







**TPS7H1210-SEP** ZHCSNP8 - NOVEMBER 2021

# 采用空间增强型塑料的 TPS7H1210-SEP -- 16.5-V、1A 负线性稳压器

### 1 特性

- 提供供应商项目图, VID V62/21616 •
- 电离辐射总剂量 (TID) 为 30krad(Si)
- 每个晶圆批次的 TID RLAT (辐射批次验收测 试): 20krad (Si)
- 确定了单粒子效应 (SEE)
  - 单粒子锁定 (SEL)、单粒子烧毁 (SEB) 和单粒子 栅穿 (SEGR) 对于线性能量传递 (LET) 的抗扰度  $= 43 MeV - cm^2/mg$
  - 单粒子功能中断 (SEFI) 和单粒子瞬变 (SET) 对 于 LET 的额定值 = 43MeV-cm<sup>2</sup>/mg
- 低噪声:13.7 µ V<sub>RMS</sub> 典型值(10Hz 至 100kHz)
- 高电源抑制比,PSRR(V<sub>IN</sub> = -6V、V<sub>OUT</sub> = -5V、I<sub>OUT</sub> = 1A 下的典型值):
  - 100Hz 时为 61dB
  - 100 kHz 时为 61dB
  - 1 MHz 时为 41dB
- 输入电压范围:-3 V 至-16.5 V
- 可调输出:-1.2 V 至-15.5 V
- 输出电流高达 1A
- 与电容值 ≥ 10 µ F 的陶瓷电容一起工作时保持稳定
- 内置电流限制和热关断保护
- 增强型航天塑料 (SEP)
  - 受控基线
  - 金键合线
  - NiPdAu 铅涂层
  - 一个组装和测试基地
  - 一个制造基地
  - 军用级 (-55°C 到 125°C ) 温度范围
  - 延长了产品生命周期
  - 延长了产品变更通知 (PCN)
  - 产品可追溯性
  - 采用增强型模塑化合物实现低释气

## 2 应用

- 支持近地轨道 (LEO) 航天应用
- 卫星电力系统 (EPS) ٠
- 模拟电路电源
  - 数据转换器: ADC 和 DAC ( 模数转换器和数模 转换器)
  - 运算放大器
  - 图像传感器
- 后置直流/直流转换器稳压和纹波滤除
- 用于空间受限区域的耐辐射超洁净模拟电源

### 3 说明

TPS7H1210-SEP 是一款低噪音、高 PSRR 负电压线 性稳压器,可提供最大 1A 的负载。

该稳压器装有一个 CMOS 逻辑电平兼容使能引脚 (EN),此引脚允许用户定制电源管理方案。其他特性 包括内置电流值限制和热关断以在故障情况下保护此器 件和系统。

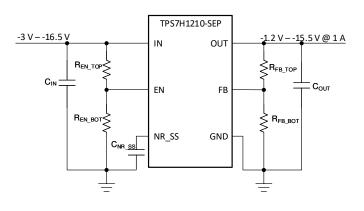
由于在设计中主要使用双极技术,TPS7H1210-SEP 器件适合于高准确度、低噪声应用,在此类应用中,为 了获得更高的系统性能,清洁的电压轨很关键。因此, 它非常适合为运算放大器、ADC、DAC 和其他高性能 模拟电路供电。

此外, TPS7H1210-SEP 器件适用于后置直流/直流转 换器稳压。通过滤除直流/直流开关转换所固有的输出 电压纹波,可确保在敏感器件和射频应用中尽可能提高 系统性能。

器件信息

器件型号 <sup>(1)</sup>	等级	封装 <sup>(2)</sup>
TPS7H1210MRGWSEP	20krad(Si)	VQFN (20) 5.00mm × 5.00mm 质量 = 83.6mg
TPS7H1210EVM	评估板	EVM

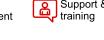
- (1) 如需了解所有可用封装,请参阅数据表末尾的可订购产品附
- 录。 尺寸和质量为标称值。 (2)



### 典型应用原理图



本文档旨在为方便起见,提供有关 TI 产品中文版本的信息,以确认产品的概要。有关适用的官方英文版本的最新信息,请访问 www.ti.com,其内容始终优先。TI不保证翻译的准确性和有效性。在实际设计之前,请务必参考最新版本的英文版本。





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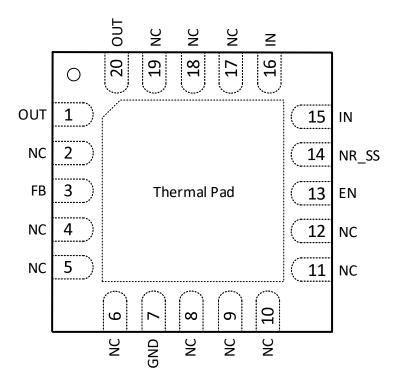
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**4 Revision History** 注:以前版本的页码可能与当前版本的页码不同

DATE	REVISION	NOTES
November 2021	*	Initial Release



### **5** Pin Configuration and Functions





#### 表 5-1. Pin Functions

PIN		I/O <sup>(1)</sup>	DESCRIPTION
NAME	NO. 1/0(1)		DESCRIPTION
EN	13	I	Enable. This dual-polarity pin turns the regulator on when $ V_{EN}  \ge 2 V$ . The EN pin can be connected to IN if not used. If $V_{EN}$ is negative polarity, then keep $ V_{EN}  \le  V_{IN} $ .
FB	3	I	Feedback. This pin is the input to the control-loop error amplifier. It is used to set the output voltage of the device and is normally equal to $V_{REF}$ ( $-1.182$ V, typical) during operation.
GND	7	_	Ground.
IN	15, 16	I	Input supply. It is recommended to connect a 10- $\mu$ F capacitor from IN to GND (as close to the device as possible).
NC	2, 4 - 6, 8 - 12, 17 - 19	_	No connect. This pin is not internally connected. It is recommended to connect these pins to GND to prevent charge buildup; however, these pins can also be left open or tied to any voltage between GND and $V_{\text{IN}}$ .
NR_SS	14	_	Noise reduction and soft start. A capacitor connected from this pin to GND controls the soft-start function and allows RMS noise to be reduced to very low levels. TI recommends connecting a 100-nF capacitor from NR_SS to GND (as close to the device as possible) to filter the noise generated by the internal band gap and maximize AC performance.
OUT	1, 20	0	Output of the regulator. A capacitor greater than or equal to 10 $\mu$ F must be tied from this pin to ground to ensure stability. TI recommends connecting a 47- $\mu$ F ceramic capacitor from OUT to GND (as close to the device as possible) to maximize AC performance.
Thermal Pad	_	_	Connect the thermal pad to a large-area ground plane. The thermal pad is not internally grounded and it must be externally tied to GND for proper operation.

(1) I = Input, O = Output, - = Other



### 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
	IN to GND	- 35	0.3	V
	FB to GND	- 2	0.3	V
Input voltage	FB to IN	- 0.3	35	V
	EN to GND	- 35	10	V
	NR_SS to IN	- 0.3	35	V
	NR_SS to GND	- 2	0.3	V
Output voltage	OUT to GND	- 33	0.3	V
	OUT to IN	- 0.3	35	V
Output current	Peak output	Internally li	mited	
Operating virtual junction temperature	TJ	- 55	150	°C
Storage temperature	T <sub>stg</sub>	- 65	150	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

### 6.2 ESD Ratings

			VALUE	UNIT	
V	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±1000	V	
V <sub>(ESD)</sub>		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	±500	v	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT	
Input voltage	IN	- 16.5		- 3	V	
	EN	V <sub>IN</sub>		10	v	
Output voltage	OUT <sup>(1)</sup>	- 15.5		$V_{REF}$	V	
Output current	OUT <sup>(2)</sup>	0		1	А	
R <sub>FB_BOT</sub> <sup>(3)</sup>	R <sub>FB_BOT</sub> is the lower feedback resistor			240	kΩ	
Input capacitance	C <sub>IN</sub>	10			μF	
Output capacitance	C <sub>OUT</sub>	10	47		μF	
C <sub>NR_SS</sub>	Noise reduction and soft start capacitor		100		nF	
Operating junction temperature	TJ	- 55		125	°C	

(1) The minimum dropout voltage must also be met.

(2) To ensure stability at no load conditions, a current from the feedback resistive network greater than or equal to 5 µA is required.

(3) This condition helps ensure stability at no load.

### 6.4 Thermal Information

		TPS7H1210-SEP	
	THERMAL METRIC <sup>(1)</sup>	RQW (VQFN)	UNIT
		20 PINS	
R <sub>0 JA</sub>	Junction-to-ambient thermal resistance	32.7	°C/W
R <sub>0</sub> JC(top)	Junction-to-case (top) thermal resistance	24	°C/W
R <sub>0 JB</sub>	Junction-to-board thermal resistance	11.8	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.3	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	11.7	°C/W
R <sub>0 JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	3.6	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.



### **6.5 Electrical Characteristics**

Over  $|V_{IN}| = 3 \text{ V}$ ,  $I_{OUT} = 1 \text{ mA}$ ,  $C_{IN} = 20 \mu\text{F}$ ,  $C_{OUT} = 20 \mu\text{F}$ ,  $C_{NR\_SS} = 0 \text{ nF}$ , FB tied to OUT, EN tied to IN, over operating temperature range ( $T_J = -55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ), unless otherwise noted.<sup>(1)</sup>

	PARAMETER	TEST CONDITION	ONS	MIN	TYP	MAX	UNIT	
POWER SUPPI	LIES AND CURRENTS							
V <sub>UVLO</sub>	Undervoltage lockout threshold				- 2		V	
		$V_{IN} = -4.6 V, V_{OUT(set)} = -5$	I <sub>OUT</sub> = 0.5 A		224	325		
	Dropout voltage	V,	I <sub>OUT</sub> = 1 A		363	500	mV	
V <sub>DO</sub>	Dropout voltage		I <sub>OUT</sub> = 1 A, T <sub>J</sub> = 25°C		363	450	IIIV	
I <sub>CL</sub>	Current limit	$V_{IN} = -6 V$ , $V_{OUT(SET)} = -5 V$ $V_{OUT(forced)} = -4.5 V$	Ι,		2.9		А	
l <sub>Q</sub>	Quiescent current	V <sub>EN</sub> = 3 V, I <sub>OUT</sub> = 0 A			210	350	μA	
I <sub>GND</sub>	Ground current <sup>(2)</sup>	V <sub>EN</sub> = 3 V, I <sub>OUT</sub> = 0.5 A			5	10	mA	
I <sub>SHDN</sub>	Shutdown current	V <sub>EN</sub> = 0.4 V V <sub>EN</sub> = -0.4 V			1	3	μA	
I <sub>FB(LKG)</sub>	Feedback leakage current <sup>(3)</sup>				14	75	nA	
ACCURACY	<b>J</b>			l				
V <sub>REF</sub>	Reference voltage	V <sub>FB</sub> = V <sub>REF</sub>		_ 1.199	- 1.182	_ 1.164	V	
		$ V_{\text{IN}}  = 3 \text{ V}, 1 \text{ mA} \leqslant I_{\text{OUT}} \leqslant 1$	A	- 2%	±1%	2%		
V <sub>ACC</sub>	Output voltage accuracy	$ V_{IN} $ = 16.5 V, 1 mA $\leq I_{OUT} \leq$	≦ 100 mA	- 2%	±1%	2%		
* ACC		V <sub>IN</sub>   = 16.5 V,  V <sub>OUT</sub>   = 15.5 V I <sub>OUT</sub> = 1 A	,	- 2%	±1%	2%		
$\Delta V_{OUT} / \Delta V_{IN}$	Line regulation	$3 V \leq  V_{IN}  \leq 16.5 V$			0.007%		V <sub>OUT</sub> /V	
$\Delta V_{OUT} / \Delta I_{OUT}$	Load regulation	$1 \text{ mA} \leq I_{OUT} \leq 1 \text{ A}$			- 0.5%		V <sub>OUT</sub> /A	
ENABLE								
V <sub>EN(+HI)</sub>	Enable turn-on (positive logic)			2		10		
V <sub>EN(-HI)</sub>	Enable turn-on (negative logic)	V <sub>IN</sub> = - 16.5 V		V <sub>IN</sub>		-2	V	
V <sub>EN(+LO)</sub>	Enable turn-off (positive logic)			0		0.4	V	
V <sub>EN(-LO)</sub>	Enable turn-off (negative logic)			- 0.4		0		
		V <sub>IN</sub> = V <sub>EN</sub> = -3 V			0.48	1		
I <sub>EN</sub>	Enable current	V <sub>IN</sub> = V <sub>EN</sub> = - 16.5 V			0.51	1	μA	
		V <sub>IN</sub> = - 16.5 V, V <sub>EN</sub> = 10 V			0.5	1		
T <sub>SD(enter)</sub>	Thermal shutdown enter temperature	1			178		*0	
T <sub>SD(exit)</sub>	Thermal shutdown exit temperature				152		°C	
NOISE AND PS	SRR							
		V <sub>IN</sub> = -6 V, V <sub>OUT</sub> = -5 V,	f = 100 Hz		61			
PSRR	Power-supply rejection ratio	$C_{OUT} = 50.11 \ \mu F$ , $I_{OUT} = 1 \ A$ ,	f = 100 kHz		61	dB		
		$C_{NR_{SS}} = 100 \text{ nF}^{(4)}$ f = 1 MHz			41		1	
V <sub>N</sub>	Output noise rms voltage (bandwidth from 10 Hz to 100 kHz)		, C <sub>IN</sub> = 11.1 μF, 00 nF, I <sub>OUT</sub> = 1 A		13.7		μV <sub>RMS</sub>	

At operating conditions,  $V_{IN} \leq 0 V$ ,  $V_{OUT(nom)} \leq V_{REF} \leq 0 V$ ; at regulation,  $V_{IN} \leq V_{OUT(nom)} - |V_{DO}|$ ;  $I_{OUT} > 0$  flows from OUT to IN. (1)

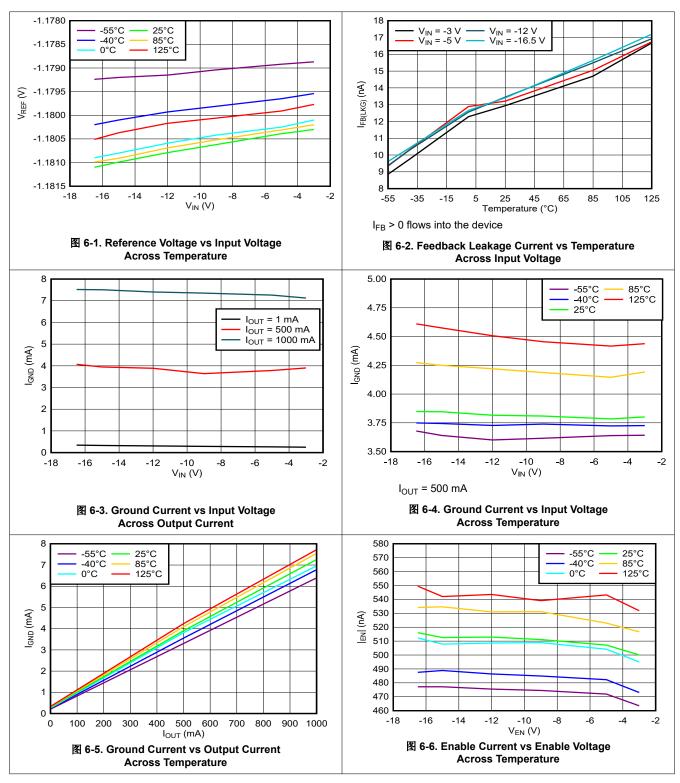
(2)  $I_{GND} = I_{IN} - I_{OUT}$ (3)  $I_{FB} > 0$  flows into the device.

(4)  $C_{IN}$  is removed as part of PSRR testing. During normal operation, follow the recommended operating condition of  $C_{IN} \ge 10 \ \mu$ F.



### 6.6 Typical Characteristics

Over  $|V_{IN}| = 3 V$ ,  $I_{OUT} = 1 mA$ ,  $C_{IN} = 20 \mu$ F,  $C_{OUT} = 20 \mu$ F,  $C_{NR}$  = 0 nF, FB tied to OUT, EN tied to IN,  $T_A = 25^{\circ}$ C, unless otherwise noted.

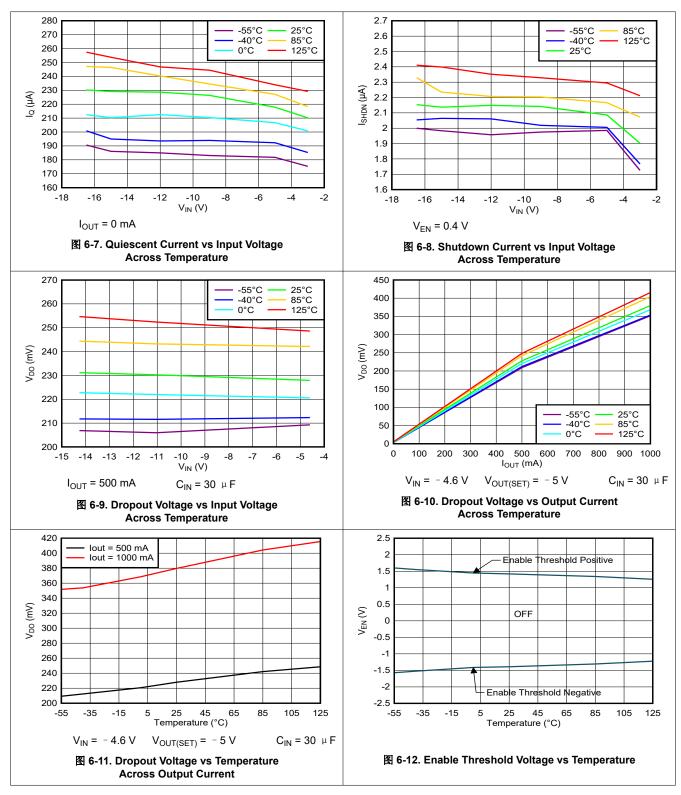


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### 6.6 Typical Characteristics (continued)

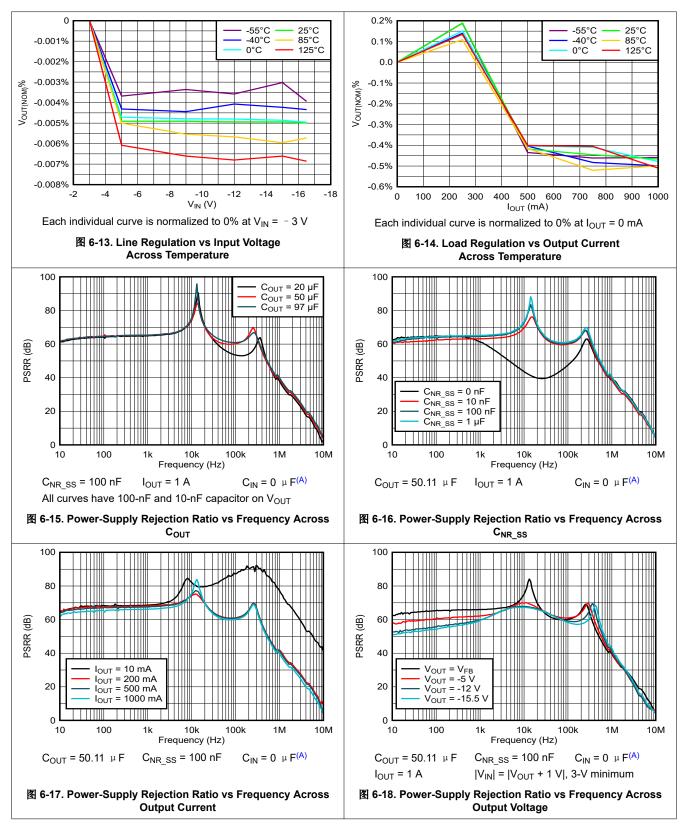
Over  $|V_{IN}| = 3 V$ ,  $I_{OUT} = 1 mA$ ,  $C_{IN} = 20 \mu$ F,  $C_{OUT} = 20 \mu$ F,  $C_{NR}$  = 0 nF, FB tied to OUT, EN tied to IN,  $T_A = 25^{\circ}$ C, unless otherwise noted.





### 6.6 Typical Characteristics (continued)

Over  $|V_{IN}| = 3 V$ ,  $I_{OUT} = 1 mA$ ,  $C_{IN} = 20 \mu$ F,  $C_{OUT} = 20 \mu$ F,  $C_{NR}$ \_SS = 0 nF, FB tied to OUT, EN tied to IN,  $T_A = 25^{\circ}$ C, unless otherwise noted.

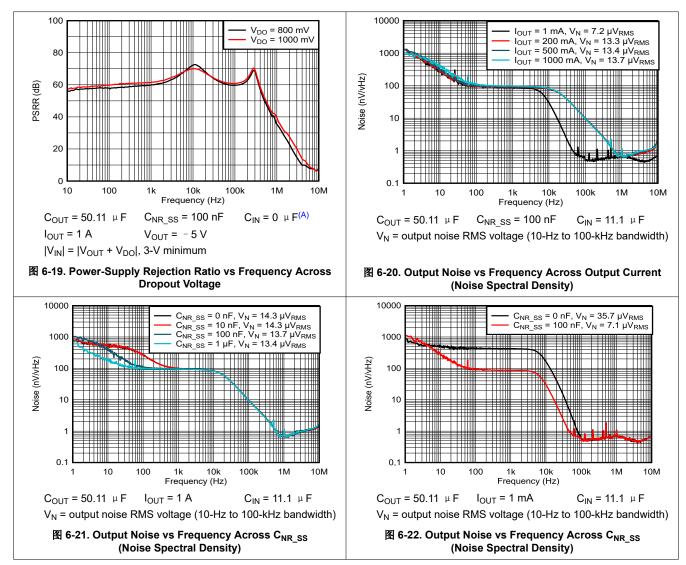


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### 6.6 Typical Characteristics (continued)

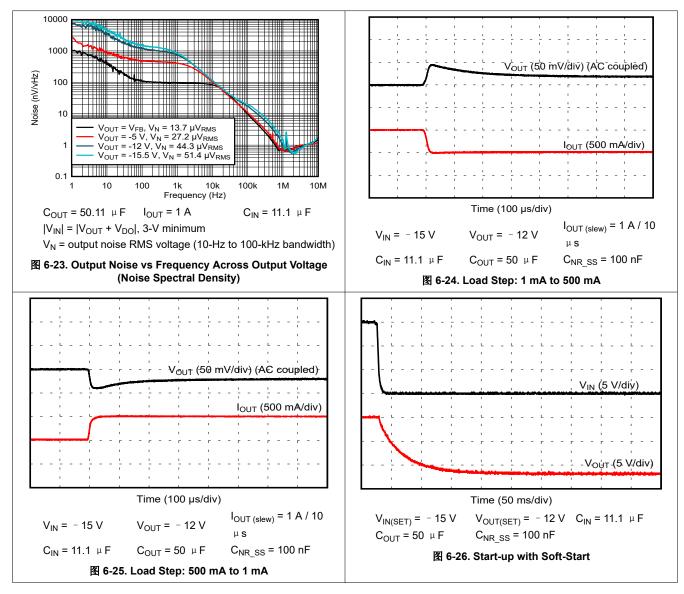
Over  $|V_{IN}| = 3 V$ ,  $I_{OUT} = 1 mA$ ,  $C_{IN} = 20 \mu$ F,  $C_{OUT} = 20 \mu$ F,  $C_{NR_SS} = 0 n$ F, FB tied to OUT, EN tied to IN,  $T_A = 25^{\circ}$ C, unless otherwise noted.





### 6.6 Typical Characteristics (continued)

Over  $|V_{IN}| = 3 V$ ,  $I_{OUT} = 1 mA$ ,  $C_{IN} = 20 \mu$ F,  $C_{OUT} = 20 \mu$ F,  $C_{NR}SS} = 0 n$ F, FB tied to OUT, EN tied to IN,  $T_A = 25^{\circ}$ C, unless otherwise noted.



A. C<sub>IN</sub> is removed as part of PSRR testing. During normal operation, follow the recommended operating condition of C<sub>IN</sub>  $\ge$  10  $\mu$  F.

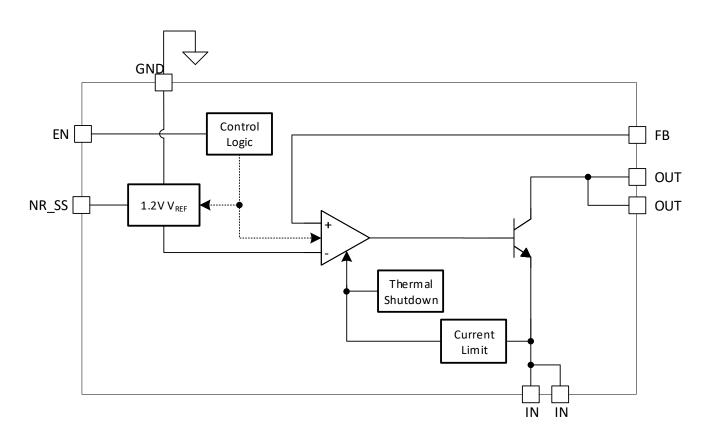


### 7 Detailed Description

### 7.1 Overview

The TPS7H1210-SEP negative voltage linear regulator uses a bipolar process to achieve very low noise and very high PSRR levels at a wide input voltage and current range. These features, plus its radiation tolerance, make this device ideal for high-performance analog applications in satellites.

### 7.2 Functional Block Diagram



### 7.3 Feature Description

### 7.3.1 Internal Current Limit

The fixed internal current limit of the TPS7H1210-SEP device helps protect the regulator during fault conditions. The maximum amount of current the device can source is the current limit (2.9 A, typical), and it is largely independent of output voltage. For reliable operation, do not operate the device in current limit for extended periods of time.



### 7.3.2 Enable Pin Operation

The TPS7H1210-SEP provides a dual-polarity enable pin (EN) that turns on the regulator when  $|V_{EN}| > 2 V$ , whether the voltage is positive or negative, as shown in  $\mathbb{K}$  7-1. Specifically, if  $V_{EN} \ge V_{EN(+HI)}$  or  $V_{EN} \le V_{EN(-HI)}$ , the regulator is enabled. If  $V_{EN(+LO)} \ge V_{EN} \ge V_{EN(-LO)}$ , the regulator is disabled.

This functionality allows for different system power management topologies; for example:

- Connecting the EN pin directly to a negative voltage, such as V<sub>IN</sub>.
- · Connecting the EN pin directly to a positive voltage, such as the output of digital logic circuitry.
- Connecting the EN pin to a resistor divider from V<sub>IN</sub> to GND to turn-on at a specific input voltage level (programmable turn-on voltage).

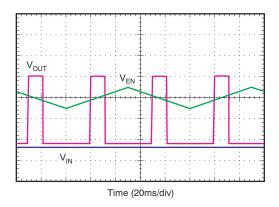


图 7-1. Enable Pin Positive and Negative Threshold

#### 7.3.3 Programmable Soft-Start

The NR\_SS capacitor acts as a noise reduction capacitor and a soft-start capacitor to slow down the rise time of the output. The output rise time, when using an NR\_SS capacitor, is approximated by 方程式 1.

$$t_{SS}$$
 (ms) = 1.2 ×  $C_{NR}_{SS}$  (nF)

(1)

In 方程式 1,  $t_{SS}$  is the soft-start time in milliseconds and  $C_{NR_SS}$  is the capacitance at the NR\_SS pin in nanofarads.

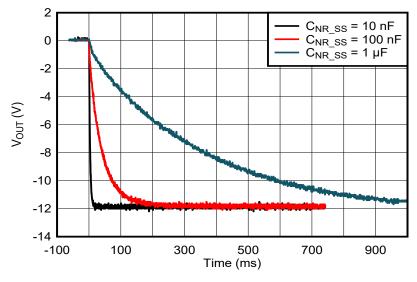


图 7-2. Start-Up Waveforms vs C<sub>NR SS</sub>



#### 7.3.4 Thermal Protection

Thermal protection disables the output when the junction temperature rises to approximately 178°C, allowing the device to cool. When the junction temperature cools to approximately 152°C, the output circuitry is enabled. Depending on power dissipation, thermal resistance, and ambient temperature, the thermal protection circuit may cycle on and off. This cycling limits the dissipation of the regulator, mitigating damage as a result of overheating.

Any tendency to activate the thermal protection circuit indicates excessive power dissipation or an inadequate heat sink. For reliable operation, limit the junction temperature to a maximum of 125°C.

The internal protection circuitry of the TPS7H1210-SEP has been designed to protect against overload conditions. It was not intended to replace proper thermal management. Continuously running the TPS7H1210-SEP into thermal shutdown degrades device reliability.

#### 7.4 Device Functional Modes

#### 7.4.1 Normal Operation

The device regulates to the nominal output voltage under all of the following conditions:

- The input voltage magnitude has previously exceeded the UVLO rising voltage magnitude and has not decreased below the UVLO falling threshold magnitude.
- The input voltage magnitude is greater than the nominal output voltage magnitude added to the dropout voltage magnitude.
- $|V_{EN}| > |V_{(HI)}|$
- The output current is less than the current limit.
- The device junction temperature is less than the maximum specified recommended operating conditions junction temperature.

#### 7.4.2 Dropout Operation

If the input voltage magnitude is lower than the magnitude of the nominal output voltage plus the specified dropout voltage, but all other conditions are met for normal operation, the device operates in dropout mode. In this condition, the output voltage is the same as the input voltage minus the dropout voltage. The transient performance of the device is significantly degraded because the pass device (as a bipolar junction transistor, or BJT) is in saturation and no longer controls the current through the LDO. Line or load transients in dropout can result in large output voltage deviations.

#### 7.4.3 Disabled

The device is disabled under any of the following conditions:

- $|V_{EN}| < |V_{(HI)}|$
- The device junction temperature is greater than the thermal shutdown temperature.

 $\pm$  7-1 shows the conditions that lead to the different modes of operation.

OPERATING MODE	PARAMETER					
OF EIXAMING MODE	V <sub>IN</sub>	V <sub>EN</sub>	I <sub>OUT</sub>	TJ		
Normal mode	$ V_{IN}  > \{  V_{OUT(nom)}  +  V_{DO} ,  V_{IN(min)}  \}$	$ V_{EN}  >  V_{(HI)} $	$I_{OUT} < I_{CL}$	T <sub>J</sub> < 125°C		
Dropout mode	$ V_{\rm IN(min)}  <  V_{\rm IN}  <  V_{\rm OUT(nom)}  +  V_{\rm DO} $	$ V_{EN}  >  V_{(HI)} $	—	T <sub>J</sub> < 125°C		
Disabled mode (any true condition disables the device)	$ V_{\rm IN}  \leqslant  V_{\rm UVLO} $	V <sub>EN</sub>   <  V <sub>(HI)</sub>	_	T <sub>J</sub> > ~178°C		

#### 表 7-1. Device Functional Mode Comparison



### 8 Application and Implementation

#### 备注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 8.1 Application Information

#### 8.1.1 Adjustable Operation

The TPS7H1210-SEP has an output voltage range of V<sub>REF</sub> to -15.5 V. The nominal output voltage of the device is set by two external resistors, as shown in  $\boxed{882}$ .

 $R_{FB\_TOP}$  and  $R_{FB\_BOT}$  can be calculated for any output voltage range using  $\beta$ <math><math>2. To ensure stability under no-load conditions at |V\_{OUT}| > |V\_{REF}|, this resistive network must provide a current equal to or greater than 5 A.

$$R_{FB_TOP} = R_{FB_BOT} \times \left(\frac{V_{OUT}}{V_{REF}} - 1\right), \text{ where } \frac{|V_{REF}|}{R_{FB_BOT}} > 5 \,\mu\text{A}$$
(2)

 $\frac{1}{8}$  8-1 shows the resistor combinations to achieve a few of the most common rails using commercially available, 1%-tolerance resistors. If greater voltage accuracy is required, consider the output voltage offset contributions because of the feedback pin current and use 0.1%-tolerance resistors.

V <sub>OUT</sub> (V)	R <sub>FB_TOP</sub> (k Ω )	R <sub>FB_ВОТ</sub> (k Ω)	RESISTOR NETWORK BIAS CURRENT (µA)	RESISTOR ERROR CONTRIBUTION <sup>(1)</sup>			
- 1.182	0	œ	N/A	N/A			
- 1.8	7.32	14	84.4	+0.001%			
- 2.5	11.3	10.2	115.9	+0.341%			
- 3.3	19.1	10.7	110.5	- 0.245%			
- 5	34	10.5	112.6	- 0.189%			
- 9	115	17.4	67.9	+0.066%			
- 10	445	15.4	76.8	- 0.086%			
- 12	137	15	78.8	+0.187%			
- 15	133	11.3	104.6	- 0.627%			

#### 表 8-1. Example 1% Tolerance Resistors for Common Voltage Rails

(1) This is the error contribution due to the mismatch between the ideal resistor ratio and the actual resistor ratio (using the indicated resistor values). It does not include the error contribution due to the resistor tolerance itself. More accurate ratios are possible by using 0.1% tolerance resistors.



#### 8.1.2 Capacitor Recommendations

It is recommended to use low equivalent series resistance (ESR) capacitors for the input, output, noise reduction, and bypass capacitors. Ceramic capacitors with an X7R dielectric is preferred. This dielectric offers stable characteristics over temperature.

High-ESR capacitors may degrade PSRR and affect stability.	

The TPS7H1210-SEP negative linear regulator achieves stability with a minimum input and output capacitance of 10  $\mu$  F. TI recommends using a 10- $\mu$  F capacitor at the input. A larger capacitor is recommended at the output. Specifically, TI recommends using a 47- $\mu$  F capacitor (or multiple capacitors to reach ~47  $\mu$  F) at the output to improve single event transient (SET) performance.

#### 8.1.3 Noise Reduction and Feed-Forward Capacitor Requirements

Although the noise-reduction ( $C_{NR_SS}$ ) capacitor is not needed to achieve stability, TI highly recommends using a 100-nF noise-reduction capacitor to minimize noise and maximize AC performance. The noise-reduction capacitor is especially important at low currents as shown in 8 6-22.

It is generally recommended to not use a feed-forward capacitor. While a feed-forward capacitor can provide some improvements in PSRR at certain frequencies, it also has additional risks. See *Pros and Cons of Using a Feed-Forward Capacitor with a Low Dropout Regulator* for additional information.



 $\boxed{8}$  8-1 shows the different PSRR performance of the device with and without a feed-forward capacitor with V<sub>IN</sub> = − 13 V, V<sub>OUT</sub> = − 12 V, I<sub>OUT</sub> = 1 A, C<sub>NR\_SS</sub> = 100 nF, and C<sub>OUT</sub> = 50  $\mu$  F.

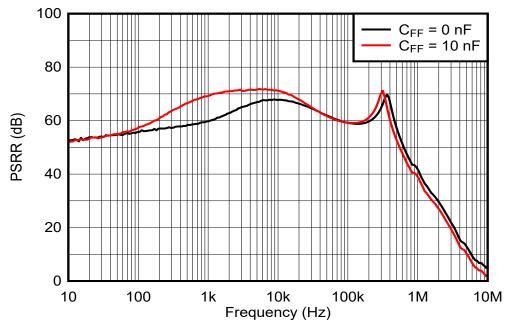


图 8-1. Power-Supply Rejection Ratio vs Frequency Across C<sub>FF</sub>



#### 8.1.4 Power-Supply Rejection Ratio (PSRR)

Using a noise-reduction capacitor ( $C_{NR_SS}$ ) of at least 10-nF greatly improves TPS7H1210-SEP power-supply rejection ratio. If the  $C_{NR_SS}$  capacitor is omitted, the PSRR can be 10 dB lower or worse across a wide range of frequencies. A 100-nF capacitor is generally recommended.

Additionally, TI recommends using at least a 47-  $\mu$  F output capacitor for both single event transient (SET) and to achieve great AC performance. A 10-  $\mu$  F input capacitor is generally sufficient for good device performance; however, a 47-  $\mu$  F input capacitor or larger may be ideal if the input rail is extremely noisy.

The high power-supply rejection of the TPS7H1210-SEP makes it a good choice for powering high-performance analog circuitry.

#### 8.1.5 Output Noise

The TPS7H1210-SEP provides low output noise when a noise-reduction capacitor (C<sub>NR SS</sub>) is used.

The noise-reduction capacitor serves as a filter for the internal reference. By using at a 100-nF noise reduction capacitor ( $C_{NR}$ ), the output noise can be reduced by approximately 80% (from 35.7  $\mu$  V<sub>RMS</sub> to 7.1  $\mu$  V<sub>RMS</sub>). See 8 6-22 for additional information. The benefit is less pronounced at higher currents (see 8 6-21).

The TPS7H1210-SEP low output voltage noise makes it an ideal solution for powering noise-sensitive circuitry.

#### 8.1.6 Transient Response

As with any regulator, increasing the size of the output capacitor reduces overshoot and undershoot magnitude, but increases duration of the transient response.

#### 8.1.7 Post DC-DC Converter Filtering

Most of the time, the voltage rails available in a system do not match the voltage specifications demanded by one or more of its circuits; these rails must be stepped up or down, depending on specific voltage requirements.

DC-DC converters are generally the preferred solution to stepping up or down a voltage rail when current consumption is not negligible. These devices offer high efficiency with minimum heat generation, but they have one primary disadvantage: they introduce a high-frequency component, and the associated harmonics, on top of the DC output signal.

If not filtered properly, this high-frequency component degrades analog circuitry performance, and reduces overall system accuracy and precision.

The TPS7H1210-SEP offers a wide-bandwidth, very-high power-supply rejection ratio (PSRR). This specification makes it ideal for post DC-DC converter filtering. TI recommends using a schematic like the one shown in 🕅 8-2 for high performance. Also, verify that the TPS7H1210-SEP regulator PSRR is still high within the fundamental frequency (and its first harmonic, if possible) of the switching regulator.

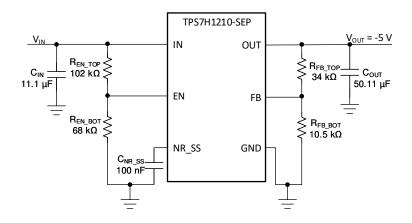
#### 8.1.8 Power for Precision Analog

One of the primary TPS7H1210-SEP applications is to provide very low noise voltage rails to high-performance analog circuitry in order to maximize system accuracy and precision. This includes powering operational amplifiers, ADCs, DACs, and RF amplifiers.

Because of the low noise levels at high voltages, the TPS7H1210-SP can directly power high performance analog circuitry with high-voltage input supply requirements.



### 8.2 Typical Application



### 图 8-2. Adjustable Operation for Optimized AC and Radiation Performance

### 8.2.1 Design Requirements

The design goals for this example are  $V_{IN} = -6 V$ ,  $V_{OUT} = -5 V$ , and  $I_{OUT} = 1$ -A maximum. The design must optimize transient response, and the input supply comes from a supply on the same printed-circuit board (PCB).

#### 8.2.2 Detailed Design Procedure

The design consists of C<sub>IN</sub>, C<sub>OUT</sub>, C<sub>NR\_SS</sub>, R<sub>FB\_TOP</sub>, R<sub>FB\_BOT</sub>, R<sub>EN\_TOP</sub>, R<sub>EN\_BOT</sub>, and the circuit shown in <u>88-2</u>.

The first step when designing with a linear regulator is to examine the maximum load current along with the input and output voltage requirements to determine if the device thermal and dropout voltage requirements can be met. At 1 A, the input dropout voltage of the TPS7H1210-SEP device is a maximum of 500 mV over temperature; thus, the dropout headroom is sufficient for operation over both input and output voltage accuracy. Keep in mind that operating an LDO close to the dropout limit reduces AC performance, but has the benefit of reducing the power dissipation across the LDO.

The maximum power dissipated in the linear regulator is the maximum voltage drop across the pass element from the input to the output multiplied by the maximum load current (plus a small amount of quiescent power). In this example, the maximum voltage drop across in the pass element is (-6 V) - (-5 V), giving us a  $V_{DROP} = 1$  V. The power dissipated in the pass element is calculated by taking this voltage drop multiplied by the maximum load current. For this example, the maximum power dissipated in the linear regulator is approximately 1 W.

To ensure an accurate output voltage,  $R_{FB\_TOP}$  and  $R_{FB\_BOT}$  must also be found, and the current through these resistors must be greater than 5 µA to ensure stability. For this design,  $R_{FB\_TOP}$  is set to 34 k $\Omega$ , to achieve reasonable leakage current leakage while continuing to hold it well above 5 µA. Then  $\overline{f}$   $\mathbb{R}$  $\mathbb{R}_{\mathsf{T}}$  3 is used to calculate the proper value for  $R_{FB}$  BOT.

$$R_{FB\_BOT} = \frac{R_{FB\_TOP} \times V_{REF}}{V_{OUT} - V_{REF}} = 10.5 \text{ k}\Omega \text{ and } I_{DIVIDER} = \frac{|V_{REF}|}{R_{FB\_BOT}} = 112.6 \text{ }\mu\text{A}$$
(3)

Next, for C<sub>IN</sub> a 10  $\mu$ F, 1  $\mu$ F, and 0.1- $\mu$ F ceramic capacitor are selected. This provides margin over the 10- $\mu$ F minimum input capacitance and reduces the impedance across a wider range of frequencies than a single 10- $\mu$ F capacitor.

For  $C_{OUT}$ , 5 × 10-µF, 1 × 100-nF, and 1 × 10-nF ceramic capacitors are selected. The multiple ceramic capacitors reduce ESR (equivalent series resistance) and ESL (equivalent series inductance) to aid in good AC performance. Additionally, better SET (single-event-transient) performance is generally achieved by choosing a larger output capacitance than the minimum of 10 µF.



Next,  $C_{NR_{SS}}$  is set at 100 nF for optimal noise performance along with maximized AC performance while keeping reasonable soft-start times.

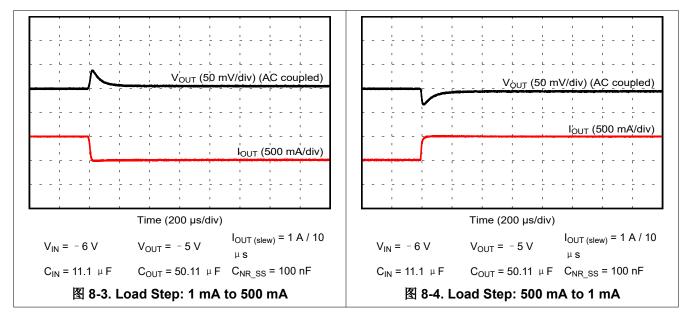
To have a configurable turn-on voltage, feed the EN pin by a resistor divider from V<sub>IN</sub> to GND. Since the TPS7H1210-SEP is commanded to turn-on when EN is less than -2 V (see V<sub>EN(-HI)</sub> in 节 6.5), 方程式 4 can be used to determine the resistors to select for a desired turn-on voltage, V<sub>IN(turn-on)</sub>.

$$R_{EN\_BOT} = \frac{R_{EN\_TOP} \times 2 V}{V_{IN(turn-on)} - 2 V}$$
(4)

For this design  $R_{EN_{TOP}} = 102 \text{ k} \Omega$  and  $R_{EN_{BOT}} = 68 \text{ k} \Omega$ , which results in  $V_{IN(turn-on)} = -5 \text{ V}$ . This means that as  $V_{IN}$  is ramping from 0 V to its final value of -6 V during start-up, the regulator will turn-on when  $V_{IN}$  reaches -5 V.

#### 8.2.3 Application Curves

图 8-3 and 图 8-4 show a 1-mA to 500-mA load step and 500-mA to 1-mA load step respectively using the values described within this section.



### 8.3 Do's and Don'ts

Place at least one low ESR 10- $\mu$ F capacitor as close as possible to both the IN and OUT terminals of the regulator to the GND pin.

Provide adequate thermal paths away from the device.

Do not place the input or output capacitor more than 10 mm away from the regulator.

Do not exceed the absolute maximum ratings.

Do not float the EN pin.

Do not resistively or inductively load the NR\_SS pin.



### 9 Power Supply Recommendations

The input supply for the LDO must be within its recommended operating conditions, of -16.5 V to -3 V. The input voltage must provide adequate headroom for the device to have a regulated output. If the input supply is noisy, additional input capacitors with low ESR can help improve the output noise performance.

### 10 Layout

Layout is a critical part of good power-supply design. Several signal paths that conduct fast-changing currents or voltages can interact with stray inductance or parasitic capacitance to generate noise or degrade the power-supply performance. To help eliminate these problems, bypass the IN pin to ground with a low ESR ceramic bypass capacitor with an X7R dielectric.

### **10.1 Layout Guidelines**

#### 10.1.1 Improve PSRR and Noise Performance

To improve AC performance such as PSRR, output noise, and transient response, TI recommends designing the board with separate planes for IN, OUT, and GND. The IN and OUT planes should be isolated from each other by a GND plane section. In addition, the ground connection for the output capacitor should connect directly to the GND pin of the device.

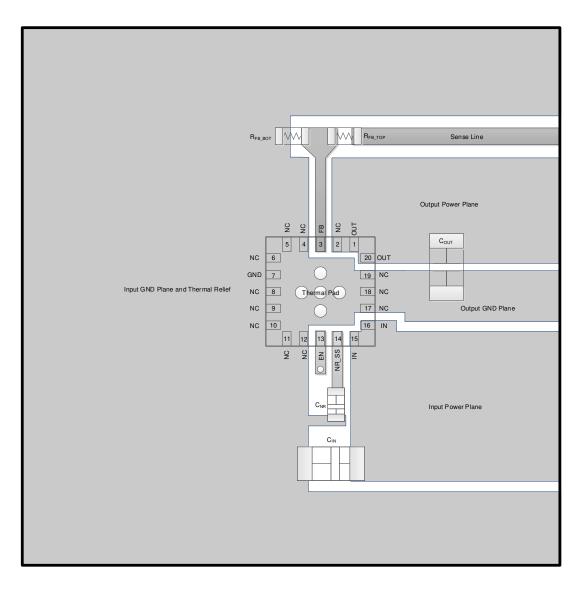
Equivalent series inductance (ESL) and equivalent series resistance (ESR) must be minimized in order to maximize performance and ensure stability. Every capacitor ( $C_{IN}$ ,  $C_{OUT}$ ,  $C_{NR_SS}$ , and  $C_{FF}$  if used) must be placed as close as possible to the device and on the same side of the PCB as the regulator itself.

Do not place any of the capacitors on the opposite side of the PCB from where the regulator is installed. The use of vias and long traces is strongly discouraged because they may impact system performance negatively and even cause instability.



### 10.2 Layout Example

It may be possible to obtain acceptable performance with alternative PCB layouts.





### **10.3 Thermal Performance**

The high-current and high-voltage characteristics of the TPS7H1210-SEP means that, often enough, high power (heat) is dissipated from the device itself. This heat, if dissipated into the PCB, creates a temperature gradient in the surrounding area that causes nearby components to react to this temperature change (drift). In high-performance systems, such drift may degrade overall system accuracy and precision.

The heat generated by the device is a result of the power dissipation, which depends on input voltage and load conditions. Power dissipation ( $P_D$ ) can be approximated by calculating the product of the output current times the voltage drop across the output pass element, as shown in  $\overline{f}$   $\overline{f}$   $\overline{f}$ :

$$P_{\rm D} = (V_{\rm IN} - V_{\rm OUT}) \times I_{\rm OUT}$$

(5)

Be sure the PCB is able to effectively dissipate the heat resulting from the power dissipation.



### 11 Device and Documentation Support

### **11.1 Device Support**

#### **11.1.1 Development Support**

#### 11.1.1.1 Spice Models

Computer simulation of circuit performance using SPICE is often useful when analyzing the performance of analog circuits and systems. A PSpice model for the TPS7H1210-SEP is available through the product folder under the *Design & Development* section.

### **11.2 Documentation Support**

#### 11.2.1 Related Documentation

For related documentation see the following:

- Texas Instrument, TPS7H1210-SEP Total Ionizing Dose (TID) radiation report
- Texas Instrument, TPS7H1210-SEP Single-Event Effects (SEE) radiation report
- Texas Instrument, TPS7H1210-SEP Evaluation Module (EVM) user's guide
- Texas Instrument, *Pros and Cons of Using a Feedforward Capacitor with a Low-Dropout Regulator* application report
- Vendor item drawing available, VID V62/21616

#### 11.3 接收文档更新通知

要接收文档更新通知,请导航至 ti.com 上的器件产品文件夹。点击*订阅更新*进行注册,即可每周接收产品信息更改摘要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

### 11.4 支持资源

**TI E2E<sup>™</sup>** 支持论坛是工程师的重要参考资料,可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解 答或提出自己的问题可获得所需的快速设计帮助。

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#### **11.6 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 11.7 术语表

TI术语表 本术语表列出并解释了术语、首字母缩略词和定义。

### 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



### PACKAGING INFORMATION

Orderable Dev	vice	Status	Package Type		Pins	-	Eco Plan	Lead finish/	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
		(1)		Drawing		Qty	(2)	Ball material	(3)		(4/5)	
TDOTULOUNDO			VOEN			70				FF ( 10F	7114040	
TPS7H1210MRG	SWSEP	ACTIVE	VQFN	RGW	20	70	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-55 to 125	7H1210	Samples
TPS7H1210MRG	WTSEP	ACTIVE	VQFN	RGW	20	250	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-55 to 125	7H1210	Samples
												Bumples
V62/21616-01	IXE	ACTIVE	VQFN	RGW	20	70	RoHS & Green	NIPDAU	Level-3-260C-168 HR		7H1210	Samples
V62/21616-01>	XE-T	ACTIVE	VQFN	RGW	20	250	RoHS & Green	NIPDAU	Level-3-260C-168 HR		7H1210	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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# **RGW 20**

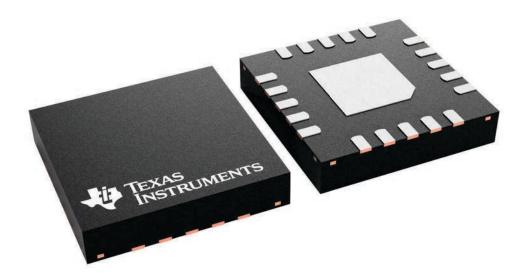
5 x 5, 0.65 mm pitch

# **GENERIC PACKAGE VIEW**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



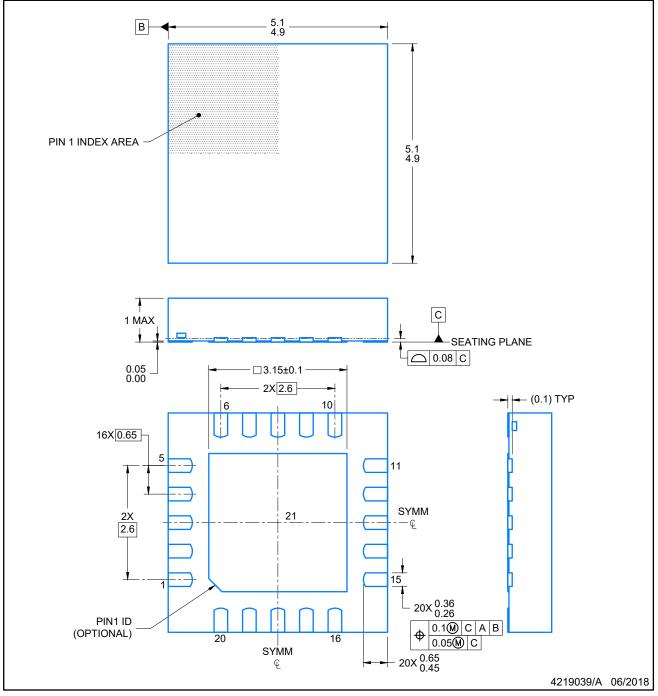


# **RGW0020A**

# **PACKAGE OUTLINE**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.

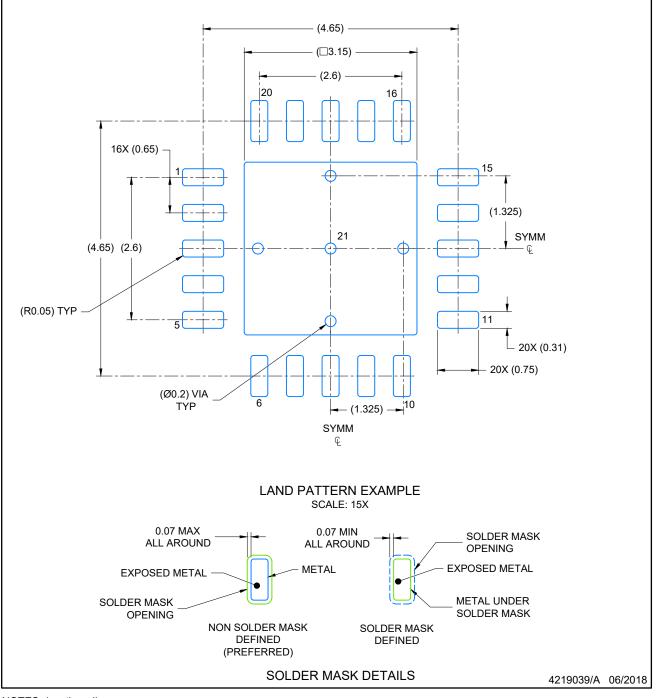


# **RGW0020A**

# **EXAMPLE BOARD LAYOUT**

### VQFN - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

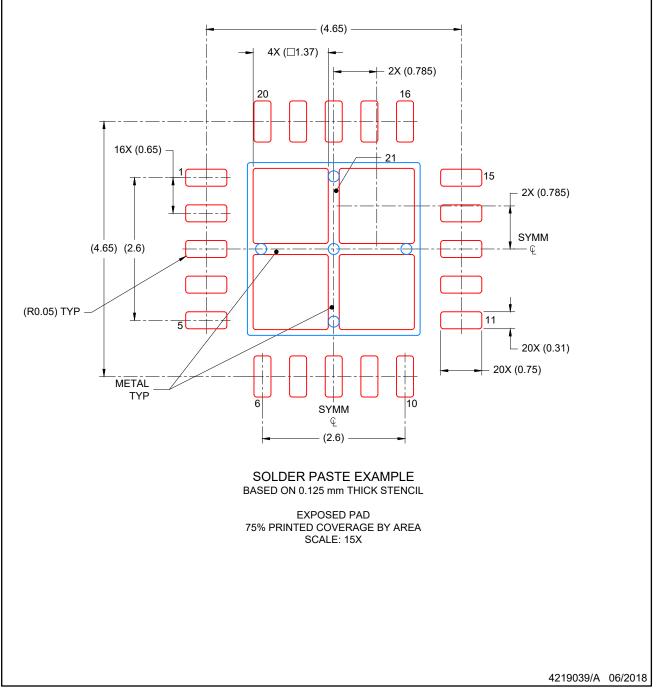


# **RGW0020A**

# **EXAMPLE STENCIL DESIGN**

# VQFN - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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