Introduction to Sections .............................................................................................................. 18
    2.3.1 Special Section Names ........................................................................................................... 19
  2.4 How the Assembler Handles Sections .......................................................................................... 19
    2.4.1 Uninitialized Sections .......................................................................................................... 20
    2.4.2 Initialized Sections .............................................................................................................. 21
    2.4.3 User-Named Sections .......................................................................................................... 21
    2.4.4 Current Section .................................................................................................................... 22
    2.4.5 Section Program Counters ................................................................................................... 22
    2.4.6 Subsections ............................................................................................................................ 22
    2.4.7 Using Sections Directives ..................................................................................................... 23
  2.5 How the Linker Handles Sections ................................................................................................. 26
    2.5.1 Combining Input Sections ...................................................................................................... 26
    2.5.2 Placing Sections .................................................................................................................... 27
  2.6 Symbols ....................................................................................................................................... 28
    2.6.1 External Symbols ................................................................................................................... 28
    2.6.2 Weak Symbols ....................................................................................................................... 29
    2.6.3 The Symbol Table .................................................................................................................. 30
  2.7 Symbolic Relocations .................................................................................................................. 30
    2.7.1 Dynamic Relocation Entries ................................................................................................. 31
  2.8 Loading a Program ....................................................................................................................... 31

3 Program Loading and Running ....................................................................................................... 32
  3.1 Loading ........................................................................................................................................ 33
    3.1.1 Load and Run Addresses ...................................................................................................... 33
    3.1.2 Bootstrap Loading .................................................................................................................. 34
  3.2 Entry Point .................................................................................................................................. 35
  3.3 Run-Time Initialization ............................................................................................................... 35
    3.3.1 __c_int00 ................................................................................................................................. 35
    3.3.2 RAM Model vs. ROM Model ................................................................................................. 35
    3.3.3 Copy Tables ........................................................................................................................... 37
  3.4 Arguments to main ..................................................................................................................... 38
  3.5 Run-Time Relocation .................................................................................................................. 38
  3.6 Additional Information ................................................................................................................. 38

4 Assembler Description ..................................................................................................................... 39
  4.1 Assembler Overview ................................................................................................................... 40
  4.2 The Assembler's Role in the Software Development Flow ....................................................... 41
  4.3 Invoking the Assembler .............................................................................................................. 42
  4.4 The Application Binary Interface ............................................................................................... 43
### Assembler Directives

<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>4.1 Directives Summary</td>
<td>75</td>
</tr>
<tr>
<td>4.2 Directives that Define Sections</td>
<td>80</td>
</tr>
<tr>
<td>4.3 Directives that Initialize Values</td>
<td>81</td>
</tr>
<tr>
<td>4.4 Directives that Perform Alignment and Reserve Space</td>
<td>83</td>
</tr>
<tr>
<td>4.5 Directives that Format the Output Listings</td>
<td>84</td>
</tr>
<tr>
<td>4.6 Directives that Reference Other Files</td>
<td>85</td>
</tr>
<tr>
<td>4.7 Directives that Enable Conditional Assembly</td>
<td>86</td>
</tr>
<tr>
<td>4.8 Directives that Define Union or Structure Types</td>
<td>86</td>
</tr>
<tr>
<td>4.9 Directives that Define Enumerated Types</td>
<td>87</td>
</tr>
<tr>
<td>4.10 Directives that Define Symbols at Assembly Time</td>
<td>87</td>
</tr>
<tr>
<td>4.11 Miscellaneous Directives</td>
<td>88</td>
</tr>
<tr>
<td>4.12 Directives Reference</td>
<td>89</td>
</tr>
<tr>
<td>5.1 Directives Summary</td>
<td>74</td>
</tr>
<tr>
<td>5.2 Directives that Define Sections</td>
<td>75</td>
</tr>
<tr>
<td>5.3 Directives that Initialize Values</td>
<td>80</td>
</tr>
<tr>
<td>5.4 Directives that Perform Alignment and Reserve Space</td>
<td>81</td>
</tr>
<tr>
<td>5.5 Directives that Format the Output Listings</td>
<td>83</td>
</tr>
<tr>
<td>5.6 Directives that Reference Other Files</td>
<td>84</td>
</tr>
<tr>
<td>5.7 Directives that Enable Conditional Assembly</td>
<td>85</td>
</tr>
<tr>
<td>5.8 Directives that Define Union or Structure Types</td>
<td>86</td>
</tr>
<tr>
<td>5.9 Directives that Define Enumerated Types</td>
<td>87</td>
</tr>
<tr>
<td>5.10 Directives that Define Symbols at Assembly Time</td>
<td>88</td>
</tr>
<tr>
<td>5.11 Miscellaneous Directives</td>
<td>89</td>
</tr>
<tr>
<td>5.12 Directives Reference</td>
<td>90</td>
</tr>
<tr>
<td>6.1 Macro Parameters/Substitution Symbols</td>
<td>155</td>
</tr>
<tr>
<td>6.2 Using Macros</td>
<td>156</td>
</tr>
<tr>
<td>6.3 Defining Macros</td>
<td>156</td>
</tr>
<tr>
<td>6.4 Macro Parameters/Substitution Symbols</td>
<td>158</td>
</tr>
</tbody>
</table>
6.3.1 Directives That Define Substitution Symbols ................................................................. 159
6.3.2 Built-In Substitution Symbol Functions ......................................................................... 160
6.3.3 Recursive Substitution Symbols .................................................................................... 161
6.3.4 Forced Substitution ........................................................................................................ 161
6.3.5 Accessing Individual Characters of Subscripted Substitution Symbols ................. 162
6.3.6 Substitution Symbols as Local Variables in Macros .................................................... 163
6.4 Macro Libraries ................................................................................................................ 163
6.5 Using Conditional Assembly in Macros ............................................................................ 164
6.6 Using Labels in Macros ..................................................................................................... 166
6.7 Producing Messages in Macros ........................................................................................ 167
6.8 Using Directives to Format the Output Listing ............................................................... 168
6.9 Using Recursive and Nested Macros ............................................................................... 169
6.10 Macro Directives Summary ............................................................................................ 170

7 Archiver Description .......................................................................................................... 171
7.1 Archiver Overview ............................................................................................................ 172
7.2 The Archiver's Role in the Software Development Flow ............................................... 173
7.3 Invoking the Archiver ....................................................................................................... 174
7.4 Archiver Examples ........................................................................................................... 175
7.5 Library Information Archiver Description ....................................................................... 176
7.5.1 Invoking the Library Information Archiver ................................................................. 176
7.5.2 Library Information Archiver Example ....................................................................... 177
7.5.3 Listing the Contents of an Index Library ................................................................. 177
7.5.4 Requirements ............................................................................................................. 177

8 Linker Description .............................................................................................................. 178
8.1 Linker Overview ............................................................................................................... 179
8.2 The Linker's Role in the Software Development Flow .................................................... 180
8.3 Invoking the Linker .......................................................................................................... 181
8.4 Linker Options ................................................................................................................ 182
8.4.1 Wildcards in File, Section, and Symbol Patterns ......................................................... 185
8.4.2 Specifying C/C++ Symbols with Linker Options ....................................................... 185
8.4.3 Relocation Capabilities (--absolute_exe and --relocatables) .................................... 185
8.4.4 Allocate Memory for Use by the Loader to Pass Arguments (--arg_size Option) .... 186
8.4.5 Compression (--cinit_compression and --copy_compression Option) .................... 186
8.4.6 Compress DWARF Information (--compress_dwarf Option) .................................... 187
8.4.7 Control Linker Diagnostics ......................................................................................... 187
8.4.8 Disable Automatic Library Selection (--disable_auto_rts Option) ......................... 188
8.4.9 Do Not Remove Unused Sections (--unused_section_elimination Option) ............ 188
8.4.10 Linker Command File Preprocessing (--disable_pp, --define and --undefine Options) 188
8.4.11 Error Correcting Code Testing (--ecc Options) ......................................................... 189
8.4.12 Define an Entry Point (--entry_point Option) .......................................................... 190
8.4.13 Set Default Fill Value (--fill_value Option) .............................................................. 190
8.4.14 Define Heap Size (--heap_size Option) ................................................................... 191
8.4.15 Hiding Symbols ......................................................................................................... 191
8.4.16 Alter the Library Search Algorithm (--library Option, --search_path Option, and C6X_C_DIR Environment Variable) ................................................................. 192
8.4.17 Change Symbol Localization ..................................................................................... 194
8.4.18 Create a Map File (--map_file Option) ..................................................................... 195
8.4.19 Managing Map File Contents (--mapfile_contents Option) .................................... 196
8.4.20 Disable Name Demangling (--no_demangle) ............................................................. 197
8.4.21 Merging of Symbolic Debugging Information ......................................................... 197
8.4.22 Strip Symbolic Information (--no_symtable Option) .............................................. 198
8.4.23 Name an Output Module (--output_file Option) ...................................................... 198
8.4.24 Prioritizing Function Placement (--preferred_order Option) .................................... 198
<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>8.4.25 C Language Options (--ram_model and --rom_model Options)</td>
<td>198</td>
</tr>
<tr>
<td>8.4.26 Retain Discarded Sections (--retain Option)</td>
<td>199</td>
</tr>
<tr>
<td>8.4.27 Scan All Libraries for Duplicate Symbol Definitions (--scan_libraries)</td>
<td>199</td>
</tr>
<tr>
<td>8.4.28 Define Stack Size (--stack_size Option)</td>
<td>199</td>
</tr>
<tr>
<td>8.4.29 Enforce Strict Compatibility (--strict_compatibility Option)</td>
<td>200</td>
</tr>
<tr>
<td>8.4.30 Mapping of Symbols (--symbol_map Option)</td>
<td>200</td>
</tr>
<tr>
<td>8.4.31 Generate Far Call Trampolines (--trampolines Option)</td>
<td>200</td>
</tr>
<tr>
<td>8.4.32 Introduce an Unresolved Symbol (--undef_sym Option)</td>
<td>202</td>
</tr>
<tr>
<td>8.4.33 Display a Message When an Undefined Output Section Is Created (--warn_sections)</td>
<td>202</td>
</tr>
<tr>
<td>8.4.34 Generate XML Link Information File (--xml_link_info Option)</td>
<td>203</td>
</tr>
<tr>
<td>8.4.35 Zero Initialization (--zero_init Option)</td>
<td>203</td>
</tr>
<tr>
<td>8.5 Linker Command Files</td>
<td>204</td>
</tr>
<tr>
<td>8.5.1 Reserved Names in Linker Command Files</td>
<td>205</td>
</tr>
<tr>
<td>8.5.2 Constants in Linker Command Files</td>
<td>205</td>
</tr>
<tr>
<td>8.5.3 Accessing Files and Libraries from a Linker Command File</td>
<td>206</td>
</tr>
<tr>
<td>8.5.4 The MEMORY Directive</td>
<td>207</td>
</tr>
<tr>
<td>8.5.5 The SECTIONS Directive</td>
<td>209</td>
</tr>
<tr>
<td>8.5.6 Placing a Section at Different Load and Run Addresses</td>
<td>222</td>
</tr>
<tr>
<td>8.5.7 Using GROUP and UNION Statements</td>
<td>224</td>
</tr>
<tr>
<td>8.5.8 Special Section Types (DSECT, COPY, NOLOAD, and NOINIT)</td>
<td>229</td>
</tr>
<tr>
<td>8.5.9 Configuring Error Correcting Code (ECC) with the Linker</td>
<td>230</td>
</tr>
<tr>
<td>8.5.10 Assigning Symbols at Link Time</td>
<td>231</td>
</tr>
<tr>
<td>8.5.11 Creating and Filling Holes</td>
<td>237</td>
</tr>
<tr>
<td>8.6 Linker Symbols</td>
<td>240</td>
</tr>
<tr>
<td>8.6.1 Using Linker Symbols in C/C++ Applications</td>
<td>240</td>
</tr>
<tr>
<td>8.6.2 Declaring Weak Symbols</td>
<td>241</td>
</tr>
<tr>
<td>8.6.3 Resolving Symbols with Object Libraries</td>
<td>241</td>
</tr>
<tr>
<td>8.7 Default Placement Algorithm</td>
<td>243</td>
</tr>
<tr>
<td>8.7.1 How the Allocation Algorithm Creates Output Sections</td>
<td>243</td>
</tr>
<tr>
<td>8.7.2 Reducing Memory Fragmentation</td>
<td>244</td>
</tr>
<tr>
<td>8.8 Linker-Generated Copy Tables</td>
<td>244</td>
</tr>
<tr>
<td>8.8.1 Using Copy Tables for Boot Loading</td>
<td>244</td>
</tr>
<tr>
<td>8.8.2 Using Built-in Link Operators in Copy Tables</td>
<td>245</td>
</tr>
<tr>
<td>8.8.3 Overlay Management Example</td>
<td>246</td>
</tr>
<tr>
<td>8.8.4 Generating Copy Tables With the table() Operator</td>
<td>246</td>
</tr>
<tr>
<td>8.8.5 Compression</td>
<td>252</td>
</tr>
<tr>
<td>8.8.6 Copy Table Contents</td>
<td>255</td>
</tr>
<tr>
<td>8.8.7 General Purpose Copy Routine</td>
<td>256</td>
</tr>
<tr>
<td>8.9 Partial (Incremental) Linking</td>
<td>257</td>
</tr>
<tr>
<td>8.10 Linking C/C++ Code</td>
<td>258</td>
</tr>
<tr>
<td>8.10.1 Run-Time Initialization</td>
<td>258</td>
</tr>
<tr>
<td>8.10.2 Object Libraries and Run-Time Support</td>
<td>259</td>
</tr>
<tr>
<td>8.10.3 Setting the Size of the Stack and Heap Sections</td>
<td>259</td>
</tr>
<tr>
<td>8.10.4 Initializing and Autonitializing Variables at Run Time</td>
<td>259</td>
</tr>
<tr>
<td>8.11 Linker Example</td>
<td>260</td>
</tr>
<tr>
<td>8.12 Dynamic Linking with the C6000 Code Generation Tools</td>
<td>265</td>
</tr>
<tr>
<td>8.12.1 Static vs Dynamic Linking</td>
<td>265</td>
</tr>
<tr>
<td>8.12.2 Bare-Metal Dynamic Linking Model</td>
<td>266</td>
</tr>
<tr>
<td>8.12.3 Building a Dynamic Executable</td>
<td>268</td>
</tr>
<tr>
<td>8.12.4 Building a Dynamic Library</td>
<td>269</td>
</tr>
<tr>
<td>8.12.5 Symbol Import/Export</td>
<td>271</td>
</tr>
<tr>
<td>9 Object File Utilities</td>
<td>275</td>
</tr>
<tr>
<td>9.1 Invoking the Object File Display Utility</td>
<td>276</td>
</tr>
</tbody>
</table>
11 Sharing C/C++ Header Files With Assembly Source .......................................................... 304

11.1 Overview of the .cdecls Directive .................................................................................. 305

11.2 Notes on C/C++ Conversions ......................................................................................... 305

11.2.1 Comments ................................................................................................................ 305

11.2.2 Conditional Compilation (#if/#else/#ifdef/etc.) ..................................................... 306

11.2.3 Pragmas .................................................................................................................. 306

11.2.4 The #error and #warning Directives ...................................................................... 306

11.2.5 Predefined symbol _ASM_HEADER_ ...................................................................... 306

11.2.6 Usage Within C/C++ asm( ) Statements ................................................................. 306

11.2.7 The #include Directive ......................................................................................... 306

11.2.8 Conversion of #define Macros .............................................................................. 306

11.2.9 The #undef Directive ............................................................................................ 307

11.2.10 Enumerations ....................................................................................................... 307

11.2.11 C Strings .............................................................................................................. 307

11.2.12 C/C++ Built-In Functions .................................................................................... 308

11.2.13 Structures and Unions ......................................................................................... 308

11.2.14 Function/Variable Prototypes .............................................................................. 308

11.2.15 C Constant Suffixes ......................................................................................... 309

9.2 Invoking the Disassembler ............................................................................................... 277

9.3 Invoking the Name Utility ............................................................................................... 277

9.4 Invoking the Strip Utility ................................................................................................. 278

10 Hex Conversion Utility Description ............................................................................... 279

10.1 The Hex Conversion Utility's Role in the Software Development Flow ....................... 280

10.2 Invoking the Hex Conversion Utility ........................................................................... 281

10.2.1 Invoking the Hex Conversion Utility From the Command Line ......................... 281

10.2.2 Invoking the Hex Conversion Utility With a Command File .................................. 283

10.3 Understanding Memory Widths ..................................................................................... 284

10.3.1 Target Width .......................................................................................................... 284

10.3.2 Specifying the Memory Width ................................................................................ 285

10.3.3 Partitioning Data Into Output Files ...................................................................... 286

10.3.4 Specifying Word Order for Output Words ............................................................. 288

10.4 The ROMS Directive .................................................................................................... 288

10.4.1 When to Use the ROMS Directive ......................................................................... 289

10.4.2 An Example of the ROMS Directive ...................................................................... 290

10.5 The SECTIONS Directive ........................................................................................... 292

10.6 The Load Image Format (--load_image Option) .......................................................... 293

10.6.1 Load Image Section Formation .............................................................................. 293

10.6.2 Load Image Characteristics .................................................................................. 293

10.7 Excluding a Specified Section ...................................................................................... 293

10.8 Assigning Output Filenames ......................................................................................... 294

10.9 Image Mode and the --fill Option .............................................................................. 295

10.9.1 Generating a Memory Image ................................................................................ 295

10.9.2 Specifying a Fill Value ......................................................................................... 295

10.9.3 Steps to Follow in Using Image Mode .................................................................. 296

10.10 Controlling the ROM Device Address ....................................................................... 296

10.11 Control Hex Conversion Utility Diagnostics ............................................................... 297

10.12 Description of the Object Formats ............................................................................. 298

10.12.1 ASCII-Hex Object Format (--ascii Option) ............................................................ 298

10.12.2 Intel MCS-86 Object Format (--intel Option) ......................................................... 299

10.12.3 Motorola Exorciser Object Format (--motorola Option) ....................................... 300

10.12.4 Extended Tektronix Object Format (--tektronix Option) ....................................... 301

10.12.5 Texas Instruments SDSMAC (TI-Tagged) Object Format (--ti_tagged Option) ...... 302

10.12.6 Ti-TXT Hex Format (--ti_txt Option) .................................................................... 303

11.11 Overview of the .cdecls Directive .............................................................................. 305

11.2 Notes on C/C++ Conversions ......................................................................................... 305

11.2.1 Comments ................................................................................................................ 305

11.2.2 Conditional Compilation (#if/#else/#ifdef/etc.) ..................................................... 306

11.2.3 Pragmas .................................................................................................................. 306

11.2.4 The #error and #warning Directives ...................................................................... 306

11.2.5 Predefined symbol _ASM_HEADER_ ...................................................................... 306

11.2.6 Usage Within C/C++ asm( ) Statements ................................................................. 306

11.2.7 The #include Directive ......................................................................................... 306

11.2.8 Conversion of #define Macros .............................................................................. 306

11.2.9 The #undef Directive ............................................................................................ 307

11.2.10 Enumerations ....................................................................................................... 307

11.2.11 C Strings .............................................................................................................. 307

11.2.12 C/C++ Built-In Functions .................................................................................... 308

11.2.13 Structures and Unions ......................................................................................... 308

11.2.14 Function/Variable Prototypes .............................................................................. 308

11.2.15 C Constant Suffixes ......................................................................................... 309
## List of Figures

1-1. TMS320C6000 Software Development Flow ................................................................. 14
2-1. Partitioning Memory Into Logical Blocks ................................................................. 19
2-2. Using Sections Directives Example ........................................................................... 24
2-3. Object Code Generated by the File in ........................................................................ 25
2-4. Combining Input Sections to Form an Executable Object Module ......................... 27
3-1. Bootloading Sequence (Simplified) ............................................................................ 34
3-2. Autoinitialization at Run Time .................................................................................... 36
3-3. Initialization at Load Time ......................................................................................... 37
4-1. The Assembler in the TMS320C6000 Software Development Flow ....................... 41
4-2. Example Assembler Listing ....................................................................................... 71
5-1. The .field Directive .................................................................................................. 82
5-2. Initialization Directives ............................................................................................. 83
5-3. The .align Directive .................................................................................................. 83
5-4. The .space and .bes Directives ................................................................................. 84
5-5. Double-Precision Floating-Point Format .................................................................. 105
5-6. The .field Directive .................................................................................................. 114
5-7. Single-Precision Floating-Point Format .................................................................... 115
5-8. The .usect Directive ................................................................................................ 153
7-1. The Archiver in the TMS320C6000 Software Development Flow ......................... 173
8-1. The Linker in the TMS320C6000 Software Development Flow ............................. 180
8-2. Section Placement Defined by ................................................................................ 211
8-3. Run-Time Execution of ............................................................................................ 224
8-4. Memory Allocation Shown in and ............................................................................ 226
8-5. Compressed Copy Table ........................................................................................... 252
8-6. Handler Table ......................................................................................................... 253
8-7. A Basic DSP Run-Time Model ................................................................................. 266
8-8. Dynamic Linking Model ........................................................................................... 267
8-9. Base Image Executable ............................................................................................. 268
10-1. The Hex Conversion Utility in the TMS320C6000 Software Development Flow .... 280
10-2. Hex Conversion Utility Process Flow ....................................................................... 284
10-3. Object File Data and Memory Widths ..................................................................... 285
10-4. Data, Memory, and ROM Widths ............................................................................. 287
10-5. The infile.out File Partitioned Into Four Output Files ........................................... 290
10-6. ASCII-Hex Object Format ...................................................................................... 298
10-7. Intel Hexadecimal Object Format ............................................................................ 299
10-8. Motorola-S Format .................................................................................................. 300
10-9. Extended Tektronix Object Format .......................................................................... 301
10-10. TI-Tagged Object Format ....................................................................................... 302
10-11. TI-TXT Object Format ........................................................................................... 303
List of Tables

4-1. TMS320C6000 Assembler Options ................................................................. 42
4-2. C6000 Processor Symbolic Constants ......................................................... 57
4-3. CPU Control Registers ............................................................................... 57
4-4. Operators Used in Expressions (Precedence) ............................................... 62
4-5. Built-In Mathematical Functions ................................................................ 65
4-6. Symbol Attributes ....................................................................................... 73
5-1. Directives that Control Section Use ............................................................. 75
5-2. Directives that Gather Sections into Common Groups ................................. 75
5-3. Directives that Affect Unused Section Elimination ....................................... 75
5-4. Directives that Initialize Values (Data and Memory) .................................. 75
5-5. Directives that Perform Alignment and Reserve Space ............................... 76
5-6. Directives that Format the Output Listing ................................................... 76
5-7. Directives that Reference Other Files .......................................................... 77
5-8. Directives that Affect Symbol Linkage and Visibility .................................. 77
5-9. Directives that Control Dynamic Symbol Visibility .................................... 77
5-10. Directives that Enable Conditional Assembly .......................................... 77
5-11. Directives that Define Union or Structure Types ....................................... 78
5-12. Directives that Define Symbols .................................................................. 78
5-13. Directives that Create or Affect Macros .................................................... 78
5-14. Directives that Control Diagnostics ............................................................ 79
5-15. Directives that Perform Assembly Source Debug ..................................... 79
5-16. Directives that Perform Miscellaneous Functions ................................... 79
6-1. Substitution Symbol Functions and Return Values .................................... 160
6-2. Creating Macros ......................................................................................... 170
6-3. Manipulating Substitution Symbols ............................................................ 170
6-4. Conditional Assembly ............................................................................... 170
6-5. Producing Assembly-Time Messages .......................................................... 170
6-6. Formatting the Listing ................................................................................ 170
8-1. Basic Options Summary ............................................................................. 182
8-2. File Search Path Options Summary ............................................................ 182
8-3. Command File Preprocessing Options Summary ....................................... 182
8-4. Diagnostic Options Summary .................................................................... 182
8-5. Linker Output Options Summary ................................................................. 183
8-6. Symbol Management Options Summary ................................................... 183
8-7. Run-Time Environment Options Summary ................................................ 183
8-8. Link-Time Optimization Options Summary ................................................ 184
8-9. Dynamic Linking Options Summary ........................................................... 184
8-10. Miscellaneous Options Summary ............................................................... 184
8-11. Predefined C6000 Macro Names ............................................................... 189
8-12. Groups of Operators Used in Expressions (Precedence) ......................... 233
8-13. Compiler Options For Dynamic Linking .................................................... 270
8-14. Linker Options For Dynamic Linking ........................................................ 271
10-1. Basic Hex Conversion Utility Options ..................................................... 281
10-2. Options for Specifying Hex Conversion Formats ..................................... 298
A-1. Symbolic Debugging Directives ................................................................. 313
D-1. Revision History ......................................................................................... 328
About This Manual

This document describes support for the C64+, C6740, and C6600 variants of the TMS320C6000™ processor series. The C6200, C6400, C6700, and C6700+ variants are not supported in v8.0 and later versions of the TI Code Generation Tools. If you are using one of these legacy devices, please use v7.4 of the Code Generation Tools and refer to SPRU186 and SPRU187 for documentation.

The TMS320C6000 Assembly Language Tools User's Guide explains how to use these object file tools:

- Assembler
- Archiver
- Linker
- Library information archiver
- Disassembler
- Object file display utility
- Name utility
- Strip utility
- Hex conversion utility

How to Use This Manual

This book helps you learn how to use the Texas Instruments object file and assembly language tools designed specifically for the TMS320C6000™ 32-bit devices. This book consists of four parts:

- **Introductory information**, consisting of Chapter 1 through Chapter 3, gives you an overview of the object file and assembly language development tools. Chapter 2, in particular, explains object modules and how they can be managed to help your TMS320C6000 application load and run. It is highly recommended that developers become familiar with what object modules are and how they are used before using the assembler and linker.

- **Assembler description**, consisting of Chapter 4 through Chapter 6, contains detailed information about using the assembler. Chapter 4 and Chapter 5 explain how to invoke the assembler and discuss source statement format, valid constants and expressions, assembler output, and assembler directives. Chapter 6 focuses on the macro language.

- **Linker and other object file tools description**, consisting of Chapter 7 through Chapter 10, describes in detail each of the tools provided with the assembler to help you create executable object files. Chapter 7 provides details about using the archiver to create object libraries. Chapter 8 explains how to invoke the linker, how the linker operates, and how to use linker directives. Chapter 9 provides a brief overview of some of the object file utilities that can be useful in examining the content of object files as well as removing symbol and debug information to reduce the size of a given object file. Chapter 10 explains how to use the hex conversion utility.

- **Additional Reference material**, consisting of Appendix A through Appendix C, provides supplementary information including symbolic debugging directives used by the TMS320C6000 C/C++ compiler. A description of the XML link information file and a glossary are also provided.
Notational Conventions

This document uses the following conventions:

- Program listings, program examples, and interactive displays are shown in a special typeface. Interactive displays use a bold version of the special typeface to distinguish commands that you enter from items that the system displays (such as prompts, command output, error messages, etc.).

Here is a sample of C code:

```c
#include <stdio.h>
main()
{
    printf("hello world\n");
}
```

- In syntax descriptions, the instruction, command, or directive is in a bold typeface and parameters are in an italic typeface. Portions of a syntax that are in bold should be entered as shown; portions of a syntax that are in italics describe the type of information that should be entered.

- Square brackets ([ and ]) identify an optional parameter. If you use an optional parameter, you specify the information within the brackets. Unless the square brackets are in the bold typeface, do not enter the brackets themselves. The following is an example of a command that has an optional parameter:

```
cl6x [options] [filenames] [--run_linker [link_options] [object files]]
```

- Braces ({ and }) indicate that you must choose one of the parameters within the braces; you do not enter the braces themselves. This is an example of a command with braces that are not included in the actual syntax but indicate that you must specify either the --rom_model or --ram_model option:

```
cl6x --run_linker {--rom_model | --ram_model} filenames [--output_file= name.out]
```

- In assembler syntax statements, The leftmost character position, column 1, is reserved for the first character of a label or symbol. If the label or symbol is optional, it is usually not shown. If it is a required parameter, it is shown starting against the left margin of the box, as in the example below. No instruction, command, directive, or parameter, other than a symbol or label, can begin in column 1.

```
symbol .usect "section name", size in bytes[, alignment]
```

- Some directives can have a varying number of parameters. For example, the .byte directive can have multiple parameters. This syntax is shown as [..., parameter].

```
.byte parameter[, ..., parameter]
```

- The TMS320C64x+ devices are referred to as C64x+. The TMS320C6600 devices are referred to as C6600. The TMS320C6740 devices are referred to as C6740.

- Other symbols and abbreviations used throughout this document include the following:

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>B, b</td>
<td>Suffix — binary integer</td>
</tr>
<tr>
<td>H, h</td>
<td>Suffix — hexadecimal integer</td>
</tr>
<tr>
<td>LSB</td>
<td>Least significant bit</td>
</tr>
<tr>
<td>MSB</td>
<td>Most significant bit</td>
</tr>
<tr>
<td>0x</td>
<td>Prefix — hexadecimal integer</td>
</tr>
<tr>
<td>Q, q</td>
<td>Suffix — octal integer</td>
</tr>
</tbody>
</table>
Related Documentation From Texas Instruments

See the following resources for further information about the TI Code Generation Tools:

- Texas Instruments Wiki: Compiler topics
- Texas Instruments E2E Community: Compiler forum

You can use the following books to supplement this user's guide:

**SPRU04 — TMS320C6000 Optimizing C/C++ Compiler User's Guide.** Describes the TMS320C6000 C/C++ compiler and the assembly optimizer. This C/C++ compiler accepts ANSI standard C/C++ source code and produces assembly language source code for the for the C64+, C6740, and C6600 variants of the TMS320C6000 platform of devices. Refer to SPRU187 when using legacy C6200, C6400, C6700, and C6700+ devices. The assembly optimizer helps you optimize your assembly code.

**SPRAB89— C6000 Embedded Application Binary Interface.** Provides a specification for the ELF-based Embedded Application Binary Interface (EABI) for the C6000 family of processors from Texas Instruments. The EABI defines the low-level interface between programs, program components, and the execution environment, including the operating system if one is present.

**SPRU190 — TMS320C6000 DSP Peripherals Overview Reference Guide.** Provides an overview and briefly describes the peripherals available on the TMS320C6000 family of digital signal processors (DSPs).

**SPRU732 — TMS320C64x/C64x+ DSP CPU and Instruction Set Reference Guide.** Describes the CPU architecture, pipeline, instruction set, and interrupts for the TMS320C64x and TMS320C64x+ digital signal processors (DSPs) of the TMS320C6000 DSP family. The C64x/C64x+ DSP generation comprises fixed-point devices in the C6000 DSP platform. The C64x+ DSP is an enhancement of the C64x DSP with added functionality and an expanded instruction set.

**SPRUGH7 — TMS320C66x CPU and Instruction Set Reference Guide.** Describes the CPU architecture, pipeline, instruction set, and interrupts for the TMS320C66x digital signal processors (DSPs) of the TMS320C6000 DSP platform. The C66x DSP generation comprises floating-point devices in the C6000 DSP platform.

**SPRUEF8— TMS320C674x CPU and Instruction Set Reference Guide.** Describes the CPU architecture, pipeline, instruction set, and interrupts for the TMS320C674x digital signal processors (DSPs) of the TMS320C6000 DSP platform. The C674x is a floating-point DSP that combines the TMS320C67x™ DSP and the TMS320C64x+™ DSP instruction set architectures into one core.
The TMS320C6000™ is supported by a set of software development tools, which includes an optimizing C/C++ compiler, an assembly optimizer, an assembler, a linker, and assorted utilities. This chapter provides an overview of these tools.

The TMS320C6000 is supported by the following assembly language development tools:

- Assembler
- Archiver
- Linker
- Library information archiver
- Object file display utility
- Disassembler
- Name utility
- Strip utility
- Hex conversion utility

This chapter shows how these tools fit into the general software tools development flow and gives a brief description of each tool. For convenience, it also summarizes the C/C++ compiler and debugging tools. For detailed information on the compiler and debugger, and for complete descriptions of the TMS320C6000, refer to the books listed in Related Documentation From Texas Instruments.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.1 Software Development Tools Overview</td>
<td>14</td>
</tr>
<tr>
<td>1.2 Tools Descriptions</td>
<td>15</td>
</tr>
</tbody>
</table>
1.1 Software Development Tools Overview

Figure 1-1 shows the TMS320C6000 software development flow. The shaded portion highlights the most common development path; the other portions are optional. The other portions are peripheral functions that enhance the development process.

Figure 1-1. TMS320C6000 Software Development Flow
1.2 Tools Descriptions

The following list describes the tools that are shown in Figure 1-1:

- **The C/C++ compiler** accepts C/C++ source code and produces TMS320C6000 machine code object modules. See the *TMS320C6000 Optimizing Compiler User's Guide* for more information.

- **The assembly optimizer** allows you to write linear assembly code without being concerned with the pipeline structure or with assigning registers. It accepts assembly code that has not been register-allocated and is unscheduled. The assembly optimizer assigns registers and uses loop optimization to turn linear assembly into highly parallel assembly that takes advantage of software pipelining. See the *TMS320C6000 Optimizing Compiler User's Guide* for more information.

- **The assembler** translates assembly language source files into machine language object modules. Source files can contain instructions, assembler directives, and macro directives. You can use assembler directives to control the assembly process, including the source listing format, data alignment, and section content. See Chapter 4 through Chapter 6. See the *TMS320C64x/C64x+ DSP CPU and Instruction Set Reference Guide (SPRU732)*, *TMS320C66x CPU and Instruction Set Reference Guide (SPRUGH7)*, and *TMS320C674x CPU and Instruction Set Reference Guide (SPRUF8)* for detailed information on the assembly language instruction set.

- **The linker** combines object files into a single static executable or dynamic object module. It performs symbolic relocation and resolves external references. The linker accepts relocatable object modules (created by the assembler) as input. It also accepts archiver library members and output modules created by a previous linker run. Link directives allow you to combine object file sections, bind sections or symbols to addresses or within memory ranges, and define global symbols. See Chapter 8. For more information about creating a dynamic object module, see Chapter 14 of *The C6000 Embedded Application Binary Interface Application Report (SPRAB89)*.

- **The archiver** allows you to collect a group of files into a single archive file, called a library. The most common use of the archiver is to collect a group of object files into an object library. The linker extracts object library members to resolve external references during the link. You can also use the archiver to collect several macros into a macro library. The assembler searches the library and uses the members that are called as macros by the source file. The archiver allows you to modify a library by deleting, replacing, extracting, or adding members. See Section 7.1.

- **The library information archiver** allows you to create an index library of several object file library variants, which is useful when several variants of a library with different options are available. Rather than refer to a specific library, you can link against the index library, and the linker will choose the best match from the indexed libraries. See Section 7.5 for more information about using the archiver to manage the content of a library.

- **You can use the library-build utility** to build your own customized run-time-support library. See the *TMS320C6000 Optimizing Compiler User's Guide* for more information.

- **The hex conversion utility** converts object files to TI-Tagged, ASCII-Hex, Intel, Motorola-S, or Tektronix object format. Converted files can be downloaded to an EPROM programmer. See Chapter 10.

- **The main product of this development process is a executable object file that can be executed on a TMS320C6000 device.** You can use an XDS emulator when refining and correcting your code.
In addition, the following utilities are provided to help examine or manage the content of a given object file:

- The **object file display utility** prints the contents of object files and object libraries in either human readable or XML formats. See Section 9.1.
- The **disassembler** decodes the machine code from object modules to show the assembly instructions that it represents. See Section 9.2.
- The **name utility** prints a list of symbol names for objects and functions defined or referenced in an object file or object archive. See Section 9.3.
- The **strip utility** removes symbol table and debugging information from object files and object libraries. See Section 9.4.
The assembler creates object modules from assembly code, and the linker creates executable object files from object modules. These executable object files can be executed by a TMS320C6000 device.

Object modules make modular programming easier because they encourage you to think in terms of blocks of code and data when you write an assembly language program. These blocks are known as sections. Both the assembler and the linker provide directives that allow you to create and manipulate sections.

This chapter focuses on the concept and use of sections in assembly language programs.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.1 Object File Format Specifications</td>
<td>18</td>
</tr>
<tr>
<td>2.2 Executable Object Files</td>
<td>18</td>
</tr>
<tr>
<td>2.3 Introduction to Sections</td>
<td>18</td>
</tr>
<tr>
<td>2.4 How the Assembler Handles Sections</td>
<td>19</td>
</tr>
<tr>
<td>2.5 How the Linker Handles Sections</td>
<td>26</td>
</tr>
<tr>
<td>2.6 Symbols</td>
<td>28</td>
</tr>
<tr>
<td>2.7 Symbolic Relocations</td>
<td>30</td>
</tr>
<tr>
<td>2.8 Loading a Program</td>
<td>31</td>
</tr>
</tbody>
</table>
2.1 Object File Format Specifications

The object files created by the assembler and linker conform to the ELF (Executable and Linking Format) binary format, which is used by the Embedded Application Binary Interface (EABI). See the *TMS320C6000 Optimizing Compiler User's Guide* (SPRUI04) and *The C6000 Embedded Application Binary Interface Application Report* (SPRAR89) for information on the EABI ABI.

COFF object files are not supported in v8.0 and later versions of the TI Code Generation Tools. If you would like to produce COFF output files, please use v7.4 of the Code Generation Tools and refer to SPRU186 for documentation.

The ELF object files generated by the assembler and linker conform to the December 17, 2003 snapshot of the System V generic ABI (or gABI).

2.2 Executable Object Files

The linker can be used to produce static executable object modules. An executable object module has the same format as object files that are used as linker input. The sections in an executable object module, however, have been combined and placed in target memory, and the relocations are all resolved.

To run a program, the data in the executable object module must be transferred, or loaded, into target system memory. See Chapter 3 for details about loading and running programs.

2.3 Introduction to Sections

The smallest unit of an object file is a section. A section is a block of code or data that occupies contiguous space in the memory map. Each section of an object file is separate and distinct.

ELF format executable object files contain segments. An ELF segment is a meta-section. It represents a contiguous region of target memory. It is a collection of sections that have the same property, such as writeable or readable. An ELF loader needs the segment information, but does not need the section information. The ELF standard allows the linker to omit ELF section information entirely from the executable object file.

Object files usually contain three default sections:

<table>
<thead>
<tr>
<th>Section</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>.text</td>
<td>contains executable code</td>
</tr>
<tr>
<td>.data</td>
<td>usually contains initialized data</td>
</tr>
<tr>
<td>.bss</td>
<td>usually reserves space for uninitialized variables</td>
</tr>
</tbody>
</table>

(1) Some targets allow content other than text, such as constants, in .text sections.

The assembler and linker allow you to create, name, and link other kinds of sections. The .text, .data, and .bss sections are archetypes for how sections are handled.

There are two basic types of sections:

**Initialized sections**

contain data or code. The .text and .data sections are initialized; user-named sections created with the .sect assembler directive are also initialized.

**Uninitialized sections**

reserve space in the memory map for uninitialized data. The .bss section is uninitialized; user-named sections created with the .usect assembler directive are also uninitialized.
Several assembler directives allow you to associate various portions of code and data with the appropriate sections. The assembler builds these sections during the assembly process, creating an object file organized as shown in Figure 2-1.

One of the linker's functions is to relocate sections into the target system's memory map; this function is called placement. Because most systems contain several types of memory, using sections can help you use target memory more efficiently. All sections are independently relocatable; you can place any section into any allocated block of target memory. For example, you can define a section that contains an initialization routine and then allocate the routine in a portion of the memory map that contains ROM. For information on section placement, see the “Specifying Where to Allocate Sections in Memory” section of the TMS320C6000 Optimizing Compiler User's Guide.

Figure 2-1 shows the relationship between sections in an object file and a hypothetical target memory.

![Figure 2-1. Partitioning Memory Into Logical Blocks](image)

### 2.3.1 Special Section Names

You can use the .sect and .usect directives to create any section name you like, but certain sections are treated in a special manner by the linker and the compiler's run-time support library. If you create a section with the same name as a special section, you should take care to follow the rules for that special section.

A few common special sections are:

- `.text` -- Used for program code.
- `.bss` -- Used for uninitialized objects (global variables).
- `.data` -- Used for initialized non-const objects (global variables).
- `.const` -- Used for initialized const objects (string constants, variables declared const).
- `.cinit` -- Used to initialize C global variables at startup.
- `.stack` -- Used for the function call stack.
- `.sysmem` - Used for the dynamic memory allocation pool.

For more information on sections, see the "Specifying Where to Allocate Sections in Memory" section of the TMS320C6000 Optimizing Compiler User's Guide.

### 2.4 How the Assembler Handles Sections

The assembler identifies the portions of an assembly language program that belong in a given section. The assembler has the following directives that support this function:

- `.bss`
- `.data`
- `.sect`
- `.text`
- `.usect`

The `.bss` and `.usect` directives create uninitialized sections; the `.text`, `.data`, and `.sect` directives create initialized sections.
You can create subsections of any section to give you tighter control of the memory map. Subsections are created using the .sect and .usect directives. Subsections are identified with the base section name and a subsection name separated by a colon; see Section 2.4.6.

### Default Sections Directive

**NOTE:** If you do not use any of the sections directives, the assembler assembles everything into the .text section.

### 2.4.1 Uninitialized Sections

Uninitialized sections reserve space in TMS320C6000 memory; they are usually placed in RAM. These sections have no actual contents in the object file; they simply reserve memory. A program can use this space at run time for creating and storing variables.

Uninitialized data areas are built by using the following assembler directives.

- The .bss directive reserves space in the .bss section.
- The .usect directive reserves space in a specific uninitialized user-named section.

Each time you invoke the .bss or .usect directive, the assembler reserves additional space in the .bss or the user-named section. The syntax is:

```
.bss symbol, size in bytes[, alignment[, bank offset]]

.symbol .usect "section name", size in bytes[, alignment[, bank offset]]
```

- **symbol** points to the first byte reserved by this invocation of the .bss or .usect directive. The symbol corresponds to the name of the variable that you are reserving space for. It can be referenced by any other section and can also be declared as a global symbol (with the .global directive).
- **size in bytes** is an absolute expression (see Section 4.9). The .bss directive reserves size in bytes bytes in the .bss section. The .usect directive reserves size in bytes bytes in section name. For both directives, you must specify a size; there is no default value.
- **alignment** is an optional parameter. It specifies the minimum alignment in bytes required by the space allocated. The default value is byte aligned; this option is represented by the value 1. The value must be a power of 2.
- **bank offset** is an optional parameter. It ensures that the space allocated to the symbol occurs on a specific memory bank boundary. The bank offset measures the number of bytes to offset from the alignment specified before assigning the symbol to that location.
- **section name** specifies the user-named section in which to reserve space. See Section 2.4.3.

Initialized section directives (.text, .data, and .sect) change which section is considered the current section (see Section 2.4.2). However, the .bss and .usect directives do not change the current section; they simply escape from the current section temporarily. Immediately after a .bss or .usect directive, the assembler resumes assembling into whatever the current section was before the directive. The .bss and .usect directives can appear anywhere in an initialized section without affecting its contents. For an example, see Section 2.4.7.

The .usect directive can also be used to create uninitialized subsections. See Section 2.4.6 for more information on creating subsections.

The .nearcommon and .farcommon directives are similar to directives that create uninitialized data sections, except that common symbols are created, instead.
2.4.2 Initialized Sections

Initialized sections contain executable code or initialized data. The contents of these sections are stored in the object file and placed in TMS320C6000 memory when the program is loaded. Each initialized section is independently relocatable and may reference symbols that are defined in other sections. The linker automatically resolves these references. The following directives tell the assembler to place code or data into a section. The syntaxes for these directives are:

```
.text
.data
.sect "section name"
```

The .sect directive can also be used to create initialized subsections. See Section 2.4.6, for more information on creating subsections.

2.4.3 User-Named Sections

User-named sections are sections that you create. You can use them like the default .text, .data, and .bss sections, but each section with a distinct name is kept distinct during assembly.

For example, repeated use of the .text directive builds up a single .text section in the object file. This .text section is allocated in memory as a single unit. Suppose there is a portion of executable code (perhaps an initialization routine) that you want the linker to place in a different location than the rest of .text. If you assemble this segment of code into a user-named section, it is assembled separately from .text, and you can use the linker to allocate it into memory separately. You can also assemble initialized data that is separate from the .data section, and you can reserve space for uninitialized variables that is separate from the .bss section.

These directives let you create user-named sections:

- The .usect directive creates uninitialized sections that are used like the .bss section. These sections reserve space in RAM for variables.
- The .sect directive creates initialized sections, like the default .text and .data sections, that can contain code or data. The .sect directive creates user-named sections with relocatable addresses.

The syntaxes for these directives are:

```
symbol .usect "section name", size in bytes[, alignment[, bank offset]]
.sect "section name"
```

The maximum number of sections is $2^{32} - 1$ (4294967295).

The `section name` parameter is the name of the section. For the .usect and .sect directives, a section name can refer to a subsection; see Section 2.4.6 for details.

Each time you invoke one of these directives with a new name, you create a new user-named section. Each time you invoke one of these directives with a name that was already used, the assembler resumes assembling code or data (or reserves space) into the section with that name. You cannot use the same names with different directives. That is, you cannot create a section with the .usect directive and then try to use the same section with .sect.
2.4.4 Current Section

The assembler adds code or data to one section at a time. The section the assembler is currently filling is the \textit{current section}. The .text, .data, and .sect directives change which section is considered the current section. When the assembler encounters one of these directives, it stops assembling into the current section (acting as an implied end of current section command). The assembler sets the designated section as the current section and assembles subsequent code into the designated section until it encounters another .text, .data, or .sect directive.

If one of these directives sets the current section to a section that already has code or data in it from earlier in the file, the assembler resumes adding to the end of that section. The assembler generates only one contiguous section for each given section name. This section is formed by concatenating all of the code or data which was placed in that section.

2.4.5 Section Program Counters

The assembler maintains a separate program counter for each section. These program counters are known as section program counters, or SPCs.

An SPC represents the current address within a section of code or data. Initially, the assembler sets each SPC to 0. As the assembler fills a section with code or data, it increments the appropriate SPC. If you resume assembling into a section, the assembler remembers the appropriate SPC's previous value and continues incrementing the SPC from that value.

The assembler treats each section as if it began at address 0; the linker relocates the symbols in each section according to the final address of the section in which that symbol is defined. See Section 2.7 for information on relocation.

2.4.6 Subsections

A subsection is created by creating a section with a colon in its name. Subsections are logical subdivisions of larger sections. Subsections are themselves sections and can be manipulated by the assembler and linker.

The assembler has no concept of subsections; to the assembler, the colon in the name is not special. The subsection .text:rtos would be considered completely unrelated to its parent section .text, and the assembler will not combine subsections with their parent sections.

Subsections are used to keep parts of a section as distinct sections so that they can be separately manipulated. For instance, by placing each function and object in a uniquely-named subsection, the linker gets a finer-grained view of the section for memory placement and unused-function elimination.

By default, when the linker sees a SECTION directive in the linker command file like ".text", it will gather .text and all subsections of .text into one large output section named ".text". You can instead use the SECTION directive to control the subsection independently. See Section 8.5.5.1 for an example.

You can create subsections in the same way you create other user-named sections: by using the .sect or .usect directive.

The syntaxes for a subsection name are:

\begin{verbatim}
  symbol .usect "section_name:subsection_name",size in bytes,[alignment],[bank offset]]
  .sect "section_name:subsection_name"
\end{verbatim}

A subsection is identified by the base section name followed by a colon and the name of the subsection. The subsection name may not contain any spaces.

A subsection can be allocated separately or grouped with other sections using the same base name. For example, you create a subsection called \_func within the .text section:

\begin{verbatim}
  .sect ".text:\_func"
\end{verbatim}

Using the linker's SECTIONS directive, you can allocate .text:\_func separately, or with all the .text sections.
You can create two types of subsections:

- Initialized subsections are created using the .sect directive. See Section 2.4.2.
- Uninitialized subsections are created using the .usect directive. See Section 2.4.1.

Subsections are placed in the same manner as sections. See Section 8.5.5 for information on the SECTIONS directive.

### 2.4.7 Using Sections Directives

Figure 2-2 shows how you can build sections incrementally, using the sections directives to swap back and forth between the different sections. You can use sections directives to begin assembling into a section for the first time, or to continue assembling into a section that already contains code. In the latter case, the assembler simply appends the new code to the code that is already in the section.

The format in Figure 2-2 is a listing file. Figure 2-2 shows how the SPCs are modified during assembly. A line in a listing file has four fields:

- **Field 1** contains the source code line counter.
- **Field 2** contains the section program counter.
- **Field 3** contains the object code.
- **Field 4** contains the original source statement.

See Section 4.11 for more information on interpreting the fields in a source listing.
### Figure 2-2. Using Sections Directives Example

```
1  400000000  .data
2  500000000  00000011  coeff  .word  011h,022h
00000004  0000022
6  7  8  9  10
11 12 13  14 00000008  0001234  ptr  .word  01234h
15  16  17
18 00000000  .text
19 00000000  00800528  sum:  MVK  10,A1
20 00000004  021085E0  ZERO  A4
21
22 00000008  01003664  aloop:  LDW  *A0++,A2
23 0000000c  00040000  NOP  3
24 0000010  0087E1A0  SUB  A1,1,A1
25 0000014  021041E0  ADD  A2,A4,A4
26 0000018  08000112  [A1]  B  aloop
27 000001c  00080000  NOP  5
28
29 0000020  0200007c-  STW  A4, +B14(var1)
30
31 32
33 34 0000000c  00000aa  ivals .word  0aah,0bbh,0cch
0000010  00000bb
0000014  00000cc
35
36
37
38 00000000  var2  .usect  "newvars",4
39 00000004  inbuf  .usect  "newvars",4
40
41 42
43 00000024  .text
44 00000024  01003664  xmult:  LDW  *A0++,A2
45 00000028  00060000  NOP  4
46 0000002c  02c44480  MPYHL  A2,A3,A4
47 00000030  02800028-  MVKL  var2,A5
48 00000034  02800068-  MVKH  var2,A5
49 00000038  02104274  STW  A4,*A5
50
51
52
53 00000000  .sect  "vectors"
54 00000000  00000012  B  sum
55 00000004  00008000  NOP  5
```

Field 1  Field 2  Field 3  Field 4

---

**How the Assembler Handles Sections**

www.ti.com

---

**Introduction to Object Modules**

SPRUI03A—January 2016

Copyright © 2016, Texas Instruments Incorporated

Submit Documentation Feedback
As Figure 2-3 shows, the file in Figure 2-2 creates five sections:

- **.text** contains 15 32-bit words of object code.
- **.data** contains six words of initialized data.
- **vectors** is a user-named section created with the .sect directive; it contains two words of object code.
- **.bss** reserves 44 bytes in memory.
- **newvars** is a user-named section created with the .usect directive; it contains eight bytes in memory.

The second column shows the object code that is assembled into these sections; the first column shows the source statements that generated the object code.

### Figure 2-3. Object Code Generated by the File in Figure 2-2

<table>
<thead>
<tr>
<th>Line numbers</th>
<th>Object code</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>19</td>
<td>00800528</td>
<td>.text</td>
</tr>
<tr>
<td>20</td>
<td>021085E0</td>
<td>.text</td>
</tr>
<tr>
<td>22</td>
<td>01003664</td>
<td>.text</td>
</tr>
<tr>
<td>23</td>
<td>00004000</td>
<td>.text</td>
</tr>
<tr>
<td>24</td>
<td>0087E1A0</td>
<td>.text</td>
</tr>
<tr>
<td>25</td>
<td>021041E0</td>
<td>.text</td>
</tr>
<tr>
<td>26</td>
<td>80000112</td>
<td>.text</td>
</tr>
<tr>
<td>27</td>
<td>00008000</td>
<td>.text</td>
</tr>
<tr>
<td>29</td>
<td>020007C-</td>
<td>.text</td>
</tr>
<tr>
<td>44</td>
<td>01003664</td>
<td>.text</td>
</tr>
<tr>
<td>45</td>
<td>00008000</td>
<td>.text</td>
</tr>
<tr>
<td>46</td>
<td>020C4480</td>
<td>.text</td>
</tr>
<tr>
<td>47</td>
<td>02800028-</td>
<td>.text</td>
</tr>
<tr>
<td>48</td>
<td>02800068-</td>
<td>.text</td>
</tr>
<tr>
<td>49</td>
<td>02140274</td>
<td>.text</td>
</tr>
<tr>
<td>5</td>
<td>00000011</td>
<td>.data</td>
</tr>
<tr>
<td>5</td>
<td>00000022</td>
<td>.data</td>
</tr>
<tr>
<td>14</td>
<td>00001234</td>
<td>.data</td>
</tr>
<tr>
<td>34</td>
<td>000000AA</td>
<td>.data</td>
</tr>
<tr>
<td>34</td>
<td>000000BB</td>
<td>.data</td>
</tr>
<tr>
<td>34</td>
<td>000000CC</td>
<td>.data</td>
</tr>
<tr>
<td>54</td>
<td>0000000'</td>
<td>vectors</td>
</tr>
<tr>
<td>54</td>
<td>00000024'</td>
<td>vectors</td>
</tr>
<tr>
<td>9</td>
<td>No data—</td>
<td>.bss</td>
</tr>
<tr>
<td>10</td>
<td>44 bytes</td>
<td>.bss</td>
</tr>
<tr>
<td>10</td>
<td>reserved</td>
<td>.bss</td>
</tr>
<tr>
<td>38</td>
<td>No data—</td>
<td>newvars</td>
</tr>
<tr>
<td>39</td>
<td>8 bytes</td>
<td>newvars</td>
</tr>
<tr>
<td>39</td>
<td>reserved</td>
<td>newvars</td>
</tr>
</tbody>
</table>
2.5 How the Linker Handles Sections

The linker has two main functions related to sections. First, the linker uses the sections in object files as building blocks; it combines input sections to create output sections in an executable output module. Second, the linker chooses memory addresses for the output sections; this is called placement. Two linker directives support these functions:

- The MEMORY directive allows you to define the memory map of a target system. You can name portions of memory and specify their starting addresses and their lengths.
- The SECTIONS directive tells the linker how to combine input sections into output sections and where to place these output sections in memory.

Subsections let you manipulate the placement of sections with greater precision. You can specify the location of each subsection with the linker's SECTIONS directive. If you do not specify a subsection, the subsection is combined with the other sections with the same base section name. See Section 8.5.5.1.

It is not always necessary to use linker directives. If you do not use them, the linker uses the target processor's default placement algorithm described in Section 8.7. When you do use linker directives, you must specify them in a linker command file.

Refer to the following sections for more information about linker command files and linker directives:

- Section 8.5, Linker Command Files
- Section 8.5.4, The MEMORY Directive
- Section 8.5.5, The SECTIONS Directive
- Section 8.7, Default Placement Algorithm

2.5.1 Combining Input Sections

Figure 2-4 provides a simplified example of the process of linking two files together.

Note that this is a simplified example, so it does not show all the sections that will be created or the actual sequence of the sections. See Section 8.7 for the actual default memory placement map for TMS320C6000.
In Figure 2-4, file1.obj and file2.obj have been assembled to be used as linker input. Each contains the .text, .data, and .bss default sections; in addition, each contains a user-named section. The executable object module shows the combined sections. The linker combines the .text section from file1.obj and the .text section from file2.obj to form one .text section, then combines the two .data sections and the two .bss sections, and finally places the user-named sections at the end. The memory map shows the combined sections to be placed into memory.

### 2.5.2 Placing Sections

Figure 2-4 illustrates the linker's default method for combining sections. Sometimes you may not want to use the default setup. For example, you may not want all of the .text sections to be combined into a single .text section. Or you may want a user-named section placed where the .data section would normally be allocated. Most memory maps contain various types of memory (RAM, ROM, EPROM, FLASH, etc.) in varying amounts; you may want to place a section in a specific type of memory.

For further explanation of section placement within the memory map, see the discussions in Section 8.5.4 and Section 8.5.5. See Section 8.7 for the actual default memory allocation map for TMS320C6000.
2.6 Symbols

An object file contains a symbol table that stores information about external symbols in the object file. The linker uses this table when it performs relocation. See Section 2.7.

An object file symbol is a named 32-bit integer value, usually representing an address. A symbol can represent such things as the starting address of a function, variable, or section.

An object file symbol can also represent an absolute integer, such as the size of the stack. To the linker, this integer is an unsigned value, but the integer may be treated as signed or unsigned depending on how it is used. The range of legal values for an absolute integer is 0 to 2^32-1 for unsigned treatment and -2^31 to 2^31-1 for signed treatment.

Symbols can be bound as global symbols, local symbols, or weak symbols. The linker handles symbols differently based on their binding. For example, the linker does not allow multiple global definitions of a symbol, but local symbols can be defined in multiple object files (but only once per object file). The linker does not resolve references to local symbols in different object files, but it does resolve references to global symbols in any other object file.

A global symbol is defined in the same manner as any other symbol; that is, it appears as a label or is defined by a directive, such as .set, .equ, .bss, or .usect. If a global symbol is defined more than once, the linker issues a multiple-definition error. (The assembler can provide a similar multiple-definition error for local symbols.)

A weak symbol is a symbol that is used in the current module but is defined in another module. The linker resolves this symbol’s definition at link time. Weak symbols are similar to global symbols, except that if one object file contains a weak symbol, and another object file contains a global symbol with the same name, the global symbol is used to resolve references. A weak reference may be unresolved at link time, in which case the address is treated as 0. Therefore, for weak references, application code must test to make sure &var is not zero before attempting to read the contents. See Section 2.6.2 for more about weak symbols.

See Section 4.8 for information about assembler symbols.

2.6.1 External Symbols

External symbols are symbols that are visible to other object modules. Because they are visible across object modules, they may be defined in one file and referenced in another file. You can use the .def, .ref, or .global directive to identify a symbol as external:

```
.def x
.ref y
.global z
.global q
```

The following code fragment illustrates these definitions.

```
q: B B3
   NOP 4
   MVK 1, B1
x: MV A0, A1
   MVKL y, B3
   MVKH y, B3
   B z
   NOP 5
```

See Section 4.8 for information about assembler symbols.
In this example, the .def definition of x says that it is an external symbol defined in this file and that other files can reference x. The .ref definition of y says that it is an undefined symbol that is defined in another file. The .global definition of z says that it is defined in some file and available in this file. The .global definition of q says that it is defined in this file and that other files can reference q.

The assembler places x, y, z, and q in the object file’s symbol table. When the file is linked with other object files, the entries for x and q resolve references to x and q in other files. The entries for y and z cause the linker to look through the symbol tables of other files for y’s and z’s definitions.

The linker attempts to match all references with corresponding definitions. If the linker cannot find a symbol's definition, it prints an error message about the unresolved reference. This type of error prevents the linker from creating an executable object module.

An error also occurs if the same symbol is defined more than once.

### 2.6.2 Weak Symbols

The linker processes absolute symbols that are defined with "weak" binding differently from absolute symbols that are defined with global binding (the default). Instead of including a weak absolute symbol in the output file's symbol table by default (as it would for a global absolute symbol), the linker only includes a weak absolute symbol in the output of a "final" link if the symbol is required to resolve an otherwise unresolved reference.

This weak symbol handling allows you to associate addresses with symbols known to have been pre-loaded (such as function addresses in system memory) and then link the current application against a pre-loaded memory image. If such symbols are defined as weak absolute symbols, the linker can minimize the number of symbols it includes in the output file's symbol table by omitting those that are not needed to resolve references. Reducing the size of the output file's symbol table reduces the time required to link, especially if there are a large number of pre-loaded symbols to link against. This feature is particularly helpful for OpenCL applications.

You can define a weak absolute symbol using either assembly or the linker command file.

**Using Assembly:** To define a weak absolute symbol in an input object file, the source file can be written in assembly. Use the .weak and .set directives in combination as shown in the following example, which defines a weak absolute symbol "ext_addr_sym":

```assembly
.weak ext_addr_sym
ext_addr_sym .set 0x12345678
```

Assemble the source file that defines weak symbols, and include the resulting object file in the link. The "ext_addr_sym" in this example is available as a weak absolute symbol in a final link. It is a candidate for removal if the symbol is not referenced elsewhere in the application. See .weak directive.

**Using the Linker Command File:** To define a weak symbol in a linker command file, use the "weak" operator in an assignment expression to designate that the symbol as eligible for removal from the output file's symbol table if it is not referenced. In a linker command file, an assignment expression outside a MEMORY or SECTIONS directive can be used to define a weak linker-defined absolute symbol. For example, you can define "ext_addr_sym" as follows:

```assembly
weak(ext_addr_sym) = 0x12345678;
```

If the linker command file is used to perform the final link, then "ext_addr_sym" is presented to the linker as a weak absolute symbol; it will not be included in the resulting output file if the symbol is not referenced. See Section 8.6.2.
If there are multiple definitions of the same absolute symbol, the linker uses certain rules to determine which definition takes precedence. Some definitions may have weak binding and others may have strong binding. "Strong" in this context means that the symbol has not been given a weak binding by either of the two methods described above. Some definitions may come from an input object file (that is, using assembly directives) and others may come from an assignment statement in a linker command file. The linker uses the following guidelines to determine which definition is used when resolving references to a symbol:

- A strongly bound symbol always takes precedence over a weakly bound symbol.
- If two symbols are both strongly bound or both weakly bound, a symbol defined in a linker command file takes precedence over a symbol defined in an input object file.
- If two symbols are both strongly bound and both are defined in an input object file, the linker provides a symbol redefinition error and halts the link process.

### 2.6.3 The Symbol Table

The assembler generates an entry in the symbol table for each .ref, .def, or .global directive in Section 2.6.1. These are external symbols, which are visible to other object modules.

The assembler also creates special symbols that point to the beginning of each section.

The assembler does not usually create symbol table entries for any symbols other than those described above, because the linker does not use them. For example, labels (Section 4.8.2) are not included in the symbol table unless they are declared with the .global directive. For informational purposes, it is sometimes useful to have entries in the symbol table for each symbol in a program. To accomplish this, invoke the assembler with the --output_all_syms option (see Section 4.3).

### 2.7 Symbolic Relocations

The assembler treats each section as if it began at address 0. Of course, all sections cannot actually begin at address 0 in memory, so the linker must relocate sections. Relocations are symbol-relative rather than section-relative.

The linker can relocate sections by:
- Allocating them into the memory map so that they begin at the appropriate address as defined with the linker’s MEMORY directive
- Adjusting symbol values to correspond to the new section addresses
- Adjusting references to relocated symbols to reflect the adjusted symbol values

The linker uses relocation entries to adjust references to symbol values. The assembler creates a relocation entry each time a relocatable symbol is referenced. The linker then uses these entries to patch the references after the symbols are relocated. Example 2-1 contains a code fragment for a TMS320C6000 device for which the assembler generates relocation entries.

#### Example 2-1. Code That Generates Relocation Entries

```
1 .global X
2 00000000 00000012! Z: B X ; Uses an external relocation
3 00000004 0180082A' MVKL Y,B3 ; Uses an internal relocation
4 00000008 0180006A' MVKH Y,B3 ; Uses an internal relocation
5 0000000C 00004000 NOP 3
6
7 00000010 001E000 Y: IDLE
8 00000014 00000212 B Y
9 00000018 00080000 NOP 5
```
In Example 2-1, both symbols X and Y are relocatable. Y is defined in the .text section of this module; X is defined in another module. When the code is assembled, X has a value of 0 (the assembler assumes all undefined external symbols have values of 0), and Y has a value of 16. The assembler generates two relocation entries: one for X and one for Y. The reference to X is an external reference (indicated by the ! character in the listing). The reference to Y is to an internally defined relocatable symbol (indicated by the ’ character in the listing).

After the code is linked, suppose that X is relocated to address 0x7100. Suppose also that the .text section is relocated to begin at address 0x7200; Y now has a relocated value of 0x7210. The linker uses the two relocation entries to patch the two references in the object code:

```
00000012 B X becomes 0fffe012
0180082A MVKL Y becomes 01B9082A
0180006A MVKH Y becomes 1860006A
```

Relocations are symbol-relative rather than section-relative. This means that the relocation in Example 2-1 generated for ‘Y’ would refer to the symbol ‘Y’ and resolve the value for ‘Y’ in the opcode based on where the definition of ‘Y’ ends up.

### 2.7.1 Dynamic Relocation Entries

Under dynamic linking models, the processing of relocation entries is handled slightly differently. If a relocation refers to a symbol that is imported from another dynamic module, then the static linker generates a dynamic relocation, which must be processed by the dynamic linker at dynamic load time (when the definition of the imported symbol is available). Only dynamic shared objects have dynamic relocations.

See Section 8.12 for information about dynamic linking. For information about creating a dynamic object module, see Chapter 14 of *The C6000 Embedded Application Binary Interface Application Report* (SPRAB89).

### 2.8 Loading a Program

The linker creates an executable object file which can be loaded in several ways, depending on your execution environment. These methods include using Code Composer Studio or the hex conversion utility. For details, see Section 3.1.
Program Loading and Running

Even after a program is written, compiled, and linked into an executable object file, there are still many tasks that need to be performed before the program does its job. The program must be loaded onto the target, memory and registers must be initialized, and the program must be set to running.

Some of these tasks need to be built into the program itself. Bootstrapping is the process of a program performing some of its own initialization. Many of the necessary tasks are handled for you by the compiler and linker, but if you need more control over these tasks, it helps to understand how the pieces are expected to fit together.

This chapter will introduce you to the concepts involved in program loading, initialization, and startup.

This chapter does not cover dynamic loading. See Chapter 14 of The C6000 Embedded Application Binary Interface Application Report (SPRAB89) for information about dynamic loaders.

This chapter currently provides examples for the C6000 device family. Refer to your device documentation for various device-specific aspects of bootstrapping.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>3.1 Loading</td>
<td>33</td>
</tr>
<tr>
<td>3.2 Entry Point</td>
<td>35</td>
</tr>
<tr>
<td>3.3 Run-Time Initialization</td>
<td>35</td>
</tr>
<tr>
<td>3.4 Arguments to main</td>
<td>38</td>
</tr>
<tr>
<td>3.5 Run-Time Relocation</td>
<td>38</td>
</tr>
<tr>
<td>3.6 Additional Information</td>
<td>38</td>
</tr>
</tbody>
</table>
3.1 Loading

A program needs to be placed into the target device's memory before it may be executed. Loading is the process of preparing a program for execution by initializing device memory with the program's code and data. A loader might be another program on the device, an external agent (for example, a debugger), or the device might initialize itself after power-on, which is known as bootstrap loading, or bootloading.

The loader is responsible for constructing the load image in memory before the program starts. The load image is the program's code and data in memory before execution. What exactly constitutes loading depends on the environment, such as whether an operating system is present. This section describes several loading schemes for bare-metal devices. This section is not exhaustive.

A program may be loaded in the following ways:

- **A debugger running on a connected host workstation.** In a typical embedded development setup, the device is subordinate to a host running a debugger such as Code Composer Studio (CCS). The device is connected with a communication channel such as a JTAG interface. CCS reads the program and writes the load image directly to target memory through the communications interface.

- **Another program running on the device.** The running program can create the load image and transfer control to the loaded program. If an operating system is present, it may have the ability to load and run programs.

- **"Burning" the load image onto an EPROM module.** The hex converter (hex6x) can assist with this by converting the executable object file into a format suitable for input to an EPROM programmer. The EPROM is placed onto the device itself and becomes a part of the device's memory. See Chapter 10 for details.

- **Bootstrap loading from a dedicated peripheral, such as an I²C peripheral.** The device may require a small program called a bootloader to perform the loading from the peripheral. The hex converter can assist in creating a bootloader.

3.1.1 Load and Run Addresses

Consider an embedded device for which the program's load image is burned onto EPROM/ROM. Variable data in the program must be writable, and so must be located in writable memory, typically RAM. However, RAM is volatile, meaning it will lose its contents when the power goes out. If this data must have an initial value, that initial value must be stored somewhere else in the load image, or it would be lost when power is cycled. The initial value must be copied from the non-volatile ROM to its run-time location in RAM before it is used. See Section 8.8 for ways this is done.

The **load address** is the location of an object in the load image.

The **run address** is the location of the object as it exists during program execution.

An object is a chunk of memory. It represents a section, segment, function, or data.

*The load and run addresses for an object may be the same.* This is commonly the case for program code and read-only data, such as the .const section. In this case, the program can read the data directly from the load address. Sections that have no initial value, such as the .bss section, do not have load data and are considered to have load and run addresses that are the same. If you specify different load and run addresses for an uninitialized section, the linker provides a warning and ignores the load address.

*The load and run addresses for an object may be different.* This is commonly the case for writable data, such as the .data section. The .data section's starting contents are placed in ROM and copied to RAM. This often occurs during program startup, but depending on the needs of the object, it may be deferred to sometime later in the program as described in Section 3.5.

Symbols in assembly code and object files almost always refer to the run address. When you look at an address in the program, you are almost always looking at the run address. The load address is rarely used for anything but initialization.

The load and run addresses for a section are controlled by the linker command file and are recorded in the object file metadata.
The load address determines where a loader places the raw data for the section. Any references to the section (such as references to labels in it) refer to its run address. The application must copy the section from its load address to its run address before the first reference of the symbol is encountered at run time; this does not happen automatically simply because you specify a separate run address. For examples that specify load and run addresses, see Section 8.5.6.1.

For an example that illustrates how to move a block of code at run time, see Example 8-10. To create a symbol that lets you refer to the load-time address, rather than the run-time address, see the .label directive. To use copy tables to copy objects from load-space to run-space at boot time, see Section 8.8.

ELF format executable object files contain segments. See Section 2.3 for information about sections and segments.

### 3.1.2 Bootstrap Loading

The details of bootstrap loading (bootloading) vary a great deal between devices. Not every device supports every bootloading mode, and using the bootloader is optional. This section discusses various bootloading schemes to help you understand how they work. Refer to your device's data sheet to see which bootloading schemes are available and how to use them.

A typical embedded system uses bootloading to initialize the device. The program code and data may be stored in ROM or FLASH memory. At power-on, an on-chip bootloader (the primary bootloader) built into the device hardware starts automatically.

#### Figure 3-1. Bootloading Sequence (Simplified)

The primary bootloader is typically very small and copies a limited amount of memory from a dedicated location in ROM to a dedicated location in RAM. (Some bootloaders support copying the program from an I/O peripheral.) After the copy is completed, it transfers control to the program.

### 3.1.2.1 Boot, Load, and Run Addresses

The boot address of a bootloaded object is where its raw data exists in ROM before power-on.

The boot, load, and run addresses for an object may all be the same; this is commonly the case for .const data. If they are different, the object's contents must be copied to the correct location before the object may be used.

The boot address may be different than the load address. The bootloader is responsible for copying the raw data to the load address.

The boot address is not controlled by the linker command file or recorded in the object file; it is strictly a convention shared by the bootloader and the program.
3.1.2.2 Primary Bootloader

The detailed operation of the primary bootloader is device-specific. Some devices have complex capabilities such as booting from an I/O peripheral or configuring memory controller parameters.

3.2 Entry Point

The entry point is the address at which the execution of the program begins. This is the address of the startup routine. The startup routine is responsible for initializing and calling the rest of the program. For a C/C++ program, the startup routine is usually named _c_int00 (see Section 3.3.1). After the program is loaded, the value of the entry point is placed in the PC register and the CPU is allowed to run.

The object file has an entry point field. For a C/C++ program, the linker will fill in _c_int00 by default. You can select a custom entry point; see Section 8.4.12. The device itself cannot read the entry point field from the object file, so it has to be encoded in the program somewhere.

- If you are using a bootloader, the boot table includes an entry point field. When it finishes running, the bootloader branches to the entry point.
- If you are using an interrupt vector, the entry point is installed as the RESET interrupt handler. When RESET is applied, the startup routine will be invoked.
- If you are using a hosted debugger, such as CCS, the debugger may explicitly set the program counter (PC) to the value of the entry point.

3.3 Run-Time Initialization

After the load image is in place, the program can run. The subsections that follow describe bootstrap initialization of a C/C++ program. An assembly-only program may not need to perform all of these steps.

3.3.1 _c_int00

The function _c_int00 is the startup routine (also called the boot routine) for C/C++ programs. It performs all the steps necessary for a C/C++ program to initialize itself.

The name _c_int00 means that it is the interrupt handler for interrupt number 0, RESET, and that it sets up the C environment. Its name need not be exactly _c_int00, but the linker sets _c_int00 as the entry point for C programs by default. The compiler's run-time-support library provides a default implementation of _c_int00.

The startup routine is responsible for performing the following actions:
1. Set up the stack by initializing SP
2. Set up the data page pointer DP (for architectures that have one)
3. Set configuration registers
4. Process the .cinit table to autoinitialize global variables (when using the --rom_model option)
5. Process the .pinit table to construct global C++ objects.
6. Call the function main with appropriate arguments
7. Call exit when main returns

3.3.2 RAM Model vs. ROM Model

The .cinit section is loaded into memory along with other initialized sections. The linker defines a "cinit" symbol that points to the beginning of the initialization tables in memory. When the program begins running, the C boot routine copies data from these tables into the .bss section.

3.3.2.1 Autoinitializing Variables at Run Time (--rom_model)

Autoinitializing variables at run time is the default method of autoinitialization. To use this method, invoke the linker with the --rom_model option.
Using this method, the .cinit section is loaded into memory along with all the other initialized sections. The linker defines a special symbol called cinit that points to the beginning of the initialization tables in memory. When the program begins running, the C boot routine copies data from the tables (pointed to by .cinit) into the specified variables in the .bss section. This allows initialization data to be stored in slow non-volatile memory and copied to fast memory each time the program is reset.

Figure 3-2 illustrates autoinitialization at run time. Use this method in any system where your application runs from code burned into slow memory or needs to survive a reset.

3.3.2.2 Initializing Variables at Load Time (--ram_model)

Initialization of variables at load time enhances performance by reducing boot time and by saving the memory used by the initialization tables. To use this method, invoke the linker with the --ram_model option.

When you use the --ram_model linker option, the linker sets the STYP_COPY bit in the .cinit section's header. This tells the loader not to load the .cinit section into memory. (The .cinit section occupies no space in the memory map.) The linker also sets the cinit symbol to -1 (normally, cinit points to the beginning of the initialization tables). This indicates to the boot routine that the initialization tables are not present in memory; accordingly, no run-time initialization is performed at boot time.

A loader must be able to perform the following tasks to use initialization at load time:

- Detect the presence of the .cinit section in the object file.
- Determine that STYP_COPY is set in the .cinit section header, so that it knows not to copy the .cinit section into memory.
- Understand the format of the initialization tables.

Figure 3-3 illustrates the initialization of variables at load time.
3.3.2.3 The --rom_model and --ram_model Linker Options

The following list outlines what happens when you invoke the linker with the --ram_model or --rom_model option.

- The symbol _c_int00 is defined as the program entry point. The _c_int00 symbol is the start of the C boot routine in boot.obj; referencing _c_int00 ensures that boot.obj is automatically linked in from the appropriate run-time-support library.
- The .cinit output section is padded with a termination record to tell the boot routine (autoinitialize at run time) or the loader (initialize at load time) when to stop reading initialization tables.
- When you initialize at load time (--ram_model option):
  - The linker sets cinit to -1. This indicates that the initialization tables are not in memory, so no initialization is performed at run time.
  - The STYP_COPY flag (0010h) is set in the .cinit section header. STYP_COPY is the special attribute that tells the loader to perform initialization directly and not to load the .cinit section into memory. The linker does not allocate space in memory for the .cinit section.
- When you autoinitialize at run time (--rom_model option), the linker defines cinit as the starting address of the .cinit section. The C boot routine uses this symbol as the starting point for autoinitialize.

3.3 Copy Tables

The RTS function copy_in can be used at run-time to move code and data around, usually from its load address to its run address. This function reads size and location information from copy tables. The linker automatically generates several kinds of copy tables. Refer to Section 8.8.

You can create and control code overlays with copy tables. See Section 8.8.4 for details and examples.

Using copy tables is similar to performing run-time relocations as described in Section 3.5, however copy tables require a specific table format.

3.3.3.1 BINIT

The BINIT (boot-time initialization) copy table is special in that the target will automatically perform the copying at auto-initialization time. Refer to Section 8.8.4.2 for more about the BINIT copy table name. The BINIT copy table is copied immediately before .cinit processing.

3.3.3.2 CINIT

EABI .cinit tables are special kinds of copy tables. Refer to Section 3.3.2.1 for more about using the .cinit section with the ROM model and Section 3.3.2.2 for more using it with the RAM model.
3.4 Arguments to main

Some programs expect arguments to main (argc, argv) to be valid. Normally this isn’t possible for an embedded program, but the TI runtime does provide a way to do it. The user must allocate an .args section of an appropriate size using the --args linker option. It is the responsibility of the loader to populate the .args section. It is not specified how the loader determines which arguments to pass to the target. The format of the arguments is the same as an array of pointers to char on the target.

See Section 8.4.4 for information about allocating memory for argument passing.

3.5 Run-Time Relocation

At times you may want to load code into one area of memory and move it to another area before running it. For example, you may have performance-critical code in an external-memory-based system. The code must be loaded into external memory, but it would run faster in internal memory. Because internal memory is limited, you might swap in different speed-critical functions at different times.

The linker provides a way to handle this. Using the SECTIONS directive, you can optionally direct the linker to allocate a section twice: first to set its load address and again to set its run address. Use the load keyword for the load address and the run keyword for the run address. See Section 3.1.1 for more about load and run addresses. If a section is assigned two addresses at link time, all labels defined in the section are relocated to refer to the run-time address so that references to the section (such as branches) are correct when the code runs.

If you provide only one allocation (either load or run) for a section, the section is allocated only once and loads and runs at the same address. If you provide both allocations, the section is actually allocated as if it were two separate sections of the same size.

Uninitialized sections (such as .bss) are not loaded, so the only significant address is the run address. The linker allocates uninitialized sections only once; if you specify both run and load addresses, the linker warns you and ignores the load address.

For a complete description of run-time relocation, see Section 8.5.6.

3.6 Additional Information

See the following sections and documents for additional information:

Section 8.4.4, "Allocate Memory for Use by the Loader to Pass Arguments (--arg_size Option)"
Section 8.4.12, "Define an Entry Point (--entry_point Option)"
Section 8.5.6.1, "Specifying Load and Run Addresses"
Section 8.8, "Linker-Generated Copy Tables"
Section 8.10.1, "Run-Time Initialization"
.label directive
Chapter 10, "Hex Conversion Utility Description"
Creating a Second-Level Bootloader for FLASH Bootloading on TMS320C6000 Platform With Code Composer Studio (SPRA999).
The TMS320C6000 assembler translates assembly language source files into machine language object files. These files are object modules, which are discussed in Chapter 2. Source files can contain the following assembly language elements:

- **Assembler directives** described in Chapter 5
- **Macro directives** described in Chapter 6
- **Assembly language instructions** described in the TMS320C64x/C64x+ DSP CPU and Instruction Set Reference Guide, TMS320C6740 DSP CPU and Instruction Set Reference Guide, and TMS320C66x CPU and Instruction Set Reference Guide.

## Table of Contents

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>4.1 Assembler Overview</td>
<td>40</td>
</tr>
<tr>
<td>4.2 The Assembler's Role in the Software Development Flow</td>
<td>41</td>
</tr>
<tr>
<td>4.3 Invoking the Assembler</td>
<td>42</td>
</tr>
<tr>
<td>4.4 The Application Binary Interface</td>
<td>43</td>
</tr>
<tr>
<td>4.5 Naming Alternate Directories for Assembler Input</td>
<td>43</td>
</tr>
<tr>
<td>4.6 Source Statement Format</td>
<td>46</td>
</tr>
<tr>
<td>4.7 Literal Constants</td>
<td>49</td>
</tr>
<tr>
<td>4.8 Assembler Symbols</td>
<td>51</td>
</tr>
<tr>
<td>4.9 Expressions</td>
<td>61</td>
</tr>
<tr>
<td>4.10 Built-in Functions and Operators</td>
<td>65</td>
</tr>
<tr>
<td>4.11 Source Listings</td>
<td>70</td>
</tr>
<tr>
<td>4.12 Debugging Assembly Source</td>
<td>72</td>
</tr>
<tr>
<td>4.13 Cross-Reference Listings</td>
<td>73</td>
</tr>
</tbody>
</table>
4.1 Assembler Overview

The assembler does the following:

- Processes the source statements in a text file to produce a relocatable object file
- Produces a source listing (if requested) and provides you with control over this listing
- Allows you to divide your code into sections and maintain a section program counter (SPC) for each section of object code
- Defines and references global symbols and appends a cross-reference listing to the source listing (if requested)
- Allows conditional assembly
- Supports macros, allowing you to define macros inline or in a library
4.2 The Assembler's Role in the Software Development Flow

Figure 4-1 illustrates the assembler's role in the software development flow. The shaded portion highlights the most common assembler development path. The assembler accepts assembly language source files as input, both those you create and those created by the TMS320C6000 C/C++ compiler.

Figure 4-1. The Assembler in the TMS320C6000 Software Development Flow
4.3 Invoking the Assembler

To invoke the assembler, enter the following:

```
cl6x input file [options]
```

- **cl6x** is the command that invokes the assembler through the compiler. The compiler considers any file with an .asm extension to be an assembly file and invokes the assembler.
- **input file** names the assembly language source file.
- **options** identify the assembler options that you want to use. Options are case sensitive and can appear anywhere on the command line following the command. Precede each option with one or two hyphens as shown.

The valid assembler options are listed in Table 4-1.

Some runtime model options, such as --big_endian and --silicon version, influence the behavior of the assembler. These options are passed to the compiler, assembler, and linker from the shell utility, which is detailed in the TMS320C6000 Optimizing Compiler User's Guide.

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>-ar=num</td>
<td></td>
<td>Suppresses the assembler remark identified by num. A remark is an informational assembler message that is less severe than a warning. If you do not specify a value for #, all remarks are suppressed.</td>
</tr>
<tr>
<td>--asm_define=name[=def]</td>
<td>ad</td>
<td>Sets the name symbol. This is equivalent to defining name with a .set directive in the case of a numeric value or with an .asg directive otherwise. If value is omitted, the symbol is set to 1. See Section 4.8.5.</td>
</tr>
<tr>
<td>--asm_dependency</td>
<td>apd</td>
<td>Performs preprocessing for assembly files, but instead of writing preprocessed output, writes a list of dependency lines suitable for input to a standard make utility. The list is written to a file with the same name as the source file but with a .ppa extension.</td>
</tr>
<tr>
<td>--asm_includes</td>
<td>api</td>
<td>Performs preprocessing for assembly files, but instead of writing preprocessed output, writes a list of files included with the .include directive. The list is written to a file with the same name as the source file but with a .ppa extension.</td>
</tr>
<tr>
<td>--asm_listing</td>
<td>al</td>
<td>Produces a listing file with the same name as the input file with a .lst extension.</td>
</tr>
<tr>
<td>--asm_undefine=name</td>
<td>au</td>
<td>Undefines the predefined constant name, which overrides any --asm_define options for the specified constant.</td>
</tr>
<tr>
<td>--cmd_file=filename</td>
<td>ahc</td>
<td>Copies the specified file for the assembly module. The file is inserted before source file statements. The copied file appears in the assembly listing files.</td>
</tr>
<tr>
<td>--cross_reference</td>
<td>ax</td>
<td>Produces a cross-reference table and appends it to the end of the listing file. If you do not request a listing file but use the --cross_reference option, the assembler creates a listing file automatically, naming it with the same name as the input file with a .lst extension.</td>
</tr>
<tr>
<td>--include_file=filename</td>
<td>ahi</td>
<td>Includes the specified file for the assembly module. The file is included before source file statements. The included file does not appear in the assembly listing files.</td>
</tr>
<tr>
<td>--include_path=pathname</td>
<td>-I</td>
<td>Specifies a directory where the assembler can find files named by the .copy, .include, or .mlib directives. There is no limit to the number of directories you can specify in this manner; each pathname must be preceded by the --include_path option. See Section 4.5.1.</td>
</tr>
<tr>
<td>--output_all_syms</td>
<td>as</td>
<td>Puts all defined symbols in the object file's symbol table. The assembler usually puts only global symbols into the symbol table. When you use --output_all_syms, symbols defined as labels or as assembly-time constants are also placed in the table.</td>
</tr>
<tr>
<td>--quiet</td>
<td>-q</td>
<td>Suppresses the banner and progress information (assembler runs in quiet mode).</td>
</tr>
</tbody>
</table>
Table 4-1. TMS320C6000 Assembler Options (continued)

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>--symdebug:dwarf or</td>
<td>-g</td>
<td>(DWARF is on by default) Enables assembler source debugging in the C source debugger. Line information is output to the object module for every line of source in the assembly language source file. You cannot use this option on assembly code that contains .line directives. See Section 4.12.</td>
</tr>
<tr>
<td>--symdebug:none</td>
<td></td>
<td></td>
</tr>
<tr>
<td>--syms_ignore_case</td>
<td>-ac</td>
<td>Makes case insignificant in the assembly language files. For example, --syms_ignore_case makes the symbols ABC and abc equivalent. If you do not use this option, case is significant (default). Case significance is enforced primarily with symbol names, not with mnemonics and register names.</td>
</tr>
</tbody>
</table>

4.4  The Application Binary Interface

An Application Binary Interface (ABI) defines the low level interface between object files, and between an executable and its execution environment. The ABI exists to allow ABI-compliant object code to link together, regardless of its source, and allows the resulting executable to run on any system that supports that ABI.

The C6000 compiler supports only the C6000 EABI ABI. For details, see The C6000 Embedded Application Binary Interface Application Report (SPRAB89).

COFF object files are no longer supported in v8.0 and later versions of the TI Code Generation Tools. If you would like to produce COFF output files, please use v7.4 of the Code Generation Tools and refer to SPRU186 for documentation.

Object modules conforming to different ABIs cannot be linked together. The linker detects this situation and generates an error; you will need to recompile C code or reassemble assembly code in order to move from COFF to ELF. Note that converting an assembly file from the COFF API to EABI requires some changes to the assembly code. See Chapter 14 of The C6000 Embedded Application Binary Interface Application Report (SPRAB89) for details.

4.5  Naming Alternate Directories for Assembler Input

The .copy, .include, and .mlib directives tell the assembler to use code from external files. The .copy and .include directives tell the assembler to read source statements from another file, and the .mlib directive names a library that contains macro functions. Chapter 5 contains examples of the .copy, .include, and .mlib directives. The syntax for these directives is:

```
.copy ["filename"]
.include ["filename"]
.mlib ["filename"]
```

The filename names a copy/include file that the assembler reads statements from or a macro library that contains macro definitions. If filename begins with a number the double quotes are required. Quotes are recommended so that there is no issue in dealing with path information that is included in the filename specification or path names that include white space. The filename may be a complete pathname, a partial pathname, or a filename with no path information.

The assembler searches for the file in the following locations in the order given:

1. The directory that contains the current source file. The current source file is the file being assembled when the .copy, .include, or .mlib directive is encountered.
2. Any directories named with the --include_path option
3. Any directories named with the C6X_A_DIR environment variable
4. Any directories named with the C6X_C_DIR environment variable

Because of this search hierarchy, you can augment the assembler's directory search algorithm by using the --include_path option (described in Section 4.5.1) or the C6X_A_DIR environment variable (described in Section 4.5.2). The C6X_C_DIR environment variable is discussed in the TMS320C6000 Optimizing Compiler User's Guide.
4.5.1 Using the --include_path Assembler Option

The --include_path assembler option names an alternate directory that contains copy/include files or macro libraries. The format of the --include_path option is as follows:

```
cl6x --include_path= pathname source filename [other options]
```

There is no limit to the number of --include_path options per invocation; each --include_path option names one pathname. In assembly source, you can use the .copy, .include, or .mlib directive without specifying path information. If the assembler does not find the file in the directory that contains the current source file, it searches the paths designated by the --include_path options.

For example, assume that a file called source.asm is in the current directory; source.asm contains the following directive statement:

```
.copy "copy.asm"
```

Assume the following paths for the copy.asm file:

UNIX: /tools/files/copy.asm
Windows: c:\tools\files\copy.asm

You could set up the search path with the commands shown below:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Enter</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne shell)</td>
<td>cl6x --include_path=/tools/files source.asm</td>
</tr>
<tr>
<td>Windows</td>
<td>cl6x --include_path=c:\tools\files source.asm</td>
</tr>
</tbody>
</table>

The assembler first searches for copy.asm in the current directory because source.asm is in the current directory. Then the assembler searches in the directory named with the --include_path option.

4.5.2 Using the C6X_A_DIR Environment Variable

An environment variable is a system symbol that you define and assign a string to. The assembler uses the C6X_A_DIR environment variable to name alternate directories that contain copy/include files or macro libraries.

The assembler looks for the C6X_A_DIR environment variable and then reads and processes it. If the assembler does not find the C6X_A_DIR variable, it then searches for C6X_C_DIR. The processor-specific variables are useful when you are using Texas Instruments tools for different processors at the same time.

See the TMS320C6000 Optimizing Compiler User's Guide for details on C6X_C_DIR.

The command syntax for assigning the environment variable is as follows:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Enter</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne Shell)</td>
<td>C6X_A_DIR=&quot; pathname, ; pathname2; ...&quot;; export C6X_A_DIR</td>
</tr>
<tr>
<td>Windows</td>
<td>set C6X_A_DIR= pathname, ; pathname2; ...</td>
</tr>
</tbody>
</table>
The *pathnames* are directories that contain copy/include files or macro libraries. The pathnames must follow these constraints:

- Pathnames must be separated with a semicolon.
- Spaces or tabs at the beginning or end of a path are ignored. For example the space before and after the semicolon in the following is ignored:
  
  ```
  set C6X_A_DIR= c:\path\one\to\tools ; c:\path\two\to\tools
  ```

- Spaces and tabs are allowed within paths to accommodate Windows directories that contain spaces. For example, the pathnames in the following are valid:
  
  ```
  set C6X_A_DIR=c:\first path\to\tools;d:\second path\to\tools
  ```

In assembly source, you can use the `.copy`, `.include`, or `.mlib` directive without specifying path information. If the assembler does not find the file in the directory that contains the current source file or in directories named by the `--include_path` option, it searches the paths named by the environment variable.

For example, assume that a file called `source.asm` contains these statements:

```
.copy "copy1.asm"
.copy "copy2.asm"
```

Assume the following paths for the files:

UNIX: `/tools/files/copy1.asm` and `/dsys/copy2.asm`

Windows: `c:\tools\files\copy1.asm` and `c:\dsys\copy2.asm`

You could set up the search path with the commands shown below:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Enter</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne shell)</td>
<td><code>C6X_A_DIR=&quot;/dsys&quot;; export C6X_A_DIR</code>&lt;br&gt;<code>cl6x --include_path=&quot;/tools/files&quot; source.asm</code></td>
</tr>
<tr>
<td>Windows</td>
<td><code>set C6X_A_DIR=c:\dsys</code>&lt;br&gt;<code>cl6x --include_path=c:\tools\files source.asm</code></td>
</tr>
</tbody>
</table>

The assembler first searches for `copy1.asm` and `copy2.asm` in the current directory because `source.asm` is in the current directory. Then the assembler searches in the directory named with the `--include_path` option and finds `copy1.asm`. Finally, the assembler searches the directory named with `C6X_A_DIR` and finds `copy2.asm`.

The environment variable remains set until you reboot the system or reset the variable by entering one of these commands:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Enter</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne shell)</td>
<td><code>unset C6X_A_DIR</code></td>
</tr>
<tr>
<td>Windows</td>
<td><code>set C6X_A_DIR=</code></td>
</tr>
</tbody>
</table>
4.6 Source Statement Format

Each line in a TMS320C6000 assembly input file can be empty, a comment, an assembler directive, a macro invocation, or an assembly instruction.

Assembly language source statements can contain five ordered fields (label, mnemonic, unit specifier, operand list, and comment). The general syntax for source statements is as follows:

```
[label[:]] [[register ]] mnemonic [unit specifier] [operand list][;comment]
```

A label can only be associated with the first instruction in an execute packet (a group of instructions that is to be executed in parallel).

Following are examples of source statements:

two .set 2 ; Symbol Two = 2
Label: MVK two,A2 ; Move 2 into register A2
.word 016h ; Initialize a word with 016h

There is no limit on characters per source statement. Each statement is one logical line of the input file. Use a backslash (\) to indicate continuation of the same instruction/directive across multiple lines.

Follow these guidelines:

- All statements must begin with a label, a blank, an asterisk, or a semicolon.
- Labels are optional for most statements; if used, they must begin in column 1.
- One or more space or tab characters must separate each field.
- Comments are optional. Comments that begin in column 1 can begin with an asterisk or a semicolon (* or ;), but comments that begin in any other column must begin with a semicolon.
- In a conditional instruction, the condition register must be surrounded by square brackets.
- The functional unit specifier is optional. If you do not specify the functional unit, the assembler assigns a legal functional unit based on the mnemonic field and the other instructions in the execute packet.

**NOTE:** A mnemonic cannot begin in column 1 or it will be interpreted as a label. Mnemonic opcodes and assembler directive names without the . prefix are valid label names. Remember to always use whitespace before the mnemonic, or the assembler will think the identifier is a new label definition.

The following sections describe each of the fields.

### 4.6.1 Label Field

A label must be a legal identifier (see Section 4.8.1) placed in column 1. Every instruction may optionally have a label. Many directives allow a label, and some require a label.

A label can be followed by a colon (:). The colon is not treated as part of the label name. If you do not use a label, the first character position must contain a blank, a semicolon, or an asterisk. You cannot use a label on an instruction that is in parallel with a previous instruction.

When you use a label on an assembly instruction or data directive, an assembler symbol (Section 4.8) with the same name is created. Its value is the current value of the section program counter (SPC, see Section 2.4.5). This symbol represents the address of that instruction. In the following example, the .word directive is used to create an array of 3 words. Because a label was used, the assembly symbol Start refers to the first word, and the symbol will have the value 40h.

```
9 * Assume some code was assembled
10 00000040 0000000A Start: .word 0Ah,3,7
   00000044 00000003
   00000048 00000007
```
When a label appears on a line by itself, it points to the instruction on the next line (the SPC is not incremented):

```
1 00000000
2 00000000 00000003 .word 3
```

A label on a line by itself is equivalent to writing:

```
Here: .equ $ ; $ provides the current value of the SPC
```

If you do not use a label, the character in column 1 must be a blank, an asterisk, or a semicolon.

### 4.6.2 Mnemonic Field

The mnemonic field follows the label field. The mnemonic field cannot start in column 1; if it does, it is interpreted as a label. There is one exception: the parallel bars (||) of the mnemonic field can start in column 1. The mnemonic field contains one of the following items:

- Parallel bars (||) indicate instructions that are in parallel with a previous instruction. You can have up to eight instructions that will be executed in parallel. The following example demonstrates six instructions to be executed in parallel:

```
|| Inst1
|| Inst2
|| Inst3
|| Inst4
|| Inst5
|| Inst6
|| Inst7
```

- Square brackets ([ ]) indicate conditional instructions. The machine-instruction mnemonic is executed based on the value of the register within the brackets; valid register names are A0, A1, A2, B0, B1, and B2. These registers are often called predicate registers.

  The instruction is executed if the value of the register is nonzero. If the register name is preceded by an exclamation point (!), then the instruction is executed if the value of the register is 0. For example:

  ```
  [A1] ZERO A2 ; If A1 is not equal to zero, A2 = 0
  ```

  The preceding exclamation point, if specified, is called a "logical NOT operator" or a "unary NOT operator".

  Next, the mnemonic field contains one of the following items:

  - Machine-instruction mnemonic (such as ADDK, MVKH, B)
  - Assembler directive (such as .data, .list, .equ, .macro, .var, .mexit)
   
   The || and "[predicate register]" constructs are not legal in combination with an assembler directive.

   - Macro invocation

### 4.6.3 Unit Specifier Field

The unit specifier field is an optional field that follows the mnemonic field for machine-instruction mnemonics. The unit specifier field begins with a period (.) followed by a functional unit specifier. In general, one instruction can be assigned to each functional unit in a single instruction cycle. There are eight functional units, two of each functional type:

- **.D1 and .D2** Data/addition/subtraction
- **.L1 and .L2** ALU/comparies/long data arithmetic
- **.M1 and .M2** Multiply
- **.S1 and .S2** Shift/ALU/branch/bit field

ALU refers to an arithmetic logic unit.
There are several ways to use the unit specifier field:

- You can specify the particular functional unit (for example, .D1).
- You can specify only the functional type (for example, .M), and the assembler assigns the specific unit (for example, .M2).
- If you do not specify the functional unit, the assembler assigns the functional unit based on the mnemonic field, operand fields, and other instructions in the same execute packet.

For more information on functional units, including which assembly instructions require which functional type, see the TMS320C64x/C64x+ DSP CPU and Instruction Set Reference Guide, or TMS320C66x DSP CPU and Instruction Set Reference Guide, or TMS320C674x CPU and Instruction Set Reference Guide.

4.6.4 Operand Field

The operand field follows the mnemonic field and contains zero or more comma-separated operands. An operand can be one of the following:

- an immediate operand (usually a constant or symbol) (see Section 4.7 and Section 4.8)
- a register operand
- a memory reference operand
- an expression that evaluates to one of the above (see Section 4.9)

An immediate operand is encoded directly in the instruction. The value of an immediate operand must be a constant expression. Most instructions with an immediate operand require an absolute constant expression, such as 1234. Some instructions (such as a call instruction) allow a relocatable constant expression, such as a symbol defined in another file. (See Section 4.9 for details about types of expressions.)

A register operand is a special pre-defined symbol that represents a CPU register.

A memory reference operand uses one of several memory addressing modes to refer to a location in memory. Memory reference operands use a special target-specific syntax defined in the appropriate CPU and Instruction Set Reference Guide.

You must separate operands with commas. Not all operand types are supported for all operands. See the description of the specific instruction in the CPU and Instruction Set Reference Guide for your device family.

4.6.5 Comment Field

A comment can begin in any column and extends to the end of the source line. A comment can contain any ASCII character, including blanks. Comments are printed in the assembly source listing, but they do not affect the assembly.

A source statement that contains only a comment is valid. If it begins in column 1, it can start with a semicolon (:) or an asterisk (*). Comments that begin anywhere else on the line must begin with a semicolon. The asterisk identifies a comment only if it appears in column 1.
4.7 Literal Constants

A literal constant (also known as a literal or in some other documents as an immediate value) is a value that represents itself, such as 12, 3.14, or “hello”.

The assembler supports several types of literals:

- Binary integer literals
- Octal integer literals
- Decimal integer literals
- Hexadecimal integer literals
- Character literals
- Character string literals
- Floating-point literals

Error checking for invalid or incomplete literals is performed.

4.7.1 Integer Literals

The assembler maintains each integer literal internally as a 32-bit signless quantity. Literals are considered unsigned values, and are not sign extended. For example, the literal 00FFh is equal to 00FF (base 16) or 255 (base 10); it does not equal -1, which is 0FFFFFFFh (base 16). Note that if you store 0FFh in a .byte location, the bits will be exactly the same as if you had stored -1. It is up to the reader of that location to interpret the signedness of the bits.

4.7.1.1 Binary Integer Literals

A binary integer literal is a string of up to 32 binary digits (0s and 1s) followed by the suffix B (or b). Binary literals of the form "0[bB][10]+" are also supported. If fewer than 32 digits are specified, the assembler rightjustifies the value and fills the unspecified bits with zeros. These are examples of valid binary literals:

- 00000000B: Literal equal to 0₁₀ or 0₁₆
- 0100000b: Literal equal to 3₂₁₀ or 2₀₁₆
- 01b: Literal equal to 1₁₀ or 1₁₆
- 11111000B: Literal equal to 248₁₀ or 0F8₁₆
- 0b00101010: Literal equal to 42₁₀ or 2A₁₆
- 0B101010: Literal equal to 42₁₀ or 2A₁₆

4.7.1.2 Octal Integer Literals

An octal integer literal is a string of up to 11 octal digits (0 through 7) followed by the suffix Q (or q). Octal literals may also begin with a 0, contain no 8 or 9 digits, and end with no suffix. These are examples of valid octal literals:

- 10Q: Literal equal to 8₁₀ or 8₁₆
- 054321: Literal equal to 22737₁₀ or 58D₁₆
- 100000Q: Literal equal to 32768₁₀ or 8000₁₆
- 226q: Literal equal to 150₁₀ or 96₁₆
4.7.1.3 Decimal Integer Literals

A decimal integer literal is a string of decimal digits ranging from -2147 483 648 to 4 294 967 295. These are examples of valid decimal integer literals:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1000</td>
<td>Literal equal to 1000&lt;sub&gt;10&lt;/sub&gt; or 3E8&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>-32768</td>
<td>Literal equal to -32 768&lt;sub&gt;10&lt;/sub&gt; or -8000&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>25</td>
<td>Literal equal to 25&lt;sub&gt;10&lt;/sub&gt; or 19&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>4815162342</td>
<td>Literal equal to 4815162342&lt;sub&gt;10&lt;/sub&gt; or 11F018BE6&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
</tbody>
</table>

4.7.1.4 Hexadecimal Integer Literals

A hexadecimal integer literal is a string of up to eight hexadecimal digits followed by the suffix H (or h) or preceded by 0x. A hexadecimal literal must begin with a decimal value (0-9) if it is indicated by the H or h suffix.

Hexadecimal digits include the decimal values 0-9 and the letters A-F or a-f. If fewer than eight hexadecimal digits are specified, the assembler right-justifies the bits.

These are examples of valid hexadecimal literals:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>78h</td>
<td>Literal equal to 120&lt;sub&gt;10&lt;/sub&gt; or 0078&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>0x78</td>
<td>Literal equal to 120&lt;sub&gt;10&lt;/sub&gt; or 0078&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>0Fh</td>
<td>Literal equal to 15&lt;sub&gt;10&lt;/sub&gt; or 000F&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>37ACh</td>
<td>Literal equal to 14252&lt;sub&gt;10&lt;/sub&gt; or 37AC&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
</tbody>
</table>

4.7.1.5 Character Literals

A character literal is a single character enclosed in single quotes. The characters are represented internally as 8-bit ASCII characters. Two consecutive single quotes are required to represent each single quote that is part of a character literal. A character literal consisting only of two single quotes is valid and is assigned the value 0. These are examples of valid character literals:

<table>
<thead>
<tr>
<th>Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>'a'</td>
<td>Defines the character literal a and is represented internally as 61&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>'C'</td>
<td>Defines the character literal C and is represented internally as 43&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>&quot;</td>
<td>Defines the character literal &quot; and is represented internally as 27&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
<tr>
<td>''</td>
<td>Defines a null character and is represented internally as 00&lt;sub&gt;16&lt;/sub&gt;</td>
</tr>
</tbody>
</table>

Notice the difference between character literals and character string literals (Section 4.7.2 discusses character strings). A character literal represents a single integer value; a string is a sequence of characters.

4.7.2 Character String Literals

A character string is a sequence of characters enclosed in double quotes. Double quotes that are part of character strings are represented by two consecutive double quotes. The maximum length of a string varies and is defined for each directive that requires a character string. Characters are represented internally as 8-bit ASCII characters.

These are examples of valid character strings:

<table>
<thead>
<tr>
<th>String</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;sample program&quot;</td>
<td>defines the 14-character string sample program.</td>
</tr>
<tr>
<td>&quot;PLAN &quot;&quot;C&quot;&quot;&quot;&quot;</td>
<td>defines the 8-character string PLAN &quot;C&quot;.</td>
</tr>
</tbody>
</table>
Character strings are used for the following:

- Filenames, as in `.copy "filename"`
- Section names, as in `.sect "section name"`
- Data initialization directives, as in `.byte "charstring"`
- Operands of `.string` directives

### 4.7.3 Floating-Point Literals

A floating-point literal is a string of decimal digits followed by a required decimal point, an optional fractional portion, and an optional exponent portion. The syntax for a floating-point number is:

```
[ +|- ] nnn . [ nnn ] [ E|e [ +|- ] nnn ]
```

Replace `nnn` with a string of decimal digits. You can precede `nnn` with a `+` or a `-`. You must specify a decimal point. For example, `3.e5` is valid, but `3e5` is not valid. The exponent indicates a power of 10. These are examples of valid floating-point literals:

- `3.0`
- `3.14`
- `3.`
- `−0.314e13`
- `+314.59e−2`

The assembler syntax does not support all C89-style float literals nor C99-style hexadecimal constants, but the `$strtod` built-in mathematical function supports both. If you want to specify a floating-point literal using one of those formats, use `$strtod`. For example:

```asm
$strtod(".3")
$strtod("0x1.234p−5")
```

You cannot directly use NaN, Inf, or `-Inf` as floating-point literals. Instead, use `$strtod` to express these values. The "NaN" and "Inf" strings are handled case-insensitively. See Section 4.10.1 for built-in functions.

```asm
$strtod("NaN")
$strtod("Inf")
```

### 4.8 Assembler Symbols

An assembler symbol is a named 32-bit signless integer value, usually representing an address or absolute integer. A symbol can represent such things as the starting address of a function, variable, or section. The name of a symbol must be a legal identifier. The identifier becomes a symbolic representation of the symbol's value, and may be used in subsequent instructions to refer to the symbol's location or value.

Some assembler symbols become external symbols, and are placed in the object file's symbol table. A symbol is valid only within the module in which it is defined, unless you use the `.global` directive or the `.def` directive to declare it as an external symbol (see `.global` directive).

See Section 2.6 for more about symbols and the symbol tables in object files.

### 4.8.1 Identifiers

Identifiers are names used as labels, registers, symbols, and substitution symbols. An identifier is a string of alphanumeric characters, the dollar sign, and underscores (`A-Z`, `a-z`, `0-9`, `$`, and `_`). The first character in an identifier cannot be a number, and identifiers cannot contain embedded blanks. The identifiers you define are case sensitive; for example, the assembler recognizes ABC, Abc, and abc as three distinct identifiers. You can override case sensitivity with the `--syms_ignore_case` assembler option (see Section 4.3).
4.8.2 Labels

An identifier used as a label becomes an assembler symbol, which represent an address in the program. Labels within a file must be unique.

NOTE: A mnemonic cannot begin in column 1 or it will be interpreted as a label. Mnemonic opcodes and assembler directive names without the . prefix are valid label names. Remember to always use whitespace before the mnemonic, or the assembler will think the identifier is a new label definition.

Symbols derived from labels can also be used as the operands of .bss, .global, .ref, or .def directives.

.label2: MVKL label2, B3
MVKH label2, B3
B label1
NOP 5

4.8.3 Local Labels

Local labels are special labels whose scope and effect are temporary. A local label can be defined in two ways:

- $n, where n is a decimal digit in the range 0-9. For example, $4 and $1 are valid local labels. See Example 4-1.
- name?, where name is any legal identifier as described above. The assembler replaces the question mark with a period followed by a unique number. When the source code is expanded, you will not see the unique number in the listing file. Your label appears with the question mark as it did in the source definition. See Example 4-2.

You cannot declare these types of labels as global.

Normal labels must be unique (they can be declared only once), and they can be used as constants in the operand field. Local labels, however, can be undefined and defined again. Local labels cannot be defined by directives.

A local label can be undefined or reset in one of these ways:

- By using the .newblock directive
- By changing sections (using a .sect, .text, or .data directive)
- By entering an include file (specified by the .include or .copy directive)
- By leaving an include file (specified by the .include or .copy directive)
Example 4-1. Local Labels of the Form $n

This is an example of code that declares and uses a local label legally:

```
$1:
   SUB  A1,1,A1
   [A1] B  $1
   SUBC A3,A0,A3
   NOP  4
   .newblock ; undefine $1 to use it again
$1  SUB  A2,1,A2
   [A2] B  $1
   MPY  A3,A3,A3
   NOP  4
```

The following code uses a local label illegally:

```
$1:
   SUB  A1,1,A1
   [A1] B  $1
   SUBC A3,A0,A3
   NOP  4
$1  SUB  A2,1,A2 ; WRONG - $1 is multiply defined
   [A2] B  $1
   MPY  A3,A3,A3
   NOP  4
```

The $1 label is not undefined before being reused by the second branch instruction. Therefore, $1 is redefined, which is illegal.

Local labels are especially useful in macros. If a macro contains a normal label and is called more than once, the assembler issues a multiple-definition error. If you use a local label and .newblock within a macro, however, the local label is used and reset each time the macro is expanded.

Up to ten local labels of the $n form can be in effect at one time. Local labels of the form name? are not limited. After you undefine a local label, you can define it and use it again. Local labels do not appear in the object code symbol table.
Example 4-2. Local Labels of the Form name?

```assembly
** First definition of local label mylab **
 nop
 mylab? nop
   B mylab?
   nop 5

** Include file has second definition of mylab **
.copy "a.inc"

** Third definition of mylab, reset upon exit from .include **
 nop
 mylab? nop
   B mylab?
   nop 5

** Fourth definition of mylab in macro, macros use different **
** namespace to avoid conflicts **

mymac .macro
 mylab? nop
   B mylab?
   nop 5
 .endm

** Macro invocation **

mymac

** Reference to third definition of mylab. Definition is not **
** reset by macro invocation. **

 B mylab?
   nop 5

** Changing section, allowing fifth definition of mylab **

.sect "Sect_One"
 nop
 mylab? .word 0
 nop
 nop
 B mylab?
 nop 5

** The .newblock directive allows sixth definition of mylab **

.newblock
 mylab? .word 0
 nop
 nop
 B mylab?
 nop 5
```

For more information about using labels in macros see Section 6.6.
4.8.4 Symbolic Constants

A symbolic constant is a symbol with a value that is an absolute constant expression (see Section 4.9). By using symbolic constants, you can assign meaningful names to constant expressions. The .set and .struct/.tag/.endstruct directives enable you to set symbolic constants (see Define Assembly-Time Constant). Once defined, symbolic constants cannot be redefined.

If you use the .set directive to assign a value to a symbol, the symbol becomes a symbolic constant and may be used where a constant expression is expected. For example:

```assembly
sym .set 3
MVK sym,B1
```

You can also use the .set directive to assign symbolic constants for other symbols, such as register names. In this case, the symbolic constant becomes a synonym for the register:

```assembly
sym .set B1
MVK 10,sym
```

The following example shows how the .set directive can be used with the .struct, .tag, and .endstruct directives. It creates the symbolic constants K, maxbuf, item, value, delta, and i_len.

```assembly
K .set 1024 ; constant definitions
maxbuf .set 2*K
item .struct ; item structure definition
value .int ; value offset = 0
delta .int ; delta offset = 4
i_len .endstruct ; item size = 8
array .tag item
  .bss array, i_len*K ; declare an array of K "items"
  .text
  LDW *[+B14(array.delta + 2*i_len)],A1
  ; access array [2].delta
```

The assembler also has many predefined symbolic constants; these are discussed in Section 4.8.6.
4.8.5 Defining Symbolic Constants (--asm_define Option)

The --asm_define option equates a constant value or a string with a symbol. The symbol can then be used in place of a value in assembly source. The format of the --asm_define option is as follows:

```
cl6x --asm_define= name [= value]
```

The `name` is the name of the symbol you want to define. The `value` is the constant or string value you want to assign to the symbol. If the `value` is omitted, the symbol is set to 1. If you want to define a quoted string and keep the quotation marks, do one of the following:

- For Windows, use `--asm_define= name = "value"`. For example, `--asm_define= car = "sedan"`
- For UNIX, use `--asm_define= name = 'value'`. For example, `--asm_define= car = 'sedan'`
- For Code Composer, enter the definition in a file and include that file with the --cmd_file (or -@) option.

Once you have defined the name with the --asm_define option, the symbol can be used with assembly directives and instructions as if it had been defined with the .set directive. For example, on the command line you enter:

```
cl6x --asm_define=SYM1=1 --asm_define=SYM2=2 --asm_define=SYM3=3 --asm_define=SYM4=4 value.asm
```

Since you have assigned values to SYM1, SYM2, SYM3, and SYM4, you can use them in source code. Example 4-3 shows how the value.asm file uses these symbols without defining them explicitly.

Within assembler source, you can test the symbol defined with the --asm_define option with these directives:

<table>
<thead>
<tr>
<th>Type of Test</th>
<th>Directive Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>Existence</td>
<td>.if $isdefined(&quot; name&quot;)</td>
</tr>
<tr>
<td>Noneexistence</td>
<td>.if $isdefined(&quot; name&quot;) = 0</td>
</tr>
<tr>
<td>Equal to value</td>
<td>.if name = value</td>
</tr>
<tr>
<td>Not equal to value</td>
<td>.if name != value</td>
</tr>
</tbody>
</table>

The argument to the $isdefined built-in function must be enclosed in quotes. The quotes cause the argument to be interpreted literally rather than as a substitution symbol.

**Example 4-3. Using Symbolic Constants Defined on Command Line**

```
IF_4: .if SYM4 = SYM2 * SYM2
      .byte SYM4 ; Equal values
    .else
      .byte SYM2 * SYM2 ; Unequal values
    .endif

IF_5: .if SYM1 <= 10
      .byte 10 ; Less than / equal
    .else
      .byte SYM1 ; Greater than
    .endif

IF_6: .if SYM3 * SYM2 != SYM4 + SYM2
      .byte SYM3 * SYM2 ; Unequal value
    .else
      .byte SYM4 + SYM4 ; Equal values
    .endif

IF_7: .if SYM1 = SYM2
      .byte SYM1
    .elseif SYM2 + SYM3 = 5
      .byte SYM2 + SYM3
    .endif
```
4.8.6 Predefined Symbolic Constants

The assembler has several types of predefined symbols.

$, the dollar-sign character, represents the current value of the section program counter (SPC).

In addition, the following predefined processor symbolic constants are available:

<table>
<thead>
<tr>
<th>Symbol name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>TI_EABI</strong></td>
<td>Set to 1 if EABI is enabled. EABI is now the only supported ABI; see Section 4.4.</td>
</tr>
<tr>
<td>.TMS320C6X</td>
<td>Always set to 1</td>
</tr>
<tr>
<td>.TMS320C6400_PLUS</td>
<td>Set to 1 if target is C6400+, C6740, or C6600; otherwise 0</td>
</tr>
<tr>
<td>.TMS320C6600</td>
<td>Set to 1 if target is C6600, otherwise 0</td>
</tr>
<tr>
<td>.TMS320C6740</td>
<td>Set to 1 if target is C6740 or C6600, otherwise 0</td>
</tr>
<tr>
<td>.LITTLE_ENDIAN</td>
<td>Set to 1 if little-endian mode is selected (the -me assembler option is not used); otherwise 0</td>
</tr>
<tr>
<td>.ASSEMBLER_VERSION</td>
<td>Set to major * 1000000 + minor * 1000 + patch version.</td>
</tr>
<tr>
<td>.BIG_ENDIAN</td>
<td>Set to 1 if big-endian mode is selected (the -me assembler option is used); otherwise 0</td>
</tr>
<tr>
<td>.SMALL_MODEL</td>
<td>Set to 1 if --memory_model:code=near and --memory_model:data=near, otherwise 0</td>
</tr>
<tr>
<td>.LARGE_MODEL</td>
<td>Set to 1 if .SMALL_MODEL is 0, otherwise 0.</td>
</tr>
</tbody>
</table>

4.8.7 Registers

The names of C6000 registers are predefined symbols, including A0-A15 and B0-B15; and A16-31 and B16-31.

In addition, control register names are predefined symbols.

Register symbols and aliases can be entered as all uppercase or all lowercase characters.

Control register symbols can be entered in all upper-case or all lower-case characters. For example, CSR can also be entered as csr.

See the "Register Conventions" section of the TMS320C6000 Optimizing Compiler User's Guide for details about the registers and their uses.

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AMR</td>
<td>Addressing mode register</td>
</tr>
<tr>
<td>CSR</td>
<td>Control status register</td>
</tr>
<tr>
<td>DNUM</td>
<td>DSP core number register</td>
</tr>
<tr>
<td>ECR</td>
<td>Exception clear register</td>
</tr>
<tr>
<td>EFR</td>
<td>Exception flag register</td>
</tr>
<tr>
<td>FADCR</td>
<td>(C6740 and C6600 only) Floating-point adder configuration register</td>
</tr>
<tr>
<td>FAUCR</td>
<td>(C6740 and C6600 only) Floating-point auxiliary configuration register</td>
</tr>
<tr>
<td>FMCR</td>
<td>(C6740 and C6600 only) Floating-point multiplier configuration register</td>
</tr>
<tr>
<td>GFPGFR</td>
<td>Galois field polynomial generator function register</td>
</tr>
<tr>
<td>GPLYA</td>
<td>GMPY A-side polynomial register</td>
</tr>
<tr>
<td>GPLYB</td>
<td>GMPY B-side polynomial register</td>
</tr>
<tr>
<td>ICR</td>
<td>Interrupt clear register</td>
</tr>
<tr>
<td>IER</td>
<td>Interrupt enable register</td>
</tr>
<tr>
<td>IERR</td>
<td>Interrupt exception report register</td>
</tr>
<tr>
<td>IFR</td>
<td>Interrupt flag register (read only)</td>
</tr>
<tr>
<td>Register</td>
<td>Description</td>
</tr>
<tr>
<td>----------</td>
<td>--------------------------------------</td>
</tr>
<tr>
<td>ILC</td>
<td>Inner loop count register</td>
</tr>
<tr>
<td>IRP</td>
<td>Interrupt return pointer</td>
</tr>
<tr>
<td>ISR</td>
<td>Interrupt set register</td>
</tr>
<tr>
<td>ISTP</td>
<td>Interrupt service table pointer</td>
</tr>
<tr>
<td>ITSR</td>
<td>Interrupt task state register</td>
</tr>
<tr>
<td>NRP</td>
<td>Nonmaskable interrupt return pointer</td>
</tr>
<tr>
<td>NTSR</td>
<td>NMI/Exception task state register</td>
</tr>
<tr>
<td>PCE1</td>
<td>Program counter, E1 phase</td>
</tr>
<tr>
<td>REP</td>
<td>Restricted entry point address register</td>
</tr>
<tr>
<td>RILC</td>
<td>Reload inner loop count register</td>
</tr>
<tr>
<td>SSR</td>
<td>Saturation status register</td>
</tr>
<tr>
<td>TSCH</td>
<td>Time-stamp counter (high 32) register</td>
</tr>
<tr>
<td>TSCL</td>
<td>Time-stamp counter (low 32) register</td>
</tr>
<tr>
<td>TSR</td>
<td>Task status register</td>
</tr>
</tbody>
</table>
### 4.8.8 Register Pairs

Many instructions in the C6000 instruction set across the various available target processors support a 64-bit register operand that can be specified as a register pair.

A register pair should be specified on the A side or the B side, depending on which functional unit an instruction is to be executed on, and whether a cross functional unit data path is utilized by the instruction. You cannot mix A-side and B-side registers in the same register pair operand.

The syntax for a register pair is as follows where \( n \% 2 == 0 \):

\[
R_{n+1} : R_n
\]

The legal register pairs are:

<table>
<thead>
<tr>
<th>A1:A0</th>
<th>B1:B0</th>
</tr>
</thead>
<tbody>
<tr>
<td>A3:A2</td>
<td>B3:B2</td>
</tr>
<tr>
<td>A5:A4</td>
<td>B5:B4</td>
</tr>
<tr>
<td>A7:A6</td>
<td>B7:B6</td>
</tr>
<tr>
<td>A9:A8</td>
<td>B9:B8</td>
</tr>
<tr>
<td>A11:A10</td>
<td>B11:B10</td>
</tr>
<tr>
<td>A13:A12</td>
<td>B13:B12</td>
</tr>
<tr>
<td>A15:A14</td>
<td>B15:B14</td>
</tr>
<tr>
<td>A17:A16</td>
<td>B17:B16</td>
</tr>
<tr>
<td>A19:A18</td>
<td>B19:B18</td>
</tr>
<tr>
<td>A21:A20</td>
<td>B21:B20</td>
</tr>
<tr>
<td>A23:A22</td>
<td>B23:B22</td>
</tr>
<tr>
<td>A27:A26</td>
<td>B27:B26</td>
</tr>
<tr>
<td>A29:A30</td>
<td>B29:B30</td>
</tr>
<tr>
<td>A31:A32</td>
<td>B31:B32</td>
</tr>
</tbody>
</table>

Here is an example of an ADD instruction that uses a register pair operand:

```
ADD.L1 A5:A4, A1, A3:A2
```

For details on using register pairs in linear assembly, see the *TMS320C6000 Optimizing Compiler User's Guide*.

For more information on functional units, including which assembly instructions require which functional type, see the *TMS320C64x/C64x+ DSP CPU and Instruction Set Reference Guide, TMS320C66x CPU and Instruction Set Reference Guide*, or *TMS320C6740 DSP CPU and Instruction Set Reference Guide*. 
4.8.9 Register Quads (C6600 Only)

Several instructions in the C6600 instruction set support a 128-bit register operand which can be specified as a register quad.

A register quad should be specified on the A side or the B side, depending on which functional unit an instruction is to be executed on, and whether a cross functional unit data path is utilized by the instruction. You cannot mix A-side and B-side registers in the same register quad operand.

The general syntax for a register quad is as follows, where \((n\%4 == 0)\):

\[ R_{n+3}; R_{n+2}; R_{n+1}; R_n \] or \[ R_{n+3}::R_n \]

The legal register quads are:

<table>
<thead>
<tr>
<th>A Register Quads</th>
<th>Short Form</th>
<th>B Register Quads</th>
<th>Short Form</th>
</tr>
</thead>
<tbody>
<tr>
<td>A3:A2:A1:A0</td>
<td>A3::A0</td>
<td>B3:B2:B1:B0</td>
<td>B3::B0</td>
</tr>
<tr>
<td>A7:A6:A5:A4</td>
<td>A7::A4</td>
<td>B7:B6:B5:B4</td>
<td>B7::B4</td>
</tr>
</tbody>
</table>

Here is an example of an ADD instruction that uses register quad operands:


For details on using register quads in C6600 linear assembly, see the TMS320C6000 Optimizing Compiler User's Guide.

For more information on functional units, including which assembly instructions require which functional type, see the TMS320C66x CPU and Instruction Set Reference Guide.

4.8.10 Substitution Symbols

Symbols can be assigned a string value. This enables you to create aliases for character strings by equating them to symbolic names. Symbols that represent character strings are called substitution symbols. When the assembler encounters a substitution symbol, its string value is substituted for the symbol name. Unlike symbolic constants, substitution symbols can be redefined.

A string can be assigned to a substitution symbol anywhere within a program; for example:

```
.global _table
.asg "B14", PAGEPTR
.asg "**B15(4)", LOCAL1
.asg "**B15(8)", LOCAL2
LDW "PAGEPTR(_table),A0
NOP 4
STW A0,LOCAL1
```

When you are using macros, substitution symbols are important because macro parameters are actually substitution symbols that are assigned a macro argument. The following code shows how substitution symbols are used in macros:

```
MAC .macro src1, src2, dst ; Multiply/Accumulate macro
  MPY src1, src2, src2
  NOP
  ADD src2, dst, dst
.endm
* MAC macro invocation
MAC A0,A1,A2
```

See Chapter 6 for more information about macros.
Expressions

Nearly all values and operands in assembly language are *expressions*, which may be any of the following:

- a literal constant
- a register
- a register pair
- a memory reference
- a symbol
- a built-in function invocation
- a mathematical or logical operation on one or more expressions

This section defines several types of expressions that are referred to throughout this document. Some instruction operands accept limited types of expressions. For example, the `.if` directive requires its operand be an absolute constant expression with an integer value. Absolute in the context of assembly code means that the value of the expression must be known at assembly time.

A **constant expression** is any expression that does not in any way refer to a register or memory reference. An **immediate operand** will usually not accept a register or memory reference. It must be given a constant expression. Constant expressions may be any of the following:

- a literal constant
- an address constant expression
- a symbol whose value is a constant expression
- a built-in function invocation on a constant expression
- a mathematical or logical operation on one or more constant expressions

An **address constant expression** is a special case of a constant expression. Some immediate operands that require an address value can accept a symbol plus an addend; for example, some branch instructions. The symbol must have a value that is an address, and it may be an external symbol. The addend must be an absolute constant expression with an integer value. For example, a valid address constant expression is "array+4".

A constant expression may be absolute or relocatable. **Absolute** means known at assembly time. **Relocatable** means constant, but not known until link time. External symbols are relocatable, even if they refer to a symbol defined in the same module.

An **absolute constant expression** may not refer to any external symbols anywhere in the expression. In other words, an absolute constant expression may be any of the following:

- a literal constant
- an absolute address constant expression
- a symbol whose value is an absolute constant expression
- a built-in function invocation whose arguments are all absolute constant expressions
- a mathematical or logical operation on one or more absolute constant expressions

A **relocatable constant expression** refers to at least one external symbol. Such expressions may contain at most one external symbol. A relocatable constant expression may be any of the following:

- an external symbol
- a relocatable address constant expression
- a symbol whose value is a relocatable constant expression
- a built-in function invocation with any arguments that are relocatable constant expressions
- a mathematical or logical operation on one or more expressions, at least one of which is a relocatable constant expression

In some cases, the value of a relocatable address expression may be known at assembly time. For example, a relative displacement branch may branch to a label defined in the same section.
4.9.1 **Mathematical and Logical Operators**

The operands of a mathematical or logical operator must be well-defined expressions. That is, you must use the correct number of operands and the operation must make sense. For example, you cannot take the XOR of a floating-point value. In addition, well-defined expressions contain only symbols or assembly-time constants that have been defined before they occur in the directive’s expression.

Three main factors influence the order of expression evaluation:

- **Parentheses**: Expressions enclosed in parentheses are always evaluated first. For example, 8 / (4 / 2) = 4, but 8 / 4 / 2 = 1. You cannot substitute braces ( {} ) or brackets ([ ] ) for parentheses.

- **Precedence groups**: Operators, listed in Table 4-4, are divided into nine precedence groups. When parentheses do not determine the order of expression evaluation, the highest precedence operation is evaluated first. For example, 8 + 4 / 2 = 10 (4 / 2 is evaluated first).

- **Left-to-right evaluation**: When parentheses and precedence groups do not determine the order of expression evaluation, the expressions are evaluated from left to right, except for Group 1, which is evaluated from right to left. For example, 8 / 4*2 = 4, but 8 / (4*2) = 1.

Table 4-4 lists the operators that can be used in expressions, according to precedence group.

<table>
<thead>
<tr>
<th>Group</th>
<th>Operator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>+</td>
<td>Unary plus</td>
</tr>
<tr>
<td></td>
<td>-</td>
<td>Unary minus</td>
</tr>
<tr>
<td></td>
<td>~</td>
<td>1s complement</td>
</tr>
<tr>
<td></td>
<td>!</td>
<td>Logical NOT</td>
</tr>
<tr>
<td>2</td>
<td>*</td>
<td>Multiplication</td>
</tr>
<tr>
<td></td>
<td>/</td>
<td>Division</td>
</tr>
<tr>
<td></td>
<td>%</td>
<td>Modulo</td>
</tr>
<tr>
<td>3</td>
<td>+</td>
<td>Addition</td>
</tr>
<tr>
<td></td>
<td>-</td>
<td>Subtraction</td>
</tr>
<tr>
<td>4</td>
<td>&lt;&lt;</td>
<td>Shift left</td>
</tr>
<tr>
<td></td>
<td>&gt;&gt;</td>
<td>Shift right</td>
</tr>
<tr>
<td>5</td>
<td>&lt;</td>
<td>Less than</td>
</tr>
<tr>
<td></td>
<td>&lt;=</td>
<td>Less than or equal to</td>
</tr>
<tr>
<td></td>
<td>&gt;</td>
<td>Greater than</td>
</tr>
<tr>
<td></td>
<td>=&gt;</td>
<td>Greater than or equal to</td>
</tr>
<tr>
<td>6</td>
<td>==</td>
<td>Equal to</td>
</tr>
<tr>
<td></td>
<td>!=</td>
<td>Not equal to</td>
</tr>
<tr>
<td>7</td>
<td>&amp;</td>
<td>Bitwise AND</td>
</tr>
<tr>
<td>8</td>
<td>^^</td>
<td>Bitwise exclusive OR (XOR)</td>
</tr>
<tr>
<td>9</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(1) Group 1 operators are evaluated right to left. All other operators are evaluated left to right.

(2) Unary + and - have higher precedence than the binary forms.

The assembler checks for overflow and underflow conditions when arithmetic operations are performed during assembly. It issues a warning (the "value truncated" message) whenever an overflow or underflow occurs. The assembler does not check for overflow or underflow in multiplication.
Expressions

4.9.2 Relational Operators and Conditional Expressions

The assembler supports relational operators that can be used in any expression; they are especially useful for conditional assembly. Relational operators include the following:

- `=` Equal to
- `!=` Not equal to
- `<` Less than
- `<=` Less than or equal to
- `>` Greater than
- `>=` Greater than or equal to

Conditional expressions evaluate to 1 if true and 0 if false and can be used only on operands of equivalent types; for example, absolute value compared to absolute value, but not absolute value compared to relocatable value.

4.9.3 Well-Defined Expressions

Some assembler directives, such as .if, require well-defined absolute constant expressions as operands. Well-defined expressions contain only symbols or assembly-time constants that have been defined before they occur in the directive’s expression. In addition, they must use the correct number of operands and the operation must make sense. The evaluation of a well-defined expression must be unambiguous.

This is an example of a well-defined expression:

```
1000h+X
```

where X was previously defined as an absolute symbol.

4.9.4 Legal Expressions

With the exception of the following expression contexts, there is no restriction on combinations of operations, constants, internally defined symbols, and externally defined symbols.

- When using the register relative addressing mode, the expression in brackets or parenthesis must be a well-defined expression, as described in Section 4.9.3. For example:
  ```
  *+A4[15]
  ```
- Expressions used to describe the offset in register relative addressing mode for the registers B14 and B15, or expressions used as the operand to the branch instruction, are subject to the same limitations. For these two cases, all legal expressions can be reduced to one of two forms:
  ```
  *+XA4[7]
  ```
  or
  ```
  relocatable symbol ± absolute symbol
  ```
  ```
  B (extern_1-10)
  ```
  ```
  or
  ```
  a well-defined expression
  ```
  ```
  *+B14/B15[14]
  ```
4.9.5 Expression Examples

Following are examples of expressions that use relocatable and absolute symbols. These examples use four symbols that are defined in the same section:

```
.globl extern_1 ; Defined in an external module
intern_1: .word '"D'  ; Relocatable, defined in
       ; current module
intern_2  ; Relocatable, defined in
       ; current module
intern_3  ; Relocatable, defined in
       ; current module
```

- **Example 1**
  The internal values must be formed by absolute constant expressions. The following examples are illegal because variables are used where constants are required.

  ```
  .word extern_1 * intern_2 - 13 ; Illegal
  MVKL (intern_1 - extern_1),A1 ; Illegal
  ```

- **Example 2**
  The first statement in the following example is valid; the statements that follow it are illegal

  ```
  B (extern_1 - 10)              ; Legal
  B (10-extern_1)                ; Can't negate reloc. symbol
  LDW *+B14 {-(intern_1)}, A1    ; Can't negate reloc. symbol
  LDW *+B14 (extern_1/10), A1    ; / not an additive operator
  B (intern_1 + extern_1)        ; Multiple relocatables
  ```

- **Example 3**
  The first statement below is legal; although intern_1 and intern_2 are relocatable, their difference is absolute because they are in the same section. Subtracting one relocatable symbol from another reduces the expression to relocatable symbol + absolute value. The second statement is illegal because the sum of two relocatable symbols is not an absolute value.

  ```
  B (intern_1 - intern_2 + extern_3) ; Legal
  B (intern_1 + intern_2 + extern_3) ; Illegal
  ```

- **Example 4**
  A relocatable symbol's placement in the expression is important to expression evaluation. Although the statement below is similar to the first statement in the previous example, it is illegal because of left-to-right operator precedence; the assembler attempts to add intern_1 to extern_3.

  ```
  B (intern_1 + extern_3 - intern_2) ; Illegal
  ```
4.10 Built-in Functions and Operators

The assembler supports built-in mathematical functions and built-in addressing operators. The built-in substitution symbol functions are discussed in Section 6.3.2.

4.10.1 Built-In Math and Trigonometric Functions

The assembler supports built-in functions for conversions and various math computations. Table 4-5 describes the built-in functions. The expr must be an absolute constant expression.

Table 4-5. Built-In Mathematical Functions

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$acos(expr)</td>
<td>Returns the arccosine of expr as a floating-point value</td>
</tr>
<tr>
<td>$asin(expr)</td>
<td>Returns the arcsine of expr as a floating-point value</td>
</tr>
<tr>
<td>$atan(expr)</td>
<td>Returns the arctangent of expr as a floating-point value</td>
</tr>
<tr>
<td>$atan2(expr, y)</td>
<td>Returns the arctangent of expr as a floating-point value in range [-π, π]</td>
</tr>
<tr>
<td>$ceil(expr)</td>
<td>Returns the smallest integer not less than expr</td>
</tr>
<tr>
<td>$cos(expr)</td>
<td>Returns the cosine of expr as a floating-point value</td>
</tr>
<tr>
<td>$cosh(expr)</td>
<td>Returns the hyperbolic cosine of expr as a floating-point value</td>
</tr>
<tr>
<td>$cvf(expr)</td>
<td>Converts expr to a floating-point value</td>
</tr>
<tr>
<td>$cvi(expr)</td>
<td>Converts expr to integer value</td>
</tr>
<tr>
<td>$exp(expr)</td>
<td>Returns the exponential function $e^{expr}$</td>
</tr>
<tr>
<td>$fabs(expr)</td>
<td>Returns the absolute value of expr as a floating-point value</td>
</tr>
<tr>
<td>$floor(expr)</td>
<td>Returns the largest integer not greater than expr</td>
</tr>
<tr>
<td>$fmod(expr, y)</td>
<td>Returns the remainder of expr1 ÷ expr2</td>
</tr>
<tr>
<td>$int(expr)</td>
<td>Returns 1 if expr has an integer value; else returns 0. Returns an integer.</td>
</tr>
<tr>
<td>$idexp(expr, expr2)</td>
<td>Multiplies expr by an integer power of 2. That is, $expr1 \times 2^{expr2}$</td>
</tr>
<tr>
<td>$log(expr)</td>
<td>Returns the natural logarithm of expr, where expr&gt;0</td>
</tr>
<tr>
<td>$log10(expr)</td>
<td>Returns the base 10 logarithm of expr, where expr&gt;0</td>
</tr>
<tr>
<td>$max(expr1, expr2)</td>
<td>Returns the maximum of two values</td>
</tr>
<tr>
<td>$min(expr1, expr2)</td>
<td>Returns the minimum of two values</td>
</tr>
<tr>
<td>$pow(expr1, expr2)</td>
<td>Returns expr1 raised to the power of expr2</td>
</tr>
<tr>
<td>$round(expr)</td>
<td>Returns expr rounded to the nearest integer</td>
</tr>
<tr>
<td>$sgn(expr)</td>
<td>Returns the sign of expr</td>
</tr>
<tr>
<td>$sin(expr)</td>
<td>Returns the sine of expr</td>
</tr>
<tr>
<td>$sinh(expr)</td>
<td>Returns the hyperbolic sine of expr as a floating-point value</td>
</tr>
<tr>
<td>$sqrt(expr)</td>
<td>Returns the square root of expr, expr&gt;0, as a floating-point value</td>
</tr>
<tr>
<td>$strtod(str)</td>
<td>Converts a character string to a double precision floating-point value. The string contains a properly-formatted C99-style floating-point literal.</td>
</tr>
<tr>
<td>$tan(expr)</td>
<td>Returns the tangent of expr as a floating-point value</td>
</tr>
<tr>
<td>$tanh(expr)</td>
<td>Returns the hyperbolic tangent of expr as a floating-point value</td>
</tr>
<tr>
<td>$trunc(expr)</td>
<td>Returns expr rounded toward 0</td>
</tr>
</tbody>
</table>
4.10.2 Built-In ELF Relocation Generating Operators

The assembler supports several C6000-specific ELF relocation generating built-in operators. The operators are used in compiler-generated code to support symbolic addressing of objects.

The operators are used to support various forms of DP-relative and PC-relative addressing instruction sequences. For more detailed information about DP-relative and PC-relative addressing instruction sequences, please see The C6000 Embedded Application Binary Interface Application Report (SPRAB89).

4.10.2.1 $DPR_BYTE(sym) / $DPR_HWORD(sym) / $DPR_WORD(sym)

The $DPR_BYTE(sym), $DPR_HWORD(sym), or $DPR_WORD(sym) operator can be applied in the source operand of a MVKL or MVKH instruction to load the DP-relative offset of a symbol's address into a register. These operators are used by the compiler when accessing data objects that are not within the signed 15-bit offset range that is needed for using the DP-relative addressing mode.

EABI requires that all sections that are accessed via DP-relative addressing be grouped together. The linker then uses the address of the first section in that group as the "static base" whose value is attached to the symbol __c6xabi_DSBT_BASE. DP-relative addressing then implicitly incorporates the value of __c6xabi_DSBT_BASE into the resolution of the referenced symbol. In the examples that follow, "static_base" in the comments indicates the location of this static base. See Chapter 4 of the The C6000 Embedded Application Binary Interface Application Report (SPRAB89) for more details about data allocation and addressing.

For example, suppose the compiler needs to access a 32-bit aligned data object called 'xyz' that is defined in the .far section. The compiler must assume that the .far section is too far away from the base of the .bss section (whose address the runtime library's boot routine has loaded into the DP register), so using DP-relative addressing mode to access 'xyz' directly is not possible. Instead, the compiler will use a MVKL/MVKH/LDW sequence of instructions:

```
MVKL $DPR_WORD(xyz),A0 ; load (xyz - static_base)/4 into A0
MVKH $DPR_WORD(xyz),A0
LDW *+DP[A0],A1 ; load *xyz into A1
```

This sequence of instructions is also referred to as far DP-relative addressing. The LDW instruction uses a scaled version of DP-relative indexed addressing. Similar to the $DPR_WORD(sym) operator, the $DPR_BYTE(sym) operator is provided to facilitate far DP-relative addressing of 8-bit data objects:

```
MVKL $DPR_BYTE(xyz),A0 ; load (xyz - static_base) into A0
MVKH $DPR_BYTE(xyz),A0
LDH *+DP[A0],A1 ; load *xyz into A1
```

The $DPR_HWORD(sym) operator is provided to facilitate far DP-relative addressing of 16-bit data objects:

```
MVKL $DPR_HWORD(xyz),A0 ; load (xyz - static_base)/2 into A0
MVKH $DPR_HWORD(xyz),A0
LDH *+DP[A0],A1 ; load *xyz into A1
```

If the data being accessed is within range of the anticipated value of the DP (assuming the static base is loaded into the DP before the MVK instructions are used), then a more efficient way to access 'xyz' directly is possible. Instead, the compiler will use a MVK/MVKH/LDW sequence of instructions:

```
MVKL $DPR_BYTE(_char_X),A4 ; load (_char_X - static_base) into A4
ADD DP,A4,A4 ; compute address of _char_X
```

Similarly, the compiler can compute the address of a 16-bit data object that is defined in the .bss section:

```
MVK $DPR_HWORD(_short_X),A4 ; load (_short_X - static_base)/2 into A4
ADD DP,A4,A4 ; compute address of _short_X
```

It can also compute a 32-bit data object that is defined in the .bss section:

```
MVK $DPR_WORD(_int_X),A4 ; load (_int_X - static_base)/4 into A4
ADD DP,A4,A4 ; compute address of _int_X
```
4.10.2.2 $GOT(sym) / $DPR_GOT(sym)

The $GOT(sym) operator can be applied in the source operand of an LDW instruction. The $DPR_GOT(sym) operator can be applied in the source operand of a MVKL or MVKH instruction. These operators are used in the context of compiler-generated code under a dynamic linking ABI (either the Bare-Metal or Linux Dynamic Linking Model). See Chapter 14 of *The C6000 Embedded Application Binary Interface Application Report* (SPRAB89) for more details on the dynamic linking models supported in the C6000 Code Generation Tools (CGT).

Symbols that are preemptable or are imported by a dynamic module will be accessed via the Global Offset Table (GOT). A GOT entry for a symbol will contain the address of the symbol as it is determined at dynamic load time. To facilitate this resolution, the static linker will emit a dynamic relocation entry that is to be processed by the dynamic linker/loader. For more information on the GOT, see *The C6000 Embedded Application Binary Interface Application Report* (SPRAB89).

If the GOT entry for a symbol, xyz, is accessible using DP-relative addressing mode, then the compiler will generate a sequence to load the symbol that uses the $GOT(sym) operator as the offset part of the DP-relative addressing mode operand:

```assembly
LDW *+DP[$GOT(xyz)],A0 ; load address of xyz into A0 via access to GOT entry
LDW *A0,A1 ; load xyz into A2
```

The actual semantics of the $GOT(sym) operator is to return the DP-relative offset of the GOT entry for the referenced symbol (xyz above).

While $DPR_GOT(sym) is semantically similar to the $GOT(sym) operator, it is used when the GOT is not accessible using DP-relative addressing mode (offset is not within signed 15-bit range of the static base address that is loaded into the data pointer register (DP)). The DP-relative offset to the GOT entry is then loaded into an index register using a MVKL/MVKH instruction sequence, and the GOT entry is then accessed via DP-relative indexed addressing to load the address of the referenced symbol:

```assembly
MVKL $DPR_GOT(xyz),A0 ; load DP-relative offset of GOT entry for xyz into A0
MVKH $DPR_GOT(xyz),A0 ; got entry for xyz into A0
LDW *+DP[A0],A1 ; get address of xyz via GOT entry
LDW *A1,A2 ; load xyz into A2
```

4.10.2.3 $PCR_OFFSET(x,y)

The $PCR_OFFSET(x,y) operator can be applied in the source operand of a MVKL, MVKH, or ADDK instruction to compute a PC-relative offset to be loaded into (in the case of MVKL/MVKH) or added to (in the case of ADDK) a register.

This operator is used in the context of compiler-generated code under the Linux ABI (using --linux compiler option). It helps the compiler to generate position-independent code by accessing a symbol that is defined in the same RO segment using PC-relative addressing.

For example, if there is to be a call to a function defined in the same file, but you would like to avoid generating a dynamic relocation that accesses the symbol that represents the destination of the call, then you can use the $PCR_OFFSET operator as follows:

```assembly
dest:
<code>
...

make_pcr_call:
MVC PCE1, B0 ; set up PC reference point in B0
MVKL $PCR_OFFSET(dest, make_pcr_call), B1 ; compute dest - make_pcr_call
MVKH $PCR_OFFSET(dest, make_pcr_call), B1 ; and load it into B1
ADD B0,B1,B0 ; compute dest address into B0 register
B B0 ; call dest indirectly through B0
...
```

The above code sequence is position independent. No matter what address 'dest' is placed at load time, the call to 'dest' will still work since it is independent of the actual address of 'dest'. However, the call does have to maintain its position relative to the definition of 'dest'.
Also in the above sequence, the compiler creates a coupling between the MVC instruction and the 'make_pcr_call' label. The 'make_pcr_call' label must be associated with the address of the MVC instruction so that when the $PCR_OFFSET(dest, make_pcr_call) operator is applied, the 'make_pcr_call' symbol becomes a representative for the PC reference point. This means that the result of 'dest - make_pcr_call' becomes the PC-relative offset which when added to the PC reference point in B0 gives the address of 'dest'.

The relocation that is generated for the $PCR_OFFSET() operator is handled during the static link step in which a dynamic module is built. This static relocation can then be discarded and no dynamic relocation will be needed to resolve the call to 'dest' in the above example.

4.10.2.4 $LABEL_DIFF(x,y) Operator

The $LABEL_DIFF(x,y) operator can be applied to an argument for a 32-bit data-defining directive (like .word, for example). The operator simply computes the difference between two labels that are defined in the same section. This operator is sometimes used by the compiler under the Linux ABI (--linux compiler option) when generating position independent code for a switch statement.

For example, in Example 4-4 a switch table is generated which contains the PC-relative offsets of the switch case labels:

Example 4-4. Generating a Switch Table With Offset Switch Case Labels

```asm
.asg A15, FP  
.asg B14, DP  
.asg B15, SP

.sect ".text"  
.clink  
.global myfunc

;***************************************************************************
;* FUNCTION NAME: myfunc *  
;***************************************************************************  
myfunc:  
;** --------------------------------------------------------------------------*
.B .S1 $C$L10
|| SUB .L2X A4,10,B5  
|| STW .D2T2 B3,*+SP--(16)
|| CMPGTU .L2 B5,7,B0  
|| STW .D2T1 A4,**+SP(12)
|| MV .S2X A4,B4
 [ B0] BNOP .S1 $C$L9,3
 ; BRANCH OCCURS {$C$L10} ; |6|
 ;** ---------------------------------------------------------------*
$C$L1:  
;** <case 0 code>  
...  
$C$L2:  
;** <case 1 code>  
...  
$C$L3:  
;** <case 2 code>  
...  
$C$L4:  
;** <case 3 code>  
...  
$C$L5:  
;** <case 4 code>  
...  
```

Example 4-4 mixes data into the code section. Compression is disabled for the code section that contains the $LABEL_DIFF() operator, since the label difference must resolve to a constant value during assembly.
4.11 Source Listings

A source listing shows source statements and the object code they produce. To obtain a listing file, invoke the assembler with the --asm_listing option (see Section 4.3).

Two banner lines, a blank line, and a title line are at the top of each source listing page. Any title supplied by the .title directive is printed on the title line. A page number is printed to the right of the title. If you do not use the .title directive, the name of the source file is printed. The assembler inserts a blank line below the title line.

Each line in the source file produces at least one line in the listing file. This line shows a source statement number, an SPC value, the object code assembled, and the source statement. Figure 4-2 shows these in an actual listing file.

**Field 1: Source Statement Number**

- **Line number**
  The source statement number is a decimal number. The assembler numbers source lines as it encounters them in the source file; some statements increment the line counter but are not listed. (For example, .title statements and statements following a .nolist are not listed.) The difference between two consecutive source line numbers indicates the number of intervening statements in the source file that are not listed.

- **Include file letter**
  A letter preceding the line number indicates the line is assembled from the include file designated by the letter.

- **Nesting level number**
  A number preceding the line number indicates the nesting level of macro expansions or loop blocks.

**Field 2: Section Program Counter**

This field contains the SPC value, which is hexadecimal. All sections (.text, .data, .bss, and named sections) maintain separate SPCs. Some directives do not affect the SPC and leave this field blank.

**Field 3: Object Code**

This field contains the hexadecimal representation of the object code. All machine instructions and directives use this field to list object code. This field also indicates the relocation type associated with an operand for this line of source code. If more than one operand is relocatable, this column indicates the relocation type for the first operand. The characters that can appear in this column and their associated relocation types are listed below:

- `!` undefined external reference
- `'` .text relocatable
- `+` .sect relocatable
- `"` .data relocatable
- `-` .bss, .usect relocatable
- `%` relocation expression

**Field 4: Source Statement Field**

This field contains the characters of the source statement as they were scanned by the assembler. The assembler accepts a maximum line length of 200 characters. Spacing in this field is determined by the spacing in the source statement.

Figure 4-2 shows an assembler listing with each of the four fields identified.
Figure 4-2. Example Assembler Listing

<table>
<thead>
<tr>
<th>Include file letter</th>
<th>Nesting level number</th>
<th>Line number</th>
<th>Field 1</th>
<th>Field 2</th>
<th>Field 3</th>
<th>Field 4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>4</td>
<td>00000000</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>5</td>
<td>00000004</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>6</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>7</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>8</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>9</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>10</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>11</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>12</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>13</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>14</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>15</td>
<td>00000000</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>16</td>
<td>00000000</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>17</td>
<td>00000000</td>
<td>0200006C-</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>18</td>
<td>00000004</td>
<td>0000016E-</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>19</td>
<td>00000008</td>
<td>00006000</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>20</td>
<td>0000000c</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>21</td>
<td>0000000c</td>
<td>02009881</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>22</td>
<td>00000010</td>
<td>00101882</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>23</td>
<td>00000014</td>
<td>00101F82</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0000018</td>
<td>02009078</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>000001c</td>
<td>02120CA0</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0000020</td>
<td>02009076</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

```
***************
** Global variables
***************
.bss   var1, 4
.bss   var2, 4

***************
** Include multiply macro
***************
.copy   mpy32.inc
.macro  A,B

<table>
<thead>
<tr>
<th>Field 1</th>
<th>Field 2</th>
<th>Field 3</th>
<th>Field 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>1</td>
<td>00000000</td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>3</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>6</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>10</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>11</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>12</td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>13</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

 ***************
 **_func multiplies 2 global ints
 ***************
.text
_func

<table>
<thead>
<tr>
<th>Field 1</th>
<th>Field 2</th>
<th>Field 3</th>
<th>Field 4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

 LDW   /*+B14(var1),A4
 LDW   /*+B14(var2),B0

 mpy32 A4,B0

```
4.12 Debugging Assembly Source

By default, when you compile an assembly file, the assembler provides symbolic debugging information that allows you to step through your assembly code in a debugger rather than using the Disassembly window in Code Composer Studio. This enables you to view source comments and other source-code annotations while debugging. The default has the same behavior as using the --symdebug:dwarf option. You can disable the generation of debugging information by using the --symdebug:none option.

The .asmfunc and .endasmfunc (see .asmfunc directive) directives enable you to use C characteristics in assembly code that makes the process of debugging an assembly file more closely resemble debugging a C/C++ source file.

The .asmfunc and .endasmfunc directives allow you to name certain areas of your code, and make these areas appear in the debugger as C functions. Contiguous sections of assembly code that are not enclosed by the .asmfunc and .endasmfunc directives are automatically placed in assembler-defined functions named with this syntax:

$ filename : starting source line : ending source line $

If you want to view your variables as a user-defined type in C code, the types must be declared and the variables must be defined in a C file. This C file can then be referenced in assembly code using the .ref directive (see .ref directive). Example 4-5 shows the cvars.c C program that defines a variable, svar, as the structure type X. The svar variable is then referenced in the addfive.asm assembly program in Example 4-6 and 5 is added to svar's second data member.

Compile both source files with the --symdebug:dwarf option (-g) and link them as follows:

```shell
cl6x --symdebug:dwarf cvars.c addfive.asm --run_linker --library=lnk.cmd --library=rts6600.lib --output_file=addfive.out
```

When you load this program into a symbolic debugger, addfive appears as a C function. You can monitor the values in svar while stepping through main just as you would any regular C variable.

**Example 4-5. Viewing Assembly Variables as C Types C Program**

```c
typedef struct
{
  int m1;
  int m2;
} X;
X svar = { 1, 2 };
```

**Example 4-6. Assembly Program for Example 4-5**

```assembly
; Tell the assembler we're referencing variable "_svar", which is defined in another file (cvars.c).
;--------------------------------------------------------------------------------------
; .ref _svar
;--------------------------------------------------------------------------------------
; addfive() - Add five to the second data member of _svar
;--------------------------------------------------------------------------------------
.text
.global addfive
addfive: .asmfunc
  LDW .D2T2 *+B14(_svar+4),B4 ; load svar.m2 into B4
  RET .S2 B3 ; return from function
  NOP 3 ; delay slots 1-3
  ADD .D2 5,B4,B4 ; add 5 to B4 (delay slot 4)
  STW .D2T2 B4,**+B14(_svar+4) ; store B4 back into svar.m2 (delay slot 5)
.endasmfunc
```
## 4.13 Cross-Reference Listings

A cross-reference listing shows symbols and their definitions. To obtain a cross-reference listing, invoke the assembler with the --cross_reference option (see Section 4.3) or use the .option directive with the X operand (see Select Listing Options). The assembler appends the cross-reference to the end of the source listing. Example 4-7 shows the four fields contained in the cross-reference listing.

### Example 4-7. An Assembler Cross-Reference Listing

<table>
<thead>
<tr>
<th>LABEL</th>
<th>VALUE</th>
<th>DEFN</th>
<th>REF</th>
</tr>
</thead>
<tbody>
<tr>
<td>.BIG_ENDIAN</td>
<td>00000000</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>.LITTLE_ENDIAN</td>
<td>00000001</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>TMS320C6400_PLUS</td>
<td>00000001</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>TMS320C6600</td>
<td>00000000</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>TMS320C6740</td>
<td>00000000</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>_func</td>
<td>00000000'</td>
<td>18</td>
<td></td>
</tr>
<tr>
<td>var1</td>
<td>00000000-</td>
<td>4</td>
<td>17</td>
</tr>
<tr>
<td>var2</td>
<td>00000004-</td>
<td>5</td>
<td>18</td>
</tr>
</tbody>
</table>

- **Label** column contains each symbol that was defined or referenced during the assembly.
- **Value** column contains an 8-digit hexadecimal number (which is the value assigned to the symbol) or a name that describes the symbol’s attributes. A value may also be preceded by a character that describes the symbol’s attributes. Table 4-6 lists these characters and names.
- **Definition** (DEFN) column contains the statement number that defines the symbol. This column is blank for undefined symbols.
- **Reference** (REF) column lists the line numbers of statements that reference the symbol. A blank in this column indicates that the symbol was never used.

### Table 4-6. Symbol Attributes

<table>
<thead>
<tr>
<th>Character or Name</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>REF</td>
<td>External reference (global symbol)</td>
</tr>
<tr>
<td>UNDF</td>
<td>Undefined</td>
</tr>
<tr>
<td>'</td>
<td>Symbol defined in a .text section</td>
</tr>
<tr>
<td>*</td>
<td>Symbol defined in a .data section</td>
</tr>
<tr>
<td>+</td>
<td>Symbol defined in a .sect section</td>
</tr>
<tr>
<td>-</td>
<td>Symbol defined in a .bss or .usect section</td>
</tr>
</tbody>
</table>
Assembler directives supply data to the program and control the assembly process. Assembler directives enable you to do the following:

- Assemble code and data into specified sections
- Reserve space in memory for uninitialized variables
- Control the appearance of listings
- Initialize memory
- Assemble conditional blocks
- Define global variables
- Specify libraries from which the assembler can obtain macros
- Examine symbolic debugging information

This chapter is divided into two parts: the first part (Section 5.1 through Section 5.11) describes the directives according to function, and the second part (Section 5.12) is an alphabetical reference.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>5.1 Directives Summary</td>
<td>75</td>
</tr>
<tr>
<td>5.2 Directives that Define Sections</td>
<td>80</td>
</tr>
<tr>
<td>5.3 Directives that Initialize Values</td>
<td>81</td>
</tr>
<tr>
<td>5.4 Directives that Perform Alignment and Reserve Space</td>
<td>83</td>
</tr>
<tr>
<td>5.5 Directives that Format the Output Listings</td>
<td>84</td>
</tr>
<tr>
<td>5.6 Directives that Reference Other Files</td>
<td>85</td>
</tr>
<tr>
<td>5.7 Directives that Enable Conditional Assembly</td>
<td>86</td>
</tr>
<tr>
<td>5.8 Directives that Define Union or Structure Types</td>
<td>86</td>
</tr>
<tr>
<td>5.9 Directives that Define Enumerated Types</td>
<td>87</td>
</tr>
<tr>
<td>5.10 Directives that Define Symbols at Assembly Time</td>
<td>87</td>
</tr>
<tr>
<td>5.11 Miscellaneous Directives</td>
<td>88</td>
</tr>
<tr>
<td>5.12 Directives Reference</td>
<td>89</td>
</tr>
</tbody>
</table>
5.1 Directives Summary

Table 5-1 through Table 5-16 summarize the assembler directives.

Besides the assembler directives documented here, the TMS320C6000 software tools support the following directives:

- Macro directives are discussed in Chapter 6; they are not discussed in this chapter.
- The assembly optimizer uses several directives that supply data and control the optimization process. Assembly optimizer directives are discussed in the *TMS320C6000 Optimizing Compiler User’s Guide*.
- The C compiler uses directives for symbolic debugging. Unlike other directives, symbolic debugging directives are not used in most assembly language programs. Appendix A discusses these directives; they are not discussed in this chapter.

Labels and Comments Are Not Shown in Syntaxes

**NOTE:** Most source statements that contain a directive can also contain a label and a comment. Labels begin in the first column (only labels and comments can appear in the first column), and comments must be preceded by a semicolon, or an asterisk if the comment is the only element in the line. To improve readability, labels and comments are not shown as part of the directive syntax here. See the detailed description of each directive for using labels with directives.

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.bss symbol, size in bytes[, alignment [bank offset]]</td>
<td>Reserves size bytes in the .bss (uninitialized data) section</td>
<td>.bss topic</td>
</tr>
<tr>
<td>.data</td>
<td>Assembles into the .data (initialized data) section</td>
<td>.data topic</td>
</tr>
<tr>
<td>.sect &quot;section name&quot;</td>
<td>Assembles into a named (initialized) section</td>
<td>.sect topic</td>
</tr>
<tr>
<td>.text</td>
<td>Assembles into the .text (executable code) section</td>
<td>.text topic</td>
</tr>
<tr>
<td>symbol .usect &quot;section name&quot;, size in bytes [alignment, bank offset]</td>
<td>Reserves size bytes in a named (uninitialized) section</td>
<td>.usect topic</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.endgroup</td>
<td>Ends the group declaration</td>
<td>.endgroup topic</td>
</tr>
<tr>
<td>.gmember section name</td>
<td>Designates section name as a member of the group</td>
<td>.gmember topic</td>
</tr>
<tr>
<td>.group group section name group type :</td>
<td>Begins a group declaration</td>
<td>.group topic</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.retain &quot;section name&quot;</td>
<td>Instructs the linker to include the current or specified section in the linked output file, regardless of whether the section is referenced or not</td>
<td>.retain topic</td>
</tr>
<tr>
<td>.retainref &quot;section name&quot;</td>
<td>Instructs the linker to include any data object that references the current or specified section.</td>
<td>.retain topic</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.bits value[, ... , value]</td>
<td>Initializes one or more successive bits in the current section</td>
<td>.bits topic</td>
</tr>
<tr>
<td>.byte value[, ... , value]</td>
<td>Initializes one or more successive bytes in the current section</td>
<td>.byte topic</td>
</tr>
<tr>
<td>.char value[, ... , value]</td>
<td>Initializes one or more successive bytes in the current section</td>
<td>.char topic</td>
</tr>
<tr>
<td>.cstring [expr,&quot;string&quot;,&quot;...&quot;, {expr,&quot;string&quot;,}]</td>
<td>Initializes one or more text strings</td>
<td>.cstring topic</td>
</tr>
</tbody>
</table>
Table 5-4. Directives that Initialize Values (Data and Memory) (continued)

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.double value[... , value]</td>
<td>Initializes one or more 64-bit, IEEE double-precision, floating-point constants</td>
<td>.double topic</td>
</tr>
<tr>
<td>.field value[size]</td>
<td>Initializes a field of size bits (1-32) with value</td>
<td>.field topic</td>
</tr>
<tr>
<td>.float value[... , value]</td>
<td>Initializes one or more 32-bit, IEEE single-precision, floating-point constants</td>
<td>.float topic</td>
</tr>
<tr>
<td>.half value[... , value]</td>
<td>Initializes one or more 16-bit integers (halfword)</td>
<td>.half topic</td>
</tr>
<tr>
<td>.int value[... , value]</td>
<td>Initializes one or more 32-bit integers</td>
<td>.int topic</td>
</tr>
<tr>
<td>.long value[... , value]</td>
<td>Initializes one or more 32-bit integers</td>
<td>.long topic</td>
</tr>
<tr>
<td>.short value[... , value]</td>
<td>Initializes one or more 16-bit integers (halfword)</td>
<td>.short topic</td>
</tr>
<tr>
<td>.string {expr, &quot;string&quot;, [... , {expr, &quot;string&quot;, }]}</td>
<td>Initializes one or more text strings</td>
<td>.string topic</td>
</tr>
<tr>
<td>.ubyte value[... , value]</td>
<td>Initializes one or more successive unsigned bytes in the current section</td>
<td>.ubyte topic</td>
</tr>
<tr>
<td>.uchar value[... , value]</td>
<td>Initializes one or more successive unsigned bytes in the current section</td>
<td>.uchar topic</td>
</tr>
<tr>
<td>.uhalf value[... , value]</td>
<td>Initializes one or more unsigned 16-bit integers (halfword)</td>
<td>.uhalf topic</td>
</tr>
<tr>
<td>.uint value[... , value]</td>
<td>Initializes one or more unsigned 32-bit integers</td>
<td>.uint topic</td>
</tr>
<tr>
<td>.ulong value[... , value]</td>
<td>Initializes one or more unsigned 32-bit integers</td>
<td>.ulong topic</td>
</tr>
<tr>
<td>.ushort value[... , value]</td>
<td>Initializes one or more unsigned 16-bit integers (halfword)</td>
<td>.ushort topic</td>
</tr>
<tr>
<td>.uword value[... , value]</td>
<td>Initializes one or more unsigned 32-bit integers</td>
<td>.uword topic</td>
</tr>
<tr>
<td>.word value[... , value]</td>
<td>Initializes one or more 32-bit integers</td>
<td>.word topic</td>
</tr>
</tbody>
</table>

Table 5-5. Directives that Perform Alignment and Reserve Space

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.align [size in bytes]</td>
<td>Aligns the SPC on a boundary specified by size in bytes, which must be a power of 2; defaults to byte boundary</td>
<td>.align topic</td>
</tr>
<tr>
<td>.bes size</td>
<td>Reserves size bytes in the current section; a label points to the end of the reserved space</td>
<td>.bes topic</td>
</tr>
<tr>
<td>.space size</td>
<td>Reserves size bytes in the current section; a label points to the beginning of the reserved space</td>
<td>.space topic</td>
</tr>
</tbody>
</table>

Table 5-6. Directives that Format the Output Listing

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.drlist</td>
<td>Enables listing of all directive lines (default)</td>
<td>.drlist topic</td>
</tr>
<tr>
<td>.drnolist</td>
<td>Suppresses listing of certain directive lines</td>
<td>.drnolist topic</td>
</tr>
<tr>
<td>.fclist</td>
<td>Allows false conditional code block listing (default)</td>
<td>.fclist topic</td>
</tr>
<tr>
<td>.fcnolist</td>
<td>Suppresses false conditional code block listing</td>
<td>.fcnolist topic</td>
</tr>
<tr>
<td>.length [page length]</td>
<td>Sets the page length of the source listing</td>
<td>.length topic</td>
</tr>
<tr>
<td>.list</td>
<td>Restarts the source listing</td>
<td>.list topic</td>
</tr>
<tr>
<td>.mlist</td>
<td>Allows macro listings and loop blocks (default)</td>
<td>.mlist topic</td>
</tr>
<tr>
<td>.mnolist</td>
<td>Suppresses macro listings and loop blocks</td>
<td>.mnolist topic</td>
</tr>
<tr>
<td>.nolist</td>
<td>Stops the source listing</td>
<td>.nolist topic</td>
</tr>
<tr>
<td>.option option[, option2, ...]</td>
<td>Selects output listing options; available options are A, B, D, H, L, M, N, O, R, T, W, and X</td>
<td>.option topic</td>
</tr>
<tr>
<td>.page</td>
<td>Ejects a page in the source listing</td>
<td>.page topic</td>
</tr>
<tr>
<td>.sslist</td>
<td>Allows expanded substitution symbol listing</td>
<td>.sslist topic</td>
</tr>
<tr>
<td>.ssnolist</td>
<td>Suppresses expanded substitution symbol listing (default)</td>
<td>.ssnolist topic</td>
</tr>
<tr>
<td>.tab size</td>
<td>Sets tab to size characters</td>
<td>.tab topic</td>
</tr>
<tr>
<td>.title &quot;string&quot;</td>
<td>Prints a title in the listing page heading</td>
<td>.title topic</td>
</tr>
</tbody>
</table>
### Table 5-6. Directives that Format the Output Listing (continued)

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.width [page width]</td>
<td>Sets the page width of the source listing</td>
<td>.width topic</td>
</tr>
</tbody>
</table>

### Table 5-7. Directives that Reference Other Files

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.copy [&quot;filename&quot;]</td>
<td>Includes source statements from another file</td>
<td>.copy topic</td>
</tr>
<tr>
<td>.include [&quot;filename&quot;]</td>
<td>Includes source statements from another file</td>
<td>.include topic</td>
</tr>
<tr>
<td>.mlib [&quot;filename&quot;]</td>
<td>Specifies a macro library from which to retrieve macro definitions</td>
<td>.mlib topic</td>
</tr>
</tbody>
</table>

### Table 5-8. Directives that Affect Symbol Linkage and Visibility

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.common symbol, size in bytes [, alignment]</td>
<td>Defines a common symbol for a variable.</td>
<td>.common topic</td>
</tr>
<tr>
<td>.def symbol[, ... , symbol[, alignment}}]</td>
<td>Identifies one or more symbols that are defined in the current module and that can be used in other modules</td>
<td>.def topic</td>
</tr>
<tr>
<td>.farcommon symbol, size in bytes [, alignment]</td>
<td>Defines a common symbol in far memory</td>
<td>.farcommon topic</td>
</tr>
<tr>
<td>.global symbol[, ... , symbol[, alignment}}]</td>
<td>Identifies one or more global (external) symbols</td>
<td>.global topic</td>
</tr>
<tr>
<td>.nearcommon symbol, size in bytes [, alignment]</td>
<td>Defines a common symbol in near memory</td>
<td>.nearcommon topic</td>
</tr>
<tr>
<td>.ref symbol[, ... , symbol[, alignment}}]</td>
<td>Identifies one or more symbols used in the current module that are defined in another module</td>
<td>.ref topic</td>
</tr>
<tr>
<td>.symdepend dst symbol name[, src symbol name]</td>
<td>Creates an artificial reference from a section to a symbol</td>
<td>.symdepend topic</td>
</tr>
<tr>
<td>.weak symbol name</td>
<td>Identifies a symbol used in the current module that is defined in another module</td>
<td>.weak topic</td>
</tr>
</tbody>
</table>

### Table 5-9. Directives that Control Dynamic Symbol Visibility

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.export &quot;symbolname&quot;</td>
<td>Sets visibility of symbolname to STV_EXPORT</td>
<td>.export topic</td>
</tr>
<tr>
<td>.hidden&quot;symbolname&quot;</td>
<td>Sets visibility of symbolname to STV_HIDDEN</td>
<td>.hidden topic</td>
</tr>
<tr>
<td>.import &quot;symbolname&quot;</td>
<td>Sets visibility of symbolname to STV_IMPORT</td>
<td>.import topic</td>
</tr>
<tr>
<td>.protected &quot;symbolname&quot;</td>
<td>Sets visibility of symbolname to STV_PROTECTED</td>
<td>.protected topic</td>
</tr>
</tbody>
</table>

### Table 5-10. Directives that Enable Conditional Assembly

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.if condition</td>
<td>Assembles code block if the condition is true</td>
<td>.if topic</td>
</tr>
<tr>
<td>.else</td>
<td>Assembles code block if the .if condition is false. When using the .if construct, the .else construct is optional.</td>
<td>.else topic</td>
</tr>
<tr>
<td>.elseif condition</td>
<td>Assembles code block if the .if condition is false and the .elseif condition is true. When using the .if construct, the .elseif construct is optional.</td>
<td>.elseif topic</td>
</tr>
<tr>
<td>.endif</td>
<td>Ends .if code block</td>
<td>.endif topic</td>
</tr>
<tr>
<td>.loop [count]</td>
<td>Begins repeatable assembly of a code block; the loop count is determined by the count.</td>
<td>.loop topic</td>
</tr>
<tr>
<td>.break [end condition]</td>
<td>Ends .loop assembly if end condition is true. When using the .loop construct, the .break construct is optional.</td>
<td>.break topic</td>
</tr>
<tr>
<td>.endloop</td>
<td>Ends .loop code block</td>
<td>.endloop topic</td>
</tr>
</tbody>
</table>
## Table 5-11. Directives that Define Union or Structure Types

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.cstruct</td>
<td>Acts like .struct, but adds padding and alignment like that which is done to C structures</td>
<td>.cstruct topic</td>
</tr>
<tr>
<td>.cunion</td>
<td>Acts like .union, but adds padding and alignment like that which is done to C unions</td>
<td>.cunion topic</td>
</tr>
<tr>
<td>.emember</td>
<td>Sets up C-like enumerated types in assembly code</td>
<td>Section 5.9</td>
</tr>
<tr>
<td>.endenum</td>
<td>Sets up C-like enumerated types in assembly code</td>
<td>Section 5.9</td>
</tr>
<tr>
<td>.endstruct</td>
<td>Ends a structure definition</td>
<td>.cstruct topic, .struct topic</td>
</tr>
<tr>
<td>.endunion</td>
<td>Ends a union definition</td>
<td>.cunion topic, .union topic</td>
</tr>
<tr>
<td>.enum</td>
<td>Sets up C-like enumerated types in assembly code</td>
<td>Section 5.9</td>
</tr>
<tr>
<td>.union</td>
<td>Begins a union definition</td>
<td>.union topic</td>
</tr>
<tr>
<td>.struct</td>
<td>Begins structure definition</td>
<td>.struct topic</td>
</tr>
<tr>
<td>.tag</td>
<td>Assigns structure attributes to a label</td>
<td>.cstruct topic, .struct topic</td>
</tr>
</tbody>
</table>

## Table 5-12. Directives that Define Symbols

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.asg [&quot;character string&quot;], substitution symbol</td>
<td>Assigns a character string to substitution symbol. Substitution symbols created with .asg can be redefined.</td>
<td>.asg topic</td>
</tr>
<tr>
<td>.clearmap</td>
<td>Cancels all .map assignments. Used by compiler for linear assembly source.</td>
<td>.clearmap topic</td>
</tr>
<tr>
<td>.define [&quot;character string&quot;], substitution symbol</td>
<td>Assigns a character string to substitution symbol. Substitution symbols created with .define cannot be redefined.</td>
<td>.asg topic</td>
</tr>
<tr>
<td>symbol equ value</td>
<td>Equates value with symbol</td>
<td>.equ topic</td>
</tr>
<tr>
<td>.elfsym name, SYM_SIZE(size)</td>
<td>Provides ELF symbol information</td>
<td>.elfsym topic</td>
</tr>
<tr>
<td>.eval expression, substitution symbol</td>
<td>Performs arithmetic on a numeric substitution symbol</td>
<td>.eval topic</td>
</tr>
<tr>
<td>.label symbol</td>
<td>Defines a load-time relocatable label in a section</td>
<td>.label topic</td>
</tr>
<tr>
<td>.map symbol/register</td>
<td>Assigns symbol to register. Used by compiler for linear assembly source.</td>
<td>.map topic</td>
</tr>
<tr>
<td>.newblock</td>
<td>Undefines local labels</td>
<td>.newblock topic</td>
</tr>
<tr>
<td>symbol set value</td>
<td>Equates value with symbol</td>
<td>.set topic</td>
</tr>
<tr>
<td>.unasg symbol</td>
<td>Turns off assignment of symbol as a substitution symbol</td>
<td>.unasg topic</td>
</tr>
<tr>
<td>.undefine symbol</td>
<td>Turns off assignment of symbol as a substitution symbol</td>
<td>.unasg topic</td>
</tr>
</tbody>
</table>

## Table 5-13. Directives that Create or Affect Macros

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>macname .macro [parameter1,..., parameterN]</td>
<td>Begin definition of macro named macname</td>
<td>.macro topic</td>
</tr>
<tr>
<td>.endm</td>
<td>End macro definition</td>
<td>.endm topic</td>
</tr>
<tr>
<td>.mexit</td>
<td>Go to .endm</td>
<td>Section 6.2</td>
</tr>
<tr>
<td>.mlib filename</td>
<td>Identify library containing macro definitions</td>
<td>.mlib topic</td>
</tr>
<tr>
<td>.var</td>
<td>Adds a local substitution symbol to a macro's parameter list</td>
<td>.var topic</td>
</tr>
</tbody>
</table>
### Table 5-14. Directives that Control Diagnostics

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.emsg string</td>
<td>Sends user-defined error messages to the output device; produces no .obj file</td>
<td>.emsg topic</td>
</tr>
<tr>
<td>.mmsg string</td>
<td>Sends user-defined messages to the output device</td>
<td>.mmsg topic</td>
</tr>
<tr>
<td>.noremark[num]</td>
<td>Identifies the beginning of a block of code in which the assembler suppresses the num remark</td>
<td>.noremark topic</td>
</tr>
<tr>
<td>.remark [num]</td>
<td>Resumes the default behavior of generating the remark(s) previously suppressed by .noremark</td>
<td>.remark topic</td>
</tr>
<tr>
<td>.wmsg string</td>
<td>Sends user-defined warning messages to the output device</td>
<td>.wmsg topic</td>
</tr>
</tbody>
</table>

### Table 5-15. Directives that Perform Assembly Source Debug

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.asmfunc</td>
<td>Identifies the beginning of a block of code that contains a function</td>
<td>.asmfunc topic</td>
</tr>
<tr>
<td>.endasmfunc</td>
<td>Identifies the end of a block of code that contains a function</td>
<td>.endasmfunc topic</td>
</tr>
</tbody>
</table>

### Table 5-16. Directives that Perform Miscellaneous Functions

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>.cdecls [options,&quot;filename&quot;, &quot;filename2&quot;, ...]</td>
<td>Share C headers between C and assembly code</td>
<td>.cdecls topic</td>
</tr>
<tr>
<td>.end</td>
<td>Ends program</td>
<td>.end topic</td>
</tr>
<tr>
<td>.nocomp</td>
<td>Instructs tools to not utilize 16-bit instructions for section</td>
<td>.nocomp topic</td>
</tr>
</tbody>
</table>

In addition to the assembly directives that you can use in your code, the C/C++ compiler produces several directives when it creates assembly code. These directives are to be used only by the compiler; do not attempt to use these directives.

- **DWARF directives listed in Section A.1**
- The .battr directive is used to encode build attributes for the object file. For more information about build attributes generated and used by the C6000 Code Generation Tools, please see *The C6000 Embedded Application Binary Interface* application report (**SPRAR89**).
- The .bound directive is used internally.
- The .comdat directive is used internally.
- The .compiler_opts directive indicates that the assembly code was produced by the compiler, and which build model options were used for this file.
- The .tls directive is used internally.
5.2 Directives that Define Sections

These directives associate portions of an assembly language program with the appropriate sections:

- The `.bss` directive reserves space in the `.bss` section for uninitialized variables.
- The `.data` directive identifies portions of code in the `.data` section. The `.data` section usually contains initialized data.
- The `.retain` directive can be used to indicate that the current or specified section must be included in the linked output. Thus even if no other sections included in the link reference the current or specified section, it is still included in the link.
- The `.retainrefs` directive can be used to force sections that refer to the specified section. This is useful in the case of interrupt vectors.
- The `.sect` directive defines an initialized named section and associates subsequent code or data with that section. A section defined with `.sect` can contain code or data.
- The `.text` directive identifies portions of code in the `.text` section. The `.text` section usually contains executable code.
- The `.usect` directive reserves space in an uninitialized named section. The `.usect` directive is similar to the `.bss` directive, but it allows you to reserve space separately from the `.bss` section.

Chapter 2 discusses these sections in detail.

Example 5-1 shows how you can use sections directives to associate code and data with the proper sections. This is an output listing; column 1 shows line numbers, and column 2 shows the SPC values. (Each section has its own program counter, or SPC.) When code is first placed in a section, its SPC equals 0. When you resume assembling into a section after other code is assembled, the section’s SPC resumes counting as if there had been no intervening code.

The directives in Example 5-1 perform the following tasks:

- `.text` initializes words with the values 1, 2, 3, 4, 5, 6, 7, and 8.
- `.data` initializes words with the values 9, 10, 11, 12, 13, 14, 15, and 16.
- `var_defs` initializes words with the values 17 and 18.
- `.bss` reserves 19 bytes.
- `xy` reserves 20 bytes.
Directives that Define Sections

The .bss and .usect directives do not end the current section or begin new sections; they reserve the specified amount of space, and then the assembler resumes assembling code or data into the current section.

Example 5-1. Sections Directives

```
00000004 00000002
  6 00000008 00000003 .word 3,4
0000000c 00000004
  7
  8  **************************************************
  9  * Start assembling into the .data section *  
 10  **************************************************
 11 00000000 .data
 12 00000000 00000009 .word 9, 10
 00000004 0000000a
 13 00000008 0000000b .word 11, 12
0000000c 0000000c
 14
 15  **************************************************
 16  * Start assembling into a named, *
 17  * initialized section, var_defs *
 18  **************************************************
 19 00000000 .sect "var_defs"
 20 00000000 00000011 .word 17, 18
 00000004 00000012
 21
 22  **************************************************
 23  * Resume assembling into the .data section *  
 24  **************************************************
 25 00000010 .data
 26 00000010 0000000d .word 13, 14
 00000014 0000000e
 27 00000000 .bss sym, 19 ; Reserve space in .bss
 28 00000018 0000000f .word 15, 16 ; Still in .data
0000001c 00000010
 29
 30  **************************************************
 31  * Resume assembling into the .text section *  
 32  **************************************************
 33 00000010 .text
 34 00000010 00000005 .word 5, 6
 00000014 00000006
 35 00000000 usym .usect "xy", 20 ; Reserve space in xy
 36 00000018 00000007 .word 7, 8 ; Still in .text
0000001c 00000008
```

5.3 Directives that Initialize Values

Several directives assemble values for the current section. For example:

- The .byte and .char directives place one or more 8-bit values into consecutive bytes of the current section. These directives are similar to .word, .int, and .long, except that the width of each value is restricted to 8 bits.

- The .double directive calculates the double-precision (64-bit) IEEE floating-point representation of one or more floating-point values and stores them in two consecutive words in the current section. The .double directive automatically aligns to the double-word boundary.

- The .field directive places a single value into a specified number of bits in the current word. With .field, you can pack multiple fields into a single word; the assembler does not increment the SPC until a word is filled. If a field will not fit in the space remaining in the current word, .field will insert zeros to fill the current word and then place the field in the next word. See the .field topic.
Figure 5-1 shows how fields are packed into a word. Using the following assembled code, notice that the SPC does not change (the fields are packed into the same word):

```
1 00000000 00000003 .field 3,4
2 00000000 00000083 .field 8,5
3 00000000 00002083 .field 16,7
```

### Figure 5-1. The .field Directive

- The `.float` directive calculates the single-precision (32-bit) IEEE floating-point representation of a single floating-point value and stores it in a word in the current section that is aligned to a word boundary.
- The `.half` and `.short` directives place one or more 16-bit values into consecutive 16-bit fields (halfwords) in the current section. These directives automatically align to a short (2-byte) boundary.
- The `.int`, `.long`, and `.word` directives place one or more 32-bit values into consecutive 32-bit fields (words) in the current section. These directives automatically align to a word boundary.
- The `.string` and `.cstring` directives place 8-bit characters from one or more character strings into the current section. The `.string` and `.cstring` directives are similar to `.byte`, placing an 8-bit character in each consecutive byte of the current section. The `.cstring` directive adds a NUL character needed by C; the `.string` directive does not add a NUL character.
- The `.ubyte`, `.uchar`, `.uhalf`, `.uint`, `.ulong`, `.ushort`, and `.uword` directives are provided as unsigned versions of their respective signed directives. These directives are used primarily by the C/C++ compiler to support unsigned types in C/C++.

### Directives that Initialize Constants When Used in a .struct/.endstruct Sequence

**NOTE:** The `.bits`, `.byte`, `.char`, `.int`, `.long`, `.word`, `.double`, `.half`, `.short`, `.string`, `.ubyte`, `.uchar`, `.uhalf`, `.uint`, `.ulong`, `.ushort`, `.uword`, `.float`, and `.field` directives do not initialize memory when they are part of a .struct/.endstruct sequence; rather, they define a member’s size. For more information, see the .struct/.endstruct directives.

Figure 5-2 compares the `.byte`, `.half`, `.word`, and `.string` directives using the following assembled code:

```
1 00000000 000000AB .byte 0ABh
2 .align 4
3 00000000 0000CDEF .half 0CDEFe
4 00000008 89ABCDEF .word 089ABCDedef
5 0000000c 00000068 .string "help"
 0000000d 00000065
 0000000e 0000006C
 0000000f 00000070
```
5.4 Directives that Perform Alignment and Reserve Space

These directives align the section program counter (SPC) or reserve space in a section:

- The `.align` directive aligns the SPC at the next byte boundary. This directive is useful with the `.field` directive when you do not want to pack two adjacent fields in the same byte. The size specified by the `.align` directive must equal a power of 2; the value must be between 1 and 32,768, inclusive.

Figure 5-3 demonstrates the `.align` directive. Using the following assembled code:

```
1 00000000 00AABBCC .field 0AABBCCh,24
3 .align 2
4 00000000 00AABBCC .field 0Bh,5
5 00000004 000000DE .field 0DEh,10
```

Figure 5-3. The `.align` Directive

```
Word | Contents | Code
1 | 00000000 00AABBCC 0AABBCCh | .field 0AABBCCh,24
3 | 00000000 00AABBCC | .field 0Bh,5
5 | 00000004 000000DE | .field 0DEh,10
```

5.4 Directives that Perform Alignment and Reserve Space

These directives align the section program counter (SPC) or reserve space in a section:

- The `.align` directive aligns the SPC at the next byte boundary. This directive is useful with the `.field` directive when you do not want to pack two adjacent fields in the same byte. The size specified by the `.align` directive must equal a power of 2; the value must be between 1 and 32,768, inclusive.

Figure 5-3 demonstrates the `.align` directive. Using the following assembled code:

```
1 00000000 00AABBCC .field 0AABBCCh,24
3 .align 2
4 00000000 00AABBCC .field 0Bh,5
5 00000004 000000DE .field 0DEh,10
```

Figure 5-3. The `.align` Directive

```
Word | Contents | Code
1 | 00000000 00AABBCC 0AABBCCh | .field 0AABBCCh,24
3 | 00000000 00AABBCC | .field 0Bh,5
5 | 00000004 000000DE | .field 0DEh,10
```

5.4 Directives that Perform Alignment and Reserve Space

These directives align the section program counter (SPC) or reserve space in a section:

- The `.align` directive aligns the SPC at the next byte boundary. This directive is useful with the `.field` directive when you do not want to pack two adjacent fields in the same byte. The size specified by the `.align` directive must equal a power of 2; the value must be between 1 and 32,768, inclusive.

Figure 5-3 demonstrates the `.align` directive. Using the following assembled code:

```
1 00000000 00AABBCC .field 0AABBCCh,24
3 .align 2
4 00000000 00AABBCC .field 0Bh,5
5 00000004 000000DE .field 0DEh,10
```

Figure 5-3. The `.align` Directive

```
Word | Contents | Code
1 | 00000000 00AABBCC 0AABBCCh | .field 0AABBCCh,24
3 | 00000000 00AABBCC | .field 0Bh,5
5 | 00000004 000000DE | .field 0DEh,10
```
Directives that Format the Output Listings

The .bes and .space directives reserve a specified number of bytes in the current section. The assembler fills these reserved bytes with 0s.

- When you use a label with .space, it points to the first byte that contains reserved bits.
- When you use a label with .bes, it points to the last byte that contains reserved bits.

**Figure 5-4** shows how the .space and .bes directives work for the following assembled code:

```
1 2 00000000 00000100 .word 100h, 200h
00000004 00000200
3 00000008 Res_1: .space 17
4 0000001c 0000001f .word 15
5 00000033 Res_2: .bes 20
6 00000034 000000BA .byte 0BAh
```

Res_1 points to the first byte in the space reserved by .space. Res_2 points to the last byte in the space reserved by .bes.

**Figure 5-4. The .space and .bes Directives**

![Diagram showing how .space and .bes directives work](image)

### 5.5 Directives that Format the Output Listings

These directives format the listing file:

- The .drlist directive causes printing of the directive lines to the listing; the .drnolist directive turns it off for certain directives. You can use the .drnolist directive to suppress the printing of the following directives. You can use the .drlist directive to turn the listing on again.

- The source code listing includes false conditional blocks that do not generate code. The .fcnist and .fcnolist directives turn this listing on and off. You can use the .fcnist directive to list false conditional blocks exactly as they appear in the source code. You can use the .fcnolist directive to list only the conditional blocks that are actually assembled.

- The .length directive controls the page length of the listing file. You can use this directive to adjust listings for various output devices.

- The .list and .nolist directives turn the output listing on and off. You can use the .nolist directive to prevent the assembler from printing selected source statements in the listing file. Use the .list directive to turn the listing on again.

- The source code listing includes macro expansions and loop blocks. The .mlist and .mnolist directives turn this listing on and off. You can use the .mlist directive to print all macro expansions and loop blocks to the listing, and the .mnolist directive to suppress this listing.
The .option directive controls certain features in the listing file. This directive has the following operands:

- **A**: Turns on listing of all directives and data, and subsequent expansions, macros, and blocks.
- **B**: Limits the listing of .byte and .char directives to one line.
- **D**: Turns off the listing of certain directives (same effect as .drnolist).
- **H**: Limits the listing of .half and .short directives to one line.
- **L**: Limits the listing of .long directives to one line.
- **M**: Turns off macro expansions in the listing.
- **N**: Turns off listing (performs .nolist).
- **O**: Turns on listing (performs .list).
- **T**: Limits the listing of .string directives to one line.
- **W**: Limits the listing of .word and .int directives to one line.
- **X**: Produces a cross-reference listing of symbols. You can also obtain a cross-reference listing by invoking the assembler with the --cross_reference option (see Section 4.3).

The .page directive causes a page eject in the output listing.

The source code listing includes substitution symbol expansions. The .sslist and .ssnolist directives turn this listing on and off. You can use the .sslist directive to print all substitution symbol expansions to the listing, and the .ssnolist directive to suppress this listing. These directives are useful for debugging the expansion of substitution symbols.

The .tab directive defines tab size.

The .title directive supplies a title that the assembler prints at the top of each page.

The .width directive controls the page width of the listing file. You can use this directive to adjust listings for various output devices.

## 5.6 Directives that Reference Other Files

These directives supply information for or about other files that can be used in the assembly of the current file:

- The .copy and .include directives tell the assembler to begin reading source statements from another file. When the assembler finishes reading the source statements in the copy/include file, it resumes reading source statements from the current file. The statements read from a copied file are printed in the listing file; the statements read from an included file are not printed in the listing file.

- The .def directive identifies a symbol that is defined in the current module and that can be used in another module. The assembler includes the symbol in the symbol table.

- The .global directive declares a symbol external so that it is available to other modules at link time. (For more information about global symbols, see Section 2.6.1). The .global directive does double duty, acting as a .def for defined symbols and as a .ref for undefined symbols. The linker resolves an undefined global symbol reference only if the symbol is used in the program. The .global directive declares a 16-bit symbol.

- The .mlib directive supplies the assembler with the name of an archive library that contains macro definitions. When the assembler encounters a macro that is not defined in the current module, it searches for it in the macro library specified with .mlib.

- The .ref directive identifies a symbol that is used in the current module but is defined in another module. The assembler marks the symbol as an undefined external symbol and enters it in the object symbol table so the linker can resolve its definition. The .ref directive forces the linker to resolve a symbol reference.

- The .symdepend directive creates an artificial reference from the section defining the source symbol name to the destination symbol. The .symdepend directive prevents the linker from removing the section containing the destination symbol if the source symbol section is included in the output module.

- The .weak directive identifies a symbol that is used in the current module but is defined in another module. It is equivalent to the .ref directive, except that the reference has weak linkage.
5.7 Directives that Enable Conditional Assembly

Conditional assembly directives enable you to instruct the assembler to assemble certain sections of code according to a true or false evaluation of an expression. Two sets of directives allow you to assemble conditional blocks of code:

- The `.if/.elseif/.else/.endif` directives tell the assembler to conditionally assemble a block of code according to the evaluation of an expression.
  
  `.if condition` marks the beginning of a conditional block and assembles code if the `.if condition` is true.
  
  `[.elseif condition]` marks a block of code to be assembled if the `.if condition` is false and the `.elseif condition` is true.
  
  `.else` marks a block of code to be assembled if the `.if condition` is false and any `.elseif conditions` are false.
  
  `.endif` marks the end of a conditional block and terminates the block.

- The `.loop/.break/.endloop` directives tell the assembler to repeatedly assemble a block of code according to the evaluation of an expression.
  
  `.loop [count]` marks the beginning of a repeatable block of code. The optional expression evaluates to the loop count.
  
  `.break [end condition]` tells the assembler to assemble repeatedly when the `.break end condition` is false and to go to the code immediately after `.endloop` when the expression is true or omitted.
  
  `.endloop` marks the end of a repeatable block.

The assembler supports several relational operators that are useful for conditional expressions. For more information about relational operators, see Section 4.9.2.

5.8 Directives that Define Union or Structure Types

These directives set up specialized types for later use with the .tag directive, allowing you to use symbolic names to refer to portions of a complex object. The types created are analogous to the struct and union types of the C language.

The .struct, .union, .cstruct, and .cunion directives group related data into an aggregate structure which is more easily accessed. These directives do not allocate space for any object. Objects must be separately allocated, and the .tag directive must be used to assign the type to the object.

```assembly
COORDT .struct ; structure tag definition
    X .byte;
    Y .byte
T_LEN .endstruct

COORD .tag COORDT ; declare COORD (coordinate)
    .bss COORD, T_LEN ; actual memory allocation

LDB *+B14(COORD.Y), A2 ; move member Y of structure
                           ; COORD into register A2
```

The .cstruct and .cunion directives guarantee that the data structure will have the same alignment and padding as if the structure were defined in analogous C code. This allows structures to be shared between C and assembly code. See Chapter 11. For .struct and .union, element offset calculation is left up to the assembler, so the layout may be different than .cstruct and .cunion.
5.9 Directives that Define Enumerated Types

These directives set up specialized types for later use in expressions allowing you to use symbolic names to refer to compile-time constants. The types created are analogous to the enum type of the C language. This allows enumerated types to be shared between C and assembly code. See Chapter 11.

See Section 11.2.10 for an example of using .enum.

5.10 Directives that Define Symbols at Assembly Time

Assembly-time symbol directives equate meaningful symbol names to constant values or strings.

• The .asg directive assigns a character string to a substitution symbol. The value is stored in the substitution symbol table. When the assembler encounters a substitution symbol, it replaces the symbol with its character string value. Substitution symbols created with .asg can be redefined.

```
.asg "10, 20, 30, 40", coefficients
        ; Assign string to substitution symbol.
.byte coefficients
        ; Place the symbol values 10, 20, 30, and 40
        ; into consecutive bytes in current section.
```

• The .define directive assigns a character string to a substitution symbol. The value is stored in the substitution symbol table. When the assembler encounters a substitution symbol, it replaces the symbol with its character string value. Substitution symbols created with .define cannot be redefined.

• The .eval directive evaluates a well-defined expression, translates the results into a character string, and assigns the character string to a substitution symbol. This directive is most useful for manipulating counters:

```
.asg 1 , x ; x = 1
.loop ; Begin conditional loop.
.byte x*10h ; Store value into current section.
.break x = 4 ; Break loop if x = 4.
.eval x+1, x ; Increment x by 1.
.endloop ; End conditional loop.
```

• The .label directive defines a special symbol that refers to the load-time address within the current section. This is useful when a section loads at one address but runs at a different address. For example, you may want to load a block of performance-critical code into slower off-chip memory to save space and move the code to high-speed on-chip memory to run. See the .label topic for an example using a load-time address label.

• The .set and .equ directives set a constant value to a symbol. The symbol is stored in the symbol table and cannot be redefined; for example:

```
bval .set 0100h ; Set bval = 0100h
.long bval, bval+2, bval+12
        ; Store the values 0100h, 0200h, and 010Ch
        ; into consecutive words in current section.
```

The .set and .equ directives produce no object code. The two directives are identical and can be used interchangeably.

• The .unasg directive turns off substitution symbol assignment made with .asg.
• The .undefined directive turns off substitution symbol assignment made with .define.
• The .var directive allows you to use substitution symbols as local variables within a macro.
5.11 Miscellaneous Directives

These directives enable miscellaneous functions or features:

- The `.asmfunc` and `.endasmfunc` directives mark function boundaries. These directives are used with the compiler `--symdebug:dwarf (-g)` option to generate debug information for assembly functions.

- The `.cdecls` directive enables programmers in mixed assembly and C/C++ environments to share C headers containing declarations and prototypes between C and assembly code.

- The `.end` directive terminates assembly. If you use the `.end` directive, it should be the last source statement of a program. This directive has the same effect as an end-of-file character.

- The `.group`, `.gmember`, and `.endgroup` directives define an ELF group section to be shared by several sections.

- The `.import`, `.export`, `.hidden`, and `.protected` directives set the dynamic visibility of a global symbol. See Section 8.12 for an explanation of symbol visibility.

- The `.newblock` directive resets local labels. Local labels are symbols of the form $n$, where $n$ is a decimal digit, or of the form NAME?, where you specify NAME. They are defined when they appear in the label field. Local labels are temporary labels that can be used as operands for jump instructions. The `.newblock` directive limits the scope of local labels by resetting them after they are used. See Section 4.8.3 for information on local labels.

- The `.nocmp` directive instructs the tools to not utilize 16-bit instructions for the section `.nocmp` appears in.

- The `.noremark` directive begins a block of code in which the assembler suppresses the specified assembler remark. A remark is an informational assembler message that is less severe than a warning. The `.remark` directive re-enables the remark(s) previously suppressed by `.noremark`.

These three directives enable you to define your own error and warning messages:

- The `.emsg` directive sends error messages to the standard output device. The `.emsg` directive generates errors in the same manner as the assembler, incrementing the error count and preventing the assembler from producing an object file.

- The `.mmsg` directive sends assembly-time messages to the standard output device. The `.mmsg` directive functions in the same manner as the `.emsg` and `.wmsg` directives but does not set the error count or the warning count. It does not affect the creation of the object file.

- The `.wmsg` directive sends warning messages to the standard output device. The `.wmsg` directive functions in the same manner as the `.emsg` directive but increments the warning count rather than the error count. It does not affect the creation of the object file.

For more information about using the error and warning directives in macros, see Section 6.7.
5.12 Directives Reference

The remainder of this chapter is a reference. Generally, the directives are organized alphabetically, one directive per topic. Related directives (such as .if/.else/.endif), however, are presented together in one topic.

.align

Align SPC on the Next Boundary

Syntax

.align [size in bytes]

Description

The .align directive aligns the section program counter (SPC) on the next boundary, depending on the size in bytes parameter. The size can be any power of 2, although only certain values are useful for alignment. An operand of 1 aligns the SPC on the next byte boundary, and this is the default if no size in bytes is given. The size in bytes must equal a power of 2; the value must be between 1 and 32,768, inclusive. The assembler assembles words containing null values (0) up to the next size in bytes boundary:

1   aligns SPC to byte boundary
2   aligns SPC to halfword boundary
4   aligns SPC to word boundary
8   aligns SPC to doubleword boundary

Using the .align directive has two effects:

• The assembler aligns the SPC on an x-byte boundary within the current section.
• The assembler sets a flag that forces the linker to align the section so that individual alignments remain intact when a section is loaded into memory.

Example

This example shows several types of alignment, including .align 2, .align 8, and a default .align.

```
1 00000000 00000004 .byte 4
2 .align 2
3 00000002 00000045 .string "Errorcnt"
   00000003 00000072
   00000004 00000072
   00000005 0000006F
   00000006 00000072
   00000007 00000063
   00000008 0000006E
   00000009 00000074
4 .align
5 00000000 0003746E .field 3,3
6 00000000 002B746E .field 5,4
7 .align 2
8 00000000 00000003 .field 3,3
9 .align 8
10 00000010 00000005 .field 5,4
11 .align
12 00000011 00000004 .byte 4
```
Assign a Substitution Symbol

**Syntax**

```
.asg "character string",substitution symbol
.define "character string",substitution symbol
.eval expression,substitution symbol
```

**Description**

The `.asg` and `.define` directives assign character strings to substitution symbols. Substitution symbols are stored in the substitution symbol table. The `.asg` directive can be used in many of the same ways as the `.set` directive, but while `.set` assigns a constant value (which cannot be redefined) to a symbol, `.asg` assigns a character string (which can be redefined) to a substitution symbol.

- The assembler assigns the *character string* to the substitution symbol.
- The *substitution symbol* must be a valid symbol name. The substitution symbol is up to 128 characters long and must begin with a letter. Remaining characters of the symbol can be a combination of alphanumeric characters, the underscore (_), and the dollar sign ($).

The `.define` directive functions in the same manner as the `.asg` directive, except that `.define` disallows creation of a substitution symbol that has the same name as a register symbol or mnemonic. It does not create a new symbol name space in the assembler, rather it uses the existing substitution symbol name space. The `.define` directive is used to prevent corruption of the assembly environment when converting C/C++ headers. See Chapter 11 for more information about using C/C++ headers in assembly source.

The `.eval` directive performs arithmetic on substitution symbols, which are stored in the substitution symbol table. This directive evaluates the *expression* and assigns the string value of the result to the substitution symbol. The `.eval` directive is especially useful as a counter in `.loop/.endloop` blocks.

- The *expression* is a well-defined alphanumeric expression in which all symbols have been previously defined in the current source module, so that the result is an absolute expression.
- The *substitution symbol* must be a valid symbol name. The substitution symbol is up to 128 characters long and must begin with a letter. Remaining characters of the symbol can be a combination of alphanumeric characters, the underscore (_), and the dollar sign ($).

See the `.unasg/.undefine` topic for information on turning off a substitution symbol.
Example

This example shows how .asg and .eval can be used.

```
1 .sslist ; show expanded substitution symbols
2
3 .asg *+B14(100), GLOB100
4 .asg *+B15(4), ARG0
5
6 00000000 003B22E4 LDW GLOB100,A0
# LDW *+B14(100),A0
7 00000004 00BC22E4 LDW ARG0,A1
# LDW *+B15(4),A1
8 00000008 00006000 NOP 4
9 0000000c 010401E0 ADD A0,A1,A2
10
11 .asg 0,x
12 .loop 5
13 .word 100*x
14 .eval x+1,x
15 .endloop
1 00000010 00000000 .word 100*x
# .word 100*0
1 00000014 00000064 .word 100*x
# .word 100*1
1 00000018 000000C8 .word 100*x
# .word 100*2
1 0000001c 0000012c .word 100*x
# .word 100*3
1 00000020 00000190 .word 100*x
# .word 100*4
1 .eval x+1,x
# .eval 4+1,x
```
.asmfunc/.endasmfunc  Mark Function Boundaries

Syntax
symbol .asmfunc [stack_usage(num)]
.endasmfunc

Description
The .asmfunc and .endasmfunc directives mark function boundaries. These directives are used with the compiler -g option (--symdebug:dwarf) to allow assembly code sections to be debugged in the same manner as C/C++ functions.

You should not use the same directives generated by the compiler (see Appendix A) to accomplish assembly debugging; those directives should be used only by the compiler to generate symbolic debugging information for C/C++ source files.

The symbol is a label that must appear in the label field.

The .asmfunc directive has an optional parameter, stack_usage, which indicates that the function may use up to num bytes.

Consecutive ranges of assembly code that are not enclosed within a pair of .asmfunc and .endasmfunc directives are given a default name in the following format:
$ filename : beginning source line : ending source line $

Example
This example generates debug information for the user_func section.

```
1 00000000 .sect ".text"
2 .global userfunc
3 .global _printf
4
5 userfunc: .asmfunc stack_usage(16)
6 00000000 00000010! CALL .S1 _printf
7 00000004 01BC94F6 STW .D2T2 B3,*B15--(16)
8 00000008 01800E2A' MVKL .S2 RL0,B3
9 0000000C 01800028+ MVKL .S1 SL1+0,A3
10 00000010 01800068+ MVKH .S1 SL1+0,A3
11
12 00000014 01BC22F5 STW .D2T1 A3,*+B15(4)
13 00000018 0180006A' || MVKH .S2 RL0,B3
14
15 0000001C 01BC92E6 RL0: LDW .D2T2 *++B15(16),B3
16 00000020 020008C0 ZERO .D1 A4
17 00000024 00004000 NOP 3
18 00000028 000C3626 RET .S2 B3
19 0000002C 00008000 NOP 5
20 .endasmfunc
21
22 00000000 .sect ".const"
23 00000000 00000048 SL1: .string "Hello World!",10,0
   00000001 00000065
   00000002 0000006C
   00000003 0000006C
   00000004 0000006F
   00000005 00000020
   00000006 00000057
   00000007 0000006F
   00000008 00000072
   00000009 0000006C
   0000000A 00000064
   0000000B 00000021
   0000000C 0000000A
   0000000D 00000000
```
**.bits**

*Initialize Bits*

**Syntax**

```
.bits value[, ... , value_n]
```

**Description**

The `.bits` directive places one or more values into consecutive bits of the current section. The `.bits` directive is similar to the `.field` directive (see `.field` topic). However, the `.bits` directive does not allow you to specify the number of bits to fill or increment the SPC.
.bss Reserve Space in the .bss Section

Syntax

```
.bss symbol, size in bytes[, alignment[, bank offset]]
```

Description

The .bss directive reserves space for variables in the .bss section. This directive is usually used to allocate space in RAM.

- The symbol is a required parameter. It defines a symbol that points to the first location reserved by the directive. The symbol name must correspond to the variable that you are reserving space for.

- The size in bytes is a required parameter; it must be an absolute constant expression. The assembler allocates size bytes in the .bss section. There is no default size.

- The alignment is an optional parameter that ensures that the space allocated to the symbol occurs on the specified boundary. This must be set to a power of 2. If the SPC is already aligned to the specified boundary, it is not incremented.

- The bank offset is an optional parameter that ensures that the space allocated to the symbol occurs on a specific memory bank boundary. The bank offset value measures the number of bytes to offset from the alignment specified before assigning the symbol to that location.

For more information about sections, see Chapter 2.

Example

In this example, the .bss directive allocates space for a variable, array. The symbol array points to 100 bytes of uninitialized space (at .bss SPC = 0). Symbols declared with the .bss directive can be referenced in the same manner as other symbols and can also be declared global.

```
1 *******************************************
2 ** Start assembling into .text section. **
3 *******************************************
4 00000000 .text
5 00000000 008001A0 MV A0,A1
6
7 *******************************************
8 ** Allocate 100 bytes in .bss. **
9 *******************************************
10 00000000 .bss array,100
11
12 *******************************************
13 ** Still in .text **
14 *******************************************
15 00000004 010401A0 MV A1,A2
16
17 *******************************************
18 ** Declare external .bss symbol **
19 *******************************************
20 .global array
```
.byte/.ubyte/.char/.uchar  Initialize Byte

Syntax

\[
\text{.byte} \ value[, ..., \ value_n]
\]
\[
\text{.ubyte} \ value[, ..., \ value_n]
\]
\[
\text{.char} \ value[, ..., \ value_n]
\]
\[
\text{.uchar} \ value[, ..., \ value_n]
\]

Description

The .byte, .ubyte, .char, and .uchar directives place one or more values into consecutive bytes of the current section. A value can be one of the following:

- An expression that the assembler evaluates and treats as an 8-bit signed number
- A character string enclosed in double quotes. Each character in a string represents a separate value, and values are stored in consecutive bytes. The entire string must be enclosed in quotes.

With little-endian ordering, the first byte occupies the eight least significant bits of a full 32-bit word. The second byte occupies bits eight through 15 while the third byte occupies bits 16 through 23. The assembler truncates values greater than eight bits.

If you use a label, it points to the location of the first byte that is initialized.

When you use these directives in a .struct/.endstruct sequence, they define a member's size; they do not initialize memory. For more information, see the .struct/.endstruct/.tag topic.

Example

In this example, 8-bit values (10, -1, abc, and a) are placed into consecutive bytes in memory with .byte. Also, 8-bit values (8, -3, def, and b) are placed into consecutive bytes in memory with .char. The label STRX has the value 0h, which is the location of the first initialized byte. The label STRY has the value 6h, which is the first byte initialized by the .char directive.

```
1 00000000 0000000A STRX .byte 10,-1,"abc","a"
   00000001 000000FF
   00000002 00000061
   00000003 00000062
   00000004 00000063
   00000005 00000061
2 00000006 00000008 STRY .char 8,-3,"def","b"
```
.cdecls

**Share C Headers Between C and Assembly Code**

**Syntax**

**Single Line:**

```
.cdecls [options ,] "filename[", "filename2"[,...]]
```

**Multiple Lines:**

```
.cdecls [options]
%
/*---------------------------------------------*/
/* C/C++ code - Typically a list of #includes and a few defines */
/*---------------------------------------------*/
%
```

**Description**

The `.cdecls` directive allows programmers in mixed assembly and C/C++ environments to share C headers containing declarations and prototypes between the C and assembly code. Any legal C/C++ can be used in a `.cdecls` block and the C/C++ declarations cause suitable assembly to be generated automatically, allowing you to reference the C/C++ constructs in assembly code; such as calling functions, allocating space, and accessing structure members; using the equivalent assembly mechanisms. While function and variable definitions are ignored, most common C/C++ elements are converted to assembly, for instance: enumerations, (non-function-like) macros, function and variable prototypes, structures, and unions.

The `.cdecls` options control whether the code is treated as C or C++ code; and how the `.cdecls` block and converted code are presented. Options must be separated by commas; they can appear in any order:

- **C**: Treat the code in the `.cdecls` block as C source code (default).
- **CPP**: Treat the code in the `.cdecls` block as C++ source code. This is the opposite of the C option.
- **NOLIST**: Do not include the converted assembly code in any listing file generated for the containing assembly file (default).
- **LIST**: Include the converted assembly code in any listing file generated for the containing assembly file. This is the opposite of the NOLIST option.
- **NOWARN**: Do not emit warnings on STDERR about C/C++ constructs that cannot be converted while parsing the `.cdecls` source block (default).
- **WARN**: Generate warnings on STDERR about C/C++ constructs that cannot be converted while parsing the `.cdecls` source block. This is the opposite of the NOWARN option.

In the single-line format, the options are followed by one or more filenames to include. The filenames and options are separated by commas. Each file listed acts as if `#include "filename"` was specified in the multiple-line format.

In the multiple-line format, the line following `.cdecls` must contain the opening `.cdecls` block indicator `%{. Everything after the `%{, up to the closing block indicator `}%`, is treated as C/C++ source and processed. Ordinary assembler processing then resumes on the line following the closing `}%`.

The text within `%{ and `}%` is passed to the C/C++ compiler to be converted into assembly language. Much of C language syntax, including function and variable definitions as well as function-like macros, is not supported and is ignored during the conversion. However, all of what traditionally appears in C header files is supported, including function and variable prototypes; structure and union declarations; non-function-like macros; enumerations; and `#defines.`
The resulting assembly language is included in the assembly file at the point of the .cdecls directive. If the LIST option is used, the converted assembly statements are printed in the listing file.

The assembly resulting from the .cdecls directive is treated similarly to a .include file. Therefore the .cdecls directive can be nested within a file being copied or included. The assembler limits nesting to ten levels; the host operating system may set additional restrictions. The assembler precedes the line numbers of copied files with a letter code to identify the level of copying. An A indicates the first copied file, B indicates a second copied file, etc.

The .cdecls directive can appear anywhere in an assembly source file, and can occur multiple times within a file. However, the C/C++ environment created by one .cdecls is not inherited by a later .cdecls; the C/C++ environment starts new for each .cdecls.

See Chapter 11 for more information on setting up and using the .cdecls directive with C header files.

Example

In this example, the .cdecls directive is used call the C header.h file.

C header file:
#define WANT_ID 10
#define NAME "John\n"
extern int a_variable;
extern float cvt_integer(int src);

struct myCstruct { int member_a; float member_b; };

enum status_enum { OK = 1, FAILED = 256, RUNNING = 0 };

Source file:
.cdecls C,LIST,"myheader.h"

.size: .int $sizeof(myCstruct)
.aoffset: .int myCstruct.member_a
.boffset: .int myCstruct.member_b
.okvalue: .int status_enum.OK
.failval: .int status_enum.FAILED
.if $defined(WANT_ID)
.id .cstring NAME
.endif
Listing File:

```asm
.cdecls C,LIST,"myheader.h"

; Assembly Generated from C/C++ Source Code

; =========== MACRO DEFINITIONS ===========
.define "10",WANT_ID
.define ""John\n\n",NAME

; =========== TYPE DEFINITIONS ===========
status_enum .enum
  00000001 OK .emember 1
  00000100 FAILED .emember 256
  00000000 RUNNING .emember 0
.endenum

myCstruct .struct 0,4
  ; struct size=(8 bytes|64 bits), alignment=4
  00000000 member_a .field 32
    ; int member_a - offset 0 bytes, size (4 bytes|32 bits)
  00000004 member_b .field 32
    ; float member_b - offset 4 bytes, size (4 bytes|32 bits)
.endstruct

; =========== EXTERNAL FUNCTIONS ===========
.globa __cvt_integer

; =========== EXTERNAL VARIABLES ===========
.globa __a_variable
  00000000 00000008 size: .int $sizeof(myCstruct)
  00000004 00000000 aoffset: .int myCstruct.member_a
  00000008 00000004 boffset: .int myCstruct.member_b
  0000000c 00000001 okvalue: .int status_enum.OK
  00000010 00000100 failval: .int status_enum.FAILED
  00000014 0000000A id .cstring NAME
    00000015 0000006F
    00000016 00000068
    00000017 0000006E
    00000018 0000000A
    00000019 00000000
.endif
```

---

**Directives Reference**

www.ti.com

---

**Assembler Directives**

SPRUI03A—January 2016

Submit Documentation Feedback

Copyright © 2016, Texas Instruments Incorporated
.common

Create a Common Symbol

Syntax

```
.common symbol, size in bytes[, alignment]
.common symbol, structure tag[, alignment]
```

Description

The `.common` directive creates a common symbol in a common block, rather than placing the variable in a memory section.

This directive is used by the compiler when the `--common` option is enabled (the default), which causes uninitialized file scope variables to be emitted as common symbols. The benefit of common symbols is that generated code can remove unused variables that would otherwise increase the size of the .bss section. (Uninitialized variables of a size larger than 32 bytes are separately optimized through placement in separate subsections that can be omitted from a link.) This optimization happens for C/C++ code by default unless you use the `--common=off` compiler option.

- The `symbol` is a required parameter. It defines a name for the symbol created by this directive. The symbol name must correspond to the variable that you are reserving space for.
- The `size in bytes` is a required parameter; it must be an absolute expression. The assembler allocates size bytes in the section used for common symbols. There is no default size.
- A `structure tag` can be used in place of a size to specify a structure created with the `.struct` directive. Either a size or a structure tag is required for this argument.
- The `alignment` is an optional parameter that ensures that the space allocated to the symbol occurs on the specified boundary. The boundary must be set to a power of 2 between $2^0$ and $2^{15}$, inclusive. If the SPC is already aligned at the specified boundary, it is not incremented.

Common symbols are symbols that are placed in the symbol table of an ELF object file. They represent an uninitialized variable. Common symbols do not reference a section. (In contrast, initialized variables need to reference a section that contains the initialized data.) The value of a common symbol is its required alignment; it has no address and stores no address. While symbols for an uninitialized common block can appear in executable object files, common symbols may only appear in relocatable object files. Common symbols are preferred over weak symbols. See the section on the "Symbol Table" in the System V ABI specification for more about common symbols.

When object files containing common symbols are linked, space is reserved in an uninitialized section for each common symbol. A symbol is created in place of the common symbol to refer to its reserved location.
.copy/.include

Syntax

.copy "filename"
.include "filename"

Description

The .copy and .include directives tell the assembler to read source statements from a different file. The statements that are assembled from a copy file are printed in the assembly listing. The statements that are assembled from an included file are not printed in the assembly listing, regardless of the number of .list/.nolist directives assembled.

When a .copy or .include directive is assembled, the assembler:
1. Stops assembling statements in the current source file
2. Assembles the statements in the copied/included file
3. Resumes assembling statements in the main source file, starting with the statement that follows the .copy or .include directive

The filename is a required parameter that names a source file. It is enclosed in double quotes and must follow operating system conventions.

You can specify a full pathname (for example, /320tools/file1.asm). If you do not specify a full pathname, the assembler searches for the file in:
1. The directory that contains the current source file
2. Any directories named with the --include_path assembler option
3. Any directories specified by the C6X_A_DIR environment variable
4. Any directories specified by the C6X_C_DIR environment variable

For more information about the --include_path option and C6X_A_DIR, see Section 4.5. For more information about C6X_C_DIR, see the TMS320C6000 Optimizing Compiler User's Guide.

The .copy and .include directives can be nested within a file being copied or included. The assembler limits nesting to 32 levels; the host operating system may set additional restrictions. The assembler precedes the line numbers of copied files with a letter code to identify the level of copying. A indicates the first copied file, B indicates a second copied file, etc.

Example 1

In this example, the .copy directive is used to read and assemble source statements from other files; then, the assembler resumes assembling into the current file.

The original file, copy.asm, contains a .copy statement copying the file byte.asm. When copy.asm assembles, the assembler copies byte.asm into its place in the listing (note listing below). The copy file byte.asm contains a .copy statement for a second file, word.asm.

When it encounters the .copy statement for word.asm, the assembler switches to word.asm to continue copying and assembling. After completing assembly of byte.asm, the assembler returns to copy.asm to assemble its remaining statement.
Listing file:

1 00000000 .space 29
2 .copy "byte.asm"
A 1 ** In byte.asm
A 2 00000001d 00000020 .byte 32,1+ 'A'
0000001e 00000042
A 3 .copy "word.asm"
B 1 ** In word.asm
B 2 00000020 0000ABCD .word 0ABCDh, 56q
00000024 0000002E
A 4 ** Back in byte.asm
A 5 00000028 0000006A .byte 67h + 3q
3 4 ** Back in original file
5 00000029 00000064 .string "done"
0000002a 0000006F
0000002b 0000006E
0000002c 00000065

Example 2

In this example, the .include directive is used to read and assemble source statements from other files; then, the assembler resumes assembling into the current file. The mechanism is similar to the .copy directive, except that statements are not printed in the listing file.

<table>
<thead>
<tr>
<th>include.asm</th>
<th>byte2.asm</th>
<th>word2.asm</th>
</tr>
</thead>
<tbody>
<tr>
<td>(source file)</td>
<td>(first copy file)</td>
<td>(second copy file)</td>
</tr>
<tr>
<td>.space 29</td>
<td>** In byte2.asm</td>
<td>** In word2.asm</td>
</tr>
<tr>
<td>.include &quot;byte2.asm&quot;</td>
<td>.byte 32,1+ 'A'</td>
<td>.word 0ABCDh, 56q</td>
</tr>
<tr>
<td>** Back in original file</td>
<td>.include &quot;word2.asm&quot;</td>
<td>** Back in byte2.asm</td>
</tr>
<tr>
<td>.string &quot;done&quot;</td>
<td>&quot;word2.asm&quot;</td>
<td>.byte 67h + 3q</td>
</tr>
</tbody>
</table>

Listing file:

1 00000000 .space 29
2 .include "byte.asm"
3
4 ** Back in original file
5 00000029 00000064 .string "done"
0000002a 0000006F
0000002b 0000006E
0000002c 00000065
Declare C Structure Type

Syntax

\[
\begin{align*}
&[stag]\ .cstruct\ |\ .cunion & [expr] \\
&[mem_0] \element \ [expr_0] \\
&[mem_1] \element \ [expr_1] \\
&\ldots \ldots \ldots \\
&[mem_n] \tag \ stag \ [expr_n] \\
&[mem_N] \element \ [expr_N] \\
&[size] \ .endstruct\ |\ .endunion \\
&label \ .tag \ stag
\end{align*}
\]

Description

The `.cstruct` and `.cunion` directives have been added to support ease of sharing of common data structures between assembly and C code. The `.cstruct` and `.cunion` directives can be used exactly like the existing `.struct` and `.union` directives except that they are guaranteed to perform data layout matching the layout used by the C compiler for C struct and union data types.

In particular, the `.cstruct` and `.cunion` directives force the same alignment and padding as used by the C compiler when such types are nested within compound data structures.

The `.endstruct` directive terminates the structure definition. The `.endunion` directive terminates the union definition.

The `.tag` directive gives structure characteristics to a `label`, simplifying the symbolic representation and providing the ability to define structures that contain other structures. The `.tag` directive does not allocate memory. The structure tag (`stag`) of a `.tag` directive must have been previously defined.

Following are descriptions of the parameters used with the `.struct`, `.endstruct`, and `.tag` directives:

- The `stag` is the structure's tag. Its value is associated with the beginning of the structure. If no stag is present, the assembler puts the structure members in the global symbol table with the value of their absolute offset from the top of the structure. The stag is optional for `.struct`, but is required for `.tag`.
- The `element` is one of the following descriptors: `.byte`, `.char`, `.int`, `.long`, `.word`, `.double`, `.half`, `.short`, `.string`, `.float`, and `.field`. All of these except `.tag` are typical directives that initialize memory. Following a `.struct` directive, these directives describe the structure element's size. They do not allocate memory. A `.tag` directive is a special case because stag must be used (as in the definition of stag).
- The `expr` is an optional expression indicating the beginning offset of the structure. The default starting point for a structure is 0.
- The `expr_{n/N}` is an optional expression for the number of elements described. This value defaults to 1. A `.string` element is considered to be one byte in size, and a `.field` element is one bit.
- The `mem_{n/N}` is an optional label for a member of the structure. This label is absolute and equates to the present offset from the beginning of the structure. A label for a structure member cannot be declared global.
- The `size` is an optional label for the total size of the structure.

Example

This example illustrates a structure in C that will be accessed in assembly code.
typedef struct STRUCT1
    {  int i0; /* offset 0 */
    short s0; /* offset 4 */
    } struct1; /* size 8, alignment 4 */
;
typedef struct STRUCT2
    {  struct1 st1; /* offset 0 */
    short s1; /* offset 8 */
    } struct2; /* size 12, alignment 4 */
;
The structure will get the following offsets once the C compiler lays out the structure elements according to the C standard rules:
;
offsetof(struct1, i0) = 0
offsetof(struct1, s0) = 4
sizeof(struct1) = 8
offsetof(struct2, s1) = 0
offsetof(struct2, i1) = 8
sizeof(struct2) = 12
;
Attempts to replicate this structure in assembly using the .struct/.union directives will not create the correct offsets because the assembler tries to use the most compact arrangement:

struct1 .struct
i0 .int ; bytes 0-3
s0 .short ; bytes 4-5
struct1len .endstruct ; size 6, alignment 4

struct2 .struct
st1 .tag struct1 ; bytes 0-5
s1 .short ; bytes 6-7
endstruct2 .endstruct ; size 8, alignment 4

.sect "data1"
 .word struct1.i0 ; 0
 .word struct1.s0 ; 4
 .word struct1len ; 6

.sect "data2"
 .word struct2.st1 ; 0
 .word struct2.s1 ; 6
 .word endstruct2 ; 8
;
The .cstruct/.cunion directives calculate offsets in the same manner as the C compiler. The resulting assembly structure can be used to access the elements of the C structure. Compare the difference in the offsets of those structures defined via .struct above and the offsets for the C code.

cstruct1 .cstruct
i0 .int ; bytes 0-3
s0 .short ; bytes 4-5
cstruct1len .endstruct ; size 8, alignment 4

cstruct2 .cstruct
st1 .tag cstruct1 ; bytes 0-7
s1 .short ; bytes 8-9
cendstruct2 .endstruct ; size 12, alignment 4

.sect "data3"
 .word cstruct1.i0, struct1.i0 ; 0
 .word cstruct1.s0, struct1.s0 ; 4
 .word cstruct1len, struct1len ; 8

.sect "data4"
 .word cstruct2.st1, struct2.st1 ; 0
 .word cstruct2.s1, struct2.s1 ; 8
 .word cendstruct2, endstruct2 ; 12
.data

Assemble Into the .data Section

Syntax
=data

Description
The .data directive sets .data as the current section; the lines that follow will be assembled into the .data section. The .data section is normally used to contain tables of data or preinitialized variables.

For more information about sections, see Chapter 2.

Example

In this example, code is assembled into the .data and .text sections.

```
1 ***********************************************
2 ** Reserve space in .data **
3 ***********************************************
4 00000000 .data
5 00000000 .space 0CCh
6 
7 ***********************************************
8 ** Assemble into .text **
9 ***********************************************
10 00000000 .text
11 00000000 00800358 ABS A0,A1
12 
13 ***********************************************
14 ** Assemble into .data **
15 ***********************************************
16 00000000 .data
17 00000000 FFFFFFFF .word -1
18 00000000 000000FF .byte 0FFh
19 
20 ***********************************************
21 ** Assemble into .text **
22 ***********************************************
23 00000000 .text
24 00000004 008001A0 MV A0,A1
25 
26 ***********************************************
27 ** Resume assembling into the .data section **
28 ***********************************************
29 00000000 .data
30 00000000 00000000 coeff .word 00h,0ah,0bh
31 00000000 0000000A
32 00000000 0000000B
```
.double Initialize Double-Precision Floating-Point Value

Syntax .double value[, ..., value,]

Description The .double directive places the IEEE double-precision floating-point representation of one or more floating-point values into the current section. Each value must be an absolute constant expression with an arithmetic type or a symbol equated to an absolute constant expression with an arithmetic type. Each constant is converted to a floating-point value in IEEE double-precision 64-bit format. Double-precision floating point constants are aligned to a double word boundary.

The 64-bit value is stored in the format shown in Figure 5-5.

Figure 5-5. Double-Precision Floating-Point Format

| S | E | E | E | E | E | E | E | E | E | E | M | M | M | M | M | M | M | M | M | M | M | M | M | M |
| 31 | 20 | 0 |

Legend:  
S = sign  
E = exponent (11-bit biased)  
M = mantissa (52-bit fraction)

When you use .double in a .struct/.endstruct sequence, .double defines a member's size; it does not initialize memory. For more information, see the .struct/.endstruct/.tag topic.

Example This example shows the .double directive.

```
1 00000000 2C280291 .double -2.0e25
00000004 C5308B2A
2 00000000 00000000 .double 6
00000000 40180000
3 00000000 00000000 .double 456
00000014 407C8000
```
Control Listing of Directives

Syntax

- .dlist
- .drnolist

Description

Two directives enable you to control the printing of assembler directives to the listing file:

The .dlist directive enables the printing of all directives to the listing file.

The .drnolist directive suppresses the printing of the following directives to the listing file. The .drnolist directive has no affect within macros.

- .asg
- .break
- .eval
- .fclist
- .ssnolist
- .fclist
- .sslist
- .asg
- .break
- .eval
- .fclist
- .ssnolist
- .fclist
- .sslist

By default, the assembler acts as if the .dlist directive had been specified.

Example

This example shows how .drnolist inhibits the listing of the specified directives.

Source file:

```
.length 65
.width 85
.asg 0, x
.loop 2
.eval x+1, x
.endloop

.drnolist
.length 55
.width 95
.asg 1, x
.loop 3
.eval x+1, x
.endloop
```

Listing file:

```
3   .asg 0, x
4   .loop 2
5   .eval x+1, x
6   .endloop
1   .eval 0+1, x
1   .eval 1+1, x
7   .drnolist
8   .loop 3
12  .loop 3
13  .eval x+1, x
14  .endloop
```
**.elfsym**

**ELF Symbol Information**

**Syntax**

```
.elfsym name, SYM_SIZE(size)
```

**Description**

The `.elfsym` directive provides additional information for symbols in the ELF format. This directive is designed to convey different types of information, so the `type, data` pair is used to represent each type. Currently, this directive only supports the SYM_SIZE type.

SYM_SIZE indicates the allocation size (in bytes) of the symbol indicated by `name`.

**Example**

This example shows the use of the ELF symbol information directive.

```
.sect ".examp"
.alignment 4
.elfsym ex_sym, SYM_SIZE(4)
ex_sym: .word 0
```
.emsg/.mmsg/.wmsg  Define Messages

Syntax

.emsg  string  
.mmsg  string  
.wmsg  string

Description

These directives allow you to define your own error and warning messages. When you use these directives, the assembler tracks the number of errors and warnings it encounters and prints these numbers on the last line of the listing file.

The .emsg directive sends an error message to the standard output device in the same manner as the assembler. It increments the error count and prevents the assembler from producing an object file.

The .mmsg directive sends an assembly-time message to the standard output device in the same manner as the .emsg and .wmsg directives. It does not, however, set the error or warning counts, and it does not prevent the assembler from producing an object file.

The .wmsg directive sends a warning message to the standard output device in the same manner as the .emsg directive. It increments the warning count rather than the error count, however. It does not prevent the assembler from producing an object file.

Example

This example sends the message ERROR -- MISSING PARAMETER to the standard output device.

Source file:

.global PARAM
MSG_EX .macro parm1
  .if $symlen(parm1) = 0
    .emsg "ERROR -- MISSING PARAMETER"
  .else
    MVK parm1, A1
  .endif
.endm
MSG_EX PARAM

Listing file:

1   .global PARAM
2   MSG_EX .macro parm1
3     .if $symlen(parm1) = 0
4     .emsg "ERROR -- MISSING PARAMETER"
5     .else
6       MVK parm1, A1
7     .endif
8     .endm
9
10  00000000 MSG_EX PARAM
1  .if $symlen(parm1) = 0
1  .emsg "ERROR -- MISSING PARAMETER"
1  .else
1  00000000 00800028! MVK PARAM, A1
1  .endif
11  MSG_EX
12  00000004   .if $symlen(parm1) = 0
1  .emsg "ERROR -- MISSING PARAMETER"
1  **** USER ERROR ***** - : ERROR -- MISSING PARAMETER
1  .else
1  MVK parm1, A1
1  .endif
1 Error, No Warnings

In addition, the following messages are sent to standard output by the assembler:

```
"t.asm", ERROR! at line 10: [ ***** USER ERROR ***** - ] ERROR --
MISSING PARAMETER
.emsg "ERROR -- MISSING PARAMETER"
```

1 Assembly Error, No Assembly Warnings
Errors in Source - Assembler Aborted
**.end**

**End Assembly**

**Syntax**

The `.end` directive is optional and terminates assembly. The assembler ignores any source statements that follow a `.end` directive. If you use the `.end` directive, it must be the last source statement of a program.

This directive has the same effect as an end-of-file character. You can use `.end` when you are debugging and you want to stop assembling at a specific point in your code.

**Description**

**Ending a Macro**

**NOTE:** Do not use the `.end` directive to terminate a macro; use the `.endm` macro directive instead.

**Example**

This example shows how the `.end` directive terminates assembly. Any source statements that follow the `.end` directive are ignored by the assembler.

**Source file:**

```
start: .text
ZERO A0
ZERO A1
ZERO A3
.end
ZERO A4
```

**Listing file:**

```
1 00000000  start: .text
2 00000000 000005E0  ZERO A0
3 00000004 008425E0  ZERO A1
4 00000008 018C65E0  ZERO A3
5 .end
```
### .farcommon/.nearcommon

**Create a Common Symbol**

**Syntax**

```
.farcommon symbol, size in bytes[, alignment]
.nearcommon symbol, structure tag[, alignment]
```

**Description**

The `.farcommon` and `.nearcommon` directives create a common symbol in a common block, rather than placing variables in a section. The `.farcommon` directive places the symbol in far memory, and the `.nearcommon` directive places the symbol in near memory.

A common symbol cannot be created for a symbol that has a memory bank specification, for example because the `DATA_MEM_BANK` pragma was used to align the variable.

These directives are used by the compiler when the `--common` option is enabled (the default), which causes uninitialized file scope variables to be emitted as common symbols. The benefit of common symbols is that generated code can remove unused variables that would otherwise increase the size of the `.bss` section. (Uninitialized variables of a size larger than 32 bytes are separately optimized through placement in separate subsections that can be omitted from a link.) This optimization happens for C/C++ code by default unless you use the `--common=off` compiler option.

- The `symbol` is a required parameter. It defines a name for the symbol created by this directive. The symbol name must correspond to the variable that you are reserving space for.
- The `size in bytes` is a required parameter; it must be an absolute expression. The assembler allocates size bytes in the section used for common symbols. There is no default size.
- A `structure tag` can be used in place of a size to specify a structure created with the `.struct` directive. Either a size or a structure tag is required for this argument.
- The `alignment` is an optional parameter that ensures that the space allocated to the symbol occurs on the specified boundary. This boundary must be set to a power of 2. If the SPC is already aligned to the specified boundary, it is not incremented.
### .fclist/.fcnolist

**Control Listing of False Conditional Blocks**

#### Syntax

<table>
<thead>
<tr>
<th>Syntax</th>
</tr>
</thead>
<tbody>
<tr>
<td>.fclist</td>
</tr>
<tr>
<td>.fcnolist</td>
</tr>
</tbody>
</table>

#### Description

Two directives enable you to control the listing of false conditional blocks:

- The `.fclist` directive allows the listing of false conditional blocks (conditional blocks that do not produce code).
- The `.fcnolist` directive suppresses the listing of false conditional blocks until a `.fclist` directive is encountered. With `.fcnolist`, only code in conditional blocks that are actually assembled appears in the listing. The `.if`, `.elseif`, `.else`, and `.endif` directives do not appear.

By default, all conditional blocks are listed; the assembler acts as if the `.fclist` directive had been used.

#### Example

This example shows the assembly language and listing files for code with and without the conditional blocks listed.

**Source file:**

```
 a .set 0
 b .set 1
 .fclist ; list false conditional blocks
 .if a
 MVK 5,A0
 .else
 MVK 0,A0
 .endif
 .fcnolist ; do not list false conditional blocks
 .if a
 MVK 5,A0
 .else
 MVK 0,A0
 .endif
```

**Listing file:**

```
 1 00000000 a .set 0
 2 00000001 b .set 1
 3 .fclist ; list false conditional blocks
 4 .if a
 5 MVK 5,A0
 6 .else
 7 00000000 00000028 MVK 0,A0
 8 .endif
 9 .fcnolist ; do not list false conditional blocks
 13 00000004 00000028 MVK 0,A0
```
.field

**Initialize Field**

<table>
<thead>
<tr>
<th>Syntax</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>.field value[, size in bits]</td>
<td>The .field directive initializes a multiple-bit field within a single word (32 bits) of memory. This directive has two operands:</td>
</tr>
<tr>
<td>• The value is a required parameter; it is an expression that is evaluated and placed in the field. The value must be absolute.</td>
<td></td>
</tr>
<tr>
<td>• The size in bits is an optional parameter; it specifies a number from 1 to 32, which is the number of bits in the field. The default size is 32 bits. If you specify a value that cannot fit in size in bits, the assembler truncates the value and issues a warning message. For example, .field 3, 1 causes the assembler to truncate the value 3 to 1; the assembler also prints the message:</td>
<td></td>
</tr>
</tbody>
</table>

"t.asm", WARNING! at line 1: [W0001] Value truncated to 1
.field 3, 1 |
| Successive .field directives pack values into the specified number of bits starting at the current 32-bit location. Fields are packed starting at the least significant bit (bit 0), moving toward the most significant bit (bit 31) as more fields are added. If the assembler encounters a field size that does not fit in the current 32-bit word, it fills the remaining bits of the current byte with 0s, increments the SPC to the next word boundary, and begins packing fields into the next word. |
| The .field directive is similar to the .bits directive (see the .bits topic). However, the .bits directive does not allow you to specify the number of bits in the field and does not automatically increment the SPC when a word boundary is reached. |
| Use the .align directive to force the next .field directive to begin packing a new word. |
| If you use a label, it points to the byte that contains the specified field. |
| When you use .field in a .struct/.endstruct sequence, .field defines a member's size; it does not initialize memory. For more information, see the .struct/.endstruct/.tag topic. |

**Example**

This example shows how fields are packed into a word. The SPC does not change until a word is filled and the next word is begun.

```
1 ************************************
2 ** Initialize a 24-bit field. **
3 ************************************
4 00000000 00BBCCDD .field 0BBCCDDh, 24
5   ************************************
6 ** Initialize a 5-bit field **
7   ************************************
8 00000000 0ABBCCDD .field 0Ah, 5
9   ************************************
10 ** Initialize a 4-bit field **
11 ** in a new word. **
12   ************************************
13 00000004 0000000C .field 0Ch, 4
14   ************************************
15 ** Initialize a 3-bit field **
16   ************************************
17 00000004 0000001C x: .field 01h, 3
18   ************************************
19 ** Initialize a 32-bit field **
20 ** relocatable field in the **
21 ** next word **
22   ************************************
23 00000008 00000004 .field x
```
Figure 5-6 shows how the directives in this example affect memory.

### Figure 5-6. The .field Directive

<table>
<thead>
<tr>
<th>Word</th>
<th>Contents</th>
<th>Code</th>
</tr>
</thead>
</table>
| (a) 0 | \[\begin{array}{c}
3130292827265242322120191817161514131211109
101110111100110011011101
\end{array}\] | .field 0BCCD, 24 |
| (b) 0 | \[\begin{array}{c}
3130292827265242322120191817161514131211109
010110111100110011011101
\end{array}\] | .field 0Ah, 5 |
| (c) 0 | \[\begin{array}{c}
3130292827265242322120191817161514131211109
00010110111100110011011101
\end{array}\] | .field 0Ch, 4 |
| (d) 1 | \[\begin{array}{c}
3130292827265242322120191817161514131211109
1100
\end{array}\] | .field 01h, 3 |
| (e) 1 | \[\begin{array}{c}
3130292827265242322120191817161514131211109
00000000000000000000000000000000000011100
\end{array}\] | .field x |
| 2 | \[\begin{array}{c}
3130292827265242322120191817161514131211109
00000000000000000000000000000000000100
\end{array}\] |
.float

*Initialize Single-Precision Floating-Point Value*

**Syntax**

```
.float value[, ... , value]
```

**Description**

The `.float` directive places the IEEE single-precision floating-point representation of a single floating-point constant into a word in the current section. The `value` must be an absolute constant expression with an arithmetic type or a symbol equated to an absolute constant expression with an arithmetic type. Each constant is converted to a floating-point value in IEEE single-precision 32-bit format.

With big-endian ordering, the 32-bit value is stored exponent byte first, most significant byte of fraction second, and least significant byte of fraction third, in the format shown in Figure 5-7.

**Figure 5-7. Single-Precision Floating-Point Format**

```
  S | E E E E E E E | M M M M M M M M M M M M M M M M M M M 0
  31 23
```

value = \((-1)^S \times (1.0 + \text{mantissa}) \times (2)^{\text{exponent} - 127}\)

**Legend:**

- S = sign (1 bit)
- E = exponent (8-bit biased)
- M = mantissa (23-bit fraction)

When you use `.float` in a `.struct/.endstruct` sequence, `.float` defines a member’s size; it does not initialize memory. For more information, see the `.struct/.endstruct/.tag` topic.

**Example**

Following are examples of the `.float` directive:

```
1 00000000 E9045951 .float -1.0e25
2 00000004 40400000 .float 3
3 00000008 42F60000 .float 123
```
Directives Reference

Identification of Global Symbols

Syntax

- **.global**
  
  Symbolic names [symbol], ..., symbol]
  
- **.def**
  
  Symbolic names [symbol], ..., symbol]
  
- **.ref**
  
  Symbolic names [symbol], ..., symbol]

Description

Three directives identify global symbols that are defined externally or can be referenced externally:

- The **.def** directive identifies a symbol that is defined in the current module and can be accessed by other files. The assembler places this symbol in the symbol table.

- The **.ref** directive identifies a symbol that is used in the current module but is defined in another module. The linker resolves this symbol's definition at link time.

- The **.global** directive acts as a **.ref** or a **.def**, as needed.

A global symbol is defined in the same manner as any other symbol; that is, it appears as a label or is defined by the **.set**, **.equ**, **.bss**, or **.usect** directive. If a global symbol is defined more than once, the linker issues a multiple-definition error. (The assembler can provide a similar multiple-definition error for local symbols.) The **.ref** directive always creates a symbol table entry for a symbol, whether the module uses the symbol or not; **.global**, however, creates an entry only if the module actually uses the symbol.

A symbol can be declared global for either of two reasons:

- If the symbol is not defined in the current module (which includes macro, copy, and include files), the **.global** or **.ref** directive tells the assembler that the symbol is defined in an external module. This prevents the assembler from issuing an unresolved reference error. At link time, the linker looks for the symbol's definition in other modules.

- If the symbol is defined in the current module, the **.global** or **.def** directive declares that the symbol and its definition can be used externally by other modules. These types of references are resolved at link time.

Example

This example shows four files. The file1.lst and file2.lst refer to each other for all symbols used; file3.lst and file4.lst are similarly related.

The **file1.lst** and **file3.lst** files are equivalent. Both files define the symbol INIT and make it available to other modules; both files use the external symbols X, Y, and Z. Also, file1.lst uses the **.global** directive to identify these global symbols; file3.lst uses **.ref** and **.def** to identify the symbols.

The **file2.lst** and **file4.lst** files are equivalent. Both files define the symbols X, Y, and Z and make them available to other modules; both files use the external symbol INIT. Also, file2.lst uses the **.global** directive to identify these global symbols; file4.lst uses **.ref** and **.def** to identify the symbols.

**file1.lst**

1 ; Global symbol defined in this file
2 .global INIT
3 ; Global symbols defined in file2.lst
4 .global X, Y, Z
5 00000000 INIT:
6 00000000 00902058 ADD.L1 0x01,A4,A1
7 0000004 0000000! .word X
8 ;
9 ;
10 ;
11 .end
file2.lst

1 ; Global symbols defined in this file
2 .global X, Y, Z
3 ; Global symbol defined in file1.lst
4 .global INIT
5 00000001 X: .set 1
6 00000002 Y: .set 2
7 00000003 Z: .set 3
8 00000000 00000000! .word INIT
9 ;
10 ;
11 ;
12 .end

file3.lst

1 ; Global symbol defined in this file
2 .def INIT
3 ; Global symbols defined in file4.lst
4 .ref X, Y, Z
5 00000000 INIT:
6 00000000 00902058 ADD.L1 0x01,A4,A1
7 00000004 00000000! .word X
8 ;
9 ;
10 ;
11 .end

file4.lst

1 ; Global symbols defined in this file
2 .def X, Y, Z
3 ; Global symbol defined in file3.lst
4 .ref INIT
5 00000001 X: .set 1
6 00000002 Y: .set 2
7 00000003 Z: .set 3
8 00000000 00000000! .word INIT
9 ;
10 ;
11 ;
12 .end
Define Common Data Section

Syntax

\[ .\text{group} \quad \text{group section name group type} \]
\[ .\text{gmember} \quad \text{section name} \]
\[ .\text{endgroup} \]

Description

Three directives instruct the assembler to make certain sections members of an ELF group section (see the ELF specification for more information on group sections).

The \texttt{.group} directive begins the group declaration. The \textit{group section name} designates the name of the group section. The \textit{group type} designates the type of the group. The following types are supported:

- \texttt{0x0} Regular ELF group
- \texttt{0x1} COMDAT ELF group

Duplicate COMDAT (common data) groups are allowed in multiple modules; the linker keeps only one. Creating such duplicate groups is useful for late instantiation of C++ templates and for providing debugging information.

The \texttt{.gmember} directive designates \textit{section name} as a member of the group.

The \texttt{.endgroup} directive ends the group declaration.
.half/.short/.uhalf/.ushort  Initialize 16-Bit Integers

Syntax

```
.half  value[, ... , value_n ]
.short  value[, ... , value_n ]
.uhalf value[, ... , value_n ]
.ushort value[, ... , value_n ]
```

Description

The .half, .uhalf, .short, and .ushort directives place one or more values into consecutive halfwords in the current section. Each value is placed in a 2-byte memory location by itself. A value can be either:

- An expression that the assembler evaluates and treats as a 16-bit signed or unsigned number
- A character string enclosed in double quotes. Each character in a string represents a separate value and is stored alone in the least significant eight bits of a 16-bit field, which is padded with 0s.

The assembler truncates values greater than 16 bits.

If you use a label with .half, .short, .uhalf, or .ushort; it points to the location where the assembler places the first byte.

These directives perform a halfword (16-bit) alignment before data is written to the section. This guarantees that data resides on a 16-bit boundary.

When you use .half, .short, .uhalf, or .ushort in a .struct/.endstruct sequence, they define a member’s size; they do not initialize memory. For more information, see the .struct/.endstruct/.tag topic.

Example

In this example, .half is used to place 16-bit values (10, -1, abc, and a) into consecutive halfwords in memory; .short is used to place 16-bit values (8, -3, def, and b) into consecutive halfwords in memory. The label STRN has the value 100h, which is the location of the first initialized halfword for .short.

```
1 00000000 .space 100h * 16
2 00000100 0000000A .half 10, -1, "abc", 'a'
00000102 0000FFFF
00000104 00000061
00000106 00000062
00000108 00000063
0000010a 00000061
3 0000010c 00000008 STRN .short 8, -3, "def", 'b'
0000010e 0000FFFF
00000110 00000064
00000112 00000065
00000114 00000066
00000116 00000062
```
Directives Reference

.if/.elseif/.else/.endif  Assemble Conditional Blocks

Syntax

```
.if  condition
  [.elseif  condition]
  [.else]
.endif
```

Description

These directives provide conditional assembly:

The .if directive marks the beginning of a conditional block. The `condition` is a required parameter.

- If the expression evaluates to true (nonzero), the assembler assembles the code that follows the expression (up to a .elseif, .else, or .endif).
- If the expression evaluates to false (0), the assembler assembles code that follows a .elseif (if present), .else (if present), or .endif (if no .elseif or .else is present).

The .elseif directive identifies a block of code to be assembled when the .if expression is false (0) and the .elseif expression is true (nonzero). When the .elseif expression is false, the assembler continues to the next .elseif (if present), .else (if present), or .endif (if no .elseif or .else is present). The .elseif is optional in a conditional block, and more than one .elseif can be used. If an expression is false and there is no .elseif, the assembler continues with the code that follows a .else (if present) or a .endif.

The .else directive identifies a block of code that the assembler assembles when the .if expression and all .elseif expressions are false (0). The .else directive is optional in the conditional block; if an expression is false and there is no .else statement, the assembler continues with the code that follows the .endif. The .elseif and .else directives can be used in the same conditional assembly block.

The .endif directive terminates a conditional block.

See Section 4.9.2 for information about relational operators.

Example

This example shows conditional assembly:

```
1  00000001 SYM1 .set 1
2  00000002 SYM2 .set 2
3  00000003 SYM3 .set 3
4  00000004 SYM4 .set 4
5
6  If_4: .if SYM4 = SYM2 * SYM2
7   00000000 00000004 .byte SYM4 ; Equal values
8   .else
9   .byte SYM2 * SYM2 ; Unequal values
10  .endif
11
12  If_5: .if SYM1 <;= 10
13  00000001 0000000A .byte 10 ; Less than / equal
14  .else
15  .byte SYM1 ; Greater than
16  .endif
17
18  If_6: .if SYM3 * SYM2 != SYM4 + SYM2
19   .byte SYM3 * SYM2 ; Unequal value
20   .else
21   .byte SYM4 + SYM4 ; Equal values
22  .endif
23
24  If_7: .if SYM1 = SYM2
25   .byte SYM1
26   .elseif SYM2 + SYM3 = 5
27  00000003 00000005 .byte SYM2 + SYM3
28```
.import/.export/.hidden/.protected  Set Dynamic Visibility of Global Symbol

Syntax

- .import "symbolname"
- .export "symbolname"
- .hidden "symbolname"
- .protected "symbolname"

Description

These directives set the dynamic visibility of a global symbol. Each takes a single symbol name, optionally enclosed in double-quotes.

- The .import directive sets the visibility of symbolname to STV_IMPORT.
- The .export directive sets the visibility of symbolname to STV_EXPORT.
- The .hidden directive sets the visibility of symbolname to STV_HIDDEN.
- The .protected directive sets the visibility of symbolname to STV_PROTECTED.

See Section 8.12 for an explanation of symbol visibility.

These directives are commonly used in the context of dynamic linking. For more about dynamic linking, see Chapter 14 of The C6000 Embedded Application Binary Interface Application Report (SPRAB89).
.int/.uint/.long/.ulong/.word/.uword  Initialize 32-Bit Integers

Syntax

- `.int value[, ..., value_n]`
- `.uint value[, ..., value_n]`
- `.long value[, ..., value_n]`
- `.ulong value[, ..., value_n]`
- `.word value[, ..., value_n]`
- `.uword value[, ..., value_n]`

Description

The `.int`, `.uint`, `.long`, `.ulong`, `.word`, and `.uword` directives place one or more values into consecutive words in the current section. Each value is placed in a 32-bit word by itself and is aligned on a word boundary. A value can be either:

- An expression that the assembler evaluates and treats as a 32-bit signed or unsigned number
- A character string enclosed in double quotes. Each character in a string represents a separate value and is stored alone in the least significant eight bits of a 32-bit field, which is padded with 0s.

A value can be either an absolute or a relocatable expression. If an expression is relocatable, the assembler generates a relocation entry that refers to the appropriate symbol; the linker can then correctly patch (relocate) the reference. This allows you to initialize memory with pointers to variables or labels.

If you use a label with these directives, it points to the first word that is initialized.

When you use these directives in a `.struct/.endstruct` sequence, they define a member's size; they do not initialize memory. See the `.struct/.endstruct/.tag` topic.

Example 1

This example uses the `.int` directive to initialize words. Notice that the symbol SYMPTR puts the symbol's address in the object code and generates a relocatable reference (indicated by the `-` character appended to the object word).

```
1 00000000 .space 73h
2 00000000 .bss PAGE, 128
3 00000080 .bss SYMPTR, 3
4 00000074 003C12E4 INST: LDW.D2 *++B15[0],A0
5 00000078 0000000A .int 10, SYMPTR, -1, 35 + 'a', INST
```

Example 2

This example initializes two 32-bit fields and defines DAT1 to point to the first location. The contents of the resulting 32-bit fields are FFFABCDh and 141h.

```
1 00000000 FFFFABCD DAT1: .long 0FFFFABCDh,'A'+100h
```

Example 3

This example initializes five words. The symbol WordX points to the first word.

```
1 00000000 0000C80 ;WordX .word 3200,1+'AB','-AF',0F410h,'A'
```
Create a Load-Time Address Label

Syntax

```
.label symbol
```

Description

The `.label` directive defines a special `symbol` that refers to the load-time address rather than the run-time address within the current section. Most sections created by the assembler have relocatable addresses. The assembler assembles each section as if it started at 0, and the linker relocates it to the address at which it loads and runs.

For some applications, it is desirable to have a section load at one address and run at a different address. For example, you may want to load a block of performance-critical code into slower memory to save space and then move the code to high-speed memory to run it. Such a section is assigned two addresses at link time: a load address and a run address. All labels defined in the section are relocated to refer to the run-time address so that references to the section (such as branches) are correct when the code runs. See Section 3.5 for more information about run-time relocation.

The `.label` directive creates a special label that refers to the load-time address. This function is useful primarily to designate where the section was loaded for purposes of the code that relocates the section.

Example

This example shows the use of a load-time address label.

```
sect ".examp"
 .label examp_load ; load address of section
 start: ; run address of section
 <code>
 finish: ; run address of section end
 .label examp_end ; load address of section end
```

See Section 8.5.6 for more information about assigning run-time and load-time addresses in the linker.
.length/.width

Set Listing Page Size

Syntax

- `.length [page length]`
- `.width [page width]`

Description

Two directives allow you to control the size of the output listing file. The `.length` directive sets the page length of the output listing file. It affects the current and following pages. You can reset the page length with another `.length` directive.

- Default length: 60 lines. If you do not use the `.length` directive or if you use the `.length` directive without specifying the `page length`, the output listing length defaults to 60 lines.
- Minimum length: 1 line
- Maximum length: 32,767 lines

The `.width` directive sets the page width of the output listing file. It affects the next line assembled and the lines following. You can reset the page width with another `.width` directive.

- Default width: 132 characters. If you do not use the `.width` directive or if you use the `.width` directive without specifying a `page width`, the output listing width defaults to 132 characters.
- Minimum width: 80 characters
- Maximum width: 200 characters

The width refers to a full line in a listing file; the line counter value, SPC value, and object code are counted as part of the width of a line. Comments and other portions of a source statement that extend beyond the page width are truncated in the listing.

The assembler does not list the `.width` and `.length` directives.

Example

The following example shows how to change the page length and width.

```
********************************************
** Page length = 65 lines **
** Page width = 85 characters **
********************************************
.length 65
.width 85

********************************************
** Page length = 55 lines **
** Page width = 100 characters **
********************************************
.length 55
.width 100
```
.list/.nolist  

**Start/Stop Source Listing**

**Syntax**

```
.list

.nolist
```

**Description**

Two directives enable you to control the printing of the source listing:

The **.list** directive allows the printing of the source listing.

The **.nolist** directive suppresses the source listing output until a **.list** directive is encountered. The **.nolist** directive can be used to reduce assembly time and the source listing size. It can be used in macro definitions to suppress the listing of the macro expansion.

The assembler does not print the **.list** or **.nolist** directives or the source statements that appear after a **.nolist** directive. However, it continues to increment the line counter. You can nest the **.list/.nolist** directives; each **.nolist** needs a matching **.list** to restore the listing.

By default, the source listing is printed to the listing file; the assembler acts as if the **.list** directive had been used. However, if you do not request a listing file when you invoke the assembler by including the --asm_listing option on the command line (see Section 4.3), the assembler ignores the **.list** directive.

**Example**

This example shows how the **.list** and **.nolist** directives turn the output listing on and off. The **.nolist**, the table: **.data** through **.byte** lines, and the **.list** directives do not appear in the listing file. Also, the line counter is incremented even when source statements are not listed.

**Source file:**

```
.data
.space 0CCh
.text
  ABS  A0,A1

.nolist

table: .data
  .word -1
  .byte 0FFh

.list

.text
  MV  A0,A1

.data
  coeff .word 00h,0ah,0bh
```

**Listing file:**

<table>
<thead>
<tr>
<th>Line</th>
<th>Source Code</th>
<th>Line counter</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>00000000 .data</td>
<td>00000000</td>
</tr>
<tr>
<td>2</td>
<td>00000000 .space 0CCh</td>
<td>0000000000</td>
</tr>
<tr>
<td>3</td>
<td>00000000 .text</td>
<td>00800358</td>
</tr>
<tr>
<td>4</td>
<td>00000000 00800358 ABS A0,A1</td>
<td>0000000000</td>
</tr>
<tr>
<td>5</td>
<td></td>
<td>00000000</td>
</tr>
<tr>
<td>13</td>
<td></td>
<td>0000000004</td>
</tr>
<tr>
<td>14</td>
<td></td>
<td>00000004</td>
</tr>
<tr>
<td>15</td>
<td></td>
<td>00801A0</td>
</tr>
<tr>
<td>16</td>
<td></td>
<td>000000d1</td>
</tr>
<tr>
<td>17</td>
<td></td>
<td>000000d4</td>
</tr>
<tr>
<td></td>
<td>coeff .word 00h,0ah,0bh</td>
<td>0000000000</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0000000A</td>
</tr>
<tr>
<td></td>
<td></td>
<td>000000dc</td>
</tr>
</tbody>
</table>

Copyright © 2016, Texas Instruments Incorporated
.loop/.endloop/.break  Assemble Code Block Repeatedly

Syntax

```
.loop [count]
.break [end-condition]
.endloop
```

Description

Three directives allow you to repeatedly assemble a block of code:

The `.loop` directive begins a repeatable block of code. The optional `count` operand, if used, must be a well-defined integer expression. The `count` indicates the number of loops to be performed (the loop count). If `count` is omitted, it defaults to 1024. The loop will be repeated count number of times, unless terminated early by a `.break` directive.

The optional `.break` directive terminates a `.loop` early. You may use `.loop` without using `.break`. The `.break` directive terminates a `.loop` only if the `end-condition` expression is true (evaluates to nonzero). If the optional `end-condition` operand is omitted, it defaults to true. If `end-condition` is true, the assembler stops repeating the `.loop` body immediately; any remaining statements after `.break` and before `.endloop` are not assembled. The assembler resumes assembling with the statement after the `.endloop` directive. If `end-condition` is false (evaluates to 0), the loop continues.

The `.endloop` directive marks the end of a repeatable block of code. When the loop terminates, whether by a `.break` directive with a true `end-condition` or by performing the loop count number of iterations, the assembler stops repeating the loop body and resumes assembling with the statement after the `.endloop` directive.

Example

This example illustrates how these directives can be used with the `.eval` directive. The code in the first six lines expands to the code immediately following those six lines.

```
1 .eval 0, x
2 COEF .loop
3 .word x*100
4 .eval x+1, x
5 .break x = 6
6 .endloop
```

```
1 00000000 00000000 .word 0*100
1 .eval 0+1, x
1 .break 1 = 6
1 00000004 00000064 .word 1*100
1 .eval 1+1, x
1 .break 2 = 6
1 00000008 000000C8 .word 2*100
1 .eval 2+1, x
1 .break 3 = 6
1 0000000c 0000012c .word 3*100
1 .eval 3+1, x
1 .break 4 = 6
1 00000010 00000190 .word 4*100
1 .eval 4+1, x
1 .break 5 = 6
1 00000014 000001f4 .word 5*100
1 .eval 5+1, x
1 .break 6 = 6
```
.macro/.endm  Define Macro

Syntax

\[
\text{macname} \ .\text{macro} [\text{parameter}_1, \ldots, \text{parameter}_n]\]

\[
\text{model statements or macro directives}
\]

.\text{endm}

Description

The .\text{macro} and .\text{endm} directives are used to define macros.

You can define a macro anywhere in your program, but you must define the macro before you can use it. Macros can be defined at the beginning of a source file, in an .\text{include/.copy} file, or in a macro library.

\text{macname}  names the macro. You must place the name in the source statement's label field.

.\text{macro}  identifies the source statement as the first line of a macro definition. You must place .\text{macro} in the opcode field.

[\text{parameters}]  are optional substitution symbols that appear as operands for the .\text{macro} directive.

\text{model statements}  are instructions or assembler directives that are executed each time the macro is called.

\text{macro directives}  are used to control macro expansion.

.\text{endm}  marks the end of the macro definition.

Macros are explained in further detail in Chapter 6.
### .map/.clearmap

**Assign a Variable to a Register**

**Syntax**

```
.map symbol_1 / register_1 [, symbol_2 / register_2, ...]

.clearmap
```

**Description**

The `.map` directive is used by the compiler when the input is linear assembly. The compiler tries to keep your symbolic names for registers defined with `.reg` by creating substitution symbols with `.map`.

The `.map` directive is similar to `.asg`, but uses a forward slash instead of a comma; and allows single quote characters in the symbolic names. For example, this linear assembly input:

```
fn: .cproc a, b, c
    .reg x, y, z
    ADD a, b, z
    ADD z, c, z
    .return z
    .endproc
```

Becomes this assembly code output:

```
fn:
    .map a/A4
    .map b/B4
    .map c/A6
    .map z/A4
    .map z'/A3
    RET .S2 B3
    ADD .L1X a, b, z'
    ADD .L1 z', c, z
    NOP 3
```

The `.clearmap` directive is used by the compiler to undefine all current `.map` substitution symbols.

See the *TMS320C6000 Optimizing Compiler User’s Guide* for details on using the `.map` directive in linear assembly code.
.mlib Define Macro Library

Syntax .mlib "filename"

Description The .mlib directive provides the assembler with the filename of a macro library. A macro library is a collection of files that contain macro definitions. The macro definition files are bound into a single file (called a library or archive) by the archiver.

Each file in a macro library contains one macro definition that corresponds to the name of the file. The filename of a macro library member must be the same as the macro name, and its extension must be .asm. The filename must follow host operating system conventions; it can be enclosed in double quotes. You can specify a full pathname (for example, c:\320tools\macs.lib). If you do not specify a full pathname, the assembler searches for the file in the following locations in the order given:

1. The directory that contains the current source file
2. Any directories named with the --include_path assembler option
3. Any directories specified by the C6X_A_DIR environment variable
4. Any directories specified by the C6X_C_DIR environment variable

See Section 4.5 for more information about the --include_path option.

A .mlib directive causes the assembler to open the library specified by filename and create a table of the library’s contents. The assembler stores names of individual library members in the opcode table as library entries. This redefines any existing opcodes or macros with the same name. If one of these macros is called, the assembler extracts the library entry and loads it into the macro table. The assembler expands the library entry as it does other macros, but it does not place the source code in the listing. Only macros called from the library are extracted, and they are extracted only once.

See Chapter 6 for more information on macros and macro libraries.

Example The code creates a macro library that defines two macros, inc1.asm and dec1.asm. The file inc1.asm contains the definition of inc1 and dec1.asm contains the definition of dec1.

<table>
<thead>
<tr>
<th>inc1.asm</th>
<th>dec1.asm</th>
</tr>
</thead>
<tbody>
<tr>
<td>* Macro for incrementing</td>
<td>* Macro for decrementing</td>
</tr>
<tr>
<td>inc1 .macro A</td>
<td>dec1 .macro A</td>
</tr>
<tr>
<td>ADD A,1,A</td>
<td>SUB A,1,A</td>
</tr>
<tr>
<td>.endm</td>
<td>.endm</td>
</tr>
</tbody>
</table>

Use the archiver to create a macro library:

ar6x -a mac inc1.asm dec1.asm

Now you can use the .mlib directive to reference the macro library and define the inc1.asm and dec1.asm macros:

1 .mlib "mac.lib"
2
3 * Macro Call
4 00000000 inc1 A0
1 00000000 000021A0 ADD A0,1,A0
5
6 * Macro Call
7 00000004 dec1 B0
1 00000004 0003E1A2 SUB B0,1,B0
Directives Reference

.mlist/.mnolist

**Start/Stop Macro Expansion Listing**

**Syntax**

- .mli st
- .mnolist

**Description**

Two directives enable you to control the listing of macro and repeatable block expansions in the listing file:

The .mli st directive allows macro and .loop/.endloop block expansions in the listing file.

The .mnolist directive suppresses macro and .loop/.endloop block expansions in the listing file.

By default, the assembler behaves as if the .mli st directive had been specified.

See Chapter 6 for more information on macros and macro libraries. See the .loop/.break/.endloop topic for information on conditional blocks.

**Example**

This example defines a macro named STR_3. The first time the macro is called, the macro expansion is listed (by default). The second time the macro is called, the macro expansion is not listed, because a .mnolist directive was assembled. The third time the macro is called, the macro expansion is again listed because a .mli st directive was assembled.

```assembly
1 STR_3 .macro P1, P2, P3
2 .string ":p1:\", ":p2:\", ":p3:\"
3 .endm
4
5 00000000 STR_3 "as", "I", "am"

1 00000000 0000003A .string ":p1:\", ":p2:\", ":p3:\"
00000001 00000070
00000002 00000031
00000003 0000003A
00000004 0000003A
00000005 00000070
00000006 00000032
00000007 0000003A
00000008 0000003A
00000009 00000070
0000000a 00000033
0000000b 0000003A

6 .mnolist
7 0000000c STR_3 "as", "I", "am"
8 .mli st
9 00000018 STR_3 "as", "I", "am"
1 00000018 0000003A .string ":p1:\", ":p2:\", ":p3:\"
00000019 00000070
0000001a 00000031
0000001b 0000003A
0000001c 0000003A
0000001d 00000070
0000001e 00000032
0000001f 0000003A
00000020 0000003A
00000021 00000070
00000022 00000033
00000023 0000003A
```
.newblock

**Terminate Local Symbol Block**

**Syntax**

```
.newblock
```

**Description**

The `.newblock` directive undefines any local labels currently defined. Local labels, by nature, are temporary; the `.newblock` directive resets them and terminates their scope.

A local label is a label in the form $n$, where $n$ is a single decimal digit, or `name?`, where `name` is a legal symbol name. Unlike other labels, local labels are intended to be used locally, and cannot be used in expressions. They can be used only as operands in 8-bit jump instructions. Local labels are not included in the symbol table.

After a local label has been defined and (perhaps) used, you should use the `.newblock` directive to reset it. The `.text`, `.data`, and `.sect` directives also reset local labels. Local labels that are defined within an include file are not valid outside of the include file. See Section 4.8.3 for more information on the use of local labels.

**Example**

This example shows how the local label $1$ is declared, reset, and then declared again.

```
1 .global table1, table2
2
3 00000000 0000028! MVKL table1,A0
4 00000004 0000068! MVKH table1,A0
5 00000008 008031A9 MVK 99, A1
6 0000000c 010848C0 || ZERO A2
7
8 00000010 80000212 $1:[A1] B $1
9 00000014 01003674 STW A2, *A0++
10 00000018 0087E1A0 SUB A1,1,A1
11 0000001c 00004000 NOP 3
12
13 .newblock ; undefine $1
14
15 00000020 0000028! MVKL table2,A0
16 00000024 0000068! MVKH table2,A0
17 00000028 008031A9 MVK 99, A1
18 0000002c 010829C0 || SUB A2,1,A2
19
20 00000030 8000212 $1:[A1] B $1
21 00000034 01003674 STW A2, *A0++
22 00000038 0087E1A0 SUB A1,1,A1
23 0000003c 00004000 NOP 3
```
### .nocmp

**Do Not Utilize 16-Bit Instructions in Section**

#### Syntax

```
.nocmp
```

#### Description

The `.nocmp` directive instructs the compiler to not utilize 16-bit instructions for the code section `.nocmp` appears in. The `.nocmp` directive can appear anywhere in the section.

#### Example

In the example, the section `one` is not compressed, whereas section `two` is compressed.

```
.sect "one"
LDW *A4, A5
LDW *B4, A5
.nocmp
NOP 4
ADD A4, A5, A6
ADD B4, B5, B6
NOP
...

.sect "two"
ADD A4, A5, A6
NOP
NOP
...
```
.noremark/.remark

Control Remarks

Syntax

.noremark num
.remark [num]

Description

The .noremark directive suppresses the assembler remark identified by num. A remark is an informational assembler message that is less severe than a warning. This directive is equivalent to using the -ar[num] assembler option.

The .remark directive re-enables the remark(s) previously suppressed.

Example

This example uses .noremark to turn off remark #5001 and then .remark to turn it back on again.

Partial source file:

```asm
SPLOOP 1

SPMASK
||

SPKERNEL 1,0
||
DADDSP .S2 B27:B26,B7:B6,B27:B26

NOP 5

.noremark 5001

SPLOOP 1

SPMASK
||

SPKERNEL 1,0
||
DADDSP .S2 B27:B26,B7:B6,B27:B26

NOP 5

.remark 5001

SPLOOP 1

SPMASK
||

SPKERNEL 1,0
||
DADDSP .S2 B27:B26,B7:B6,B27:B26

NOP 5
```

Resulting listing file:

```asm
1 2 ; Example using .noremark to turn off remark #5001 and
3 ; then .remark to turn it back on again
4
5 00000000 0c66 SPLOOP 1
6 7 00000002 2c66 SPMASK
8 00000004 12490f02 ||
9 10 00000008 08034001 SPKERNEL 1,0
11 0000000c 1d1b4b22 ||
12 13 00000010 8c6e NOP 5
14
```
.noremark 5001
SPLOOP 1
SPMASK
SPKERNEL 1,0
DADDSP .S2 B27:B26,B7:B6,B27:B26
NOP 5
SPLOOP 1
SPKERNEL 1,0
DADDSP .S2 B27:B26,B7:B6,B27:B26
NOP 5

.option Select Listing Options

Syntax

```
.option option1, option2, . . .
```

Description

The .option directive selects options for the assembler output listing. The options must be separated by commas; each option selects a listing feature. These are valid options:

- **A** turns on listing of all directives and data, and subsequent expansions, macros, and blocks.
- **B** limits the listing of .byte and .char directives to one line.
- **D** turns off the listing of certain directives (same effect as .drnolist).
- **H** limits the listing of .half and .short directives to one line.
- **L** limits the listing of .long directives to one line.
- **M** turns off macro expansions in the listing.
- **N** turns off listing (performs .nolist).
- **O** turns on listing (performs .list).
- **T** limits the listing of .string directives to one line.
- **W** limits the listing of .word and .int directives to one line.
- **X** produces a cross-reference listing of symbols. You can also obtain a cross-reference listing by invoking the assembler with the --cross_reference option (see Section 4.3).

Options are not case sensitive.

Example

This example shows how to limit the listings of the .byte, .char, .int, long, .word, and .string directives to one line each.

```
 ****************************************
 ** Limit the listing of .byte, .char, **
 ** .int, .word, and .string **
 ** directives to 1 line each. **
 ****************************************
 .option B, W, T
 00000000 000000BD .byte -'C', 0B0h, 5
 00000003 000000BC .char -'D', 0C0h, 6
 00000006 0000000A .int 10, 35 + 'a', "abc"
 10 0000001C AABBCDDD .long 0AABBCDDDh, 536 + 'A'
 11 00000024 0000155A .word 5546, 78h
 12 0000002c 00000052 .string "Registers"
 13
 14 ****************************************
 ** Reset the listing options. **
 15 ****************************************
 .option R
 16 00000035 0000B0BD .byte -'C', 0B0h, 5
 00000036 000000B0
 00000037 00000005
 19 00000038 0000000C .char -'D', 0C0h, 6
 00000039 0000000C
 0000003a 00000006
 20 0000003c 0000000A .int 10, 35 + 'a', "abc"
 00000040 00000084
 00000044 00000061
 00000048 00000062
 0000004c 00000063
 21 00000050 AABBCDDD .long 0AABBCDDDh, 536 + 'A'
 00000054 00000259
 22 00000058 0000155A .word 5546, 78h
 0000005c 00000078
```

The `.page` directive produces a page eject in the listing file. The `.page` directive is not printed in the source listing, but the assembler increments the line counter when it encounters the `.page` directive. Using the `.page` directive to divide the source listing into logical divisions improves program readability.

This example shows how the `.page` directive causes the assembler to begin a new page of the source listing.

**Source file:**
Source file (generic)
```
.title "**** Page Directive Example ****"
;
;
.
.page
```

**Listing file:**
```
TMS320C6000 Assembler Version x.xx Day Time Year
Copyright (c) 1996-2011 Texas Instruments Incorporated
**** Page Directive Example **** PAGE 1

2 ;
3 ;
4 ;
```

No Errors, No Warnings
.retain / .retainrefs

**Conditionally Retain Sections In Object Module Output**

**Syntax**

```
.retain["section name"]
.retainrefs["section name"]
```

**Description**

The `.retain` directive indicates that the current or specified section is not eligible for removal via conditional linking. You can also override conditional linking for a given section with the --retain linker option. You can disable conditional linking entirely with the --unused_section_elimination=off linker option.

The `.retainrefs` directive indicates that any sections that refer to the current or specified section are not eligible for removal via conditional linking. For example, applications may use an .intvecs section to set up interrupt vectors. The .intvecs section is eligible for removal during conditional linking by default. You can force the .intvecs section and any sections that reference it to be retained by applying the .retain and .retainrefs directives to the .intvecs section.

The `section name` identifies the section. If the directive is used without a section name, it applies to the current initialized section. If the directive is applied to an uninitialized section, the section name is required. The section name must be enclosed in double quotes. A section name can contain a subsection name in the form `section name:subsection name`.

The linker assumes that all sections by default are eligible for removal via conditional linking. (However, the linker does automatically retain the .reset section.) The .retain directive is useful for overriding this default conditional linking behavior for sections that you want to keep included in the link, even if the section is not referenced by any other section in the link. For example, you could apply a .retain directive to an interrupt function that you have written in assembly language, but which is not referenced from any normal entry point in the application.
Example 1

This example of an interrupt function that has a .retain directive applied to it.

```
.sect "*.text:interrupts:retain"
.retain
.global _int_func1

;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
;* FUNCTION NAME: int_func1 *
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
_int_func1:
  STW .D2 FP,*SP++(-88) ; [B_D] |31|
  STW .D2 B3,*SP(80) ; [B_D] |31|
  STW .D2 A4,*SP(24) ; [B_D] |31|
  STW .D2 B2,*SP(84) ; [B_D] |31|
  STW .D2 B9,*SP(76) ; [B_D] |31|
  STW .D2 B8,*SP(72) ; [B_D] |31|
  STW .D2 B7,*SP(68) ; [B_D] |31|
  STW .D2 B6,*SP(64) ; [B_D] |31|
  STW .D2 B5,*SP(60) ; [B_D] |31|
  STW .D2 B4,*SP(56) ; [B_D] |31|
  STW .D2 B1,*SP(52) ; [B_D] |31|
  STW .D2 B0,*SP(48) ; [B_D] |31|
  STW .D2 A7,*SP(36) ; [B_D] |31|
  STW .D2 A6,*SP(32) ; [B_D] |31|
  STW .D2 A5,*SP(28) ; [B_D] |31|
  CALL .S1 _foo ; [A_S] |32|
  | | STW .D2 A8,*SP(40) ; [B_D] |31|
  ...
  STW .D2 B4,*(+DP(_a_i)) ; [B_D] |33|
  RET .S2 IRP ; [B_Sb] |34|
  | | LDW .D2 *SP(56),B4 ; [B_D] |34|
  | | LDW .D2 **+SP(88),FP ; [B_D] |34|
  NOP 4 ; [A_L]
```
**.sect Assemble Into Named Section**

**Syntax**

```
.sect " section name "
.sect " section name " [,{RO|RW}] [,{ALLOC|NOALLOC}]
```

**Description**

The `.sect` directive defines a named section that can be used like the default `.text` and `.data` sections. The `.sect` directive sets `section name` to be the current section; the lines that follow are assembled into the `section name` section.

The `section name` identifies the section. The section name must be enclosed in double quotes. A section name can contain a subsection name in the form `section name : subsection name`. See Chapter 2 for more information about sections.

The sections can be marked read-only (RO) or read-write (RW). Also, the sections can be marked for allocation (ALLOC) or no allocation (NOALLOC). These attributes can be specified in any order, but only one attribute from each set can be selected. RO conflicts with RW, and ALLOC conflicts with NOALLOC. If conflicting attributes are specified the assembler generates an error, for example:

```
"t.asm", ERROR! at line 1:[E0000] Attribute RO cannot be combined with attr RW
.sect "illegal_sect",RO,RW
```

**Example**

This example defines two special-purpose sections, Sym_Defs and Vars, and assembles code into them.

```
1 **********************************************
2 ** Begin assembling into .text section. **
3 **********************************************
4 00000000 .text
5 00000000 000005E0 ZERO A0
6 00000004 008425E0 ZERO A1
7
8 **********************************************
9 ** Begin assembling into vars section. **
10 **********************************************
11 00000000 .sect "vars"
12 00000000 4048F5C3 pi .float 3.14
13 00000004 000007D0 max .int 2000
14 00000008 00000001 min .int 1
15
16 **********************************************
17 ** Resume assembling into .text section. **
18 **********************************************
19 00000008 .text
20 00000008 010000A8 MVK 1,A2
21 0000000c 018000A8 MVK 1,A3
22
23 **********************************************
24 ** Resume assembling into vars section. **
25 **********************************************
26 0000000c .sect "vars"
27 0000000c 00000019 count .short 25
```
.set/.equ

**Define Assembly-Time Constant**

**Syntax**

```
symbol .set  value
symbol .equ  value
```

**Description**

The `.set` and `.equ` directives equate a constant value to a `.set/.equ` symbol. The symbol can then be used in place of a value in assembly source. This allows you to equate meaningful names with constants and other values. The `.set` and `.equ` directives are identical and can be used interchangeably.

- The `symbol` is a label that must appear in the label field.
- The `value` must be a well-defined expression, that is, all symbols in the expression must be previously defined in the current source module.

Undefined external symbols and symbols that are defined later in the module cannot be used in the expression. If the expression is relocatable, the symbol to which it is assigned is also relocatable.

The value of the expression appears in the object field of the listing. This value is not part of the actual object code and is not written to the output file.

Symbols defined with `.set` or `.equ` can be made externally visible with the `.def` or `.global` directive (see the `.global/.def/.ref` topic). In this way, you can define global absolute constants.

**Example**

This example shows how symbols can be assigned with `.set` and `.equ`.

```
1 **********************************************
2 ** Equate symbol AUX_R1 to register A1 **
3 ** and use it instead of the register. **
4 **********************************************
5 00000001 AUX_R1 .set A1
6 00000000 00B802D4 STH AUX_R1,*+B14
7
8 **********************************************
9 ** Set symbol index to an integer expr. **
10 ** and use it as an immediate operand. **
11 **********************************************
12 00000035 INDEX .equ 100/2 +3
13 00000004 01001AD0 ADDK INDEX, A2
14
15 **********************************************
16 ** Set symbol SYMTAB to a relocatable expr. **
17 ** and use it as a relocatable operand. **
18 **********************************************
19 00000008 0000000A LABEL .word 10
20 00000009 SYMTAB .set LABEL + 1
21
22 **********************************************
23 ** Set symbol NSYMS equal to the symbol **
24 ** INDEX and use it as you would INDEX. **
25 **********************************************
26 00000035 NSYMS .set INDEX
27 00000000c 00000035 .word NSYMS
```
.space/.bes

** Reserve Space **

Syntax

```
[label] .space  size in bytes

[label] .bes  size in bytes
```

Description

The .space and .bes directives reserve the number of bytes given by `size in bytes` in the current section and fill them with 0s. The section program counter is incremented to point to the word following the reserved space.

When you use a label with the .space directive, it points to the first byte reserved. When you use a label with the .bes directive, it points to the last byte reserved.

Example

This example shows how memory is reserved with the .space and .bes directives.

```
1 ****************************************************
2 ** Begin assembling into the .text section. **
3 ****************************************************
4 00000000 .text
5 ****************************************************
6 ** Reserve 0F0 bytes (60 words in .text section). **
7 ****************************************************
8 00000000 .space 0F0h
9 000000F0 00000100 .word 100h, 200h
000000F4 00000200
10 ****************************************************
11 ** Begin assembling into the .data section. **
12 ****************************************************
13 00000000 .data
14 00000000 00000049 .string "In .data"
00000001 0000006E
00000002 00000020
00000003 0000002E
00000004 00000064
00000005 00000061
00000006 00000074
00000007 00000061
15 ****************************************************
16 ** Reserve 100 bytes in the .data section; **
17 ** RES_1 points to the first word **
18 ** that contains reserved bytes. **
19 ****************************************************
20 00000008 RES_1: .space 100
21 0000000c 0000000F .word 15
22 00000070 00000008" .word RES_1
23 ****************************************************
24 ** Reserve 20 bytes in the .data section; **
25 ** RES_2 points to the last word **
26 ** that contains reserved bytes. **
27 ****************************************************
28 00000087 RES_2: .bes 20
29 00000088 00000036 .word 36h
30 0000008c 00000087" .word RES_2
```
.sslist/.ssnolist

Control Listing of Substitution Symbols

Syntax

.sslist

.ssnnolist

Description

Two directives allow you to control substitution symbol expansion in the listing file:

The .sslist directive allows substitution symbol expansion in the listing file. The expanded line appears below the actual source line.

The .ssnnolist directive suppresses substitution symbol expansion in the listing file.

By default, all substitution symbol expansion in the listing file is suppressed; the assembler acts as if the .ssnnolist directive had been used.

Lines with the pound (#) character denote expanded substitution symbols.

Example

This example shows code that, by default, suppresses the listing of substitution symbol expansion, and it shows the .sslist directive assembled, instructing the assembler to list substitution symbol code expansion.

```
1 00000000 .bss x,4
2 00000004 .bss y,4
3 00000008 .bss z,4
4 5 addm .macro src1,src2,dst
6 LDW *+B14(:src1:), A0
7 LDW *+B14(:src2:), A1
8 NOP 4
9 ADD A0,A1,A0
10 STW A0,**B14(:dst:)
11 .endm
12
13 00000000 addm x,y,z
  1 00000000 0000006C- LDW *+B14(x), A0
  1 00000004 0080016C- LDW *+B14(y), A1
  1 00000008 00006000 NOP 4
  1 0000000c 000401E0 ADD A0,A1,A0
  1 00000010 0000027C- STW A0,**B14(z)
14
15 00000004 addm x,y,z
  1 000000014 0000006C- LDW *+B14(:src1:), A0
  # LDW *+B14(x), A0
  1 00000018 0080016C- LDW *+B14(:src2:), A1
  # LDW *+B14(y), A1
  1 0000001c 00006000 NOP 4
  1 00000020 000401E0 ADD A0,A1,A0
  1 00000024 0000027C- STW A0,**B14(:dst:)
  # STW A0,**B14(z)
17
```
.string/.cstring Initialize Text

**Syntax**

```
.string  {expr | "string,"} [ , ... , {expr | "string,"} ]
.cstring {expr | "string,"} [ , ... , {expr | "string,"} ]
```

**Description**

The `.string` and `.cstring` directives place 8-bit characters from a character string into the current section. The `expr` or `string` can be one of the following:

- An expression that the assembler evaluates and treats as an 8-bit signed number.
- A character string enclosed in double quotes. Each character in a string represents a separate value, and values are stored in consecutive bytes. The entire string *must* be enclosed in quotes.

The `.cstring` directive adds a NUL character needed by C; the `.string` directive does not add a NUL character. In addition, `.cstring` interprets C escapes (`\ `\a` `\b` `\f` `\n` `\r` `\t` `\v` `<octal>`).

The assembler truncates any values that are greater than eight bits. Operands must fit on a single source statement line.

If you use a label, it points to the location of the first byte that is initialized.

When you use `.string` and `.cstring` in a `.struct/.endstruct` sequence, the directive only defines a member's size; it does not initialize memory. For more information, see the `.struct/.endstruct/.tag` topic.

**Example**

In this example, 8-bit values are placed into consecutive bytes in the current section. The label Str_Ptr has the value 0h, which is the location of the first initialized byte.

```
1 00000000 00000041 Str_Ptr: .string "ABCD"
   00000001 00000042
   00000002 00000043
   00000003 00000044
2 00000004 00000041 .string 41h, 42h, 43h, 44h
   00000005 00000042
   00000006 00000043
   00000007 00000044
3 00000008 00000041 .string "Austin", "Houston"
   00000009 00000075
   0000000a 00000073
   0000000b 00000074
   0000000c 00000069
   0000000d 0000006e
   0000000e 00000048
   0000000f 0000006f
   00000010 00000075
   00000011 00000073
   00000012 00000074
   00000013 0000006f
   00000014 0000006f
4 00000015 00000030 .string 36 + 12
```
### Declare Structure Type

**Syntax**

```
[stag]   .struct   [expr]
[mem_0]  element  [expr_0]
[mem_1]  element  [expr_1]
           .    .    .
           .    .    .
[mem_n]  .tag    stag  [expr_n]
           .    .    .
           .    .    .
[mem_N]  element  [expr_N]
[size]   .endstruct
label    .tag    stag
```

**Description**

The `.struct` directive assigns symbolic offsets to the elements of a data structure definition. This allows you to group similar data elements together and let the assembler calculate the element offset. This is similar to a C structure or a Pascal record. The `.struct` directive does not allocate memory; it merely creates a symbolic template that can be used repeatedly.

The `.endstruct` directive terminates the structure definition.

The `.tag` directive gives structure characteristics to a label, simplifying the symbolic representation and providing the ability to define structures that contain other structures. The `.tag` directive does not allocate memory. The structure tag (`stag`) of a `.tag` directive must have been previously defined.

Following are descriptions of the parameters used with the `.struct`, `.endstruct`, and `.tag` directives:

- **The `stag`** is the structure's tag. Its value is associated with the beginning of the structure. If no `stag` is present, the assembler puts the structure members in the global symbol table with the value of their absolute offset from the top of the structure. The `stag` is optional for `.struct`, but is required for `.tag`.
- **The `expr`** is an optional expression indicating the beginning offset of the structure. The default starting point for a structure is 0.
- **The `mem_n/N`** is an optional label for a member of the structure. This label is absolute and equates to the present offset from the beginning of the structure. A label for a structure member cannot be declared global.
- **The `element`** is one of the following descriptors: `.byte`, `.char`, `.int`, `.long`, `.word`, `.double`, `.half`, `.short`, `.string`, `.float`, `.field`, and `.tag`. All of these except `.tag` are typical directives that initialize memory. Following a `.struct` directive, these directives describe the structure element's size. They do not allocate memory. The `.tag` directive is a special case because `stag` must be used (as in the definition of `stag`).
- **The `expr_n/N`** is an optional expression for the number of elements described. This value defaults to 1. A `.string` element is considered to be one byte in size, and a `.field` element is one bit.
- **The `size`** is an optional label for the total size of the structure.

---

### Directives that Can Appear in a `.struct/.endstruct` Sequence

**NOTE:** The only directives that can appear in a `.struct/.endstruct` sequence are element descriptors, conditional assembly directives, and the `.align` directive, which aligns the member offsets on word boundaries. Empty structures are illegal.
The following examples show various uses of the .struct, .tag, and .endstruct directives.

Example 1

1. real_rec .struct ; stag
2. 00000000 nom .int ; member1 = 0
3. 00000004 den .int ; member2 = 1
4. 00000008 real_len .endstruct ; real_len = 2
5. 00000000 0080016C- LDW *+B14(real+real_rec.den), A1 ; access structure
6. 00000000 .bss real, real_len ; allocate mem rec

Example 2

11. cplx_rec .struct ; stag
12. 00000000 reali .tag real_rec ; member1 = 0
13. 00000008 imagi .tag real_rec ; member2 = 2
14. 00000010 cplx_len .endstruct ; cplx_len = 4
15. 00000008 .bss complex, cplx_len ; allocate mem rec
16. 00000004 0100046C- LDW *+B14(complex.imagi.nom), A2 ; access structure
17. 00000008 0100036C- LDW *+B14(complex.reali.den), A2 ; access structure
18. 0000000C 018C4A78 CMPEQ A2, A3, A3 ; attribute

Example 3

1. .struct ; no stag puts mems into global symbol table
2. 00000000 X .byte ; create 3 dim
3. 00000001 Y .byte ; templates
4. 00000002 Z .byte
5. 00000003 .endstruct

Example 4

1. bit_rec .struct ; stag
2. 00000000 stream .string 64
3. 00000040 bit7 .field 7 ; bit7 = 64
4. 00000040 bit1 .field 9 ; bit9 = 64
5. 00000042 bit5 .field 10 ; bit5 = 64
6. 00000044 x_int .byte ; x_int = 68
7. 00000045 bit_len .endstruct ; length = 72
8. 00000000 .bss bits, bit_len
9. 00000000 0109E7A0 AND 0Fh, A2, A2 ; mask off garbage
The .symdepend directive creates an artificial reference from the section defining src symbol name to the symbol dst symbol name. This prevents the linker from removing the section containing dst symbol name if the section defining src symbol name is included in the output module. If src symbol name is not specified, a reference from the current section is created.

The .weak directive identifies a symbol that is used in the current module but is defined in another module. The linker resolves this symbol's definition at link time. Instead of including a weak symbol in the output file's symbol table by default (as it would for a global symbol), the linker only includes a weak symbol in the output of a "final" link if the symbol is required to resolve an otherwise unresolved reference. See Section 2.6.2 for details about how weak symbols are handled by the linker.

The .weak directive is equivalent to the .ref directive, except that the reference has weak linkage.

A symbol can be declared global in either of the following ways:

- If the symbol is not defined in the current module (which includes macro, copy, and include files), use the .weak directive to tell the assembler that the symbol is defined in an external module. This prevents the assembler from issuing a multiple-definition error. (The assembler can provide a similar multiple-definition error for local symbols.) The .weak directive always creates a symbol table entry for a symbol, whether the module uses the symbol or not; .symdepend, however, creates an entry only if the module actually uses the symbol.

For example, use the .weak and .set directives in combination as shown in the following example, which defines a weak absolute symbol "ext_addr_sym":

```assembly
.weak ext_addr_sym
ext_addr_sym .set 0x12345678
```

If you assemble such assembly source and include the resulting object file in the link, the "ext_addr_sym" in this example is available as a weak absolute symbol in a final link. It is a candidate for removal if the symbol is not referenced elsewhere in the application.
### .tab

**Define Tab Size**

<table>
<thead>
<tr>
<th>Syntax</th>
<th>Description</th>
<th>Example</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>.tab size</code></td>
<td>The <code>.tab</code> directive defines the tab size. Tabs encountered in the source input are translated to <code>size</code> character spaces in the listing. The default tab size is eight spaces.</td>
<td>In this example, each of the lines of code following a <code>.tab</code> statement consists of a single tab character followed by an NOP instruction.</td>
</tr>
</tbody>
</table>

**Source file:**

```plaintext
; default tab size
NOP
NOP
NOP
.tab 4
NOP
NOP
NOP
.tab 16
NOP
NOP
NOP
```

**Listing file:**

```
1 ; default tab size
  00000000 00000000 NOP
  00000004 00000000 NOP
  00000008 00000000 NOP
  .tab 4
  0000000c 00000000 NOP
  00000010 00000000 NOP
  00000014 00000000 NOP
  .tab 16
  00000018 00000000 NOP
  0000001c 00000000 NOP
  00000020 00000000 NOP
```
**.text**

**Assemble Into the .text Section**

**Syntax**

`.text`

**Description**

The `.text` sets .text as the current section. Lines that follow this directive will be assembled into the .text section, which usually contains executable code. The section program counter is set to 0 if nothing has yet been assembled into the .text section. If code has already been assembled into the .text section, the section program counter is restored to its previous value in the section.

The .text section is the default section. Therefore, at the beginning of an assembly, the assembler assembles code into the .text section unless you use a .data or .sect directive to specify a different section.

For more information about sections, see Chapter 2.

**Example**

This example assembles code into the .text and .data sections.

```
1 ******************************************
2 ** Begin assembling into .data section. **
3 ******************************************
4 00000000 .data
5 00000000 00000005 .byte 5,6
   00000001 00000006
6 7
   ******************************************
8 ** Begin assembling into .text section. **
9 ******************************************
10 00000000 .text
11 00000000 00000001 .byte 1
12 00000001 00000002 .byte 2,3
   00000002 00000003
13
14  ******************************************
15 ** Resume assembling into .data section.**
16 ******************************************
17 00000002 .data
18 00000002 00000007 .byte 7,8
   00000003 00000008
19
20  ******************************************
21 ** Resume assembling into .text section.**
22 ******************************************
23 00000003 .text
24 00000003 00000004 .byte 4
```
.title

**Define Page Title**

### Syntax

```
.title "string"
```

### Description

The `.title` directive supplies a title that is printed in the heading on each listing page. The source statement itself is not printed, but the line counter is incremented.

The `string` is a quote-enclosed title of up to 64 characters. If you supply more than 64 characters, the assembler truncates the string and issues a warning:

```
*** WARNING! line x: W0001: String is too long - will be truncated
```

The assembler prints the title on the page that follows the directive and on subsequent pages until another `.title` directive is processed. If you want a title on the first page, the first source statement must contain a `.title` directive.

### Example

In this example, one title is printed on the first page and a different title is printed on succeeding pages.

**Source file:**

```
.title "**** Fast Fourier Transforms ****"
; .
; .
; .
.title "**** Floating-Point Routines ****"
.page
```

**Listing file:**

```
TMS320C6000 Assembler  Version x.xx Day Time Year
Copyright (c) 1996-2011 Texas Instruments Incorporated
**** Fast Fourier Transforms ****       PAGE 1

2 ; .
3 ; .
4 ; .

TMS320C6000 Assembler  Version x.xx Day Time Year
Copyright (c) 1996-2011 Texas Instruments Incorporated
**** Floating-Point Routines ****       PAGE 2
```

No Errors, No Warnings
### Declare Union Type

#### Syntax

```
[stag] .union [expr]

[mem_0] element [expr_0]
[mem_1] element [expr_1]

... ... ...

[mem_n] .tag stag [expr_n]

... ... ...

[mem_N] element [expr_N]

[size] .endunion

label .tag stag
```

#### Description

The `.union` directive assigns symbolic offsets to the elements of alternate data structure definitions to be allocated in the same memory space. This enables you to define several alternate structures and then let the assembler calculate the element offset. This is similar to a C union. The `.union` directive does not allocate any memory; it merely creates a symbolic template that can be used repeatedly.

A `.struct` definition can contain a `.union` definition, and `.structs` and `.unions` can be nested.

The `.endunion` directive terminates the union definition.

The `.tag` directive gives structure or union characteristics to a `label`, simplifying the symbolic representation and providing the ability to define structures or unions that contain other structures or unions. The `.tag` directive does not allocate memory. The structure or union tag of a `.tag` directive must have been previously defined.

Following are descriptions of the parameters used with the `.struct`, `.endstruct`, and `.tag` directives:

- **The `utag`** is the union's tag. It is the union's tag. Its value is associated with the beginning of the union. If no `utag` is present, the assembler puts the union members in the global symbol table with the value of their absolute offset from the top of the union. In this case, each member must have a unique name.

- **The `expr`** is an optional expression indicating the beginning offset of the union. Unions default to start at 0. This parameter can only be used with a top-level union. It cannot be used when defining a nested union.

- **The `mem`** is an optional label for a member of the union. This label is absolute and equates to the present offset from the beginning of the union. A label for a union member cannot be declared global.

- **The `element`** is one of the following descriptors: .byte, .char, .int, .long, .word, .double, .half, .short, .string, .float, and .field. An element can also be a complete declaration of a nested structure or union, or a structure or union declared by its tag. Following a `.union` directive, these directives describe the element's size. They do not allocate memory.

- **The `expr`** is an optional expression for the number of elements described. This value defaults to 1. A `.string` element is considered to be one byte in size, and a `.field` element is one bit.

- **The `size`** is an optional label for the total size of the union.
Directives that Can Appear in a .union/.endunion Sequence

**NOTE:** The only directives that can appear in a .union/.endunion sequence are element descriptors, structure and union tags, and conditional assembly directives. Empty structures are illegal.

These examples show unions with and without tags.

**Example 1**

```
1 .global employid
2 xample .union ; utag
3 0000 ival .word ; member1 = int
4 0000 fval .float ; member2 = float
5 0000 sval .string ; member3 = string
6 0002 real_len .endunion ; real_len = 2
7
8 000000 .bss employid, real_len ; allocate memory
9
10 employid .tag xample ; name an instance
11 000000 0000- ADD employid.fval, A ; access union element
```

**Example 2**

```
1
2 ; utag
3 0000 x .long ; member1 = long
4 0000 y .float ; member2 = float
5 0000 z .word ; member3 = word
6 0002 size_u .endunion ; real_len = 2
7
```
The .usect directive reserves space for variables in an uninitialized, named section. This directive is similar to the .bss directive; both simply reserve space for data and that space has no contents. However, .usect defines additional sections that can be placed anywhere in memory, independently of the .bss section.

- The symbol points to the first location reserved by this invocation of the .usect directive. The symbol corresponds to the name of the variable for which you are reserving space.
- The section name must be enclosed in double quotes. This parameter names the uninitialized section. A section name can contain a subsection name in the form section name : subsection name.
- The size in bytes is an expression that defines the number of bytes that are reserved in section name.
- The alignment is an optional parameter that ensures that the space allocated to the symbol occurs on the specified boundary. This boundary must be set to a power of 2.
- The bank offset is an optional parameter that ensures that the space allocated to the symbol occurs on a specific memory bank boundary. The bank offset value measures the number of bytes to offset from the alignment specified before assigning the symbol to that location.

Initialized sections directives (.text, .data, and .sect) tell the assembler to pause assembling into the current section and begin assembling into another section. A .usect or .bss directive encountered in the current section is simply assembled, and assembly continues in the current section.

Variables that can be located contiguously in memory can be defined in the same specified section; to do so, repeat the .usect directive with the same section name and the subsequent symbol (variable name).

For more information about sections, see Chapter 2.

This example uses the .usect directive to define two uninitialized, named sections, var1 and var2. The symbol ptr points to the first byte reserved in the var1 section. The symbol array points to the first byte in a block of 100 bytes reserved in var1, and dflag points to the first byte in a block of 50 bytes in var1. The symbol vec points to the first byte reserved in the var2 section.

Syntax

```assembly
symbol .usect "section name", size in bytes[, alignment[, bank offset] ]
```
Figure 5-8 shows how this example reserves space in two uninitialized sections, var1 and var2.

```
1 ***************************************************
2 ** Assemble into .text section **
3 ***************************************************
4 00000000 .text
5 00000000 008001A0 MV A0,A1
6
7 ***************************************************
8 ** Reserve 2 bytes in var1. **
9 ***************************************************
10 00000000 ptr .usect "var1",2
11 00000004 0100004C- LDH *+B14(ptr),A2 ; still in .text
12
13 ***************************************************
14 ** Reserve 100 bytes in var1 **
15 ***************************************************
16 00000002 array .usect "var1",100
17 00000008 01800128- MVK array,A3 ; still in .text
18 0000000c 01800068- MVKH array,A3
19
20 ***************************************************
21 ** Reserve 50 bytes in var1 **
22 ***************************************************
23 00000006 dflag .usect "var1",50
24 00000010 02003328- MVK dflag,A4
25 00000014 02000068- MVKH dflag,A4
26
27 ***************************************************
28 ** Reserve 100 bytes in var1 **
29 ***************************************************
30 00000000 vec .usect "var2",100
31 00000018 000002A- MVK vec,B0 ; still in .text
32 0000001c 0000006A- MVKH vec,B0
```

Figure 5-8. The .usect Directive

```
ptr --> Section var1

2 bytes

array --> 100 bytes

152 bytes reserved in var1

dflag --> 50 bytes

ptr --> Section var2

100 bytes

100 bytes reserved in var2
```
**.unasg/.undefine**  
*Turn Off Substitution Symbol*

**Syntax**

```plaintext
.unasg symbol
.undefine symbol
```

**Description**

The `.unasg` and `.undefine` directives remove the definition of a substitution symbol created using `.asg` or `.define`. The named `symbol` will removed from the substitution symbol table from the point of the `.undefine` or `.unasg` to the end of the assembly file. See Section 4.8.10 for more information on substitution symbols.

These directives can be used to remove from the assembly environment any C/C++ macros that may cause a problem. See Chapter 11 for more information about using C/C++ headers in assembly source.

---

**.var**  
*Use Substitution Symbols as Local Variables*

**Syntax**

```plaintext
.var sym1 [, sym2, ..., symn]
```

**Description**

The `.var` directive allows you to use substitution symbols as local variables within a macro. With this directive, you can define up to 32 local macro substitution symbols (including parameters) per macro.

The `.var` directive creates temporary substitution symbols with the initial value of the null string. These symbols are not passed in as parameters, and they are lost after expansion.

See Section 4.8.10 for more information on substitution symbols. See Chapter 6 for information on macros.
The TMS320C6000 assembler supports a macro language that enables you to create your own instructions. This is especially useful when a program executes a particular task several times. The macro language lets you:

- Define your own macros and redefine existing macros
- Simplify long or complicated assembly code
- Access macro libraries created with the archiver
- Define conditional and repeatable blocks within a macro
- Manipulate strings within a macro
- Control expansion listing

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>6.1 Using Macros</td>
<td>156</td>
</tr>
<tr>
<td>6.2 Defining Macros</td>
<td>156</td>
</tr>
<tr>
<td>6.3 Macro Parameters/Substitution Symbols</td>
<td>158</td>
</tr>
<tr>
<td>6.4 Macro Libraries</td>
<td>163</td>
</tr>
<tr>
<td>6.5 Using Conditional Assembly in Macros</td>
<td>164</td>
</tr>
<tr>
<td>6.6 Using Labels in Macros</td>
<td>166</td>
</tr>
<tr>
<td>6.7 Producing Messages in Macros</td>
<td>167</td>
</tr>
<tr>
<td>6.8 Using Directives to Format the Output Listing</td>
<td>168</td>
</tr>
<tr>
<td>6.9 Using Recursive and Nested Macros</td>
<td>169</td>
</tr>
<tr>
<td>6.10 Macro Directives Summary</td>
<td>170</td>
</tr>
</tbody>
</table>
6.1 Using Macros

Programs often contain routines that are executed several times. Instead of repeating the source statements for a routine, you can define the routine as a macro, then call the macro in the places where you would normally repeat the routine. This simplifies and shortens your source program.

If you want to call a macro several times but with different data each time, you can assign parameters within a macro. This enables you to pass different information to the macro each time you call it. The macro language supports a special symbol called a substitution symbol, which is used for macro parameters. See Section 6.3 for more information.

Using a macro is a 3-step process.

Step 1. Define the macro. You must define macros before you can use them in your program. There are two methods for defining macros:

(a) Macros can be defined at the beginning of a source file or in a copy/include file. See Section 6.2, Defining Macros, for more information.

(b) Macros can also be defined in a macro library. A macro library is a collection of files in archive format created by the archiver. Each member of the archive file (macro library) may contain one macro definition corresponding to the member name. You can access a macro library by using the .mlib directive. For more information, see Section 6.4.

Step 2. Call the macro. After you have defined a macro, call it by using the macro name as a mnemonic in the source program. This is referred to as a macro call.

Step 3. Expand the macro. The assembler expands your macros when the source program calls them. During expansion, the assembler passes arguments by variable to the macro parameters, replaces the macro call statement with the macro definition, then assembles the source code. By default, the macro expansions are printed in the listing file. You can turn off expansion listing by using the .mnolist directive. For more information, see Section 6.8.

When the assembler encounters a macro definition, it places the macro name in the opcode table. This redefines any previously defined macro, library entry, directive, or instruction mnemonic that has the same name as the macro. This allows you to expand the functions of directives and instructions, as well as to add new instructions.

6.2 Defining Macros

You can define a macro anywhere in your program, but you must define the macro before you can use it. Macros can be defined at the beginning of a source file or in a .copy/.include file (see Copy Source File); they can also be defined in a macro library. For more information about macro libraries, see Section 6.4.

Macro definitions can be nested, and they can call other macros, but all elements of the macro must be defined in the same file. Nested macros are discussed in Section 6.9.

A macro definition is a series of source statements in the following format:

```
macname .macro [parameter, ] [, ... , parameter, ]
  model statements or macro directives
  [.mexit]
  .endm
```

- `macname` names the macro. You must place the name in the source statement's label field. Only the first 128 characters of a macro name are significant. The assembler places the macro name in the internal opcode table, replacing any instruction or previous macro definition with the same name.
- `.macro` is the directive that identifies the source statement as the first line of a macro definition. You must place .macro in the opcode field.
- `parameter`, `parameter` are optional substitution symbols that appear as operands for the .macro directive. Parameters are discussed in Section 6.3.
**model statements** are instructions or assembler directives that are executed each time the macro is called.

**macro directives** are used to control macro expansion.

**.mexit** is a directive that functions as a `goto .endm`. The `.mexit` directive is useful when error testing confirms that macro expansion fails and completing the rest of the macro is unnecessary.

**.endm** is the directive that terminates the macro definition.

If you want to include comments with your macro definition but do not want those comments to appear in the macro expansion, use an exclamation point to precede your comments. If you do want your comments to appear in the macro expansion, use an asterisk or semicolon. See Section 6.7 for more information about macro comments.

**Example 6-1** shows the definition, call, and expansion of a macro.

### Example 6-1. Macro Definition, Call, and Expansion

Macro definition: The following code defines a macro, sadd4, with four parameters:

```
1 sadd4 .macro r1,r2,r3,r4
2 !
3 ! sadd4 r1, r2 ,r3, r4
4 ! r1 = r1 + r2 + r3 + r4 (saturated)
5 !
6 SADD r1,r2,r1
7 SADD r1,r3,r1
8 SADD r1,r4,r1
9 .endm
```

Macro call: The following code calls the sadd4 macro with four arguments:

```
10 00000000 sadd4 A0,A1,A2,A3
```

Macro expansion: The following code shows the substitution of the macro definition for the macro call. The assembler substitutes A0, A1, A2, and A3 for the r1, r2, r3, and r4 parameters of sadd4.

```
1 00000000 00040278 SADD A0,A1,A0
1 00000004 00080278 SADD A0,A2,A0
1 00000008 000C0278 SADD A0,A3,A0
```
6.3 Macro Parameters/Substitution Symbols

If you want to call a macro several times with different data each time, you can assign parameters within the macro. The macro language supports a special symbol, called a substitution symbol, which is used for macro parameters.

Macro parameters are substitution symbols that represent a character string. These symbols can also be used outside of macros to equate a character string to a symbol name (see Section 4.8.10).

Valid substitution symbols can be up to 128 characters long and must begin with a letter. The remainder of the symbol can be a combination of alphanumeric characters, underscores, and dollar signs.

Substitution symbols used as macro parameters are local to the macro they are defined in. You can define up to 32 local substitution symbols (including substitution symbols defined with the .var directive) per macro. For more information about the .var directive, see Section 6.3.6.

During macro expansion, the assembler passes arguments by variable to the macro parameters. The character-string equivalent of each argument is assigned to the corresponding parameter. Parameters without corresponding arguments are set to the null string. If the number of arguments exceeds the number of parameters, the last parameter is assigned the character-string equivalent of all remaining arguments.

If you pass a list of arguments to one parameter or if you pass a comma or semicolon to a parameter, you must surround these terms with quotation marks.

At assembly time, the assembler replaces the macro parameter/substitution symbol with its corresponding character string, then translates the source code into object code.

Example 6-2 shows the expansion of a macro with varying numbers of arguments.

Example 6-2. Calling a Macro With Varying Numbers of Arguments

Macro definition:

```
Parms .macro a,b,c
 ; a = :a:
 ; b = :b:
 ; c = :c:
.endm
```

Calling the macro:

```
Parms 100,label
 ; a = 100
 ; b = label
 ; c = ""
Parms 100, , x
 ; a = 100
 ; b = ""
 ; c = x
Parms """"string""",x,y
 ; a = "string"
 ; b = x
 ; c = y
```

6.3.1 Directives That Define Substitution Symbols

You can manipulate substitution symbols with the .asg and .eval directives.

- The .asg directive assigns a character string to a substitution symbol.
  For the .asg directive, the quotation marks are optional. If there are no quotation marks, the assembler reads characters up to the first comma and removes leading and trailing blanks. In either case, a character string is read and assigned to the substitution symbol. The syntax of the .asg directive is:

  \[ \text{.asg["character string"]}, \text{substitution symbol} \]

Example 6-3 shows character strings being assigned to substitution symbols.

**Example 6-3. The .asg Directive**

```
.asg "A4", RETVAL ; return value
```

- The .eval directive performs arithmetic on numeric substitution symbols.
  The .eval directive evaluates the expression and assigns the string value of the result to the substitution symbol. If the expression is not well defined, the assembler generates an error and assigns the null string to the symbol. The syntax of the .eval directive is:

  \[ \text{.eval well-defined expression , substitution symbol} \]

Example 6-4 shows arithmetic being performed on substitution symbols.

**Example 6-4. The .eval Directive**

```
.asg 1,counter
.loop 100
.word counter
.eval counter + 1,counter
.endloop
```

In Example 6-4, the .asg directive could be replaced with the .eval directive (.eval 1, counter) without changing the output. In simple cases like this, you can use .eval and .asg interchangeably. However, you must use .eval if you want to calculate a value from an expression. While .asg only assigns a character string to a substitution symbol, .eval evaluates an expression and then assigns the character string equivalent to a substitution symbol.

See **Assign a Substitution Symbol** for more information about the .asg and .eval assembler directives.
6.3.2 Built-In Substitution Symbol Functions

The following built-in substitution symbol functions enable you to make decisions on the basis of the string value of substitution symbols. These functions always return a value, and they can be used in expressions. Built-in substitution symbol functions are especially useful in conditional assembly expressions. Parameters of these functions are substitution symbols or character-string constants.

In the function definitions shown in Table 6-1, \( a \) and \( b \) are parameters that represent substitution symbols or character-string constants. The term string refers to the string value of the parameter. The symbol \( ch \) represents a character constant.

Table 6-1. Substitution Symbol Functions and Return Values

<table>
<thead>
<tr>
<th>Function</th>
<th>Return Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$symlen(a)</td>
<td>Length of string ( a )</td>
</tr>
<tr>
<td>$symcmp(a,b)</td>
<td>(&lt; 0 ) if ( a &lt; b ); ( 0 ) if ( a = b ); ( &gt; 0 ) if ( a &gt; b )</td>
</tr>
<tr>
<td>$firstch(a,ch)</td>
<td>Index of the first occurrence of character constant ( ch ) in string ( a )</td>
</tr>
<tr>
<td>$lastch(a,ch)</td>
<td>Index of the last occurrence of character constant ( ch ) in string ( a )</td>
</tr>
<tr>
<td>$isdefed(a)</td>
<td>1 if string ( a ) is defined in the symbol table</td>
</tr>
<tr>
<td></td>
<td>0 if string ( a ) is not defined in the symbol table</td>
</tr>
<tr>
<td>$ismember(a,b)</td>
<td>Top member of list ( b ) is assigned to string ( a )</td>
</tr>
<tr>
<td></td>
<td>0 if ( b ) is a null string</td>
</tr>
<tr>
<td>$iscons(a)</td>
<td>1 if string ( a ) is a binary constant</td>
</tr>
<tr>
<td></td>
<td>2 if string ( a ) is an octal constant</td>
</tr>
<tr>
<td></td>
<td>3 if string ( a ) is a hexadecimal constant</td>
</tr>
<tr>
<td></td>
<td>4 if string ( a ) is a character constant</td>
</tr>
<tr>
<td></td>
<td>5 if string ( a ) is a decimal constant</td>
</tr>
<tr>
<td>$isname(a)</td>
<td>1 if string ( a ) is a valid symbol name</td>
</tr>
<tr>
<td></td>
<td>0 if string ( a ) is not a valid symbol name</td>
</tr>
<tr>
<td>$isreg(a)</td>
<td>1 if string ( a ) is a valid predefined register name</td>
</tr>
<tr>
<td></td>
<td>0 if string ( a ) is not a valid predefined register name</td>
</tr>
</tbody>
</table>

(1) For more information about predefined register names, see Section 4.8.6.

Example 6-5 shows built-in substitution symbol functions.

**Example 6-5. Using Built-In Substitution Symbol Functions**

```assembly
pushx .macro list
  !
  ! Push more than one item
  ! $ismember removes the first item in the list
  .var item
  .loop
  .break ($ismember(item, list) = 0)
  STW item,*B15--[1]
  .endloop
  .endm

pushx A0,A1,A2,A3
```
6.3.3 Recursive Substitution Symbols

When the assembler encounters a substitution symbol, it attempts to substitute the corresponding character string. If that string is also a substitution symbol, the assembler performs substitution again. The assembler continues doing this until it encounters a token that is not a substitution symbol or until it encounters a substitution symbol that it has already encountered during this evaluation.

In Example 6-6, the x is substituted for z; z is substituted for y; and y is substituted for x. The assembler recognizes this as infinite recursion and ceases substitution.

Example 6-6. Recursive Substitution

```
.asg "x",z ; declare z and assign z = "x"
.asg "z",y ; declare y and assign y = "z"
.asg "y",x ; declare x and assign x = "y"
MVKL x, A1
MVKH x, A1
* MVKL x, A1 ; recursive expansion
* MVKH x, A1 ; recursive expansion
```

6.3.4 Forced Substitution

In some cases, substitution symbols are not recognizable to the assembler. The forced substitution operator, which is a set of colons surrounding the symbol, enables you to force the substitution of a symbol's character string. Simply enclose a symbol with colons to force the substitution. Do not include any spaces between the colons and the symbol. The syntax for the forced substitution operator is:

```
:symbol:
```

The assembler expands substitution symbols surrounded by colons before expanding other substitution symbols.

You can use the forced substitution operator only inside macros, and you cannot nest a forced substitution operator within another forced substitution operator.

Example 6-7 shows how the forced substitution operator is used.

Example 6-7. Using the Forced Substitution Operator

```
force .macro x
 .loop 8
PORT:x: .set x*4
 .eval x+1, x
 .endloop
.endm
 .global portbase
force
PORT0 .set 0
PORT1 .set 4
 .
 .
PORT7 .set 28
```
6.3.5 Accessing Individual Characters of Subscripted Substitution Symbols

In a macro, you can access the individual characters (substrings) of a substitution symbol with subscripted substitution symbols. You must use the forced substitution operator for clarity.

You can access substrings in two ways:

- 
  :symbol (well-defined expression):
  This method of subscripting evaluates to a character string with one character.

- 
  :symbol (well-defined expression , well-defined expression ):
  In this method, expression represents the substring's starting position, and expression represents the substring's length. You can specify exactly where to begin subscripting and the exact length of the resulting character string. The index of substring characters begins with 1, not 0.

Example 6-8 and Example 6-9 show built-in substitution symbol functions used with subscripted substitution symbols. In Example 6-8, subscripted substitution symbols redefine the STW instruction so that it handles immediates. In Example 6-9, the subscripted substitution symbol is used to find a substring strg1 beginning at position start in the string strg2. The position of the substring strg1 is assigned to the substitution symbol pos.

Example 6-8. Using Subscripted Substitution Symbols to Redefine an Instruction

```
storex .macro x
  .var tmp
  .asg :x(1):, tmp
  .if $symcmp(tmp,"A") == 0
    STW x,*A15--(4)
  .elseif $symcmp(tmp,"B") == 0
    STW x,*A15--(4)
  .else if $iscons(x)
    MVK x,A0
    STW A0,*A15--(4)
  .else
    .emsg "Bad Macro Parameter"
  .endif
.endm

storex 10h
storex A15
```
Example 6-9. Using Subscripted Substitution Symbols to Find Substrings

```asm
substr .macro start,strg1,strg2,pos
 .var len1,len2,i,tmp
 .if $symlen(start) = 0
 .eval 1,start
 .endif
 .eval 0,pos
 .eval start,i
 .eval $symlen(strg1),len1
 .eval $symlen(strg2),len2
 .loop
 .break I = (len2 - len1 + 1)
 .asg ":strg2(i,len1):",tmp
 .if $symcmp(strg1,tmp) = 0
 .eval i,pos
 .break
 .else
 .eval I + 1,i
 .endif
 .endloop
 .endm
 .asg 0,pos
 .asg "ar1 ar2 ar3 ar4",regs
 substr 1,"ar2",regs,pos
 .word pos
```

6.3.6 Substitution Symbols as Local Variables in Macros

If you want to use substitution symbols as local variables within a macro, you can use the `.var` directive to define up to 32 local macro substitution symbols (including parameters) per macro. The `.var` directive creates temporary substitution symbols with the initial value of the null string. These symbols are not passed in as parameters, and they are lost after expansion.

```
$.var sym_1[,sym_2,...,sym_n]
```

The `.var` directive is used in Example 6-8 and Example 6-9.

6.4 Macro Libraries

One way to define macros is by creating a macro library. A macro library is a collection of files that contain macro definitions. You must use the archiver to collect these files, or members, into a single file (called an archive). Each member of a macro library contains one macro definition. The files in a macro library must be unassembled source files. The macro name and the member name must be the same, and the macro filename's extension must be .asm. For example:

<table>
<thead>
<tr>
<th>Macro Name</th>
<th>Filename in Macro Library</th>
</tr>
</thead>
<tbody>
<tr>
<td>simple</td>
<td>simple.asm</td>
</tr>
<tr>
<td>add3</td>
<td>add3.asm</td>
</tr>
</tbody>
</table>

You can access the macro library by using the `.mlib` assembler directive (described in Define Macro Library). The syntax is:

```
.mlib filename
```
When the assembler encounters the .mlib directive, it opens the library named by filename and creates a table of the library's contents. The assembler enters the names of the individual members within the library into the opcode tables as library entries; this redefines any existing opcodes or macros that have the same name. If one of these macros is called, the assembler extracts the entry from the library and loads it into the macro table.

The assembler expands the library entry the same way it expands other macros. See Section 6.1 for how the assembler expands macros. You can control the listing of library entry expansions with the .mlist directive. For information about the .mlist directive, see Section 6.8 and Start/Stop Macro Expansion Listing. Only macros that are actually called from the library are extracted, and they are extracted only once.

You can use the archiver to create a macro library by including the desired files in an archive. A macro library is no different from any other archive, except that the assembler expects the macro library to contain macro definitions. The assembler expects only macro definitions in a macro library; putting object code or miscellaneous source files into the library may produce undesirable results. For information about creating a macro library archive, see Section 7.1.

### 6.5 Using Conditional Assembly in Macros

The conditional assembly directives are .if/.elseif/.else/.endif and .loop/.break/.endloop. They can be nested within each other up to 32 levels deep. The format of a conditional block is:

```
.if well-defined expression
    [.elseif well-defined expression]
    [.else]
    .endif
```

The .elseif and .else directives are optional in conditional assembly. The .elseif directive can be used more than once within a conditional assembly code block. When .elseif and .else are omitted and when the .if expression is false (0), the assembler continues to the code following the .endif directive. See Assemble Conditional Blocks for more information on the .if/.elseif/.else/.endif directives.

The .loop/.break/.endloop directives enable you to assemble a code block repeatedly. The format of a repeatable block is:

```
.loop [well-defined expression]
    [.break [well-defined expression]]
    .endloop
```

The .loop directive's optional well-defined expression evaluates to the loop count (the number of loops to be performed). If the expression is omitted, the loop count defaults to 1024 unless the assembler encounters a .break directive with an expression that is true (nonzero). See Assemble Conditional Blocks Repeatedly for more information on the .loop/.break/.endloop directives.

The .break directive and its expression are optional in repetitive assembly. If the expression evaluates to false, the loop continues. The assembler breaks the loop when the .break expression evaluates to true or when the .break expression is omitted. When the loop is broken, the assembler continues with the code after the .endloop directive. For more information, see Section 5.7.
Example 6-10, Example 6-11, and Example 6-12 show the .loop/.break/.endloop directives, properly nested conditional assembly directives, and built-in substitution symbol functions used in a conditional assembly code block.

**Example 6-10. The .loop/.break/.endloop Directives**

```
.asg 1,x
.loop
  .break (x == 10) ; if x == 10, quit loop/break with expression
  .eval x+1,x
.endloop
```

**Example 6-11. Nested Conditional Assembly Directives**

```
.asg 1,x
.loop
  .if (x == 10) ; if x == 10, quit loop
  .break (x == 10) ; force break
  .endif
  .eval x+1,x
.endloop
```

**Example 6-12. Built-In Substitution Symbol Functions in a Conditional Assembly Code Block**

```
MACK3 .macro src1, src2, sum, k
  !  dst = dst + k * (src1 * src2)
  .if k = 0
    MPY src1, src2, src2
    NOP
    ADD src2, sum, sum
  .else
    MPY src1, src2, src2
    MVK k, src1
    MPY src1, src2, src2
    NOP
    ADD src2, sum, sum
  .endif
.endm

MACK3 A0,A1,A3,0
MACK3 A0,A1,A3,100
```
6.6 Using Labels in Macros

All labels in an assembly language program must be unique. This includes labels in macros. If a macro is expanded more than once, its labels are defined more than once. Defining a label more than once is illegal. The macro language provides a method of defining labels in macros so that the labels are unique. Simply follow each label with a question mark, and the assembler replaces the question mark with a period followed by a unique number. When the macro is expanded, you do not see the unique number in the listing file. Your label appears with the question mark as it did in the macro definition. You cannot declare this label as global. See Section 4.8.3 for more about labels.

The syntax for a unique label is:

```
label ?
```

Example 6-13 shows unique label generation in a macro. The maximum label length is shortened to allow for the unique suffix. For example, if the macro is expanded fewer than 10 times, the maximum label length is 126 characters. If the macro is expanded from 10 to 99 times, the maximum label length is 125. The label with its unique suffix is shown in the cross-listing file. To obtain a cross-listing file, invoke the assembler with the --cross_reference option (see Section 4.3).

**Example 6-13. Unique Labels in a Macro**

```
1 min .macro x,y,z
2
3 MV y,z
4 || CMPLT x,y,y
5 [y] B l?
6 NOP 5
7 ? MV x,z
8 l?
9 .endm
10
11 00000000 MIN A0,A1,A2
12 00000000 010401A1 MV A1,A2
13 00000004 00840AF8 || CMPLT A0,A1,A1
14 00000008 80000292 [A1] B l?
15 000000c 000D8000 NOP 5
16 0000010 010001A0 MV A0,A2
17 0000014 l?

```

<table>
<thead>
<tr>
<th>LABEL</th>
<th>VALUE</th>
<th>DEFN</th>
<th>REF</th>
</tr>
</thead>
<tbody>
<tr>
<td>.TMS320C60</td>
<td>00000001</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>.tms320c60</td>
<td>00000001</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>l$1$</td>
<td>00000014</td>
<td>12</td>
<td>12</td>
</tr>
</tbody>
</table>
6.7 Producing Messages in Macros

The macro language supports three directives that enable you to define your own assembly-time error and warning messages. These directives are especially useful when you want to create messages specific to your needs. The last line of the listing file shows the error and warning counts. These counts alert you to problems in your code and are especially useful during debugging.

-.emsg sends error messages to the listing file. The .emsg directive generates errors in the same manner as the assembler, incrementing the error count and preventing the assembler from producing an object file.

-.mmsg sends assembly-time messages to the listing file. The .mmsg directive functions in the same manner as the .emsg directive but does not set the error count or prevent the creation of an object file.

-.wmsg sends warning messages to the listing file. The .wmsg directive functions in the same manner as the .emsg directive, but it increments the warning count and does not prevent the generation of an object file.

Macro comments are comments that appear in the definition of the macro but do not show up in the expansion of the macro. An exclamation point in column 1 identifies a macro comment. If you want your comments to appear in the macro expansion, precede your comment with an asterisk or semicolon.

Example 6-14 shows user messages in macros and macro comments that do not appear in the macro expansion.

For more information about the .emsg, .mmsg, and .wmsg assembler directives, see Define Messages.

Example 6-14. Producing Messages in a Macro

TEST .macro x,y
! This macro checks for the correct number of parameters.
! It generates an error message if x and y are not present.
! The first line tests for proper input.
! .if ($symlen(x) + ||$symlen(y) == 0)
  .emsg "ERROR --missing parameter in call to TEST"
  .mexit
  .else
    .endif
  .if
    .endif
  .endm
6.8 Using Directives to Format the Output Listing

Macros, substitution symbols, and conditional assembly directives may hide information. You may need to see this hidden information, so the macro language supports an expanded listing capability.

By default, the assembler shows macro expansions and false conditional blocks in the list output file. You may want to turn this listing off or on within your listing file. Four sets of directives enable you to control the listing of this information:

- **Macro and loop expansion listing**
  .mlist expands macros and .loop/.endloop blocks. The .mlist directive prints all code encountered in those blocks.
  .mnolist suppresses the listing of macro expansions and .loop/.endloop blocks.
  For macro and loop expansion listing, .mlist is the default.

- **False conditional block listing**
  .fclist causes the assembler to include in the listing file all conditional blocks that do not generate code (false conditional blocks). Conditional blocks appear in the listing exactly as they appear in the source code.
  .fcnolist suppresses the listing of false conditional blocks. Only the code in conditional blocks that actually assemble appears in the listing. The .if, .elseif, .else, and .endif directives do not appear in the listing.
  For false conditional block listing, .fclist is the default.

- **Substitution symbol expansion listing**
  .sslist expands substitution symbols in the listing. This is useful for debugging the expansion of substitution symbols. The expanded line appears below the actual source line.
  .ssnolist turns off substitution symbol expansion in the listing.
  For substitution symbol expansion listing, .ssnolist is the default.

- **Directive listing**
  .drlist causes the assembler to print to the listing file all directive lines.
  .drnolist suppresses the printing of certain directives in the listing file. These directives are .asg, .eval, .var, .sslist, .mlist, .fclist, .ssnolist, .mnolist, .fcnolist, .emsg, .wmsg, .mmsg, .length, .width, and .break.
  For directive listing, .drlist is the default.
6.9 Using Recursive and Nested Macros

The macro language supports recursive and nested macro calls. This means that you can call other macros in a macro definition. You can nest macros up to 32 levels deep. When you use recursive macros, you call a macro from its own definition (the macro calls itself).

When you create recursive or nested macros, you should pay close attention to the arguments that you pass to macro parameters because the assembler uses dynamic scoping for parameters. This means that the called macro uses the environment of the macro from which it was called.

Example 6-15 shows nested macros. The y in the in_block macro hides the y in the out_block macro. The x and z from the out_block macro, however, are accessible to the in_block macro.

Example 6-15. Using Nested Macros

```assembly
in_block .macro y,a
  ; visible parameters are y,a and x,z from the calling macro
.endm

out_block .macro x,y,z
  ; visible parameters are x,y,z

in_block x,y ; macro call with x and y as arguments
  .
.endm
out_block ; macro call
```

Example 6-16 shows recursive and fact macros. The fact macro produces assembly code necessary to calculate the factorial of n, where n is an immediate value. The result is placed in the A1 register. The fact macro accomplishes this by calling fact1, which calls itself recursively.

Example 6-16. Using Recursive Macros

```assembly
.fcnolist

fact1 .macro n
  .if n == 1
    MVK globcnt, A1 ; Leave the answer in the A1 register.
  .else
    .eval 1, temp ; Compute the decrement of symbol n.
    .eval globcnt*temp, globcnt ; Multiply to get a new result.
    fact1 temp ; Recursive call.
  .endif
.endm

fact .macro n
  .if ! $iscons(n) ; Test that input is a constant.
    .emsg "Parm not a constant"
  .elseif n < 1 ; Type check input.
    MVK 0, A1
  .else
    .var temp
    .asg n, globcnt
    fact1 n ; Perform recursive procedure
  .endif
.endm
```

Macro Language Description
The directives listed in Table 6-2 through Table 6-6 can be used with macros. The .macro, .mexit, .endm and .var directives are valid only with macros; the remaining directives are general assembly language directives.

### Table 6-2. Creating Macros

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>Macro Use</th>
<th>Directive</th>
</tr>
</thead>
<tbody>
<tr>
<td>.endm</td>
<td>End macro definition</td>
<td>Section 6.2</td>
<td>.endm</td>
</tr>
<tr>
<td>macname .macro [parameter, [ ... , parameter_n]]</td>
<td>Define macro by macname</td>
<td>Section 6.2</td>
<td>.macro</td>
</tr>
<tr>
<td>.mexit</td>
<td>Go to .endm</td>
<td>Section 6.2</td>
<td>Section 6.2</td>
</tr>
<tr>
<td>.mlib filename</td>
<td>Identify library containing macro definitions</td>
<td>Section 6.4</td>
<td>.mlib</td>
</tr>
</tbody>
</table>

### Table 6-3. Manipulating Substitution Symbols

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>Macro Use</th>
<th>Directive</th>
</tr>
</thead>
<tbody>
<tr>
<td>.asg &quot;character string&quot;, substitution symbol</td>
<td>Assign character string to substitution symbol</td>
<td>Section 6.3.1</td>
<td>.asg</td>
</tr>
<tr>
<td>.eval well-defined expression, substitution symbol</td>
<td>Perform arithmetic on numeric substitution symbols</td>
<td>Section 6.3.1</td>
<td>.eval</td>
</tr>
<tr>
<td>.var sym_1, sym_2, ..., sym_n</td>
<td>Define local macro symbols</td>
<td>Section 6.3.6</td>
<td>.var</td>
</tr>
</tbody>
</table>

### Table 6-4. Conditional Assembly

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>Macro Use</th>
<th>Directive</th>
</tr>
</thead>
<tbody>
<tr>
<td>.break [well-defined expression]</td>
<td>Optional repeatable block assembly</td>
<td>Section 6.5</td>
<td>.break</td>
</tr>
<tr>
<td>.endif</td>
<td>End conditional assembly</td>
<td>Section 6.5</td>
<td>.endif</td>
</tr>
<tr>
<td>.endloop</td>
<td>End repeatable block assembly</td>
<td>Section 6.5</td>
<td>.endloop</td>
</tr>
<tr>
<td>.else</td>
<td>Optional conditional assembly block</td>
<td>Section 6.5</td>
<td>.else</td>
</tr>
<tr>
<td>.elseif well-defined expression</td>
<td>Optional conditional assembly block</td>
<td>Section 6.5</td>
<td>.elseif</td>
</tr>
<tr>
<td>.if well-defined expression</td>
<td>Begin conditional assembly</td>
<td>Section 6.5</td>
<td>.if</td>
</tr>
<tr>
<td>.loop [well-defined expression]</td>
<td>Begin repeatable block assembly</td>
<td>Section 6.5</td>
<td>.loop</td>
</tr>
</tbody>
</table>

### Table 6-5. Producing Assembly-Time Messages

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>Macro Use</th>
<th>Directive</th>
</tr>
</thead>
<tbody>
<tr>
<td>.emsg</td>
<td>Send error message to standard output</td>
<td>Section 6.7</td>
<td>.emsg</td>
</tr>
<tr>
<td>.mmsg</td>
<td>Send assembly-time message to standard output</td>
<td>Section 6.7</td>
<td>.mmsg</td>
</tr>
<tr>
<td>.wmsg</td>
<td>Send warning message to standard output</td>
<td>Section 6.7</td>
<td>.wmsg</td>
</tr>
</tbody>
</table>

### Table 6-6. Formatting the Listing

<table>
<thead>
<tr>
<th>Mnemonic and Syntax</th>
<th>Description</th>
<th>Macro Use</th>
<th>Directive</th>
</tr>
</thead>
<tbody>
<tr>
<td>.fclist</td>
<td>Allow false conditional code block listing (default)</td>
<td>Section 6.8</td>
<td>.fclist</td>
</tr>
<tr>
<td>.fcnolist</td>
<td>Suppress false conditional code block listing</td>
<td>Section 6.8</td>
<td>.fcnolist</td>
</tr>
<tr>
<td>.mlist</td>
<td>Allow macro listings (default)</td>
<td>Section 6.8</td>
<td>.mlist</td>
</tr>
<tr>
<td>.mnolist</td>
<td>Suppress macro listings</td>
<td>Section 6.8</td>
<td>.mnolist</td>
</tr>
<tr>
<td>.sslist</td>
<td>Allow expanded substitution symbol listing</td>
<td>Section 6.8</td>
<td>.sslist</td>
</tr>
<tr>
<td>.ssnolist</td>
<td>Suppress expanded substitution symbol listing (default)</td>
<td>Section 6.8</td>
<td>.ssnolist</td>
</tr>
</tbody>
</table>
The TMS320C6000 archiver lets you combine several individual files into a single archive file. For example, you can collect several macros into a macro library. The assembler searches the library and uses the members that are called as macros by the source file. You can also use the archiver to collect a group of object files into an object library. The linker includes in the library the members that resolve external references during the link. The archiver allows you to modify a library by deleting, replacing, extracting, or adding members.
7.1 Archiver Overview

You can build libraries from any type of files. Both the assembler and the linker accept archive libraries as input; the assembler can use libraries that contain individual source files, and the linker can use libraries that contain individual object files.

One of the most useful applications of the archiver is building libraries of object modules. For example, you can write several arithmetic routines, assemble them, and use the archiver to collect the object files into a single, logical group. You can then specify the object library as linker input. The linker searches the library and includes members that resolve external references.

You can also use the archiver to build macro libraries. You can create several source files, each of which contains a single macro, and use the archiver to collect these macros into a single, functional group. You can use the .mlib directive during assembly to specify that macro library to be searched for the macros that you call. Chapter 6 discusses macros and macro libraries in detail, while this chapter explains how to use the archiver to build libraries.
7.2 The Archiver's Role in the Software Development Flow

Figure 7-1 shows the archiver's role in the software development process. The shaded portion highlights the most common archiver development path. Both the assembler and the linker accept libraries as input.

Figure 7-1. The Archiver in the TMS320C6000 Software Development Flow
7.3 Invoking the Archiver

To invoke the archiver, enter:

```
ar6x[-]command [options] libname [filename; ... filename, ]
```

- `ar6x` is the command that invokes the archiver.
- `[-]command` tells the archiver how to manipulate the existing library members and any specified. A command can be preceded by an optional hyphen. You must use one of the following commands when you invoke the archiver, but you can use only one command per invocation. The archiver commands are as follows:
  - `@` uses the contents of the specified file instead of command line entries. You can use this command to avoid limitations on command line length imposed by the host operating system. Use a `;` at the beginning of a line in the command file to include comments. (See Example 7-1 for an example using an archiver command file.)
  - `a` adds the specified files to the library. This command does not replace an existing member that has the same name as an added file; it simply appends new members to the end of the archive.
  - `d` deletes the specified members from the library.
  - `r` replaces the specified members in the library. If you do not specify filenames, the archiver replaces the library members with files of the same name in the current directory. If the specified file is not found in the library, the archiver adds it instead of replacing it.
  - `t` prints a table of contents of the library. If you specify filenames, only those files are listed. If you do not specify any filenames, the archiver lists all the members in the specified library.
  - `x` extracts the specified files. If you do not specify member names, the archiver extracts all library members. When the archiver extracts a member, it simply copies the member into the current directory; it does not remove it from the library.

- `options` In addition to one of the commands, you can specify options. To use options, combine them with a command; for example, to use the a command and the s option, enter `-as` or as. The hyphen is optional for archiver options only. These are the archiver options:
  - `-q` (quiet) suppresses the banner and status messages.
  - `-s` prints a list of the global symbols that are defined in the library. (This option is valid only with the a, r, and d commands.)
  - `-u` replaces library members only if the replacement has a more recent modification date. You must use the r command with the `-u` option to specify which members to replace.
  - `-v` (verbose) provides a file-by-file description of the creation of a new library from an old library and its members.

- `libname` names the archive library to be built or modified. If you do not specify an extension for `libname`, the archiver uses the default extension `.lib`.

- `filenames` names individual files to be manipulated. These files can be existing library members or new files to be added to the library. When you enter a filename, you must enter a complete filename including extension, if applicable.

**Naming Library Members**

**NOTE:** It is possible (but not desirable) for a library to contain several members with the same name. If you attempt to delete, replace, or extract a member whose name is the same as another library member, the archiver deletes, replaces, or extracts the first library member with that name.
The following are examples of typical archiver operations:

- If you want to create a library called function.lib that contains the files sine.obj, cos.obj, and flt.obj, enter:
  
  ```
  ar6x -a function sine.obj cos.obj flt.obj
  ```
  
The archiver responds as follows:
  
  ```
  ==> new archive 'function.lib' ==> building new archive 'function.lib'
  ```

- You can print a table of contents of function.lib with the -t command, enter:
  
  ```
  ar6x -t function
  ```
  
The archiver responds as follows:
  
  ```
  FILE NAME SIZE DATE
  ---------------- ----- ------------------------
  sine.obj 300 Wed Jun 15 10:00:24 2011
  cos.obj 300 Wed Jun 15 10:00:30 2011
  flt.obj 300 Wed Jun 15 09:59:56 2011
  ```

- If you want to add new members to the library, enter:
  
  ```
  ar6x -as function atan.obj
  ```
  
The archiver responds as follows:
  
  ```
  ==> symbol defined: '_sin'
  ==> symbol defined: '_cos'
  ==> symbol defined: '_tan'
  ==> symbol defined: '_atan'
  ==> building archive 'function.lib'
  ```

Because this example does not specify an extension for the libname, the archiver adds the files to the library called function.lib. If function.lib does not exist, the archiver creates it. (The -s option tells the archiver to list the global symbols that are defined in the library.)

- If you want to modify a library member, you can extract it, edit it, and replace it. In this example, assume there is a library named macros.lib that contains the members push.asm, pop.asm, and swap.asm.
  
  ```
  ar6x -x macros push.asm
  ```
  
The archiver makes a copy of push.asm and places it in the current directory; it does not remove push.asm from the library. Now you can edit the extracted file. To replace the copy of push.asm in the library with the edited copy, enter:
  
  ```
  ar6x -r macros push.asm
  ```

- If you want to use a command file, specify the command filename after the -@ command. For example:
  
  ```
  ar6x -@modules.cmd
  ```
  
The archiver responds as follows:
  
  ```
  ==> building archive 'modules.lib'
  ```
Example 7-1 is the modules.cmd command file. The r command specifies that the filenames given in the command file replace files of the same name in the modules.lib library. The -u option specifies that these files are replaced only when the current file has a more recent revision date than the file that is in the library.

**Example 7-1. Archiver Command File**

```plaintext
; Command file to replace members of the
; modules library with updated files
; Use r command and u option:
ru
; Specify library name:
modules.lib
; List filenames to be replaced if updated:
align.asm
bss.asm
data.asm
text.asm
sect.asm
clink.asm
copy.asm
double.asm
drnolist.asm
emsg.asm
end.asm
```

### 7.5 Library Information Archiver Description

Section 7.1 explains how to use the archiver to create libraries of object files for use in the linker of one or more applications. You can have multiple versions of the same object file libraries, each built with different sets of build options. For example, you might have different versions of your object file library for big and little endian, for different architecture revisions, or for different ABIs depending on the typical build environments of client applications. However, if you have several versions of a library, it can be cumbersome to keep track of which version of the library needs to be linked in for a particular application.

When several versions of a single library are available, the library information archiver can be used to create an index library of all of the object file library versions. This index library is used in the linker in place of a particular version of your object file library. The linker looks at the build options of the application being linked, and uses the specified index library to determine which version of your object file library to include in the linker. If one or more compatible libraries were found in the index library, the most suitable compatible library is linked in for your application.

#### 7.5.1 Invoking the Library Information Archiver

To invoke the library information archiver, enter:

```
libinfo6x [options] -o=libname libname1 [libname2 ... libname_n]
```

- **libinfo6x** is the command that invokes the library information archiver.
- **options** changes the default behavior of the library information archiver. These options are:
  - `-o libname` specifies the name of the index library to create or update. This option is required.
  - `-u` updates any existing information in the index library specified with the -o option instead of creating a new index.
- **libnames** names individual object file libraries to be manipulated. When you enter a libname, you must enter a complete filename including extension, if applicable.
7.5.2 Library Information Archiver Example

Consider these object file libraries that all have the same members, but are built with different build options:

<table>
<thead>
<tr>
<th>Object File Library Name</th>
<th>Build Options</th>
</tr>
</thead>
<tbody>
<tr>
<td>mylib_64plus_be.lib</td>
<td>-mv6400+ --endian=big</td>
</tr>
<tr>
<td>mylib_64plus_le.lib</td>
<td>-mv6400+ --endian=little</td>
</tr>
<tr>
<td>mylib_6740_le.lib</td>
<td>-mv6740 --endian=little</td>
</tr>
<tr>
<td>mylib_6600_be.lib</td>
<td>-mv6600 --endian=big</td>
</tr>
</tbody>
</table>

Using the library information archiver, you can create an index library called mylib.lib from the above libraries:

```
libinfo6x -o mylib.lib mylib_6600_be.lib mylib_6600_le.lib
```

You can now specify mylib.lib as a library for the linker of an application. The linker uses the index library to choose the appropriate version of the library to use. If the --issue_remarks option is specified before the --run_linker option, the linker reports which library was chosen.

- **Example 1** (ISA 64plus, little endian):
  ```
  cl6x -mv64plus --endian=little --issue_remarks main.c -z -l lnk.cmd ./mylib.lib
  <Linking>
  remark: linking in "mylib_64plus_le.lib" in place of "mylib.lib"
  ```

- **Example 2** (ISA 6600, big endian):
  ```
  cl6x -mv6600 --endian=big --issue_remarks main.c -z -l lnk.cmd ./mylib.lib
  <Linking>
  remark: linking in "mylib_6600_be.lib" in place of "mylib.lib"
  ```

7.5.3 Listing the Contents of an Index Library

The archiver's -t option can be used on an index library to list the archives indexed by an index library:

```
ar6x t mylib.lib
```

<table>
<thead>
<tr>
<th>SIZE</th>
<th>DATE</th>
<th>FILE NAME</th>
</tr>
</thead>
<tbody>
<tr>
<td>119</td>
<td>Wed Feb 03 12:45:22 2010</td>
<td>mylib_6600_be.lib</td>
</tr>
<tr>
<td>119</td>
<td>Wed Feb 03 12:45:22 2010</td>
<td>mylib_6600_le.lib</td>
</tr>
<tr>
<td>119</td>
<td>Wed Feb 03 12:45:22 2010</td>
<td>mylib_64plus_be.lib</td>
</tr>
<tr>
<td>119</td>
<td>Wed Feb 03 12:45:22 2010</td>
<td>mylib_64plus_le.lib</td>
</tr>
<tr>
<td>0</td>
<td>Wed Sep 30 12:45:22 2009</td>
<td><strong>TI</strong>$LIBINFO</td>
</tr>
</tbody>
</table>

The indexed object file libraries have an additional .libinfo extension in the archiver listing. The __TI__$LIBINFO member is a special member that designates *mylib.lib* as an index library, rather than a regular library.

If the archiver's -d command is used on an index library to delete a .libinfo member, the linker will no longer choose the corresponding library when the index library is specified.

Using any other archiver option with an index library, or using -d to remove the __TI__$LIBINFO member, results in undefined behavior, and is not supported.

7.5.4 Requirements

You must follow these requirements to use library index files:

- At least one application object file must appear on the linker command line before the index library.
- Each object file library specified as input to the library information archiver must only contain object file members that are built with the same build options.
- The linker expects the index library and all of the libraries it indexes to be in a single directory.
Chapter 8

**Linker Description**

The TMS320C6000 linker creates a static executable or dynamic object module by combining object modules. This chapter describes the linker options, directives, and statements used to create static executables and dynamic object modules. Object libraries, command files, and other key concepts are discussed as well.

The concept of sections is basic to linker operation; Chapter 2 includes a detailed discussion of sections.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>8.1 Linker Overview</td>
<td>179</td>
</tr>
<tr>
<td>8.2 The Linker's Role in the Software Development Flow</td>
<td>180</td>
</tr>
<tr>
<td>8.3 Invoking the Linker</td>
<td>181</td>
</tr>
<tr>
<td>8.4 Linker Options</td>
<td>182</td>
</tr>
<tr>
<td>8.5 Linker Command Files</td>
<td>204</td>
</tr>
<tr>
<td>8.6 Linker Symbols</td>
<td>240</td>
</tr>
<tr>
<td>8.7 Default Placement Algorithm</td>
<td>243</td>
</tr>
<tr>
<td>8.8 Linker-Generated Copy Tables</td>
<td>244</td>
</tr>
<tr>
<td>8.9 Partial (Incremental) Linking</td>
<td>257</td>
</tr>
<tr>
<td>8.10 Linking C/C++ Code</td>
<td>258</td>
</tr>
<tr>
<td>8.11 Linker Example</td>
<td>260</td>
</tr>
<tr>
<td>8.12 Dynamic Linking with the C6000 Code Generation Tools</td>
<td>265</td>
</tr>
</tbody>
</table>
8.1 Linker Overview

The TMS320C6000 linker allows you to allocate output sections efficiently in the memory map. As the linker combines object files, it performs the following tasks:

- Allocates sections into the target system's configured memory
- Relocates symbols and sections to assign them to final addresses
- Resolves undefined external references between input files

The linker command language controls memory configuration, output section definition, and address binding. The language supports expression assignment and evaluation. You configure system memory by defining and creating a memory model that you design. Two powerful directives, MEMORY and SECTIONS, allow you to:

- Allocate sections into specific areas of memory
- Combine object file sections
- Define or redefine global symbols at link time
8.2 The Linker’s Role in the Software Development Flow

Figure 8-1 illustrates the linker’s role in the software development process. The linker accepts several types of files as input, including object files, command files, libraries, and partially linked files. The linker creates an executable object module that can be downloaded to one of several development tools or executed by a TMS320C6000 device.

Figure 8-1. The Linker in the TMS320C6000 Software Development Flow
8.3 Invoking the Linker

The general syntax for invoking the linker is:

```
cl6x --run_linker [options] filename1, ..., filename_n
```

- **cl6x --run_linker** is the command that invokes the linker. The `--run_linker` option's short form is `-z`.
- **options** can appear anywhere on the command line or in a linker command file. (Options are discussed in Section 8.4.)
- **filename1, filename_n** can be object files, linker command files, or archive libraries. The default extension for all input files is `.obj`; any other extension must be explicitly specified. The linker can determine whether the input file is an object or ASCII file that contains linker commands. The default output filename is `a.out`, unless you use the `--output_file` option to name the output file.

There are two methods for invoking the linker:

- **Specify options and filenames on the command line.** This example links two files, file1.obj and file2.obj, and creates an output module named link.out.
  
  ```
  cl6x --run_linker file1.obj file2.obj --output_file=link.out
  ```

- **Put filenames and options in a linker command file.** Filenames that are specified inside a linker command file must begin with a letter. For example, assume the file linker.cmd contains the following lines:
  ```
  --output_file=link.out file1.obj file2.obj
  ```

  Now you can invoke the linker from the command line; specify the command filename as an input file:
  ```
  cl6x --run_linker linker.cmd
  ```

  When you use a command file, you can also specify other options and files on the command line. For example, you could enter:
  ```
  cl6x --run_linker --map_file=link.map linker.cmd file3.obj
  ```

  The linker reads and processes a command file as soon as it encounters the filename on the command line, so it links the files in this order: file1.obj, file2.obj, and file3.obj. This example creates an output file called link.out and a map file called link.map.

For information on invoking the linker for C/C++ files, see Section 8.10.
## 8.4 Linker Options

Linker options control linking operations. They can be placed on the command line or in a command file. Linker options must be preceded by a hyphen (-). Options can be separated from arguments (if they have them) by an optional space.

### Table 8-1. Basic Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--run_linker</td>
<td>-z</td>
<td>Enables linking</td>
<td>Section 8.3</td>
</tr>
<tr>
<td>--output_file</td>
<td>-o</td>
<td>Names the executable output module. The default filename is a.out.</td>
<td>Section 8.4.23</td>
</tr>
<tr>
<td>--map_file</td>
<td>-m</td>
<td>Produces a map or listing of the input and output sections, including holes, and places the listing in <code>filename</code></td>
<td>Section 8.4.18</td>
</tr>
<tr>
<td>--stack_size</td>
<td>-stack</td>
<td>Sets C system stack size to <code>size</code> bytes and defines a global symbol that specifies the stack size. Default = 1K bytes</td>
<td>Section 8.4.28</td>
</tr>
<tr>
<td>--heap_size</td>
<td>-heap</td>
<td>Sets heap size (for the dynamic memory allocation in C) to <code>size</code> bytes and defines a global symbol that specifies the heap size. Default = 1K bytes</td>
<td>Section 8.4.14</td>
</tr>
</tbody>
</table>

### Table 8-2. File Search Path Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--library</td>
<td>-l</td>
<td>Names an archive library or link command <code>filename</code> as linker input</td>
<td>Section 8.4.16</td>
</tr>
<tr>
<td>--search_path</td>
<td>-i</td>
<td>Alters library-search algorithms to look in a directory named with <code>pathname</code> before looking in the default location. This option must appear before the -- library option.</td>
<td>Section 8.4.16.1</td>
</tr>
<tr>
<td>--priority</td>
<td>-priority</td>
<td>Satisfies unresolved references by the first library that contains a definition for that symbol</td>
<td>Section 8.4.16.3</td>
</tr>
<tr>
<td>--reread_libs</td>
<td>-x</td>
<td>Forces rereading of libraries, which resolves back references.</td>
<td>Section 8.4.16.3</td>
</tr>
<tr>
<td>--disable_auto_rts</td>
<td></td>
<td>Disables the automatic selection of a run-time-support library</td>
<td>Section 8.4.8</td>
</tr>
</tbody>
</table>

### Table 8-3. Command File Preprocessing Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--define</td>
<td></td>
<td>Predefines <code>name</code> as a preprocessor macro.</td>
<td>Section 8.4.10</td>
</tr>
<tr>
<td>--undefine</td>
<td></td>
<td>Removes the preprocessor macro <code>name</code>.</td>
<td>Section 8.4.10</td>
</tr>
<tr>
<td>--disable_pp</td>
<td></td>
<td>Disables preprocessing for command files</td>
<td>Section 8.4.10</td>
</tr>
</tbody>
</table>

### Table 8-4. Diagnostic Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--diag_error</td>
<td></td>
<td>Categorizes the diagnostic identified by <code>num</code> as an error</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--diag_remark</td>
<td></td>
<td>Categorizes the diagnostic identified by <code>num</code> as a remark</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--diag_suppress</td>
<td></td>
<td>Suppresses the diagnostic identified by <code>num</code></td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--diag_warning</td>
<td></td>
<td>Categorizes the diagnostic identified by <code>num</code> as a warning</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--display_error_number</td>
<td></td>
<td>Displays a diagnostic's identifiers along with its text</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--emit_warnings_as_errors</td>
<td>-pdew</td>
<td>Treats warnings as errors</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--issue_remarks</td>
<td>-pdew</td>
<td>Issues remarks (nonserious warnings)</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--no_demangle</td>
<td></td>
<td>Disables demangling of symbol names in diagnostics</td>
<td>Section 8.4.20</td>
</tr>
<tr>
<td>--no_warnings</td>
<td></td>
<td>Suppresses warning diagnostics (errors are still issued)</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--set_error_limit</td>
<td></td>
<td>Sets the error limit to <code>num</code>. The linker abandons linking after this number of errors. (The default is 100.)</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--verbose_diagnostics</td>
<td></td>
<td>Provides verbose diagnostics that display the original source with line-wrap</td>
<td>Section 8.4.7</td>
</tr>
<tr>
<td>--warn_sections</td>
<td>-w</td>
<td>Displays a message when an undefined output section is created</td>
<td>Section 8.4.33</td>
</tr>
</tbody>
</table>
### Table 8-5. Linker Output Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--absolute_exe</td>
<td>-a</td>
<td>Produces an absolute, executable module. This is the default; if neither --absolute_exe nor --relocatable is specified, the linker acts as if --absolute_exe were specified.</td>
<td>Section 8.4.3.1</td>
</tr>
<tr>
<td>--ecc:data_error</td>
<td></td>
<td>Inject the specified errors into the output file for testing</td>
<td>Section 8.4.11</td>
</tr>
<tr>
<td>--ecc:ecc_error</td>
<td></td>
<td>Inject the specified errors into the Error Correcting Code (ECC) for testing</td>
<td>Section 8.5.9</td>
</tr>
<tr>
<td>--mapfile_contents</td>
<td></td>
<td>Controls the information that appears in the map file.</td>
<td>Section 8.4.19</td>
</tr>
<tr>
<td>--relocatable</td>
<td>-r</td>
<td>Produces a nonexecutable, relocatable output module</td>
<td>Section 8.4.3.2</td>
</tr>
<tr>
<td>--rom</td>
<td>-r</td>
<td>Create a ROM object</td>
<td>Section 8.5.9</td>
</tr>
<tr>
<td>--xml_link_info</td>
<td></td>
<td>Generates a well-formed XML file containing detailed information about the</td>
<td>Section 8.4.34</td>
</tr>
<tr>
<td></td>
<td></td>
<td>result of a link</td>
<td></td>
</tr>
</tbody>
</table>

### Table 8-6. Symbol Management Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--entry_point</td>
<td>-e</td>
<td>Defines a global symbol that specifies the primary entry point for the output module</td>
<td>Section 8.4.12</td>
</tr>
<tr>
<td>--globalize</td>
<td></td>
<td>Changes the symbol linkage to global for symbols that match pattern</td>
<td>Section 8.4.17</td>
</tr>
<tr>
<td>--hide</td>
<td></td>
<td>Hides global symbols that match pattern</td>
<td>Section 8.4.15</td>
</tr>
<tr>
<td>--localize</td>
<td></td>
<td>Changes the symbol linkage to local for symbols that match pattern</td>
<td>Section 8.4.17</td>
</tr>
<tr>
<td>--make_global</td>
<td>-g</td>
<td>Makes symbol/global (overrides -h)</td>
<td>Section 8.4.17</td>
</tr>
<tr>
<td>--make_static</td>
<td>-h</td>
<td>Makes all global symbols static</td>
<td>Section 8.4.17</td>
</tr>
<tr>
<td>--no_symtable</td>
<td>-s</td>
<td>Strips symbol table information and line number entries from the output module</td>
<td>Section 8.4.22</td>
</tr>
<tr>
<td>--retain</td>
<td></td>
<td>Retains a list of sections that otherwise would be discarded</td>
<td>Section 8.4.26</td>
</tr>
<tr>
<td>--scan_libraries</td>
<td>-scanlibs</td>
<td>Scans all libraries for duplicate symbol definitions</td>
<td>Section 8.4.27</td>
</tr>
<tr>
<td>--symbol_map</td>
<td></td>
<td>Maps symbol references to a symbol definition of a different name</td>
<td>Section 8.4.30</td>
</tr>
<tr>
<td>--undef_sym</td>
<td>-u</td>
<td>Places an unresolved external symbol into the output module's symbol table</td>
<td>Section 8.4.32</td>
</tr>
<tr>
<td>--unhide</td>
<td></td>
<td>Reveals (un-hides) global symbols that match pattern</td>
<td>Section 8.4.15</td>
</tr>
</tbody>
</table>

### Table 8-7. Run-Time Environment Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--arg_size</td>
<td>--args</td>
<td>Allocates memory to be used by the loader to pass arguments</td>
<td>Section 8.4.4</td>
</tr>
<tr>
<td>--fill_value</td>
<td>-f</td>
<td>Sets default fill values for holes within output sections; fill_value is a 32-bit constant</td>
<td>Section 8.4.13</td>
</tr>
<tr>
<td>--ram_model</td>
<td>-cr</td>
<td>Initializes variables at load time</td>
<td>Section 8.4.25</td>
</tr>
<tr>
<td>--rom_model</td>
<td>-c</td>
<td>Autoinitializes variables at run time</td>
<td>Section 8.4.25</td>
</tr>
<tr>
<td>--trampolines</td>
<td></td>
<td>Generates far call trampolines; on by default</td>
<td>Section 8.4.31</td>
</tr>
</tbody>
</table>
### Table 8-8. Link-Time Optimization Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--cinit_compression</td>
<td></td>
<td>Specifies the type of compression to apply to the c auto initialization data</td>
<td>Section 8.4.5</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(default is rle)</td>
<td></td>
</tr>
<tr>
<td>--compress_dwarf</td>
<td></td>
<td>Aggressively reduces the size of DWARF information from input object files</td>
<td>Section 8.4.6</td>
</tr>
<tr>
<td>--copy_compression</td>
<td></td>
<td>Compresses data copied by linker copy tables</td>
<td>Section 8.4.5</td>
</tr>
<tr>
<td>--unused_section_elimination</td>
<td></td>
<td>Eliminates sections that are not needed in the executable module; on by</td>
<td>Section 8.4.9</td>
</tr>
<tr>
<td></td>
<td></td>
<td>default</td>
<td></td>
</tr>
</tbody>
</table>

### Table 8-9. Dynamic Linking Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--dsbt_index</td>
<td></td>
<td>Specifies the Data Segment Base Table (DSBT) index to be assumed for the</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>dynamic shared object or dynamic library being linked</td>
<td></td>
</tr>
<tr>
<td>--dsbt_size</td>
<td></td>
<td>Specifies the number of entries to be reserved for the Data Segment Base</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Table (DSBT)</td>
<td></td>
</tr>
<tr>
<td>--dynamic</td>
<td></td>
<td>Generates a bare-metal dynamic executable or library (argument is optional;</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>if no argument is specified, then a dynamic executable (exe) is generated)</td>
<td></td>
</tr>
<tr>
<td>--export</td>
<td></td>
<td>Exports the specified function symbol (sym)</td>
<td>Section 8.12.3.1</td>
</tr>
<tr>
<td>--fini</td>
<td></td>
<td>Specifies function symbol (sym) of the termination code</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td>--import</td>
<td></td>
<td>Imports the specified symbol</td>
<td>Section 8.12.4.1</td>
</tr>
<tr>
<td>--init</td>
<td></td>
<td>Specifies the function symbol (sym) of the initialization code</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td>--linux</td>
<td></td>
<td>Generates code for Linux</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td>--pic</td>
<td></td>
<td>Generates position independent addressing for a shared object. Default is</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>near.</td>
<td></td>
</tr>
<tr>
<td>--rpath</td>
<td></td>
<td>Adds specified directory to the beginning of the dynamic library search path</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td>--runpath</td>
<td></td>
<td>Adds specified directory to the end of the dynamic library search path</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td>--shared</td>
<td></td>
<td>Generates an ELF dynamically shared object (DSO)</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td>--soname</td>
<td></td>
<td>Specifies the name to be associated with this linked dynamic output; this</td>
<td>Section 8.12.4.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>name is stored in the file's dynamic table</td>
<td></td>
</tr>
<tr>
<td>--sysv</td>
<td></td>
<td>Generates SysV ELF output file</td>
<td>Section 8.12.4.3</td>
</tr>
</tbody>
</table>

### Table 8-10. Miscellaneous Options Summary

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>--linker_help</td>
<td>-help</td>
<td>Displays information about syntax and available options</td>
<td>–</td>
</tr>
<tr>
<td>--minimize_trampoline</td>
<td></td>
<td>Selects the trampoline minimization algorithm (argument is optional; algorithm</td>
<td>Section 8.4.31.2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>is postorder by default)</td>
<td></td>
</tr>
<tr>
<td>--preferred_order</td>
<td></td>
<td>Prioritizes placement of functions</td>
<td>Section 8.4.24</td>
</tr>
<tr>
<td>--strict_compatibility</td>
<td></td>
<td>Performs more conservative and rigorous compatibility checking of input object</td>
<td>Section 8.4.29</td>
</tr>
<tr>
<td></td>
<td></td>
<td>files</td>
<td></td>
</tr>
<tr>
<td>--trampoline_min_spacing</td>
<td></td>
<td>When trampoline reservations are spaced more closely than the specified limit,</td>
<td>Section 8.4.31.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>tries to make them adjacent</td>
<td></td>
</tr>
<tr>
<td>--zero_init</td>
<td></td>
<td>Controls preinitialization of uninitialized variables. Default is on.</td>
<td>Section 8.4.35</td>
</tr>
</tbody>
</table>
8.4.1 **Wildcards in File, Section, and Symbol Patterns**

The linker allows file, section, and symbol names to be specified using the asterisk (*) and question mark (?) wildcards. Using * matches any number of characters and using ? matches a single character. Using wildcards can make it easier to handle related objects, provided they follow a suitable naming convention.

For example:

- `mp3*.obj` /* matches anything .obj that begins with mp3 */
- `task?.o*` /* matches task1.obj, task2.obj, taskX.o55, etc. */

```c
SECTIONS
{
    .fast_code: { *.obj(*fast*) } > FAST_MEM
    .vectors : { vectors.obj(.vector:part1:*) } > 0xFFFFF00
    .str_code : { rts*.lib<str*.obj>(.text) } > S1ROM
}
```

8.4.2 **Specifying C/C++ Symbols with Linker Options**

The link-time symbol is the same as the C/C++ identifier name. The compiler does not prepend an underscore to the beginning of C/C++ identifiers.

See Section 8.6.1 for information about referring to linker symbols in C/C++ code.

8.4.3 **Relocation Capabilities (--absolute_exe and --relocatable Options)**

The linker performs relocation, which is the process of adjusting all references to a symbol when the symbol's address changes (Section 2.7).

The linker supports two options (--absolute_exe and --relocatable) that allow you to produce an absolute or a relocatable output module. The linker also supports a third option (-ar) that allows you to produce an executable, relocatable output module.

When the linker encounters a file that contains no relocation or symbol table information, it issues a warning message (but continues executing). Relinking an absolute file can be successful only if each input file contains no information that needs to be relocated (that is, each file has no unresolved references and is bound to the same virtual address that it was bound to when the linker created it).

8.4.3.1 **Producing an Absolute Output Module (--absolute_exe option)**

When you use the --absolute_exe option without the --relocatable option, the linker produces an absolute, executable output module. Absolute files contain no relocation information. Executable files contain the following:

- Special symbols defined by the linker (see Section 8.5.10.4)
- An header that describes information such as the program entry point
- No unresolved references

The following example links file1.obj and file2.obj and creates an absolute output module called a.out:

```bash
c16x --run_linker --absolute_exe file1.obj file2.obj
```

The --absolute_exe and --relocatable Options

**NOTE:** If you do not use the --absolute_exe or the --relocatable option, the linker acts as if you specified --absolute_exe.

8.4.3.2 **Producing a Relocatable Output Module (--relocatable option)**

When you use the --relocatable option, the linker retains relocation entries in the output module. If the output module is relocated (at load time) or relinked (by another linker execution), use --relocatable to retain the relocation entries.
The linker produces a file that is not executable when you use the --relocatable option without the --absolute_exe option. A file that is not executable does not contain special linker symbols or an optional header. The file can contain unresolved references, but these references do not prevent creation of an output module.

This example links file1.obj and file2.obj and creates a relocatable output module called a.out:

```
cl6x --run_linker --relocatable file1.obj file2.obj
```

The output file a.out can be relinked with other object files or relocated at load time. (Linking a file that will be relinked with other files is called partial linking. For more information, see Section 8.9.)

### 8.4.3.3 Producing an Executable, Relocatable Output Module (--ar Option)

If you invoke the linker with both the --absolute_exe and --relocatable options, the linker produces an executable, relocatable object module. The output file contains the special linker symbols, an optional header, and all resolved symbol references; however, the relocation information is retained.

This example links file1.obj and file2.obj to create an executable, relocatable output module called xr.out:

```
cl6x --run_linker --ar file1.obj file2.obj --output_file=xr.out
```

### 8.4.4 Allocate Memory for Use by the Loader to Pass Arguments (--arg_size Option)

The --arg_size option instructs the linker to allocate memory to be used by the loader to pass arguments from the command line of the loader to the program. The syntax of the --arg_size option is:

```
--arg_size= size
```

The `size` is the number of bytes to be allocated in target memory for command-line arguments.

By default, the linker creates the `__c_args__` symbol and sets it to -1. When you specify `--arg_size=size`, the following occur:

- The linker creates an uninitialized section named `.args` of `size` bytes.
- The `__c_args__` symbol contains the address of the `.args` section.

The loader and the target boot code use the `.args` section and the `__c_args__` symbol to determine whether and how to pass arguments from the host to the target program. See the *TMS320C6000 Optimizing Compiler User's Guide* for information about the loader.

### 8.4.5 Compression (--cinit_compression and --copy_compression Option)

By default, the linker does not compress data. These two options specify compression through the linker.

The --cinit_compression option specifies the compression type the linker applies to the C autoinitialization data. The default is rle.

Overlays can be managed by using linker-generated copy tables. To save ROM space the linker can compress the data copied by the copy tables. The compressed data is decompressed during copy. The --copy_compression option controls the compression of the copy data tables.

The syntax for the options are:

```
--cinit_compression[=compression_kind]
--copy_compression[=compression_kind]
```

The `compression_kind` can be one of the following types:

- **off**. Don't compress the data.
- **rle**. Compress data using Run Length Encoding.
- **lzss**. Compress data using Lempel-Ziv Storer and Symanski compression.
8.4.6 Compress DWARF Information (--compress_dwarf Option)

The --compress_dwarf option aggressively reduces the size of DWARF information by eliminating duplicate information from input object files. The --compress_dwarf option eliminates duplicate information that could not be removed through the use of ELF COMDAT groups. (See the ELF specification for information on COMDAT groups.)

8.4.7 Control Linker Diagnostics

The linker uses certain C/C++ compiler options to control linker-generated diagnostics. The diagnostic options must be specified before the --run_linker option.

--diag_error=num Categorize the diagnostic identified by num as an error. To find the numeric identifier of a diagnostic message, use the --display_error_number option first in a separate link. Then use --diag_error=num to recategorize the diagnostic as an error. You can only alter the severity of discretionary diagnostics.

--diag_remark=num Categorize the diagnostic identified by num as a remark. To find the numeric identifier of a diagnostic message, use the --display_error_number option first in a separate link. Then use --diag_remark=num to recategorize the diagnostic as a remark. You can only alter the severity of discretionary diagnostics.

--diag_suppress=num Suppress the diagnostic identified by num. To find the numeric identifier of a diagnostic message, use the --display_error_number option first in a separate link. Then use --diag_suppress=num to suppress the diagnostic. You can only suppress discretionary diagnostics.

--diag_warning=num Categorize the diagnostic identified by num as a warning. To find the numeric identifier of a diagnostic message, use the --display_error_number option first in a separate link. Then use --diag_warning=num to recategorize the diagnostic as a warning. You can only alter the severity of discretionary diagnostics.

--display_error_number Display a diagnostic's numeric identifier along with its text. Use this option in determining which arguments you need to supply to the diagnostic suppression options (--diag_suppress, --diag_error, --diag_remark, and --diag_warning). This option also indicates whether a diagnostic is discretionary. A discretionary diagnostic is one whose severity can be overridden. A discretionary diagnostic includes the suffix -D; otherwise, no suffix is present. See the TMS320C6000 Optimizing Compiler User's Guide for more information on understanding diagnostic messages.

--emit_warnings_as_errors Treat all warnings as errors. This option cannot be used with the --no_warnings option. The --diag_remark option takes precedence over this option. This option takes precedence over the --diag_warning option.

--issue_remarks Issue remarks (nonserious warnings), which are suppressed by default.

--no_warnings Suppress warning diagnostics (errors are still issued).

--set_error_limit=num Set the error limit to num, which can be any decimal value. The linker abandons linking after this number of errors. (The default is 100.)

--verbose_diagnostics Provide verbose diagnostics that display the original source with line-wrap and indicate the position of the error in the source line
8.4.8 Disable Automatic Library Selection (--disable_auto_rts Option)

The --disable_auto_rts option disables the automatic selection of a run-time-support library. See the TMS320C6000 Optimizing Compiler User's Guide for details on the automatic selection process.

8.4.9 Do Not Remove Unused Sections (--unused_section_elimination Option)

In order to minimize the footprint, the ELF linker does not include a section that is not needed to resolve any references in the final executable. Use --unused_section_elimination=off to disable this optimization. The syntax for the option is:

--unused_section_elimination[=on|off]

The linker default behavior is equivalent to --unused_section_elimination=on.

8.4.10 Linker Command File Preprocessing (--disable_pp, --define and --undefine Options)

The linker preprocesses linker command files using a standard C preprocessor. Therefore, the command files can contain well-known preprocessing directives such as #define, #include, and #if / #endif.

Three linker options control the preprocessor:

--disable_pp Disables preprocessing for command files
--define=name[=val] Predefines name as a preprocessor macro
--undefine=name Removes the macro name

The compiler has --define and --undefine options with the same meanings. However, the linker options are distinct; only --define and --undefine options specified after --run_linker are passed to the linker. For example:

c6x --define=FOO=1 main.c --run_linker --define=BAR=2 lnk.cmd

The linker sees only the --define for BAR; the compiler only sees the --define for FOO.

When one command file #includes another, preprocessing context is carried from parent to child in the usual way (that is, macros defined in the parent are visible in the child). However, when a command file is invoked other than through #include, either on the command line or by the typical way of being named in another command file, preprocessing context is not carried into the nested file. The exception to this is --define and --undefine options, which apply globally from the point they are encountered. For example:

--define GLOBAL
#define LOCAL
#include "incfile.cmd" /* sees GLOBAL and LOCAL */
nestfile.cmd /* only sees GLOBAL */

Two cautions apply to the use of --define and --undefine in command files. First, they have global effect as mentioned above. Second, since they are not actually preprocessing directives themselves, they are subject to macro substitution, probably with unintended consequences. This effect can be defeated by quoting the symbol name. For example:

--define MYSYM=123
--undefine MYSYM /* expands to --undefine 123 (!) */
--undefine "MYSYM" /* ahh, that's better */
The linker uses the same search paths to find #include files as it does to find libraries. That is, #include files are searched in the following places:

1. If the #include file name is in quotes (rather than <brackets>), in the directory of the current file
2. In the list of directories specified with --library options or environment variables (see Section 8.4.16)

There are two exceptions: relative pathnames (such as "./../name") always search the current directory; and absolute pathnames (such as "/usr/tools/name") bypass search paths entirely.

The linker provides the built-in macro definitions listed in Table 8-11. The availability of these macros within the linker is determined by the command-line options used, not the build attributes of the files being linked. If these macros are not set as expected, confirm that your project's command line uses the correct compiler option settings.

<table>
<thead>
<tr>
<th>Macro Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><em>DATE</em></td>
<td>Expands to the compilation date in the form mmm dd yyyy</td>
</tr>
<tr>
<td><em>FILE</em></td>
<td>Expands to the current source filename</td>
</tr>
<tr>
<td><em>TI_COMPILER_VERSION</em></td>
<td>Defined to a 7-9 digit integer, depending on if X has 1, 2, or 3 digits. The number does not contain a decimal. For example, version 3.2.1 is represented as 3002001. The leading zeros are dropped to prevent the number being interpreted as an octal.</td>
</tr>
<tr>
<td><em>TI_EABI</em></td>
<td>Defined to 1 if EABI is enabled; otherwise, it is undefined.</td>
</tr>
<tr>
<td><em>TIME</em></td>
<td>Expands to the compilation time in the form &quot;hh:mm:ss&quot;</td>
</tr>
<tr>
<td><em>TMS320C6X</em>_</td>
<td>Always defined</td>
</tr>
<tr>
<td><em>TMS320C6600</em></td>
<td>Defined to 1 if --silicon_version=6600; otherwise it is undefined.</td>
</tr>
<tr>
<td><em>TMS320C6740</em>_</td>
<td>Defined to 1 if --silicon_version=6740; otherwise it is undefined.</td>
</tr>
<tr>
<td><em>TMS320C64_PLUS</em>_</td>
<td>Defined to 1 if --silicon_version=6400+; otherwise it is undefined.</td>
</tr>
<tr>
<td><em>TMS320C6400_PLUS</em>_</td>
<td>Defined to 1 if --silicon_version=6400+; otherwise it is undefined; an alternate macro for <em>TMS320C64_PLUS</em>_</td>
</tr>
<tr>
<td><em>DSBT</em></td>
<td>Defined to 1 if --dsbt is specified (to use Dynamic Segment Base Table); otherwise it is undefined.</td>
</tr>
</tbody>
</table>

8.4.11 Error Correcting Code Testing (--ecc Options)

Error Correcting Codes (ECC) can be generated and placed in separate sections through the linker command file. ECC uses extra bits to allow errors to be detected and/or corrected by a device. The ECC support provided by the linker is compatible with the ECC support in TI Flash memory on various TI devices. TI Flash memory uses a modified Hamming(72,64) code, which uses 8 parity bits for every 64 bits. Check the documentation for your Flash memory to see if ECC is supported. (ECC for read-write memory is handled completely in hardware at run time.)

See Section 8.5.9 for details on linker command file syntax for ECC support.

To test ECC error detection and handling, you can use two command-line options that inject bit errors into the linked executable. These options let you specify an address where an error should appear and a bitmask of bits in the code/data at that address to flip. You can specify the address of the error absolutely or as an offset from a symbol.

When a data error is injected, the ECC parity bits for the data are calculated as if the error were not present. This simulates bit errors that might actually occur and test ECC's ability to correct different levels of errors.

The --ecc:data_error option injects errors into the load image at the specified location. The syntax is:

--ecc:data_error=(symbol+offset|address)[,page],bitmask

The address is the location of the minimum addressable unit where the error is to be injected. A symbol+offset can be used to specify the location of the error to be injected with a signed offset from that symbol. The page number is needed to make the location non-ambiguous if the address occurs on multiple memory pages. The bitmask is a mask of the bits to flip; its width should be the width of an addressable unit.
For example, the following command line flips the least-significant bit in the byte at the address 0x100, making it inconsistent with the ECC parity bits for that byte:
```
clex test.c --ecc:data_error=0x100,0x01 -z -o test.out
```

The following command flips two bits in the third byte of the code for main():
```
clex test.c --ecc:data_error=main+2,0x42 -z -o test.out
```

The `--ecc:ecc_error` option injects errors into the ECC parity bits that correspond to the specified location. Note that the ecc_error option can therefore only specify locations inside ECC input ranges, whereas the data_error option can also specify errors in the ECC output memory ranges. The syntax is:
```
--ecc:ecc_error=(symbol+offset|address)[,page],bitmask
```

The parameters for this option are the same as for `--ecc:data_error`, except that the `bitmask` must be exactly 8 bits. Mirrored copies of the affected ECC byte will also contain the same injected error.

An error injected into an ECC byte with `--ecc:ecc_error` may cause errors to be detected at run time in any of the 8 data bytes covered by that ECC byte.

For example, the following command flips every bit in the ECC byte that contains the parity information for the byte at 0x200:
```
clex test.c --ecc:ecc_error=0x200,0xff -z -o test.out
```

The linker disallows injecting errors into memory ranges that are neither an ECC range nor the input range for an ECC range. The compiler can only inject errors into initialized sections.

### 8.4.12 Define an Entry Point (`--entry_point` Option)

The memory address at which a program begins executing is called the **entry point**. When a loader loads a program into target memory, the program counter (PC) must be initialized to the entry point; the PC then points to the beginning of the program.

The linker can assign one of four values to the entry point. These values are listed below in the order in which the linker tries to use them. If you use one of the first three values, it must be an external symbol in the symbol table.

- **The value specified by the `--entry_point` option.**
  - Syntax:
    ```
    --entry_point=global_symbol
    ```
  - Where `global_symbol` defines the entry point and must be defined as an external symbol of the input files. The external symbol name of C or C++ objects may be different than the name declared in the source language; refer to the [TMS320C6000 Optimizing Compiler User's Guide](#).

- **The value of symbol _c_int00 (if present).**
  - Must be the entry point if you are linking code produced by the C compiler.

- **The value of symbol _main (if present)**

- **0 (default value)**

This example links file1.obj and file2.obj. The symbol begin is the entry point; begin must be defined as external in file1 or file2.
```
clex --run_linker --entry_point=begin file1.obj file2.obj
```

See Section 8.6.1 for information about referring to linker symbols in C/C++ code.

### 8.4.13 Set Default Fill Value (`--fill_value` Option)

The `--fill_value` option fills the holes formed within output sections. The syntax for the option is:
```
--fill_value=value
```

- **`value`** is a 32-bit constant (up to eight hexadecimal digits). If you do not use `--fill_value`, the linker uses 0 as the default fill value.

This example fills holes with the hexadecimal value ABCDABCD:
```
clex --run_linker --fill_value=0xABCDABCD file1.obj file2.obj
```
8.4.14 Define Heap Size (--heap_size Option)

The C/C++ compiler uses an uninitialized section called .sysmem for the C run-time memory pool used by malloc(). You can set the size of this memory pool at link time by using the --heap_size option. The syntax for the --heap_size option is:

```
--heap_size= size
```

The size must be a constant. This example defines a 4K byte heap:

```
cl6x --run_linker --heap_size=0x1000 /* defines a 4k heap (.sysmem section)*/
```

The linker creates the .sysmem section only if there is a .sysmem section in an input file.

The linker also creates a global symbol __TI_SYSMEM_SIZE and assigns it a value equal to the size of the heap. The default size is 1K bytes. See Section 8.6.1 for information about referring to linker symbols in C/C++ code. For more about C/C++ linking, see Section 8.10.

8.4.15 Hiding Symbols

Symbol hiding prevents the symbol from being listed in the output file's symbol table. While localization is used to prevent name space clashes in a link unit, symbol hiding is used to obscure symbols which should not be visible outside a link unit. Such symbol’s names appear only as empty strings or “no name” in object file readers. The linker supports symbol hiding through the --hide and --unhide options.

The syntax for these options are:

```
--hide=' pattern '
--unhide=' pattern '
```

The pattern is a string with optional wildcards ? or *. Use ? to match a single character and use * to match zero or more characters.

The --hide option hides global symbols with a linkname matching the pattern. It hides symbols matching the pattern by changing the name to an empty string. A global symbol that is hidden is also localized.

The --unhide option reveals (un-hides) global symbols that match the pattern that are hidden by the --hide option. The --unhide option excludes symbols that match pattern from symbol hiding provided the pattern defined by --unhide is more restrictive than the pattern defined by --hide.

These options have the following properties:

- The --hide and --unhide options can be specified more than once on the command line.
- The order of --hide and --unhide has no significance.
- A symbol is matched by only one pattern defined by either --hide or --unhide.
- A symbol is matched by the most restrictive pattern. Pattern A is considered more restrictive than Pattern B, if Pattern A matches a narrower set than Pattern B.
- It is an error if a symbol matches patterns from --hide and --unhide and one does not supersede the other. Pattern A supersedes pattern B if A can match everything B can and more. If Pattern A supersedes Pattern B, then Pattern B is said to more restrictive than Pattern A.
- These options affect final and partial linking.

In map files these symbols are listed under the Hidden Symbols heading.
8.4.16 Alter the Library Search Algorithm (--library Option, --search_path Option, and C6X_C_DIR Environment Variable)

Usually, when you want to specify a file as linker input, you simply enter the filename; the linker looks for the file in the current directory. For example, suppose the current directory contains the library object.lib. If this library defines symbols that are referenced in the file file1.obj, this is how you link the files:

```
cl6x --run_linker file1.obj object.lib
```

If you want to use a file that is not in the current directory, use the --library linker option. The --library option’s short form is -l. The syntax for this option is:

```
--library=[pathname] filename
```

The `filename` is the name of an archive, an object file, or linker command file. You can specify up to 128 search paths.

The --library option is not required when one or more members of an object library are specified for input to an output section. For more information about allocating archive members, see Section 8.5.5.5.

You can augment the linker’s directory search algorithm by using the --search_path linker option or the C6X_C_DIR environment variable. The linker searches for object libraries and command files in the following order:

1. It searches directories named with the --search_path linker option. The --search_path option must appear before the --library option on the command line or in a command file.
2. It searches directories named with C6X_C_DIR.
3. If C6X_C_DIR is not set, it searches directories named with the assembler’s C6X_A_DIR environment variable.
4. It searches the current directory.

8.4.16.1 Name an Alternate Library Directory (--search_path Option)

The --search_path option names an alternate directory that contains input files. The --search_path option’s short form is -I. The syntax for this option is:

```
--search_path= pathname
```

The `pathname` names a directory that contains input files.

When the linker is searching for input files named with the --library option, it searches through directories named with --search_path first. Each --search_path option specifies only one directory, but you can have several --search_path options per invocation. When you use the --search_path option to name an alternate directory, it must precede any --library option used on the command line or in a command file.

For example, assume that there are two archive libraries called r.lib and lib2.lib that reside in ld and ld2 directories. The table below shows the directories that r.lib and lib2.lib reside in, how to set environment variables, and how to use both libraries during a link. Select the row for your operating system:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Enter</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne shell)</td>
<td>cl6x --run_linker f1.obj f2.obj --search_path=/ld --search_path=/ld2 --library=r.lib --library=lib2.lib</td>
</tr>
<tr>
<td>Windows</td>
<td>cl6x --run_linker f1.obj f2.obj --search_path\ld --search_path\ld2 --library=r.lib --library=lib2.lib</td>
</tr>
</tbody>
</table>
**8.4.16.2 Name an Alternate Library Directory (C6X_C_DIR Environment Variable)**

An environment variable is a system symbol that you define and assign a string to. The linker uses an environment variable named C6X_C_DIR to name alternate directories that contain object libraries. The command syntaxes for assigning the environment variable are:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Enter</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne shell)</td>
<td>C6X_C_DIR=&quot;pathname; pathname; ...&quot;; export C6X_C_DIR</td>
</tr>
<tr>
<td>Windows</td>
<td>set C6X_C_DIR= pathname; pathname; ...</td>
</tr>
</tbody>
</table>

The *pathnames* are directories that contain input files. Use the --library linker option on the command line or in a command file to tell the linker which library or linker command file to search for. The pathnames must follow these constraints:

- Pathnames must be separated with a semicolon.
- Spaces or tabs at the beginning or end of a path are ignored. For example the space before and after the semicolon in the following is ignored:
  ```
  set C6X_C_DIR= c:\path\one\to\tools ; c:\path\two\to\tools
  ```
- Spaces and tabs are allowed within paths to accommodate Windows directories that contain spaces. For example, the pathnames in the following are valid:
  ```
  set C6X_C_DIR=c:\first path\to\tools;d:\second path\to\tools
  ```

In the example below, assume that two archive libraries called r.lib and lib2.lib reside in ld and ld2 directories. The table below shows how to set the environment variable, and how to use both libraries during a link. Select the row for your operating system:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Invocation Command</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne shell)</td>
<td>C6X_C_DIR=&quot;/ld ;/ld2&quot;; export C6X_C_DIR; cl6x --run linker f1.obj f2.obj --library=r.lib --library=lib2.lib</td>
</tr>
<tr>
<td>Windows</td>
<td>cl6x --run linker f1.obj f2.obj --library=r.lib --library=lib2.lib</td>
</tr>
</tbody>
</table>

The environment variable remains set until you reboot the system or reset the variable by entering:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>Enter</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNIX (Bourne shell)</td>
<td>unset C6X_C_DIR</td>
</tr>
<tr>
<td>Windows</td>
<td>set C6X_C_DIR=</td>
</tr>
</tbody>
</table>

The assembler uses an environment variable named C6X_A_DIR to name alternate directories that contain copy/include files or macro libraries. If C6X_C_DIR is not set, the linker searches for object libraries in the directories named with C6X_A_DIR. For information about C6X_A_DIR, see Section 4.5.2. For more information about object libraries, see Section 8.6.3.

**8.4.16.3 Exhaustively Read and Search Libraries (--reread.libs and --priority Options)**

There are two ways to exhaustively search for unresolved symbols:

- Reread libraries if you cannot resolve a symbol reference (--reread.libs).
- Search libraries in the order that they are specified (--priority).

The linker normally reads input files, including archive libraries, only once when they are encountered on the command line or in the command file. When an archive is read, any members that resolve references to undefined symbols are included in the link. If an input file later references a symbol defined in a previously read archive library, the reference is not resolved.
With the --reread_libs option, you can force the linker to reread all libraries. The linker rereads libraries until no more references can be resolved. Linking using --reread_libs may be slower, so you should use it only as needed. For example, if a.lib contains a reference to a symbol defined in b.lib, and b.lib contains a reference to a symbol defined in a.lib, you can resolve the mutual dependencies by listing one of the libraries twice, as in:

```
c16x --run_linker --library=a.lib --library=b.lib --library=a.lib
```

or you can force the linker to do it for you:

```
c16x --run_linker --reread_libs --library=a.lib --library=b.lib
```

The --priority option provides an alternate search mechanism for libraries. Using --priority causes each unresolved reference to be satisfied by the first library that contains a definition for that symbol. For example:

```
objfile references A
lib1 defines B
lib2 defines A, B; obj defining A references B
```

% c16x --run_linker objfile lib1 lib2

Under the existing model, objfile resolves its reference to A in lib2, pulling in a reference to B, which resolves to the B in lib2.

Under --priority, objfile resolves its reference to A in lib2, pulling in a reference to B, but now B is resolved by searching the libraries in order and resolves B to the first definition it finds, namely the one in lib1.

The --priority option is useful for libraries that provide overriding definitions for related sets of functions in other libraries without having to provide a complete version of the whole library.

For example, suppose you want to override versions of malloc and free defined in the rts6600_elf.lib without providing a full replacement for rts6600_elf.lib. Using --priority and linking your new library before rts6600_elf.lib guarantees that all references to malloc and free resolve to the new library.

The --priority option is intended to support linking programs with SYS/BIOS where situations like the one illustrated above occur.

### 8.4.17 Change Symbol Localization

Symbol localization changes symbol linkage from global to local (static). This is used to obscure global symbols in a library which should not be visible outside the library, but must be global because they are accessed by several modules in the library. The linker supports symbol localization through the --localize and --globalize linker options.

The syntax for these options are:

```
--localize=' pattern '
--globalize=' pattern '
```

The `pattern` is a string with optional wildcards ? or *. Use ? to match a single character and use * to match zero or more characters.

The --localize option changes the symbol linkage to local for symbols matching the `pattern`.

The --globalize option changes the symbol linkage to global for symbols matching the `pattern`. The --globalize option only affects symbols that are localized by the --localize option. The --globalize option excludes symbols that match the pattern from symbol localization, provided the pattern defined by --globalize is more restrictive than the pattern defined by --localize.

See Section 8.4.2 for information about using C/C++ identifiers in linker options such as --localize and --globalize.

These options have the following properties:

- The --localize and --globalize options can be specified more than once on the command line.
- The order of --localize and --globalize options has no significance.
- A symbol is matched by only one pattern defined by either --localize or --globalize.
- A symbol is matched by the most restrictive pattern. Pattern A is considered more restrictive than
Pattern B, if Pattern A matches a narrower set than Pattern B.

- It is an error if a symbol matches patterns from --localize and --globalize and if one does not supersede other. Pattern A supersedes pattern B if A can match everything B can, and some more. If Pattern A supersedes Pattern B, then Pattern B is said to be more restrictive than Pattern A.
- These options affect final and partial linking.

In map files these symbols are listed under the Localized Symbols heading.

8.4.17.1 Make All Global Symbols Static (--make_static Option)

The --make_static option makes all global symbols static. Static symbols are not visible to externally linked modules. By making global symbols static, global symbols are essentially hidden. This allows external symbols with the same name (in different files) to be treated as unique.

The --make_static option effectively nullifies all .global assembler directives. All symbols become local to the module in which they are defined, so no external references are possible. For example, assume file1.obj and file2.obj both define global symbols called EXT. By using the --make_static option, you can link these files without conflict. The symbol EXT defined in file1.obj is treated separately from the symbol EXT defined in file2.obj.

cl6x --run_linker --make_static file1.obj file2.obj

The --make_static option makes all global symbols static. If you have a symbol that you want to remain global and you use the --make_static option, you can use the --make_global option to declare that symbol to be global. The --make_global option overrides the effect of the --make_static option for the symbol that you specify. The syntax for the --make_global option is:

--make_global= global_symbol

8.4.18 Create a Map File (--map_file Option)

The syntax for the --map_file option is:

--map_file= filename

The linker map describes:
- Memory configuration
- Input and output section allocation
- Linker-generated copy tables
- Trampolines
- The addresses of external symbols after they have been relocated
- Hidden and localized symbols

The map file contains the name of the output module and the entry point; it can also contain up to three tables:
- A table showing the new memory configuration if any nondefault memory is specified (memory configuration). The table has the following columns; this information is generated on the basis of the information in the MEMORY directive in the linker command file:
  - **Name.** This is the name of the memory range specified with the MEMORY directive.
  - **Origin.** This specifies the starting address of a memory range.
  - **Length.** This specifies the length of a memory range.
  - **Unused.** This specifies the total amount of unused (available) memory in that memory area.
  - **Attributes.** This specifies one to four attributes associated with the named range:
    - **R** specifies that the memory can be read.
    - **W** specifies that the memory can be written to.
    - **X** specifies that the memory can contain executable code.
    - **I** specifies that the memory can be initialized.
For more information about the MEMORY directive, see Section 8.5.4.

- A table showing the linked addresses of each output section and the input sections that make up the output sections (section placement map). This table has the following columns; this information is generated on the basis of the information in the SECTIONS directive in the linker command file:
  - **Output section.** This is the name of the output section specified with the SECTIONS directive.
  - **Origin.** The first origin listed for each output section is the starting address of that output section. The indented origin value is the starting address of that portion of the output section.
  - **Length.** The first length listed for each output section is the length of that output section. The indented length value is the length of that portion of the output section.
  - **Attributes/input sections.** This lists the input file or value associated with an output section. If the input section could not be allocated, the map file will indicate this with "FAILED TO ALLOCATE".

For more information about the SECTIONS directive, see Section 8.5.5.

- A table showing each external symbol and its address sorted by symbol name.
- A table showing each external symbol and its address sorted by symbol address.

The following example links file1.obj and file2.obj and creates a map file called map.out:

```
c16x --run_linker file1.obj file2.obj --map_file=map.out
```

Example 8-26 shows an example of a map file.

### 8.4.19 Managing Map File Contents (--mapfile_contents Option)

The --mapfile_contents option assists with managing the content of linker-generated map files. The syntax for the --mapfile_contents option is:

```
--mapfile_contents=[filter[, filter]]
```

When the --map_file option is specified, the linker produces a map file containing information about memory usage, placement information about sections that were created during a link, details about linker-generated copy tables, and symbol values.

The --mapfile_contents option provides a mechanism for you to control what information is included in or excluded from a map file. When you specify --mapfile_contents=help from the command line, a help screen listing available filter options is displayed. The following filter options are available:

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Description</th>
<th>Default State</th>
</tr>
</thead>
<tbody>
<tr>
<td>copytables</td>
<td>Copy tables</td>
<td>On</td>
</tr>
<tr>
<td>entry</td>
<td>Entry point</td>
<td>On</td>
</tr>
<tr>
<td>load_addr</td>
<td>Display load addresses</td>
<td>Off</td>
</tr>
<tr>
<td>memory</td>
<td>Memory ranges</td>
<td>On</td>
</tr>
<tr>
<td>modules</td>
<td>Module view</td>
<td>On</td>
</tr>
<tr>
<td>sections</td>
<td>Sections</td>
<td>On</td>
</tr>
<tr>
<td>sym_defs</td>
<td>Defined symbols per file</td>
<td>Off</td>
</tr>
<tr>
<td>sym_dp</td>
<td>Symbols sorted by data page</td>
<td>On</td>
</tr>
<tr>
<td>sym_name</td>
<td>Symbols sorted by name</td>
<td>On</td>
</tr>
<tr>
<td>sym_runaddr</td>
<td>Symbols sorted by run address</td>
<td>On</td>
</tr>
<tr>
<td>all</td>
<td>Enables all attributes</td>
<td></td>
</tr>
<tr>
<td>none</td>
<td>Disables all attributes</td>
<td></td>
</tr>
</tbody>
</table>

The --mapfile_contents option controls display filter settings by specifying a comma-delimited list of display attributes. When prefixed with the word no, an attribute is disabled instead of enabled. For example:

```
--mapfile_contents=copytables,noentry
--mapfile_contents=all,nocopytables
--mapfile_contents=none,entry
```
By default, those sections that are currently included in the map file when the --map_file option is specified are included. The filters specified in the --mapfile_contents options are processed in the order that they appear in the command line. In the third example above, the first filter, none, clears all map file content. The second filter, entry, then enables information about entry points to be included in the generated map file. That is, when --mapfile_contents=none,entry is specified, the map file contains only information about entry points.

The load_addr and sym_defs attributes are both disabled by default.

If you turn on the load_addr filter, the map file includes the load address of symbols that are included in the symbol list in addition to the run address (if the load address is different from the run address).

You can use the sym_defs filter to include information sorted on a file by file basis. You may find it useful to replace the sym_name, sym_dp, and sym_runaddr sections of the map file with the sym_defs section by specifying the following --mapfile_contents option:

```
--mapfile_contents=nosym_name,nosym_dp,nosym_runaddr,sym_defs
```

By default, information about global symbols defined in an application are included in tables sorted by name, data page, and run address. If you use the --mapfile_contents=sym_defs option, static variables are also listed.

### 8.4.20 Disable Name Demangling (--no_demangle)

By default, the linker uses demangled symbol names in diagnostics. For example:

```
undefined symbol  first referenced in file
ANewClass::getValue()       test.obj
```

The --no_demangle option disables the demangling of symbol names in diagnostics. For example:

```
undefined symbol  first referenced in file
_ZN9ANewClass8getValueEv       test.obj
```

### 8.4.21 Merging of Symbolic Debugging Information

By default, the linker eliminates duplicate entries of symbolic debugging information. Such duplicate information is commonly generated when a C program is compiled for debugging. For example:

```
- [ header.h ]-
typedef struct
{  
  <define some structure members>
} XYZ;

- [ f1.c ]-
#include "header.h"
...

- [ f2.c ]-
#include "header.h"
...
```

When these files are compiled for debugging, both f1.obj and f2.obj have symbolic debugging entries to describe type XYZ. For the final output file, only one set of these entries is necessary. The linker eliminates the duplicate entries automatically.
8.4.22 Strip Symbolic Information (--no_symtable Option)

The --no_symtable option creates a smaller output module by omitting symbol table information and line number entries. The --no_sym_table option is useful for production applications when you do not want to disclose symbolic information to the consumer.

This example links file1.obj and file2.obj and creates an output module, stripped of line numbers and symbol table information, named nosym.out:

```
cl6x --run_linker --output_file=nosym.out --no_symtable file1.obj file2.obj
```

Using the --no_symtable option limits later use of a symbolic debugger.

---

NOTE: The --no_symtable option is deprecated. To remove symbol table information, use the strip6x utility as described in Section 9.4.

---

8.4.23 Name an Output Module (--output_file Option)

The linker creates an output module when no errors are encountered. If you do not specify a filename for the output module, the linker gives it the default name a.out. If you want to write the output module to a different file, use the --output_file option. The syntax for the --output_file option is:

```
--output_file= filename
```

The `filename` is the new output module name.

This example links file1.obj and file2.obj and creates an output module named run.out:

```
cl6x --run_linker --output_file=run.out file1.obj file2.obj
```

8.4.24 Prioritizing Function Placement (--preferred_order Option)

The compiler prioritizes the placement of a function relative to others based on the order in which --preferred_order options are encountered during the linker invocation. The syntax is:

```
--preferred_order= function specification
```

Refer to the *TMS320C6000 Optimizing Compiler User's Guide* for details on the program cache layout tool, which is impacted by --preferred_option.

8.4.25 C Language Options (--ram_model and --rom_model Options)

The --ram_model and --rom_model options cause the linker to use linking conventions that are required by the C compiler.

- The --ram_model option tells the linker to initialize variables at load time.
- The --rom_model option tells the linker to autoinitalize variables at run time.

For more information, see Section 8.10, Section 3.3.2.1, and Section 3.3.2.2.
8.4.26 Retain Discarded Sections (--retain Option)

When --unused_section_elimination is on, the ELF linker does not include a section in the final link if it is not needed in the executable to resolve references. The --retain option tells the linker to retain a list of sections that would otherwise not be retained. This option accepts the wildcards '*' and '?'. When wildcards are used, the argument should be in quotes. The syntax for this option is:

```
--retain=sym_or_scn_spec
```

The --retain option take one of the following forms:

- **--retain= symbol_spec**
  
  Specifying the symbol format retains sections that define symbol_spec. For example, this code retains sections that define symbols that start with init:
  
  ```
  --retain=init*
  ```
  
  You cannot specify --retain=''.

- **--retain= file_spec[scn_spec, scn_spec, ...]**
  
  Specifying the file format retains sections that match one or more scn_spec from files matching the file_spec. For example, this code retains .intvec sections from all input files:
  
  ```
  --retain=*.int*'
  ```
  
  You can specify --retain='(*)' to retain all sections from all input files. However, this does not prevent sections from library members from being optimized out.

- **--retain= ar_spec<mem_spec, [mem_spec, ...]>(scn_spec[scn_spec, scn_spec, ...])**

  Specifying the archive format retains sections matching one or more scn_spec from members matching one or more mem_spec from archive files matching ar_spec. For example, this code retains the .text sections from printf.obj in the rts64plus_eabi.lib library:
  
  ```
  --retain=rts64plus_eabi.lib<printf.obj>(.text)
  ```

  If the library is specified with the --library option (--library=rts64plus_eabi.lib) the library search path is used to search for the library. You cannot specify '<<(*)'.

8.4.27 Scan All Libraries for Duplicate Symbol Definitions (--scan_libraries)

The --scan_libraries option scans all libraries during a link looking for duplicate symbol definitions to those symbols that are actually included in the link. The scan does not consider absolute symbols or symbols defined in COMDAT sections. The --scan_libraries option helps determine those symbols that were actually chosen by the linker over other existing definitions of the same symbol in a library.

The library scanning feature can be used to check against unintended resolution of a symbol reference to a definition when multiple definitions are available in the libraries.

8.4.28 Define Stack Size (--stack_size Option)

The TMS320C6000 C/C++ compiler uses an uninitialized section, .stack, to allocate space for the run-time stack. You can set the size of this section in bytes at link time with the --stack_size option. The syntax for the --stack_size option is:

```
--stack_size= size
```

The size must be a constant and is in bytes. This example defines a 4K byte stack:

```
c16x --run_linker --stack_size=0x1000 /* defines a 4K heap (.stack section)*/
```

If you specified a different stack size in an input section, the input section stack size is ignored. Any symbols defined in the input section remain valid; only the stack size is different.

When the linker defines the .stack section, it also defines a global symbol, __TI_STACK_SIZE, and assigns it a value equal to the size of the section. The default software stack size is 1K bytes. See Section 8.6.1 for information about referring to linker symbols in C/C++ code.
8.4.29 Enforce Strict Compatibility (--strict_compatibility Option)

The linker performs more conservative and rigorous compatibility checking of input object files when you specify the --strict_compatibility option. Using this option guards against additional potential compatibility issues, but may signal false compatibility errors when linking in object files built with an older toolset, or with object files built with another compiler vendor's toolset. To avoid issues with legacy libraries, the --strict_compatibility option is turned off by default.

8.4.30 Mapping of Symbols (--symbol_map Option)

Symbol mapping allows a symbol reference to be resolved by a symbol with a different name. Symbol mapping allows functions to be overridden with alternate definitions. This feature can be used to patch in alternate implementations, which provide patches (bug fixes) or alternate functionality. The syntax for the -symbol_map option is:

```
--symbol_map= refname=defname
```

For example, the following code makes the linker resolve any references to foo by the definition foo_patch:
```
--symbol_map='foo=foo_patch'
```

8.4.31 Generate Far Call Trampolines (--trampolines Option)

The C6000 device has PC-relative call and PC-relative branch instructions whose range is smaller than the entire address space. When these instructions are used, the destination address must be near enough to the instruction that the difference between the call and the destination fits in the available encoding bits. If the called function is too far away from the calling function, the linker generates an error.

The alternative to a PC-relative call is an absolute call, which is often implemented as an indirect call: load the called address into a register, and call that register. This is often undesirable because it takes more instructions (speed- and size-wise) and requires an extra register to contain the address.

By default, the compiler generates near calls. The --trampolines option causes the linker to generate a trampoline code section for each call that is linked out-of-range of its called destination. The trampoline code section contains a sequence of instructions that performs a transparent long branch to the original called address. Each calling instruction that is out-of-range from the called function is redirected to the trampoline.

For example, in a section of C code the bar function calls the foo function. The compiler generates this code for the function:
```
bar:
    ...
    call foo ; call the function "foo"
    ...
```

If the foo function is placed out-of-range from the call to foo that is inside of bar, then with --trampolines the linker changes the original call to foo into a call to foo_trampoline as shown:
```
bar:
    ...
    call foo_trampoline ; call a trampoline for foo
    ...
```

The above code generates a trampoline code section called foo_trampoline, which contains code that executes a long branch to the original called function, foo. For example:
```
foo_trampoline:
    branch_long foo
```

Trampolines can be shared among calls to the same called function. The only requirement is that all calls to the called function be linked near the called function's trampoline.

The syntax for this option is:

```
--trampolines=[on|off]
```

The default setting is on. For C6000, trampolines are turned on by default.
When the linker produces a map file (the --map_file option) and it has produced one or more trampolines, then the map file will contain statistics about what trampolines were generated to reach which functions. A list of calls for each trampoline is also provided in the map file.

The Linker Assumes B15 Contains the Stack Pointer

NOTE: Assembly language programmers must be aware that the linker assumes B15 contains the stack pointer. The linker must save and restore values on the stack in trampoline code that it generates. If you do not use B15 as the stack pointer, you should use the linker option that disables trampolines, --trampolines=off. Otherwise, trampolines could corrupt memory and overwrite register values.

8.4.31.1 Advantages and Disadvantages of Using Trampolines

The advantage of using trampolines is that you can treat all calls as near calls, which are faster and more efficient. You will only need to modify those calls that don't reach. In addition, there is little need to consider the relative placement of functions that call each other. Cases where calls must go through a trampoline are less common than near calls.

While generating far call trampolines provides a more straightforward solution, trampolines have the disadvantage that they are somewhat slower than directly calling a function. They require both a call and a branch. Additionally, while inline code could be tailored to the environment of the call, trampolines are generated in a more general manner, and may be slightly less efficient than inline code.

An alternative method to creating a trampoline code section for a call that cannot reach its called function is to actually modify the source code for the call. In some cases this can be done without affecting the size of the code. However, in general, this approach is extremely difficult, especially when the size of the code is affected by the transformation.

8.4.31.2 Minimizing the Number of Trampolines Required (--minimize_trampolines Option)

The --minimize_trampolines option attempts to place sections so as to minimize the number of far call trampolines required, possibly at the expense of optimal memory packing. The syntax is:

```
--minimize_trampolines=postorder
```

The argument selects a heuristic to use. The postorder heuristic attempts to place functions before their callers, so that the PC-relative offset to the callee is known when the caller is placed. By placing the callee first, its address is known when the caller is placed so the linker can definitively know if a trampoline is required.

8.4.31.3 Making Trampoline Reservations Adjacent (--trampoline_min_spacing Option)

When a call is placed and the callee's address is unknown, the linker must provisionally reserve space for a far call trampoline in case the callee turns out to be too far away. Even if the callee ends up being close enough, the trampoline reservation can interfere with optimal placement for very large code sections.

When trampoline reservations are spaced more closely than the specified limit, use the --trampoline_min_spacing option to try to make them adjacent. The syntax is:

```
--trampoline_min_spacing=size
```

A higher value minimizes fragmentation, but may result in more trampolines. A lower value may reduce trampolines, at the expense of fragmentation and linker running time. Specifying 0 for this option disables coalescing. The default is 16K.

8.4.31.4 Carrying Trampolines From Load Space to Run Space

It is sometimes useful to load code in one location in memory and run it in another. The linker provides the capability to specify separate load and run allocations for a section. The burden of actually copying the code from the load space to the run space is left to you.
A copy function must be executed before the real function can be executed in its run space. To facilitate this copy function, the assembler provides the .label directive, which allows you to define a load-time address. These load-time addresses can then be used to determine the start address and size of the code to be copied. However, this mechanism will not work if the code contains a call that requires a trampoline to reach its called function. This is because the trampoline code is generated at link time, after the load-time addresses associated with the .label directive have been defined. If the linker detects the definition of a .label symbol in an input section that contains a trampoline call, then a warning is generated.

To solve this problem, you can use the START(), END(), and SIZE() operators (see Section 8.5.10.7). These operators allow you to define symbols to represent the load-time start address and size inside the linker command file. These symbols can be referenced by the copy code, and their values are not resolved until link time, after the trampoline sections have been allocated.

Here is an example of how you could use the START() and SIZE() operators in association with an output section to copy the trampoline code section along with the code containing the calls that need trampolines:

```
SECTIONS
{ .foo : load = ROM, run = RAM, start(foo_start), size(foo_size)
    { x.obj(.text) }
    .text: {} > ROM
    .far: { --library=rts.lib(.text) } > FAR_MEM
}
```

A function in x.obj contains an run-time-support call. The run-time-support library is placed in far memory and so the call is out-of-range. A trampoline section will be added to the .foo output section by the linker. The copy code can refer to the symbols foo_start and foo_size as parameters for the load start address and size of the entire .foo output section. This allows the copy code to copy the trampoline section along with the original x.obj code in .text from its load space to its run space.

See Section 8.6.1 for information about referring to linker symbols in C/C++ code.

### 8.4.32 Introduce an Unresolved Symbol (--undef_sym Option)

The --undef_sym option introduces the linkname for an unresolved symbol into the linker's symbol table. This forces the linker to search a library and include the member that defines the symbol. The linker must encounter the --undef_sym option before it links in the member that defines the symbol. The syntax for the --undef_sym option is:

```
--undef_sym= symbol
```

For example, suppose a library named rts6600_elf.lib contains a member that defines the symbol symtab; none of the object files being linked reference symtab. However, suppose you plan to relink the output module and you want to include the library member that defines symtab in this link. Using the --undef_sym option as shown below forces the linker to search rts6600_elf.lib for the member that defines symtab and to link in the member.

```
c16x --run_linker --undef_sym=symtab file1.obj file2.obj rts6600_elf.lib
```

If you do not use --undef_sym, this member is not included, because there is no explicit reference to it in file1.obj or file2.obj.

### 8.4.33 Display a Message When an Undefined Output Section Is Created (--warn_sections)

In a linker command file, you can set up a SECTIONS directive that describes how input sections are combined into output sections. However, if the linker encounters one or more input sections that do not have a corresponding output section defined in the SECTIONS directive, the linker combines the input sections that have the same name into an output section with that name. By default, the linker does not display a message to tell you that this occurred.

You can use the --warn_sections option to cause the linker to display a message when it creates a new output section.

For more information about the SECTIONS directive, see Section 8.5.5. For more information about the default actions of the linker, see Section 8.7.
8.4.34 Generate XML Link Information File (--xml_link_info Option)

The linker supports the generation of an XML link information file through the --xml_link_info=file option. This option causes the linker to generate a well-formed XML file containing detailed information about the result of a link. The information included in this file includes all of the information that is currently produced in a linker generated map file. See Appendix B for specifics on the contents of the generated XML file.

8.4.35 Zero Initialization (--zero_init Option)

The C and C++ standards require that global and static variables that are not explicitly initialized must be set to 0 before program execution. The C/C++ compiler supports preinitialization of uninitialized variables by default. To turn this off, specify the linker option --zero_init=off.

The syntax for the --zero_init option is:

```
--zero_init[=on|off]
```

Disabling Zero Initialization Not Recommended

**NOTE:** In general, this option it is not recommended. If you turn off zero initialization, automatic initialization of uninitialized global and static objects to zero will not occur. You are then expected to initialize these variables to zero in some other manner.
8.5 Linker Command Files

Linker command files allow you to put linker options and directives in a file; this is useful when you invoke the linker often with the same options and directives. Linker command files are also useful because they allow you to use the MEMORY and SECTIONS directives to customize your application. You must use these directives in a command file; you cannot use them on the command line.

Linker command files are ASCII files that contain one or more of the following:

- Input filenames, which specify object files, archive libraries, or other command files. (If a command file calls another command file as input, this statement must be the last statement in the calling command file. The linker does not return from called command files.)
- Linker options, which can be used in the command file in the same manner that they are used on the command line
- The MEMORY and SECTIONS linker directives. The MEMORY directive defines the target memory configuration (see Section 8.5.4). The SECTIONS directive controls how sections are built and allocated (see Section 8.5.5.)
- Assignment statements, which define and assign values to global symbols

To invoke the linker with a command file, enter the `cl6x --run_linker` command and follow it with the name of the command file:

```
cl6x --run_linker command_filename
```

The linker processes input files in the order that it encounters them. If the linker recognizes a file as an object file, it links the file. Otherwise, it assumes that a file is a command file and begins reading and processing commands from it. Command filenames are case sensitive, regardless of the system used.

Example 8-1 shows a sample linker command file called link.cmd.

### Example 8-1. Linker Command File

```
a.obj /* First input filename */
b.obj /* Second input filename */
--output_file=prog.out /* Option to specify output file */
--map_file=prog.map /* Option to specify map file */
```

The sample file in Example 8-1 contains only filenames and options. (You can place comments in a command file by delimiting them with /* and */.) To invoke the linker with this command file, enter:

```
cl6x --run_linker link.cmd
```

You can place other parameters on the command line when you use a command file:

```
cl6x --run_linker --relocatable link.cmd c.obj d.obj
```

The linker processes the command file as soon as it encounters the filename, so a.obj and b.obj are linked into the output module before c.obj and d.obj.

You can specify multiple command files. If, for example, you have a file called names.lst that contains filenames and another file called dir.cmd that contains linker directives, you could enter:

```
cl6x --run_linker names.lst dir.cmd
```

One command file can call another command file; this type of nesting is limited to 16 levels. If a command file calls another command file as input, this statement must be the last statement in the calling command file.

Blanks and blank lines are insignificant in a command file except as delimiters. This also applies to the format of linker directives in a command file. Example 8-2 shows a sample command file that contains linker directives.
Example 8-2. Command File With Linker Directives

```
a.obj b.obj c.obj /* Input filenames */
--output_file=prog.out /* Options */
--map_file=prog.map

MEMORY /* MEMORY directive */
{
    FAST_MEM: origin = 0x0100 length = 0x0100
    SLOW_MEM: origin = 0x7000 length = 0x1000
}

SECTIONS /* SECTIONS directive */
{
    .text: > SLOW_MEM
    .data: > SLOW_MEM
    .bss: > FAST_MEM
}
```

For more information, see Section 8.5.4 for the MEMORY directive, and Section 8.5.5 for the SECTIONS directive.

8.5.1 Reserved Names in Linker Command Files

The following names (in both uppercase and lowercase) are reserved as keywords for linker directives. Do not use them as symbol or section names in a command file.

<table>
<thead>
<tr>
<th>Reserved Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADDRESS_MASK</td>
<td>f, LOAD, ORIGIN, START</td>
</tr>
<tr>
<td>ALGORITHM</td>
<td>FILL, LOAD_END, PAGE, TABLE</td>
</tr>
<tr>
<td>ALIGN</td>
<td>GROUP, LOAD_SIZE, PALIGN, TYPE</td>
</tr>
<tr>
<td>ATTR</td>
<td>HAMMING_MASK, LOAD_START, PARITY_MASK, UNION</td>
</tr>
<tr>
<td>BLOCK</td>
<td>HIGH, MEMORY, RUN, UNORDERED</td>
</tr>
<tr>
<td>COMPRESSION</td>
<td>INPUT_PAGE, MIRRORING, RUN_END, VFILL</td>
</tr>
<tr>
<td>COPY</td>
<td>INPUT_RANGE, NOINIT, RUN_SIZE</td>
</tr>
<tr>
<td>DSECT</td>
<td>I (lowercase L), NOLOAD, RUN_START</td>
</tr>
<tr>
<td>ECC</td>
<td>LEN, o, SECTIONS</td>
</tr>
<tr>
<td>END</td>
<td>LENGTH, ORG, SIZE</td>
</tr>
</tbody>
</table>

In addition, any section names used by the TI tools are reserved from being used as the prefix for other names, unless the section will be a subsection of the section name used by the TI tools. For example, section names may not begin with .debug.

8.5.2 Constants in Linker Command Files

You can specify constants with either of two syntax schemes: the scheme used for specifying decimal, octal, or hexadecimal constants (but not binary constants) used in the assembler (see Section 4.7) or the scheme used for integer constants in C syntax.

Examples:

<table>
<thead>
<tr>
<th>Format</th>
<th>Decimal</th>
<th>Octal</th>
<th>Hexadecimal</th>
</tr>
</thead>
<tbody>
<tr>
<td>Assembler format</td>
<td>32</td>
<td>40q</td>
<td>020h</td>
</tr>
<tr>
<td>C format</td>
<td>32</td>
<td>040</td>
<td>0x20</td>
</tr>
</tbody>
</table>
8.5.3 Accessing Files and Libraries from a Linker Command File

Many applications use custom linker command files (or LCFs) to control the placement of code and data in target memory. For example, you may want to place a specific data object from a specific file into a specific location in target memory. This is simple to do using the available LCF syntax to reference the desired object file or library. However, a problem that many developers run into when they try to do this is a linker generated "file not found" error when accessing an object file or library from inside the LCF that has been specified earlier in the command-line invocation of the linker. Most often, this error occurs because the syntax used to access the file on the linker command-line does not match the syntax that is used to access the same file in the LCF.

Consider a simple example. Imagine that you have an application that requires a table of constants called "app_coeffs" to be defined in a memory area called "DDR". Assume also that the "app_coeffs" data object is defined in a .data section that resides in an object file, app_coeffs.obj. app_coeffs.obj is then included in the object file library app_data.lib. In your LCF, you can control the placement of the "app_coeffs" data object as follows:

```
SECTIONS
{
  ...
  .coeffs: { app_data.lib<app_coeffs.obj>(.data) } > DDR
  ...
}
```

Now assume that the app_data.lib object library resides in a sub-directory called "lib" relative to where you are building the application. In order to gain access to app_data.lib from the build command-line, you can use a combination of the –i and –l options to set up a directory search path which the linker can use to find the app_data.lib library:

```
%> cl6x < compile options/files > -z -i ./lib -l app_data.lib mylnk.cmd < link options/files
```

The –i option adds the lib sub-directory to the directory search path and the –l option instructs the linker to look through the directories in the directory search path to find the app_data.lib library. However, if you do not update the reference to app_data.lib in mylnk.cmd, the linker will fail to find the app_data.lib library and generate a "file not found" error. The reason is that when the linker encounters the reference to app_data.lib inside the SECTIONS directive, there is no –l option preceding the reference. Therefore, the linker tries to open app_data.lib in the current working directory.

In essence, the linker has a few different ways of opening files:

- If there is a path specified, the linker will look for the file in the specified location. For an absolute path, the linker will try to open the file in the specified directory. For a relative path, the linker will follow the specified path starting from the current working directory and try to open the file at that location.
- If there is no path specified, the linker will try to open the file in the current working directory.
- If a –l option precedes the file reference, then the linker will try to find and open the referenced file in one of the directories in the directory search path. The directory search path is set up via –i options and environment variables (like C_DIR and C6X_C_DIR).

As long as a file is referenced in a consistent manner on the command line and throughout any applicable LCFs, the linker will be able to find and open your object files and libraries.

Returning to the earlier example, you can insert a –l option in front of the reference to app_data.lib in mylnk.cmd to ensure that the linker will find and open the app_data.lib library when the application is built:

```
SECTIONS
{
  ...
  .coeffs: { -l app_data.lib<app_coeffs.obj>(.data) } > DDR
  ...
}
```

Another benefit to using the –l option when referencing a file from within an LCF is that if the location of the referenced file changes, you can modify the directory search path to incorporate the new location of the file (using –l option on the command line, for example) without having to modify the LCF.
8.5.4 The MEMORY Directive

The linker determines where output sections are allocated into memory; it must have a model of target memory to accomplish this. The MEMORY directive allows you to specify a model of target memory so that you can define the types of memory your system contains and the address ranges they occupy. The linker maintains the model as it allocates output sections and uses it to determine which memory locations can be used for object code.

The memory configurations of TMS320C6000 systems differ from application to application. The MEMORY directive allows you to specify a variety of configurations. After you use MEMORY to define a memory model, you can use the SECTIONS directive to allocate output sections into defined memory.

For more information, see Section 2.5.

8.5.4.1 Default Memory Model

If you do not use the MEMORY directive, the linker uses a default memory model that is based on the TMS320C6000 architecture. This model assumes that the full 32-bit address space (2^32 locations) is present in the system and available for use. For more information about the default memory model, see Section 8.7.

8.5.4.2 MEMORY Directive Syntax

The MEMORY directive identifies ranges of memory that are physically present in the target system and can be used by a program. Each range has several characteristics:

- **Name**
- **Starting address**
- **Length**
- **Optional set of attributes**
- **Optional fill specification**

When you use the MEMORY directive, be sure to identify all memory ranges that are available for the program to access at run time. Memory defined by the MEMORY directive is configured; any memory that you do not explicitly account for with MEMORY is unconfigured. The linker does not place any part of a program into unconfigured memory. You can represent nonexistent memory spaces by simply not including an address range in a MEMORY directive statement.

The MEMORY directive is specified in a command file by the word MEMORY (uppercase), followed by a list of memory range specifications enclosed in braces. The MEMORY directive in Example 8-3 defines a system that has 4K bytes of fast external memory at address 0x0000 0000, 2K bytes of slow external memory at address 0x0000 1000 and 4K bytes of slow external memory at address 0x1000 0000. It also demonstrates the use of memory range expressions as well as start/end/size address operators (see Section 8.5.4.3).

**Example 8-3. The MEMORY Directive**

```c
MEMORY
{
  FAST_MEM (RX): origin = 0x00000000 length = 0x00001000 + BUFFER
  SLOW_MEM (RW): origin = end(FAST_MEM) length = 0x00001800 - size(FAST_MEM)
  EXT_MEM (RX): origin = 0x10000000 length = size(FAST_MEM)
}
```
The general syntax for the MEMORY directive is:

```
MEMORY
{
    name 1 [( attr )] : origin = expression , length = expression [, fill = constant]
    .
    .
    name n [( attr )] : origin = expression , length = expression [, fill = constant]
}
```

name names a memory range. A memory name can be one to 64 characters; valid characters include A-Z, a-z, $, ., and _. The names have no special significance to the linker; they simply identify memory ranges. Memory range names are internal to the linker and are not retained in the output file or in the symbol table. All memory ranges must have unique names and must not overlap.

attr specifies one to four attributes associated with the named range. Attributes are optional; when used, they must be enclosed in parentheses. Attributes restrict the allocation of output sections into certain memory ranges. If you do not use any attributes, you can allocate any output section into any range with no restrictions. Any memory for which no attributes are specified (including all memory in the default model) has all four attributes. Valid attributes are:
- **R** specifies that the memory can be read.
- **W** specifies that the memory can be written to.
- **X** specifies that the memory can contain executable code.
- **I** specifies that the memory can be initialized.

origin specifies the starting address of a memory range; enter as origin, org, or o. The value, specified in bytes, is a 32-bit integer constant expression, which can be decimal, octal, or hexadecimal.

length specifies the length of a memory range; enter as length, len, or l. The value, specified in bytes, is a 32-bit integer constant expression, which can be decimal, octal, or hexadecimal.

fill specifies a fill character for the memory range; enter as fill or f. Fills are optional. The value is an integer constant and can be decimal, octal, or hexadecimal. The fill value is used to fill areas of the memory range that are not allocated to a section. (See Section 8.5.9.3 for virtual filling of memory ranges when using Error Correcting Code (ECC).)

---

**Filling Memory Ranges**

**NOTE:** If you specify fill values for large memory ranges, your output file will be very large because filling a memory range (even with 0s) causes raw data to be generated for all unallocated blocks of memory in the range.

The following example specifies a memory range with the R and W attributes and a fill constant of 0xFFFFFFFFh:

```
MEMORY
{
    RFIL (RW) : o = 0x00000020, l = 0x00001000, f = 0xFFFFFFFF
}
```

You normally use the MEMORY directive in conjunction with the SECTIONS directive to control placement of output sections. For more information about the SECTIONS directive, see Section 8.5.5.
8.5.4.3 Expressions and Address Operators

Memory range origin and length can use expressions of integer constants with the following operators:

Binary operators:  
* / % + - << >> == =
< <= >> >= & && ||

Unary operators:  
- ~ !

Expressions are evaluated using standard C operator precedence rules.
No checking is done for overflow or underflow, however, expressions are evaluated using a larger integer type.
Preprocess directive #define constants can be used in place of integer constants. Global symbols cannot be used in Memory Directive expressions.

Three address operators reference memory range properties from prior memory range entries:

START(MR) Returns start address for previously defined memory range MR.
SIZE(MR) Returns size of previously defined memory range MR.
END(MR) Returns end address for previously defined memory range MR.

Example 8-4. Origin and Length as Expressions

```c
/********************************************************/
/* Sample command file with MEMORY directive */
/********************************************************/
file1.obj file2.obj /* Input files */
--output_file=prog.out /* Options */
#define ORIGIN 0x00000000
#define BUFFER 0x00000200
#define CACHE 0x0001000
MEMORY
{
  FAST_MEM (RX): origin = ORIGIN + CACHE length = 0x00001000 + BUFFER
  SLOW_MEM (RW): origin = end(FAST_MEM) length = 0x00001800 - size(FAST_MEM)
  EXT_MEM (RX): origin = 0x10000000 length = size(FAST_MEM) - CACHE
}
```

8.5.5 The SECTIONS Directive

After you use MEMORY to specify the target system's memory model, you can use SECTIONS to place output sections into specific named memory ranges or into memory that has specific attributes. For example, you could allocate the .text and .data sections into the area named FAST_MEM and allocate the .bss section into the area named SLOW_MEM.

The SECTIONS directive controls your sections in the following ways:

- Describes how input sections are combined into output sections
- Defines output sections in the executable program
- Allows you to control where output sections are placed in memory in relation to each other and to the entire memory space (Note that the memory placement order is not simply the sequence in which sections occur in the SECTIONS directive.)
- Permits renaming of output sections

For more information, see Section 2.5, Section 2.7, and Section 2.4.6. Subsections allow you to manipulate sections with greater precision.

If you do not specify a SECTIONS directive, the linker uses a default algorithm for combining and allocating the sections. Section 8.7 describes this algorithm in detail.
### 8.5.5.1 SECTIONS Directive Syntax

The SECTIONS directive is specified in a command file by the word SECTIONS (uppercase), followed by a list of output section specifications enclosed in braces.

The general syntax for the SECTIONS directive is:

```
SECTIONS
{
    name : [property [, property] [, property] ... ]
    name : [property [, property] [, property] ... ]
    name : [property [, property] [, property] ... ]
```

Each section specification, beginning with `name`, defines an output section. (An output section is a section in the output file.) Section names can refer to sections, subsections, or archive library members. (See Section 8.5.5.4 for information on multi-level subsections.) After the section name is a list of properties that define the section's contents and how the section is allocated. The properties can be separated by optional commas. Possible properties for a section are as follows:

- **Load allocation** defines where in memory the section is to be loaded. See Section 3.5, Section 3.1.1, and Section 8.5.6.
  
  ```
  Syntax:     load = allocation or > allocation
  ```

- **Run allocation** defines where in memory the section is to be run.
  
  ```
  Syntax:     run = allocation or run > allocation
  ```

- **Input sections** defines the input sections (object files) that constitute the output section. See Section 8.5.5.3.
  
  ```
  Syntax:     { input_sections }
  ```

- **Section type** defines flags for special section types. See Section 8.5.8.
  
  ```
  Syntax:     type = COPY or type = DSECT or type = NOLOAD
  ```

- **Fill value** defines the value used to fill uninitialized holes. See Section 8.5.11.
  
  ```
  Syntax:     fill = value
  ```

Example 8-5 shows a SECTIONS directive in a sample linker command file.
Example 8-5. The SECTIONS Directive

```c
/*******************
/* Sample command file with SECTIONS directive */
/*******************
file1.obj  file2.obj /* Input files */
--output_file=prog.out /* Options */
SECTIONS
{
  .text: load = EXT_MEM, run = 0x00000800
  .const: load = FAST_MEM
  .bss: load = SLOW_MEM
  .vectors: load = 0x00000000
    t1.obj(.intvec1)
    t2.obj(.intvec2)
    endvec = .;
  .data:alpha: align = 16
  .data:beta: align = 16
}
```

Figure 8-2 shows the output sections defined by the SECTIONS directive in Example 8-5 (.vectors, .text, .const, .bss, .data:alpha, and .data:beta) and shows how these sections are allocated in memory using the MEMORY directive given in Example 8-3.

Figure 8-2. Section Placement Defined by Example 8-5

- Bound at 0x00000000 - The .vectors section is composed of the .intvec1 section from t1.obj and the .intvec2 section from t2.obj.
- Allocated in FAST_MEM - The .const section combines the .const sections from file1.obj and file2.obj.
- Allocated in SLOW_MEM - The .bss section combines the .bss sections from file1.obj and file2.obj.
- Aligned on 16-byte boundary - The .data:alpha subsection combines the .data:alpha subsections from file1.obj and file2.obj. The .data:beta subsection combines the .data:beta subsections from file1.obj and file2.obj. The linker places the subsections anywhere there is space for them (in SLOW_MEM in this illustration) and aligns each on a 16-byte boundary.
- Empty range of memory as defined in above - The .text section combines the .text sections from file1.obj and file2.obj. The linker combines all sections named .text into this section. The application must relocate the section to run at 0x00000800.

- Allocated in EXT_MEM - Empty range of memory as defined in above
8.5.5.2 Section Allocation and Placement

The linker assigns each output section two locations in target memory: the location where the section will be loaded and the location where it will be run. Usually, these are the same, and you can think of each section as having only a single address. The process of locating the output section in the target's memory and assigning its address(es) is called placement. For more information about using separate load and run placement, see Section 8.5.6.

If you do not tell the linker how a section is to be allocated, it uses a default algorithm to place the section. Generally, the linker puts sections wherever they fit into configured memory. You can override this default placement for a section by defining it within a SECTIONS directive and providing instructions on how to allocate it.

You control placement by specifying one or more allocation parameters. Each parameter consists of a keyword, an optional equal sign or greater-than sign, and a value optionally enclosed in parentheses. If load and run placement are separate, all parameters following the keyword LOAD apply to load placement, and those following the keyword RUN apply to run placement. The allocation parameters are:

- **Binding**: allocates a section at a specific address.
  
  .text: load = 0x1000

- **Named memory**: allocates the section into a range defined in the MEMORY directive with the specified name (like SLOW_MEM) or attributes.
  
  .text: load > SLOW_MEM

- **Alignment**: uses the align or palign keyword to specify the section must start on an address boundary.
  
  .text: align = 0x100

- **Blocking**: uses the block keyword to specify the section must fit between two address aligned to the blocking factor. If a section is too large, it starts on an address boundary.
  
  .text: Block(0x100)

For the load (usually the only) allocation, use a greater-than sign and omit the load keyword:

- .text: > SLOW_MEM
- .text: {...} > SLOW_MEM
- .text: > 0x4000

If more than one parameter is used, you can string them together as follows:

- .text: > SLOW_MEM align 16

Or if you prefer, use parentheses for readability:

- .text: load = (SLOW_MEM align(16))

You can also use an input section specification to identify the sections from input files that are combined to form an output section. See Section 8.5.5.3.

Additional information about controlling the order in which code and data are placed in memory is provided in the FAQ topic on section placement.

### 8.5.5.2.1 Binding

You can set the starting address for an output section by following the section name with an address:

- .text: 0x00001000

This example specifies that the .text section must begin at location 0x1000. The binding address must be a 32-bit constant.

Output sections can be bound anywhere in configured memory (assuming there is enough space), but they cannot overlap. If there is not enough space to bind a section to a specified address, the linker issues an error message.

---

**NOTE:** You cannot bind a section to an address if you use alignment or named memory. If you try to do this, the linker issues an error message.
8.5.5.2.2 Named Memory

You can allocate a section into a memory range that is defined by the MEMORY directive (see Section 8.5.4). This example names ranges and links sections into them:

```
MEMORY
{  
  SLOW_MEM (RIX) : origin = 0x00000000, length = 0x00001000
  FAST_MEM (RWIX) : origin = 0x03000000, length = 0x00000300
}
SECTIONS
{  
  .text : > SLOW_MEM
  .data : > FAST_MEM ALIGN(128)
  .bss : > FAST_MEM
}
```

In this example, the linker places .text into the area called SLOW_MEM. The .data and .bss output sections are allocated into FAST_MEM. You can align a section within a named memory range; the .data section is aligned on a 128-byte boundary within the FAST_MEM range.

Similarly, you can link a section into an area of memory that has particular attributes. To do this, specify a set of attributes (enclosed in parentheses) instead of a memory name. Using the same MEMORY directive declaration, you can specify:

```
SECTIONS
{  
  .text: > (X) /* .text --> executable memory */
  .data: > (RI) /* .data --> read or init memory */
  .bss : > (RW) /* .bss --> read or write memory */
}
```

In this example, the .text output section can be linked into either the SLOW_MEM or FAST_MEM area because both areas have the X attribute. The .data section can also go into either SLOW_MEM or FAST_MEM because both areas have the R and I attributes. The .bss output section, however, must go into the FAST_MEM area because only FAST_MEM is declared with the W attribute.

You cannot control where in a named memory range a section is allocated, although the linker uses lower memory addresses first and avoids fragmentation when possible. In the preceding examples, assuming no conflicting assignments exist, the .text section starts at address 0. If a section must start on a specific address, use binding instead of named memory.

8.5.5.2.3 Controlling Placement Using The HIGH Location Specifier

The linker allocates output sections from low to high addresses within a designated memory range by default. Alternatively, you can cause the linker to allocate a section from high to low addresses within a memory range by using the HIGH location specifier in the SECTION directive declaration. You might use the HIGH location specifier in order to keep RTS code separate from application code, so that small changes in the application do not cause large changes to the memory map.

For example, given this MEMORY directive:

```
MEMORY
{  
  RAM : origin = 0x0200, length = 0x0800
  FLASH : origin = 0x1100, length = 0xE3E0
  VECTORS : origin = 0xFFE0, length = 0x001E
  RESET : origin = 0xFFFE, length = 0x0002
}
```

and an accompanying SECTIONS directive:

```
SECTIONS
{  
  .bss : {} > RAM
  .sysmem : {} > RAM
  .stack : {} > RAM (HIGH)
}
```
The HIGH specifier used on the .stack section placement causes the linker to attempt to allocate .stack into the higher addresses within the RAM memory range. The .bss and .sysmem sections are allocated into the lower addresses within RAM. Example 8-6 illustrates a portion of a map file that shows where the given sections are allocated within RAM for a typical program.

Example 8-6. Linker Placement With the HIGH Specifier

<table>
<thead>
<tr>
<th>Section</th>
<th>Offset</th>
<th>Address Range</th>
<th>Nature</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>.bss</td>
<td>0</td>
<td>00000200-0000270</td>
<td>UNINITIALIZED</td>
<td>00000200</td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : defs.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>0000031a 000003a2 0000041a 00000460 00000468 0000046c 0000046e</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : trgdrv.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>lowlev.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>memory.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>_lock.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>fopen.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>hello.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.sysmem</td>
<td>0</td>
<td>00000470-000005b0</td>
<td>UNINITIALIZED</td>
<td>00000470</td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : memory.obj (.sysmem)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.stack</td>
<td>0</td>
<td>000008c0-000009c0</td>
<td>UNINITIALIZED</td>
<td>000008c0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : boot.obj (.stack)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>hello.obj (.bss)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

As shown in Example 8-6, the .bss and .sysmem sections are allocated at the lower addresses of RAM (0x0200 - 0x0590) and the .stack section is allocated at address 0x08c0, even though lower addresses are available.

Without using the HIGH specifier, the linker allocation would result in the code shown in Example 8-7.

The HIGH specifier is ignored if it is used with specific address binding or automatic section splitting (>> operator).

Example 8-7. Linker Placement Without HIGH Specifier

<table>
<thead>
<tr>
<th>Section</th>
<th>Offset</th>
<th>Address Range</th>
<th>Nature</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>.bss</td>
<td>0</td>
<td>00000200-0000270</td>
<td>UNINITIALIZED</td>
<td>00000200</td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : defs.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>0000031a 000003a2 0000041a 00000460 00000468 0000046c 0000046e</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : trgdrv.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>lowlev.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>memory.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>_lock.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>fopen.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>hello.obj (.bss)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.stack</td>
<td>0</td>
<td>00000470-000005b0</td>
<td>UNINITIALIZED</td>
<td>00000470</td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : boot.obj (.stack)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>.sysmem</td>
<td>0</td>
<td>000005b0-000006b0</td>
<td>UNINITIALIZED</td>
<td>000005b0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>rtsxxx.lib : memory.obj (.sysmem)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
8.5.5.2.4 Alignment and Blocking

You can tell the linker to place an output section at an address that falls on an n-byte boundary, where n is a power of 2, by using the align keyword. For example, the following code allocates .text so that it falls on a 32-byte boundary:

```
.text: load = align(32)
```

Blocking is a weaker form of alignment that allocates a section anywhere within a block of size n. The specified block size must be a power of 2. For example, the following code allocates .bss so that the entire section is contained in a single 128-byte block or begins on that boundary:

```
bss: load = block(0x0080)
```

You can use alignment or blocking alone or in conjunction with a memory area, but alignment and blocking cannot be used together.

8.5.5.2.5 Alignment With Padding

As with align, you can tell the linker to place an output section at an address that falls on an n-byte boundary, where n is a power of 2, by using the palign keyword. In addition, palign ensures that the size of the section is a multiple of its placement alignment restrictions, padding the section size up to such a boundary, as needed.

For example, the following code lines allocate .text on a 2-byte boundary within the PMEM area. The .text section size is guaranteed to be a multiple of 2 bytes. Both statements are equivalent:

```
.text: palign(2) {} > PMEM
.text: palign = 2 {} > PMEM
```

If the linker adds padding to an initialized output section then the padding space is also initialized. By default, padding space is filled with a value of 0 (zero). However, if a fill value is specified for the output section then any padding for the section is also filled with that fill value. For example, consider the following section specification:

```
.mytext: palign(8), fill = 0xffffffff {} > PMEM
```

In this example, the length of the .mytext section is 6 bytes before the palign operator is applied. The contents of .mytext are as follows:

```
addr  content
-----  -------
0000   0x1234
0002   0x1234
0004   0x1234
```

After the palign operator is applied, the length of .mytext is 8 bytes, and its contents are as follows:

```
addr  content
-----  -------
0000   0x1234
0002   0x1234
0004   0x1234
0006   0xff
```

The size of .mytext has been bumped to a multiple of 8 bytes and the padding created by the linker has been filled with 0xff.
The fill value specified in the linker command file is interpreted as a 16-bit constant. If you specify this code:

```
.mytext: palign(8), fill = 0xff {} > PMEM
```

The fill value assumed by the linker is 0x00ff, and .mytext will then have the following contents:

<table>
<thead>
<tr>
<th>addr</th>
<th>content</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>0x1234</td>
</tr>
<tr>
<td>0002</td>
<td>0x1234</td>
</tr>
<tr>
<td>0004</td>
<td>0x1234</td>
</tr>
<tr>
<td>0006</td>
<td>0x00ff</td>
</tr>
</tbody>
</table>

If the palign operator is applied to an uninitialized section, then the size of the section is bumped to the appropriate boundary, as needed, but any padding created is not initialized.

The palign operator can also take a parameter of `power2`. This parameter tells the linker to add padding to increase the section's size to the next power of two boundary. In addition, the section is aligned on that power of 2 as well. For example, consider the following section specification:

```
.mytext: palign(power2) {} > PMEM
```

Assume that the size of the .mytext section is 120 bytes and PMEM starts at address 0x10020. After applying the palign(power2) operator, the .mytext output section will have the following properties:

<table>
<thead>
<tr>
<th>name</th>
<th>addr</th>
<th>size</th>
<th>align</th>
</tr>
</thead>
<tbody>
<tr>
<td>.mytext</td>
<td>0x00010080</td>
<td>0x80</td>
<td>128</td>
</tr>
</tbody>
</table>
### 8.5.5.3 Specifying Input Sections

An input section specification identifies the sections from input files that are combined to form an output section. In general, the linker combines input sections by concatenating them in the order in which they are specified. However, if alignment or blocking is specified for an input section, all of the input sections within the output section are ordered as follows:

- All aligned sections, from largest to smallest
- All blocked sections, from largest to smallest
- All other sections, from largest to smallest

The size of an output section is the sum of the sizes of the input sections that it comprises.

**Example 8-8** shows the most common type of section specification; note that no input sections are listed.

**Example 8-8. The Most Common Method of Specifying Section Contents**

```plaintext
SECTIONS
{
    .text: /* Build .text output section */
    .data: *
    .bss: *
}
```

In **Example 8-8**, the linker takes all the .text sections from the input files and combines them into the .text output section. The linker concatenates the .text input sections in the order that it encounters them in the input files. The linker performs similar operations with the .data and .bss sections. You can use this type of specification for any output section.

You can explicitly specify the input sections that form an output section. Each input section is identified by its filename and section name. If the filename is hyphenated (or contains special characters), enclose it within quotes:

```plaintext
SECTIONS
{
    .text: /* Build .text output section */
    { /* Link .text section from f1.obj */
        f1.obj(.text)
    }
    { /* Link secl section from f2.obj */
        f2.obj(secl)
    }
    { /* Link ALL sections from f3-new.obj */
        "f3-new.obj"
    }
    { /* Link .text and sec2 from f4.obj */
        f4.obj"(.text,sec2)
    }
}
```

It is not necessary for input sections to have the same name as each other or as the output section they become part of. If a file is listed with no sections, *all* of its sections are included in the output section. If any additional input sections have the same name as an output section but are not explicitly specified by the `SECTIONS` directive, they are automatically linked in at the end of the output section. For example, if the linker found more .text sections in the preceding example and these .text sections were not specified anywhere in the `SECTIONS` directive, the linker would concatenate these extra sections after f4.obj(sec2).

The specifications in **Example 8-8** are actually a shorthand method for the following:

```plaintext
SECTIONS
{
    .text: { *(.text) }
    .data: { *(.data) }
    .bss: { *(.bss) }
}
```

The specification `*(.text)` means *the unallocated .text sections from all input files*. This format is useful if:

- You want the output section to contain all input sections that have a specified name, but the output section name is different from the input sections' name.
- You want the linker to allocate the input sections before it processes additional input sections or commands within the braces.
The following example illustrates the two purposes above:

```c
SECTIONS
{
  .text : {
    abc.obj(xqt)
    *(.text)
  }
  .data : {
    *(.data)
    fil.obj(table)
  }
}
```

In this example, the .text output section contains a named section xqt from file abc.obj, which is followed by all the .text input sections. The .data section contains all the .data input sections, followed by a named section table from the file fil.obj. This method includes all the unallocated sections. For example, if one of the .text input sections was already included in another output section when the linker encountered *(.text), the linker could not include that first .text input section in the second output section.

Each input section acts as a prefix and gathers longer-named sections. For example, the pattern *(.data) matches .dataspecial. This mechanism enables the use of subsections, which are described in the following section.

### 8.5.5.4 Using Multi-Level Subsections

Subsections can be identified with the base section name and one or more subsection names separated by colons. For example, A:B and A:B:C name subsections of the base section A. In certain places in a linker command file specifying a base name, such as A, selects the section A as well as any subsections of A, such as A:B or A:C:D.

A name such as A:B can specify a (sub)section of that name as well as any (multi-level) subsections beginning with that name, such as A:B:C, A:B:OTHER, etc. All subsections of A:B are also subsections of A. A and A:B are supersections of A:B:C. Among a group of supersections of a subsection, the nearest supersection is the supersection with the longest name. Thus, among {A, A:B} the nearest supersection of A:B:C:D is A:B. With multiple levels of subsections, the constraints are the following:

1. When specifying input sections within a file (or library unit) the section name selects an input section of the same name and any subsections of that name.

2. Input sections that are not explicitly allocated are allocated in an existing output section of the same name or in the nearest existing supersection of such an output section. An exception to this rule is that during a partial link (specified by the --relocatable linker option) a subsection is allocated only to an existing output section of the same name.

3. If no such output section described in 2) is defined, the input section is put in a newly created output section with the same name as the base name of the input section.

Consider linking input sections with the following names:

<table>
<thead>
<tr>
<th>Europe Region</th>
<th>Europe Region</th>
<th>Europe Region</th>
</tr>
</thead>
<tbody>
<tr>
<td>europe:north:norway</td>
<td>europe:central:france</td>
<td>europe:south:spain</td>
</tr>
<tr>
<td>europe:north:sweden</td>
<td>europe:central:germany</td>
<td>europe:south:italy</td>
</tr>
<tr>
<td>europe:north:finland</td>
<td>europe:central:denmark</td>
<td>europe:south:malta</td>
</tr>
<tr>
<td>europe:north:iceland</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

This SECTIONS specification allocates the input sections as indicated in the comments:

```c
SECTIONS {
  nordic: {*{europe:north}
                       {*{europe:central:denmark}) /* the nordic countries */
  central: {*{europe:central}) /* france, germany */
  therest: {*{europe}) /* spain, italy, malta */
}
```
This SECTIONS specification allocates the input sections as indicated in the comments:

```
SECTIONS {
    islands: {*{europe:south:malta)} /* malta, iceland */
             {*{europe:north:iceland}} /* finland */
    europe:north:finland : {} /* norway, sweden */
    europe:north : {} /* norway, sweden */
    europe:central : {} /* germany, denmark */
    europe:central:france: {} /* france */

    /* (italy, spain) go into a linker-generated output section *europe* */
}
```

**Upward Compatibility of Multi-Level Subsections**

**NOTE:** Existing linker commands that use the existing single-level subsection features and which do not contain section names containing multiple colon characters continue to behave as before. However, if section names in a linker command file or in the input sections supplied to the linker contain multiple colon characters, some change in behavior could be possible. You should carefully consider the impact of the rules for multiple levels to see if it affects a particular system link.

### 8.5.5.5 Specifying Library or Archive Members as Input to Output Sections

You can specify one or more members of an object library or archive for input to an output section. Consider this SECTIONS directive:

**Example 8-9. Archive Members to Output Sections**

```
SECTIONS {
    boot > BOOT1
    { --library=rtsXX.lib<boot.obj> (.text)
        --library=rtsXX.lib<exit.obj strcpy.obj> (.text)
    }
    .rts > BOOT2
    { --library=rtsXX.lib (.text)
    }
    .text > RAM
    { * (.text)
    }
}
```

In **Example 8-9**, the .text sections of boot.obj, exit.obj, and strcpy.obj are extracted from the run-time-support library and placed in the .boot output section. The remainder of the run-time-support library object that is referenced is allocated to the .rts output section. Finally, the remainder of all other .text sections are to be placed in section .text.

An archive member or a list of members is specified by surrounding the member name(s) with angle brackets < and > after the library name. Any object files separated by commas or spaces from the specified archive file are legal within the angle brackets.

The --library option (which normally implies a library path search be made for the named file following the option) listed before each library in **Example 8-9** is optional when listing specific archive members inside < >. Using < > implies that you are referring to a library.
To collect a set of the input sections from a library in one place, use the \texttt{--library} option within the \texttt{SECTIONS} directive. For example, the following collects all the \texttt{.text} sections from \texttt{rts6600_elf.lib} into the \texttt{.rtstest} section:

\begin{verbatim}
SECTIONS
{ .rtstest \{ --library=rts6600_elf.lib(.text) \} > RAM }
\end{verbatim}

\textbf{SECTIONS Directive Effect on \texttt{--priority}}

\textbf{NOTE:} Specifying a library in a \texttt{SECTIONS} directive causes that library to be entered in the list of libraries that the linker searches to resolve references. If you use the \texttt{--priority} option, the first library specified in the command file will be searched first.

\section*{8.5.5.6 Allocation Using Multiple Memory Ranges}

The linker allows you to specify an explicit list of memory ranges into which an output section can be allocated. Consider the following example:

\begin{verbatim}
MEMORY
{ 
P_MEM1 : origin = 0x02000, length = 0x01000
P_MEM2 : origin = 0x04000, length = 0x01000
P_MEM3 : origin = 0x06000, length = 0x01000
P_MEM4 : origin = 0x08000, length = 0x01000
}
SECTIONS
{ .text : { } > P_MEM1 | P_MEM2 | P_MEM4 }
\end{verbatim}

The \texttt{|} operator is used to specify the multiple memory ranges. The \texttt{.text} output section is allocated as a whole into the first memory range in which it fits. The memory ranges are accessed in the order specified. In this example, the linker first tries to allocate the section in \texttt{P_MEM1}. If that attempt fails, the linker tries to place the section into \texttt{P_MEM2}, and so on. If the output section is not successfully allocated in any of the named memory ranges, the linker issues an error message.

With this type of \texttt{SECTIONS} directive specification, the linker can seamlessly handle an output section that grows beyond the available space of the memory range in which it is originally allocated. Instead of modifying the linker command file, you can let the linker move the section into one of the other areas.

\section*{8.5.5.7 Automatic Splitting of Output Sections Among Non-Contiguous Memory Ranges}

The linker can split output sections among multiple memory ranges for efficient allocation. Use the \texttt{\textgreater \textgreater} operator to indicate that an output section can be split, if necessary, into the specified memory ranges:

\begin{verbatim}
MEMORY
{ 
P_MEM1 : origin = 0x2000, length = 0x1000
P_MEM2 : origin = 0x4000, length = 0x1000
P_MEM3 : origin = 0x6000, length = 0x1000
P_MEM4 : origin = 0x8000, length = 0x1000
}
SECTIONS
{ .text: { *(.text) } \textgreater \textgreater P_MEM1 | P_MEM2 | P_MEM3 | P_MEM4 }
\end{verbatim}

In this example, the \texttt{\textgreater \textgreater} operator indicates that the \texttt{.text} output section can be split among any of the listed memory areas. If the \texttt{.text} section grows beyond the available memory in \texttt{P_MEM1}, it is split on an input section boundary, and the remainder of the output section is allocated to \texttt{P_MEM2 | P_MEM3 | P_MEM4}. The \texttt{|} operator is used to specify the list of multiple memory ranges.
You can also use the >> operator to indicate that an output section can be split within a single memory range. This functionality is useful when several output sections must be allocated into the same memory range, but the restrictions of one output section cause the memory range to be partitioned. Consider the following example:

```c
MEMORY {
  RAM : origin = 0x1000, length = 0x8000
}
SECTIONS {
  .special: { f1.obj(.text) } load = 0x4000
  .text: { *(.text) } >> RAM
}
```

The .special output section is allocated near the middle of the RAM memory range. This leaves two unused areas in RAM: from 0x1000 to 0x4000, and from the end of f1.obj(.text) to 0x8000. The specification for the .text section allows the linker to split the .text section around the .special section and use the available space in RAM on either side of .special.

The >> operator can also be used to split an output section among all memory ranges that match a specified attribute combination. For example:

```c
MEMORY {
  P_MEM1 (RWX) : origin = 0x1000, length = 0x2000
  P_MEM2 (RWI) : origin = 0x4000, length = 0x1000
}
SECTIONS {
  .text: { *(.text) } >> (RW)
}
```

The linker attempts to allocate all or part of the output section into any memory range whose attributes match the attributes specified in the SECTIONS directive.

This SECTIONS directive has the same effect as:

```c
SECTIONS {
  .text: { *(.text) } >> P_MEM1 | P_MEM2
}
```

Certain sections should not be split:

- Certain sections created by the compiler, including
  - The .cinit section, which contains the autoinitialization table for C/C++ programs
  - The .pinit section, which contains the list of global constructors for C++ programs
  - The .bss section, which defines global variables
- An output section with an input section specification that includes an expression to be evaluated. The expression may define a symbol that is used in the program to manage the output section at run time.
- An output section that has a START(), END(), OR SIZE() operator applied to it. These operators provide information about a section's load or run address, and size. Splitting the section may compromise the integrity of the operation.
- The run allocation of a UNION. (Splitting the load allocation of a UNION is allowed.)

If you use the >> operator on any of these sections, the linker issues a warning and ignores the operator.
### 8.5.6 Placing a Section at Different Load and Run Addresses

At times, you may want to load code into one area of memory and run it in another. For example, you may have performance-critical code in slow external memory. The code must be loaded into slow external memory, but it would run faster in fast external memory.

The linker provides a simple way to accomplish this. You can use the SECTIONS directive to direct the linker to allocate a section twice: once to set its load address and again to set its run address. For example:

```
.fir: load = SLOW_MEM, run = FAST_MEM
```

Use the `load` keyword for the load address and the `run` keyword for the run address.

See Section 3.5 for an overview on run-time relocation.

The application must copy the section from its load address to its run address; this does not happen automatically when you specify a separate run address. (The TABLE operator instructs the linker to produce a copy table; see Section 8.8.4.1.)

#### 8.5.6.1 Specifying Load and Run Addresses

The load address determines where a loader places the raw data for the section. Any references to the section (such as labels in it) refer to its run address. See Section 3.1.1 for an overview of load and run addresses.

If you provide only one allocation (either load or run) for a section, the section is allocated only once and loads and runs at the same address. If you provide both allocations, the section is allocated as if it were two sections of the same size. This means that both allocations occupy space in the memory map and cannot overlay each other or other sections. (The UNION directive provides a way to overlay sections; see Section 8.5.7.2.)

If either the load or run address has additional parameters, such as alignment or blocking, list them after the appropriate keyword. Everything related to allocation after the keyword `load` affects the load address until the keyword `run` is seen, after which, everything affects the run address. The load and run allocations are completely independent, so any qualification of one (such as alignment) has no effect on the other. You can also specify run first, then load. Use parentheses to improve readability.

The examples that follow specify load and run addresses.

In this example, align applies only to load:

```
.data: load = SLOW_MEM, align = 32, run = FAST_MEM
```

The following example uses parentheses, but has effects that are identical to the previous example:

```
.data: load = (SLOW_MEM align 32), run = FAST_MEM
```

The following example aligns FAST_MEM to 32 bits for run allocations and aligns all load allocations to 16 bits:

```
.data: run = FAST_MEM, align 32, load = align 16
```

For more information on run-time relocation see Section 3.5.

Uninitialized sections (such as `.bss`) are not loaded, so their only significant address is the run address. The linker allocates uninitialized sections only once: if you specify both run and load addresses, the linker warns you and ignores the load address. Otherwise, if you specify only one address, the linker treats it as a run address, regardless of whether you call it load or run.

This example specifies load and run addresses for an uninitialized section:

```
.bss: load = 0x1000, run = FAST_MEM
```

A warning is issued, load is ignored, and space is allocated in FAST_MEM. All of the following examples have the same effect. The `.bss` section is allocated in FAST_MEM.

```
.dbss: load = FAST_MEM
.bss: run = FAST_MEM
.bss: > FAST_MEM
```
8.5.6.2 Referring to the Load Address by Using the .label Directive

Normally, any reference to a symbol refers to its run-time address. However, it may be necessary at run time to refer to a load-time address. Specifically, the code that copies a section from its load address to its run address must have access to the load address. The .label directive defines a special symbol that refers to the section's load address. Thus, whereas normal symbols are relocated with respect to the run address, .label symbols are relocated with respect to the load address. See Create a Load-Time Address Label for more information on the .label directive.

Example 8-10 and Example 8-11 show the use of the .label directive to copy a section from its load address in SLOW_MEM to its run address in FAST_MEM. Figure 8-3 illustrates the run-time execution of Example 8-10.

If you use the table operator, the .label directive is not needed. See Section 8.8.4.1.

Example 8-10. Moving a Function from Slow to Fast Memory at Run Time

```assembly
.sect "fir"
.align 4
.label fir_src
.fir
    ; insert code here
    .label fir_end
    .text
    MVKL fir_src, A4
    MVKH fir_src, A4
    MVKL fir_end, A5
    MVKH fir_end, A5
    MVKH fir, A6
    SUB A5, A4, A1
    loop:
        [!A1] B done
        LDW *A4+, B3
        NOP 4
        ; branch occurs
        STW B3, *A6+
        SUB A1, 4, A1
        B loop
        NOP 5
        ; branch occurs
done:
    B fir
    NOP 5
    ; call occurs
```

Example 8-11. Linker Command File for Example 8-10

```assembly
/* PARTIAL LINKER COMMAND FILE FOR FIR EXAMPLE */

MEMORY
{
    FAST_MEM : origin = 0x00001000, length = 0x00001000
    SLOW_MEM : origin = 0x10000000, length = 0x00001000
}

SECTIONS
{
    .text: load = FAST_MEM
    .fir: load = SLOW_MEM, run FAST_MEM
}
```
8.5.7 Using GROUP and UNION Statements

Two SECTIONS statements allow you to organize or conserve memory: GROUP and UNION. Grouping sections causes the linker to allocate them contiguously in memory. Unioning sections causes the linker to allocate them to the same run address.

8.5.7.1 Grouping Output Sections Together

The SECTIONS directive’s GROUP option forces several output sections to be allocated contiguously and in the order listed, unless the UNORDERED operator is used. For example, assume that a section named term_rec contains a termination record for a table in the .data section. You can force the linker to allocate .data and term_rec together:

Example 8-12. Allocate Sections Together

```c
SECTIONS
{
    .text /* Normal output section */
    .bss /* Normal output section */
    GROUP 0x00001000 : /* Specify a group of sections */
    {
        .data /* First section in the group */
        term_rec /* Allocated immediately after .data */
    }
}
```

You can use binding, alignment, or named memory to allocate a GROUP in the same manner as a single output section. In the preceding example, the GROUP is bound to address 0x1000. This means that .data is allocated at 0x1000, and term_rec follows it in memory.

See Section 8.6.1 for information about referring to linker symbols in C/C++ code.
You Cannot Specify Addresses for Sections Within a GROUP

NOTE: When you use the GROUP option, binding, alignment, or allocation into named memory can be specified for the group only. You cannot use binding, named memory, or alignment for sections within a group.

8.5.7.2 Overlaying Sections With the UNION Statement

For some applications, you may want to allocate more than one section that occupies the same address during run time. For example, you may have several routines you want in fast external memory at different stages of execution. Or you may want several data objects that are not active at the same time to share a block of memory. The UNION statement within the SECTIONS directive provides a way to allocate several sections at the same run-time address.

In Example 8-13, the .bss sections from file1.obj and file2.obj are allocated at the same address in FAST_MEM. In the memory map, the union occupies as much space as its largest component. The components of a union remain independent sections; they are simply allocated together as a unit.

Example 8-13. The UNION Statement

```
SECTIONS
{
    .text: load = SLOW_MEM
    UNION: run = FAST_MEM
    {
        .bss:part1: { file1.obj(.bss) }
        .bss:part2: { file2.obj(.bss) }
    }
    .bss:part3: run = FAST_MEM { globals.obj(.bss) }
}
```

Allocation of a section as part of a union affects only its run address. Under no circumstances can sections be overlaid for loading. If an initialized section is a union member (an initialized section, such as .text, has raw data), its load allocation must be separately specified. See Example 8-14.

Example 8-14. Separate Load Addresses for UNION Sections

```
UNION run = FAST_MEM
{
    .text:part1: load = SLOW_MEM, { file1.obj(.text) }
    .text:part2: load = SLOW_MEM, { file2.obj(.text) }
}
```
Since the .text sections contain raw data, they cannot load as a union, although they can be run as a union. Therefore, each requires its own load address. If you fail to provide a load allocation for an initialized section within a UNION, the linker issues a warning and allocates load space anywhere it can in configured memory.

Uninitialized sections are not loaded and do not require load addresses.

The UNION statement applies only to allocation of run addresses, so it is meaningless to specify a load address for the union itself. For purposes of allocation, the union is treated as an uninitialized section: any one allocation specified is considered a run address, and if both run and load addresses are specified, the linker issues a warning and ignores the load address.
8.5.7.3 Nesting UNIONs and GROUPs

The linker allows arbitrary nesting of GROUP and UNION statements with the SECTIONS directive. By nesting GROUP and UNION statements, you can express hierarchical overlays and groupings of sections. Example 8-15 shows how two overlays can be grouped together.

Example 8-15. Nesting GROUP and UNION Statements

```c
SECTIONS
{
  GROUP 0x1000 : run = FAST_MEM
  {
    UNION:
    {
      mysect1: load = SLOW_MEM
      mysect2: load = SLOW_MEM
    }
    UNION:
    {
      mysect3: load = SLOW_MEM
      mysect4: load = SLOW_MEM
    }
  }
}
```

For this example, the linker performs the following allocations:

- The four sections (mysect1, mysect2, mysect3, mysect4) are assigned unique, non-overlapping load addresses. The name you defined with the .label directive is used in the SLOW_MEM memory region. This assignment is determined by the particular load allocations given for each section.
- Sections mysect1 and mysect2 are assigned the same run address in FAST_MEM.
- Sections mysect3 and mysect4 are assigned the same run address in FAST_MEM.
- The run addresses of mysect1/mysect2 and mysect3/mysect4 are allocated contiguously, as directed by the GROUP statement (subject to alignment and blocking restrictions).

To refer to groups and unions, linker diagnostic messages use the notation:

GROUP_n UNION_n

where n is a sequential number (beginning at 1) that represents the lexical ordering of the group or union in the linker control file without regard to nesting. Groups and unions each have their own counter.

8.5.7.4 Checking the Consistency of Allocators

The linker checks the consistency of load and run allocations specified for unions, groups, and sections. The following rules are used:

- Run allocations are only allowed for top-level sections, groups, or unions (sections, groups, or unions that are not nested under any other groups or unions). The linker uses the run address of the top-level structure to compute the run addresses of the components within groups and unions.
- The linker does not accept a load allocation for UNIONs.
- The linker does not accept a load allocation for uninitialized sections.
- In most cases, you must provide a load allocation for an initialized section. However, the linker does not accept a load allocation for an initialized section that is located within a group that already defines a load allocator.
• As a shortcut, you can specify a load allocation for an entire group, to determine the load allocations for every initialized section or subgroup nested within the group. However, a load allocation is accepted for an entire group only if all of the following conditions are true:
  – The group is initialized (that is, it has at least one initialized member).
  – The group is not nested inside another group that has a load allocator.
  – The group does not contain a union containing initialized sections.

• If the group contains a union with initialized sections, it is necessary to specify the load allocation for each initialized section nested within the group. Consider the following example:

```
SECTIONS
{
  GROUP: load = SLOW_MEM, run = SLOW_MEM
  {
    .text1:
    UNION:
    {
      .text2:
      .text3:
    }
  }
}
```

The load allocator given for the group does not uniquely specify the load allocation for the elements within the union:.text2 and .text3. In this case, the linker issues a diagnostic message to request that these load allocations be specified explicitly.

### 8.5.7.5 Naming UNIONs and GROUPs

You can give a name to a UNION or GROUP by entering the name in parentheses after the declaration. For example:

```
GROUP(BSS_SYSMEM_STACK_GROUP)
{
  .bss :{}
  .sysmem :{}
  .stack :{}
} load=D_MEM, run=D_MEM
```

The name you defined is used in diagnostics for easy identification of the problem LCF area. For example:

```
warning: LOAD placement ignored for "BSS_SYSMEM_STACK_GROUP": object is uninitialized
```

```
UNION(TEXT_CINIT_UNION)
{
  .const :{}load=D_MEM, table(table1)
  .pinit :{}load=D_MEM, table(table1)
}run=P_MEM
```

```
warning: table(table1) operator ignored: table(table1) has already been applied to a section in the "UNION(TEXT_CINIT_UNION)" in which ".pinit" is a descendant
```
8.5.8 Special Section Types (DSECT, COPY, NOLOAD, and NOINIT)

You can assign the following special types to output sections: DSECT, COPY, NOLOAD, and NOINIT. These types affect the way that the program is treated when it is linked and loaded. You can assign a type to a section by placing the type after the section definition. For example:

```
SECTIONS
{
  sec1: load = 0x00002000, type = DSECT {f1.obj}
  sec2: load = 0x00004000, type = COPY {f2.obj}
  sec3: load = 0x00006000, type = NOLOAD {f3.obj}
  sec4: load = 0x00008000, type = NOINIT {f4.obj}
}
```

- The DSECT type creates a dummy section with the following characteristics:
  - It is not included in the output section memory allocation. It takes up no memory and is not included in the memory map listing.
  - It can overlay other output sections, other DSECTs, and unconfigured memory.
  - Global symbols defined in a dummy section are relocated normally. They appear in the output module's symbol table with the same value they would have if the DSECT had actually been loaded. These symbols can be referenced by other input sections.
  - Undefined external symbols found in a DSECT cause specified archive libraries to be searched.
  - The section's contents, relocation information, and line number information are not placed in the output module.

In the preceding example, none of the sections from f1.obj are allocated, but all the symbols are relocated as though the sections were linked at address 0x2000. The other sections can refer to any of the global symbols in sec1.

- A COPY section is similar to a DSECT section, except that its contents and associated information are written to the output module. The .cinit section that contains initialization tables for the TMS320C6000 C/C++ compiler has this attribute under the run-time initialization model.

- A NOLOAD section differs from a normal output section in one respect: the section's contents, relocation information, and line number information are not placed in the output module. The linker allocates space for the section, and it appears in the memory map listing.

- A NOINIT section is not C auto-initialized by the linker. It is your responsibility to initialize this section as needed.
8.5.9 Configuring Error Correcting Code (ECC) with the Linker

Error Correcting Codes (ECC) can be generated and placed in separate sections through the linker command file. ECC uses extra bits to allow errors to be detected and/or corrected by a device. The ECC support provided by the linker is compatible with the ECC support in TI Flash memory on various TI devices. TI Flash memory uses a modified Hamming(72,64) code, which uses 8 parity bits for every 64 bits. Check the documentation for your Flash memory to see if ECC is supported. (ECC for read-write memory is handled completely in hardware at run time.)

See Section 8.4.11 for command-line options that introduce bit errors into code that has a corresponding ECC section or into the ECC parity bits themselves. You can use these options to test your ECC error handling code.

ECC can be generated during linking. The ECC data is included in the resulting object file, alongside code and data, as a data section located at the appropriate address. No extra ECC generation step is required after compilation, and the ECC can be uploaded to the device along with everything else.

You can control the generation of ECC data using the ECC specifier in the memory map (Section 8.5.9.1) and the ECC directive (Section 8.5.9.2).

8.5.9.1 Using the ECC Specifier in the Memory Map

To generate ECC, add a separate memory range to your memory map to hold ECC data and to indicate which memory range contains the Flash data that corresponds to this ECC data. If you have multiple memory ranges for Flash data, you should add a separate ECC memory range for each Flash data range.

The definition of an ECC memory range can also provide parameters for how to generate the ECC data.

The memory map for a device supporting Flash ECC may look something like this:

```plaintext
MEMORY {
    VECTORS : origin=0x00000000 length=0x000020
    FLASH0 : origin=0x00000020 length=0x17FFE0
    FLASH1 : origin=0x00180000 length=0x180000
    STACKS : origin=0x08000000 length=0x000500
    RAM : origin=0x08000500 length=0x03FB00
    ECC_VEC : origin=0xf0400000 length=0x000004 ECC={ input_range=VECTORS }
    ECC_FLA0 : origin=0xf0400004 length=0x02FFFC ECC={ input_range=FLASH0 }
    ECC_FLA1 : origin=0xf0430000 length=0x030000 ECC={ input_range=FLASH1 }
}
```

The "ECC" specifier attached to the ECC memory ranges indicates the data memory range that the ECC range covers. The ECC specifier supports the following parameters:

- input_range = <memory range> The data memory range covered by this ECC data range. Required.
- input_page = <page number> The page number of the input range. Required only if the input range’s name is ambiguous.
- algorithm = <ECC algorithm name> The name of an ECC algorithm defined later in the command file using the ECC directive. Optional if only one algorithm is defined. (See Section 8.5.9.2.)
- fill = true | false Whether to generate ECC data for holes in the initialized data of the input range. The default is "true". Using fill=false produces behavior similar to the nowECC tool. The input range can be filled normally or using a virtual fill (see Section 8.5.9.3).
8.5.9.2 Using the ECC Directive

In addition to specifying ECC memory ranges in the memory map, the linker command file must specify parameters for the algorithm that generates ECC data. You might need multiple ECC algorithm specifications if you have multiple Flash devices.

Each TI device supporting Flash ECC has exactly one set of valid values for these parameters. The linker command files provided with Code Composer Studio include the ECC parameters necessary for ECC support on the Flash memory accessible by the device. Documentation is provided here for completeness.

You specify algorithm parameters with the top-level ECC directive in the linker command file. For example:

```c
ECC {
    algo_name : address_mask = 0x003ffff8
    hamming_mask = FMC
    parity_mask = 0xf
    mirroring = F021
}
```

This ECC directive accepts the following attributes:

- `address_mask = <32-bit mask>`: This mask determines which bits of the address of each 64-bit piece of memory are used in the calculation of the ECC byte for that memory. Default is 0.
- `hamming_mask = FMC | R4`: This setting determines for which data bits the ECC bits encode parity. Default is FMC.
- `parity_mask = <8-bit mask>`: This mask determines which ECC bits encode even parity and which bits encode odd parity. Default is 0, meaning that all bits encode even parity.
- `mirroring = F021 | F035`: This setting determines the order of the ECC bytes and their duplication pattern for redundancy. Default is F021.

8.5.9.3 Using the VFILL Specifier in the Memory Map

Normally, specifying a fill value for a MEMORY range creates initialized data sections to cover any previously uninitialized areas of memory. To generate ECC data for an entire memory range, the linker either needs to have initialized data in the entire range, or needs to know what value uninitialized memory areas will have at run time.

In cases where you want to generate ECC for an entire memory range, but do not want to initialize the entire range by specifying a fill value, you can use the "vfll" specifier instead of a "fill" specifier to virtually fill the range:

```c
MEMORY {
    FLASH : origin=0x0000 length=0x4000 vfll=0xffffffff
}
```

The vfll specifier is functionally equivalent to omitting a fill specifier, except that it allows ECC data to be generated for areas of the input memory range that remain uninitialized. This has the benefit of reducing the size of the resulting object file.

The vfll specifier has no effect other than in ECC data generation. It cannot be specified along with a fill specifier, since that would introduce ambiguity.

8.5.10 Assigning Symbols at Link Time

Linker assignment statements allow you to define external (global) symbols and assign values to them at link time. You can use this feature to initialize a variable or pointer to an allocation-dependent value. See Section 8.6.1 for information about referring to linker symbols in C/C++ code.
8.5.10.1 Syntax of Assignment Statements

The syntax of assignment statements in the linker is similar to that of assignment statements in the C language:

- `symbol = expression;` assigns the value of expression to symbol
- `symbol += expression;` adds the value of expression to symbol
- `symbol -= expression;` subtracts the value of expression from symbol
- `symbol *= expression;` multiplies symbol by expression
- `symbol /= expression;` divides symbol by expression

The symbol should be defined externally. If it is not, the linker defines a new symbol and enters it into the symbol table. The expression must follow the rules defined in Section 8.5.10.3. Assignment statements must terminate with a semicolon.

The linker processes assignment statements after it allocates all the output sections. Therefore, if an expression contains a symbol, the address used for that symbol reflects the symbol's address in the executable output file.

For example, suppose a program reads data from one of two tables identified by two external symbols, Table1 and Table2. The program uses the symbol cur_tab as the address of the current table. The cur_tab symbol must point to either Table1 or Table2. You could accomplish this in the assembly code, but you would need to reassemble the program to change tables. Instead, you can use a linker assignment statement to assign cur_tab at link time:

```
prog.obj /* Input file */
cur_tab = Table1; /* Assign cur_tab to one of the tables */
```

8.5.10.2 Assigning the SPC to a Symbol

A special symbol, denoted by a dot (.), represents the current value of the section program counter (SPC) during allocation. The SPC keeps track of the current location within a section. The linker’s . symbol is analogous to the assembler's $ symbol. The . symbol can be used only in assignment statements within a SECTIONS directive because . is meaningful only during allocation and SECTIONS controls the allocation process. (See Section 8.5.5.)

The . symbol refers to the current run address, not the current load address, of the section.

For example, suppose a program needs to know the address of the beginning of the .data section. By using the .global directive (see Identify Global Symbols), you can create an external undefined variable called Dstart in the program. Then, assign the value of . to Dstart:

```
SECTIONS
{
    .text: {}
    .data: {Dstart = .;}
    .bss : {}
}
```

This defines Dstart to be the first linked address of the .data section. (Dstart is assigned before .data is allocated.) The linker relocates all references to Dstart.

A special type of assignment assigns a value to the . symbol. This adjusts the SPC within an output section and creates a hole between two input sections. Any value assigned to . to create a hole is relative to the beginning of the section, not to the address actually represented by the . symbol. Holes and assignments to . are described in Section 8.5.11.
8.5.10.3 Assignment Expressions

These rules apply to linker expressions:

- Expressions can contain global symbols, constants, and the C language operators listed in Table 8-12.
- All numbers are treated as long (32-bit) integers.
- Constants are identified by the linker in the same way as by the assembler. That is, numbers are recognized as decimal unless they have a suffix (H or h for hexadecimal and Q or q for octal). C language prefixes are also recognized (0 for octal and 0x for hex). Hexadecimal constants must begin with a digit. No binary constants are allowed.
- Symbols within an expression have only the value of the symbol's address. No type-checking is performed.
- Linker expressions can be absolute or relocatable. If an expression contains any relocatable symbols (and 0 or more constants or absolute symbols), it is relocatable. Otherwise, the expression is absolute. If a symbol is assigned the value of a relocatable expression, it is relocatable; if it is assigned the value of an absolute expression, it is absolute.

The linker supports the C language operators listed in Table 8-12 in order of precedence. Operators in the same group have the same precedence. Besides the operators listed in Table 8-12, the linker also has an align operator that allows a symbol to be aligned on an n-byte boundary within an output section (n is a power of 2). For example, the following expression aligns the SPC within the current section on the next 16-byte boundary. Because the align operator is a function of the current SPC, it can be used only in the same context as . —that is, within a SECTIONS directive.

```
. = align(16);
```

<table>
<thead>
<tr>
<th>Group 1 (Highest Precedence)</th>
<th>Group 6</th>
</tr>
</thead>
<tbody>
<tr>
<td>! Logical NOT</td>
<td>&amp; Bitwise AND</td>
</tr>
<tr>
<td>~ Bitwise NOT</td>
<td></td>
</tr>
<tr>
<td>- Negation</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Group 2</th>
<th>Group 7</th>
</tr>
</thead>
<tbody>
<tr>
<td>* Multiplication</td>
<td></td>
</tr>
<tr>
<td>/ Division</td>
<td></td>
</tr>
<tr>
<td>% Modulus</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Group 3</th>
<th>Group 8</th>
</tr>
</thead>
<tbody>
<tr>
<td>+ Addition</td>
<td>&amp; &amp; Logical AND</td>
</tr>
<tr>
<td>- Subtraction</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Group 4</th>
<th>Group 9</th>
</tr>
</thead>
<tbody>
<tr>
<td>&gt;&gt; Arithmetic right shift</td>
<td></td>
</tr>
<tr>
<td>&lt;&lt; Arithmetic left shift</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Group 5</th>
<th>Group 10 (Lowest Precedence)</th>
</tr>
</thead>
<tbody>
<tr>
<td>== Equal to</td>
<td>= Assignment</td>
</tr>
<tr>
<td>!= Not equal to</td>
<td>+ = A = B is equivalent to A = A + B</td>
</tr>
<tr>
<td>&gt; Greater than</td>
<td>- = A = B is equivalent to A = A - B</td>
</tr>
<tr>
<td>&lt; Less than</td>
<td>* = A = B is equivalent to A = A * B</td>
</tr>
<tr>
<td>&lt;= Less than or equal to</td>
<td>/ = A = B is equivalent to A = A / B</td>
</tr>
<tr>
<td>&gt;= Greater than or equal to</td>
<td></td>
</tr>
</tbody>
</table>
8.5.10.4 Symbols Defined by the Linker

The linker automatically defines several symbols based on which sections are used in your assembly source. A program can use these symbols at run time to determine where a section is linked. Since these symbols are external, they appear in the linker map. Each symbol can be accessed in any assembly language module if it is declared with a .global directive (see Identify Global Symbols). You must have used the corresponding section in a source module for the symbol to be created. Values are assigned to these symbols as follows:

- `.text` is assigned the first address of the .text output section. (It marks the beginning of executable code.)
- `.etext` is assigned the first address following the .text output section. (It marks the end of executable code.)
- `.data` is assigned the first address of the .data output section. (It marks the beginning of initialized data tables.)
- `.edata` is assigned the first address following the .data output section. (It marks the end of initialized data tables.)
- `.bss` is assigned the first address of the .bss output section. (It marks the beginning of uninitialized data.)
- `end` is assigned the first address following the .bss output section. (It marks the end of uninitialized data.)

The following symbols are defined only for C/C++ support when the --ram_model or --rom_model option is used.

- `__TI_STACK_END` is assigned the end of the .stack size.
- `__TI_STACK_SIZE` is assigned the size of the .stack section for.
- `__TI_STATIC_BASE` is assigned the value to be loaded into the data pointer register (DP) at boot time. This is typically the start of the first section containing a definition of a symbol that is referenced via near-DP addressing.
- `__TI_SYSMEM_SIZE` is assigned the size of the .sysmem section.

See Section 8.6.1 for information about referring to linker symbols in C/C++ code.

8.5.10.5 Assigning Exact Start, End, and Size Values of a Section to a Symbol

The code generation tools currently support the ability to load program code in one area of (slow) memory and run it in another (faster) area. This is done by specifying separate load and run addresses for an output section or group in the linker command file. Then execute a sequence of instructions (the copying code in Example 8-10) that moves the program code from its load area to its run area before it is needed.

There are several responsibilities that a programmer must take on when setting up a system with this feature. One of these responsibilities is to determine the size and run-time address of the program code to be moved. The current mechanisms to do this involve use of the .label directives in the copying code. A simple example is illustrated in Example 8-10.

This method of specifying the size and load address of the program code has limitations. While it works fine for an individual input section that is contained entirely within one source file, this method becomes more complicated if the program code is spread over several source files or if the programmer wants to copy an entire output section from load space to run space.

Another problem with this method is that it does not account for the possibility that the section being moved may have an associated far call trampoline section that needs to be moved with it.
8.5.10.6 Why the Dot Operator Does Not Always Work

The dot operator (.) is used to define symbols at link-time with a particular address inside of an output section. It is interpreted like a PC. Whatever the current offset within the current section is, that is the value associated with the dot. Consider an output section specification within a SECTIONS directive:

```c
outsect:
{
  s1.obj(.text)
  end_of_s1 = .;
  start_of_s2 = .;
  s2.obj(.text)
  end_of_s2 = .;
}
```

This statement creates three symbols:
- `end_of_s1`—the end address of .text in s1.obj
- `start_of_s2`—the start address of .text in s2.obj
- `end_of_s2`—the end address of .text in s2.obj

Suppose there is padding between s1.obj and s2.obj created as a result of alignment. Then `start_of_s2` is not really the start address of the .text section in s2.obj, but it is the address before the padding needed to align the .text section in s2.obj. This is due to the linker’s interpretation of the dot operator as the current PC. It is also true because the dot operator is evaluated independently of the input sections around it.

Another potential problem in the above example is that `end_of_s2` may not account for any padding that was required at the end of the output section. You cannot reliably use `end_of_s2` as the end address of the output section. One way to get around this problem is to create a dummy section immediately after the output section in question. For example:

```c
GROUP
{
  outsect:
  {
    start_of_outsect = .;
    ...
  }
  dummy: { size_of_outsect = . - start_of_outsect; }
}
```

8.5.10.7 Address and Dimension Operators

Six operators allow you to define symbols for load-time and run-time addresses and sizes:

- **LOAD_START( sym )**
  - Defines `sym` with the load-time start address of related allocation unit
- **START( sym )**
  - Defines `sym` with the load-time start address of related allocation unit
- **LOAD_END( sym )**
  - Defines `sym` with the load-time end address of related allocation unit
- **END( sym )**
  - Defines `sym` with the load-time end address of related allocation unit
- **LOAD_SIZE( sym )**
  - Defines `sym` with the load-time size of related allocation unit
- **SIZE( sym )**
  - Defines `sym` with the load-time size of related allocation unit
- **RUN_START( sym )**
  - Defines `sym` with the run-time start address of related allocation unit
- **RUN_END( sym )**
  - Defines `sym` with the run-time end address of related allocation unit
- **RUN_SIZE( sym )**
  - Defines `sym` with the run-time size of related allocation unit

Linker Command File Operator Equivalencies --

**NOTE:** LOAD_START() and START() are equivalent, as are LOAD_END()/END() and LOAD_SIZE()/SIZE(). The LOAD names are recommended for clarity.

These address and dimension operators can be associated with several different kinds of allocation units, including input items, output sections, GROUPs, and UNIONs. The following sections provide some examples of how the operators can be used in each case.
These symbols defined by the linker can be accessed at runtime using the \texttt{\_symval} operator, which is essentially a cast operation. For example, suppose your linker command file contains the following:

\[
\text{.text: RUN\_START(text\_run\_start), RUN\_SIZE(text\_run\_size) \{ *(.text) \}}
\]

Your C program can access these symbols as follows:

\[
\text{extern char text\_run\_start, text\_run\_size;}
\]

\[
\text{printf(".text load start is %lx\n", \_symval(&text\_run\_start));}
\]

\[
\text{printf(".text load size is %lx\n", \_symval(&text\_run\_size));}
\]

See Section 8.6.1 for more information about referring to linker symbols in C/C++ code.

\subsection{Input Items}

Consider an output section specification within a SECTIONS directive:

\[
\text{outsect:}
\]

\[
\{ \\
\quad s1.obj(.text) \\
\quad \text{end\_of\_s1} = .; \\
\quad \text{start\_of\_s2} = .; \\
\quad s2.obj(.text) \\
\quad \text{end\_of\_s2} = .; \\
\}
\]

This can be rewritten using the START and END operators as follows:

\[
\text{outsect:}
\]

\[
\{ \\
\quad s1.obj(.text) \{ \text{END(end\_of\_s1)} \} \\
\quad s2.obj(.text) \{ \text{START(start\_of\_s2), END(end\_of\_s2)} \} \\
\}
\]

The values of end\_of\_s1 and end\_of\_s2 will be the same as if you had used the dot operator in the original example, but start\_of\_s2 would be defined after any necessary padding that needs to be added between the two .text sections. Remember that the dot operator would cause start\_of\_s2 to be defined before any necessary padding is inserted between the two input sections.

The syntax for using these operators in association with input sections calls for braces \{ \} to enclose the operator list. The operators in the list are applied to the input item that occurs immediately before the list.

\subsection{Output Section}

The START, END, and SIZE operators can also be associated with an output section. Here is an example:

\[
\text{outsect: START(start\_of\_outsect), SIZE(size\_of\_outsect) \{ \\
\quad <\text{list of input items}> \\
\}}
\]

In this case, the SIZE operator defines size\_of\_outsect to incorporate any padding that is required in the output section to conform to any alignment requirements that are imposed.

The syntax for specifying the operators with an output section does not require braces to enclose the operator list. The operator list is simply included as part of the allocation specification for an output section.
8.5.10.7.3 GROUPs

Here is another use of the START and SIZE operators in the context of a GROUP specification:

```
GROUP
    { outsect1: { ... } }
    { outsect2: { ... } }
} load = ROM, run = RAM, START(group_start), SIZE(group_size);
```

This can be useful if the whole GROUP is to be loaded in one location and run in another. The copying code can use group_start and group_size as parameters for where to copy from and how much is to be copied. This makes the use of .label in the source code unnecessary.

8.5.10.7.4 UNIONs

The RUN_SIZE and LOAD_SIZE operators provide a mechanism to distinguish between the size of a UNION's load space and the size of the space where its constituents are going to be copied before they are run. Here is an example:

```
UNION: run = RAM, LOAD_START(union_load_addr),
    LOAD_SIZE(union_ld_sz), RUN_SIZE(union_run_sz)
    { .text1: load = ROM, SIZE(text1_size) { f1.obj(.text) }
    .text2: load = ROM, SIZE(text2_size) { f2.obj(.text) }
    }
```

Here union ld_sz is going to be equal to the sum of the sizes of all output sections placed in the union. The union_run_sz value is equivalent to the largest output section in the union. Both of these symbols incorporate any padding due to blocking or alignment requirements.

8.5.11 Creating and Filling Holes

The linker provides you with the ability to create areas within output sections that have nothing linked into them. These areas are called holes. In special cases, uninitialized sections can also be treated as holes. This section describes how the linker handles holes and how you can fill holes (and uninitialized sections) with values.

8.5.11.1 Initialized and Uninitialized Sections

There are two rules to remember about the contents of output sections. An output section contains either:

- Raw data for the entire section
- No raw data

A section that has raw data is referred to as initialized. This means that the object file contains the actual memory image contents of the section. When the section is loaded, this image is loaded into memory at the section's specified starting address. The .text and .data sections always have raw data if anything was assembled into them. Named sections defined with the .sect assembler directive also have raw data.

By default, the .bss section (see Reserve Space in the .bss Section) and sections defined with the .usect directive (see Reserve Uninitialized Space) have no raw data (they are uninitialized). They occupy space in the memory map but have no actual contents. Uninitialized sections typically reserve space in fast external memory for variables. In the object file, an uninitialized section has a normal section header and can have symbols defined in it; no memory image, however, is stored in the section.

8.5.11.2 Creating Holes

You can create a hole in an initialized output section. A hole is created when you force the linker to leave extra space between input sections within an output section. When such a hole is created, the linker must supply raw data for the hole.

Holes can be created only within output sections. Space can exist between output sections, but such space is not a hole. To fill the space between output sections, see Section 8.5.4.2.
To create a hole in an output section, you must use a special type of linker assignment statement within an output section definition. The assignment statement modifies the SPC (denoted by .) by adding to it, assigning a greater value to it, or aligning it on an address boundary. The operators, expressions, and syntaxes of assignment statements are described in Section 8.5.10.

The following example uses assignment statements to create holes in output sections:

```
SECTIONS
{
  outsect:
  {
    file1.obj(.text) . += 0x0100 /* Create a hole with size 0x0100 */
    file2.obj(.text) . = align(16); /* Create a hole to align the SPC */
    file3.obj(.text) }
}
```

The output section outsect is built as follows:
1. The .text section from file1.obj is linked in.
2. The linker creates a 256-byte hole.
3. The .text section from file2.obj is linked in after the hole.
4. The linker creates another hole by aligning the SPC on a 16-byte boundary.
5. Finally, the .text section from file3.obj is linked in.

All values assigned to the . symbol within a section refer to the relative address within the section. The linker handles assignments to the . symbol as if the section started at address 0 (even if you have specified a binding address). Consider the statement . = align(16) in the example. This statement effectively aligns the file3.obj .text section to start on a 16-byte boundary within outsect. If outsect is ultimately allocated to start on an address that is not aligned, the file3.obj .text section will not be aligned either.

The . symbol refers to the current run address, not the current load address, of the section.

Expressions that decrement the . symbol are illegal. For example, it is invalid to use the -= operator in an assignment to the . symbol. The most common operators used in assignments to the . symbol are += and align.

If an output section contains all input sections of a certain type (such as .text), you can use the following statements to create a hole at the beginning or end of the output section.

```
.text: { .+= 0x0100; } /* Hole at the beginning */
.data: { *(.data) . += 0x0100; } /* Hole at the end */
```

Another way to create a hole in an output section is to combine an uninitialized section with an initialized section to form a single output section. In this case, the linker treats the uninitialized section as a hole and supplies data for it. The following example illustrates this method:

```
SECTIONS
{
  outsect:
  {
    file1.obj(.text) file1.obj(.bss) /* This becomes a hole */
  }
}
```

Because the .text section has raw data, all of outsect must also contain raw data. Therefore, the uninitialized .bss section becomes a hole.

Uninitialized sections become holes only when they are combined with initialized sections. If several uninitialized sections are linked together, the resulting output section is also uninitialized.
8.5.11.3 Filling Holes

When a hole exists in an initialized output section, the linker must supply raw data to fill it. The linker fills holes with a 32-bit fill value that is replicated through memory until it fills the hole. The linker determines the fill value as follows:

1. If the hole is formed by combining an uninitialized section with an initialized section, you can specify a fill value for the uninitialized section. Follow the section name with an = sign and a 32-bit constant. For example:

   ```
   SECTIONS
   { outsect:
     { file1.obj(.text)
       file2.obj(.bss)= 0xFF00FF00 /* Fill this hole with 0xFF00FF00 */
     }
   }
   ```

2. You can also specify a fill value for all the holes in an output section by supplying the fill value after the section definition:

   ```
   SECTIONS
   { outsect:fill = 0xFF00FF00 /* Fills holes with 0xFF00FF00 */
     . += 0x0010; /* This creates a hole */
     file1.obj(.text)
     file1.obj(.bss) /* This creates another hole */
   }
   ```

3. If you do not specify an initialization value for a hole, the linker fills the hole with the value specified with the --fill_value option (see Section 8.4.13). For example, suppose the command file link.cmd contains the following SECTIONS directive:

   ```
   SECTIONS { .text: { .= 0x0100; } /* Create a 100 word hole */ }
   ```

   Now invoke the linker with the --fill_value option:

   ```
   cl6x --run_linker --fill_value=0xFFFFFFFF link.cmd
   ```

   This fills the hole with 0xFFFFFFFF.

4. If you do not invoke the linker with the --fill_value option or otherwise specify a fill value, the linker fills holes with 0s.

Whenever a hole is created and filled in an initialized output section, the hole is identified in the link map along with the value the linker uses to fill it.

8.5.11.4 Explicit Initialization of Uninitialized Sections

You can force the linker to initialize an uninitialized section by specifying an explicit fill value for it in the SECTIONS directive. This causes the entire section to have raw data (the fill value). For example:

```
SECTIONS
{ 
  .bss: fill = 0x12341234 /* Fills .bss with 0x12341234 */
}
```
8.6 Linker Symbols

This section provides information about using and resolving linker symbols.

8.6.1 Using Linker Symbols in C/C++ Applications

Linker symbols have a name and a value. The value is a 32-bit unsigned integer, even if it represents a pointer value on a target that has pointers smaller than 32 bits.

The most common kind of symbol is generated by the compiler for each function and variable. The value represents the target address where that function or variable is located. When you refer to the symbol by name in the linker command file or in an assembly file, you get that 32-bit integer value.

However, in C and C++ names mean something different. If you have a variable named x that contains the value Y, and you use the name "x" in your C program, you are actually referring to the contents of variable x. If "x" is used on the right-hand side of an expression, the compiler fetches the value Y. To realize this variable, the compiler generates a linker symbol named x with the value &x. Even though the C/C++ variable and the linker symbol have the same name, they don't represent the same thing. In C, x is a variable name with the address &x and content Y. For linker symbols, x is an address, and that address contains the value Y.

Because of this difference, there are some tricks to referring to linker symbols in C code. The basic technique is to cause the compiler to creating a "fake" C variable or function and take its address. The details differ depending on the type of linker symbol.

Linker symbols that represent a function address: In C code, declare the function as an extern function. Then, refer to the value of the linker symbol using the same name. This works because function pointers "decay" to their address value when used without adornment. For example:

extern void _c_int00(void);

printf("\_c\_int00 %lx\n", (unsigned long)&\_c\_int00);

Suppose your linker command file defines the following linker symbol:

dfunc\_sym=printf+100;

Your C application can refer to this symbol as follows:

extern void dfunc\_sym(void);

printf("\_func\_sym %lx\n", _symval(dfunc\_sym)); /* these two are equivalent */
printf("\_func\_sym %lx\n", (unsigned long)&dfunc\_sym);

Linker symbols that represent a data address: In C code, declare the variable as an extern variable. Then, refer to the value of the linker symbol using the & operator. Because the variable is at a valid data address, we know that a data pointer can represent the value.

Suppose your linker command file defines the following linker symbols:

data\_sym=.data+100;
xyz=12345

Your C application can refer to these symbols as follows:

extern char data\_sym;
extern int xyz;

printf("\_data\_sym %lx\n", _symval(data\_sym)); /* these two are equivalent */
printf("\_data\_sym %p\n", &data\_sym);

myvar = &xyz;
**Linker Symbols**

**Linker symbols for an arbitrary address:** In C code, declare this as an extern symbol. The type does not matter. If you are using GCC extensions, declare it as "extern void". If you are not using GCC extensions, declare it as "extern char". Then, refer to the value of the linker symbol mySymbol as _symval(&mySymbol). You must use the _symval operator, which is equivalent to a cast, because the 32-bit value of the linker symbol could be wider than a data pointer. The compiler treats _symval(&mySymbol) in a special way that can represent all 32 bits, even when pointers are 16 bits. Targets that have 32-bit pointers can usually use &mySymbol instead of the _symval operator. However, the portable way to access such linker symbols across TI targets is to use _symval(&mySymbol).

Suppose your linker command file defines the following linker symbol:

```c
abs_sym=0x12345678;
```

Your C application can refer to this symbol as follows:

```c
extern char abs_sym;
printf("abs_sym %lx\n", _symval(&abs_sym));
```

### 8.6.2 Declaring Weak Symbols

In a linker command file, an assignment expression outside a MEMORY or SECTIONS directive can be used to define a linker-defined symbol. To define a weak symbol in a linker command file, use the "weak" operator in an assignment expression to designate that the symbol as eligible for removal from the output file’s symbol table if it is not referenced. For example, you can define "ext_addr_sym" as follows:

```c
weak(ext_addr_sym) = 0x12345678;
```

When the linker command file is used to perform the final link, then "ext_addr_sym" is presented to the linker as a weak absolute symbol; it will not be included in the resulting output file if the symbol is not referenced.

See Section 2.6.2 for details about how weak symbols are handled by the linker.

### 8.6.3 Resolving Symbols with Object Libraries

An object library is a partitioned archive file that contains object files as members. Usually, a group of related modules are grouped together into a library. When you specify an object library as linker input, the linker includes any members of the library that define existing unresolved symbol references. You can use the archiver to build and maintain libraries. Section 7.1 contains more information about the archiver.

Using object libraries can reduce link time and the size of the executable module. Normally, if an object file that contains a function is specified at link time, the file is linked whether the function is used or not; however, if that same function is placed in an archive library, the file is included only if the function is referenced.

The order in which libraries are specified is important, because the linker includes only those members that resolve symbols that are undefined at the time the library is searched. The same library can be specified as often as necessary; it is searched each time it is included. Alternatively, you can use the --reread_libs option to reread libraries until no more references can be resolved (see Section 8.4.16.3). A library has a table that lists all external symbols defined in the library; the linker searches through the table until it determines that it cannot use the library to resolve any more references.

The following examples link several files and libraries, using these assumptions:

- Input files f1.obj and f2.obj both reference an external function named clrscr.
- Input file f1.obj references the symbol origin.
- Input file f2.obj references the symbol fillclr.
- Member 0 of library libc.lib contains a definition of origin.
- Member 3 of library liba.lib contains a definition of fillclr.
- Member 1 of both libraries defines clrscr.
If you enter:

```
cl6x --run_linker f1.obj f2.obj liba.lib libc.lib
```

then:

- Member 1 of liba.lib satisfies the f1.obj and f2.obj references to `clrscr` because the library is searched and the definition of `clrscr` is found.
- Member 0 of libc.lib satisfies the reference to `origin`.
- Member 3 of liba.lib satisfies the reference to `fillclr`.

If, however, you enter:

```
cl6x --run_linker f1.obj f2.obj libc.lib liba.lib
```

then the references to `clrscr` are satisfied by member 1 of libc.lib.

If none of the linked files reference symbols defined in a library, you can use the `--undef_sym` option to force the linker to include a library member. (See Section 8.4.32.) The next example creates an undefined symbol `rout1` in the linker's global symbol table:

```
cl6x --run_linker --undef_sym=rout1 libc.lib
```

If any member of libc.lib defines `rout1`, the linker includes that member.

Library members are allocated according to the SECTIONS directive default allocation algorithm; see Section 8.5.5.

Section 8.4.16 describes methods for specifying directories that contain object libraries.
8.7 Default Placement Algorithm

The MEMORY and SECTIONS directives provide flexible methods for building, combining, and allocating sections. However, any memory locations or sections you choose not to specify must still be handled by the linker. The linker uses algorithms to build and allocate sections in coordination with any specifications you do supply.

If you do not use the MEMORY and SECTIONS directives, the linker allocates output sections as though the memory map and section definitions were as shown in Example 8-16 were specified.

Example 8-16. Default Allocation for TMS320C6000 Devices

```
MEMORY
{
    RAM : origin = 0x00000001, length = 0xFFFFFFFF
}
SECTIONS
{
    .text : ALIGN(32) {} > RAM
    .const : ALIGN(8) {} > RAM
    .data : ALIGN(8) {} > RAM
    .bss : ALIGN(8) {} > RAM
    .cinit : ALIGN(4) {} > RAM ; cflag option only
    .pinit : ALIGN(4) {} > RAM ; cflag option only
    .stack : ALIGN(8) {} > RAM ; cflag option only
    .far : ALIGN(8) {} > RAM ; cflag option only
    .sysmem: ALIGN(8) {} > RAM ; cflag option only
    .switch: ALIGN(4) {} > RAM ; cflag option only
    .cio : ALIGN(4) {} > RAM ; cflag option only
}
```

Also see Section 2.5.1 for information about default memory allocation.

All .text input sections are concatenated to form a .text output section in the executable output file, and all .data input sections are combined to form a .data output section.

If you use a SECTIONS directive, the linker performs no part of this default allocation. Instead, allocation is performed according to the rules specified by the SECTIONS directive and the general algorithm described next in Section 8.7.1.

8.7.1 How the Allocation Algorithm Creates Output Sections

An output section can be formed in one of two ways:

- **Method 1** As the result of a SECTIONS directive definition
- **Method 2** By combining input sections with the same name into an output section that is not defined in a SECTIONS directive

If an output section is formed as a result of a SECTIONS directive, this definition completely determines the section's contents. (See Section 8.5.5 for examples of how to define an output section's content.)

If an output section is formed by combining input sections not specified by a SECTIONS directive, the linker combines all such input sections that have the same name into an output section with that name. For example, suppose the files f1.obj and f2.obj both contain named sections called Vectors and that the SECTIONS directive does not define an output section for them. The linker combines the two Vectors sections from the input files into a single output section named Vectors, allocates it into memory, and includes it in the output file.

By default, the linker does not display a message when it creates an output section that is not defined in the SECTIONS directive. You can use the --warn_sections linker option (see Section 8.4.33) to cause the linker to display a message when it creates a new output section.
After the linker determines the composition of all output sections, it must allocate them into configured memory. The MEMORY directive specifies which portions of memory are configured. If there is no MEMORY directive, the linker uses the default configuration as shown in Example 8-16. (See Section 8.5.4 for more information on configuring memory.)

8.7.2 Reducing Memory Fragmentation

The linker's allocation algorithm attempts to minimize memory fragmentation. This allows memory to be used more efficiently and increases the probability that your program will fit into memory. The algorithm comprises these steps:
1. Each output section for which you supply a specific binding address is placed in memory at that address.
2. Each output section that is included in a specific, named memory range or that has memory attribute restrictions is allocated. Each output section is placed into the first available space within the named area, considering alignment where necessary.
3. Any remaining sections are allocated in the order in which they are defined. Sections not defined in a SECTIONS directive are allocated in the order in which they are encountered. Each output section is placed into the first available memory space, considering alignment where necessary.

If you want to control the order in which code and data are placed in memory, see the FAQ topic on section placement.

8.8 Linker-Generated Copy Tables

The linker supports extensions to the linker command file syntax that enable the following:
• Make it easier for you to copy objects from load-space to run-space at boot time
• Make it easier for you to manage memory overlays at run time
• Allow you to split GROUPs and output sections that have separate load and run addresses

8.8.1 Using Copy Tables for Boot Loading

In some embedded applications, there is a need to copy or download code and/or data from one location to another at boot time before the application actually begins its main execution thread. For example, an application may have its code and/or data in FLASH memory and need to copy it into on-chip memory before the application begins execution.

One way to develop such an application is to create a copy table in assembly code that contains three elements for each block of code or data that needs to be moved from FLASH to on-chip memory at boot time:
• The load address
• The run address
• The size

The process you follow to develop such an application might look like this:
1. Build the application to produce a .map file that contains the load and run addresses of each section that has a separate load and run placement.
2. Edit the copy table (used by the boot loader) to correct the load and run addresses as well as the size of each block of code or data that needs to be moved at boot time.
3. Build the application again, incorporating the updated copy table.
4. Run the application.

This process puts a heavy burden on you to maintain the copy table (by hand, no less). Each time a piece of code or data is added or removed from the application, you must repeat the process in order to keep the contents of the copy table up to date.
8.8.2 Using Built-in Link Operators in Copy Tables

You can avoid some of this maintenance burden by using the LOAD_START(), RUN_START(), and SIZE() operators that are already part of the linker command file syntax. For example, instead of building the application to generate a .map file, the linker command file can be annotated:

```c
SECTIONS
{
  .flashcode: { app_tasks.obj(.text) }
  load = FLASH, run = PMEM,
  LOAD_START(_flash_code_ld_start),
  RUN_START(_flash_code_rn_start),
  SIZE(_flash_code_size)
  ...
}
```

In this example, the LOAD_START(), RUN_START(), and SIZE() operators instruct the linker to create three symbols:

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>_flash_code_ld_start</td>
<td>Load address of .flashcode section</td>
</tr>
<tr>
<td>_flash_code_rn_start</td>
<td>Run address of .flashcode section</td>
</tr>
<tr>
<td>_flash_code_size</td>
<td>Size of .flashcode section</td>
</tr>
</tbody>
</table>

These symbols can then be referenced from the copy table. The actual data in the copy table will be updated automatically each time the application is linked. This approach removes step 1 of the process described in Section 8.8.1.

While maintenance of the copy table is reduced markedly, you must still carry the burden of keeping the copy table contents in sync with the symbols that are defined in the linker command file. Ideally, the linker would generate the boot copy table automatically. This would avoid having to build the application twice and free you from having to explicitly manage the contents of the boot copy table.

For more information on the LOAD_START(), RUN_START(), and SIZE() operators, see Section 8.5.10.7.
8.8.3 Overlay Management Example

Consider an application that contains a memory overlay that must be managed at run time. The memory overlay is defined using a UNION in the linker command file as illustrated in Example 8-17:

Example 8-17. Using a UNION for Memory Overlay

```
SECTIONS
{
  ...
  UNION
  {
    GROUP
    {
      .task1: { task1.obj(.text) }
      .task2: { task2.obj(.text) }
    } load = ROM, LOAD_START(_task12_load_start), SIZE(_task12_size)
    GROUP
    {
      .task3: { task3.obj(.text) }
      .task4: { task4.obj(.text) }
    } load = ROM, LOAD_START(_task34_load_start), SIZE(_task34_size)
  } run = RAM, RUN_START(_task_run_start)
  ...
}
```

The application must manage the contents of the memory overlay at run time. That is, whenever any services from .task1 or .task2 are needed, the application must first ensure that .task1 and .task2 are resident in the memory overlay. Similarly for .task3 and .task4.

To affect a copy of .task1 and .task2 from ROM to RAM at run time, the application must first gain access to the load address of the tasks (_task12_load_start), the run address (_task_run_start), and the size (_task12_size). Then this information is used to perform the actual code copy.

8.8.4 Generating Copy Tables With the table() Operator

The linker supports extensions to the linker command file syntax that enable you to do the following:

- Identify any object components that may need to be copied from load space to run space at some point during the run of an application
- Instruct the linker to automatically generate a copy table that contains (at least) the load address, run address, and size of the component that needs to be copied
- Instruct the linker to generate a symbol specified by you that provides the address of a linker-generated copy table. For instance, Example 8-17 can be written as shown in Example 8-18:
Example 8-18. Produce Address for Linker Generated Copy Table

```c
SECTIONS
{
...

UNION
{
    GROUP
    {
        .task1: { task1.obj(.text) }
        .task2: { task2.obj(.text) }
    } load = ROM, table(_task12_copy_table)

    GROUP
    {
        .task3: { task3.obj(.text) }
        .task4: { task4.obj(.text) }
    } load = ROM, table(_task34_copy_table)

    } run = RAM

...

}
```

Using the SECTIONS directive from Example 8-18 in the linker command file, the linker generates two copy tables named: _task12_copy_table and _task34_copy_table. Each copy table provides the load address, run address, and size of the GROUP that is associated with the copy table. This information is accessible from application source code using the linker-generated symbols, _task12_copy_table and _task34_copy_table, which provide the addresses of the two copy tables, respectively.

Using this method, you need not worry about the creation or maintenance of a copy table. You can reference the address of any copy table generated by the linker in C/C++ or assembly source code, passing that value to a general purpose copy routine, which will process the copy table and affect the actual copy.

8.8.4.1 The table() Operator

You can use the table() operator to instruct the linker to produce a copy table. A table() operator can be applied to an output section, a GROUP, or a UNION member. The copy table generated for a particular table() specification can be accessed through a symbol specified by you that is provided as an argument to the table() operator. The linker creates a symbol with this name and assigns it the address of the copy table as the value of the symbol. The copy table can then be accessed from the application using the linker-generated symbol.

Each table() specification you apply to members of a given UNION must contain a unique name. If a table() operator is applied to a GROUP, then none of that GROUP's members may be marked with a table() specification. The linker detects violations of these rules and reports them as warnings, ignoring each offending use of the table() specification. The linker does not generate a copy table for erroneous table() operator specifications.

Copy tables can be generated automatically; see Section 8.8.4. The table operator can be used with compression; see Section 8.8.5.
8.8.4.2 Boot-Time Copy Tables

The linker supports a special copy table name, BINIT (or binit), that you can use to create a boot-time copy table. This table is handled before the .cinit section is used to initialize variables at startup. For example, the linker command file for the boot-loaded application described in Section 8.8.2 can be rewritten as follows:

```plaintext
SECTIONS
{
    .flashcode: { app_tasks.obj(.text) }
    load = FLASH, run = PMEM,
    table(BINIT)
    ...
}
```

For this example, the linker creates a copy table that can be accessed through a special linker-generated symbol, __binit__, which contains the list of all object components that need to be copied from their load location to their run location at boot-time. If a linker command file does not contain any uses of table(BINIT), then the __binit__ symbol is given a value of -1 to indicate that a boot-time copy table does not exist for a particular application.

You can apply the table(BINIT) specification to an output section, GROUP, or UNION member. If used in the context of a UNION, only one member of the UNION can be designated with table(BINIT). If applied to a GROUP, then none of that GROUP's members may be marked with table(BINIT). The linker detects violations of these rules and reports them as warnings, ignoring each offending use of the table(BINIT) specification.

8.8.4.3 Using the table() Operator to Manage Object Components

If you have several pieces of code that need to be managed together, then you can apply the same table() operator to several different object components. In addition, if you want to manage a particular object component in multiple ways, you can apply more than one table() operator to it. Consider the linker command file excerpt in Example 8-19:

```plaintext
Example 8-19. Linker Command File to Manage Object Components

SECTIONS
{
    UNION
    {
        .first: { a1.obj(.text), b1.obj(.text), c1.obj(.text) }
        load = EMEM, run = PMEM, table(BINIT), table(_first_ctbl)
    }
    .second: { a2.obj(.text), b2.obj(.text) }
    load = EMEM, run = PMEM, table(_second_ctbl)
    }
    .extra: load = EMEM, run = PMEM, table(BINIT)
    ...
}
```

In this example, the output sections .first and .extra are copied from external memory (EMEM) into program memory (PMEM) at boot time while processing the BINIT copy table. After the application has started executing its main thread, it can then manage the contents of the overlay using the two overlay copy tables named: _first_ctbl and _second_ctbl.
8.8.4.4 Linker-Generated Copy Table Sections and Symbols

The linker creates and allocates a separate input section for each copy table that it generates. Each copy table symbol is defined with the address value of the input section that contains the corresponding copy table.

The linker generates a unique name for each overlay copy table input section. For example, table(_first_ctbl) would place the copy table for the .first section into an input section called .ovly:_first_ctbl. The linker creates a single input section, .binit, to contain the entire boot-time copy table.

Example 8-20 illustrates how you can control the placement of the linker-generated copy table sections using the input section names in the linker command file.

Example 8-20. Controlling the Placement of the Linker-Generated Copy Table Sections

```plaintext
SECTIONS
{
  UNION
  {
    .first: { a1.obj(.text), b1.obj(.text), c1.obj(.text) }
      load = EMEM, run = PMEM, table(BINIT), table(_first_ctbl)
    .second: { a2.obj(.text), b2.obj(.text) }
      load = EMEM, run = PMEM, table(_second_ctbl)
  }
  .extra: load = EMEM, run = PMEM, table(BINIT)
  ...
  .ovly: { } > BMEM
  .binit: { } > BMEM
}
```

For the linker command file in Example 8-20, the boot-time copy table is generated into a .binit input section, which is collected into the .binit output section, which is mapped to an address in the BMEM memory area. The _first_ctbl is generated into the .ovly:_first_ctbl input section and the _second_ctbl is generated into the .ovly:_second_ctbl input section. Since the base names of these input sections match the name of the .ovly output section, the input sections are collected into the .ovly output section, which is then mapped to an address in the BMEM memory area.

If you do not provide explicit placement instructions for the linker-generated copy table sections, they are allocated according to the linker's default placement algorithm.

The linker does not allow other types of input sections to be combined with a copy table input section in the same output section. The linker does not allow a copy table section that was created from a partial link session to be used as input to a succeeding link session.
8.8.4.5 Splitting Object Components and Overlay Management

It is possible to split sections that have separate load and run placement instructions. The linker can access both the load address and run address of every piece of a split object component. Using the table() operator, you can tell the linker to generate this information into a copy table. The linker gives each piece of the split object component a COPY_RECORD entry in the copy table object.

For example, consider an application which has seven tasks. Tasks 1 through 3 are overlaid with tasks 4 through 7 (using a UNION directive). The load placement of all of the tasks is split among four different memory areas (LMEM1, LMEM2, LMEM3, and LMEM4). The overlay is defined as part of memory area PMEM. You must move each set of tasks into the overlay at run time before any services from the set are used.

You can use table() operators in combination with splitting operators, >>, to create copy tables that have all the information needed to move either group of tasks into the memory overlay as shown in Example 8-21.

Example 8-21. Creating a Copy Table to Access a Split Object Component

```
SECTIONS
{
  UNION
  {
    .task1to3: { *(.task1), *(.task2), *(.task3) }
    load >> LMEM1 | LMEM2 | LMEM4, table(_task13_ctbl)
  
  GROUP
  {
    .task4: { *(.task4) }
    .task5: { *(.task5) }
    .task6: { *(.task6) }
    .task7: { *(.task7) }
  
  load >> LMEM1 | LMEM3 | LMEM4, table(_task47_ctbl)
  }
}

run = PMEM
...
.ovly: > LMEM4
```
Example 8-22 illustrates a possible driver for such an application.

**Example 8-22. Split Object Component Driver**

```c
#include <cpy_tbl.h>

extern far COPY_TABLE task13_ctbl;
extern far COPY_TABLE task47_ctbl;

extern void task1(void);
...
extern void task7(void);

main()
{
  ...
  copy_in(&task13_ctbl);
  task1();
  task2();
  task3();
  ...

  copy_in(&task47_ctbl);
  task4();
  task5();
  task6();
  task7();
  ...
}
```

You must declare a COPY_TABLE object as `far` to allow the overlay copy table section placement to be independent from the other sections containing data objects (such as `.bss`).

The contents of the `.task1to3` section are split in the section's load space and contiguous in its run space. The linker-generated copy table, `_task13_ctbl`, contains a separate COPY_RECORD for each piece of the split section `.task1to3`. When the address of `_task13_ctbl` is passed to `copy_in()`, each piece of `.task1to3` is copied from its load location into the run location.

The contents of the GROUP containing tasks 4 through 7 are also split in load space. The linker performs the GROUP split by applying the split operator to each member of the GROUP in order. The copy table for the GROUP then contains a COPY_RECORD entry for every piece of every member of the GROUP. These pieces are copied into the memory overlay when the `_task47_ctbl` is processed by `copy_in()`.

The split operator can be applied to an output section, GROUP, or the load placement of a UNION or UNION member. The linker does not permit a split operator to be applied to the run placement of either a UNION or of a UNION member. The linker detects such violations, emits a warning, and ignores the offending split operator usage.
8.8.5 Compression

When automatically generating copy tables, the linker provides a way to compress the load-space data. This can reduce the read-only memory footprint. This compressed data can be decompressed while copying the data from load space to run space.

You can specify compression in two ways:

- The linker command line option --copy_compression=compression_kind can be used to apply the specified compression to any output section that has a table() operator applied to it.
- The table() operator accepts an optional compression parameter. The syntax is:

  table( name, compression= compression_kind )

  The compression_kind can be one of the following types:
  - off. Don't compress the data.
  - rle. Compress data using Run Length Encoding.

A table() operator without the compression keyword uses the compression kind specified using the command line option --copy_compression.

When you choose compression, it is not guaranteed that the linker will compress the load data. The linker compresses load data only when such compression reduces the overall size of the load space. In some cases even if the compression results in smaller load section size the linker does not compress the data if the decompression routine offsets for the savings.

For example, assume RLE compression reduces the size of section1 by 30 bytes. Also assume the RLE decompression routine takes up 40 bytes in load space. By choosing to compress section1 the load space is increased by 10 bytes. Therefore, the linker will not compress section1. On the other hand, if there is another section (say section2) that can benefit by more than 10 bytes from applying the same compression then both sections can be compressed and the overall load space is reduced. In such cases the linker compresses both the sections.

You cannot force the linker to compress the data when doing so does not result in savings.

You cannot compress the decompression routines or any member of a GROUP containing .cinit.

8.8.5.1 Compressed Copy Table Format

The copy table format is the same irrespective of the compression. The size field of the copy record is overloaded to support compression. Figure 8-5 illustrates the compressed copy table layout.

**Figure 8-5. Compressed Copy Table**

<table>
<thead>
<tr>
<th>Rec size</th>
<th>Rec cnt</th>
</tr>
</thead>
<tbody>
<tr>
<td>Load address</td>
<td>Run address</td>
</tr>
</tbody>
</table>

In Figure 8-5, if the size in the copy record is non-zero it represents the size of the data to be copied, and also means that the size of the load data is the same as the run data. When the size is 0, it means that the load data is compressed.

8.8.5.2 Compressed Section Representation in the Object File

When the load data is not compressed, the object file can have only one section with a different load and run address.

Consider the following table() operation in the linker command file.

```plaintext
SECTIONS
{
  .task1: load = ROM, run = RAM, table(_task1_table)
}
```
The output object file has one output section named .task1 which has a different load and run addresses. This is possible because the load space and run space have identical data when the section is not compressed.

Alternatively, consider the following:

```c
SECTIONS
{
  .task1: load = ROM, run = RAM, table(_task1_table, compression=rle)
}
```

If the linker compresses the .task1 section then the load space data and the run space data are different. The linker creates the following two sections:

- **.task1**: This section is uninitialized. This output section represents the run space image of section task1.
- **.task1.load**: This section is initialized. This output section represents the load space image of the section task1. This section usually is considerably smaller in size than .task1 output section.

### 8.8.5.3 Compressed Data Layout

The compressed load data has the following layout:

<table>
<thead>
<tr>
<th>8-bit index</th>
<th>Compressed data</th>
</tr>
</thead>
</table>

The first eight bits of the load data are the handler index. This handler index is used to index into a handler table to get the address of a handler function that knows how to decode the data that follows. The handler table is a list of 32-bit function pointers as shown in Figure 8-6.

**Figure 8-6. Handler Table**

```
_TI_Handler_Table_Base:
   32-bit handler address 1
     :
     :
   32-bit handler address N

_TI_Handler_Table_Limit:
```

The linker creates a separate output section for the load and run space. For example, if .task1.load is compressed using RLE, the handler index points to an entry in the handler table that has the address of the run-time-support routine __TI_decompress_rle().

### 8.8.5.4 Run-Time Decompression

During run time you call the run-time-support routine copy_in() to copy the data from load space to run space. The address of the copy table is passed to this routine. First the routine reads the record count. Then it repeats the following steps for each record:

1. Read load address, run address and size from record.
2. If size is zero go to step 5.
3. Call memcpy passing the run address, load address and size.
4. Go to step 1 if there are more records to read.
5. Read the first byte from load address. Call this index.
6. Read the handler address from (&__TI_Handler_Base)[index].
7. Call the handler and pass load address + 1 and run address.
8. Go to step 1 if there are more records to read.

The routines to handle the decompression of load data are provided in the run-time-support library.
8.8.5.5 Compression Algorithms

**Run Length Encoding (RLE):**

| 8-bit index | Initialization data compressed using run length encoding |

The data following the 8-bit index is compressed using run length encoded (RLE) format. C6000 uses a simple run length encoding that can be decompressed using the following algorithm:

1. Read the first byte, Delimiter (D).
2. Read the next byte (B).
3. If B ≠ D, copy B to the output buffer and go to step 2.
4. Read the next byte (L).
   (a) If L == 0, then length is either a 16-bit, a 24-bit value, or we’ve reached the end of the data, read next byte (L).
   (i) If L == 0, length is a 24-bit value or the end of the data is reached, read next byte (L).
   (ii) If L == 0, the end of the data is reached, go to step 7.
   (ii) Else L <<= 16, read next two bytes into lower 16 bits of L to complete 24-bit value for L.
   (ii) Else L <<= 8, read next byte into lower 8 bits of L to complete 16-bit value for L.
   (b) Else if L > 0 and L < 4, copy D to the output buffer L times. Go to step 2.
   (c) Else, length is 8-bit value (L).
5. Read the next byte (C); C is the repeat character.
6. Write C to the output buffer L times; go to step 2.
7. End of processing.

The C6000 run-time support library has a routine `__TI_decompress_rle24()` to decompress data compressed using RLE. The first argument to this function is the address pointing to the byte after the 8-bit index. The second argument is the run address from the C auto initialization record.

**RLE Decompression Routine**

**NOTE:** The previous decompression routine, `__TI_decompress_rle()`, is included in the run-time-support library for decompressing RLE encodings that are generated by older versions of the linker.

**Lempel-Ziv-Storer-Szymanski Compression (LZSS):**

| 8-bit index | Data compressed using LZSS |

The data following the 8-bit index is compressed using LZSS compression. The C6000 run-time-support library has the routine `__TI_decompress_lzss()` to decompress the data compressed using LZSS. The first argument to this function is the address pointing to the byte after the 8-bit Index, and the second argument is the run address from the C auto initialization record.
8.8.6 Copy Table Contents

To use a copy table generated by the linker, you must know the contents of the copy table. This information is included in a run-time-support library header file, cpy_tbl.h, which contains a C source representation of the copy table data structure that is generated by the linker. Example 8-23 shows the copy table header file.

Example 8-23. TMS320C6000 cpy_tbl.h File

```c
/* cpy_tbl.h
/*
/* Copyright (c) 2011 Texas Instruments Incorporated */
/* Specification of copy table data structures which can be automatically */
/* generated by the linker (using the table() operator in the LCF). */
/*
/****************************************************************************/
/****************************************************************************/
/* Copy Record Data Structure */
/****************************************************************************/
typedef struct copy_record
{
    unsigned int load_addr;
    unsigned int run_addr;
    unsigned int size;
} COPY_RECORD;

/****************************************************************************/
/* Copy Table Data Structure */
/****************************************************************************/
typedef struct copy_table
{
    unsigned short rec_size;
    unsigned short num_recs;
    COPY_RECORD recs[1];
} COPY_TABLE;

/****************************************************************************/
/* Prototype for general purpose copy routine. */
/****************************************************************************/
extern void copy_in(COPY_TABLE *tp);

#ifdef __cplusplus
} /* extern "C" namespace std */
#endif /* _CPP_STYLE_HEADER */
using std::COPY_RECORD;
using std::COPY_TABLE;
using std::copy_in;
#endif /* !_CPY_TBL */
```

For each object component that is marked for a copy, the linker creates a COPY_RECORD object for it. Each COPY_RECORD contains at least the following information for the object component:

- The load address
- The run address
- The size
The linker collects all COPY_RECORDs that are associated with the same copy table into a COPY_TABLE object. The COPY_TABLE object contains the size of a given COPY_RECORD, the number of COPY_RECORDs in the table, and the array of COPY_RECORDs in the table. For instance, in the BINIT example in Section 8.8.4.2, the .first and .extra output sections will each have their own COPY_RECORD entries in the BINIT copy table. The BINIT copy table will then look like this:

```c
COPY_TABLE __binit__ = { 12, 2,
    { <load address of .first>,
      <run address of .first>,
      <size of .first> },
    { <load address of .extra>,
      <run address of .extra>,
      <size of .extra> } };
```

### 8.8.7 General Purpose Copy Routine

The cpy_tbl.h file in Example 8-23 also contains a prototype for a general-purpose copy routine, copy_in(), which is provided as part of the run-time-support library. The copy_in() routine takes a single argument: the address of a linker-generated copy table. The routine then processes the copy table data object and performs the copy of each object component specified in the copy table.

The copy_in() function definition is provided in the cpy_tbl.c run-time-support source file shown in Example 8-24.

**Example 8-24. Run-Time-Support cpy_tbl.c File**

```c
#include <cpy_tbl.h>
#include <string.h>

typedef void (*handler_fptr)(const unsigned char *in, unsigned char *out);

void copy_in(COPY_TABLE *tp)
{
    unsigned short I;

    for (I = 0; I < tp->num_recs; I++)
    {
        COPY_RECORD crp = tp->recs[I];
        unsigned char *ld_addr = (unsigned char *)crp.load_addr;
        unsigned char *rn_addr = (unsigned char *)crp.run_addr;

        if (crp.size)
        {
            /* Copy record has a non-zero size so the data is not compressed. */
            /* Just copy the data. */
            memcpy(rn_addr, ld_addr, crp.size);
        }
```
Example 8-24. Run-Time-Support cpy_tbl.c File (continued)

```c
#ifdef __TI_EABI__
    else if (HANDLER_TABLE)
    {
        /*------------------------------------------------------------------
        /* Copy record has size zero so the data is compressed. The first */
        /* byte of the load data has the handler index. Use this index with */
        /* the handler table to get the handler for this data. Then call */
        /* the handler by passing the load and run address. */
        /*------------------------------------------------------------------
        unsigned char index = *((unsigned char *)ld_addr++);
        handler_fptr hndl = (handler_fptr)(&HANDLER_TABLE)[index];
        (*hndl)((const unsigned char *)ld_addr, (unsigned char *)rn_addr);
    }
#endif
}
```

8.9 Partial (Incremental) Linking

An output file that has been linked can be linked again with additional modules. This is known as partial linking or incremental linking. Partial linking allows you to partition large applications, link each part separately, and then link all the parts together to create the final executable program.

Follow these guidelines for producing a file that you will relink:

- The intermediate files produced by the linker must have relocation information. Use the --relocatable option when you link the file the first time. (See Section 8.4.3.2.)
- Intermediate files must have symbolic information. By default, the linker retains symbolic information in its output. Do not use the --no_sym_table option if you plan to relink a file, because --no_sym_table strips symbolic information from the output module. (See Section 8.4.22.)
- Intermediate link operations should be concerned only with the formation of output sections and not with allocation. All allocation, binding, and MEMORY directives should be performed in the final link. Since the ELF object file format is used, input sections are not combined into output sections during a partial link unless a matching SECTIONS directive is specified in the link step command file.
- If the intermediate files have global symbols that have the same name as global symbols in other files and you want them to be treated as static (visible only within the intermediate file), you must link the files with the --make_static option (see Section 8.4.17.1).
- If you are linking C code, do not use --ram_model or --rom_model until the final linker. Every time you invoke the linker with the --ram_model or --rom_model option, the linker attempts to create an entry point. (See Section 8.4.25, Section 3.3.2.1, and Section 3.3.2.2.)

The following example shows how you can use partial linking:

**Step 1:** Link the file file1.com; use the --relocatable option to retain relocation information in the output file tempout1.out.

```
cl6x --run_linker --relocatable --output_file=tempout1 file1.com
```

file1.com contains:

```c
SECTIONS
{
    ss1:    { f1.obj
              f2.obj
              ...
              fn.obj
        }
}
```
Step 2: Link the file file2.com; use the --relocatable option to retain relocation information in the output file tempout2.out.

```
cl6x --run_linker --relocatable --output_file=tempout2 file2.com
```

file2.com contains:

```
SECTIONS
{
  ss2: {
    g1.obj
    g2.obj
    .
    .
    .
    gn.obj
  }
}
```

Step 3: Link tempout1.out and tempout2.out.

```
cl6x --run_linker --map_file=final.map --
  output_file=final.out tempout1.out tempout2.out
```

8.10 Linking C/C++ Code

The C/C++ compiler produces assembly language source code that can be assembled and linked. For example, a C program consisting of modules prog1, prog2, etc., can be assembled and then linked to produce an executable file called prog.out:

```
cl6x --run_linker --rom_model --
  output_file prog.out prog1.obj prog2.obj ... rts6600_elf.lib
```

The --rom_model option tells the linker to use special conventions that are defined by the C/C++ environment.

The archive libraries shipped by TI contain C/C++ run-time-support functions.

C, C++, and mixed C and C++ programs can use the same run-time-support library. Run-time-support functions and variables that can be called and referenced from both C and C++ will have the same linkage.

For more information about the TMS320C6000 C/C++ language, including the run-time environment and run-time-support functions, see the TMS320C6000 Optimizing Compiler User's Guide.

8.10.1 Run-Time Initialization

All C/C++ programs must be linked with code to initialize and execute the program, called a bootstrap routine, also known as the boot.obj object module. The symbol _c_int00 is defined as the program entry point and is the start of the C boot routine in boot.obj; referencing _c_int00 ensures that boot.obj is automatically linked in from the run-time-support library. When a program begins running, it executes boot.obj first. The boot.obj symbol contains code and data for initializing the run-time environment and performs the following tasks:

- Sets up the system stack and configuration registers
- Processes the run-time .cinit initialization table and autoinitializes global variables (when the linker is invoked with the --rom_model option)
- Disables interrupts and calls _main

The run-time-support object libraries contain boot.obj. You can:

- Use the archiver to extract boot.obj from the library and then link the module in directly.
- Include the appropriate run-time-support library as an input file (the linker automatically extracts boot.obj when you use the --ram_model or --rom_model option).
8.10.2 Object Libraries and Run-Time Support

The TMS320C6000 Optimizing Compiler User's Guide describes additional run-time-support functions that are included in rts.src. If your program uses any of these functions, you must link the appropriate run-time-support library with your object files.

You can also create your own object libraries and link them. The linker includes and links only those library members that resolve undefined references.

8.10.3 Setting the Size of the Stack and Heap Sections

The C/C++ language uses two uninitialized sections called .sysmem and .stack for the memory pool used by the malloc() functions and the run-time stacks, respectively. You can set the size of these by using the --heap_size or --stack_size option and specifying the size of the section as a 4-byte constant immediately after the option. If the options are not used, the default size of the heap is 1K bytes and the default size of the stack is 1K bytes.

See Section 8.4.14 for setting heap sizes and Section 8.4.28 for setting stack sizes.

8.10.4 Initializing and AutoInitializing Variables at Run Time

Autoinitializing variables at run time is the default method of autoinitialization. To use this method, invoke the linker with the --rom_model option. See Section 3.3.2.1 for details.

Initialization of variables at load time enhances performance by reducing boot time and by saving the memory used by the initialization tables. To use this method, invoke the linker with the --ram_model option. See Section 3.3.2.2 for details.

See Section 3.3.2.3 for information about the steps that are performed when you invoke the linker with the --ram_model or --rom_model option.
This example links three object files named demo.obj, filter.obj, tables.obj, and lex.obj and creates a program called demo.out.

Assume that target memory has the following program memory configuration:

<table>
<thead>
<tr>
<th>Address Range</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00000020 to 0x00210000</td>
<td>PMEM</td>
</tr>
<tr>
<td>0x00400000 to 0x01400000</td>
<td>EXT0</td>
</tr>
<tr>
<td>0x01400000 to 0x01800000</td>
<td>EXT1</td>
</tr>
<tr>
<td>0x02000000 to 0x03000000</td>
<td>EXT2</td>
</tr>
<tr>
<td>0x03000000 to 0x04000000</td>
<td>EXT3</td>
</tr>
<tr>
<td>0x80000000 to 0x82000000</td>
<td>BMEM</td>
</tr>
</tbody>
</table>

The output sections are constructed in the following manner:

- Executable code, contained in the .text sections of demo.obj, filter.obj, and lex.obj, as well as executable code from the RTS library, are linked into program memory PMEM.

- Two data objects are defined in tables.obj. Each is placed in its own output section: .tableA and .tableB. When the program is loaded, both the .tableA and .tableB output sections are linked into separate locations in the BMEM area. However, run-time access to these tables refers to the run-time location indicated by the symbol "filter_matrix", which is defined as the start address of the UNION containing both .tableA and .tableB. This location is linked into the EXT1 memory area. At run-time, the application is responsible for copying either .tableA or .tableB from its load location in BMEM to its run location in EXT1 before attempting to access data from the table that was copied. The linker supports the copy table mechanisms described in Section 8.8 to help facilitate this action.

- All data objects that are accessed using DP-relative addressing are collected into a group consisting of the .neardata, .rodata, and .bss output sections. This group is linked into the BMEM memory area.

- Since the demo.out program uses command line arguments that must be specified when demo.out is loaded and run, the application must reserve space for passing command-line arguments to the program in the .args section. The amount of space allocated for the .args section is indicated in the "--args 0x1000" option near the top of the linker command file. The .args output section is then linked into the BMEM memory area. Support for processing command-line arguments is provided in the boot routine contained in the RTS library that will be linked into the demo.out program.

- The size of the software stack is indicated by the "--stack 0x6000" option near the top of the linker command file. Likewise, the size of the heap, from which memory can be dynamically allocated at run-time, is indicated via the "--heap 0x3000" option near the top of the linker command file. Both the .stack and .sysmem (which contains the heap) output sections are linked into the BMEM memory area.

---

**Linker Description**

SPRU03A—January 2016

Copyright © 2016, Texas Instruments Incorporated

Submit Documentation Feedback
Example 8-25 shows the linker command file for this example. Example 8-26 shows the map file.

**Example 8-25. Linker Command File, mylnk.cmd**

```plaintext
/****************************************************************************/
/*** Specify Linker Options  **********************************************/
-heap 0x3000
-stack 0x6000
-args 0x1000
--output_file=demo.out /* Name the output file */
--map_file=demo.map /* Create an output map file */

-u filter_table_A
-u filter_table_B

/****************************************************************************/
/*** Specify the Input Files  **********************************************/
demo.obj
tables.obj
filter.obj
lex.obj

/****************************************************************************/
/*** Specify Runtime Support Library to be linked in  **********************/
-l libc.a

/****************************************************************************/
/*** Specify the Memory Configuration  **********************************/
MEMORY
{
  PMEM: o = 00000020h  l = 0020ffe0h
  EXT0: o = 00400000h  l = 01000000h
  EXT1: o = 01400000h  l = 00400000h
  EXT2: o = 02000000h  l = 01000000h
  EXT3: o = 03000000h  l = 01000000h
  BMEM: o = 80000000h  l = 02000000h
}

/****************************************************************************/
/* Specify the Output Sections  ******************************************/

SECTIONS
{
  .text : > PMEM

  UNION
  {
    .tableA: { tables.obj(.tableA) } load > BMEM, table(tableA_cpy)
    .tableB: { tables.obj(.tableB) } load > BMEM, table(tableB_cpy)
  } RUN = EXT1, RUN_START(filter_matrix)

  GROUP
  {
    .neardata:
    .rodata:
    .bss:
  } > EXT2
```

```
Example 8-25. Linker Command File, mylnk.cmd (continued)

```
.stack:    > BMEM
.args :    > BMEM
.cinit:    > BMEM
.cio:      > BMEM
.const:     > BMEM
.data:     > BMEM
.switch:   > BMEM
.sysmem:   > BMEM
.far:      > BMEM
.fardata:  > BMEM
.ppinfo:   > BMEM
}
/****************************************************************************/
/*** End of Command File ***/
/****************************************************************************/
```

Invoke the linker by entering the following command:

```
c16x --run_linker mylnk.cmd
```

This creates the map file shown in Example 8-26 and an output file called demo.out that can be run on a TMS320C6000.
Example 8-26. Output Map File, demo.map

OUTPUT FILE NAME: <demo.out>
ENTRY POINT SYMBOL: "_c_int00" address: 00007a00

MEMORY CONFIGURATION

<table>
<thead>
<tr>
<th>name</th>
<th>origin</th>
<th>length</th>
<th>used</th>
<th>unused</th>
<th>attr</th>
<th>fill</th>
</tr>
</thead>
<tbody>
<tr>
<td>PMEM</td>
<td>00000020</td>
<td>0020ffe0</td>
<td>00008080</td>
<td>00207f60</td>
<td>RWIX</td>
<td></td>
</tr>
<tr>
<td>EXT0</td>
<td>00400000</td>
<td>01000000</td>
<td>00000000</td>
<td>01000000</td>
<td>RWIX</td>
<td></td>
</tr>
<tr>
<td>EXT1</td>
<td>01400000</td>
<td>00400000</td>
<td>00000030</td>
<td>003fffd0</td>
<td>RWIX</td>
<td></td>
</tr>
<tr>
<td>EXT2</td>
<td>02000000</td>
<td>01000000</td>
<td>0000001c</td>
<td>00fffe4</td>
<td>RWIX</td>
<td></td>
</tr>
<tr>
<td>EXT3</td>
<td>03000000</td>
<td>01000000</td>
<td>00000000</td>
<td>01000000</td>
<td>RWIX</td>
<td></td>
</tr>
<tr>
<td>BMEM</td>
<td>80000000</td>
<td>02000000</td>
<td>0000a9d4</td>
<td>01ff562c</td>
<td>RWIX</td>
<td></td>
</tr>
</tbody>
</table>

SEGMENT ALLOCATION MAP

<table>
<thead>
<tr>
<th>run origin</th>
<th>load origin</th>
<th>length</th>
<th>init length</th>
<th>attrs</th>
<th>members</th>
</tr>
</thead>
<tbody>
<tr>
<td>00000020</td>
<td>00000020</td>
<td>00008080</td>
<td>00008080</td>
<td>r-x</td>
<td></td>
</tr>
<tr>
<td>00000020</td>
<td>00000020</td>
<td>00008060</td>
<td>00008060</td>
<td>r-x</td>
<td>.text</td>
</tr>
<tr>
<td>00000020</td>
<td>00000020</td>
<td>00000020</td>
<td>00000020</td>
<td>r--</td>
<td>.ovly</td>
</tr>
<tr>
<td>01400000</td>
<td>8000a8c0</td>
<td>00000030</td>
<td>00000030</td>
<td>rw-</td>
<td></td>
</tr>
<tr>
<td>01400000</td>
<td>8000a8c0</td>
<td>00000030</td>
<td>00000030</td>
<td>rw-</td>
<td>.tableA</td>
</tr>
<tr>
<td>01400000</td>
<td>8000a8f0</td>
<td>00000030</td>
<td>00000030</td>
<td>rw-</td>
<td>.tableB</td>
</tr>
<tr>
<td>02000000</td>
<td>02000000</td>
<td>00000001c</td>
<td>000000000</td>
<td>rw-</td>
<td>.neardata</td>
</tr>
<tr>
<td>80000000</td>
<td>80000000</td>
<td>00000600</td>
<td>00000600</td>
<td>rw-</td>
<td>.stack</td>
</tr>
<tr>
<td>80006000</td>
<td>80006000</td>
<td>00000300</td>
<td>000000000</td>
<td>rw-</td>
<td>.sysmem</td>
</tr>
<tr>
<td>80009000</td>
<td>80009000</td>
<td>00001398</td>
<td>000001000</td>
<td>rw-</td>
<td></td>
</tr>
<tr>
<td>80009000</td>
<td>80009000</td>
<td>00001000</td>
<td>000001000</td>
<td>rw-</td>
<td>.args</td>
</tr>
<tr>
<td>8000a800</td>
<td>8000a800</td>
<td>00000398</td>
<td>000000000</td>
<td>rw-</td>
<td>.fardata</td>
</tr>
<tr>
<td>8000a398</td>
<td>8000a398</td>
<td>00000288</td>
<td>00000288</td>
<td>r--</td>
<td>.const</td>
</tr>
<tr>
<td>8000a620</td>
<td>8000a620</td>
<td>00000268</td>
<td>000000000</td>
<td>rw-</td>
<td>.far</td>
</tr>
<tr>
<td>8000a768</td>
<td>8000a768</td>
<td>00000120</td>
<td>000000000</td>
<td>rw-</td>
<td>.cio</td>
</tr>
<tr>
<td>8000a888</td>
<td>8000a888</td>
<td>00000038</td>
<td>00000038</td>
<td>r--</td>
<td>.switch</td>
</tr>
<tr>
<td>8000a920</td>
<td>8000a920</td>
<td>000000b4</td>
<td>000000b4</td>
<td>r--</td>
<td>.cinit</td>
</tr>
</tbody>
</table>

SECTION ALLOCATION MAP

<table>
<thead>
<tr>
<th>output attributes/section page</th>
<th>origin</th>
<th>length</th>
<th>input sections</th>
</tr>
</thead>
<tbody>
<tr>
<td>.text</td>
<td>0</td>
<td>00000020</td>
<td>0000005c0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>rts6740_elf.lib: divd.obj (.text:__c6xabi_divd)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>:_printfi.obj (.text:_getarg_diouxp)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>:_printfi.obj (.text:_setfield)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>:<em>printfi.obj (.text:</em> TI_printfi)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>:fputs.obj (.text:fputs)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>...</td>
</tr>
<tr>
<td>.neardata</td>
<td>0</td>
<td>02000000</td>
<td>0000001c</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>UNINITIALIZED</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0</td>
<td>02000000</td>
</tr>
</tbody>
</table>
Example 8-26. Output Map File, demo.map (continued)

```
.rodata 0 0200001c 00000000 UNINITIALIZED
.bss 0 0200001c 00000000 UNINITIALIZED
.stack 0 80000000 00006000 UNINITIALIZED
  80000000 00000008 rts740_elf.lib : boot.obj (.stack)
  80000008 00005ff8 --HOLE--
.sysmem 0 80006000 00003000 UNINITIALIZED
  80006000 00000008 rts740_elf.lib : memory.obj (.sysmem)
  80006008 00002ff8 --HOLE--
.[args 0 80009000 00001000
  80009000 00001000 --HOLE-- [fill = 0]
...
.tableA 0 8000a8c0 00000030 RUN ADDR = 01400000
  8000a8c0 00000030 tables.obj (.tableA)
.tableB 0 8000a8f0 00000030 RUN ADDR = 01400000
  8000a8f0 00000030 tables.obj (.tableB)
...

LINKER GENERATED COPY TABLES

tableA_cpy @ 00008080 records: 1, size/record: 12, table size: 16
  .tableA: load addr=8000a8c0, load size=00000030, run addr=01400000,
    run size=00000030, compression=none
.tableB_cpy @ 00008090 records: 1, size/record: 12, table size: 16
  .tableB: load addr=8000a8f0, load size=00000030, run addr=01400000,
    run size=00000030, compression=none
__TI_cinit_table @ 8000a9bc records: 3, size/record: 8, table size: 24
  .fardata: load addr=8000a920, load size=00000072 bytes, run addr=8000a000,
    run size=00000039 bytes, compression=rle
  .neardata: load addr=8000a994, load size=00000014 bytes, run addr=02000000,
    run size=0000001c bytes, compression=rle
  .far: load addr=8000a9b4, load size=00000008 bytes, run addr=8000a620,
    run size=00000048 bytes, compression=zero_init

LINKER GENERATED HANDLER TABLE

__TI_handler_table @ 8000a9a8 records: 3, size/record: 4, table size: 12
  index: 0, handler: __TI_decompress_rle24
  index: 1, handler: __TI_decompress_none
  index: 2, handler: __TI_zero_init

GLOBAL SYMBOLS: SORTED ALPHABETICALLY BY Name

address name
-------- -----
00007fc0 C$$EXIT
00007700 C$$IO$$
000071c0 HOSTclose
00005d20 HOSTlseek
00008080 __TI_table_tableA_cpy
00008090 __TI_table_tableB_cpy
...
[121 symbols]
```
8.12 Dynamic Linking with the C6000 Code Generation Tools

The C6000 v7.2 Code Generation Tools (CGT) support dynamic linking. If you are not already familiar with the EABI support in the C6000 compiler, please see the \textit{C6000 Embedded Application Binary Interface Application Report (SPRAB89).}

The compiler generates object files in ELF object file format. The C6000 CGT makes use of the industry-standard dynamic linking mechanisms that are detailed in the \textit{ELF Specification (Tool Interface Standard).}

8.12.1 Static vs Dynamic Linking

Static linking is the traditional process of combining relocatable object files and static libraries into a static link unit: either an ELF executable file (.exe) or an ELF shared object (.so). The term \textit{object} is used to refer generically to either.

8.12.1.1 Code Size Reduction

A program consists of exactly one executable file (also commonly known as a client application) and any additional shared objects (such as libraries) that it depends on to satisfy any undefined references. If multiple executables depend on the same library, they can share a single copy of its code (hence the “shared” in “shared object”), thereby significantly reducing the memory requirements of the system.

A dynamic shared object (DSO), as the name implies, can be shared among several applications that may be running one-at-a-time in a single threaded environment, or at the same time in a multi-threaded environment. Rather than making a separate copy of the DSO code in memory for each application that needs to use it, a single version of the code can reside in one location (like ROM) where references to its functions can be resolved as the executables and other DSOs that use it are loaded and dynamically linked.

8.12.1.2 Binding Time

In a conventionally linked static executable, symbols are bound to addresses and library code is bound to the executable at link-time, so the library that the executable is bound to at link-time is the one that it will always use, regardless of changes or defect fixes that are made to the library.

In a static shared library, symbols are still bound to addresses at link-time, but the library code is not bound to the executable that uses the library until run-time.

With a dynamic shared library, decisions about binding library symbols to addresses and resolving symbol references between a dynamic shared library and the other objects that use it (or are used by it) are delayed until actual load-time. This allows you to load a shared library when its services are needed, and unload it when its services are not needed. Thus, making more effective use of limited target memory space.

8.12.1.3 Modular Development

Dynamically linking encourages modular development. The interface for a dynamic shared object is explicitly defined via the importing and exporting of global symbols. A cleanly defined interface for a dynamic shared object will tend to improve the cohesion of the code that implements the services provided by a given dynamic object.

8.12.1.4 Recommended Reading

8.12.2 Bare-Metal Dynamic Linking Model

The bare-metal dynamic linking model is intended to support an application environment in which a Real Time Operating System (RTOS) is loaded and running on a DSP processor.

8.12.2.1 Consider a Static DSP Application

First, consider an example of a basic DSP run-time model. If the RTOS and the applications that use it are built as a single static executable, the resulting system will look something like this:

![Figure 8-7. A Basic DSP Run-Time Model](image)

In this scenario, the DSP application is a single static executable file that contains: the RTOS, any required driver functions, and all tasks that the application needs to carry out. All of the addresses in the static executable are bound at link-time, they cannot be relocated at load-time. Execution of the DSP application will proceed from the application's entry point.
8.12.2.2 Make it Dynamic

In a dynamic linking system you can build dynamic modules that are loaded and relocated by a dynamic loader at run time. The dynamic loader can also perform dynamic symbol resolution: resolving symbol references from dynamic modules with the symbol definitions from other dynamic modules. The dynamic linking model supports the creation of such dynamic modules. In particular, it supports creating dynamic executables and dynamic libraries.

A dynamic executable:
- Will have a dynamic segment
- Can export/import symbols
- Is optionally relocatable (can contain dynamic relocations)
- Must have an entry point
- Can be created using -c/-cr compiler options
- Must use far DP or absolute addressing to access imported data, but can use near DP addressing to access its own data

A dynamic library:
- Will have a dynamic segment
- Can export/import symbols
- Is relocatable
- Does not require an entry point
- Cannot be created using -c/-cr compiler option
- Must use far DP or absolute addressing to access its own data as well as data that it imports from other modules

Figure 8-8. Dynamic Linking Model

If we convert the earlier RTOS example into a dynamic system, the RTOS part of the system is still built like an executable and is assumed to be loaded by traditional means (bootstrap loader) and set running on the DSP by a host application.

Application tasks can be built as dynamic libraries that can then be loaded by the dynamic loader and linked against the RTOS that is already loaded and running on the DSP. In this scenario, the RTOS is a dynamic executable and is also sometimes referred to as the base image. The dynamic library is dynamically linked against the RTOS base image at load time.
In Figure 8-8, the dynamic loader is running on a General Purpose Processor (GPP) and is able to interact with the user to load and unload dynamic library components onto the DSP as needed. Another scenario is to load the dynamic loader as part of the RTOS base image executable:

**Figure 8-9. Base Image Executable**

An example of this scenario is the reference implementation of the C6000 dynamic loader. It is written to be built and run as a dynamic executable base image itself. It contains an interactive user interface which allows the user to identify their own base image, load and link dynamic libraries against that base image, and then execute a function that is defined in the dynamic library. For more details about the reference implementation of the dynamic loader, please see the Dynamic Loader wiki article at [http://processors.wiki.ti.com/index.php/C6000_Dynamic_Loader](http://processors.wiki.ti.com/index.php/C6000_Dynamic_Loader).

### 8.12.2.3 Symbol Resolution

A dynamic library in a dynamic DSP application can utilize services that are provided by the RTOS. These functions in the RTOS that are callable from a dynamic library must be exported when the RTOS is built. Similarly, a dynamic library must import any function or data object symbols that are part of the RTOS when the dynamic library is built.

Exported symbols in a dynamic object, dynA, are available for use by any other dynamic object that links with dynA. When a dynamic object imports a symbol, it is asserting that when the object is loaded, the definition of that symbol must be contained in a dynamic object that is already loaded or one that is required to be loaded. The symbol importing and exporting mechanisms lie at the core of how dynamic objects are designed to interact with each other. This subject is explored in more detail in Section 8.12.4.1.

### 8.12.3 Building a Dynamic Executable

A dynamic executable is essentially a statically linked executable file that contains extra information in the form of a dynamic segment that can be used when a dynamic library is loaded and needs symbols that are defined in the dynamic executable.

In the sample system described here, the reference implementation of the dynamic loader (dl6x.6x) is built as a base image. This base image also contains the basic I/O functions and some run-time-support (RTS) functions. The base image should export these I/O and RTS functions. These symbols will then become available to a dynamic library when it is dynamically loaded and linked against the dynamic executable.
8.12.3.1 Exporting Symbols

To accomplish exporting of symbols, there are two methods available:

- **Recommended**: Declare exported symbols explicitly in the source of the dynamic executable using __declspec(dllexport).

  For example, if you want to export exp_func from the dynamic executable, you can declare it in your source as follows:

  ```c
  __declspec(dllexport) int exp_func();
  ```

- Use the --export option at link time. You can specify one or more symbols to be exported with --export=symbol on the linker command line or in a linker command file. For example, you could export exp_func() at link time with:

  ```sh
  cl6x ... -z --dynamic=exe --export=exp_func ...
  ```

In general, to build a dynamic executable, you must specify --dynamic=exe or --dynamic on the linker command line or in a linker command file. Consider the build of the dl6x.6x file described in the Dynamic Loader wiki article at [http://processors.wiki.ti.com/index.php/C6000_Dynamic_Loader](http://processors.wiki.ti.com/index.php/C6000_Dynamic_Loader) as an example of how to build a dynamic executable or base image:

```sh
cl6x ... -z *.obj ... --dynamic --export=printf ...
```

In this example, the --dynamic option indicates that the result of the link is going to be a dynamic executable. The --export=printf indicates that the printf() run-time-support function is exported by the dynamic executable and, if imported by a dynamic library, can be called at run time by the functions defined in the dynamic library.

8.12.4 Building a Dynamic Library

A dynamic library is a shared object that contains dynamic information in the form of a dynamic segment. It is relocatable and can import symbols from other ELF dynamic objects that it links against and it can also export symbols that it defines itself.

8.12.4.1 Importing/Exporting Symbols

Importing and exporting of symbols can be accomplished in two ways, similarly to how it can be done in dynamic executables:

- **Recommended**: Declare exported and/or imported symbols explicitly in the source code of the dynamic library using __declspec(dllexport) for exported symbols and __declspec(dllimport) for imported symbols.

  For example, if you want to export a function, red_fish(), and import another function, blue_fish(), you could specify this in a source file as follows:

  ```c
  __declspec(dllexport) long red_fish();
  __declspec(dllimport) int blue_fish();
  ```

- You can also specify symbols to be imported or exported on the linker command line (or in a linker command file) using --import=symbol or --export=symbol.

  So at link time, you might say:

  ```sh
  cl6x ... -z --dynamic=lib --export=red_fish --import=blue_fish
  blue.dll -o red.dll
  ```

  This informs the linker that the definition of red_fish() will be in the red.dll dynamic library and that we can find and use the definition of blue_fish() in blue.dll.

In general, to build a dynamic library, you must specify --dynamic=lib on the linker command line or in a linker command file. In addition, if any symbols are imported from other dynamic objects, then those dynamic objects must be specified on the linker command line when the dynamic library is built. This is sometimes referred to as static binding.
8.12.4.2 A Simple Example - hello.dll

This section describes a simple walk-through of the process used to build, load, and run a function that is defined in a dynamic library.

- First compile this simple "Hello World" source:

```c
#include <stdio.h>
__declspec(dllexport) int start();

int start()
{
    printf("Hello World\n");
    return 0;
}
```

- Then build a dynamic library called hello.dll:

```bash
cl6x -mv6400+ hello.c -z --import=printf --dynamic=lib -o hello.dll
dlx6.6x -e start
```

- Now, load the dynamic loader using a loader that supports C6000 ELF executable object files. Then start the dynamic loader running. When using the reference implementation of the dynamic loader (RIDL), you will see the RIDL prompt come up and then you need to issue the following commands:

```
RIDL> base_image dlx6.6x
RIDL> load hello.dll
RIDL> execute
```

You should see the "Hello World" message displayed and then control will return to the RIDL prompt. To terminate the dynamic loader you can enter the exit command from the RIDL prompt.


8.12.4.3 Summary of Compiler and Linker Options

This is a brief summary of the compiler and linker options that are related to support for the Dynamic Linking Model in the C6000 CGT.

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>--dsbt</td>
<td>Generates addressing via Dynamic Segment Base Table</td>
</tr>
<tr>
<td>--export_all_cpp_vtbl</td>
<td>Exports C++ virtual tables by default</td>
</tr>
<tr>
<td>--import_undef=off</td>
<td>on</td>
</tr>
<tr>
<td>--import_helper_functions</td>
<td>Specifies that all compiler generated calls to run-time-support functions are treated as calls to imported functions. See Section 8.12.5.</td>
</tr>
<tr>
<td>--inline_plt=off</td>
<td>on</td>
</tr>
<tr>
<td>--linux</td>
<td>Generates code for Linux.</td>
</tr>
<tr>
<td>--pic=off</td>
<td>on</td>
</tr>
<tr>
<td>--visibility=hidden</td>
<td>default</td>
</tr>
<tr>
<td>--wchar_t</td>
<td>Generates 32-bit wchar_t type. By default the compiler generates 16-bit wchar_t.</td>
</tr>
</tbody>
</table>
### Dynamic Linking with the C6000 Code Generation Tools

**Table 8-14. Linker Options For Dynamic Linking**

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>--dsbt_index=int</td>
<td>Requests a specific Data Segment Base Table (DSBT) index to be associated with the current output file. If the DSBT model is being used, and you do not request a specific DSBT index for the output file, then a DSBT index is assigned to the module at load time.</td>
</tr>
<tr>
<td>--dsbt_size=int</td>
<td>Specifies the size of the Data Segment Base Table (DSBT) for the current output file, in words. If the DSBT model is being used, this option can be used to override the default DSBT size (8 words).</td>
</tr>
<tr>
<td>--dynamic[=exe]</td>
<td>Specifies that the result of a link will be a dynamic executable. See Section 8.12.3.1.</td>
</tr>
<tr>
<td>--dynamic=lib</td>
<td>Specifies that the result of a link will be a dynamic library. See Section 8.12.4.1.</td>
</tr>
<tr>
<td>--export=symbol</td>
<td>Specifies that symbol is exported by the ELF object that is generated for this link.</td>
</tr>
<tr>
<td>--fini=symbol</td>
<td>Specifies the symbol name of the termination code for the output file currently being linked.</td>
</tr>
<tr>
<td>--import=symbol</td>
<td>Specifies that symbol is imported by the ELF object that is generated for this link.</td>
</tr>
<tr>
<td>--init=symbol</td>
<td>Specifies the symbol name of the initialization code for the output file currently being linked.</td>
</tr>
<tr>
<td>--rpath=dir</td>
<td>Adds a directory to the beginning of the dynamic library search path.</td>
</tr>
<tr>
<td>--runpath=dir</td>
<td>Adds a directory to the end of the dynamic library search path.</td>
</tr>
<tr>
<td>--shared</td>
<td>Generates a dynamically shared object.</td>
</tr>
<tr>
<td>--soname=string</td>
<td>Specifies shared object name to be used to identify this ELF object to the any downstream ELF object consumers.</td>
</tr>
<tr>
<td>--sysv</td>
<td>Generates SysV ELF output file.</td>
</tr>
</tbody>
</table>

#### 8.12.5 Symbol Import/Export

In a dynamic linking system you can build dynamic modules that are loaded and relocated by a dynamic loader at run time. The dynamic loader can also perform dynamic symbol resolution: resolve references from dynamic modules with the definitions from other dynamic objects.

Only symbols explicitly imported or exported have dynamic linkage and participate in dynamic linking. Normal global symbols don’t participate in dynamic symbol resolution. A symbol is exported if it is visible from a module during dynamic symbol resolution. A dynamic object is a dynamic library or a dynamic executable. Such a dynamic object imports a symbol when its symbol references are resolved by definitions from another dynamic object. The dynamic object that has the definition and makes it visible is said to export the symbol.

**8.12.5.1 ELF Symbols**

ELF symbols have two attributes that contribute to static and dynamic symbol binding:

- Symbol Binding - symbol’s scope with respect to other files
- Symbol Visibility - symbol’s scope with respect to other run-time components (dynamic executable or dynamic libraries)

A more detailed discussion of the symbol binding and visibility characteristics can be found in the ELF Specification (Tool Interface Standard).

**8.12.5.1.1 Symbol Binding Attribute Values**

- **STB_LOCAL**
  - Indicates that a symbol is not visible outside the module where it is defined.
  - Any local references to the symbol will be resolved by the definition in the current module.

- **STB_GLOBAL**
  - Indicates that a symbol is visible to all files being combined during the link step
  - Any references to a global symbol that are left unresolved will result in a link-time error

- **STB_WEAK**
  - Indicates that a symbol is visible to all files being combined during a link step.
  - Global symbol definition takes precedence over corresponding weak symbol def.
8.12.5.1.2 ELF Symbol Visibility

GLOBAL/WEAK symbols can have any of the following visibility attributes:

- **STV_DEFAULT**
  - Symbol definition is visible outside the defining component.
  - Symbol definition can be preempted.
  - Symbol references can be resolved by definition outside the referenced component.

- **STV_PROTECTED**
  - Symbol definition is visible outside the defining component.
  - Symbol definition cannot be preempted.
  - Symbol reference must be resolved by a definition in the same component.

- **STV_HIDDEN**
  - Symbol definition is not visible outside its own component.
  - Symbol reference must be resolved by a definition in the same component.

8.12.5.2 Controlling Import/Export of Symbols

Symbols can be imported/exported by using:

- Source Code Annotations
- ELF Linkage Macros
- Compiler Options
- Linker Options

8.12.5.2.1 Source Code Annotations (Recommended)

A global symbol can be imported or exported by adding a __declspec() symbol annotation to the source file.

- Export Using __declspec(dllexport)

  ```
  __declspec(dllexport) int foo() { }
  ```

  __declspec(dllexport) can be applied to both symbol declarations and symbol definitions.

- Import Using __declspec(dllimport)

  ```
  __declspec(dllimport) int bar();
  ```

  __declspec(dllimport) can be applied to a symbol declaration.

  The compiler generates a warning if __declspec(dllimport) is applied to a symbol definition.

  - Typically an API is exported by a module and is imported by another module. __declspec() can be added to the API header file
  - The linker uses the most restrictive visibility for symbols. For example, consider if the following were true:
    - foo() is declared with __declspec(dllimport) in a.c
    - foo() is declared plain (no __declspec()) in b.c
    - a.c and b.c are compiled into ab.dll
  Then, the symbol, foo, is **not** imported in ab.dll and the linker reports an error indicating that the reference to foo() is unresolved.

  - Some of the benefits of using the __declspec() approach include:
    - It enables the compiler to generate more optimal code.
    - The optimizer does not optimize out exported symbols.
    - The source code becomes a self-documenting in specifying the API for a given module, making it easier to read and maintain.
    - It can be used in the Dynamic Linking Model
8.12.5.2.2 Import/Export Using ELF Linkage Macros (elf_linkage.h)

The C6000 compiler provides a header file, elf_linkage.h, in the include sub-directory of the installed toolset. The elf_linkage.h file defines several macros that can be used to control symbol visibility:

- **TI_IMPORT symbol declaration**
  This macro imports the declared symbol. The TI_IMPORT macro cannot be applied to symbol definitions.
  ```c
  TI_IMPORT int foo(void);
  extern TI_IMPORT long global_variable;
  ```

- **TI_EXPORT symbol definition|symbol declaration**
  This macro exports the symbol that is being declared or defined. The source module that makes use of this macro must contain a definition of the symbol.
  ```c
  TI_EXPORT int foo(void);
  TI_EXPORT long global_variable;
  ```

- **TI_PATCHABLE symbol definition**
  This macro makes the definition of the symbol visible outside of the source module that uses it. Other modules can import the defined symbol. Also, a reference to the symbol can be patched (or redirected) to a different definition of the symbol if needed. The compiler will generate an indirect call to a function that has been marked as patchable. This technique is also sometimes called symbol preemption.
  ```c
  TI_PATCHABLE int foo(void);
  TI_PATCHABLE long global_variable;
  ```

- **TI_DEFAULT symbol definition|symbol declaration**
  This macro specifies that the symbol in question can be either imported or exported. The definition of the symbol is visible outside the module. Other modules can import the symbol definition. Any references to the symbol can also be patched.

- **TI_PROTECTED symbol definition|symbol declaration**
  This macro specifies that the symbol in question is visible outside of the module. Other modules can import the symbol definition. However, a reference to the symbol can never be patched (symbol is non-preemptable).

- **TI_HIDDEN symbol definition|symbol declaration**
  The definition of the symbol is not visible outside the module that defines it.

8.12.5.2.3 Import/Export Using Compiler Options

The following compiler options can be used to control the symbol visibility of global symbols. The symbols using source code annotations to control the visibility are not affected by these compiler options.

- **--visibility=default visibility**
  The --visibility option specifies the default visibility for global symbols. This option does not affect the visibility of symbols that use the __declspec() or TI_xxx macros to specify a visibility in the source code. The default visibility is one of the following:
  - hidden - Global symbols are not imported or exported. This is the default compiler behavior.
  - default - All global symbols are imported, exported, and patchable.
  - protected - All global symbols are exported.

- **--import_undef**
  The --import_undef option makes all of the global symbol references imported. This option can be combined with the --visibility option. For example, the following option combination makes all definitions exported and all references imported:
  ```
  --import_undef --visibility=protected
  ```
  The --import_undef option takes precedence over the --visibility option.
• **--import_helper_functions**
  The compiler generates calls to functions that are defined in the run-time-support library. For example, to perform unsigned long division in user code, the compiler generates a call to \_c6xabi\_divul. Since there is no declaration and you do not call these functions directly, the \_declspec() annotation cannot be used. This prevents you from importing such functions from the run-time-support library that is built as a dynamic library. To address this issue, the compiler supports the **--import_helper_functions** option. When specified on the compiler command line, for each run-time-support function that is called by the compiler, that function symbol will be imported.

### 8.12.5.2.4 Import/Export Using Linker Options

To import or export a symbol when the source code cannot be updated with a \_declspec() annotation, the following linker options can be used:

- **--import=symbol**
  This option adds symbol to the dynamic symbol table as an imported reference. At link-time, the static linker searches through any object libraries that are included in the link to make sure that a definition of symbol is available.
  If a definition of symbol is included in the current link, then the **--import** option is ignored with a warning.

- **--export=symbol**
  This option adds symbol to the dynamic symbol table as an exported definition. At link-time, if there are any objects that contain an unresolved external reference to symbol when the object that exports symbol is encountered, then the object that contains the exported definition is included in the link.
  If the **--export=symbol** option is used on the compile of an object that does not have a definition of symbol in it, then the compiler generates an error.

---

**The --import and --export Options**

**NOTE:** The **--import** and **--export** options cannot be used when building a Linux executable or DSO.
This chapter describes how to invoke the following utilities:

- **The object file display utility** prints the contents of object files, executable files, and/or archive libraries in both text and XML formats.
- **The disassembler** accepts object files and executable files as input and produces an assembly listing as output. This listing shows assembly instructions, their opcodes, and the section program counter values.
- **The name utility** prints a list of names defined and referenced in an object file, executable files, and/or archive libraries.
- **The strip utility** removes symbol table and debugging information from object and executable files.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>9.1 Invoking the Object File Display Utility</td>
<td>276</td>
</tr>
<tr>
<td>9.2 Invoking the Disassembler</td>
<td>277</td>
</tr>
<tr>
<td>9.3 Invoking the Name Utility</td>
<td>277</td>
</tr>
<tr>
<td>9.4 Invoking the Strip Utility</td>
<td>278</td>
</tr>
</tbody>
</table>
9.1 Invoking the Object File Display Utility

The object file display utility, ofd6x, prints the contents of object files (.obj), executable files (.out), and/or archive libraries (.lib) in both text and XML formats. Hidden symbols are listed as no name, while localized symbols are listed like any other local symbol.

To invoke the object file display utility, enter the following:

```
ofd6x [options] input filename [input filename]
```

- **ofd6x** is the command that invokes the object file display utility.
- **input filename** names the object file (.obj), executable file (.out), or archive library (.lib) source file. The filename must contain an extension.
- **options** identify the object file display utility options that you want to use. Options are not case sensitive and can appear anywhere on the command line following the command. Precede each option with a hyphen.
  - **-cg** Prints function stack usage and callee information in XML format. While the XML output may be accessed by a developer, this option was primarily designed to be used by tools such as Code Composer Studio to display an application’s worst case stack usage.
  - **--dwarf_display=attributes** Controls the DWARF display filter settings by specifying a comma-delimited list of **attributes**. When prefixed with no, an attribute is disabled instead of enabled.
    - Examples: `--dwarf_display=nodabbrev,nodline`
    - `--dwarf_display=all,nodabbrev`
    - `--dwarf_display=none,dinfo,types`
    - The ordering of attributes is important (see **--obj_display**). The list of available display attributes can be obtained by invoking ofd6x `--dwarf_display=help`.
  - **-g** Appends DWARF debug information to program output.
  - **-h** Displays help
  - **-o=filename** Sends program output to `filename` rather than to the screen.
  - **--obj_display attributes** Controls the object file display filter settings by specifying a comma-delimited list of **attributes**. When prefixed with no, an attribute is disabled instead of enabled.
    - Examples: `--obj_display=rawdata,nostrings`
    - `--obj_display=all,norawdata`
    - `--obj_display=none,header`
    - The ordering of attributes is important. For instance, in "--obj_display=none,header", ofd6x disables all output, then re-enables file header information. If the attributes are specified in the reverse order, (header,none), the file header is enabled, the all output is disabled, including the file header. Thus, nothing is printed to the screen for the given files. The list of available display attributes can be obtained by invoking ofd6x `--dwarf_display=help`.
  - **-v** Prints verbose text output.
  - **-x** Displays output in XML format.
  - **--xml_indent=num** Sets the number of spaces to indent nested XML tags.
If an archive file is given as input to the object file display utility, each object file member of the archive is processed as if it was passed on the command line. The object file members are processed in the order in which they appear in the archive file.

If the object file display utility is invoked without any options, it displays information about the contents of the input files on the console screen.

**Object File Display Format**

*NOTE:* The object file display utility produces data in a text format by default. This data is not intended to be used as input to programs for further processing of the information. XML format should be used for mechanical processing.

### 9.2 Invoking the Disassembler

The disassembler, *dis6x*, examines the output of the assembler or linker. This utility accepts an object file or executable file as input and writes the disassembled object code to standard output or a specified file.

To invoke the disassembler, enter the following:

```
[options] input filename[.] [output filename]
```

- **dis6x** is the command that invokes the disassembler.
- **options** identifies the name utility options you want to use. Options are not case sensitive and can appear anywhere on the command line following the invocation. Precede each option with a hyphen (-). The name utility options are as follows:
  - `-a` disables the printing of branch destination addresses along with labels.
  - `-b` displays data as bytes instead of words.
  - `-c` dumps the object file information.
  - `-d` disables display of data sections.
  - `-h` shows the current help screen.
  - `-i` disassembles .data sections as instructions.
  - `-l` disassembles data sections as text.
  - `-n` suppresses FP header information for C64x+ Compact FPs.
  - `-o##` disassembles single word ## or 0x## then exits.
  - `-q` (quiet mode) suppresses the banner and all progress information.
  - `-qq` (super quiet mode) suppresses all headers.
  - `-s` suppresses printing of address and data words.
  - `-t` suppresses the display of text sections in the listing.
  - `-v` displays family of the target.
- **input filename[.ext]** is the name of the input file. If the optional extension is not specified, the file is searched for in this order:
  1. `infile`
  2. `infile.out`, an executable file
  3. `infile.obj`, an object file
- **output filename** is the name of the optional output file to which the disassembly will be written. If an output filename is not specified, the disassembly is written to standard output.

### 9.3 Invoking the Name Utility

The name utility, *nm6x*, prints the list of names defined and referenced in an object file, executable file, or archive library. It also prints the symbol value and an indication of the kind of symbol. Hidden symbols are listed as "".
Invoking the Strip Utility

To invoke the name utility, enter the following:

```
 nm6x [-options] [input filenames]
```

- **nm6x** is the command that invokes the name utility.
- **input filename** is a file name such as (.obj), executable file (.out), or archive library (.lib).
- **options** identifies the name utility options you want to use. Options are not case sensitive and can appear anywhere on the command line following the invocation. Precede each option with a hyphen (-). The name utility options are as follows:
  - **-a** prints all symbols.
  - **-f** prepends file name to each symbol.
  - **-g** prints only global symbols.
  - **-h** shows the current help screen.
  - **-l** produces a detailed listing of the symbol information.
  - **-n** sorts symbols numerically rather than alphabetically.
  - **-o file** outputs to the given file.
  - **-p** causes the name utility to not sort any symbols.
  - **-q** (quiet mode) suppresses the banner and all progress information.
  - **-r** sorts symbols in reverse order.
  - **-s** lists symbols in the dynamic symbol table for an ELF object module.
  - **-u** only prints undefined symbols.

```
9.4 Invoking the Strip Utility
```

The strip utility, strip6x, removes symbol table and debugging information from object and executable files. To invoke the strip utility, enter the following:

```
 strip6x [-p] input filename [input filename]
```

- **strip6x** is the command that invokes the strip utility.
- **input filename** is a file name such as (.obj) or an executable file (.out).
- **options** identifies the strip utility options you want to use. Options are not case sensitive and can appear anywhere on the command line following the invocation. Precede each option with a hyphen (-). The strip utility option is as follows:
  - **-o filename** writes the stripped output to filename.
  - **-p** removes all information not required for execution. This option causes more information to be removed than the default behavior, but the object file is left in a state that cannot be linked. This option should be used only with static executable or dynamic object module files.

When the strip utility is invoked without the -o option, the input object files are replaced with the stripped version.
The TMS320C6000 assembler and linker create object files which are in binary formats that encourage modular programming and provide powerful and flexible methods for managing code segments and target system memory.

Most EPROM programmers do not accept object files as input. The hex conversion utility converts an object file into one of several standard ASCII hexadecimal formats, suitable for loading into an EPROM programmer. The utility is also useful in other applications requiring hexadecimal conversion of an object file (for example, when using debuggers and loaders).

The hex conversion utility can produce these output file formats:
- ASCII-Hex, supporting 32-bit addresses
- Extended Tektronix (Tektronix)
- Intel MCS-86 (Intel)
- Motorola Exorciser (Motorola-S), supporting 16-bit addresses
- Texas Instruments SDSMAC (TI-Tagged), supporting 16-bit addresses
- Texas Instruments TI-TXT format, supporting 16-bit addresses

### Topic Page

10.1 The Hex Conversion Utility's Role in the Software Development Flow ............... 280
10.2 Invoking the Hex Conversion Utility ................................................................. 281
10.3 Understanding Memory Widths ................................................................. 284
10.4 The ROMS Directive .................................................................................. 288
10.5 The SECTIONS Directive ........................................................................ 292
10.6 The Load Image Format (--load_image Option) ................................................. 293
10.7 Excluding a Specified Section ..................................................................... 293
10.8 Assigning Output Filenames ......................................................................... 294
10.9 Image Mode and the --fill Option ............................................................... 295
10.10 Controlling the ROM Device Address ...................................................... 296
10.11 Control Hex Conversion Utility Diagnostics ............................................. 297
10.12 Description of the Object Formats .......................................................... 298
10.1 The Hex Conversion Utility’s Role in the Software Development Flow

Figure 10-1 highlights the role of the hex conversion utility in the software development process.

Figure 10-1. The Hex Conversion Utility in the TMS320C6000 Software Development Flow
10.2 Invoking the Hex Conversion Utility

There are two basic methods for invoking the hex conversion utility:

- **Specify the options and filenames on the command line.** The following example converts the file firmware.out into TI-Tagged format, producing two output files, firm.lsb and firm.msb.

  hex6x -t firmware -o firm.lsb -o firm.msb

  hex6x --ti_tagged firmware --outfile=firm.lsb --outfile=firm.msb

- **Specify the options and filenames in a command file.** You can create a file that stores command line options and filenames for invoking the hex conversion utility. The following example invokes the utility using a command file called hexutil.cmd:

  hex6x hexutil.cmd

In addition to regular command line information, you can use the hex conversion utility ROMS and SECTIONS directives in a command file.

10.2.1 Invoking the Hex Conversion Utility From the Command Line

To invoke the hex conversion utility, enter:

```
hex6x [options] filename
```

`hex6x` is the command that invokes the hex conversion utility. `options` supplies additional information that controls the hex conversion process. You can use options on the command line or in a command file. Table 10-1 lists the basic options.

- All options are preceded by a hyphen and are not case sensitive.
- Several options have an additional parameter that must be separated from the option by at least one space.
- Options with multi-character names must be spelled exactly as shown in this document; no abbreviations are allowed.
- Options are not affected by the order in which they are used. The exception to this rule is the --quiet option, which must be used before any other options.

`filename` names an object file or a command file (for more information, see Section 10.2.2).

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>--byte</td>
<td>-byte</td>
<td>Number output locations by bytes rather than by target addressing</td>
<td>--</td>
</tr>
<tr>
<td>--entrypoint=addr</td>
<td>-e</td>
<td>Specify the entry point address or global symbol at which to begin execution after boot loading</td>
<td></td>
</tr>
<tr>
<td>--exclude={fname(sname)</td>
<td>-exclude</td>
<td>If the filename (fname) is omitted, all sections matching sname will be excluded.</td>
<td>Section 10.7</td>
</tr>
<tr>
<td>--fill=value</td>
<td>-fill</td>
<td>Fill holes with value</td>
<td>Section 10.9.2</td>
</tr>
<tr>
<td>--help</td>
<td>-options, -h</td>
<td>Display the syntax for invoking the utility and list available options. If the option is followed by another option or phrase, detailed information about that option or phrase is displayed. For example, to see information about options associated with generating a boot table, use --help boot.</td>
<td>Section 10.2.2</td>
</tr>
<tr>
<td>--image</td>
<td>-image</td>
<td>Select image mode</td>
<td>Section 10.9.1</td>
</tr>
<tr>
<td>--linkerfill</td>
<td>-linkerfill</td>
<td>Include linker fill sections in images</td>
<td>--</td>
</tr>
<tr>
<td>--map=filename</td>
<td>-map</td>
<td>Generate a map file</td>
<td>Section 10.4.2</td>
</tr>
<tr>
<td>--memwidth=value</td>
<td>-memwidth</td>
<td>Define the system memory word width (default 32 bits)</td>
<td>Section 10.3.2</td>
</tr>
<tr>
<td>--order={L</td>
<td>M}</td>
<td>-order</td>
<td>Specify data ordering (endianness)</td>
</tr>
</tbody>
</table>
Table 10-1. Basic Hex Conversion Utility Options (continued)

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Description</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>--outfile=filename</td>
<td>-o</td>
<td>Specify an output filename</td>
<td>Section 10.8</td>
</tr>
<tr>
<td>--quiet</td>
<td>-q</td>
<td>Run quietly (when used, it must appear before other options)</td>
<td>Section 10.2.2</td>
</tr>
<tr>
<td>--romwidth=value</td>
<td>-romwidth</td>
<td>Specify the ROM device width (default depends on format used). This option is ignored for the TI-TXT and TI-Tagged formats.</td>
<td>Section 10.3.3</td>
</tr>
<tr>
<td>--zero</td>
<td>-zero, -z</td>
<td>Reset the address origin to 0 in image mode</td>
<td>Section 10.9.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Diagnostic Options</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>--diag_error=id</td>
<td></td>
<td>Categorizes the diagnostic identified by id as an error</td>
<td>Section 10.11</td>
</tr>
<tr>
<td>--diag_remark=id</td>
<td></td>
<td>Categorizes the diagnostic identified by id as a remark</td>
<td>Section 10.11</td>
</tr>
<tr>
<td>--diag_suppress=id</td>
<td></td>
<td>Suppresses the diagnostic identified by id</td>
<td>Section 10.11</td>
</tr>
<tr>
<td>--diag_warning=id</td>
<td></td>
<td>Categorizes the diagnostic identified by id as a warning</td>
<td>Section 10.11</td>
</tr>
<tr>
<td>--display_error_number</td>
<td></td>
<td>Displays a diagnostic's identifiers along with its text</td>
<td>Section 10.11</td>
</tr>
<tr>
<td>--issue_remarks</td>
<td></td>
<td>Issues remarks (nonserious warnings)</td>
<td>Section 10.11</td>
</tr>
<tr>
<td>--no_warnings</td>
<td></td>
<td>Suppresses warning diagnostics (errors are still issued)</td>
<td>Section 10.11</td>
</tr>
<tr>
<td>--set_error_limit=count</td>
<td></td>
<td>Sets the error limit to count. The linker abandons linking after this number of errors. (The default is 100.)</td>
<td>Section 10.11</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Boot Table Options</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>--boot</td>
<td>-boot</td>
<td>Convert all initialized sections into bootable form (use instead of a SECTIONS directive)</td>
<td></td>
</tr>
<tr>
<td>-bootorg=addr</td>
<td>-bootorg</td>
<td>Specify origin address of the boot loader table</td>
<td></td>
</tr>
<tr>
<td>-bootsection=section</td>
<td>-bootsection</td>
<td>Specify which section contains the boot routine and where it should be placed</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output Options</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>--ascii</td>
<td>-a</td>
<td>Select ASCII-Hex</td>
<td>Section 10.12.1</td>
</tr>
<tr>
<td>--intel</td>
<td>-i</td>
<td>Select Intel</td>
<td>Section 10.12.2</td>
</tr>
<tr>
<td>--motorola=1</td>
<td>-m1</td>
<td>Select Motorola-S1</td>
<td>Section 10.12.3</td>
</tr>
<tr>
<td>--motorola=2</td>
<td>-m2</td>
<td>Select Motorola-S2</td>
<td>Section 10.12.3</td>
</tr>
<tr>
<td>--motorola=3</td>
<td>-m3</td>
<td>Select Motorola-S3 (default -m option)</td>
<td>Section 10.12.3</td>
</tr>
<tr>
<td>--tektronix</td>
<td>-x</td>
<td>Select Tektronix (default format when no output option is specified)</td>
<td>Section 10.12.4</td>
</tr>
<tr>
<td>--ti_tagged</td>
<td>-t</td>
<td>Select TI-Tagged</td>
<td>Section 10.12.5</td>
</tr>
<tr>
<td>--ti_txt</td>
<td></td>
<td>Select TI-Txt</td>
<td>Section 10.12.6</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Load Image Options</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>--load_image</td>
<td></td>
<td>Select load image</td>
<td>Section 10.6</td>
</tr>
<tr>
<td>--section_name_prefix=string</td>
<td></td>
<td>Specify the section name prefix for load image object files</td>
<td>Section 10.6</td>
</tr>
</tbody>
</table>
10.2.2 Invoking the Hex Conversion Utility With a Command File

A command file is useful if you plan to invoke the utility more than once with the same input files and options. It is also useful if you want to use the ROMS and SECTIONS hex conversion utility directives to customize the conversion process.

Command files are ASCII files that contain one or more of the following:

- **Options and filenames.** These are specified in a command file in exactly the same manner as on the command line.
- **ROMS directive.** The ROMS directive defines the physical memory configuration of your system as a list of address-range parameters. (See Section 10.4.)
- **SECTIONS directive.** The hex conversion utility SECTIONS directive specifies which sections from the object file are selected. (See Section 10.5.)
- **Comments.** You can add comments to your command file by using the /* and */ delimiters. For example:
  ```
  /* This is a comment. */
  ```

To invoke the utility and use the options you defined in a command file, enter:

```
hex6x command_filename
```

You can also specify other options and files on the command line. For example, you could invoke the utility by using both a command file and command line options:

```
hex6x firmware.cmd --map=firmware.mxp
```

The order in which these options and filenames appear is not important. The utility reads all input from the command line and all information from the command file before starting the conversion process. However, if you are using the -q option, **it must appear as the first option on the command line or in a command file.**

The --help option displays the syntax for invoking the compiler and lists available options. If the --help option is followed by another option or phrase, detailed information about the option or phrase is displayed. For example, to see information about options associated with generating a boot table use --help boot.

The --quiet option suppresses the hex conversion utility's normal banner and progress information.

- **Assume that a command file named firmware.cmd contains these lines:**
  ```
  firmware.out /* input file */
  --ti_tagged /* TI-Tagged */
  --outfile=firm.lsb /* output file */
  --outfile=firm.msb /* output file */
  ```

  You can invoke the hex conversion utility by entering:
  ```
  hex6x firmware.cmd
  ```

- **This example shows how to convert a file called appl.out into eight hex files in Intel format. Each output file is one byte wide and 4K bytes long:**
  ```
  appl.out /* input file */
  --intel /* Intel format */
  --map=appl.mxp /* map file */
  ```

  ROMS
  ```
  |
  ROW1: origin=0x00000000 len=0x4000 romwidth=8
  files={ appl.u0 appl.u1 appl.u2 appl.u3 }
  ROW2: origin=0x00004000 len=0x4000 romwidth=8
  files={ appl.u4 appl.u5 appl.u6 appl.u7 }
  ```

  SECTIONS
  ```
  { .text, .data, .cinit, .sect1, .vectors, .const: }
  ```
10.3 Understanding Memory Widths

The hex conversion utility makes your memory architecture more flexible by allowing you to specify memory and ROM widths. To use the hex conversion utility, you must understand how the utility treats word widths. Three widths are important in the conversion process:

- Target width
- Memory width
- ROM width

The terms target word, memory word, and ROM word refer to a word of such a width.

Figure 10-2 illustrates the separate and distinct phases of the hex conversion utility's process flow.

**Figure 10-2. Hex Conversion Utility Process Flow**

Raw data in object files is represented in the target's addressable units. For the C6000, this is 32 bits.

10.3.1 Target Width

Target width is the unit size (in bits) of the target processor's word. The width is fixed for each target and cannot be changed. The TMS320C6000 targets have a width of 32 bits.
### 10.3.2 Specifying the Memory Width

Memory width is the physical width (in bits) of the memory system. Usually, the memory system is physically the same width as the target processor width: a 32-bit processor has a 32-bit memory architecture. However, some applications require target words to be broken into multiple, consecutive, and narrower memory words.

By default, the hex conversion utility sets memory width to the target width (in this case, 32 bits).

You can change the memory width (except for TI-TXT format) by:

- Using the --memwidth option. This changes the memory width value for the entire file.
- Setting the memwidth parameter of the ROMS directive. This changes the memory width value for the address range specified in the ROMS directive and overrides the --memwidth option for that range. See Section 10.4.

For both methods, use a value that is a power of 2 greater than or equal to 8.

You should change the memory width default value of 32 only when you need to break single target words into consecutive, narrower memory words.

---

**TI-TXT Format is 8 Bits Wide**

**NOTE:** You cannot change the memory width of the TI-TXT format. The TI-TXT hex format supports an 8-bit memory width only.

---

Figure 10-3 demonstrates how the memory width is related to object file data.
10.3.3  Partitioning Data Into Output Files

ROM width determines how the hex conversion utility partitions the data into output files. ROM width specifies the physical width (in bits) of each ROM device and corresponding output file (usually one byte or eight bits). After the object file data is mapped to the memory words, the memory words are broken into one or more output files. The number of output files is determined by the following formulas:

- If memory width ≥ ROM width:
  number of files = memory width ÷ ROM width
- If memory width < ROM width:
  number of files = 1

For example, for a memory width of 32, you could specify a ROM width value of 32 and get a single output file containing 32-bit words. Or you can use a ROM width value of 16 to get two files, each containing 16 bits of each word.

The default ROM width that the hex conversion utility uses depends on the output format:

- All hex formats except TI-Tagged are configured as lists of 8-bit bytes; the default ROM width for these formats is 8 bits.
- TI-Tagged is a 16-bit format; the default ROM width for TI-Tagged is 16 bits.

The TI-Tagged Format is 16 Bits Wide

NOTE: You cannot change the ROM width of the TI-Tagged format. The TI-Tagged format supports a 16-bit ROM width only.

The TI-TXT Format is 8 Bits Wide

NOTE: You cannot change the ROM width of the TI-TXT format. The TI-TXT hex format supports only an 8-bit ROM width.

You can change ROM width (except for TI-Tagged and TI-TXT formats) by:

- Using the --romwidth option. This option changes the ROM width value for the entire object file.
- Setting the romwidth parameter of the ROMS directive. This parameter changes the ROM width value for a specific ROM address range and overrides the --romwidth option for that range. See Section 10.4.

For both methods, use a value that is a power of 2 greater than or equal to 8.

If you select a ROM width that is wider than the natural size of the output format, the utility simply writes multibyte fields into the file. The --romwidth option is ignored for the TI-TXT and TI-Tagged formats.

Figure 10-4 illustrates how the object file data, memory, and ROM widths are related to one another.

Memory width and ROM width are used only for grouping the object file data; they do not represent values. Thus, the byte ordering of the object file data is maintained throughout the conversion process. To refer to the partitions within a memory word, the bits of the memory word are always numbered from right to left as follows:

```
--memwidth=32
A A B B C C D D 1 1 2 2 3 3 4 4
31 0
```
Figure 10-4. Data, Memory, and ROM Widths

Source file

.word 0 AABBCDh
.word 0 1 2 3 4 4 4 h

Object file data (assumed to be in little-endian format)

11 22 33 44

Memory widths (variable)

Output files

--romwidth=8
--outfile=file.b0  DD 44
--outfile=file.b1  CC 33
--outfile=file.b2  BB 22
--outfile=file.b3  AA 11

--romwidth=16
--outfile=file.wrd  CCDDAABB3 4 4 1 1 2 2

--romwidth=8
--outfile=file.b0  DD BB 44 22
--outfile=file.b1  CC AA 33 11

--romwidth=8
--outfile=file.by t  DDCCBAA4 4 3 3 2 2 1 1

Data after phase I of hex6x

Data after phase II of hex6x
10.3.4 Specifying Word Order for Output Words

There are two ways to split a wide word into consecutive memory locations in the same hex conversion utility output file:

- `--order=M` specifies big-endian ordering, in which the most significant part of the wide word occupies the first of the consecutive locations.
- `--order=L` specifies little-endian ordering, in which the least significant part of the wide word occupies the first of the consecutive locations.

By default, the utility uses little-endian format. Unless your boot loader program expects big-endian format, avoid using `--order=M`.

When the -order Option Applies

**NOTE:**

- This option applies only when you use a memory width with a value of 32 (``memwidth32``). Otherwise, the hex utility does not have access to the entire 32-bit word and cannot perform the byte swapping necessary to change the endianness; `--order` is ignored.
- This option does not affect the way memory words are split into output files. Think of the files as a set: the set contains a least significant file and a most significant file, but there is no ordering over the set. When you list filenames for a set of files, you always list the least significant first, regardless of the `--order` option.

10.4 The ROMS Directive

The ROMS directive specifies the physical memory configuration of your system as a list of address-range parameters.

Each address range produces one set of files containing the hex conversion utility output data that corresponds to that address range. Each file can be used to program one single ROM device.

The ROMS directive is similar to the MEMORY directive of the TMS320C6000 linker: both define the memory map of the target address space. Each line entry in the ROMS directive defines a specific address range. The general syntax is:

```plaintext
ROMS
{
  romname : [origin=value,] [length=value,] [romwidth=value,]
            [memwidth=value,] [fill=value]
            [files={ filename_1, filename_2, ...}]
}
ROMS
```

*romname* identifies a memory range. The name of the memory range can be one to eight characters in length. The name has no significance to the program; it simply identifies the range, except when the output is for a load image in which case it denotes the section name. (Duplicate memory range names are allowed.)

*origin* specifies the starting address of a memory range. It can be entered as origin, org, or o. The associated value must be a decimal, octal, or hexadecimal constant. If you omit the origin value, the origin defaults to 0. The following table summarizes the notation you can use to specify a decimal, octal, or hexadecimal constant:
### length

 specifies the length of a memory range as the physical length of the ROM device. It can be entered as length, len, or l. The value must be a decimal, octal, or hexadecimal constant. If you omit the length value, it defaults to the length of the entire address space.

### romwidth

 specifies the physical ROM width of the range in bits (see Section 10.3.3). Any value you specify here overrides the --romwidth option. The value must be a decimal, octal, or hexadecimal constant that is a power of 2 greater than or equal to 8.

### memwidth

 specifies the memory width of the range in bits (see Section 10.3.2). Any value you specify here overrides the --memwidth option. The value must be a decimal, octal, or hexadecimal constant that is a power of 2 greater than or equal to 8. When using the memwidth parameter, you must also specify the paddr parameter for each section in the SECTIONS directive. (See Section 10.5.)

### fill

 specifies a fill value to use for the range. In image mode, the hex conversion utility uses this value to fill any holes between sections in a range. A hole is an area between the input sections that comprises an output section that contains no actual code or data. The fill value must be a decimal, octal, or hexadecimal constant with a width equal to the target width. Any value you specify here overrides the --fill option. When using fill, you must also use the --image command line option. (See Section 10.9.2.)

### files

 identifies the names of the output files that correspond to this range. Enclose the list of names in curly braces and order them from least significant to most significant output file, where the bits of the memory word are numbered from right to left. The number of file names must equal the number of output files that the range generates. To calculate the number of output files, see Section 10.3.3. The utility warns you if you list too many or too few filenames.

Unless you are using the --image option, all of the parameters that define a range are optional; the commas and equal signs are also optional. A range with no origin or length defines the entire address space. In image mode, an origin and length are required for all ranges.

Ranges must not overlap and must be listed in order of ascending address.

### 10.4.1 When to Use the ROMS Directive

If you do not use a ROMS directive, the utility defines a single default range that includes the entire address space. This is equivalent to a ROMS directive with a single range without origin or length.

Use the ROMS directive when you want to:

- **Program large amounts of data into fixed-size ROMs.** When you specify memory ranges corresponding to the length of your ROMs, the utility automatically breaks the output into blocks that fit into the ROMs.

- **Restrict output to certain segments.** You can also use the ROMS directive to restrict the conversion to a certain segment or segments of the target address space. The utility does not convert the data that falls outside of the ranges defined by the ROMS directive. Sections can span range boundaries; the utility splits them at the boundary into multiple ranges. If a section falls completely outside any of the ranges you define, the utility does not convert that section and issues no messages or warnings. Thus, you can exclude sections without listing them by name with the SECTIONS directive. However, if a section falls partially in a range and partially in unconfigured memory, the utility issues a warning and converts only the part within the range.
• **Use image mode.** When you use the --image option, you must use a ROMS directive. Each range is filled completely so that each output file in a range contains data for the whole range. Holes before, between, or after sections are filled with the fill value from the ROMS directive, with the value specified with the --fill option, or with the default value of 0.

### 10.4.2 An Example of the ROMS Directive

The ROMS directive in Example 10-1 shows how 16K bytes of 16-bit memory could be partitioned for two 8K-byte 8-bit EPROMs. Figure 10-5 illustrates the input and output files.

**Example 10-1. A ROMS Directive Example**

```plaintext
infile.out
--image
--memwidth 16
ROMS
{
  EPROM1: org = 0x00004000, len = 0x2000, romwidth = 8
  files = { rom4000.b0, rom4000.b1}

  EPROM2: org = 0x00006000, len = 0x2000, romwidth = 8,
         fill = 0xFF00FF00,
         files = { rom6000.b0, rom6000.b1}
}
```

**Figure 10-5. The infile.out File Partitioned Into Four Output Files**

The map file (specified with the --map option) is advantageous when you use the ROMS directive with multiple ranges. The map file shows each range, its parameters, names of associated output files, and a list of contents (section names and fill values) broken down by address. Example 10-2 is a segment of the map file resulting from the example in Example 10-1.
Example 10-2. Map File Output From Example 10-1 Showing Memory Ranges

EPROM1 defines the address range from 0x00004000 through 0x00005FFF with the following sections:

<table>
<thead>
<tr>
<th>This section ...</th>
<th>Has this range ...</th>
</tr>
</thead>
<tbody>
<tr>
<td>.text</td>
<td>0x00004000 through 0x0000487F</td>
</tr>
<tr>
<td>.data</td>
<td>0x00005B80 through 0x00005FFF</td>
</tr>
</tbody>
</table>

The rest of the range is filled with 0h (the default fill value), converted into two output files:
- rom4000.b0 contains bits 0 through 7
- rom4000.b1 contains bits 8 through 15

EPROM2 defines the address range from 0x00006000 through 0x00007FFF with the following sections:

<table>
<thead>
<tr>
<th>This section ...</th>
<th>Has this range ...</th>
</tr>
</thead>
<tbody>
<tr>
<td>.data</td>
<td>0x00006000 through 0x0000633F</td>
</tr>
<tr>
<td>.table</td>
<td>0x00006700 through 0x00007c7f</td>
</tr>
</tbody>
</table>

The rest of the range is filled with 0xFF00FF00 (from the specified fill value). The data from this range is converted into two output files:
- rom6000.b0 contains bits 0 through 7
- rom6000.b1 contains bits 8 through 15
10.5 The SECTIONS Directive

You can convert specific sections of the object file by name with the hex conversion utility SECTIONS directive. You can also specify those sections that you want to locate in ROM at a different address than the load address specified in the linker command file. If you:

- Use a SECTIONS directive, the utility converts only the sections that you list in the directive and ignores all other sections in the object file.
- Do not use a SECTIONS directive, the utility converts all initialized sections that fall within the configured memory.

Uninitialized sections are never converted, whether or not you specify them in a SECTIONS directive.

Sections Generated by the C/C++ Compiler

NOTE: The TMS320C6000 C/C++ compiler automatically generates these sections:
- Initialized sections: .text, .const, .cinit, and .switch
- Uninitialized sections: .bss, .stack, and .sysmem

Use the SECTIONS directive in a command file. (See Section 10.2.2.) The general syntax is:

```plaintext
SECTIONS
{
    oname(sname): [paddr=value]
    oname(sname): [paddr= boot]
    oname(sname): [boot]
    ... 
}
```

SECTIONS begins the directive definition.
oneame identifies the object filename the section is located within. The filename is optional when only a single input file is given, but required otherwise.
sname identifies a section in the input file. If you specify a section that does not exist, the utility issues a warning and ignores the name.
paddr=value specifies the physical ROM address at which this section should be located. This value overrides the section load address given by the linker. This value must be a decimal, octal, or hexadecimal constant. It can also be the word boot (to indicate a boot table section for use with a boot loader). If your file contains multiple sections, and if one section uses a paddr parameter, then all sections must use a paddr parameter.

boot configures a section for loading by a boot loader. This is equivalent to using paddr=boot. Boot sections have a physical address determined by the location of the boot table. The origin of the boot table is specified with the --bootorg option.

For more similarity with the linker's SECTIONS directive, you can use colons after the section names (in place of the equal sign on the boot keyboard). For example, the following statements are equivalent:

```plaintext
SECTIONS { .text: .data: boot }
SECTIONS { .text: .data = boot }
```

In the example below, the object file contains six initialized sections: .text, .data, .const, .vectors, .coeff, and .tables. Suppose you want only .text and .data to be converted. Use a SECTIONS directive to specify this:

```plaintext
SECTIONS { .text: .data: }
```

To configure both of these sections for boot loading, add the boot keyword:

```plaintext
SECTIONS { .text = boot .data = boot }
```
Using the --boot Option and the SECTIONS Directive

**NOTE:** When you use the SECTIONS directive with the boot table (--boot) option, the --boot option is ignored. You must explicitly specify any boot sections in the SECTIONS directive. For more information about --boot and other command line options associated with boot tables, see Section 10.2.

### 10.6 The Load Image Format (--load_image Option)

A load image is an object file which contains the load addresses and initialized sections of one or more executable files. The load image object file can be used for ROM masking or can be relinked in a subsequent link step.

#### 10.6.1 Load Image Section Formation

The load image sections are formed by collecting the initialized sections from the input executables. There are two ways the load image sections are formed:

- **Using the ROMS Directive.** Each memory range that is given in the ROMS directive denotes a load image section. The romname is the section name. The origin and length parameters are required. The memwidth, romwidth, and files parameters are invalid and are ignored.

  When using the ROMS directive and the load_image option, the --image option is required.

- **Default Load Image Section Formation.** If no ROMS directive is given, the load image sections are formed by combining contiguous initialized sections in the input executables. Sections with gaps smaller than the target word size are considered contiguous.

The default section names are image_1, image_2, ... If another prefix is desired, the --section_name_prefix=prefix option can be used.

#### 10.6.2 Load Image Characteristics

All load image sections are initialized data sections. In the absence of a ROMS directive, the load/run address of the load image section is the load address of the first input section in the load image section. If the SECTIONS directive was used and a different load address was given using the paddr parameter, this address will be used.

The load image format always creates a single load image object file. The format of the load image object file is determined based on the input files. The file is not marked executable and does not contain an entry point. The default load image object file name is ti_load_image.obj. This can be changed using the --outfile option. Only one --outfile option is valid when creating a load image, all other occurrences are ignored.

---

**Concerning Load Image Format**

**NOTE:** These options are invalid when creating a load image:

- --memwidth
- --romwidth
- --order
- --zero
- --byte

If a boot table is being created, either using the SECTIONS directive or the --boot option, the ROMS directive must be used.

### 10.7 Excluding a Specified Section

The --exclude section_name option can be used to inform the hex utility to ignore the specified section. If a SECTIONS directive is used, it overrides the --exclude option.
Assigning Output Filenames

For example, if a SECTIONS directive containing the section name mysect is used and an --exclude mysect is specified, the SECTIONS directive takes precedence and mysect is not excluded.

The --exclude option has a limited wildcard capability. The * character can be placed at the beginning or end of the name specifier to indicate a suffix or prefix, respectively. For example, --exclude sect* disqualifies all sections that begin with the characters sect.

If you specify the --exclude option on the command line with the * wildcard, use quotes around the section name and wildcard. For example, --exclude"sect*". Using quotes prevents the * from being interpreted by the hex conversion utility. If --exclude is in a command file, do not use quotes.

If multiple object files are given, the object file in which the section to be excluded can be given in the form oname(sname). If the object filename is not provided, all sections matching the section name are excluded. Wildcards cannot be used for the filename, but can appear within the parentheses.

10.8 Assigning Output Filenames

When the hex conversion utility translates your object file into a data format, it partitions the data into one or more output files. When multiple files are formed by splitting memory words into ROM words, filenames are always assigned in order from least to most significant, where bits in the memory words are numbered from right to left. This is true, regardless of target or endian ordering.

The hex conversion utility follows this sequence when assigning output filenames:

1. **It looks for the ROMS directive.** If a file is associated with a range in the ROMS directive and you have included a list of files (files = {. . .}) on that range, the utility takes the filename from the list.

   For example, assume that the target data is 32-bit words being converted to four files, each eight bits wide. To name the output files using the ROMS directive, you could specify:

   ```
   ROMS
   {
     RANGE1: romwidth=8, files={ xyz.b0 xyz.b1 xyz.b2 xyz.b3 }
   }
   ```

   The utility creates the output files by writing the least significant bits to xyz.b0 and the most significant bits to xyz.b3.

2. **It looks for the --outfile options.** You can specify names for the output files by using the --outfile option. If no filenames are listed in the ROMS directive and you use --outfile options, the utility takes the filename from the list of --outfile options. The following line has the same effect as the example above using the ROMS directive:

   ```
   --outfile=xyz.b0 --outfile=xyz.b1 --outfile=xyz.b2 --outfile=xyz.b3
   ```

   If both the ROMS directive and --outfile options are used together, the ROMS directive overrides the --outfile options.

3. **It assigns a default filename.** If you specify no filenames or fewer names than output files, the utility assigns a default filename. A default filename consists of the base name from the input file plus a 2- to 3-character extension. The extension has three parts:

   (a) A format character, based on the output format (see Section 10.12):

   - a for ASCII-Hex
   - i for Intel
   - m for Motorola-S
   - t for TI-Tagged
   - x for Tektronix

   (b) The range number in the ROMS directive. Ranges are numbered starting with 0. If there is no ROMS directive, or only one range, the utility omits this character.

   (c) The file number in the set of files for the range, starting with 0 for the least significant file.

   For example, assume a.out is for a 32-bit target processor and you are creating Intel format output. With no output filenames specified, the utility produces four output files named a.i0, a.i1, a.i2, a.i3.

   If you include the following ROMS directive when you invoke the hex conversion utility, you would have
eight output files:

```plaintext
ROMS
{
    range1: o = 0x00001000  l = 0x1000
    range2: o = 0x00002000  l = 0x1000
}
```

<table>
<thead>
<tr>
<th>These output files</th>
<th>Contain data in these locations</th>
</tr>
</thead>
<tbody>
<tr>
<td>a.i00, a.i01, a.i02, a.i03</td>
<td>0x00001000 through 0x00001FFF</td>
</tr>
<tr>
<td>a.i10, a.i11, a.i12, a.i13</td>
<td>0x00002000 through 0x00002FFF</td>
</tr>
</tbody>
</table>

10.9 Image Mode and the --fill Option

This section points out the advantages of operating in image mode and describes how to produce output files with a precise, continuous image of a target memory range.

10.9.1 Generating a Memory Image

With the --image option, the utility generates a memory image by completely filling all of the mapped ranges specified in the ROMS directive.

An object file consists of blocks of memory (sections) with assigned memory locations. Typically, all sections are not adjacent; there are holes between sections in the address space for which there is no data. When such a file is converted without the use of image mode, the hex conversion utility bridges these holes by using the address records in the output file to skip ahead to the start of the next section. In other words, there may be discontinuities in the output file addresses. Some EPROM programmers do not support address discontinuities.

In image mode, there are no discontinuities. Each output file contains a continuous stream of data that corresponds exactly to an address range in target memory. Any holes before, between, or after sections are filled with a fill value that you supply.

An output file converted by using image mode still has address records, because many of the hexadecimal formats require an address on each line. However, in image mode, these addresses are always contiguous.

Defining the Ranges of Target Memory

**NOTE:** If you use image mode, you must also use a ROMS directive. In image mode, each output file corresponds directly to a range of target memory. You must define the ranges. If you do not supply the ranges of target memory, the utility tries to build a memory image of the entire target processor address space. This is potentially a huge amount of output data. To prevent this situation, the utility requires you to explicitly restrict the address space with the ROMS directive.

10.9.2 Specifying a Fill Value

The --fill option specifies a value for filling the holes between sections. The fill value must be specified as an integer constant following the --fill option. The width of the constant is assumed to be that of a word on the target processor. For example, specifying --fill=0xFFFF. The constant value is not sign extended.

The hex conversion utility uses a default fill value of 0 if you do not specify a value with the fill option. *The --fill option is valid only when you use --image*; otherwise, it is ignored.
10.9.3 Steps to Follow in Using Image Mode

**Step 1:** Define the ranges of target memory with a ROMS directive. See Section 10.4.

**Step 2:** Invoke the hex conversion utility with the --image option. You can optionally use the --zero option to reset the address origin to 0 for each output file. If you do not specify a fill value with the ROMS directive and you want a value other than the default of 0, use the --fill option.

10.10 Controlling the ROM Device Address

The hex conversion utility output address field corresponds to the ROM device address. The EPROM programmer burns the data into the location specified by the hex conversion utility output file address field. The hex conversion utility offers some mechanisms to control the starting address in ROM of each section. However, many EPROM programmers offer direct control of the location in ROM in which the data is burned.

Depending on whether or not you are using the boot loader, the hex conversion utility output file controlling mechanisms are different.

**Non-boot loader mode.** The address field of the hex conversion utility output file is controlled by the following mechanisms listed from low to high priority:

1. **The linker command file.** By default, the address field of the hex conversion utility output file is the load address (as given in the linker command file).

2. **The paddr parameter of the SECTIONS directive.** When the paddr parameter is specified for a section, the hex conversion utility bypasses the section load address and places the section in the address specified by paddr.

3. **The --zero option.** When you use the --zero option, the utility resets the address origin to 0 for each output file. Since each file starts at 0 and counts upward, any address records represent offsets from the beginning of the file (the address within the ROM) rather than actual target addresses of the data. You must use the --zero option in conjunction with the --image option to force the starting address in each output file to be zero. If you specify the --zero option without the --image option, the utility issues a warning and ignores the --zero option.

**Boot-Loader Mode.** When the boot loader is used, the hex conversion utility places the different sections that are in the boot table into consecutive memory locations. Each section becomes a boot table block whose destination address is equal to the linker-assigned section load address.

In a boot table, the address field of the hex conversion utility output file is not related to the section load addresses assigned by the linker. The address fields of the boot table are simply offsets to the beginning of the table. The section load addresses assigned by the linker will be encoded into the boot table along with the size of the section and the data contained within the section. These addresses will be used to store the data into memory during the boot load process.

The beginning of the boot table defaults to the linked load address of the first bootable section in the input file, unless you use one of the following mechanisms, listed here from low to high priority. Higher priority mechanisms override the values set by low priority options in an overlapping range.

1. **The ROM origin specified in the ROMS directive.** The hex conversion utility places the boot table at the origin of the first memory range in a ROMS directive.

2. **The --bootorg option.** The hex conversion utility places the boot table at the address specified by the --bootorg option if you select boot loading from memory.
### 10.11 Control Hex Conversion Utility Diagnostics

The hex conversion utility uses certain C/C++ compiler options to control hex-converter-generated diagnostics.

- **--diag_error=id**
  Categorizes the diagnostic identified by `id` as an error. To determine the numeric identifier of a diagnostic message, use the `--display_error_number` option first in a separate link. Then use `--diag_error=id` to recategorize the diagnostic as an error. You can only alter the severity of discretionary diagnostics.

- **--diag_remark=id**
  Categorizes the diagnostic identified by `id` as a remark. To determine the numeric identifier of a diagnostic message, use the `--display_error_number` option first in a separate link. Then use `--diag_remark=id` to recategorize the diagnostic as a remark. You can only alter the severity of discretionary diagnostics.

- **--diag_suppress=id**
  Suppresses the diagnostic identified by `id`. To determine the numeric identifier of a diagnostic message, use the `--display_error_number` option first in a separate link. Then use `--diag_suppress=id` to suppress the diagnostic. You can only suppress discretionary diagnostics.

- **--diag_warning=id**
  Categorizes the diagnostic identified by `id` as a warning. To determine the numeric identifier of a diagnostic message, use the `--display_error_number` option first in a separate link. Then use `--diag_warning=id` to recategorize the diagnostic as a warning. You can only alter the severity of discretionary diagnostics.

- **--display_error_number**
  Displays a diagnostic's numeric identifier along with its text. Use this option in determining which arguments you need to supply to the diagnostic suppression options (`--diag_suppress`, `--diag_error`, `--diag_remark`, and `--diag_warning`). This option also indicates whether a diagnostic is discretionary. A discretionary diagnostic is one whose severity can be overridden. A discretionary diagnostic includes the suffix `D`; otherwise, no suffix is present. See the TMS320C6000 Optimizing Compiler User's Guide for more information on understanding diagnostic messages.

- **--issue_remarks**
  Issues remarks (nonserious warnings), which are suppressed by default.

- **--no_warnings**
  Suppresses warning diagnostics (errors are still issued).

- **--set_error_limit=count**
  Sets the error limit to `count`, which can be any decimal value. The linker abandons linking after this number of errors. (The default is 100.)

- **--verbose_diagnostics**
  Provides verbose diagnostics that display the original source with line-wrap and indicate the position of the error in the source line.
10.12 Description of the Object Formats

The hex conversion utility has options that identify each format. Table 10-2 specifies the format options. They are described in the following sections.

- You need to use only one of these options on the command line. If you use more than one option, the last one you list overrides the others.
- The default format is Tektronix (--tektronix option).

<table>
<thead>
<tr>
<th>Option</th>
<th>Alias</th>
<th>Format</th>
<th>Address Bits</th>
<th>Default Width</th>
</tr>
</thead>
<tbody>
<tr>
<td>--ascii</td>
<td>-a</td>
<td>ASCII-Hex</td>
<td>16</td>
<td>8</td>
</tr>
<tr>
<td>--intel</td>
<td>-i</td>
<td>Intel</td>
<td>32</td>
<td>8</td>
</tr>
<tr>
<td>--motorola=1</td>
<td>-m1</td>
<td>Motorola-S1</td>
<td>16</td>
<td>8</td>
</tr>
<tr>
<td>--motorola=2</td>
<td>-m2</td>
<td>Motorola-S2</td>
<td>24</td>
<td>8</td>
</tr>
<tr>
<td>--motorola=3</td>
<td>-m3</td>
<td>Motorola-S3</td>
<td>32</td>
<td>8</td>
</tr>
<tr>
<td>–ti-tagged</td>
<td>-t</td>
<td>TI-Tagged</td>
<td>16</td>
<td>16</td>
</tr>
<tr>
<td>–ti_txt</td>
<td>-x</td>
<td>TI_TXT</td>
<td>8</td>
<td>8</td>
</tr>
</tbody>
</table>

Address bits determine how many bits of the address information the format supports. Formats with 16-bit addresses support addresses up to 64K only. The utility truncates target addresses to fit in the number of available bits.

The default width determines the default output width of the format. You can change the default width by using the --romwidth option or by using the romwidth parameter in the ROMS directive. You cannot change the default width of the TI-Tagged format, which supports a 16-bit width only.

10.12.1 ASCII-Hex Object Format (--ascii Option)

The ASCII-Hex object format supports 32-bit addresses. The format consists of a byte stream with bytes separated by spaces. Figure 10-6 illustrates the ASCII-Hex format.

The file begins with an ASCII STX character (ctrl-B, 02h) and ends with an ASCII ETX character (ctrl-C, 03h). Address records are indicated with $AXXXXXXX, in which XXXXXXXX is a 8-digit (16-bit) hexadecimal address. The address records are present only in the following situations:

- When discontinuities occur
- When the byte stream does not begin at address 0

You can avoid all discontinuities and any address records by using the --image and --zero options. This creates output that is simply a list of byte values.
10.12.2 Intel MCS-86 Object Format (--intel Option)

The Intel object format supports 16-bit addresses and 32-bit extended addresses. Intel format consists of a 9-character (4-field) prefix (which defines the start of record, byte count, load address, and record type), the data, and a 2-character checksum suffix.

The 9-character prefix represents three record types:

<table>
<thead>
<tr>
<th>Record Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>Data record</td>
</tr>
<tr>
<td>01</td>
<td>End-of-file record</td>
</tr>
<tr>
<td>04</td>
<td>Extended linear address record</td>
</tr>
</tbody>
</table>

Record type 00, the data record, begins with a colon (:) and is followed by the byte count, the address of the first data byte, the record type (00), and the checksum. The address is the least significant 16 bits of a 32-bit address; this value is concatenated with the value from the most recent 04 (extended linear address) record to create a full 32-bit address. The checksum is the 2s complement (in binary form) of the preceding bytes in the record, including byte count, address, and data bytes.

Record type 01, the end-of-file record, also begins with a colon (:) followed by the byte count, the address, the record type (01), and the checksum.

Record type 04, the extended linear address record, specifies the upper 16 address bits. It begins with a colon (:) followed by the byte count, a dummy address of 0h, the record type (04), the most significant 16 bits of the address, and the checksum. The subsequent address fields in the data records contain the least significant bytes of the address.

Figure 10-7 illustrates the Intel hexadecimal object format.
10.12.3 Motorola Exorciser Object Format (--motorola Option)

The Motorola S1, S2, and S3 formats support 16-bit, 24-bit, and 32-bit addresses, respectively. The formats consist of a start-of-file (header) record, data records, and an end-of-file (termination) record. Each record consists of five fields: record type, byte count, address, data, and checksum. The three record types are:

<table>
<thead>
<tr>
<th>Record Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>S0</td>
<td>Header record</td>
</tr>
<tr>
<td>S1</td>
<td>Code/data record for 16-bit addresses (S1 format)</td>
</tr>
<tr>
<td>S2</td>
<td>Code/data record for 24-bit addresses (S2 format)</td>
</tr>
<tr>
<td>S3</td>
<td>Code/data record for 32-bit addresses (S3 format)</td>
</tr>
<tr>
<td>S7</td>
<td>Termination record for 32-bit addresses (S3 format)</td>
</tr>
<tr>
<td>S8</td>
<td>Termination record for 24-bit addresses (S2 format)</td>
</tr>
<tr>
<td>S9</td>
<td>Termination record for 16-bit addresses (S1 format)</td>
</tr>
</tbody>
</table>

The byte count is the character pair count in the record, excluding the type and byte count itself. The checksum is the least significant byte of the 1s complement of the sum of the values represented by the pairs of characters making up the byte count, address, and the code/data fields.

Figure 10-8 illustrates the Motorola-S object format.

Figure 10-8. Motorola-S Format
### 10.12.4 Extended Tektronix Object Format (--tektronix Option)

The Tektronix object format supports 32-bit addresses and has two types of records:

- **Data records** contain the header field, the load address, and the object code.
- **Termination records** signify the end of a module.

The header field in the data record contains the following information:

<table>
<thead>
<tr>
<th>Item</th>
<th>Number of ASCII Characters</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>%</td>
<td>1</td>
<td>Data type is Tektronix format</td>
</tr>
<tr>
<td>Block length</td>
<td>2</td>
<td>Number of characters in the record, minus the %</td>
</tr>
<tr>
<td>Block type</td>
<td>1</td>
<td>6 = data record</td>
</tr>
<tr>
<td></td>
<td></td>
<td>8 = termination record</td>
</tr>
<tr>
<td>Checksum</td>
<td>2</td>
<td>A 2-digit hex sum modulo 256 of all values in the record except the % and the checksum itself.</td>
</tr>
</tbody>
</table>

The load address in the data record specifies where the object code will be located. The first digit specifies the address length; this is always 8. The remaining characters of the data record contain the object code, two characters per byte.

*Figure 10-9* illustrates the Tektronix object format.
10.12.5 **Texas Instruments SDSMAC (TI-Tagged) Object Format (--ti_tagged Option)**

The Texas Instruments SDSMAC (TI-Tagged) object format supports 16-bit addresses, including start-of-file record, data records, and end-of-file record. Each data records consists of a series of small fields and is signified by a tag character:

<table>
<thead>
<tr>
<th>Tag Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>K</td>
<td>Followed by the program identifier</td>
</tr>
<tr>
<td>7</td>
<td>Followed by a checksum</td>
</tr>
<tr>
<td>8</td>
<td>Followed by a dummy checksum (ignored)</td>
</tr>
<tr>
<td>9</td>
<td>Followed by a 16-bit load address</td>
</tr>
<tr>
<td>B</td>
<td>Followed by a data word (four characters)</td>
</tr>
<tr>
<td>F</td>
<td>Identifies the end of a data record</td>
</tr>
<tr>
<td>*</td>
<td>Followed by a data byte (two characters)</td>
</tr>
</tbody>
</table>

Figure 10-10 illustrates the tag characters and fields in TI-Tagged object format.

![Figure 10-10. TI-Tagged Object Format](image)

If any data fields appear before the first address, the first field is assigned address 0000h. Address fields may be expressed but not required for any data byte. The checksum field, preceded by the tag character 7, is the 2s complement of the sum of the 8-bit ASCII values of characters, beginning with the first tag character and ending with the checksum tag character (7 or 8). The end-of-file record is a colon (:\).
10.12.6  **TI-TXT Hex Format (--)ti_txt Option**

The TI-TXT hex format supports 16-bit hexadecimal data. It consists of section start addresses, data byte, and an end-of-file character. These restrictions apply:

- The number of sections is unlimited.
- Each hexadecimal start address must be even.
- Each line must have 16 data bytes, except the last line of a section.
- Data bytes are separated by a single space.
- The end-of-file termination tag q is mandatory.

The data record contains the following information:

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>@ADDR</td>
<td>Hexadecimal start address of a section</td>
</tr>
<tr>
<td>DATAn</td>
<td>Hexadecimal data byte</td>
</tr>
<tr>
<td>q</td>
<td>End-of-file termination character</td>
</tr>
</tbody>
</table>

**Figure 10-11. TI-TXT Object Format**

```
@ADDR1
DATA01 DATA02 ........ DATA16
DATA17 DATA32 ........ DATA32
DATAn ........ DATAn

@ADDR2
DATA01 ................. DATAn
q

End-of-line character
```

**Example 10-3. TI-TXT Object Format**

```
@F000
31 40 00 03 B2 40 80 5A 20 01 D2 D3 22 00 D2 E3
21 00 3F 40 E8 FD 1F 83 FE 23 F9 3F
@FFFE
00 F0
Q
```
You can use the .cdecls assembler directive to share C headers containing declarations and prototypes between C and assembly code. Any legal C/C++ can be used in a .cdecls block and the C/C++ declarations will cause suitable assembly to be generated automatically, allowing you to reference the C/C++ constructs in assembly code.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>11.1 Overview of the .cdecls Directive</td>
<td>305</td>
</tr>
<tr>
<td>11.2 Notes on C/C++ Conversions</td>
<td>305</td>
</tr>
<tr>
<td>11.3 Notes on C++ Specific Conversions</td>
<td>309</td>
</tr>
<tr>
<td>11.4 Special Assembler Support</td>
<td>310</td>
</tr>
</tbody>
</table>
11.1 Overview of the .cdecls Directive

The .cdecls directive allows programmers in mixed assembly and C/C++ environments to share C headers containing declarations and prototypes between the C and assembly code. Any legal C/C++ can be used in a .cdecls block and the C/C++ declarations will cause suitable assembly to be generated automatically. This allows the programmer to reference the C/C++ constructs in assembly code — calling functions, allocating space, and accessing structure members — using the equivalent assembly mechanisms. While function and variable definitions are ignored, most common C/C++ elements are converted to assembly: enumerations, (non function-like) macros, function and variable prototypes, structures, and unions.

See the .cdecls directive description for details on the syntax of the .cdecls assembler directive.

The .cdecls directive can appear anywhere in an assembly source file, and can occur multiple times within a file. However, the C/C++ environment created by one .cdecls is not inherited by a later .cdecls; the C/C++ environment starts over for each .cdecls instance.

For example, the following code causes the warning to be issued:

```
.cdecls C,NOLIST
{%
  #define ASMTEST 1
%
.cdecls C,NOLIST
{%
  #ifndef ASMTEST
    #warn "ASMTEST not defined!" /* will be issued */
  #endif
%
```

Therefore, a typical use of the .cdecls block is expected to be a single usage near the beginning of the assembly source file, in which all necessary C/C++ header files are included.

Use the compiler --include_path=path options to specify additional include file paths needed for the header files used in assembly, as you would when compiling C files.

Any C/C++ errors or warnings generated by the code of the .cdecls are emitted as they normally would for the C/C++ source code. C/C++ errors cause the directive to fail, and any resulting converted assembly is not included.

C/C++ constructs that cannot be converted, such as function-like macros or variable definitions, cause a comment to be output to the converted assembly file. For example:

```
; ASM HEADER WARNING - variable definition 'ABCD' ignored
```

The prefix ASM HEADER WARNING appears at the beginning of each message. To see the warnings, either the WARN parameter needs to be specified so the messages are displayed on STDERR, or else the LIST parameter needs to be specified so the warnings appear in the listing file, if any.

Finally, note that the converted assembly code does not appear in the same order as the original C/C++ source code and C/C++ constructs may be simplified to a normalized form during the conversion process, but this should not affect their final usage.

11.2 Notes on C/C++ Conversions

The following sections describe C and C++ conversion elements that you need to be aware of when sharing header files with assembly source.

11.2.1 Comments

Comments are consumed entirely at the C level, and do not appear in the resulting converted assembly file.
11.2.2 Conditional Compilation (#if/#else/#ifdef/etc.)

Conditional compilation is handled entirely at the C level during the conversion step. Define any necessary macros either on the command line (using the compiler --define='name=value' option) or within a .cdecls block using #define. The #if, #ifdef, etc. C/C++ directives are not converted to assembly .if, .else, .elseif, and .endif directives.

11.2.3 Pragmas

Pragmas found in the C/C++ source code cause a warning to be generated as they are not converted. They have no other effect on the resulting assembly file. See the .cdecls topic for the WARN and NOWARN parameter discussion for where these warnings are created.

11.2.4 The #error and #warning Directives

These preprocessor directives are handled completely by the compiler during the parsing step of conversion. If one of these directives is encountered, the appropriate error or warning message is emitted. These directives are not converted to .emsg or .wmsg in the assembly output.

11.2.5 Predefined symbol __ASM_HEADER__

The C/C++ macro __ASM_HEADER__ is defined in the compiler while processing code within .cdecls. This allows you to make changes in your code, such as not compiling definitions, during the .cdecls processing.

Be Careful With the __ASM_HEADER__ Macro

NOTE: You must be very careful not to use this macro to introduce any changes in the code that could result in inconsistencies between the code processed while compiling the C/C++ source and while converting to assembly.

11.2.6 Usage Within C/C++ asm( ) Statements

The .cdecls directive is not allowed within C/C++ asm( ) statements and will cause an error to be generated.

11.2.7 The #include Directive

The C/C++ #include preprocessor directive is handled transparently by the compiler during the conversion step. Such #includes can be nested as deeply as desired as in C/C++ source. The assembly directives .include and .copy are not used or needed within a .cdecls. Use the command line --include_path option to specify additional paths to be searched for included files, as you would for C compilation.

11.2.8 Conversion of #define Macros

Only object-like macros are converted to assembly. Function-like macros have no assembly representation and so cannot be converted. Pre-defined and built-in C/C++ macros are not converted to assembly (i.e., __FILE__, __TIME__, __TI_COMPILER_VERSION__, etc.). For example, this code is converted to assembly because it is an object-like macro:

```c
#define NAME Charley
```

This code is not converted to assembly because it is a function-like macro:

```c
#define MAX(x,y) (x>y ? x : y)
```

Some macros, while they are converted, have no functional use in the containing assembly file. For example, the following results in the assembly substitution symbol FOREVER being set to the value while(1), although this has no useful use in assembly because while(1) is not legal assembly code.

```c
#define FOREVER while(1)
```
Macro values are not interpreted as they are converted. For example, the following results in the assembler substitution symbol OFFSET being set to the literal string value 5+12 and not the value 17. This happens because the semantics of the C/C++ language require that macros are evaluated in context and not when they are parsed.

#define OFFSET 5+12

Because macros in C/C++ are evaluated in their usage context, C/C++ printf escape sequences such as \n are not converted to a single character in the converted assembly macro. See Section 11.2.11 for suggestions on how to use C/C++ macro strings.

Macros are converted using the .define directive (see Section 11.4.2), which functions similarly to the .asg assembler directive. The exception is that .define disallows redefinitions of register symbols and mnemonics to prevent the conversion from corrupting the basic assembly environment. To remove a macro from the assembly scope, .undef can be used following the .cdecls that defines it (see Section 11.4.3).

The macro functionality of # (stringize operator) is only useful within functional macros. Since functional macros are not supported by this process, # is not supported either. The concatenation operator ## is only useful in a functional context, but can be used degenerately to concatenate two strings and so it is supported in that context.

### 11.2.9 The #undef Directive

Symbols undefined using the #undef directive before the end of the .cdecls are not converted to assembly.

### 11.2.10 Enumerations

Enumeration members are converted to .enum elements in assembly. For example:

```c
enum state { ACTIVE=0x10, SLEEPING=0x01, INTERRUPT=0x100, POWEROFF, LAST};
```

is converted to the following assembly code:

```assembly
state .enum
ACTIVE .emember 16
SLEEPING .emember 1
INTERRUPT .emember 256
POWEROFF .emember 257
LAST .emember 258
.endenum
```

The members are used via the pseudo-scoping created by the .enum directive.

The usage is similar to that for accessing structure members, enum_name.member.

This pseudo-scoping is used to prevent enumeration member names from corrupting other symbols within the assembly environment.

### 11.2.11 C Strings

Because C string escapes such as \n and \t are not converted to hex characters 0x0A and 0x09 until their use in a string constant in a C/C++ program, C macros whose values are strings cannot be represented as expected in assembly substitution symbols. For example:

```c
#define MSG "\tHI
"
```

becomes, in assembly:

```assembly
.definet "\tHI\n",MSG ; 6 quoted characters! not 5!
```

When used in a C string context, you expect this statement to be converted to 5 characters (tab, H, I, newline, NULL), but the .string assembler directive does not know how to perform the C escape conversions.

You can use the .cstring directive to cause the escape sequences and NULL termination to be properly handled as they would in C/C++. Using the above symbol MSG with a .cstring directive results in 5 characters of memory being allocated, the same characters as would result if used in a C/C++ strong context. (See Section 11.4.7 for the .cstring directive syntax.)
11.2.12 C/C++ Built-In Functions

The C/C++ built-in functions, such as sizeof( ), are not translated to their assembly counterparts, if any, if they are used in macros. Also, their C expression values are not inserted into the resulting assembly macro because macros are evaluated in context and there is no active context when converting the macros to assembly.

Suitable functions such as $sizeof( )$ are available in assembly expressions. However, as the basic types such as int/char/float have no type representation in assembly, there is no way to ask for $sizeof(int)$, for example, in assembly.

11.2.13 Structures and Unions

C/C++ structures and unions are converted to assembly .struct and .union elements. Padding and ending alignments are added as necessary to make the resulting assembly structure have the same size and member offsets as the C/C++ source. The primary purpose is to allow access to members of C/C++ structures, as well as to facilitate debugging of the assembly code. For nested structures, the assembly .tag feature is used to refer to other structures/unions.

The alignment is also passed from the C/C++ source so that the assembly symbol is marked with the same alignment as the C/C++ symbol. (See Section 11.2.3 for information about pragmas, which may attempt to modify structures.) Because the alignment of structures is stored in the assembly symbol, built-in assembly functions like $sizeof( )$ and $alignof( )$ can be used on the resulting structure name symbol.

When using unnamed structures (or unions) in typedefs, such as:

```c
typedef struct { int a_member; } mystrname;
```

This is really a shorthand way of writing:

```c
struct temporary_name { int a_member; };
typedef temporary_name mystrname;
```

The conversion processes the above statements in the same manner: generating a temporary name for the structure and then using .define to output a typedef from the temporary name to the user name. You should use your `mystrname` in assembly the same as you would in C/C++, but do not be confused by the assembly structure definition in the list, which contains the temporary name. You can avoid the temporary name by specifying a name for the structure, as in:

```c
typedef struct a_st_name { ... } mystrname;
```

If a shorthand method is used in C to declare a variable with a particular structure, for example:

```c
extern struct a_name { int a_member; } a_variable;
```

Then after the structure is converted to assembly, a .tag directive is generated to declare the structure of the external variable, such as:

```assembly
_a_variable .tag a_st_name
```

This allows you to refer to `a_variable.a_member` in your assembly code.

11.2.14 Function/Variable Prototypes

Non-static function and variable prototypes (not definitions) will result in a .global directive being generated for each symbol found.

See Section 11.3.1 for C++ name mangling issues.

Function and variable definitions will result in a warning message being generated (see the WARN/NOWARN parameter discussion for where these warnings are created) for each, and they will not be represented in the converted assembly.

The assembly symbol representing the variable declarations will not contain type information about those symbols. Only a .global will be issued for them. Therefore, it is your responsibility to ensure the symbol is used appropriately.

See Section 11.2.13 for information on variables names which are of a structure/union type.
11.2.15  C Constant Suffixes

The C constant suffixes u, l, and f are passed to the assembly unchanged. The assembler will ignore these suffixes if used in assembly expressions.

11.2.16  Basic C/C++ Types

Only complex types (structures and unions) in the C/C++ source code are converted to assembly. Basic types such as int, char, or float are not converted or represented in assembly beyond any existing .int, .char, .float, etc. directives that previously existed in assembly.

Typedefs of basic types are therefore also not represented in the converted assembly.

11.3  Notes on C++ Specific Conversions

The following sections describe C++ specific conversion elements that you need to be aware of when sharing header files with assembly source.

11.3.1  Name Mangling

Symbol names may be mangled in C++ source files. When mangling occurs, the converted assembly will use the mangled names to avoid symbol name clashes. You can use the demangler (dem6x) to demangle names and identify the correct symbols to use in assembly.

To defeat name mangling in C++ for symbols where polymorphism (calling a function of the same name with different kinds of arguments) is not required, use the following syntax:

```
extern "C" void somefunc(int arg);
```

The above format is the short method for declaring a single function. To use this method for multiple functions, you can also use the following syntax:

```
extern "C"
{
    void somefunc(int arg);
    int anotherfunc(int arg);
    ...
}
```

11.3.2  Derived Classes

Derived classes are only partially supported when converting to assembly because of issues related to C++ scoping which does not exist in assembly. The greatest difference is that base class members do not automatically become full (top-level) members of the derived class. For example:

```
class base
{
    public:
        int b1;
};

class derived : public base
{
    public:
        int d1;
}
```

In C++ code, the class derived would contain both integers b1 and d1. In the converted assembly structure "derived", the members of the base class must be accessed using the name of the base class, such as derived.__b_base.b1 rather than the expected derived.b1.

A non-virtual, non-empty base class will have __b_ prepended to its name within the derived class to signify it is a base class name. That is why the example above is derived.__b_base.b1 and not simply derived.base.b1.
11.3.3 Templates
No support exists for templates.

11.3.4 Virtual Functions
No support exists for virtual functions, as they have no assembly representation.

11.4 Special Assembler Support

11.4.1 Enumerations (.enum/.emember/.endenum)
The following directives support a pseudo-scoping for enumerations:

```plaintext
ENUM_NAME .enum
MEMBER1 .emember [value]
MEMBER2 .emember [value]
...
.endenum
```

The .enum directive begins the enumeration definition and .endenum terminates it.
The enumeration name (ENUM_NAME) cannot be used to allocate space; its size is reported as zero.
The format to use the value of a member is ENUM_NAME.MEMBER, similar to a structure member usage.
The .emember directive optionally accepts the value to set the member to, just as in C/C++. If not specified, the member takes a value one more than the previous member. As in C/C++, member names cannot be duplicated, although values can be. Unless specified with .emember, the first enumeration member will be given the value 0 (zero), as in C/C++.

The .endenum directive cannot be used with a label, as structure .endstruct directives can, because the .endenum directive has no value like the .endstruct does (containing the size of the structure).

Conditional compilation directives (.if/.else/.elseif/.endif) are the only other non-enumeration code allowed within the .enum/.endenum sequence.

11.4.2 The .define Directive
The .define directive functions in the same manner as the .asg directive, except that .define disallows creation of a substitution symbol that has the same name as a register symbol or mnemonic. It does not create a new symbol name space in the assembler, rather it uses the existing substitution symbol name space. The syntax for the directive is:

```plaintext
.define substitution string , substitution symbol name
```

The .define directive is used to prevent corruption of the assembly environment when converting C/C++ headers.

11.4.3 The .undefine/.unasg Directives
The .undef directive is used to remove the definition of a substitution symbol created using .define or .asg. This directive will remove the named symbol from the substitution symbol table from the point of the .undef to the end of the assembly file. The syntax for these directives is:

```plaintext
.undefine substitution symbol name
.unasg substitution symbol name
```

This can be used to remove from the assembly environment any C/C++ macros that may cause a problem.

Also see Section 11.4.2, which covers the .define directive.
11.4.4 The $defined( ) Built-In Function

The $defined directive returns true/1 or false/0 depending on whether the name exists in the current substitution symbol table or the standard symbol table. In essence $defined returns TRUE if the assembler has any user symbol in scope by that name. This differs from $isdefed in that $isdefed only tests for NON-substitution symbols. The syntax is:

```
$defined( substitution symbol name )
```

A statement such as ".if $defined(macroname)" is then similar to the C code "#ifdef macroname". See Section 11.4.2 and Section 11.4.3 for the use of .define and .undef in assembly.

11.4.5 The $sizeof Built-In Function

The assembly built-in function $sizeof( ) can be used to query the size of a structure in assembly. It is an alias for the already existing $structsz( ). The syntax is:

```
$sizeof( structure name )
```

The $sizeof function can then be used similarly to the C built-in function sizeof( ).

The assembler's $sizeof( ) built-in function cannot be used to ask for the size of basic C/C++ types, such as $sizeof(int), because those basic type names are not represented in assembly. Only complex types are converted from C/C++ to assembly.

Also see Section 11.2.12, which notes that this conversion does not happen automatically if the C/C++ sizeof( ) built-in function is used within a macro.

11.4.6 Structure/Union Alignment and $alignof( )

The assembly .struct and .union directives take an optional second argument which can be used to specify a minimum alignment to be applied to the symbol name. This is used by the conversion process to pass the specific alignment from C/C++ to assembly.

The assembly built-in function $alignof( ) can be used to report the alignment of these structures. This can be used even on assembly structures, and the function will return the minimum alignment calculated by the assembler.

11.4.7 The .cstring Directive

You can use the .cstring directive to cause the escape sequences and NULL termination to be properly handled as they would in C/C++.

```
.cstring "String with C escapes.\nWill be NULL terminated.\012"
```

See Section 11.2.11 for more information on the .cstring directive.
Symbolic Debugging Directives

The assembler supports several directives that the TMS320C6000 C/C++ compiler uses for symbolic debugging.

These directives are not meant for use by assembly-language programmers. They require arguments that can be difficult to calculate manually, and their usage must conform to a predetermined agreement between the compiler, the assembler, and the debugger. This appendix documents these directives for informational purposes only.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>A.1 DWARF Debugging Format</td>
<td>313</td>
</tr>
<tr>
<td>A.2 Debug Directive Syntax</td>
<td>313</td>
</tr>
</tbody>
</table>
A.1 DWARF Debugging Format

A subset of the DWARF symbolic debugging directives are always listed in the assembly language file that the compiler creates for program analysis purposes. To list the complete set used for full symbolic debug, invoke the compiler with the --symdebug:dwarf option, as shown below:

```
clix --symdebug:dwarf --keep_asm input_file
```

The --keep_asm option instructs the compiler to retain the generated assembly file.

To disable the generation of all symbolic debug directives, invoke the compiler with the -symdebug:none option:

```
clix --symdebug:none --keep_asm input_file
```

The DWARF debugging format consists of the following directives:

- The `.dwtag` and `.dwendtag` directives define a Debug Information Entry (DIE) in the .debug_info section.
- The `.dwartr` directive adds an attribute to an existing DIE.
- The `.dwpsn` directive identifies the source position of a C/C++ statement.
- The `.dwcie` and `.dwendentry` directives define a Common Information Entry (CIE) in the .debug_frame section.
- The `.dwdfe` and `.dwendentry` directives define a Frame Description Entry (FDE) in the .debug_frame section.
- The `.dwcfi` directive defines a call frame instruction for a CIE or FDE.

A.2 Debug Directive Syntax

Table A-1 is an alphabetical listing of the symbolic debugging directives. For information on the C/C++ compiler, refer to the TMS320C6000 Optimizing Compiler User's Guide.

<table>
<thead>
<tr>
<th>Label</th>
<th>Directive</th>
<th>Arguments</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>.block</td>
<td>[beginning line number]</td>
</tr>
</tbody>
</table>
|         | .dwartr   | DIE label, DIE attribute name (DIE attribute value), [DIE attribute name (attribute value)], [...]
|         | .dwcfi    | call frame instruction opcode[, operand[, operand]]                        |
| CIE label | .dwcie    | version[, return address register]                                        |
|         | .dwendentry |                                                           |
|         | .dwendtag |                                                             |
|         | .dwdfe    | CIE label                                                                 |
|         | .dwpsn    | "filename ", line number, column number                                |
| DIE label | .dwtag    | DIE tag name, DIE attribute name (DIE attribute value), [DIE attribute name (attribute value)], [...]
|         | .endblock | [ending line number]                                                     |
|         | .endfunc  | [ending line number[, register mask[, frame size]]]                       |
|         | .eos      |                                                           |
|         | .etag     | name[, size]                                                             |
|         | .file     | "filename "                                                             |
|         | .func     | [beginning line number]                                                 |
|         | .line     | line number[, address]                                                  |
|         | .member   | name, value[, type, storage class, size, tag, dims]                      |
|         | .stag     | name[, size]                                                             |
|         | .sym      | name, value[, type, storage class, size, tag, dims]                      |
|         | .utag     | name[, size]                                                             |
XML Link Information File Description

The TMS320C6000 linker supports the generation of an XML link information file via the `--xml_link_info` option. This option causes the linker to generate a well-formed XML file containing detailed information about the result of a link. The information included in this file includes all of the information that is currently produced in a linker-generated map file.

As the linker evolves, the XML link information file may be extended to include additional information that could be useful for static analysis of linker results.

This appendix enumerates all of the elements that are generated by the linker into the XML link information file.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>B.1 XML Information File Element Types</td>
<td>315</td>
</tr>
<tr>
<td>B.2 Document Elements</td>
<td>315</td>
</tr>
</tbody>
</table>
B.1 XML Information File Element Types

These element types will be generated by the linker:

- **Container elements** represent an object that contains other elements that describe the object. Container elements have an id attribute that makes them accessible from other elements.
- **String elements** contain a string representation of their value.
- **Constant elements** contain a 32-bit unsigned long representation of their value (with a 0x prefix).
- **Reference elements** are empty elements that contain an idref attribute that specifies a link to another container element.

In Section B.2, the element type is specified for each element in parentheses following the element description. For instance, the `<link_time>` element lists the time of the link execution (string).

B.2 Document Elements

The root element, or the document element, is `<link_info>`. All other elements contained in the XML link information file are children of the `<link_info>` element. The following sections describe the elements that an XML information file can contain.

B.2.1 Header Elements

The first elements in the XML link information file provide general information about the linker and the link session:

- The `<banner>` element lists the name of the executable and the version information (string).
- The `<copyright>` element lists the TI copyright information (string).
- The `<link_time>` is a timestamp representation of the link time (unsigned 32-bit int).
- The `<output_file>` element lists the name of the linked output file generated (string).
- The `<entry_point>` element specifies the program entry point, as determined by the linker (container) with two entries:
  - The `<name>` is the entry point symbol name, if any (string).
  - The `<address>` is the entry point address (constant).

*Example B-1. Header Element for the hi.out Output File*

```
<banner>TMS320Cxx Linker Version x.xx (Jan 6 2008)</banner>
<copyright>Copyright (c) 1996-2008 Texas Instruments Incorporated</copyright>
<link_time>0x43dfd8a4</link_time>
<output_file>hi.out</output_file>
<entry_point>
  <name>_c_int00</name>
  <address>0xaf80</address>
</entry_point>
```
B.2.2 Input File List

The next section of the XML link information file is the input file list, which is delimited with a `<input_file_list>` container element. The `<input_file_list>` can contain any number of `<input_file>` elements.

Each `<input_file>` instance specifies the input file involved in the link. Each `<input_file>` has an id attribute that can be referenced by other elements, such as an `<object_component>`. An `<input_file>` is a container element enclosing the following elements:

- The `<path>` element names a directory path, if applicable (string).
- The `<kind>` element specifies a file type, either archive or object (string).
- The `<file>` element specifies an archive name or filename (string).
- The `<name>` element specifies an object file name, or archive member name (string).

Example B-2. Input File List for the hi.out Output File

```xml
<input_file_list>
  <input_file id="fl-1">
    <kind>object</kind>
    <file>hi.obj</file>
    <name>hi.obj</name>
  </input_file>
  <input_file id="fl-2">
    <path>/tools/lib/</path>
    <kind>archive</kind>
    <file>rtsxxx.lib</file>
    <name>boot.obj</name>
  </input_file>
  <input_file id="fl-3">
    <path>/tools/lib/</path>
    <kind>archive</kind>
    <file>rtsxxx.lib</file>
    <name>exit.obj</name>
  </input_file>
  <input_file id="fl-4">
    <path>/tools/lib/</path>
    <kind>archive</kind>
    <file>rtsxxx.lib</file>
    <name>printf.obj</name>
  </input_file>
  ...
</input_file_list>
```
B.2.3 Object Component List

The next section of the XML link information file contains a specification of all of the object components that are involved in the link. An example of an object component is an input section. In general, an object component is the smallest piece of object that can be manipulated by the linker.

The `<object_component_list>` is a container element enclosing any number of `<object_component>` elements.

Each `<object_component>` specifies a single object component. Each `<object_component>` has an id attribute so that it can be referenced directly from other elements, such as a `<logical_group>`. An `<object_component>` is a container element enclosing the following elements:

- The `<name>` element names the object component (string).
- The `<load_address>` element specifies the load-time address of the object component (constant).
- The `<run_address>` element specifies the run-time address of the object component (constant).
- The `<size>` element specifies the size of the object component (constant).
- The `<input_file_ref>` element specifies the source file where the object component originated (reference).

**Example B-3. Object Component List for the fl-4 Input File**

```
<object_component id="oc-20">
  <name>.text</name>
  <load_address>0xac00</load_address>
  <run_address>0xac00</run_address>
  <size>0xc0</size>
  <input_file_ref idref="fl-4"/>
</object_component>
<object_component id="oc-21">
  <name>.data</name>
  <load_address>0x80000000</load_address>
  <run_address>0x80000000</run_address>
  <size>0x0</size>
  <input_file_ref idref="fl-4"/>
</object_component>
<object_component id="oc-22">
  <name>.bss</name>
  <load_address>0x80000000</load_address>
  <run_address>0x80000000</run_address>
  <size>0x0</size>
  <input_file_ref idref="fl-4"/>
</object_component>
```
B.2.4 Logical Group List

The `<logical_group_list>` section of the XML link information file is similar to the output section listing in a linker-generated map file. However, the XML link information file contains a specification of GROUP and UNION output sections, which are not represented in a map file. There are three kinds of list items that can occur in a `<logical_group_list>`:

- The `<logical_group>` is the specification of a section or GROUP that contains a list of object components or logical group members. Each `<logical_group>` element is given an id so that it may be referenced from other elements. Each `<logical_group>` is a container element enclosing the following elements:
  - The `<name>` element names the logical group (string).
  - The `<load_address>` element specifies the load-time address of the logical group (constant).
  - The `<run_address>` element specifies the run-time address of the logical group (constant).
  - The `<size>` element specifies the size of the logical group (constant).
  - The `<contents>` element lists elements contained in this logical group (container). These elements refer to each of the member objects contained in this logical group:
    - The `<object_component_ref>` is an object component that is contained in this logical group (reference).
    - The `<logical_group_ref>` is a logical group that is contained in this logical group (reference).

- The `<overlay>` is a special kind of logical group that represents a UNION, or a set of objects that share the same memory space (container). Each `<overlay>` element is given an id so that it may be referenced from other elements (like from an `<allocated_space>` element in the placement map). Each `<overlay>` contains the following elements:
  - The `<name>` element names the overlay (string).
  - The `<run_address>` element specifies the run-time address of overlay (constant).
  - The `<size>` element specifies the size of logical group (constant).
  - The `<contents>` container element lists elements contained in this overlay. These elements refer to each of the member objects contained in this logical group:
    - The `<object_component_ref>` is an object component that is contained in this logical group (reference).
    - The `<logical_group_ref>` is a logical group that is contained in this logical group (reference).

- The `<split_section>` is another special kind of logical group that represents a collection of logical groups that is split among multiple memory areas. Each `<split_section>` element is given an id so that it may be referenced from other elements. The id consists of the following elements.
  - The `<name>` element names the split section (string).
  - The `<contents>` container element lists elements contained in this split section. The `<logical_group_ref>` elements refer to each of the member objects contained in this split section, and each element referenced is a logical group that is contained in this split section (reference).
Example B-4. Logical Group List for the fl-4 Input File

```xml
<logical_group_list>
  ... 
  <logical_group id="lg-7">
    <name>.text</name>
    <load_address>0x20</load_address>
    <run_address>0x20</run_address>
    <size>0xb240</size>
    <contents>
      <object_component_ref idref="oc-34"/>
      <object_component_ref idref="oc-108"/>
      <object_component_ref idref="oc-e2"/>
    </contents>
  </logical_group>
  ... 
  <overlay id="lg-b">
    <name>UNION_1</name>
    <run_address>0xb600</run_address>
    <size>0xc0</size>
    <contents>
      <object_component_ref idref="oc-45"/>
    </overlay>
    <logical_group_ref idref="lg-8"/>
  </contents>
</split_section>
  ... 
  <split_section id="lg-12">
    <name>.task_scn</name>
    <size>0x120</size>
    <contents>
      <logical_group_ref idref="lg-10"/>
      <logical_group_ref idref="lg-11"/>
    </contents>
  </split_section>
  ... 
</logical_group_list>
```
B.2.5 Placement Map

The `<placement_map>` element describes the memory placement details of all named memory areas in the application, including unused spaces between logical groups that have been placed in a particular memory area.

The `<memory_area>` is a description of the placement details within a named memory area (container). The description consists of these items:

- The `<name>` names the memory area (string).
- The `<page_id>` gives the id of the memory page in which this memory area is defined (constant).
- The `<origin>` specifies the beginning address of the memory area (constant).
- The `<length>` specifies the length of the memory area (constant).
- The `<used_space>` specifies the amount of allocated space in this area (constant).
- The `<unused_space>` specifies the amount of available space in this area (constant).
- The `<attributes>` lists the RWXI attributes that are associated with this area, if any (string).
- The `<fill_value>` specifies the fill value that is to be placed in unused space, if the fill directive is specified with the memory area (constant).
- The `<usage_details>` lists details of each allocated or available fragment in this memory area. If the fragment is allocated to a logical group, then a `<logical_group_ref>` element is provided to facilitate access to the details of that logical group. All fragment specifications include `<start_address>` and `<size>` elements.
  - The `<allocated_space>` element provides details of an allocated fragment within this memory area (container):
    - The `<start_address>` specifies the address of the fragment (constant).
    - The `<size>` specifies the size of the fragment (constant).
    - The `<logical_group_ref>` provides a reference to the logical group that is allocated to this fragment (reference).
  - The `<available_space>` element provides details of an available fragment within this memory area (container):
    - The `<start_address>` specifies the address of the fragment (constant).
    - The `<size>` specifies the size of the fragment (constant).

Example B-5. Placement Map for the fl-4 Input File

```
<placement_map>
  <memory_area>
    <name>PMEM</name>
    <page_id>0x0</page_id>
    <origin>0x20</origin>
    <length>0x100000</length>
    <used_space>0xb240</used_space>
    <unused_space>0xf4dc0</unused_space>
    <attributes>RWXI</attributes>
    <usage_details>
      <allocated_space>
        <start_address>0x20</start_address>
        <size>0xb240</size>
        <logical_group_ref idref="lg-7"/>
      </allocated_space>
      <available_space>
        <start_address>0xb260</start_address>
        <size>0xf4dc0</size>
      </available_space>
    </usage_details>
  </memory_area>
  ...
</placement_map>
```
B.2.6 Far Call Trampoline List

The `<far_call_trampoline_list>` is a list of `<far_call_trampoline>` elements. The linker supports the generation of far call trampolines to help a call site reach a destination that is out of range. A far call trampoline function is guaranteed to reach the called function (callee) as it may utilize an indirect call to the called function.

The `<far_call_trampoline_list>` enumerates all of the far call trampolines that are generated by the linker for a particular link. The `<far_call_trampoline_list>` can contain any number of `<far_call_trampoline>` elements. Each `<far_call_trampoline>` is a container enclosing the following elements:

- The `<callee_name>` element names the destination function (string).
- The `<callee_address>` is the address of the called function (constant).
- The `<trampoline_object_component_ref>` is a reference to an object component that contains the definition of the trampoline function (reference).
- The `<trampoline_address>` is the address of the trampoline function (constant).
- The `<callee_name>` enumerates all call sites that utilize this trampoline to reach the called function (container).
- The `<trampoline_call_site>` provides the details of a trampoline call site (container) and consists of these items:
  - The `<caller_address>` specifies the call site address (constant).
  - The `<callee_object_component_ref>` is the object component where the call site resides (reference).

Example B-6. Fall Call Trampoline List for the fl-4 Input File

```xml
<far_call_trampoline_list>
  ...
  <far_call_trampoline>
    <callee_name>_foo</callee_name>
    <callee_address>0x08000030</callee_address>
    <trampoline_object_component_ref idref="oc-123"/>
    <trampoline_address>0x2020</trampoline_address>
    <caller_list>
      <call_site>
        <caller_address>0x1800</caller_address>
        <callee_object_component_ref idref="oc-23"/>
      </call_site>
      <call_site>
        <caller_address>0x1810</caller_address>
        <callee_object_component_ref idref="oc-23"/>
      </call_site>
    </caller_list>
  </far_call_trampoline>
  ...
</far_call_trampoline_list>
```
B.2.7 Symbol Table

The `<symbol_table>` contains a list of all of the global symbols that are included in the link. The list provides information about a symbol's name and value. In the future, the symbol_table list may provide type information, the object component in which the symbol is defined, storage class, etc.

The `<symbol>` is a container element that specifies the name and value of a symbol with these elements:

- The `<name>` element specifies the symbol name (string).
- The `<value>` element specifies the symbol value (constant).

Example B-7. Symbol Table for the fl-4 Input File

```xml
<symbol_table>
  <symbol>
    <name>_c_int00</name>
    <value>0xaf80</value>
  </symbol>
  <symbol>
    <name>_main</name>
    <value>0xb1e0</value>
  </symbol>
  <symbol>
    <name>_printf</name>
    <value>0xac00</value>
  </symbol>
  ...
</symbol_table>
```
ABI — Application binary interface.

absolute address — An address that is permanently assigned to a TMS320C6000 memory location.

absolute constant expression — An expression that does not refer to any external symbols or any registers or memory reference. The value of the expression must be knowable at assembly time.

address constant expression — A symbol with a value that is an address plus an addend that is an absolute constant expression with an integer value.

alignment — A process in which the linker places an output section at an address that falls on an n-byte boundary, where n is a power of 2. You can specify alignment with the SECTIONS linker directive.

allocation — A process in which the linker calculates the final memory addresses of output sections.

ANSI — American National Standards Institute; an organization that establishes standards voluntarily followed by industries.

archive library — A collection of individual files grouped into a single file by the archiver.

archiver — A software program that collects several individual files into a single file called an archive library. With the archiver, you can add, delete, extract, or replace members of the archive library.

ASCII — American Standard Code for Information Interchange; a standard computer code for representing and exchanging alphanumeric information.

assembler — A software program that creates a machine-language program from a source file that contains assembly language instructions, directives, and macro definitions. The assembler substitutes absolute operation codes for symbolic operation codes and absolute or relocatable addresses for symbolic addresses.

assembly-time constant — A symbol that is assigned a constant value with the .set directive.

big endian — An addressing protocol in which bytes are numbered from left to right within a word. More significant bytes in a word have lower numbered addresses. Endian ordering is hardware-specific and is determined at reset. See also little endian

binding — A process in which you specify a distinct address for an output section or a symbol.

block — A set of statements that are grouped together within braces and treated as an entity.

.bss section — One of the default object file sections. You use the assembler .bss directive to reserve a specified amount of space in the memory map that you can use later for storing data. The .bss section is uninitialized.

byte — Per ANSI/ISO C, the smallest addressable unit that can hold a character.

C/C++ compiler — A software program that translates C source statements into assembly language source statements.

command file — A file that contains options, filenames, directives, or commands for the linker or hex conversion utility.

comment — A source statement (or portion of a source statement) that documents or improves readability of a source file. Comments are not compiled, assembled, or linked; they have no effect on the object file.
compiler program — A utility that lets you compile, assemble, and optionally link in one step. The compiler runs one or more source modules through the compiler (including the parser, optimizer, and code generator), the assembler, and the linker.

conditional processing — A method of processing one block of source code or an alternate block of source code, according to the evaluation of a specified expression.

configured memory — Memory that the linker has specified for allocation.

custom — A type whose value cannot change.

custom expression — An expression that does not in any way refer to a register or memory reference.

cross-reference listing — An output file created by the assembler that lists the symbols that were defined, what line they were defined on, which lines referenced them, and their final values.

.data section — One of the default object file sections. The .data section is an initialized section that contains initialized data. You can use the .data directive to assemble code into the .data section.

directives — Special-purpose commands that control the actions and functions of a software tool (as opposed to assembly language instructions, which control the actions of a device).

DWARF — A standardized debugging data format that was originally designed along with ELF, although it is independent of the object file format.

EABI — An embedded application binary interface (ABI) that provides standards for file formats, data types, and more.

ELF — Executable and linking format; a system of object files configured according to the System V Application Binary Interface specification.

emulator — A hardware development system that duplicates the TMS320C6000 operation.

entry point — A point in target memory where execution starts.

environment variable — A system symbol that you define and assign to a string. Environmental variables are often included in Windows batch files or UNIX shell scripts such as .cshrc or .profile.

epilog — The portion of code in a function that restores the stack and returns. See also pipelined-loop epilog.

executable module — A linked object file that can be executed in a target system.

expression — A constant, a symbol, or a series of constants and symbols separated by arithmetic operators.

external symbol — A symbol that is used in the current program module but defined or declared in a different program module.

field — For the TMS320C6000, a software-configurable data type whose length can be programmed to be any value in the range of 1-32 bits.

global symbol — A symbol that is either defined in the current module and accessed in another, or accessed in the current module but defined in another.

GROUP — An option of the SECTIONS directive that forces specified output sections to be allocated contiguously (as a group).

hex conversion utility — A utility that converts object files into one of several standard ASCII hexadecimal formats, suitable for loading into an EPROM programmer.

high-level language debugging — The ability of a compiler to retain symbolic and high-level language information (such as type and function definitions) so that a debugging tool can use this information.

hole — An area between the input sections that compose an output section that contains no code.
identifier— Names used as labels, registers, and symbols.

immediate operand — An operand whose value must be a constant expression.

incremental linking — Linking files in several passes. Incremental linking is useful for large applications, because you can partition the application, link the parts separately, and then link all of the parts together.

initialization at load time — An autoinitialization method used by the linker when linking C/C++ code. The linker uses this method when you invoke it with the --ram_model link option. This method initializes variables at load time instead of run time.

initialized section — A section from an object file that will be linked into an executable module.

input section — A section from an object file that will be linked into an executable module.

ISO — International Organization for Standardization; a worldwide federation of national standards bodies, which establishes international standards voluntarily followed by industries.

label — A symbol that begins in column 1 of an assembler source statement and corresponds to the address of that statement. A label is the only assembler statement that can begin in column 1.

linker — A software program that combines object files to form an object module that can be allocated into system memory and executed by the device.

listing file — An output file, created by the assembler, that lists source statements, their line numbers, and their effects on the section program counter (SPC).

literal constant — A value that represents itself. It may also be called a literal or an immediate value.

little endian — An addressing protocol in which bytes are numbered from right to left within a word. More significant bytes in a word have higher numbered addresses. Endian ordering is hardware-specific and is determined at reset. See also big endian

loader — A device that places an executable module into system memory.

macro — A user-defined routine that can be used as an instruction.

macro call — The process of invoking a macro.

macro definition — A block of source statements that define the name and the code that make up a macro.

macro expansion — The process of inserting source statements into your code in place of a macro call.

macro library — An archive library composed of macros. Each file in the library must contain one macro; its name must be the same as the macro name it defines, and it must have an extension of .asm.

map file — An output file, created by the linker, that shows the memory configuration, section composition, section allocation, symbol definitions and the addresses at which the symbols were defined for your program.

member — The elements or variables of a structure, union, archive, or enumeration.

memory map — A map of target system memory space that is partitioned into functional blocks.

memory reference operand — An operand that refers to a location in memory using a target-specific syntax.

mnemonic — An instruction name that the assembler translates into machine code.

model statement — Instructions or assembler directives in a macro definition that are assembled each time a macro is invoked.

named section — An initialized section that is defined with a .sect directive.

object file — An assembled or linked file that contains machine-language object code.
**object library** — An archive library made up of individual object files.

**object module** — A linked, executable object file that can be downloaded and executed on a target system.

**operand** — An argument of an assembly language instruction, assembler directive, or macro directive that supplies information to the operation performed by the instruction or directive.

**optimizer** — A software tool that improves the execution speed and reduces the size of C programs. See also assembly optimizer.

**options** — Command-line parameters that allow you to request additional or specific functions when you invoke a software tool.

**output module** — A linked, executable object file that is downloaded and executed on a target system.

**output section** — A final, allocated section in a linked, executable module.

**partial linking** — Linking files in several passes. Incremental linking is useful for large applications because you can partition the application, link the parts separately, and then link all of the parts together.

**quiet run** — An option that suppresses the normal banner and the progress information.

**raw data** — Executable code or initialized data in an output section.

**register operand** — A special pre-defined symbol that represents a CPU register.

**relocatable constant expression** — An expression that refers to at least one external symbol, register, or memory location. The value of the expression is not known until link time.

**relocation** — A process in which the linker adjusts all the references to a symbol when the symbol's address changes.

**ROM width** — The width (in bits) of each output file, or, more specifically, the width of a single data value in the hex conversion utility file. The ROM width determines how the utility partitions the data into output files. After the target words are mapped to memory words, the memory words are broken into one or more output files. The number of output files is determined by the ROM width.

**run address** — The address where a section runs.

**run-time-support library** — A library file, rts.src, that contains the source for the run time-support functions.

**section** — A relocatable block of code or data that ultimately will be contiguous with other sections in the memory map.

**section program counter (SPC)** — An element that keeps track of the current location within a section; each section has its own SPC.

**sign extend** — A process that fills the unused MSBs of a value with the value's sign bit.

**source file** — A file that contains C/C++ code or assembly language code that is compiled or assembled to form an object file.

**static variable** — A variable whose scope is confined to a function or a program. The values of static variables are not discarded when the function or program is exited; their previous value is resumed when the function or program is reentered.

**storage class** — An entry in the symbol table that indicates how to access a symbol.

**string table** — A table that stores symbol names that are longer than eight characters (symbol names of eight characters or longer cannot be stored in the symbol table; instead they are stored in the string table). The name portion of the symbol's entry points to the location of the string in the string table.

**structure** — A collection of one or more variables grouped together under a single name.
subsection — A relocatable block of code or data that ultimately will occupy continuous space in the memory map. Subsections are smaller sections within larger sections. Subsections give you tighter control of the memory map.

symbol — A name that represents an address or a value.

symbolic constant — A symbol with a value that is an absolute constant expression.

symbolic debugging — The ability of a software tool to retain symbolic information that can be used by a debugging tool such as an emulator.

tag — An optional type name that can be assigned to a structure, union, or enumeration.

target memory — Physical memory in a system into which executable object code is loaded.

.text section — One of the default object file sections. The .text section is initialized and contains executable code. You can use the .text directive to assemble code into the .text section.

unconfigured memory — Memory that is not defined as part of the memory map and cannot be loaded with code or data.

uninitialized section — A object file section that reserves space in the memory map but that has no actual contents. These sections are built with the .bss and .usect directives.

UNION — An option of the SECTIONS directive that causes the linker to allocate the same address to multiple sections.

union — A variable that can hold objects of different types and sizes.

unsigned value — A value that is treated as a nonnegative number, regardless of its actual sign.

variable — A symbol representing a quantity that can assume any of a set of values.

well-defined expression — A term or group of terms that contains only symbols or assembly-time constants that have been defined before they appear in the expression.

word — A 32-bit addressable location in target memory
Table D-1 lists significant changes that have been made between the *TMS320C6000 Assembly Language Tools User's Guide* for the v7.4 of the Code Generation Tools (SPRU186) and the current version of this document.

### Table D-1. Revision History

<table>
<thead>
<tr>
<th>Chapter</th>
<th>Location</th>
<th>Additions / Modifications / Deletions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Linker Description</td>
<td>Section 8.5.3</td>
<td>Information about accessing files and libraries from a linker command file has been added.</td>
</tr>
<tr>
<td>Object File Utilities</td>
<td>Section 9.1</td>
<td>A –cg option has been added to the Object File Display utility to display function stack usage and callee information in XML format.</td>
</tr>
<tr>
<td><strong>Previous Revisions:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Preface</td>
<td>--</td>
<td>The C6200, C6400, C6700, and C6700+ variants are not supported in v8.0 and later versions of the TI Code Generation Tools. This document applies to the C64x+, C6740, and C6600 variants of the TMS320C6000™ processor series. Sections of this document that referred to the legacy variants have been removed or simplified. If you are using a legacy device, please use v7.4 of the Code Generation Tools and refer to SPRU186 for documentation.</td>
</tr>
<tr>
<td>--</td>
<td>--</td>
<td>The software simulator for C6000 devices is no longer supported. It was supported only for legacy devices.</td>
</tr>
<tr>
<td>Introduction</td>
<td>Section 1.2</td>
<td>The Absolute Lister and Cross-Reference Lister are no longer supported. They were supported only for legacy devices.</td>
</tr>
<tr>
<td>Object Modules</td>
<td>Section 2.1</td>
<td>The COFF object file format and the associated STABS debugging format are no longer supported. The C6000 Code Generation Tools now support only the Embedded Application Binary Interface (EABI) ABI, which works only with object files that use the ELF object file format and the DWARF debug format. Sections of this document that referred to the COFF format have been removed or simplified. If you want COFF support, please use v7.4 of the Code Generation Tools and refer to SPRU186 for documentation.</td>
</tr>
<tr>
<td>Object Modules</td>
<td>Section 2.6.2</td>
<td>You can now define weak symbols using assembly or the linker command file. The linker can omit weak symbols if they are not needed to resolve references.</td>
</tr>
<tr>
<td>Program Loading and Running</td>
<td>Section 3.1.2</td>
<td>Secondary bootloaders are no longer described. They were used with legacy devices.</td>
</tr>
<tr>
<td>Linker</td>
<td>Section 8.4.10</td>
<td>Added a list of the linker's predefined macros.</td>
</tr>
<tr>
<td>Linker</td>
<td>Section 8.5.10.7</td>
<td>Information is provided about the _symval operator.</td>
</tr>
<tr>
<td>Linker</td>
<td>Section 8.6.1</td>
<td>Added information about referencing linker symbols.</td>
</tr>
</tbody>
</table>
IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as “components”) are sold subject to TI’s terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers’ products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers’ products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI’s goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or “enhanced plastic” are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have not been so designated is solely at the Buyer’s risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

<table>
<thead>
<tr>
<th>Products</th>
<th>Applications</th>
<th><a href="http://www.ti.com">www.ti.com</a></th>
</tr>
</thead>
<tbody>
<tr>
<td>Audio</td>
<td>Automotive and Transportation</td>
<td>audio.ti.com</td>
</tr>
<tr>
<td>Amplifiers</td>
<td>Communications and Telecom</td>
<td>amplifier.ti.com</td>
</tr>
<tr>
<td>Data Converters</td>
<td>Computers and Peripherals</td>
<td>dataconverter.ti.com</td>
</tr>
<tr>
<td>DLP® Products</td>
<td>Consumer Electronics</td>
<td>dlp.ti.com</td>
</tr>
<tr>
<td>DSP</td>
<td>Energy and Lighting</td>
<td>dsp.ti.com</td>
</tr>
<tr>
<td>Clocks and Timers</td>
<td>Industrial</td>
<td><a href="http://www.ti.com/clocks">www.ti.com/clocks</a></td>
</tr>
<tr>
<td>Interface</td>
<td>Medical</td>
<td>interface.ti.com</td>
</tr>
<tr>
<td>Logic</td>
<td>Security</td>
<td>logic.ti.com</td>
</tr>
<tr>
<td>Power Mgmt</td>
<td>Space, Avionics and Defense</td>
<td>power.ti.com</td>
</tr>
<tr>
<td>Microcontrollers</td>
<td>Video and Imaging</td>
<td>microcontroller.ti.com</td>
</tr>
<tr>
<td>RFID</td>
<td></td>
<td><a href="http://www.ti-rfid.com">www.ti-rfid.com</a></td>
</tr>
<tr>
<td>OMAP Applications Processors</td>
<td>TI E2E Community</td>
<td><a href="http://www.ti.com/omap">www.ti.com/omap</a></td>
</tr>
<tr>
<td>Wireless Connectivity</td>
<td></td>
<td><a href="http://www.ti.com/wirelessconnectivity">www.ti.com/wirelessconnectivity</a></td>
</tr>
</tbody>
</table>

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2016, Texas Instruments Incorporated